Subscrib Topic component

Topic:/arm_1/arm_controller/position_command
Msg:brics_actuator/JointPositions

Topic:/arm_1/arm_controller/velocity_command
Msg:brics_actuator/JointVelocities

Topic:/arm_1/arm_controller/torques_command
Msg:brics_actuator/JointTorques

Topic:/arm_1/gripper_controller/position_command
Msg:brics_actuator/JointPositions

ROS Node

Callback 1

Callback 2

Publish Topic component

Topic:/arm_1/arm_controller/command
Msg:

Topic:/arm_1/gripper_controller/command
Msg: