

# Lecture VIII

- **Vector norms and the associated matrix norms**
- **Some max and minimax principles**
- **Location of eigenvalues**

# Vector Norms

Any **regular vector-norm** satisfies:

$|x|$  denotes the (**generic**) norm of vector  $x$ .

- $|x| > 0$ , if  $x \neq 0$ ;  $|x| = 0$ , if  $x = 0$ .
- $|\lambda x| = |\lambda| \cdot |x|$ , for any scalar  $\lambda$ .
- $|x + y| \leq |x| + |y|$ , "**triangle inequality**"
- $|x|$  depends continuously on  $x$ .
- $\exists \alpha, \beta > 0$  such that

$$\alpha \max_k |x_k| \leq |x| \leq \beta \max_k |x_k|, \quad \forall \text{ vector } x.$$

# *Comment*

It is of interest to note that the last 2 properties in the definition of norm follow from the first 3 properties.

# Examples of Norm

(1) The **Euclidean** norm of  $x$  is:

$$|x| = \left( \sum_{k=1}^n |x_k|^2 \right)^{\frac{1}{2}} \doteq \|x\| \text{ (or sometimes, } |x|_2 \text{)}.$$

(2) **Riemannian metric**:

$$|x| = \langle Px, x \rangle^{\frac{1}{2}} = \left( \sum_j \sum_k p_{jk} x_k \bar{x}_j \right)^{\frac{1}{2}}$$

where  $P$  is positive definite.

# Examples of Norm

(3) The "Manhattan", or  $l_1$  norm of  $x$  is:

$$|x|_1 = \sum_{k=1}^n |x_k|.$$

(4) The " $l_\infty$ " norm:  $|x|_\infty = \max_{1 \leq i \leq n} |x_i|.$

(5) The " $l_p$ " norm:  $|x|_p = \left( \sum_{i=1}^n |x_i|^p \right)^{1/p}.$

Hardy, Littlewood, Polya, *Inequalities*, Cambridge Univ. Press, 1988



# Exercise

All norms over any finite-dimensional space are equivalent.

Some useful inequalities:

$$|x|_1 \leq \sqrt{n} |x|_2, \quad |x|_1 \leq n |x|_\infty,$$

$$|x|_2 \leq |x|_1, \quad |x|_2 \leq \sqrt{n} |x|_\infty,$$

$$|x|_\infty \leq |x|_1, \quad |x|_\infty \leq |x|_2.$$

# The Related Matrix Norm

For any given regular vector-norm  $|x|$ ,  
we can define the related matrix-norm as


$$|A| = \max_{x \neq 0} \frac{|Ax|}{|x|}, \quad A : n \times m \text{ matrix.}$$

**Remark:** It reduces to the vector norm  
when  $m = 1$ .

# Example of matrix-norm

From the Euclidean vector-norm, define the related *spectral* matrix-norm:

$$\begin{aligned}\|A\|_2 &= \max_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2} \\&= \max_{x \neq 0} \sqrt{\frac{\langle Ax, Ax \rangle}{\langle x, x \rangle}} = \max_{x \neq 0} \sqrt{\frac{\langle A^* Ax, x \rangle}{\langle x, x \rangle}} \\&= \sqrt{\lambda_{\max}(A^* A)}, \text{ using Rayleigh's principle below.}\end{aligned}$$

 (maximum) Singular Value of A



For example,

$$A = \begin{pmatrix} 0 & -2 \\ 1 & 0 \end{pmatrix} \Rightarrow A^* A = \begin{pmatrix} 1 & 0 \\ 0 & 4 \end{pmatrix}$$

$$\Rightarrow \|A\| = \sqrt{4} = 2.$$

# Other Matrix Norms

- **Frobenius norm** (or, Euclidean norm,  $l_2$ -norm, Schur norm, Hilbert-Schmidt norm):

$$|A|_F := |A|_2 = \left( \sum_{i,j=1}^n |a_{ij}|^2 \right)^{1/2}.$$

- **$l_1$ -norm**:  $|A|_1 = \sum_{i,j=1}^n |a_{ij}|.$

- **$l_\infty$ -norm**:  $|A|_\infty = \sum_{j=1}^n |a^j|_\infty$ , where  $A = \begin{bmatrix} a^1 & a^2 & \cdots & a^n \end{bmatrix}.$

# Fundamental Theorem

For any matrix norm  $\|\bullet\|$ , then

$$\rho(A) \leq \|A\|, \quad \text{with } A \text{ a square matrix}$$

where  $\rho(A)$  is the **spectral radius** of  $A$ , i.e.

$$\rho(A) = \max \{ |\lambda| : \lambda \text{ is an eigenvalue of } A \}.$$

**Remark:** Provided an upper-bound for all eigenvalues of any given matrix.

Indeed, we have

$$|\lambda||x| = |\lambda x| = |Ax| \leq \|A\| \bullet |x|$$

where  $x$  is an associated eigenvector.

So,  $\rho(A) \leq \|A\|$ .

# Example

Verify this theorem on the following matrices:

$$1) A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix};$$

$$2) A = \begin{pmatrix} 0 & j \\ -j & 0 \end{pmatrix}.$$

You may consider the  $l_2$ -norm only.



# Question

What are the **tightest** bounds in

$$c_1 \|x\|^2 \leq \langle Hx, x \rangle \leq c_2 \|x\|^2$$

where  $H$  is an  $n \times n$  Hermitian matrix.

# Simplified Question

Given a Hermitian matrix  $H$ ,  
what is the maximum of

$$\bar{u}^T H u := \langle H u, u \rangle, \quad \|u\| = 1$$

# The Rayleigh Principle

Consider a Hermitian matrix  $H$ . Then,

$$\max_{\|u\|=1} \langle Hu, u \rangle = \lambda_1$$

where  $\lambda_1$  is the largest eigenvalue of  $H$ .

Moreover, the equality is attained with  $u$  being a  $\lambda_1$ -associated eigenvector.

# Corollary

If  $H$  is Hermitian and  $\lambda_1$  is its largest eigenvalue, then

$$\lambda_1 = \max_{x \neq 0} \frac{\langle Hx, x \rangle}{\langle x, x \rangle},$$

where  $\frac{\langle Hx, x \rangle}{\langle x, x \rangle}$  is called Rayleigh quotient.

# Comment

As a direct consequence, we obtain a useful inequality:

$$\left| x^T H x \right| \leq \lambda_{\max}(H) |x|^2, \quad \forall x$$

when  $H$  is also positive definite.



# An Example

Consider the matrix  $H = \begin{pmatrix} 4 & 3i \\ -3i & 2 \end{pmatrix}$ .

- Is it Hermitian?
- Compute its eigenvalues.
- Verify the Rayleigh's Principle.

# Answer

- Yes, it is Hermitian, and therefore, its eigenvalues must be real.
- $\lambda_{1,2} = 3 \pm \sqrt{10}$ .
- $$\frac{\langle Hx, x \rangle}{\langle x, x \rangle} = \frac{4|x_1|^2 + 3i\bar{x}_1x_2 - 3i\bar{x}_2x_1 + 2|x_2|^2}{|x_1|^2 + |x_2|^2} \leq 3 + \sqrt{10} \quad (\text{using CFT. Do you know why/how?})$$

where the equality is attained when  $\begin{bmatrix} x_1 & x_2 \end{bmatrix}^T = x$  is an eigenvector associated with  $3 + \sqrt{10}$ .

# Comment

The Rayleigh principle *cannot* be applied to non-Hermitian matrix. Here is a simple counter-example:

$$A = \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix}, \quad b \neq 0.$$

# Proof of the Rayleigh Principle

As shown previously with canonical diagonal form, a Hermitian matrix  $H$  only has real eigenvalues  $\lambda_1 \geq \dots \geq \lambda_n$  and has mutually orthogonal eigenvectors

$$\{u^i\}_{i=1}^n, \text{ with } \|u^i\| = \sqrt{\langle u^i, u^i \rangle} = 1.$$

*Notice that*  $\lambda_i = \langle Hu^i, u^i \rangle, \forall 1 \leq i \leq n.$

## Proof (cont'd)

Since  $\{u^i\}_{i=1}^n$  are mutually orthogonal, then, every **unit** vector  $u$  can be written as

$$u = c_1 u^1 + \cdots + c_n u^n,$$

$$\text{with } |c_1|^2 + \cdots + |c_n|^2 = 1.$$

On the other hand,  $Hu = \sum c_i \lambda_i u^i$ , implying

$$\langle Hu, u \rangle = \sum \lambda_i |c_i|^2 \leq \lambda_1, \text{ as wished.}$$



# On Other Eigenvalues

Consider Hermitian  $H$  having real eigenvalues

$\lambda_1 \geq \dots \geq \lambda_n$ . Let  $\{u^k\}_{k=1}^{i-1}$  be mutually orthogonal unit eigenvectors associated with  $\{\lambda_k\}_{k=1}^{i-1}$ . Then,

$$\lambda_i = \max_{\substack{\|u\|=1 \\ \langle u, u^k \rangle = 0 \\ 1 \leq k \leq i-1}} \langle Hu, u \rangle$$

Benefit of quadratic forms

# Courant's MinMax Theorem

To **independently** evaluate each eigenvalue:

*Theorem*: Let  $\lambda_1 \geq \dots \geq \lambda_n$  be the eigenvalues of a Hermitian matrix  $H \in \mathbb{C}^{n \times n}$ .

Then, for  $1 \leq i < n$ ,

$$\lambda_{i+1} = \min_{v^1, \dots, v^i} \max_{\substack{\|u\|=1 \\ \langle u, v^k \rangle = 0 \\ k=1, \dots, i}} \langle Hu, u \rangle.$$

# An Example

Consider the quadratic form

$$\langle Hu, u \rangle = 3u_1^2 + 2u_2^2 + u_3^2 \Rightarrow H = \text{diag}(3, 2, 1).$$

Thus,  $\lambda_1 = 3$ ,  $\lambda_2 = 2$ ,  $\lambda_3 = 1$ , and

its associated eigenvectors are:

$$u^1 = e^1 = \text{col}(1, 0, 0), \quad u^2 = e^2 = \text{col}(0, 1, 0),$$

$$u^3 = e^3 = \text{col}(0, 0, 1).$$

## An Example (cont'd)

By Rayleigh's principle,

$$\begin{aligned}\lambda_2 &= \max_{\substack{\|u\|=1 \\ \langle u, e^1 \rangle = 0}} \left( 3u_1^2 + 2u_2^2 + u_3^2 \right) \\ &= \max_{u_2^2 + u_3^2 = 1} \left( 2u_2^2 + u_3^2 \right) = 2, \text{ as expected.}\end{aligned}$$

By Courant's principle,

$$\lambda_2 = \min_{v^1} \max_{\substack{\|u\|=1 \\ \langle u, v^1 \rangle = 0}} \left( 3u_1^2 + 2u_2^2 + u_3^2 \right) := \min_{v^1} \phi(v^1).$$

## An Example (cont'd)

Clearly,  $\phi(0) = \lambda_1 = 3$  (Rayleigh's principle).

When  $v^1 \neq 0$ , to compute  $\lambda_2$  is equivalent to solving two (constrained) nonlinear optimization problems.

Here, we apply a graphical proof to yield:

$$\lambda_2 = 2 = \phi(e^1) = \min \phi(v^1),$$

because  $3u_1^2$  is the dominating term.



# A Useful Test

For any  $n \times n$  Hermitian matrix  $H = (h_{ij})$ , it is positive definite **if and only if** all its leading principal minors are positive:

$$h_{11} > 0, \det \begin{pmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{pmatrix} > 0, \dots,$$

$$\det \begin{pmatrix} h_{11} & \dots & h_{1n} \\ \vdots & \ddots & \vdots \\ h_{n1} & \dots & h_{nn} \end{pmatrix} > 0.$$

# Recursive Proof

$\Rightarrow$ : If  $H$  is positive definite, then all its eigenvalues are positive. Then,  $\det H > 0$ .

Let  $H_k$  denote the submatrix of  $H$  formed of the first  $k$  rows and columns of  $H$ .

Then,  $H_k$  must be positive definite, because

$$\langle H_k x^k, x^k \rangle = \langle Hx, x \rangle, \text{ with } x = \begin{pmatrix} x^k \\ 0 \end{pmatrix}.$$

*That* is:  $\det H_k > 0$ , as wished.

# Recursive Proof

←: Now,  $\det H_k > 0, \forall k$ . In order to prove the positive definiteness of  $H$ , we need the following "Inclusion Principle".

# The Inclusion Principle

From a Hermitian matrix  $A = (a_{ij})_{n \times n}$ , form an  $(n-1) \times (n-1)$  matrix  $B$  by deleting the last row and column of  $A$ . Then, the eigenvalues  $\alpha_1 \geq \dots \geq \alpha_n$  of  $A$ , and  $\beta_1 \geq \dots \geq \beta_{n-1}$  of  $B$  satisfy:

$$\alpha_1 \geq \beta_1 \geq \alpha_2 \geq \dots \geq \alpha_{n-1} \geq \beta_{n-1} \geq \alpha_n.$$

*Proof:* using Courant's MinMax theorem.



# Recursive Proof (cont'd)

$\Leftarrow$ : Now,  $\det H_k > 0, \forall k$ . Then,  $H_1 = (h_{11})$  is positive definite. By induction, assume that  $H_k, k < n$ , is positive definite. We then need to prove that  $H_{k+1}$  is positive definite.

Let  $\alpha_1 \geq \dots \geq \alpha_{k+1}$  be the eigenvalues of  $H_{k+1}$ , and  $\beta_1 \geq \dots \geq \beta_k$  be the eigenvalues of  $H_k$ .

It follows from the inclusion principle that

$$\alpha_1 \geq \beta_1 \geq \dots \geq \beta_k \geq \alpha_{k+1}$$



## Recursive Proof (cont'd)

$\Leftarrow$ :  $\alpha_1 \geq \beta_1 \geq \dots \geq \beta_k \geq \alpha_{k+1}$  implies  
 $\alpha_1 > 0, \dots, \alpha_k > 0$ .

It remains to prove  $\alpha_{k+1} > 0$  to conclude the positive definiteness of  $H_{k+1}$ .

Using  $\alpha_1 \cdots \alpha_k \bullet \alpha_{k+1} = \det H_{k+1} > 0$ , we have  
 $\alpha_{k+1} > 0$ .

# ***Question***

**How to provide a fine characterization for the location of the eigenvalues of a matrix?**

## *Comment*

The location of eigenvalues of an LTI system determines the stability nature of the system. See **Lecture XII**.

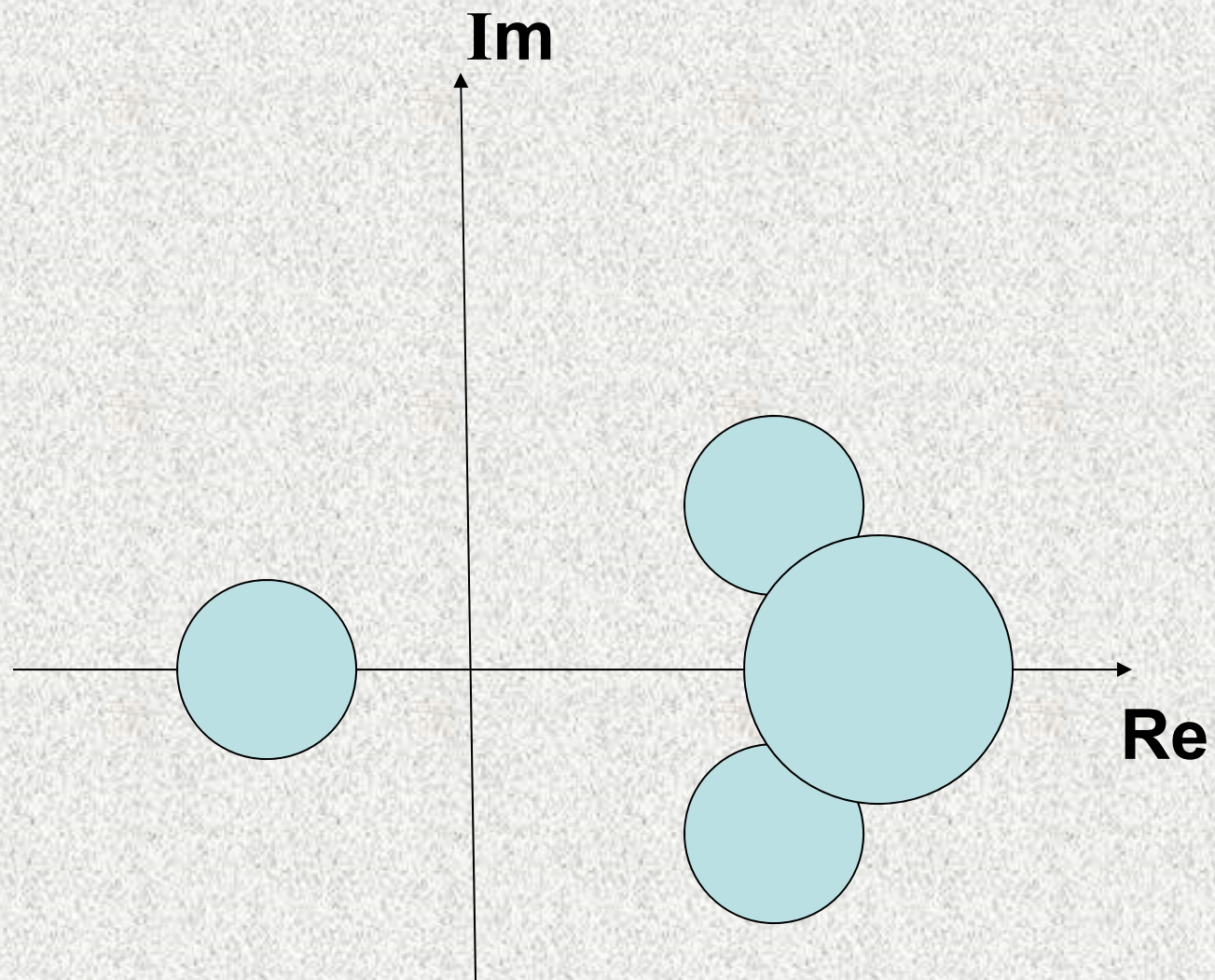
# Gersgorin Disc Theorem

1) All eigenvalues of  $A = [a_{ij}]_{n \times n}$  are located in the union

$$\text{of } n \text{ discs } \bigcup_{i=1}^n \left\{ z \in \mathbb{C} : |z - a_{ii}| \leq \sum_{j=1, j \neq i}^n |a_{ij}| \right\} \triangleq G(A).$$

2) If a union of  $k$  of these discs forms a connected region disjoint from the remaining  $n - k$  discs, then there are exactly  $k$  eigenvalues in this region.

*Proof:* See the textbook (2<sup>nd</sup> Ed., 2013, pp. 387-389).





# Essential Idea

Consider

$A = D + \varepsilon B$ ,  $\varepsilon$  sufficiently small  
with  $D = \text{diag}(a_{ii})$ .

**Observation:**

The eigenvalues of perturbed matrix  $A$  should be "close" to those of the unperturbed matrix  $D$ .

# Sketch of Proof

Take an eigenvector  $u$  associated with  $\lambda$ ,  
and let  $|u_m| = \max |u_j| \neq 0$ . Using  $(\lambda I - A)u = 0$ ,

$$(\lambda - a_{mm})u_m + \sum_{j \neq m} (-a_{mj})u_j = 0$$

$$\Rightarrow |\lambda - a_{mm}| \cdot |u_m| \leq \left| \sum_{j \neq m} a_{mj} u_j \right| \leq \sum_{j \neq m} |a_{mj}| \cdot |u_m|$$

$$\Rightarrow |\lambda - a_{mm}| \leq \sum_{j \neq m} |a_{mj}|, \text{ as wished.}$$

# Comment

Since  $A$  and  $A^T$  have the same eigenvalues, all eigenvalues of  $A = [a_{ij}]_{n \times n}$  are also located in the union

$$\text{of } n \text{ discs } \bigcup_{j=1}^n \left\{ z \in \mathbb{C} : |z - a_{jj}| \leq \sum_{i=1, i \neq j}^n |a_{ij}| \right\} \triangleq G(A^T).$$

*Clearly*, all eigenvalues of any matrix  $A$  are inside  $G(A) \cap G(A^T)$ .

# Example

By means of this theorem, we can give an estimate of all eigenvalues (when the exact values are **not** easy to obtain). For example,

$$A = \begin{pmatrix} 0 & 1 & -1 \\ 1.3 & 2 & -0.7 \\ 0.5 & 0.5i & 4i \end{pmatrix}.$$

# Exercise 1

Let  $A = (a_{ij})_{n \times n}$ . Show that

$$|\det A|^2 \leq \prod_{i=1}^n \left( \sum_{j=1}^n |a_{ij}| \right)^2.$$

When does the equality hold?



## Exercise 2

Assume  $B = (b_{ij})_{n \times n}$  satisfies

$$|b_{ii}| > \sum_{j=1, j \neq i}^n |b_{ij}|, \text{ for all } i = 1, \dots, n.$$

Show that  $\det B \neq 0$ .

## Exercise 3

Consider the matrix

$$A = \begin{pmatrix} 7 & -16 & 8 \\ -16 & 7 & -8 \\ 8 & -8 & -5 \end{pmatrix}$$

1) Use the Geršgorin theorem to say as much as you can about the location of the eigenvalues of  $A$  and its spectral radius.

2) Then, consider  $D^{-1}AD$ , with  $D = \text{diag}(p_1, p_2, p_3) > 0$ .

Can you obtain any improvement in your location of the eigenvalues via appropriate choice of parameters  $p_i$ .

# Homework 8

1. If  $\lambda_n$  is the least eigenvalue of a Hermitian

matrix  $H$ , show that  $\lambda_n = \min_{x \neq 0} \frac{\langle Hx, x \rangle}{\langle x, x \rangle}$ .

2. Find all possible values of  $\mu$  guaranteeing the positive-definiteness of

$$H = \begin{pmatrix} 1 & 2 & 3 \\ 2 & \mu & 4 \\ 3 & 4 & 5 \end{pmatrix}.$$

# Homework 8

3. Show that  $|x| = \max_k |x_k|$ , denoted as  $|x|_\infty$ ,

and  $|x| = \sum_k |x_k|$ , denoted as  $|x|_1$ ,

are both norms.

What are their associated matrix norms?