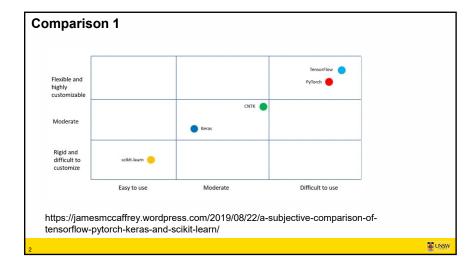


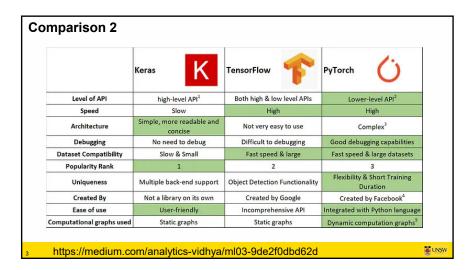
COMP9444: Neural Networks and Deep Learning

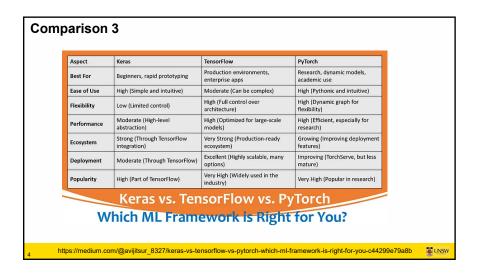
Week 2c. PyTorch

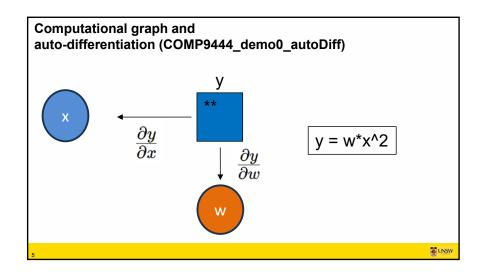
Raymond Louie

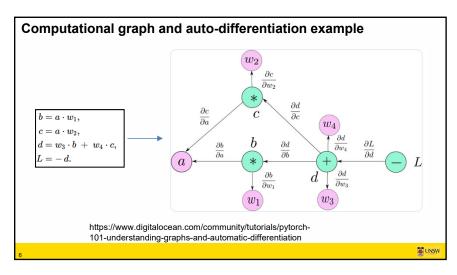
School of Computer Science and Engineering Feb 26, 2024

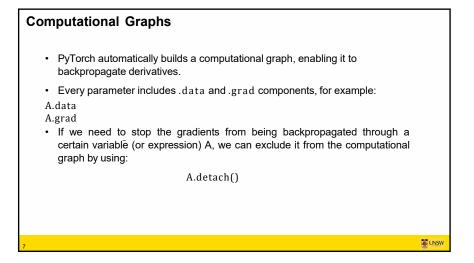


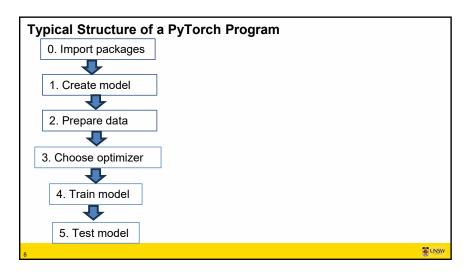


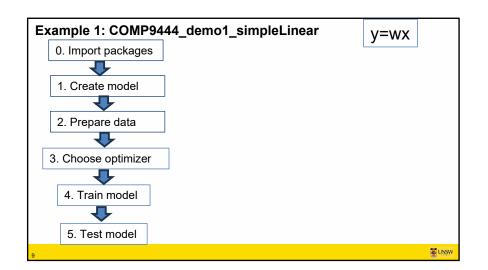


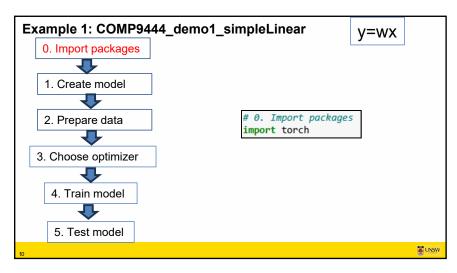


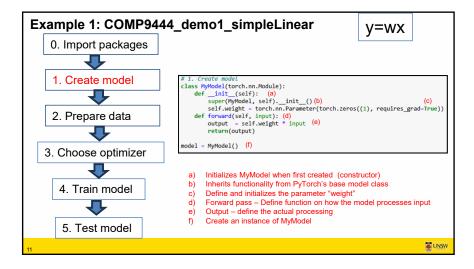


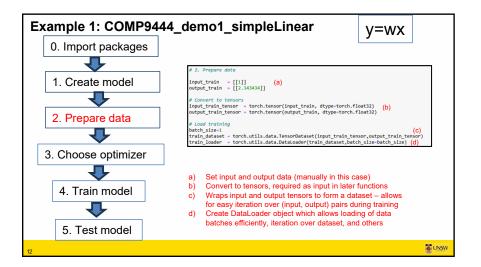


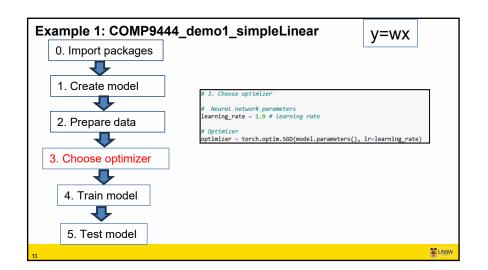


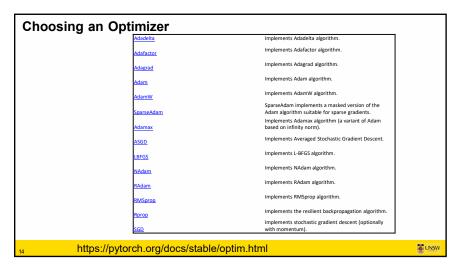


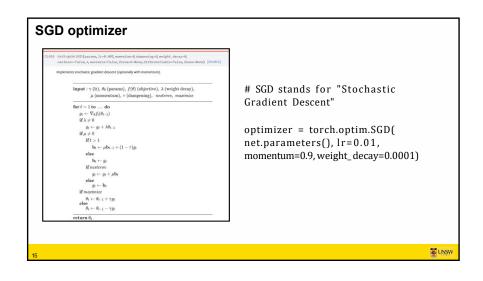


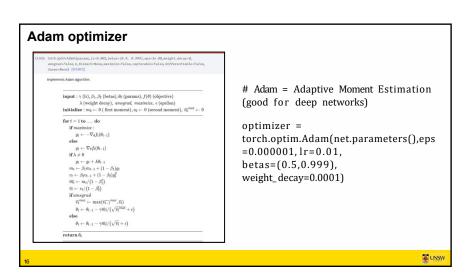


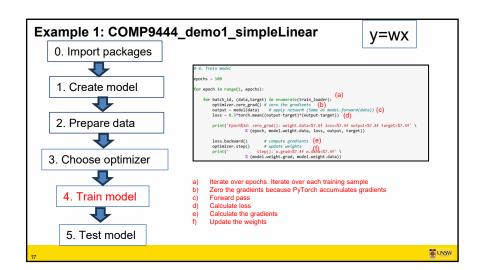


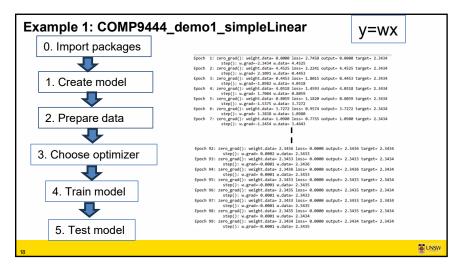


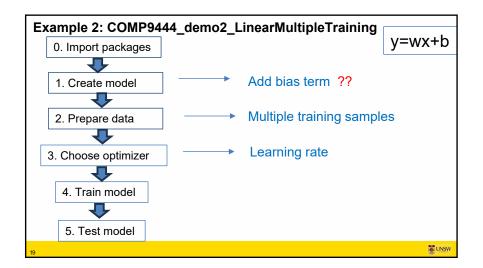


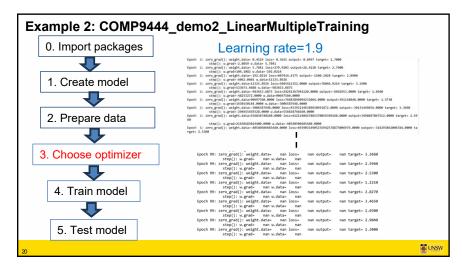


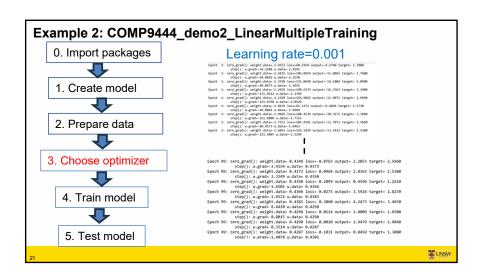


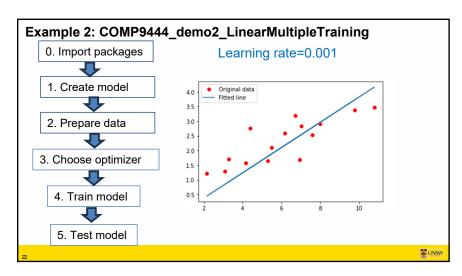


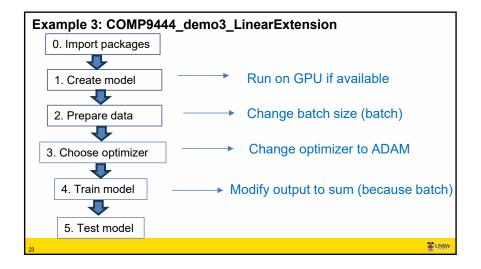


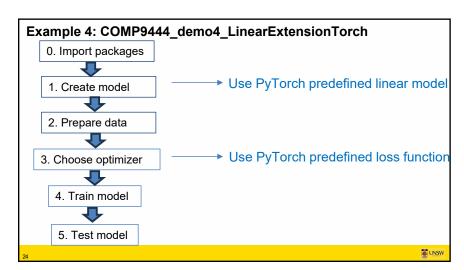


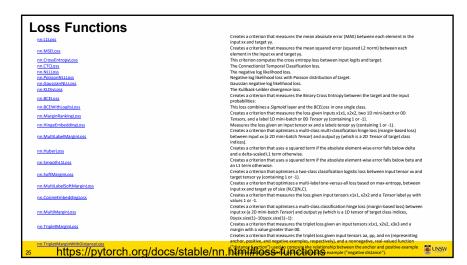


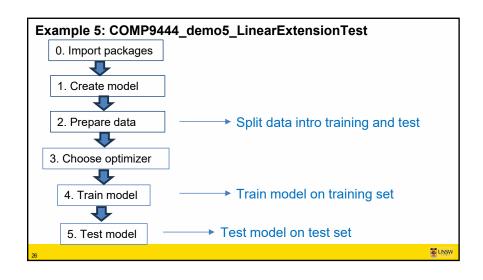


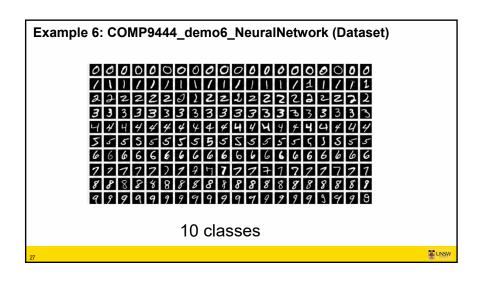


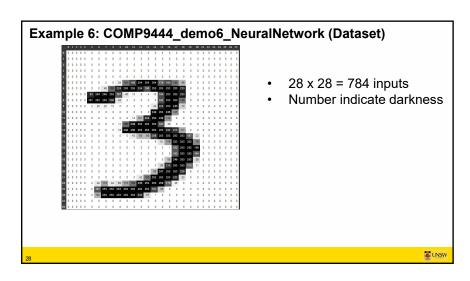


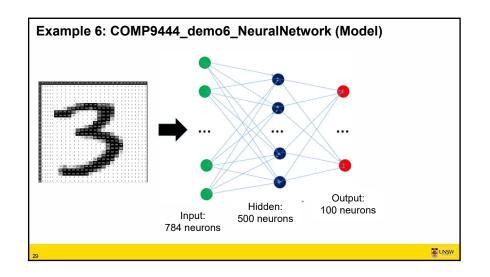


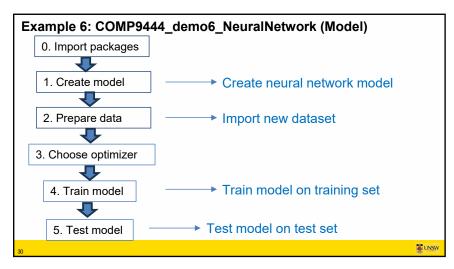












Sequential Components Network layers: - nn.Linear() - nn.Conv2d() (Week 4) Intermediate Operators: - nn.Dropout() - nn.BatchNorm() (Week 4) Activation Functions: - nn.Sigmoid() - nn.Tanh() - nn.ReLU() (Week 3)

More on the computational graph optimizer.zero grad() sets all .grad components to zero. loss.backward() updates the .grad component of all Parameters by backpropagating gradients through the computational graph. optimizer.step() updates the .data components. By default, loss.backward() discards the computational graph after computing the gradients. If needed, we can force it to keep the computational graph by calling it this way: loss.backward(retain graph=True)

In summary... -

```
# create neural network
net = MyNetwork().to(device) # CPU or GPU
# prepare to load the training and test data
train_loader = torch.utils.data.DataLoader(...)
test_loader = torch.utils.data.DataLoader(...)

# choose between SGD, Adam or other optimizer
optimizer = torch.optim.SGD(net.parameters,...)

for epoch in range(1, epochs): # training loop
    train(args, net, device, train loader, optimizer)
    # periodically evaluate network on test data
    if epoch %10 == 0:
        test( args, net, device, test loader)
```

```
Class MyNetwork(torch.nn.Module):

def __init__(self):
    super(MyNetwork, self). _init _()
    # define structure of the network here

def forward(self, input):
    # apply network and return output
```

```
import torch.utils.data

# input and target values for the XOR task
input = torch.Tensor([[0,0],[0,1],[1,0],[1,1]])
target = torch.Tensor([[0],[1],[1],[0]])

xdata = torch.utils.data.TensorDataset(input,target)
train_loader = torch.utils.data.DataLoader(xdata,batch size=4)
```

import pandas as pd df = pd.read_csv("sonar.all-data.csv") df = df.replace('R',0) df = df.replace('M',1) data = torch.tensor(df.values,dtype=torch.float32) num_input = data.shape[1] - 1 input = data[:,0:num_input] target = data[:,num_input:num_input+1] dataset = torch.utils.data.TensorDataset(input,target)

```
from data import ImageFolder

# load images from a specified directory
dataset = ImageFolder(folder, transform)

import torchvision.datasets as dsets

# download popular image datasets remotely
mnistset = dsets.MNIST(...)
cifarset = dsets.CIFAR10(...)
celebset = dsets.CelebA(...)
```

```
Training

def train(args, net, device, train Joader, optimizer):

for batch idx, (data,target) in enumerate(train loader):

optimizer.zero_grad()  # zero the gradients
output = net(data)  # apply network
loss = ...  # compute loss function
loss.backward()  # compute gradients
optimizer.step()  # update weights
```

Loss Functions loss = torch.sum((output-target)*(output-target)) loss = F.nll_loss(output,target) # (Week 3) loss = F.binary_cross_entropy(output,target) # (Week 3) loss = F.softmax(output,dim=1) # (Week 3) loss = F.log_softmax(output,dim=1) # (Week 3)