

Problem 1.

Consider the initial-value problem

$$\dot{x}(t) = \begin{pmatrix} 3 & 2 & 1 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{pmatrix} x(t) \triangleq Ax(t), \text{ with } x(0) = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}.$$

1.1) Transform the matrix A into a Jordan form.1.2) On the basis of the Jordan form, solve the initial-value problem for all $t \geq 0$.

\rightarrow (1.1) We can see the rank of the matrix A
 ~~\neq~~ $\underline{\text{rank}}(A) = 3$.

(i) Computing Eigenvalues:

$$A - \lambda I = \begin{bmatrix} 3-\lambda & 2 & 1 \\ 0 & 3-\lambda & 0 \\ 0 & 0 & 3-\lambda \end{bmatrix}$$

$$\det(A - \lambda I) = -\lambda^3 + 9\lambda^2 - 27\lambda + 27$$

This is the characteristic polynomial. \nearrow

roots (eigenvalues) are :

$$\boxed{\lambda_1 = 3, \lambda_2 = 3}$$

(ii) Finding eigenvectors :

$$\text{for } \lambda = 3, A - \lambda I = \begin{bmatrix} 3-\lambda & 2 & 1 \\ 0 & 3-\lambda & 0 \\ 0 & 0 & 3-\lambda \end{bmatrix} = \begin{bmatrix} 0 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Reducing this to row echelon form :

$$(A - \lambda I) X = \begin{bmatrix} 0 & 1 & 1/2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

After solving we get eigenvectors as:

$$v_1 = \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

Jordan form is computed by :

$$A = S \cdot J \cdot S^{-1}$$

where S is the transformation matrix
& J is the Jordan form.

After solving , we get ,

$$S = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 1/2 \\ 2 & 0 & 0 \end{bmatrix}, \quad J = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{bmatrix}, \quad S^{-1} = \underline{\underline{\begin{bmatrix} 0 & 0 & 1/2 \\ 1 & 0 & 0 \\ 0 & 2 & 1 \end{bmatrix}}}$$

(102) To solve the initial value problem, we have to:

(i) find general soln:

$$x(t) = c_1 v_1 e^{\lambda_1 t} + c_2 v_2 e^{\lambda_2 t} \rightarrow ①$$

but \therefore we are using the jordan form: $\begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{bmatrix}$

eigenvalues will be the same: $\lambda_1 = 3, \lambda_2 = 3$

eigenvectors after solving is:

$$v_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$



Substituting these computed eigenvalues and eigenvectors in equ ①

$$x(t) = c_1 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} e^{3t} + c_2 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} (e^{3t} + t)$$

but, we have to find the one that satisfies

$$\text{when } t = 0, \quad x(t) = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$$

$$\text{when } t = 0, \mathbf{x}(t) = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} = c_1 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} e^0 + c_2 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} e^0$$

After solving

$$\boxed{\begin{array}{l} c_2 = 1 \\ c_1 = 2 \end{array}}$$

substituting c_1 & c_2 in the general soln.

$$x = 1 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} e^{3t} + 2 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} (e^{3t} + t)$$

soln. of the
initial value
problem.

(2)

Problem 2.

Suppose the n Gersgorin discs of an $n \times n$ matrix A are mutually disjoint. Show that every eigenvalue of A is real, if A is real.

→ We know that there would be at most n eigenvalues

- since it is a $n \times n$ matrix
- and since each of the disk is disjoint,
- we can take $m=1$ in the Gerschgorin circle theorem

to see that each disk must contain exactly one of the eigenvalues.

- we also know that $\because B$ is real, then coef. of characteristic polynomial of B are all real.

→ i.e. either the eigenvalues are real or they occur in complex conjugate pairs.

Suppose we have a complex conjugate pair

$$\lambda_1 = a + bi \quad \& \quad \lambda_2 = a - bi$$

we can see that:

$$|a \pm bi - b_{ii}| = \sqrt{(a+b_{ii})^2 + b^2}$$

$$|a \pm bi - b_{ii}| = \sqrt{(a+b_{ii})^2 + b^2}$$

From above, we can say that both of these would necessarily lie in the same gerschgorin disc, we cannot have complex eigenvalues.

Conclusion: The eigenvalues must be real if A is real. as complex values must appear in conjugate pairs.

(3)

Problem 3.

Consider $A = \begin{pmatrix} 1 & 1 \\ -1.5 & 2 \end{pmatrix}$ and show that $\rho(A) < \min \|D^{-1}AD\|_\infty$ over all $D = \begin{pmatrix} p_1 & 0 \\ 0 & p_2 \end{pmatrix}$,

with $p_1 > 0$ and $p_2 > 0$. (Recall that $\|M\|_\infty$ stands for the maximum row sum matrix norm of $M \in \mathbb{R}^{n \times n}$, i.e. $\|M\|_\infty := \max_{1 \leq i \leq n} \sum_{j=1}^n |a_{ij}|$.)

→ let λ be the eigenvalue of A .

We will s.t $\rightarrow Ax = \lambda x$.

then, λ is also the eigenvalue of $D^{-1}AD$

$$\text{let } y = \left(\frac{x_1}{p_1}, \frac{x_2}{p_2} \right)^T$$

then,

$$D^{-1}AD y = \begin{bmatrix} \frac{1}{p_1} & 0 \\ 0 & \frac{1}{p_2} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1.5 & 2 \end{bmatrix} \begin{bmatrix} p_1 & 0 \\ 0 & p_2 \end{bmatrix} \begin{bmatrix} x_1 \\ p_1 \\ x_2 \\ p_2 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} \frac{1}{p_1} & 0 \\ 0 & \frac{1}{p_2} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1.5 & 2 \end{bmatrix} \begin{bmatrix} \frac{p_1 \cdot x_1}{p_1} \\ \frac{p_2 \cdot x_2}{p_2} \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} \frac{1}{\rho_1} & 0 \\ 0 & \frac{1}{\rho_2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\Rightarrow \lambda \begin{bmatrix} \frac{x_1}{\rho_1} \\ \frac{x_2}{\rho_2} \end{bmatrix} \quad \left. \right\} \text{we know this is } y.$$

$$D^{-1} A D y = \lambda y.$$

$$\text{Now, } \|\lambda \cdot y\|_\infty = \|D^{-1} A D y\|_\infty$$

$$\|\lambda\| \cdot \|y\|_\infty = \|D^{-1} A D y\|_\infty$$

\Rightarrow we know that $\|M\|_\infty$ is a matrix norm, and thus, it is homogeneous.

$$\text{i.e. } \|\lambda\| \|y\|_\infty \leq \|D^{-1} A D\|_\infty \|y\|_\infty$$

$$|\lambda| \leq \|D^{-1} A D\|_\infty$$

$$\max |\lambda| \leq \|D^{-1} A D\|_\infty$$

\Rightarrow we also know that $\max |\lambda|$ is $= \rho(A)$

where $\rho(A)$ is the spectral radius of A .

$$\Rightarrow \rho(A) \leq \|D^{-1}AD\|_\infty$$

and

$$\rho(A) \leq \min \|D^{-1}AD\|_\infty$$

which is what we wanted to prove.