

ROS Package Stress Test

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Test setup

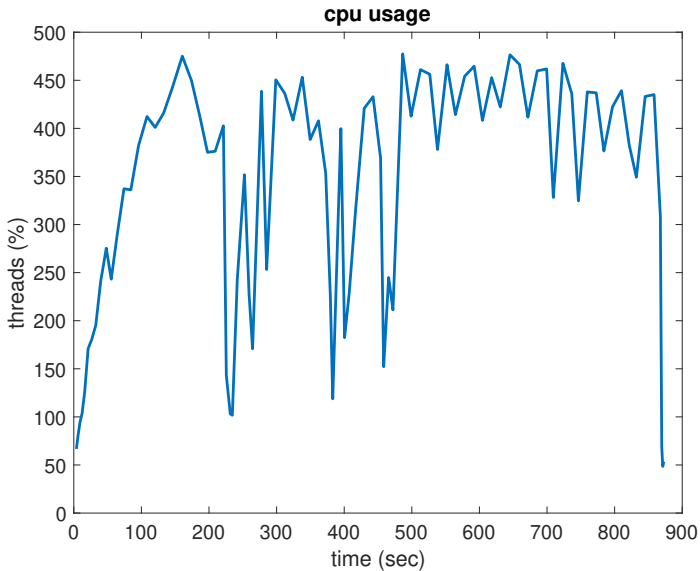
► Gaming laptop

- mot_realsense
- cartographer_ros
- teb_local_planner
- pointcloud_to_laserscan
- scan_unifier

► Simulation desktop

- gazebo_ros w/ 10ms step size
- two velodyne_gazebo_plugins w/ 20Hz

cartographer_ros usage



teb_local_planner usage (30Hz target frequency)

