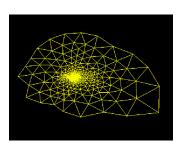
Cl583: Data Structures and Operating Systems Algorithmic strategies to solve NP-hard problems



Depth-first and breadth-first

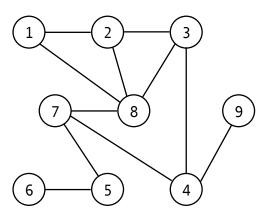
Many NP problems can be reduced to a problem in which the nodes in a graph must be visited exactly once – this is a more general idea of traversal, which we used with trees.

For instance, we may need to transmit a network packet to every computer on a network, making sure that no computer receives it twice.

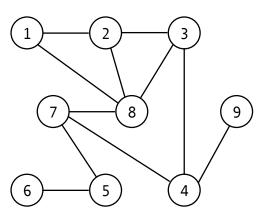
There are two ways we might do this: depth-first and breadth-first.

Depth-first and breadth-first

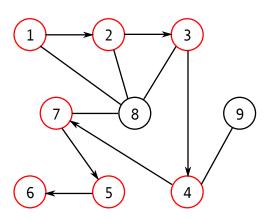
A depth-first traversal will go as far as possible down a given path before it considers any other. A breadth-first traversal goes evenly in many directions.



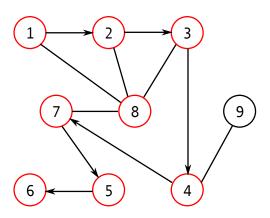
In a depth-first traversal, we visit the starting node then follow edges through the graph until we reach a dead-end. In an undirected graph a node is a dead end if all nodes adjacent to it have been visited. In a directed graph a node is also a dead end if it has no outgoing edges.



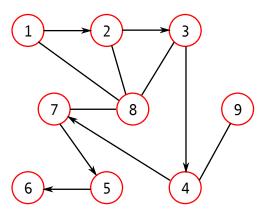
When we reach a dead end we go back up the path until we find a node with an unvisited adjacent node. One traversal of this graph starting at 1 reaches a dead end at 6: [1, 2, 3, 4, 7, 5, 6].

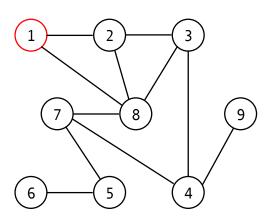


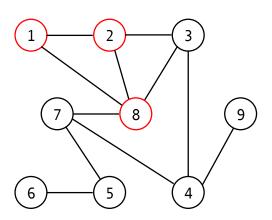
We then go back to node 7 and find that 8 is unvisited. We visit 8 and reach a dead end.

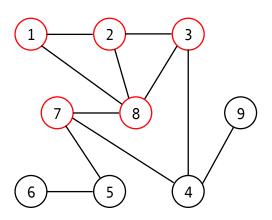


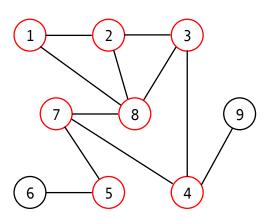
We then go back to 4 and find that 9 is unvisited. The next time we go back up the path we end up at the starting node and we are done.

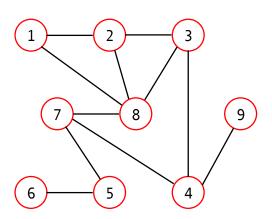






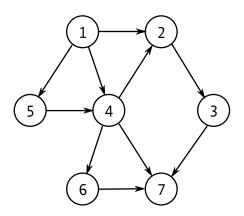






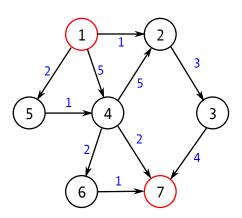
Traversal

Implementations of depth-first traversal often use a stack. Implementations of breadth-first traversal often use a queue. Give DF and BF traversals starting at the node labelled 1 for this directed graph:



Weighted graphs

Consider the problem of finding "cheapest" paths in a directed and weighted graph:



Minimum spanning trees

The problem of finding cheapest or shortest paths in a a weighted and connected graph reduces to that of finding the minimum spanning tree (MST). A spanning tree for a graph, G, contains all the nodes of G and a subset of the edges and has no cycles. A connected graph is one in which there is a path from every node to any other.

The MST for a graph, G, is a spanning tree in which the total of the edge weights is minimal.

We can calculate the MST by brute force – for n edges this takes 2^n comparisons between potential MSTs – this is an NP problem.