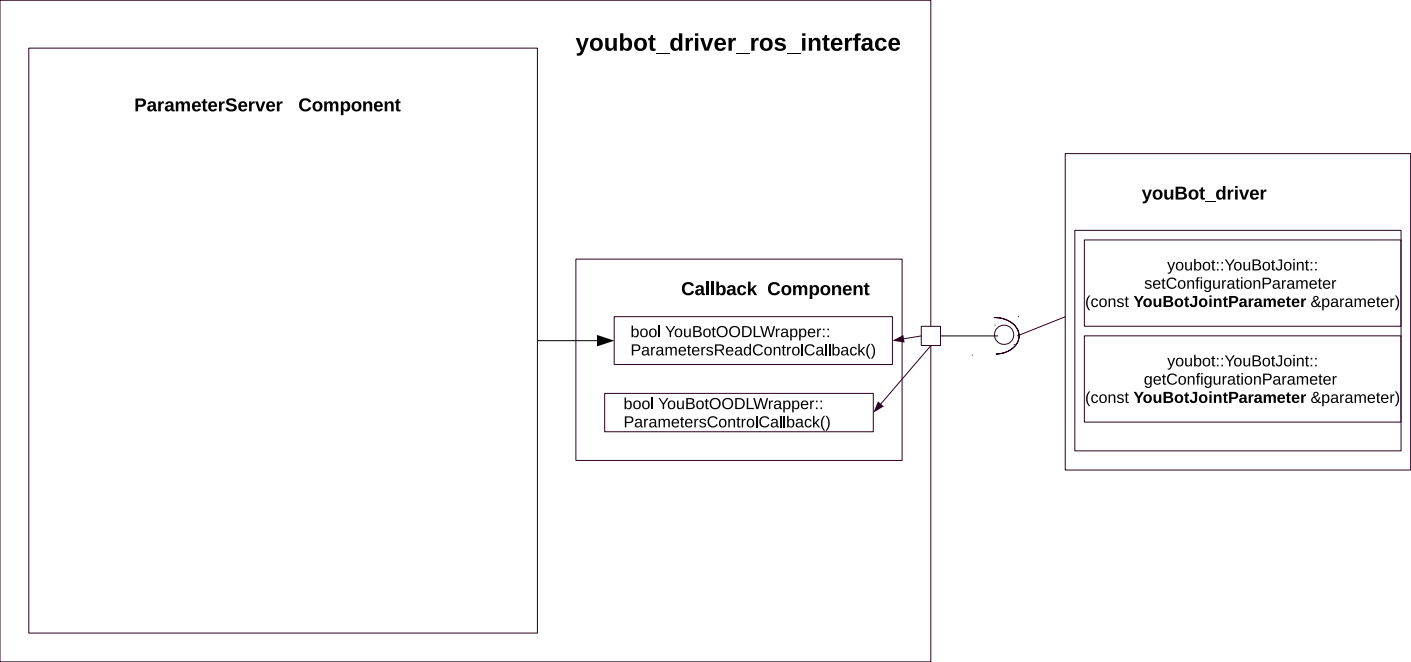
youbot_driver_ros_interface
ParameterServer Component
Callback Component
bool YouBotOODLWrapper::
ParametersReadControlCallback()
bool YouBotOODLWrapper::
ParametersControlCallback()
youBot_driver
youbot::YouBotJoint::
setConfigurationParameter
(const YouBotJointParameter &parameter)
youbot::YouBotJoint::
getConfigurationParameter
(const YouBotJointParameter &parameter)