

# COMP9444: Neural Networks and Deep Learning

Week 2c. PyTorch

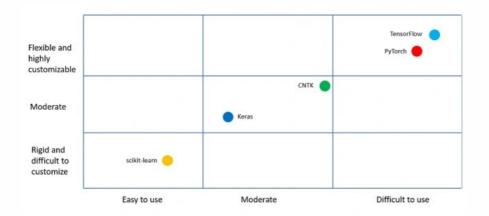
### Raymond Louie

School of Computer Science and Engineering

Feb 26, 2024

1

### **Comparison 1**



https://jamesmccaffrey.wordpress.com/2019/08/22/a-subjective-comparison-of-tensorflow-pytorch-keras-and-scikit-learn/



### **Comparison 2**

	Keras K	TensorFlow	PyTorch C	
Level of API	high-level API <sup>1</sup>	Both high & low level APIs	Lower-level API <sup>2</sup>	
Speed	Slow	High	High	
Architecture	Simple, more readable and concise	Not very easy to use	Complex <sup>3</sup>	
Debugging	No need to debug	Difficult to debugging	Good debugging capabilities	
Dataset Compatibility	Slow & Small	Fast speed & large	Fast speed & large datasets	
Popularity Rank	1	2	3	
Uniqueness	Multiple back-end support	Object Detection Functionality	Flexibility & Short Training Duration	
Created By	Not a library on its own	Created by Google	Created by Facebook <sup>4</sup>	
Ease of use	User-friendly	Incomprehensive API	Integrated with Python language	
Computational graphs used	Static graphs	Static graphs	Dynamic computation graphs <sup>5</sup>	



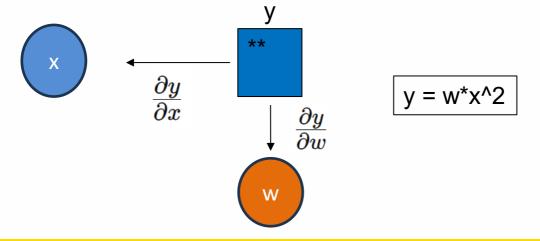
### **Comparison 3**

Aspect	Keras	TensorFlow	PyTorch
Best For	Beginners, rapid prototyping	Production environments, enterprise apps	Research, dynamic models, academic use
Ease of Use	High (Simple and intuitive)	Moderate (Can be complex)	High (Pythonic and intuitive)
Flexibility	Low (Limited control)	High (Full control over architecture)	High (Dynamic graph for flexibility)
Performance	Moderate (High-level abstraction)	High (Optimized for large-scale models)	High (Efficient, especially for research)
Ecosystem	Strong (Through TensorFlow integration)	Very Strong (Production-ready ecosystem)	Growing (Improving deployment features)
Deployment	Moderate (Through TensorFlow)	Excellent (Highly scalable, many options)	Improving (TorchServe, but less mature)
Popularity	High (Part of TensorFlow)	Very High (Widely used in the industry)	Very High (Popular in research)

Which ML Framework is Right for You?

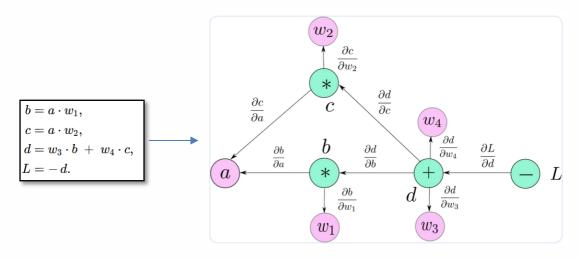


# Computational graph and auto-differentiation (COMP9444\_demo0\_autoDiff)





### Computational graph and auto-differentiation example



https://www.digitalocean.com/community/tutorials/pytorch-101-understanding-graphs-and-automatic-differentiation



### **Computational Graphs**

- PyTorch automatically builds a computational graph, enabling it to backpropagate derivatives.
- Every parameter includes .data and .grad components, for example:

A.data

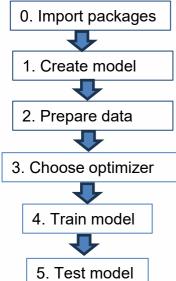
A.grad

 If we need to stop the gradients from being backpropagated through a certain variable (or expression) A, we can exclude it from the computational graph by using:

A.detach()



### **Typical Structure of a PyTorch Program**



y=wx

0. Import packages



1. Create model



2. Prepare data



3. Choose optimizer



4. Train model











1. Create model



2. Prepare data



3. Choose optimizer



4. Train model



5. Test model

# 0. Import packages import torch



0. Import packages



1. Create model



2. Prepare data



3. Choose optimizer



4. Train model



```
# 1. Create model
class MyModel(torch.nn.Module):
    def __init__(self): (a)
        super(MyModel, self).__init__() (b)
        self.weight = torch.nn.Parameter(torch.zeros((1), requires_grad=True))
    def forward(self, input): (d)
        output = self.weight * input (e)
        return(output)

model = MyModel() (f)
```

- a) Initializes MyModel when first created (constructor)
- b) Inherits functionality from PyTorch's base model class
- c) Define and initializes the parameter "weight"
- d) Forward pass Define function on how the model processes input
- e) Output define the actual processing
- f) Create an instance of MyModel





Import packages



1. Create model



2. Prepare data



3. Choose optimizer



4. Train model



```
# 2. Prepare data

input_train = [[1]] (a)

output_train = [[2.343434]]

# Convert to tensors

input_train_tensor = torch.tensor(input_train, dtype=torch.float32)

output_train_tensor = torch.tensor(output_train, dtype=torch.float32)

# Load training

batch_size=1

train_dataset = torch.utils.data.TensorDataset(input_train_tensor,output_train_tensor)

train_dataset = torch.utils.data.DataLoader(train_dataset,batch_size=batch_size) (d)
```

- a) Set input and output data (manually in this case)
- b) Convert to tensors, required as input in later functions
- Wraps input and output tensors to form a dataset allows for easy iteration over (input, output) pairs during training
- d) Create DataLoader object which allows loading of data batches efficiently, iteration over dataset, and others





0. Import packages



1. Create model



2. Prepare data



3. Choose optimizer



4. Train model



```
# 3. Choose optimizer

# Neural network parameters
learning_rate = 1.9 # learning rate

# Optimizer
optimizer = torch.optim.SGD(model.parameters(), lr=learning_rate)
```

### **Choosing an Optimizer**

<u>Adadelta</u>	Implements Adadelta algorithm.		
<u>Adafactor</u>	Implements Adafactor algorithm.		
Adagrad Adagrad	Implements Adagrad algorithm.		
Adam	Implements Adam algorithm.		
AdamW	Implements AdamW algorithm.		
SparseAdam	SparseAdam implements a masked version of the Adam algorithm suitable for sparse gradients.		
<u>Adamax</u>	Implements Adamax algorithm (a variant of Adam based on infinity norm).		
<u>ASGD</u>	Implements Averaged Stochastic Gradient Descent.		
<u>LBFGS</u>	Implements L-BFGS algorithm.		
NAdam NAdam	Implements NAdam algorithm.		
RAdam_	Implements RAdam algorithm.		
RMSprop	Implements RMSprop algorithm.		
Rprop	Implements the resilient backpropagation algorithm.		
SGD	Implements stochastic gradient descent (optionally with momentum).		



### **SGD** optimizer

```
CLASS torch.optim.SGD(params, 1x=0.001, momentum=0, dampening=0, weight_decay=0,
          nesterov=False, *, maximize=False, foreach=None, differentiable=False, fused=None) [SOURCE]
        Implements stochastic gradient descent (optionally with momentum)
                      input : \gamma (lr), \theta_0 (params), f(\theta) (objective), \lambda (weight decay),
                                   \mu (momentum), \tau (dampening), nesterov, maximize
                      for t = 1 to ... do
                          q_t \leftarrow \nabla_{\theta} f_t(\theta_{t-1})
                          if \lambda \neq 0
                               g_t \leftarrow g_t + \lambda \theta_{t-1}
                          if \mu \neq 0
                               ift > 1
                                    \mathbf{b}_t \leftarrow \mu \mathbf{b}_{t-1} + (1 - \tau)q_t
                                else
                                    \mathbf{b}_t \leftarrow g_t
                                if nesteron
                                    a_t \leftarrow a_t + \mu \mathbf{b}_t
                                else
                                    q_t \leftarrow \mathbf{b}_t
                           if maximize
                               \theta_t \leftarrow \theta_{t-1} + \gamma q_t
                                \theta_t \leftarrow \theta_{t-1} - \gamma q_t
                      return \theta_t
```

# SGD stands for "Stochastic Gradient Descent"

```
optimizer = torch.optim.SGD(
net.parameters(), lr=0.01,
momentum=0.9, weight_decay=0.0001)
```



### Adam optimizer

```
CLASS torch.optim.Adam(params, 1x=0.001, betas=(0.9, 0.999), eps=1e-08, weight_decay=0,
           amsgrad=False, *, foreach=None, maximize=False, capturable=False, differentiable=False,
           fused=None) [SOURCE]
          Implements Adam algorithm
                        input : \gamma (lr), \beta_1, \beta_2 (betas), \theta_0 (params), f(\theta) (objective)
                                      \lambda (weight decay), amsgrad, maximize, \epsilon (epsilon)
                        initialize: m_0 \leftarrow 0 (first moment), v_0 \leftarrow 0 (second moment), \widehat{v_0}^{max} \leftarrow 0
                         for t = 1 to ... do
                              if maximize:
                                   g_t \leftarrow -\nabla_{\theta} f_t(\theta_{t-1})
                              else
                                   q_t \leftarrow \nabla_{\theta} f_t(\theta_{t-1})
                             if \lambda \neq 0
                                   g_t \leftarrow g_t + \lambda \theta_{t-1}
                              m_t \leftarrow \beta_1 m_{t-1} + (1 - \beta_1) q_t
                              v_t \leftarrow \beta_0 v_{t-1} + (1 - \beta_0)q_t^2
                             \widehat{m_t} \leftarrow m_t / (1 - \beta_1^t)
                             \widehat{v_t} \leftarrow v_t/(1-\beta_2^t)
                             if amsarad
                                   \widehat{v_t}^{max} \leftarrow \max(\widehat{v_{t-1}}^{max}, \widehat{v_t})
                                   \theta_t \leftarrow \theta_{t-1} - \gamma \widehat{m_t} / (\sqrt{\widehat{v_t}^{max}} + \epsilon)
                                   \theta_t \leftarrow \theta_{t-1} - \gamma \widehat{m_t} / (\sqrt{\widehat{v_t}} + \epsilon)
                        return \theta_t
```

```
# Adam = Adaptive Moment Estimation (good for deep networks)
```

```
optimizer =
torch.optim.Adam(net.parameters(),eps
=0.000001, lr=0.01,
betas=(0.5,0.999),
weight_decay=0.0001)
```





Import packages



1. Create model



2. Prepare data



3. Choose optimizer



4. Train model



```
4. Train model
enochs = 100
for epoch in range(1, epochs):
   for batch id, (data, target) in enumerate(train loader):
       optimizer.zero grad() # zero the gradients (b)
       output = model(data) # apply network (Same as model.forward(data)) (C)
       loss = 0.5*torch.mean((output-target)*(output-target)) (d)
       print('Epoch%3d: zero grad(): weight.data=%7.4f loss=%7.4f output=%7.4f target=%7.4f' \
                     % (epoch, model, weight, data, loss, output, target))
       loss.backward()
                             # compute gradients (e)
                             # update weights
       optimizer.step()
       print('
                          step(): w.grad=%7.4f w.data=%7.4f' \
                     % (model.weight.grad, model.weight.data))
```

- a) Iterate over epochs. Iterate over each training sample
- b) Zero the gradients because PyTorch accumulates gradients
- c) Forward pass
- d) Calculate loss
- e) Calculate the gradients
- f) Update the weights





0. Import packages



1 Create model



2. Prepare data



3. Choose optimizer



4. Train model



5. Test model

Epoch 1: zero grad(): weight.data= 0.0000 loss= 2.7458 output= 0.0000 target= 2.3434 step(): w.grad=-2.3434 w.data= 4.4525

Epoch 2: zero grad(): weight.data= 4.4525 loss= 2.2241 output= 4.4525 target= 2.3434 step(): w.grad= 2.1091 w.data= 0.4453

Epoch 3: zero grad(): weight.data= 0.4453 loss= 1.8015 output= 0.4453 target= 2.3434 step(): w.grad=-1.8982 w.data= 4.0518

Epoch 4: zero grad(): weight.data= 4.0518 loss= 1.4593 output= 4.0518 target= 2.3434 step(): w.grad= 1.7084 w.data= 0.8059

Epoch 5: zero grad(): weight.data= 0.8059 loss= 1.1820 output= 0.8059 target= 2.3434 step(): w.grad=-1.5375 w.data= 3.7272

Epoch 6: zero grad(): weight.data= 3.7272 loss= 0.9574 output= 3.7272 target= 2.3434 step(): w.grad= 1.3838 w.data= 1.0980

Epoch 7: zero grad(): weight.data= 1.0980 loss= 0.7755 output= 1.0980 target= 2.3434 step(): w.grad=-1.2454 w.data= 3.4643



Epoch 92: zero grad(): weight.data= 2.3436 loss= 0.0000 output= 2.3436 target= 2.3434 step(): w.grad= 0.0002 w.data= 2.3433

Epoch 93: zero grad(): weight.data= 2.3433 loss= 0.0000 output= 2.3433 target= 2.3434 step(): w.grad=-0.0001 w.data= 2.3436

Epoch 94: zero grad(): weight.data= 2.3436 loss= 0.0000 output= 2.3436 target= 2.3434 step(): w.grad= 0.0001 w.data= 2.3433 Epoch 95: zero grad(): weight.data= 2.3433 loss= 0.0000 output= 2.3433 target= 2.3434

step(): w.grad=-0.0001 w.data= 2.3435 Epoch 96: zero grad(): weight.data= 2.3435 loss= 0.0000 output= 2.3435 target= 2.3434

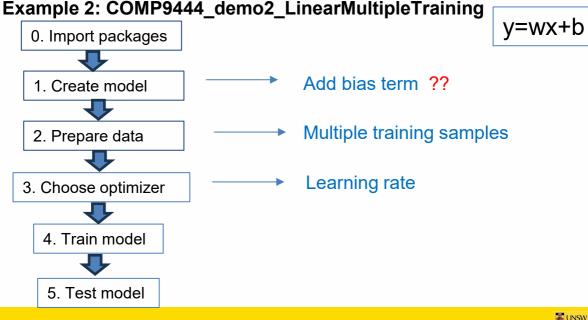
step(): w.grad= 0.0001 w.data= 2.3433 Epoch 97: zero grad(): weight.data= 2.3433 loss= 0.0000 output= 2.3433 target= 2.3434

step(): w.grad=-0.0001 w.data= 2.3435 Epoch 98: zero grad(): weight.data= 2.3435 loss= 0.0000 output= 2.3435 target= 2.3434

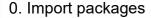
step(): w.grad= 0.0001 w.data= 2.3434 Epoch 99: zero grad(): weight.data= 2.3434 loss= 0.0000 output= 2.3434 target= 2.3434

step(): w.grad=-0.0001 w.data= 2.3435





### Example 2: COMP9444\_demo2\_LinearMultipleTraining





1. Create model



2. Prepare data



3. Choose optimizer



4. Train model



Test model

### Learning rate=1.9

Epoch 1: zero\_grad(): weight.data= 0.4529 loss= 0.3615 output= 0.8497 target= 1.7000 step(): w.grad=-2.8059 w.data= 5.7841

Epoch 1: zero\_grad(): weight.data=-192.0214 loss=607414.4375 output=-1100.1028 target= 2.0900 step(): w.grad=-6062.0601 w.data=11325.8926

Epoch 1: zero\_grad(): weight.data=11325.8926 loss=3045412352.0000 output=78046.9219 target= 3.1900 step(): w.grad=523673.4688 w.data=-983653.6875

Epoch 1: zero\_grad(): weight.data=-983653.6875 loss=24241367941120.0000 output=-6962953.0000 target= 1.6940 step(): w.grad=-48253272.0000 w.data=90697560.0000

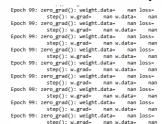
Epoch 1: zero\_grad(): weight.data=90697560.0000 loss=76483849894232064.0000 output=391110848.0000 target= 1.5730 step(): w.grad=1630150144.0000 v.drata=3005587648.0000 loss=60587648.0000 output=301110848.0000 target= 1.5730 step(): w.grad=1630150144.0000 v.drata=300587648.0000 loss=630574643389380991872.0000 output=30131449856.0000 target= 3.3660

step(): w.grad=-294655459328.0000 w.data=556838748160.0000

Epoch 1: zero\_grad(): weight.data=556838748160.0000 loss=6121140427883370059399168.0000 output=3498897047552.0000 target= 2.59

step(): w.grad-21630183014400.0000 w.data--40540506685440.0000

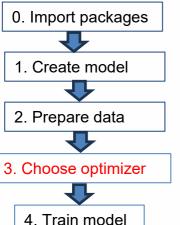
Epoch 1: zero\_grad(): weight.data--40540506685440.0000 loss-49308314905235942578875006976.0000 output--314293862006784.0000 target= 2.5300



nan	output=	nan	target=	3.3660
nan	output=	nan	target=	2.5960
nan	output=	nan	target=	2.5300
nan	output=	nan	target=	1.2210
nan	output=	nan	target=	2.8270
nan	output=	nan	target=	3.4650
nan	output=	nan	target=	1.6500
nan	output=	nan	target=	2.9040
nan	output=	nan	target=	1.3000



### Example 2: COMP9444\_demo2\_LinearMultipleTraining



5. Test model

### Learning rate=0.001

- Epoch 1: zero\_grad(): weight.data=-2.4553 loss=60.2364 output=-9.2760 target= 1.7000 step(): w.grad=-36.2208 w.data=-2.4191
  - Epoch 1: zero\_grad(): weight.data=-2.4191 loss=106.0914 output=-11.8065 target= 2.7600 step(): w.grad=-64.0926 w.data=-2.3550
- Epoch 1: zero\_grad(): weight.data=-2.3550 loss=131.0648 output=-14.1004 target= 2.0900 step(): w.grad=-80.0473 w.data=-2.2659
- Epoch 1: zero\_grad(): weight.data=-2.2659 loss=190.6374 output=-16.3363 target= 3.1900 step(): w.grad=-131.0212 w.data=-2.1349
- Epoch 1: zero\_grad(): weight.data--2.1349 loss-154.9022 output--15.9073 target- 1.6940 step(): w.grad--121.9768 w.data--2.0129

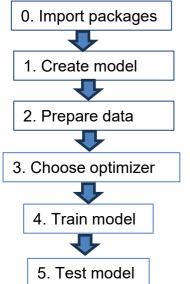
- Epoch 1: zero\_grad(): weight.data=-1.6463 loss=129.1424 output=-13.5412 target= 2.5300 step(): w.grad=-121.9807 w.data=-1.5244



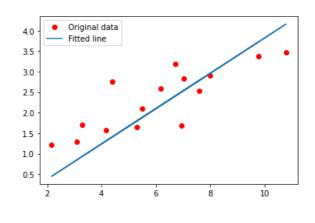
- Epoch 99: zero\_grad(): weight.data= 0.4373 loss= 0.0469 output= 2.8363 target= 2.5300 step(): w.grad= 2.3249 w.data= 0.4350
- Epoch 99: zero\_grad(): weight.data= 0.4350 loss= 0.2899 output= 0.4596 target= 1.2210
   step(): w.grad=-1.6501 w.data= 0.4366
- Epoch 99: zero\_grad(): weight.data= 0.4366 loss= 0.0275 output= 2.5924 target= 2.8270 step(): w.grad=-1.6522 w.data= 0.4383
- Epoch 99: zero\_grad(): weight.data= 0.4383 loss= 0.3060 output= 4.2473 target= 3.4650 step(): w.grad= 8.4420 w.data= 0.4298
- Epoch 99: zero\_grad(): weight.data= 0.4298 loss= 0.0114 output= 1.8009 target= 1.6500 step(): w.grad= 0.8015 w.data= 0.4290
- Epoch 99: zero\_grad(): weight.data= 0.4290 loss= 0.0010 output= 2.9479 target= 2.9040 sten(): w.grad= 0.3514 w.data= 0.4287
- Epoch 99: zero\_grad(): weight.data= 0.4287 loss= 0.1031 output= 0.8459 target= 1.3000 step(): w.grad=-1.4078 w.data= 0.4301



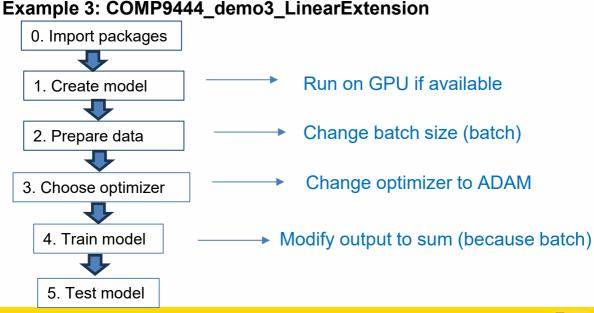
### Example 2: COMP9444\_demo2\_LinearMultipleTraining



### Learning rate=0.001







# Example 4: COMP9444 demo4 LinearExtensionTorch 0. Import packages Use PyTorch predefined linear model Create model 2. Prepare data Use PyTorch predefined loss function 3. Choose optimizer 4. Train model Test model

#### Loss Functions

nn.l 11 oss

nn.MSELoss

nn.CrossEntropyLoss

nn.CTCLoss

nn.NLLLoss

nn.PoissonNLLLoss

nn.GaussianNLLLoss

nn.KLDivLoss

nn.BCELoss

nn.BCEWithLogitsLoss

nn.MarginRankingLoss

nn.HingeEmbeddingLoss

nn.MultiLabelMarginLoss

nn.HuberLoss

nn.SmoothL1Loss

nn.SoftMarginLoss

nn.MultiLabelSoftMarginLoss

nn.CosineEmbeddingLoss

nn.MultiMarginLoss

nn.TripletMarginLoss

Creates a criterion that measures the mean absolute error (MAE) between each element in the input xx and target yy.

Creates a criterion that measures the mean squared error (squared L2 norm) between each element in the input xx and target vv.

This criterion computes the cross entropy loss between input logits and target.

The Connectionist Temporal Classification loss.

The negative log likelihood loss.

Negative log likelihood loss with Poisson distribution of target.

Gaussian negative log likelihood loss.

The Kullback-Leibler divergence loss.

Creates a criterion that measures the Binary Cross Entropy between the target and the input probabilities:

This loss combines a Sigmoid layer and the BCELoss in one single class.

Creates a criterion that measures the loss given inputs x1x1, x2x2, two 1D mini-batch or 0D

Tensors, and a label 1D mini-batch or 0D Tensor vv (containing 1 or -1).

Measures the loss given an input tensor xx and a labels tensor yy (containing 1 or -1).

Creates a criterion that optimizes a multi-class multi-classification hinge loss (margin-based loss) between input xx (a 2D mini-batch Tensor) and output vy (which is a 2D Tensor of target class indices).

Creates a criterion that uses a squared term if the absolute element-wise error falls below delta and a delta-scaled L1 term otherwise

Creates a criterion that uses a squared term if the absolute element-wise error falls below beta and an I 1 term otherwise.

Creates a criterion that optimizes a two-class classification logistic loss between input tensor xx and target tensor vv (containing 1 or -1).

Creates a criterion that optimizes a multi-label one-versus-all loss based on max-entropy, between input xx and target vv of size (N.C)(N.C).

Creates a criterion that measures the loss given input tensors x1x1, x2x2 and a Tensor label yy with values 1 or -1.

Creates a criterion that optimizes a multi-class classification hinge loss (margin-based loss) between input xx (a 2D mini-batch Tensor) and output vy (which is a 1D tensor of target class indices.

 $0 \le v \le x$ , size(1)-10 $\le v \le x$ , size(1)-1):

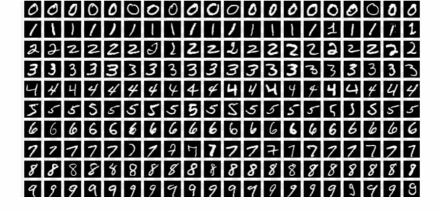
Creates a criterion that measures the triplet loss given an input tensors x1x1, x2x2, x3x3 and a margin with a value greater than 00.

Creates a criterion that measures the triplet loss given input tensors aa, pp, and nn (representing anchor, positive, and negative examples, respectively), and a nonnegative, real-valued function

# Example 5: COMP9444\_demo5\_LinearExtensionTest Import packages Create model 2. Prepare data Split data intro training and test 3. Choose optimizer Train model on training set 4. Train model Test model on test set Test model



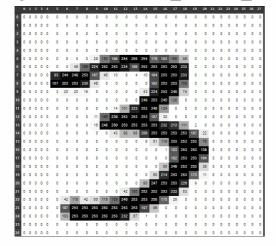
### Example 6: COMP9444\_demo6\_NeuralNetwork (Dataset)



10 classes

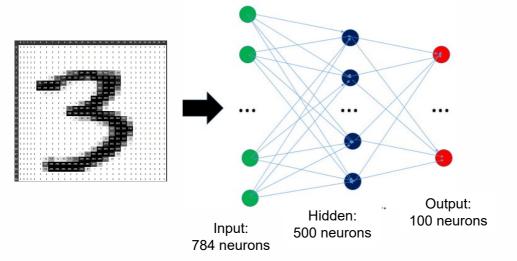


### Example 6: COMP9444\_demo6\_NeuralNetwork (Dataset)



- 28 x 28 = 784 inputs
- Number indicate darkness

### Example 6: COMP9444\_demo6\_NeuralNetwork (Model)





# Example 6: COMP9444 demo6 NeuralNetwork (Model) Import packages Create model Create neural network model 2. Prepare data Import new dataset 3. Choose optimizer Train model on training set 4. Train model Test model on test set Test model

### **Sequential Components**

### Network layers:

- → nn.Linear()
- nn.Conv2d() (Week 4)

#### Intermediate Operators:

- → nn.Dropout()
- nn.BatchNorm() (Week 4)

#### **Activation Functions:**

- → nn.Sigmoid()
- → nn.Tanh()
- → nn.ReLU() (Week 3)



### More on the computational graph

- optimizer.zero grad() sets all .grad components to zero.
- loss.backward() updates the .grad component of all Parameters by backpropagating gradients through the computational graph.
- optimizer.step() updates the .data components.
- By default, loss.backward() discards the computational graph after computing the gradients.
- If needed, we can force it to keep the computational graph by calling it this way:

loss.backward(retain graph=True)



### In summary...

\_



### Typical Structure of a PyTorch Program

```
# create neural network
net = MyNetwork().to(device) # CPU or GPU
# prepare to load the training and test data
train_loader = torch.utils.data.DataLoader(...)
test loader = torch.utils.data.DataLoader(...)
# choose between SGD, Adam or other optimizer
optimizer = torch.optim.SGD(net.parameters,...)
for epoch in range(1, epochs): # training loop
    train(args, net, device, train loader, optimizer)
    # periodically evaluate network on test data
    if epoch \% 10 == 0:
        test( args, net, device, test_loader)
```

### **Defining a Network Structure**

```
class MyNetwork(torch.nn.Module):
    def __init__(self):
        super(MyNetwork, self). _init __()
        # define structure of the network here
    def forward(self, input):
        # apply network and return output
```



### **Declaring Data Explicitly**

```
import torch.utils.data
# input and target values for the XOR task
input = torch.Tensor([[0,0],[0,1],[1,0],[1,1]])
target = torch.Tensor([[0],[1],[1],[0]])
xdata = torch.utils.data.TensorDataset(input,target)
train_loader = torch.utils.data.DataLoader(xdata,batch size=4)
```



### **Loading Data from a .csv File**

```
import pandas as pd
df = pd.read_csv("sonar.all-data.csv")
df = df.replace('R',0)
df = df.replace('M',1)
data = torch.tensor(df.values,dtype=torch.float32)
num input = data.shape[1] - 1
input = data[:,0:num_input]
target = data[:,num input:num input+1]
dataset = torch.utils.data.TensorDataset(input,target)
```

### **Custom Datasets**

```
from data import ImageFolder
    # load images from a specified directory
    dataset = ImageFolder(folder, transform)

import torchvision.datasets as dsets
    # download popular image datasets remotely
    mnistset = dsets.MNIST(...)
    cifarset = dsets.CIFAR10(...)
    celebset = dsets.CelebA(...)
```



### **Choosing an Optimizer**



### **Training**

```
def train(args, net, device, train loader, optimizer):
   for batch idx, (data,target) in enumerate(train loader):
      optimizer.zero_grad()  # zero the gradients
      output = net(data)  # apply network
      loss = ...  # compute loss function
      loss.backward()  # compute gradients
      optimizer.step()  # update weights
```



### **Loss Functions**

```
loss = torch.sum((output-target)*(output-target))
loss = F.nll_loss(output,target)  # (Week 3)
loss = F.binary_cross_entropy(output,target)  # (Week 3)
loss = F.softmax(output,dim=1)  # (Week 3)
loss = F.log_softmax(output,dim=1)  # (Week 3)
```



### **Testing**

```
def test(args, net, device, test loader):
    with torch.no_grad(): # suppress updating of gradients
        net.eval() # toggle batch norm, dropout
            for data, target in test_loader:
                 output = model(data)
                 test_loss = ...
                  print(test_loss)
        net.train() # toggle batch norm, dropout back again
```

