## ADT < MATRIX GRAPH >

< vertexIndexMap, vertices, adjacencyMatrix >

Graph (vertexIndexMap ∈ Map of vertices to indices, vertices ∈ List of vertices, adjacencyMatrix ∈ Edge[][])

- \* Primitive Operations:
- \* addVertex → V → Void
- \* addEdge →V x V →Void
- \* dfs →V →List<String>
- \* dijkstra →V →Map<V, Integer>
- \* updateMatrix → ()→Void
- \* getEdge →V x V →Edge<V>

# Operaciones:

# addVertex(vertex)

"Adds a vertex to the adjacency matrix"

 $\{Pre: vertex \in V\}$ 

{Post: Adds the vertex to the adjacency matrix}

# addEdge(from, to)

"Adds an edge from 'from' to 'to' in the adjacency matrix"

{Pre: from, to  $\in V$ }

{Post: Adds an edge from 'from' to 'to' in the adjacency matrix}

### dfs(start)

"Performs Depth-First Search (DFS) starting from the specified vertex"

 $\{Pre: start \in V\}$ 

{Post: Returns a list of vertices visited in DFS order}

## dijkstra(start)

"Performs Dijkstra's algorithm starting from the specified vertex"

 $\{Pre: start \in V\}$ 

{Post: Returns a map of vertices and their respective distances from the starting vertex}

updateMatrix()
"Updates the adjacency matrix when a new vertex is added"

{Pre: None}

{Post: Updates the adjacency matrix to include the new vertex}

getEdge(from, to)
"Gets the edge from 'from' to 'to' in the adjacency matrix"

 $\{Pre: from, to \in V\}$ 

{Post: Returns the edge from 'from' to 'to' or null if no edge exists}