



6. Explain the relation between

$\mathbf{b}$  is a linear combination of columns of  $A$ .  $\iff A\mathbf{x} = \mathbf{b}$  is consistent.

7. Explain the relation between

Every vector  $\mathbf{b}$  in  $\mathbb{R}^m$  is a linear combination of columns of  $A$ .  $\iff$  The columns of  $A$  span  $\mathbb{R}^m$ .

8. Why is the existence of at least one free variable for an equation equivalent to that  $A\mathbf{x} = \mathbf{0}$  has a nontrivial solution?

9. What are the concepts linearly INdependent and linearly dependent?

10. Why does every set containing the zero vector is always linearly dependent?

11. Explain the relation between

The columns of  $A$  form a linearly INdependent set.  $\iff A\mathbf{x} = \mathbf{0}$  has only the trivial solution.



16. What is the meaning of a map  $f$  being a linear transformation from  $\mathbb{R}^n$  to  $\mathbb{R}^m$ ?

17. Why is every matrix transformation a linear transformation?

18. Why do you only need images of  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$  to describe a linear transformation  $T$  from  $\mathbb{R}^2$  to  $\mathbb{R}^n$ ?

19. Explain the concept of a map being one-to-one (injective)? Once your map turns out to be a linear transformation, how can you change the condition for the map begin one-to-one?

20. Explain the concept of a map being onto (surjective)?

21. Explain the relation between

A matrix transformation is one-to-one.  $\iff$  The columns form a linearly INdependent set.

22. Explain the relation between

A matrix transformation is onto  $\mathbb{R}^m$ .  $\iff$  The columns span  $\mathbb{R}^m$ .

23. In terms of the multiplication of a matrix with a vector, explain how to multiply two matrices. What would be the condition for defining matrix multiplication?
24. What is the transpose of a matrix  $A$ ? (NOTE. By hand, you can prove that  $(AB)^T = B^T A^T$ . Let's just take the formula for granted.)
25. What is the inverse matrix of a matrix  $A$ ? What is the meaning of a matrix  $A$  being invertible? (NOTE. We only define the inverse matrix for a SQUARE matrix  $A$ .)
26. Why do we say “the” inverse matrix, not “a” inverse matrix?
27. Why is this true?

$$(AB)^{-1} = B^{-1}A^{-1}$$

28. Once you have the inverse matrix of  $A$ , how can you use the inverse matrix  $A^{-1}$  to find the solution for  $A\mathbf{x} = \mathbf{b}$ ?
29. Why is the RREF of an invertible matrix  $A$  the identity matrix? (Hint. Explain this in terms of “linear relations of columns”.)
30. Explain an algorithm for finding  $A^{-1}$  using row operations. Why does this hold?

31. What is a subspace of  $\mathbb{R}^n$ ? (NOTE. A subspace satisfies “linear combination condition.”)

32. What is  $\text{Col } A$ ? Explain why  $\text{Col } A$  is a subspace of  $\mathbb{R}^m$ .

33. What is  $\text{Nul } A$ ? Explain why  $\text{Nul } A$  is a subspace of  $\mathbb{R}^n$ .

34. What is a basis (for a subspace of  $\mathbb{R}^n$ )?

35. Why do we say “a” basis, not “the” basis?

36. How can you find a basis for  $\text{Col } A$  given the RREF of  $A$ ?

37. What is the dimension (of a subspace of  $\mathbb{R}^n$ )?
38. In terms of ‘the number of pivots’, what can you say about the dimension of  $\text{Col } A$  and  $\text{Nul } A$ ?
39. We can say that the dimension is the number of ‘maximal linearly independent vectors’. What does it mean?
40. What is the rank (of a matrix  $A$ )?
41. Why do we say “the” dimension and “the” rank, not “a“ of them?



42. Explain the change-of-basis matrix for two bases  $\mathcal{B}$  and  $\mathcal{C}$  of  $V$ . Specifically, explain how to get  $P_{\mathcal{C} \leftarrow \mathcal{B}}$  from the equation (= the definition)

$$[\mathbf{v}]_{\mathcal{C}} = P_{\mathcal{C} \leftarrow \mathcal{B}} [\mathbf{v}]_{\mathcal{B}}.$$

43. Given a linear transformation  $T : V \rightarrow W$ , explain what *the matrix for  $T$  relative to  $\mathcal{B}$  and  $\mathcal{C}$*  is. (Let's use the notation  $[T]_{\mathcal{B}}^{\mathcal{C}}$ .) The equation (= the definition) for this matrix is given by

$$[T(\mathbf{v})]_{\mathcal{C}} = [T]_{\mathcal{B}}^{\mathcal{C}} [\mathbf{v}]_{\mathcal{B}}.$$