```
youbot_oodl.cpp
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YouBotOODLWrapper.cpp
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+armCurrentsCommandCallbak() void

+armParametersControlCallbak() bool

+armParametersReadControlCallbak() bool
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joitn_state_observer_oodl.h
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YouBotOODLWrapper.h
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youbot_trajectoty_action_server/ joitn_state_observer.h
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YouBotConfiguratrion.h
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