

1. Mark “T” if the statement is always true, “F” if it is sometimes false. *No explanations are needed.*

- (T) | If W and W' are subspaces of a vector space V , the set of vectors in V that belong to both W and W' is a subspace of V .

- (F) | If A is similar to B and B is orthogonal then A must be orthogonal.

- (T) | For every subspace H of \mathbb{R}^n , there is a matrix A such that $H = \text{Nul } A$.

- (F) | If λ is an eigenvalue of A and μ is an eigenvalue of B and both are $n \times n$, then $\lambda\mu$ must be an eigenvalue of AB .

- (F) | The normal equation $A^T A \mathbf{x} = A^T \mathbf{b}$ always have a unique solution.

- (T) | The change-of-coordinates matrix $P_{\mathcal{C} \leftarrow \mathcal{B}}$ between the bases $\mathcal{B} = \{2e_1, 3e_2\}$ and $\mathcal{C} = \{-3e_1, 4e_2\}$ of \mathbb{R}^2 is a diagonal matrix.

- (T) | There exists a real 3×3 matrix of rank 2 with only one distinct eigenvalue.

- (F) | The set of vectors $[x_1 \ x_2 \ x_3]^T$ so that $x_1 + x_2 + x_3 \geq 0$ forms a subspace of \mathbb{R}^3 .

- (F) | If V is a vector space, and H_1 and H_2 are subspaces, then the union of H_1 and H_2 (i.e. the set of vectors that lie in H_1 or H_2) is always a subspace.

- (F) | The dimensions of the column space and of the nullspace of a matrix add up to the number of rows.

- (T) | Suppose that A is a symmetric $n \times n$ matrix and W is a subspace of \mathbb{R}^n such that $Aw \in W$ for all $w \in W$. Then, $Av \in W^\perp$ for all $v \in W^\perp$ where W^\perp is the orthogonal complement of W with respect to the dot product.

- (F) | Suppose that $v_1(t)$, $v_2(t)$ are vector functions taking values in \mathbb{R}^2 . If the Wronskian $W[v_1, v_2](t)$ is equal to 0 for all $t \in \mathbb{R}$, then $v_1(t)$, $v_2(t)$ are linearly dependent.

- (F) | The set of solutions to $ay'' + by' + cy = 0$ is a two-dimensional vector space for any $a, b, c \in \mathbb{R}$.

- (F) | The eigenvalues of an orthogonal matrix are all real.

- (T) | For any matrix A , the matrix AA^T is diagonalizable.

- (T) | The function $y(t) = t \sin t$ is a solution to $y''' + 2y'' + y = 0$.

2. Select the correct answers. Be aware that there might be more than one answer to each problem.

1) A number λ is an eigenvalue of an $n \times n$ matrix A if and only if:

- (a) $\det(A - \lambda I_n) = 0$.
- (b) λ is a pivot of A .
- (c) $A - \lambda I_n$ is invertible.
- (d) $A\mathbf{x} = \lambda\mathbf{x}$ for some $\mathbf{x} \in \mathbb{R}^n$.

2) A collection of n vectors $\mathbf{v}_1, \dots, \mathbf{v}_n$ in \mathbb{R}^n is linearly independent if and only if:

- (a) It forms a basis of \mathbb{R}^n .
- (b) Any two vectors in it are linearly independent.
- (c) $\mathbf{v}_1 + \dots + \mathbf{v}_n = \mathbf{0}$ implies that each $\mathbf{v}_i = \mathbf{0}$.
- (d) $c_1\mathbf{v}_1 + \dots + c_n\mathbf{v}_n = \mathbf{0}$ implies that each $c_i = 0$.

3) The rank of a matrix A is

- (a) The number of rows.
- (b) The dimension of its column space.
- (c) The dimension of its row space.
- (d) $\dim(\text{Row } A)^\perp$.

3. Find the general solution to the equation

$$y'' + 3y' + 2y = \frac{1}{e^t + 1}.$$

Homogeneous case solution : $y_1(t) = e^{-2t}$, $y_2(t) = e^{-t}$.

Use variation of parameters : $v_1(t) = \int \frac{-y_2 s}{W} dt$ and $v_2 = \int \frac{y_1 s}{W} dt$. $W = y_1 y_2' - y_1' y_2 = e^{-2t} \cdot (-1)e^{-t} - (-2)e^{-2t} \cdot e^{-t} = e^{-3t}$.

$$\text{So, } v_1(t) = \int -\frac{e^{-2t} \cdot e^{-t}}{e^{-3t}} dt = \int \frac{-e^{2t}}{e^{t+1}} dt = \int -\frac{2}{s+1} ds \quad (s = e^t, ds = e^t dt = s dt)$$

$$= \int \left(-1 + \frac{1}{s+1}\right) ds = -s + \ln(s+1) = -e^t + \ln(e^t + 1).$$

$$v_2(t) = \int \frac{e^{-2t} \cdot \frac{1}{e^t+1}}{e^{-3t}} dt = \int \frac{e^t}{e^t+1} dt = \ln(e^t+1) \quad (\text{bc } \int \frac{f'}{f} = \ln f)$$

General solution : $(-e^t + \ln(e^t+1)) \cdot e^{-2t} + \ln(e^t+1) \cdot e^{-t} + C_1 e^{-2t} + C_2 e^{-t}$.

4. Find the general solution to the following system:

$$\mathbf{x}'(t) = \begin{bmatrix} 1 & -6 \\ 1 & -4 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} 2 \\ 1 \end{bmatrix} t e^{-3t}.$$

Homogeneous case solution : Find eigenvalues and eigenvectors.

$$A = \begin{bmatrix} 1 & -6 \\ 1 & -4 \end{bmatrix}, \chi_A(\lambda) = \det(A - \lambda I) = (\lambda - 1)(\lambda + 4) + 6 = \lambda^2 + 3\lambda + 2.$$

$$\lambda = -1 \rightarrow \text{Nul } \begin{bmatrix} 2 & -6 \\ 1 & -3 \end{bmatrix} \ni \begin{bmatrix} 3 \\ 1 \end{bmatrix} \Rightarrow \mathbf{x}_1(t) = \begin{bmatrix} 3 \\ 1 \end{bmatrix} \cdot e^{-t}$$

$$\lambda = -2 \rightarrow \text{Nul } \begin{bmatrix} 3 & -6 \\ 1 & -2 \end{bmatrix} \ni \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \mathbf{x}_2(t) = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \cdot e^{-2t}$$

Particular solution : Method of Undetermined Coefficients

$$\mathbf{x}_p(t) = (ut + v) \cdot e^{-3t} \quad \text{6/c } \begin{bmatrix} 2 \\ 1 \end{bmatrix} t \cdot e^{-3t} \text{ is (poly of deg 1) } \times \text{ exponential.}$$

$$(\text{LHS}) = u \cdot e^{-3t} + (-3)(ut + v)e^{-3t} \quad (\text{RHS}) = A(ut + v)e^{-3t} + \begin{bmatrix} 2 \\ 1 \end{bmatrix} t e^{-3t}.$$

Cancel out e^{-3t} and look at the terms $\omega_1 t$ and $\omega_2 t$ separately.

$$\omega_1 t: -3u = Au + \begin{bmatrix} 2 \\ 1 \end{bmatrix} \Rightarrow (A + 3I)u = \begin{bmatrix} -2 \\ -1 \end{bmatrix} \quad u = \begin{bmatrix} -2 \\ -1 \end{bmatrix}.$$

$$\omega_2 t: u - 3v = Av \Rightarrow v = \begin{bmatrix} -2 \\ -1 \end{bmatrix}.$$

$$\text{General solution: } \left(\begin{bmatrix} -2 \\ -1 \end{bmatrix} t + \begin{bmatrix} -2 \\ -1 \end{bmatrix} \right) e^{-3t} + C_1 \begin{bmatrix} 3 \\ 1 \end{bmatrix} e^{-t} + C_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-2t}.$$

5. The system $\mathbf{x}'(t) = \begin{bmatrix} 2 & 3 \\ 0 & 2 \end{bmatrix} \mathbf{x}(t)$ has a solution $\mathbf{x}_1(t) = e^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$. Find another solution which is linearly independent to $\mathbf{x}_1(t)$. (Hint. Try $\mathbf{x}_2(t) = te^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + e^{2t} v$.)

Try $\mathbf{x}_2(t) = t \cdot e^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + e^{2t} v$.

$$(\text{LHS}) \quad e^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 2te^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 2e^{2t} v \quad (\text{RHS}) \quad A \begin{bmatrix} 1 \\ 0 \end{bmatrix} te^{2t} + Av \cdot e^{2t} \text{ where } A = \begin{bmatrix} 2 & 3 \\ 0 & 2 \end{bmatrix}.$$

Similarly to #4, we look at the terms $\omega_1 t$ and $\omega_2 t$ separately.

$$\omega_1 t: 2 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} = A \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

$$\omega_2 t: \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 2v = Av \Rightarrow v = \begin{bmatrix} 0 \\ 1/3 \end{bmatrix} \text{ is one solution.}$$

$$\text{So, } \mathbf{x}_2(t) = te^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + e^{2t} \begin{bmatrix} 0 \\ 1/3 \end{bmatrix}.$$

6. Find the values of the positive number λ for which the given problem below has a nontrivial solution.

$$y'' + \lambda y = 0 \text{ for } 0 < x < \pi; \quad y(0) = 0, \quad y'(\pi) = 0.$$

For the sake of simplicity, let $\beta = \sqrt{\lambda}$.
The auxiliary equation is $r^2 + \lambda = 0 \Rightarrow r = \pm \sqrt{\lambda} i = \pm \beta i$. Hence, $y_1(t) = \cos\beta t$, $y_2(t) = \sin\beta t$.

Let $y(t) = C_1 y_1(t) + C_2 y_2(t)$.

$$0 = y(0) = C_1 \cdot 1 + C_2 \cdot 0 = C_1. \quad \text{So, } C_1 = 0. \Rightarrow y(t) = C_2 y_2(t).$$

Now, $y'(t) = C_2 \cdot \beta \cos\beta t$. But we want a nontrivial solution. So, $C_2 \neq 0$ and β is $\sqrt{\lambda} > 0$. So, $\cos\beta\pi = 0$ which implies that $\beta = \frac{n\pi}{2}$ (n : integer).
 $\Rightarrow \lambda = \frac{(2n+1)^2}{4}$ (n : integer).

Namely, $\lambda = \frac{1}{4}, \frac{9}{4}, \frac{25}{4}, \frac{49}{4}, \dots$ are only possible λ 's.

7. Suppose that $f(x) = 0$ for $-\pi < x < 0$ and $f(x) = 1$ for $0 \leq x \leq \pi$. Find the Fourier series for $f(x)$ on $[-\pi, \pi]$.¹

Fourier series is $\frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos nx + b_n \sin nx)$ where $a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos nx dx$
 $b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin nx dx$.

$$\text{So, } a_n = \frac{1}{\pi} \int_0^{\pi} \cos nx dx = \frac{1}{\pi} \cdot \frac{\sin nx}{n} \Big|_0^{\pi} \text{ if } n \neq 0. \quad (\text{n=0 case} \Rightarrow \frac{1}{\pi} \int_0^{\pi} 1 dx = 1.) \\ = \frac{1}{\pi} \cdot 0 = 0.$$

$$b_n = \frac{1}{\pi} \int_0^{\pi} \sin nx dx = \frac{1}{\pi} \cdot -\frac{\cos nx}{n} \Big|_0^{\pi} = \frac{1}{n\pi} (1 - (-1)^n) = \begin{cases} \frac{2}{n\pi} & n: \text{odd} \\ 0 & n: \text{even} \end{cases}$$

So, the Fourier series is $\frac{a_0}{2} \left(\sin x + \frac{1}{3} \sin 3x + \frac{1}{5} \sin 5x + \dots \right)$.

¹Optional.