

Exercise 5 – Computational Materials Engineering

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Goals:

- Understand the calculation of forces.
- Understand how the time step in molecular dynamics works.

In lecture 3, the forces on atom K for a system of N atoms interacting via the superposition of pairwise Morse potentials was found to be

$$\vec{F}_K = - \sum_{\substack{j=1 \\ j \neq K}}^N \frac{du_M(R_{KJ})}{dR_{KJ}} \frac{\vec{R}_{KJ}}{R_{KJ}}, \quad (1)$$

where

$$u_M(R) = D_0 [e^{-2\alpha(R-R_0)} - 2e^{-\alpha(R-R_0)}]. \quad (2)$$

It is recommended to create a new directory for this exercise and save all the scripts in that folder.

Tasks

Task 1: Consider two particles 1 and 2 with positions $\vec{r}_1 = (0, 0, z_1)$, $\vec{r}_2 = (0, 0, z_2)$ and calculate the force vectors acting on both atoms by evaluating equation (1) for $z_1 = 0$, $z_2 = 0.5$ and $D_0 = 1$ eV, $\alpha = 1$ Å⁻¹ and $R_0 = 1$ Å.

Task 2: Download *dimer.py* and *MorseCalculator.py* from ILIAS. *MorseCalculator.py* contains the information how the energy and forces are calculated. You need to save the file in the same folder as *dimer.py*. Open and run *dimer.py*. Try to understand what it does. Compare the forces the script calculates with the forces that you obtained in Task 1.

Task 3: As we now know how forces are calculated, we have all ingredients to do a molecular dynamics simulation using the velocity-Verlet propagator as discussed in lecture 4. Before we perform the actual simulation, we calculate manually what to expect. Use the formulae

$$\vec{r}_i(t + \Delta t) = \vec{r}_i(t) + \vec{v}_i(t)\Delta t + \frac{1}{2} \frac{\vec{F}_i(t)}{m_i} \Delta t^2 + O(\Delta t^3) \quad (3)$$

$$\vec{v}_i(t + \Delta t) = \vec{v}_i(t) + \frac{1}{2} \frac{\vec{F}_i(t) + \vec{F}_i(t + \Delta t)}{m_i} \Delta t + O(\Delta t^3) \quad (4)$$

to determine the velocities and positions of a dimer after a single time step of 1 fs. The dimer has the initial positions $\vec{r}_1 = (0, 0, 0)$, $\vec{r}_2 = (0, 0, 0.5)$, interacts via the Morse potential from Task 1 and has zero initial velocity. The mass of each atom is 1.008 u (unified atomic mass unit).

Note: Handling the units correctly is tricky. If you use the units as given during this exercise sheet, it might be useful to know that the conversion factor from [$\frac{\text{eV}}{\text{\AA} u}$ fs²] to [Å] and from [$\frac{\text{eV}}{\text{\AA} u}$ fs] to [$\frac{\text{\AA}}{\text{fs}}$] is approximately 0.00964853322 (these are useful for the “ $\frac{\vec{F}_i(t)}{m_i} \Delta t^2$ ” and the “ $\frac{\vec{F}_i(t)}{m_i} \Delta t$ ” terms).

Task 4: Download, open, understand and run the *dimer_dynamics.py* script. You need to download the *Verlet.py* script and save it in the same folder. Compare the values that the script prints to your screen with the values that you calculated in Task 3.

Task 5: Open *Verlet.py* and try to understand the implementation of the velocity-Verlet algorithm (i.e. everything that is written below “*def step(self, f=None)*”).

Results:

Task1:

$$\vec{F}_K = - \sum_{\substack{j=1 \\ j \neq K}}^N \frac{du_M(R_{KJ})}{dR_{KJ}} \frac{\overrightarrow{R_{KJ}}}{R_{KJ}}$$

$$u_M(R) = D_0 [e^{-2\alpha(R-R_0)} - 2e^{-\alpha(R-R_0)}]$$

Calculation for k=2, j=1 (N=2, k ≠ j) [Force acting on the second atom]

$$\vec{F}_2 = - \frac{du_M(R_{21})}{dR_{21}} \frac{\overrightarrow{R_{21}}}{R_{21}}$$

Calculate Components of the formula:

$$\overrightarrow{R_{21}} = \begin{pmatrix} 0 \text{Å} \\ 0 \text{Å} \\ 0.5 \text{Å} - 0 \text{Å} \end{pmatrix} = \begin{pmatrix} 0 \text{Å} \\ 0 \text{Å} \\ 0.5 \text{Å} \end{pmatrix}$$

$$R_{21} = \sqrt{(R_{21x})^2 + (R_{21y})^2 + (R_{21z})^2}$$

$$R_{21} = \sqrt{(R_{2x} - R_{1x})^2} = \sqrt{(0 \text{Å} - 0.5 \text{Å})^2} = 0.5 \text{Å}$$

$$\frac{du_M(R_{KJ})}{dR_{KJ}} = D_0 2\alpha [-e^{-2\alpha(R-R_0)} + e^{-\alpha(R-R_0)}]$$

Insert calculated components and values ($z_1 = 0$, $z_2 = 0.5$ and $D_0 = 1 \text{ eV}$, $\alpha = 1 \text{ Å}^{-1}$ and $R_0 = 1 \text{ Å}$):

$$\vec{F}_2 = - \frac{du_M(R_{21})}{dR_{21}} \frac{\overrightarrow{R_{21}}}{R_{21}}$$

$$\vec{F}_2 = -1 \text{ eV} \cdot 2 \text{ Å}^{-1} [-e^{-2 \cdot 1 \text{ Å}^{-1} (0.5 \text{Å} - 1.0 \text{Å})} + e^{-1 \text{ Å}^{-1} (0.5 \text{Å} - 1.0 \text{Å})}] \begin{pmatrix} 0 \text{Å}/0.5 \text{Å} \\ 0 \text{Å}/0.5 \text{Å} \\ 0.5 \text{Å}/0.5 \text{Å} \end{pmatrix}$$

$$\vec{F}_2(t) = \begin{pmatrix} 0 \text{ eV/Å} \\ 0 \text{ eV/Å} \\ 2.139 \text{ eV/Å} \end{pmatrix}$$

The force is acting towards positive z-direction on the second atom. Carry out the same computation with k=1, j=2 (N=2, k ≠ j) [Force acting on the first atom]:

$$\vec{F}_1(t) = \begin{pmatrix} 0 \text{ eV/Å} \\ 0 \text{ eV/Å} \\ -2.139 \text{ eV/Å} \end{pmatrix}$$

The only difference is the $\overrightarrow{R_{12}}$ vector: $\overrightarrow{R_{12}} = \begin{pmatrix} 0 \text{Å} \\ 0 \text{Å} \\ 0 \text{Å} - 0.5 \text{Å} \end{pmatrix} = \begin{pmatrix} 0 \text{Å} \\ 0 \text{Å} \\ -0.5 \text{Å} \end{pmatrix}$

Task 3: Velocity verlet procedure:

1. Calculate new positions $\vec{r}_1(t + \Delta t), \vec{r}_2(t + \Delta t)$ [using formula 3]
2. Calculate new forces $\vec{f}_1(t + \Delta t), \vec{f}_2(t + \Delta t)$ [same procedure than Task1]
3. Calculate new velocities $\vec{v}_1(t + \Delta t), \vec{v}_2(t + \Delta t)$ [using formula 4]

$$1) \vec{r}_i(t + \Delta t) = \vec{r}_i(t) + \vec{v}_i(t)\Delta t + \frac{1}{2} \frac{\vec{F}_i(t)}{m_i} \Delta t^2 + O(\Delta t^3)$$

$$\vec{r}_1(t + 1fs) = \begin{pmatrix} 0 \text{ \AA} \\ 0 \text{ \AA} \\ 0 \text{ \AA} \end{pmatrix} + 0 \frac{\text{\AA}}{fs} \Delta t + \frac{1}{2} \frac{\begin{pmatrix} 0 \text{ eV/\AA} \\ 0 \text{ eV/\AA} \\ -2.139 \text{ eV/\AA} \end{pmatrix}}{1.008u} (1fs)^2 0.0096485 \frac{\text{\AA u}}{eV fs^2} \text{\AA} + O(\Delta t^3)$$

$0.0096485 \frac{\text{\AA u}}{eV fs^2} \text{\AA}$ is the conversion to \AA.

$$\vec{r}_1(t + 1fs) = \begin{pmatrix} 0 \text{ \AA} \\ 0 \text{ \AA} \\ -0.010237 \text{ \AA} \end{pmatrix}$$

Same procedure for $\vec{r}_2(t + 1fs)$

$$\vec{r}_2(t + 1fs) = \begin{pmatrix} 0 \text{ \AA} \\ 0 \text{ \AA} \\ 0.510237 \text{ \AA} \end{pmatrix}$$

$$2) \vec{F}_K = - \sum_{\substack{J=1 \\ J \neq K}}^N \frac{du_M(R_{KJ})}{dR_{KJ}} \frac{\vec{R}_{KJ}}{R_{KJ}}$$

$$\vec{F}_1(t + \Delta t) = \begin{pmatrix} 0 \text{ eV/\AA} \\ 0 \text{ eV/\AA} \\ -1.98783 \text{ eV/\AA} \end{pmatrix}, \vec{F}_2(t + \Delta t) = \begin{pmatrix} 0 \text{ eV/\AA} \\ 0 \text{ eV/\AA} \\ 1.98783 \text{ eV/\AA} \end{pmatrix}$$

$$3) \vec{v}_i(t + \Delta t) = \vec{v}_i(t) + \frac{1}{2} \frac{\vec{F}_i(t) + \vec{F}_i(t + \Delta t)}{m_i} \Delta t + O(\Delta t^3)$$

$$\vec{v}_1(t + 1fs) = 0 \frac{\text{\AA}}{fs} + \frac{1}{2} \frac{\begin{pmatrix} 0 \text{ eV/\AA} \\ 0 \text{ eV/\AA} \\ -2.139 \text{ eV/\AA} \end{pmatrix} + \begin{pmatrix} 0 \text{ eV/\AA} \\ 0 \text{ eV/\AA} \\ -1.98783 \text{ eV/\AA} \end{pmatrix}}{1.008 u} 1fs 0.0096485 \frac{\text{\AA u}}{eV fs} \frac{\text{\AA}}{fs} + O(\Delta t^3)$$

$$\vec{v}_1(t + 1fs) = \begin{pmatrix} 0 \frac{\text{\AA}}{fs} \\ 0 \frac{\text{\AA}}{fs} \\ -0.01975 \frac{\text{\AA}}{fs} \end{pmatrix}, \text{ analogous } \vec{v}_2(t + 1fs) = \begin{pmatrix} 0 \frac{\text{\AA}}{fs} \\ 0 \frac{\text{\AA}}{fs} \\ 0.01975 \frac{\text{\AA}}{fs} \end{pmatrix},$$