CS 190I Deep Learning Variational Auto-Encoder

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Course Evaluation

- https://esci.id.ucsb.edu
- https://bit.ly/3FSqFs0
- Feedback is important and helpful for improving the course
- Encourage narrative comments
- Bonus 5% to final exam, if response rate > 90% (48% today)

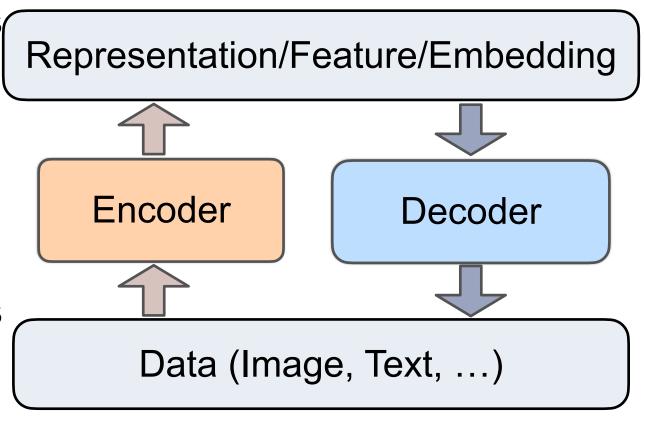
Recap

- Graph neural network
 - message passed along graph edges
 - aggregate message/embedding by FFN
 - many variants: GCN, GAT, GraphSAGE

Variational Auto-Encoder (VAE)

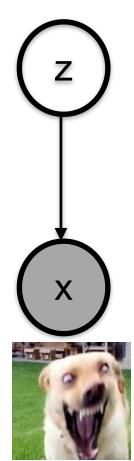
VAE

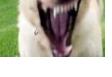
- Hidden
 representations
 follow a prior
 distribution
- Encoder will produce a distribution of representations (posterior distribution)



Deep Latent Model

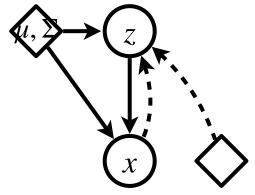
- z follows a prior distribution, e.g. Gaussian(0, I)
- p(x|z) is defined by a deep neural network $f(z; \theta)$
- To learn θ , use $E_{(Z|X)}[\log p(X,Z;\theta)]$





Graphical Model for VAE

- Assuming data X is generated from a latent variable \boldsymbol{Z}
- Generation process
 - draw $Z \sim N(\mu, \Sigma)$
 - draw $X \mid Z \sim p(f(Z))$, defined by a neural network f



- The goal is to maximize the data log-likelihood $\log p(X;\theta) = \log \left\lceil p(X \,\middle|\, Z) p(Z) dZ \right\rceil$
- Hard to optimize over θ , if f(Z) is very complex such as a CNN, RNN, or Transformer.

VAE

Objective: maximize the data loglikelihood

$$\max \ell(\theta) = \sum_{n} \log p(x_n; \theta)$$

$$= \sum_{n} \log \left(p(x_n; \theta) - p(x_n; \theta) \right) dx$$

$$= \sum_{n} \log \int p(x_n | z_n; \theta) p(z_n; \theta) dz_n$$

VAE

$$\max \ell(\theta) = \sum_{n} \log p(x_n; \theta)$$
$$= \sum_{n} \log \int p(x_n | z_n; \theta) p(z_n; \theta) dz_n$$

- But $\log p(x; \theta)$ is intractable.
- $q(z \mid x; \phi)$ is the posterior • For any distribution $q(z \mid x, \phi)$:

$$\log p(x; \theta) \ge \mathrm{E}_{q(z|x;\phi)} \left[\log \frac{p(x, z; \theta)}{q(z|x; \phi)} \right] = \mathrm{ELBO}$$

- Derivation via Jensen's inequality.
- Maximizing the ELBO instead of maximizing $\log p(x;\theta)$

Understanding ELBO

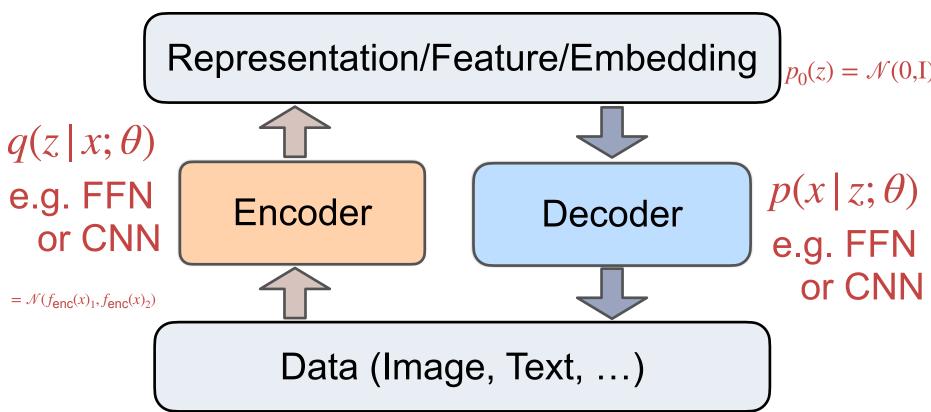
$$\begin{split} \log p(X;\theta) &\geq \mathrm{E}_q[\log \frac{p(X,Z;\theta)}{q(Z\,|\,X;\phi)}] \\ \max \max_{\theta} \max_{\phi} \mathrm{ELBO} &= \sum_{n} \mathrm{E}_q\left[\log \frac{p(x_n\,|\,z_n;\theta)p_0(z_n)}{q(z_n\,|\,x_n;\phi)}\right] \\ &= \\ &= \mathrm{E}_q\left[\log p(x_n\,|\,z_n;\theta)\right] - \mathrm{KL}\left(q(z_n\,|\,x_n;\phi)\|p_0(z_n)\right) \end{split}$$

Reconstruction loss

Regularization

VAE

Let $q(z | x; \phi)$ and $p(x | z; \theta)$ share the same parameter θ



Training VAE

gradient descent(ascent for max)

$$\max_{\theta} \max_{\phi} \text{ELBO} = \sum_{n} E_{q(z_n|x_n;\theta)} \left[\log \frac{p(x_n|z_n;\theta)p_0(z_n)}{q(z_n|x_n;\theta)} \right]$$

$$= \sum_{n} E_{q(z_n|x_n;\theta)} \left[r(\theta, z_n, x_n) \right]$$

$$r(\theta, z_n, x_n) = \log \frac{p(x_n|z_n;\theta)p_0(z_n)}{q(z_n|x_n;\theta)}$$

Computing gradient:

$$\nabla_{\theta} \mathbf{E}_{q(z_n|x_n;\theta)} \left[r(\theta, z_n, x_n) \right]$$

Gradient of ELBO

$$r(\theta, z_n, x_n) = \log \frac{p(x_n | z_n; \theta) p_0(z_n)}{q(z_n | x_n; \theta)}$$

Computing gradient:

$$\nabla_{\theta} \mathbf{E}_{q(z_n|x_n;\theta)} \left[r(\theta, z_n, x_n) \right]$$

Gradient of ELBO

$$r(\theta, z_n, x_n) = \log \frac{p(x_n | z_n; \theta) p_0(z_n)}{q(z_n | x_n; \theta)}$$

Computing gradient:

$$\nabla_{\theta} \mathbf{E}_{q(z_n \mid x_n; \theta)} \left[r(\theta, z_n, x_n) \right] = \mathbf{E}_{q(z_n \mid x_n; \theta)} \left[\nabla_{\theta} r(\theta, z_n, x_n) \right] + \int r(\theta, z_n, x_n) \nabla_{\theta} q(z_n \mid x_n; \theta) d_{z_n}$$

1. sample $z_n \sim q(z_n | x_n; \theta) = \mathcal{N}(f(x_n)_1, f(x_n)_2)$, then compute average of $\nabla_{\theta} r(\theta, z_n, x_n)$

Gradient of ELBO

$$r(\theta, z_n, x_n) = \log \frac{p(x_n | z_n; \theta) p_0(z_n)}{q(z_n | x_n; \theta)}$$

Computing gradient:

$$\nabla_{\theta} \mathbf{E}_{q(z_n|x_n;\theta)} \left[r(\theta, z_n, x_n) \right] = \mathbf{E}_{q(z_n|x_n;\theta)} \left[\nabla_{\theta} r(\theta, z_n, x_n) \right] + \int r(\theta, z_n, x_n) \nabla_{\theta} q(z_n|x_n;\theta) d_{z_n}$$

2. rewrite as

$$\int r(\theta, z_n, x_n) \nabla_{\theta} q(z_n | x_n; \theta) d_{z_n} = \mathbb{E}_{q(z_n | x_n; \theta)} \left[r(\theta, z_n, x_n) \nabla_{\theta} \log q(z_n | x_n; \theta) \right]$$
then sample $z_n \sim q(z_n | x_n; \theta) = \mathcal{N}(f(x_n)_1, f(x_n)_2)$
compute average of $r(\theta, z_n, x_n) \nabla_{\theta} q(z_n | x_n; \theta)$

Problem — high variance

Reparameterization Trick

$$q(z_n | x_n; \theta) = \mathcal{N}(f(x_n)_1, f(x_n)_2) = \mathcal{N}(\mu_{\theta}(x_n), \Sigma_{\theta}(x_n))$$

Treating $\epsilon \sim N(0,1)$, standard Gaussian distribution, then

$$E_{q(z_n|x_n;\theta)}\left[r(\theta,z_n,x_n)\right] = E_{\epsilon \sim N(0,1)}\left[r(\theta,z_n,x_n)\right]$$

where
$$z_n = \Sigma_{\theta}^{\frac{1}{2}}(x_n)\epsilon + \mu_{\theta}(x_n)$$

Taking gradient does not depend on the distribution

Reparameterization Trick

$$\begin{split} &\nabla_{\theta} \mathbf{E}_{q(z_{n}|x_{n};\theta)} \left[\log \frac{p(x_{n}|z_{n};\theta)p_{0}(z_{n})}{q(z_{n}|x_{n};\theta)} \right] \\ &= \nabla_{\theta} \mathbf{E}_{q(z_{n}|x_{n};\theta)} \left[\log p(x_{n}|z_{n};\theta) \right] - \mathrm{KL} \left(q(z_{n}|x_{n};\phi) \| p_{0}(z_{n}) \right) \\ &= \nabla_{\theta} \mathbf{E}_{e \sim N(0,1)} \left[\log p(x_{n}|z_{n};\theta) \right] - \mathrm{KL} \left(\mathcal{N}(\mu_{\theta}(x_{n}), \Sigma_{\theta}(x_{n})) \| \mathcal{N}(0,1) \right) \\ &= \nabla_{\theta} \mathbf{E}_{e \sim N(0,1)} \left[\log p(x_{n}|z_{n};\theta) \right] - \frac{1}{2} \left(\mu_{\theta}(x_{n})^{T} \mu_{\theta}(x_{n}) + \mathrm{tr}(\Sigma_{\theta})(x_{n}) - M - \mathrm{logDet}(\Sigma_{\theta}(x_{n})) \right) \\ &= \mathbf{E}_{e \sim N(0,1)} \left[\nabla_{\theta} \log p(x_{n}|z_{n};\theta) \right] - \nabla_{\theta} \frac{1}{2} \left(\mu_{\theta}(x_{n})^{T} \mu_{\theta}(x_{n}) + \mathrm{tr}(\Sigma_{\theta}(x_{n})) - M - \mathrm{logDet}(\Sigma_{\theta}(x_{n})) \right) \\ &\text{where } \mathcal{Z}_{n} = \sum_{\theta} \frac{1}{2} \left(x_{n} \right) \mathcal{E} + \mu_{\theta} \left(x_{n} \right) \end{split}$$

Compute Gradient using Reparameterization Trick

For each data point x_n, current parameter θ

Step 1: sample $\epsilon \sim N(0,1)$

Step 2: using encoder forward to compute μ , $\Sigma = f_{\rm enc}(x_n; \theta)$

Step 3:
$$z(\theta) = \sum_{i=1}^{1} \epsilon_i + \mu_i$$

Step 4: using decoder forward to compute $p(x_n | z(\theta); \theta)$

Step 5: define

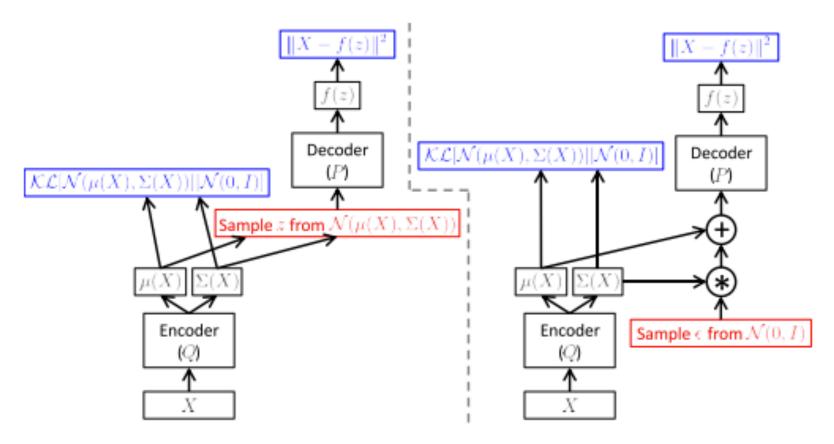
$$\operatorname{err} = \log p(x_n \,|\, z_n; \theta) - \beta \cdot \operatorname{KL} \left(q(z \,|\, x_n; \theta) || p_0(z) \right)$$
 , then

using back-propagation to compute gradient for θ \uparrow

$$\frac{1}{2} \left(\mu_{\theta}(x_n)^T \mu_{\theta}(x_n) + \operatorname{tr}(\Sigma_{\theta})(x_n) - M - \operatorname{logDet}(\Sigma_{\theta}(x_n)) \right)$$

Training VAE

Reparameterization trick

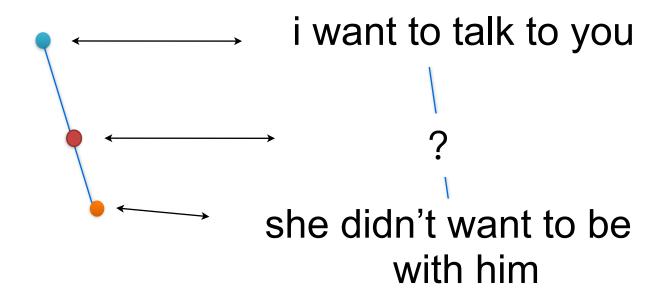


Tutorial on Variational Autoencoders (Doersch Carl, 2016)

Sentence VAE

Generating Sentence from Continuous vectors

 Key challenge: Interpolation in continuous space should yield reasonable sentences



Conditional Sequence Generation

Given a latent variable z, a sequence of text tokens $x = (x_1, x_2, ..., x_t)$ can be generated with RNN (or LSTM, transformer), CRNN model:

$$p(x | z; \theta) = \prod_{t} p(x_{t} | x_{t}, z; \theta)$$

$$p(x_{t} | x_{t}, z; \theta) = \operatorname{softmax}(W \cdot h_{t})$$

$$h_{t} = RNN(h_{t-1}, [x_{t-1}, z], \theta)$$

VAE for Sentence Generation

Decoding:

 $z \sim N(0, I)$

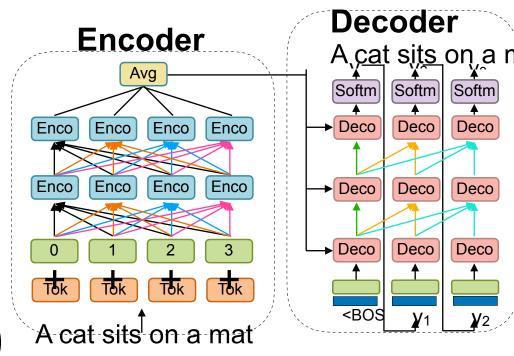
generate x from Transformer(z) or LSTM(z)

Encoding:

$$q(z \mid x) = N(\mu, \sigma^2)$$

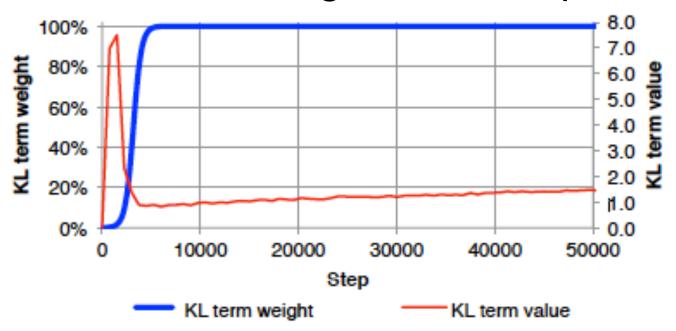
 $\mu = W_1 \cdot h_t, \ \sigma^2 = \exp W_2 \cdot h_t$

 $h_t = \text{Transformer}(x; \theta)$



Training VAE: Posterior Collapse

- KL term in ELBO collapses to zero and latent variable encodes little information.
- Solution: KL annealing & word dropout



Examples on Sentence Interpolation

```
"i want to talk to you."

"i want to be with you."

"i do n't want to be with you."

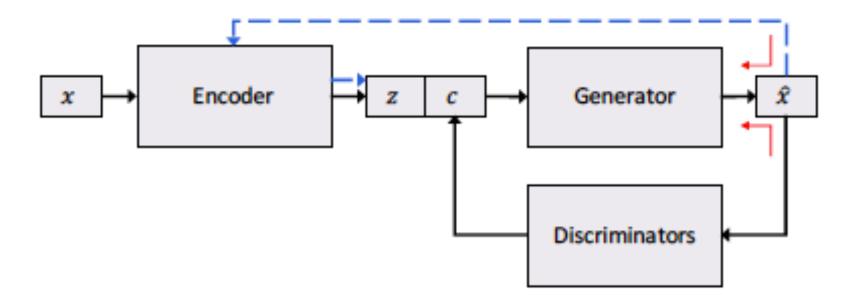
i do n't want to be with you.

she did n't want to be with him.
```

he was silent for a long moment. he was silent for a moment. it was quiet for a moment. it was dark and cold. there was a pause. it was my turn.

Variants

Controllable sentence generation with both continuous and discrete labels



Toward Controlled Generation of Text, (Hu et. al. ICML 2017)

Generating with Varying Semantic Label

the film is strictly routine! the film is full of imagination.

after watching this movie, i felt that disappointed. after seeing this film, i 'm a fan.

the acting is uniformly bad either.
the performances are uniformly good.

this is just awful. this is pure genius. the acting is bad. the movie is so much fun.

none of this is very original. highly recommended viewing for its courage, and ideas.

too bland highly watchable

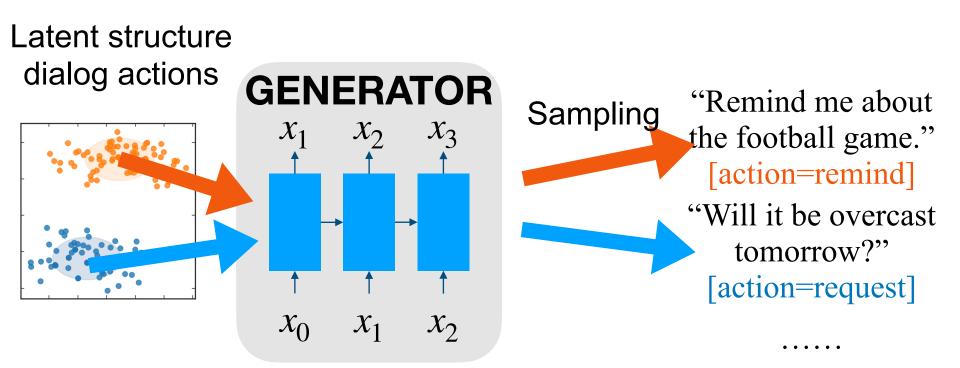
i can analyze this movie without more than three words . i highly recommend this film to anyone who appreciates music .

Toward Controlled Generation of Text, (Hu et. al. ICML 2017)

Deep Latent Variable Models for Text

- Interpretable Deep Latent Representation from Raw Text
 - Learning Exponential Family Mixture VAE [ICML 20]
- Disentangled Representation Learning for Text Generation
 - Data to Generation: VTM [ICLR 20b]
 - Learning syntax-semantic representation [ACL 19c]
- One model to acquire 4 language skills
 - Mirror Generative NMT [ICLR 20a]

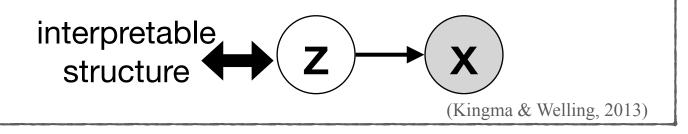
Learning Interpretable Latent Representation



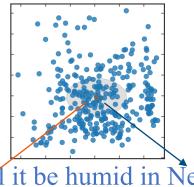
Generate Sentences with interpretable factors

How to Interpret Latent Variables in VAEs?

Variational Auto-encoder (VAE)



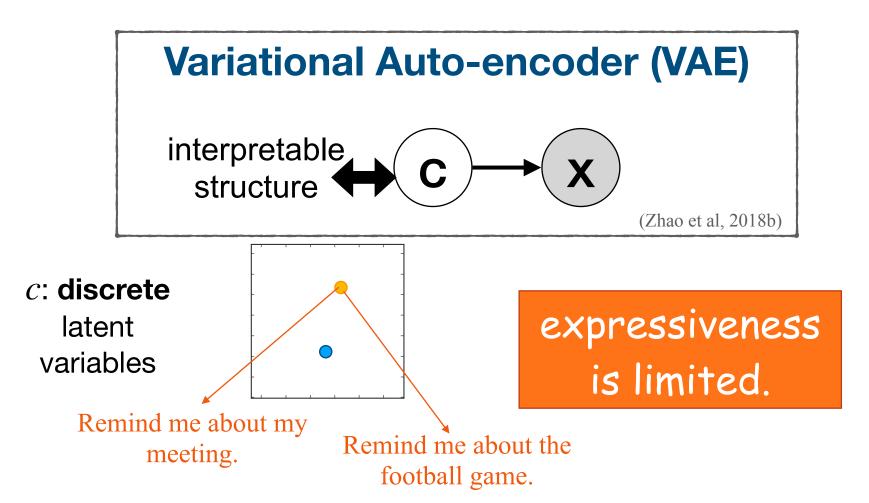
z:
continuou
s latent
variables



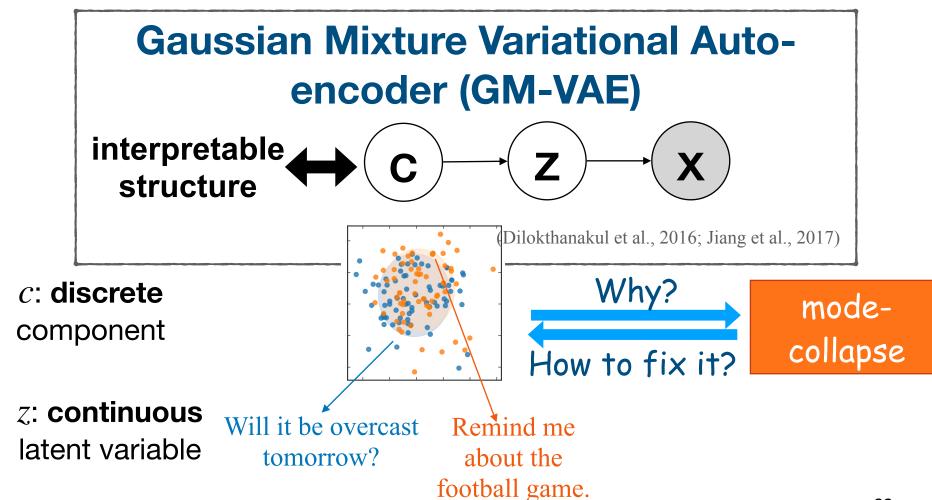
difficult to interpret discrete factors

Will it be humid in New York today? Remind me about my meeting.

VAEs Introduce Latent Variables

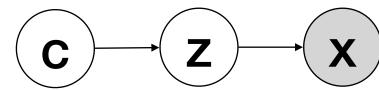


Discrete Variables Could Enhance Interpretability - but one has to do it right!



Do it right for VAE w/ hierarchical priors - Dispersed Exponential-family Mixture VAE

Exponential-family Mixture VAE



adding dispersion term in training

Dispersed EM-VAE

$$L(\theta; x) = \text{ELBO} + \beta \cdot L_d,$$

dispersion term

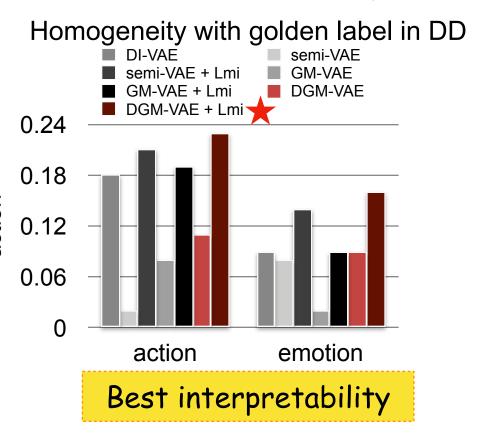
$$L_d = \mathbb{E}_{q_{\phi}(c|x)} A(\boldsymbol{\eta}_c) - \widehat{A}(\mathbb{E}_{q_{\phi}(c|x)} \boldsymbol{\eta}_c).$$

DEM-VAE [W. Shi, H. Zhou, N. Miao, Lei Li, ICML 2020]

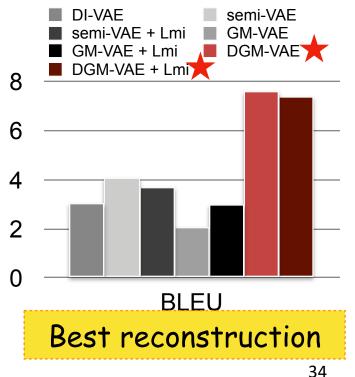
B3

Generation Quality and Interpretability

DGM-VAE obtains the best performance in interpretability and reconstruction



BLEU of reconstruction in DD



Latent Variables Learned by DEM-VAE are Semantically Meaningful

Example actions and corresponding utterances (classified by $q_{\phi}(c \mid x)$)

Inferred action=Inform-route/address

"There is a Safeway 4 miles away."

"There are no hospitals within 2 miles."

"There is Jing Jing and PF Changs."

. . .

Inferred action = Request-weather

"What is the weather today?"

"What is the weather like in the city?"

"What's the weather forecast in New

York?"

. .

Utterances of the same actions could be assigned with the same discrete latent variable c.

Generate Sensible Dialog Response with DEM-VAE

Input Context

Sys: "Taking you to Chevron."

sampling different values of discrete latent variables

(action = thanks)

(action = request-address)

Predict

User: "Thank you car, let's go there!"

Predict

User: "What is the address?"

Responses with different actions are generated by sampling different values of discrete latent variables.

Summary

- Auto-Encoder: learning representation by reconstruction
- Variational Auto-Encoder: put prior on latent representation and use variational method to train

Next Up

Industrial talk on computer vision