

youbot_driver_ros_interface

Callback Component

Subscribed Topic: /arm_1/arm_controller/current_command
Msg: youbot_driver_ros_interface/JointCurrents

YouBotOODLWrapper::
armCurrentsCommandCallback()

Published Topic: /joint_current
Msg: youbot_driver_ros_interface/JointCurrents

YouBotOODLWrapper::
computeOODLSensorReadings()

YouBotOODLWrapper::
publishOODLSensorReadings()

youbot_driver

youbot::YouBotJoint::
setData (**JointCurrentSetpoint** &data)

youbot::YouBotJoint::
getData (**JointCurrentSetpoint** &data)