

# 实战项目 1：AI 手势虚拟拖拽方块

步骤：

1. OpenCV 获取视频流
2. 在画面上画一个方块
3. 通过 mediapipe 获取手指关键点坐标  
( <https://google.github.io/mediapipe/solutions/hands> )
4. 判断手指是否在方块上
5. 根据食指和中指指尖的坐标，利用勾股定理计算距离，当距离较小且都落在矩形内，则触发拖拽（矩形变色）；
6. 矩形跟着手指动；
7. 两指放开，则矩形停止移动

完善：画面显示 FPS 等信息

标准答案：

```
# 导入 OpenCV
import cv2

# 导入 mediapipe
import mediapipe as mp

# 导入其他依赖包
import time
import math

# 方块管理类
class SquareManager:

    def __init__(self, rect_width):
        # 方框长度
```

```
self.rect_width = rect_width

# 方块 list

self.square_count = 0

self.rect_left_x_list = []
self.rect_left_y_list = []
self.alpha_list = []

# 中指与矩形左上角点的距离

self.L1 = 0
self.L2 = 0

# 激活移动模式

self.drag_active = False

# 激活的方块 ID

self.active_index = -1

# 创建一个方块，但是没有显示

def create(self, rect_left_x, rect_left_y, alpha=0.4):

    self.rect_left_x_list.append(rect_left_x)

    self.rect_left_y_list.append(rect_left_y)

    self.alpha_list.append(alpha)

    self.square_count += 1

# 更新位置

def display(self, class_obj):

    for i in range(0, self.square_count):
```

```
x = self.rect_left_x_list[i]
y = self.rect_left_y_list[i]
alpha = self.alpha_list[i]

overlay = class_obj.image.copy()

if (i == self.active_index):
    cv2.rectangle(overlay, (x, y), (x + self.rect_width, y + self.rect_width),
(255, 0, 255), -1)
else:
    cv2.rectangle(overlay, (x, y), (x + self.rect_width, y + self.rect_width),
(255, 0, 0), -1)

# Following line overlays transparent rectangle over the self.image
class_obj.image = cv2.addWeighted(overlay, alpha, class_obj.image, 1 - alpha,
0)

# 判断落在哪个方块上，返回方块的 ID
def checkOverlay(self, check_x, check_y):
    for i in range(0, self.square_count):
        x = self.rect_left_x_list[i]
        y = self.rect_left_y_list[i]

        if (x < check_x < (x + self.rect_width)) and (y < check_y < (y +
self.rect_width)):
            # 保存被激活的方块 ID
            self.active_index = i
```

```
    return i

    return -1

# 计算与指尖的距离

def setLen(self, check_x, check_y):
    # 计算距离

    self.L1 = check_x - self.rect_left_x_list[self.active_index]

    self.L2 = check_y - self.rect_left_y_list[self.active_index]

# 更新方块

def updateSquare(self, new_x, new_y):
    # print(self.rect_left_x_list[self.active_index])

    self.rect_left_x_list[self.active_index] = new_x - self.L1

    self.rect_left_y_list[self.active_index] = new_y - self.L2

# 识别控制类

class HandControlVolume:

    def __init__(self):
        # 初始化 mediapipe

        self.mp_drawing = mp.solutions.drawing_utils

        self.mp_drawing_styles = mp.solutions.drawing_styles

        self.mp_hands = mp.solutions.hands

# 中指与矩形左上角点的距离

self.L1 = 0

self.L2 = 0
```

```
# image 实例，以便另一个类调用

self.image = None


# 主函数

def recognize(self):

    # 计算刷新率

    fpsTime = time.time()

    # OpenCV 读取视频流

    cap = cv2.VideoCapture(0)

    # 视频分辨率

    resize_w = int(cap.get(cv2.CAP_PROP_FRAME_WIDTH))

    resize_h = int(cap.get(cv2.CAP_PROP_FRAME_HEIGHT))

    # 画面显示初始化参数

    rect_percent_text = 0

    # 初始化方块管理器

    squareManager = SquareManager(150)

    # 创建多个方块

    for i in range(0, 5):

        squareManager.create(200 * i + 20, 200, 0.6)

    with self.mp_hands.Hands(min_detection_confidence=0.7,

                             min_tracking_confidence=0.5,

                             max_num_hands=2) as hands:

        while cap.isOpened():

            # 从摄像头读取帧

            ret, frame = cap.read()

            if not ret:
```

```
# 初始化矩形

success, self.image = cap.read()

self.image = cv2.resize(self.image, (resize_w, resize_h))

if not success:

    print("空帧.")

    continue

# 提高性能

self.image.flags.writeable = False

# 转为 RGB

self.image = cv2.cvtColor(self.image, cv2.COLOR_BGR2RGB)

# 镜像

self.image = cv2.flip(self.image, 1)

# mediapipe 模型处理

results = hands.process(self.image)

self.image.flags.writeable = True

self.image = cv2.cvtColor(self.image, cv2.COLOR_RGB2BGR)

# 判断是否有手掌

if results.multi_hand_landmarks:

    # 遍历每个手掌

    for hand_landmarks in results.multi_hand_landmarks:

        # 在画面标注手指

        self.mp_drawing.draw_landmarks(

            self.image,

            hand_landmarks,
```

```
    self.mp_hands.HAND_CONNECTIONS,  
  
    self.mp_drawing_styles.get_default_hand_landmarks_style(),  
  
    self.mp_drawing_styles.get_default_hand_connections_style())  
  
    # 解析手指，存入各个手指坐标  
  
    landmark_list = []  
  
    # 用来存储手掌范围的矩形坐标  
  
    paw_x_list = []  
  
    paw_y_list = []  
  
    for landmark_id, finger_axis in enumerate(  
  
        hand_landmarks.landmark):  
  
        landmark_list.append([  
  
            landmark_id, finger_axis.x, finger_axis.y,  
  
            finger_axis.z  
  
        ])  
  
        paw_x_list.append(finger_axis.x)  
  
        paw_y_list.append(finger_axis.y)  
  
    if landmark_list:  
  
        # 比例缩放到像素  
  
        ratio_x_to_pixel = lambda x: math.ceil(x * resize_w)  
  
        ratio_y_to_pixel = lambda y: math.ceil(y * resize_h)  
  
        # 设计手掌左上角、右下角坐标  
  
        paw_left_top_x, paw_right_bottom_x = map(ratio_x_to_pixel,  
  
                                                [min(paw_x_list),  
  
                                                 max(paw_x_list)])  
  
        paw_left_top_y, paw_right_bottom_y = map(ratio_y_to_pixel,
```

```
[min(paw_y_list),  
max(paw_y_list)])  
  
        # 给手掌画框框  
        cv2.rectangle(self.image, (paw_left_top_x - 30, paw_left_top_y  
- 30),  
                      (paw_right_bottom_x + 30, paw_right_bottom_y +  
30), (0, 255, 0), 2)  
  
        # 获取中指指尖坐标  
        middle_finger_tip = landmark_list[12]  
        middle_finger_tip_x = ratio_x_to_pixel(middle_finger_tip[1])  
        middle_finger_tip_y = ratio_y_to_pixel(middle_finger_tip[2])  
  
        # 获取食指指尖坐标  
        index_finger_tip = landmark_list[8]  
        index_finger_tip_x = ratio_x_to_pixel(index_finger_tip[1])  
        index_finger_tip_y = ratio_y_to_pixel(index_finger_tip[2])  
        # 中间点  
        between_finger_tip = (middle_finger_tip_x + index_finger_tip_x)  
// 2, (  
        middle_finger_tip_y + index_finger_tip_y) // 2  
        # print(middle_finger_tip_x)  
        thumb_finger_point = (middle_finger_tip_x, middle_finger_tip_y)  
        index_finger_point = (index_finger_tip_x, index_finger_tip_y)  
        # 画指尖 2 点  
        circle_func = lambda point: cv2.circle(self.image, point, 10,  
(255, 0, 255), -1)
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```
        self.image = circle_func(thumb_finger_point)

        self.image = circle_func(index_finger_point)

        self.image = circle_func(between_finger_tip)

        # 画 2 点连线

        self.image = cv2.line(self.image, thumb_finger_point,
index_finger_point, (255, 0, 255), 5)

        # 勾股定理计算长度

        line_len = math.hypot((index_finger_tip_x -
middle_finger_tip_x),

(middle_finger_tip_y) - middle_finger_tip_y))

        # 将指尖距离映射到文字

        rect_percent_text = math.ceil(line_len)

        # 激活模式，需要让矩形跟随移动

        if squareManager.drag_active:

            # 更新方块

            squareManager.updateSquare(between_finger_tip[0],
between_finger_tip[1])

            if (line_len > 100):

                # 取消激活

                squareManager.drag_active = False

                squareManager.active_index = -1

                # 移除之前存在的矩形

                squareManager.image = np.zeros_like(squareManager.image)

                # 重新绘制矩形

                squareManager.image = cv2.rectangle(squareManager.image,
(between_finger_tip[0] - 10, between_finger_tip[1] - 10),
(between_finger_tip[0] + 10, between_finger_tip[1] + 10), (0, 255, 0), 2)

                # 将新矩形添加到原图上

                self.image = cv2.add(self.image, squareManager.image)

            else:

                # 取消激活

                squareManager.drag_active = False

                squareManager.active_index = -1

                # 移除之前存在的矩形

                squareManager.image = np.zeros_like(squareManager.image)

                # 重新绘制矩形

                squareManager.image = cv2.rectangle(squareManager.image,
(between_finger_tip[0] - 10, between_finger_tip[1] - 10),
(between_finger_tip[0] + 10, between_finger_tip[1] + 10), (0, 255, 0), 2)

                # 将新矩形添加到原图上

                self.image = cv2.add(self.image, squareManager.image)

        elif (line_len < 100) and

(squareManager.checkOverlay(between_finger_tip[0],
between_finger_tip[1]) != -1) and (
```

```
squareManager.drag_active == False):  
    # 激活  
    squareManager.drag_active = True  
  
    # 计算距离  
    squareManager.setLen(between_finger_tip[0],  
                          between_finger_tip[1])  
  
    # 显示方块，传入本实例，主要为了半透明的处理  
    squareManager.display(self)  
  
    # 显示距离  
    cv2.putText(self.image, "Distance:" + str(rect_percent_text), (10, 120),  
                cv2.FONT_HERSHEY_PLAIN, 3,  
                (255, 0, 0), 3)  
  
    # 显示当前激活  
    cv2.putText(self.image, "Active:" + (  
        "None" if squareManager.active_index == -1 else  
        str(squareManager.active_index)), (10, 170),  
        cv2.FONT_HERSHEY_PLAIN, 3, (255, 0, 0), 3)  
  
    # 显示刷新率 FPS  
    cTime = time.time()  
  
    fps_text = 1 / (cTime - fpsTime)  
  
    fpsTime = cTime  
  
    cv2.putText(self.image, "FPS: " + str(int(fps_text)), (10, 70),  
                cv2.FONT_HERSHEY_PLAIN, 3, (255, 0, 0), 3)  
  
    # 显示画面
```

```
# self.image = cv2.resize(self.image, (resize_w//2, resize_h//2))

cv2.imshow('virtual drag and drop', self.image)

if cv2.waitKey(5) & 0xFF == 27 :

    break

cap.release()

# 开始程序

control = HandControlVolume()

control.recognize()
```

自己答案：

```
import cv2

import mediapipe as mp

import math

import time


video = cv2.VideoCapture(0)


#激活方块标志

sign = False


#获取视频长宽

video_width = int(video.get(cv2.CAP_PROP_FRAME_WIDTH))

video_height = int(video.get(cv2.CAP_PROP_FRAME_HEIGHT))



#正方形相关参数

rec_width = 150

rec_height = 150
```

```
dis_x = now_posx = start_posx = 50
dis_y = now_posy = start_posy = 50

#mediapipe 相关参数

mp_drawing = mp.solutions.drawing_utils
mp_drawing_styles = mp.solutions.drawing_styles
mp_hands = mp.solutions.hands

hands = mp_hands.Hands(
    model_complexity=0,           #模型复杂度
    min_detection_confidence=0.5, #检测最小置信度
    min_tracking_confidence=0.5)  #手部跟踪最小置信度

start_time = time.time()

def rectangle_draw(start, img, x, y):
    #情况一：画黄色矩形
    if start:
        img = cv2.rectangle(img, (x, y), (x + rec_width, y + rec_height), (0, 255, 0), -1)
    #情况二：画绿色矩形
    elif start == False:
        img = cv2.rectangle(img, (x, y), (x + rec_width, y + rec_height), (255, 255, 0), -1)

while True:
    ret, frame = video.read()
    #将 cv2 的 BGR 格式转换成 RGB
    frame = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
```

```
# 镜像
frame = cv2.flip(frame, 1)

# if sign == False:
#     rec_x = dis_x
#     rec_y = dis_y
# 绘制实心正方形
#     frame = cv2.rectangle(frame, (rec_x, rec_y), (rec_x + rec_width, rec_y +
rec_height), (0, 255, 0), -1)
results = hands.process(frame)

if results.multi_hand_landmarks:
    for hand_landmarks in results.multi_hand_landmarks:
        #获得食指坐标 x, y
        finger1_x = int(hand_landmarks.landmark[8].x * video_width)
        finger1_y = int(hand_landmarks.landmark[8].y * video_height)
        #print(finger1_x, finger1_y)

        #获得中指坐标 x, y
        finger2_x = int(hand_landmarks.landmark[12].x * video_width)
        finger2_y = int(hand_landmarks.landmark[12].y * video_height)
        #print(finger2_x, finger2_y)

        #验证是否是食指、中指
        # frame = cv2.circle(frame, (finger1_x, finger1_y), 30, (255, 0, 0), -1)
        # frame = cv2.circle(frame, (finger2_x, finger2_y), 30, (255, 0, 0), -1)

        #获得中指和食指的距离—勾股定理
```

```

# distance =math.sqrt( (finger2_x - finger1_x)**2 + (finger2_x - finger1_x)**2)
distance = math.hypot((finger1_x - finger2_x), (finger1_y - finger2_y))

#print(distance)

#情况一：触发移动条件，方块跟随手指

if distance < 45:

    if (finger1_x < now_posx + rec_width) and (finger1_x > now_posx) and
(finger1_y > now_posy) and (finger1_y < now_posy + rec_height):

        if sign == False:

            sign = True

            #计算矩形左上角点与食指的相对距离

            dis_x = finger1_x - now_posx

            dis_y = finger1_y - now_posy

#情况二：解除/原始状态

elif distance > 240:

    sign = False

#避免方块移出视频画面

if now_posx + rec_width > video_width: #右限位

    sign = False

    now_posx = video_width - rec_width

elif now_posx < 0: #左限位

    sign = False

    now_posx = 0

elif now_posy < 0: #上限位

    sign = False

    now_posy = 0

elif now_posy + rec_height > video_height: #下限位

```

```
sign = False

now_posy = video_height - rec_height


#移动跟随算法

if sign:

    now_posx = finger1_x - dis_x

    now_posy = finger1_y - dis_y


#绘制手指关键点

mp_drawing.draw_landmarks(

    frame,

    hand_landmarks,

    mp_hands.HAND_CONNECTIONS,

    mp_drawing_styles.get_default_hand_landmarks_style(),

    mp_drawing_styles.get_default_hand_connections_style())


#矩形半透明处理

overlay = frame.copy()

rectangle_draw(sign, frame, now_posx, now_posy)

frame = cv2.addWeighted(overlay, 0.5, frame, 1 - 0.5, 0)


#左上角显示帧率

now_time = time.time()

fps = int(1 / (now_time - start_time))

start_time = now_time

font = cv2.FONT_HERSHEY_PLAIN

frame = cv2.putText(img = frame, text = str(fps), org = (20, 50), fontFace = font, fontScale = 3, color = (0, 255, 255), thickness = 3, lineType = cv2.LINE_AA)
```

```
#恢复颜色  
  
frame = cv2.cvtColor(frame, cv2.COLOR_RGB2BGR)  
  
#显示视频画面，设置退出条件  
  
cv2.imshow("Mac Camera", frame)  
  
if cv2.waitKey(10) & 0xFF == 27:  
  
    break  
  
  
#释放句柄  
  
video.release()  
  
cv2.destroyAllWindows()
```

实现效果：

