Operating System Structure

Multiprogramming batch systems

- A bit historical
- Needed for efficiency: Single user cannot keep CPU and I/O devices busy at all times
- Multiprogramming organizes jobs (code and data) so CPU always has one to execute
- A subset of total jobs in system is kept in memory
- One job selected and run via job scheduling
- When it has to wait (for I/O for example), OS switches to another job
- Typically used non-preemptive = cooperative multitasking

Timesharing/interactive systems

- Logical extension in which CPU switches jobs so frequently that users can interact with each job while it is running, creating interactive computing (response time should be < 1 second) -> preemptive
- Each user has at least one program executing in memory ⇒ process
- If several jobs ready to run at the same time
 ⇒ CPU scheduling selects
 one of them

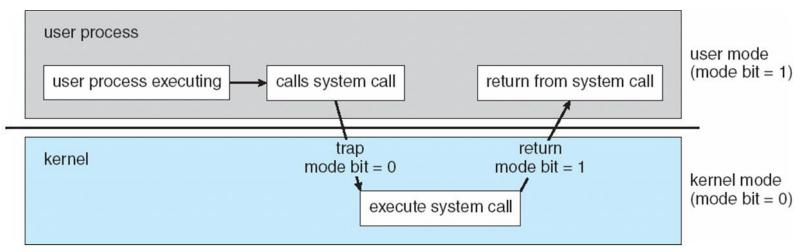
operating system job 1 job 2 job 3 job 4 512M

Operating-System Operations

- The operating system is invoked via interrupts. Invocation may be due to either:
 - Hardware interrupts by one of the devices.
 - A timer interrupt is a hardware interrupt caused by an on-chip timer, and is used to preempt applications and invoke the OS kernel on regular intervals (called OS tick)
 - The interrupt interval is usually 1 to 50 mS.
 - Interrupts from device controllers.
 - Software interrupts:
 - Operating system services are requested using the trap instruction (aka system request), which is a software interrupt.
 - Illegal operations:
 - Software error (e.g., division by zero) causes an exception
 - Illegal instruction or illegal access also cause exceptions.
- Note that the operating system may also be running its own threads (kernel threads).
 - The OS scheduler thus schedules user jobs/processes AND kernel threads

Operating-System Operations (cont.)

- Dual-mode operation of CPU allows OS to protect itself and other system components
 - Mode bit provided by hardware determines whether the CPU is in User mode or kernel mode.
 - Provides ability to distinguish when system is running user code or kernel code
 - Some instructions designated as privileged, only executable in kernel mode
 - Some memory locations may be configured to be only accessible in kernel mode.
 - System call (using the trap instruction) changes mode to kernel-mode.
 - Return from a system call resets the mode bit back to user-mode



Transition from user mode to kernel mode

Operating-System Operations (cont.)

- Increasingly CPUs support multi-mode operations:
 - Privileged/kernel modes: e.g. interrupts, kernel threads, etc.
 - Non-privileged/user modes: e.g. user threads/processes, virtual machine manager (VMM) mode for guest VMs, etc.

Open-Source Operating Systems

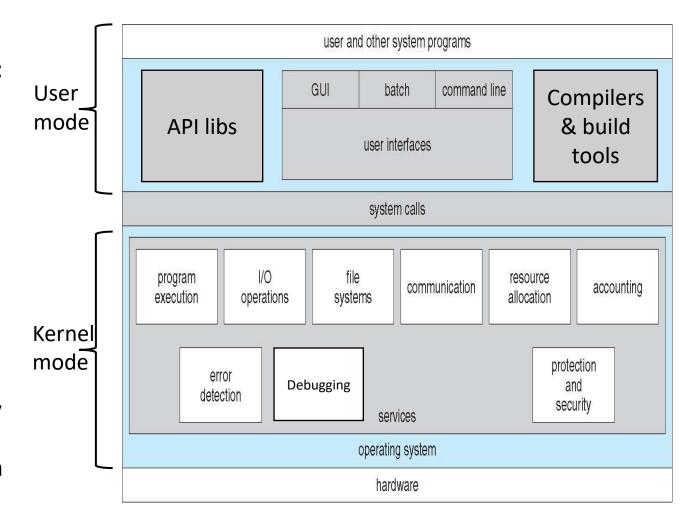
- Operating systems made available in source-code format rather than just binary closed-source
- Examples include GNU/Linux and BSD UNIX (e.g. FreeBSD and NetBSD) and a few more.
- When building or developing applications and drivers for an open source OS, good attention must be paid to the licensing model:
 - Reciprocal: e.g. GPLv1, GPLv2, etc.
 - Permissive: e.g. BSD, MIT, etc.
- Can be installed on VMMs like VMware Workstation (Free on Windows) or Virtualbox (open source and free on many platforms)
 - Use to run guest operating systems for exploration, testing or educational purposes.

Some notes

- Vector table can be remapped from ROM to another area of the main memory, once the kernel boots, and thus the kernel can then setup its interrupt handlers.
- C cannot access CPU registers. Also, before a C program can run, its environment needs to be initialized (e.g stacks, constants, pre-initialized variables, etc.).
 - For that reason, portions of the startup code in the boot ROM is often written in assembly language, but once it initializes the C environment, C code can be run thereafter.

2.1 Operating System Services

- One of the operating systems' main tasks is to provide an environment and services for application programs to run:
 - API Libraries
 - Compilers and build tools
 - User interface Almost all operating systems have a user interface (UI).
 - Varies between Command-Line (CLI), Graphics User Interface (GUI), Batch
 - Program execution The system must be able to load a program into memory and to run that program and also end its execution (normally or abnormally - indicating error)
 - I/O operations A running program may require I/O, which may involve a file or an I/O device



Operating-System Operations (cont.)

- Timer to prevent infinite loop / process hogging resources (in preemptive multitasking)
 - Timer is set to interrupt the CPU after some time period (e.g. 1 50 ms)
 - The interrupt is handled by the OS kernel.
 - The timer registers are memory-mapped to a memory area that can be accessed only in privileged mode.
 - The kernel sets up the timer for the next interrupt (timer tick) before scheduling a process to run.
 - This is in order to regain control or preempt a running process that exceeds its allotted time

Kernell

mode

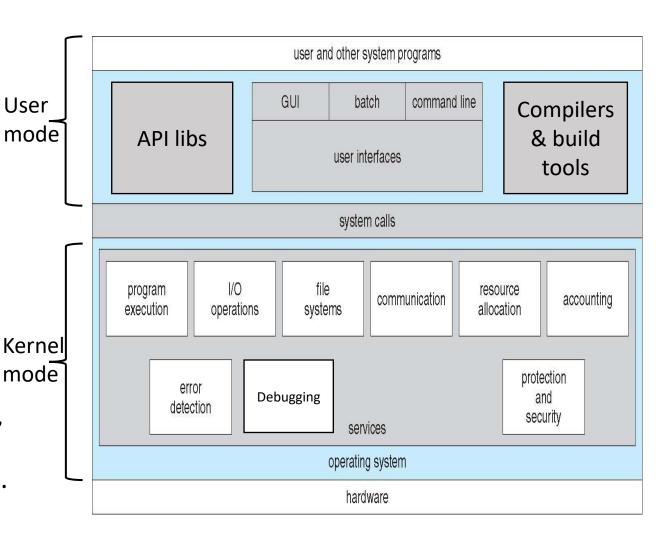
File-system manipulation - The file system is of particular interest.
 Programs need to read and write files and directories, create and delete diserthem, search them, list file mode Information, permission management.

Interprocess Communications –
 Processes may exchange information, on the same computer or between computers over a network

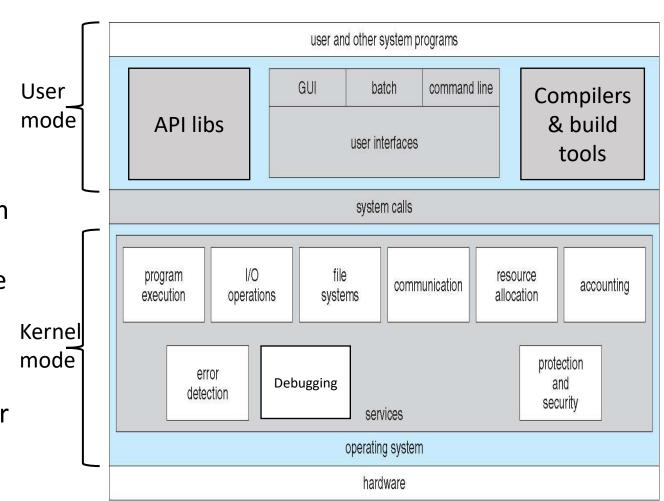
 Communications may be via shared memory or through message passing (packets or messages moved by the OS)

user and other system programs GUI batch command line Compilers **API libs** & build user interfaces tools system calls program resource communication accounting allocation execution operations systems protection error Debugging detection security services operating system hardware

- Error detection OS needs to be constantly aware of possible errors
 - May occur in the CPU and memory hardware, in I/O devices, or in user programs.
 - For each type of error, OS should take the appropriate action to ensure correct and consistent computing
- **Debugging:** OS provides debugging facilities which can greatly enhance the user's and programmer's abilities mode to efficiently use the system. In Linux, the kernel component that provides this facility is the "ptrace" system call. User mode debuggers (e.g. gdb) use this kernel facility to debug user programs.



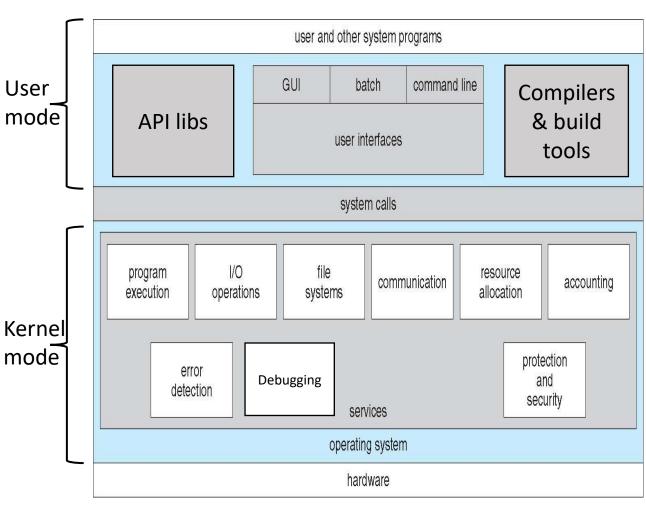
- The second main goal of an OS is to provide functions that ensure the efficient and secure operation of the system:
 - Resource allocation When multiple jobs (or processes) are running concurrently, resources must be allocated to each of them
 - Many types of resources -CPU cycles, main memory, file storage, I/O devices.
 - Accounting To keep track of which users/processes use how much and what kinds of computer resources (may collect statistics useful for researchers or system admins for detecting system misuse or intrusion).



Protection and security - The owners of information stored in a multiuser or networked computer system may want to control use of User that information, concurrent mode processes should not interfere with each other

 Protection involves ensuring that all access to system resources is controlled

 Security of the system from outsiders requires user authentication, extends to defending external I/O devices from invalid access attempts

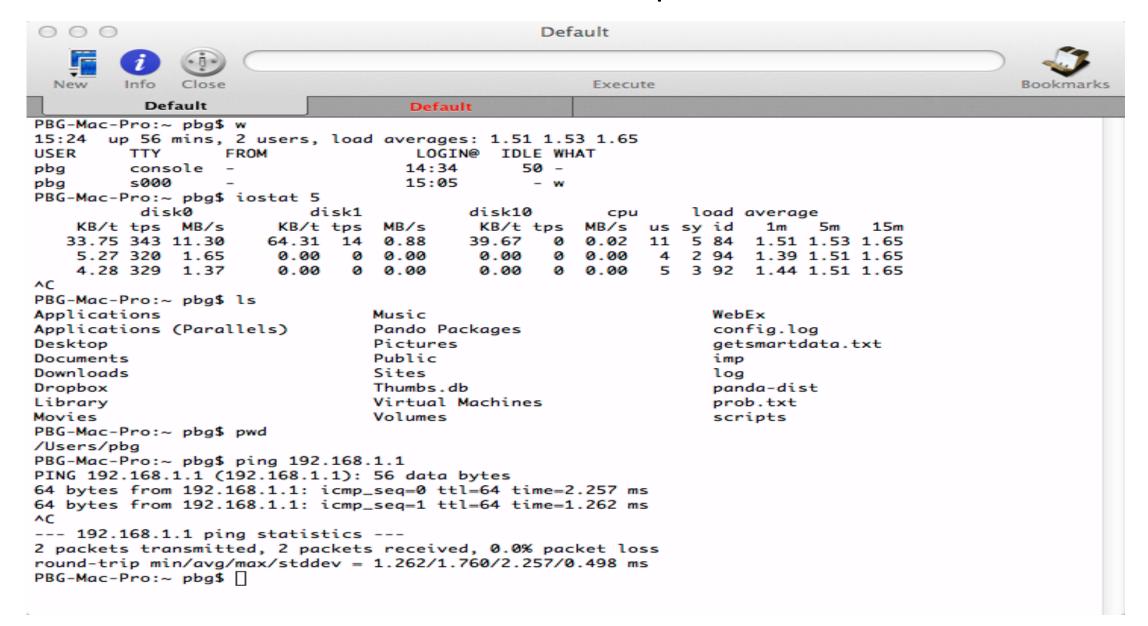


2.2 Operating System's User Interface - CLI

CLI or command interpreter allows direct command entry

- Usually implemented as a systems program
- Sometimes multiple flavors implemented shells (e.g. c shell, Bourne shell, bash, korn shell, ash, etc.).
- Primarily fetches a command from user and executes it
- Two different implementations:
 - Commands are built into the shell (e.g. BusyBox, widely used in embedded Linux).
 - Commands are just names of other programs that execute the command.
 In this implementation, adding new features doesn't require shell
 modification (For Linux, usually placed at /bin, as required by the Linux
 Foundation "File System Hierarchy", FSH)

Bourne Shell Command Interpreter

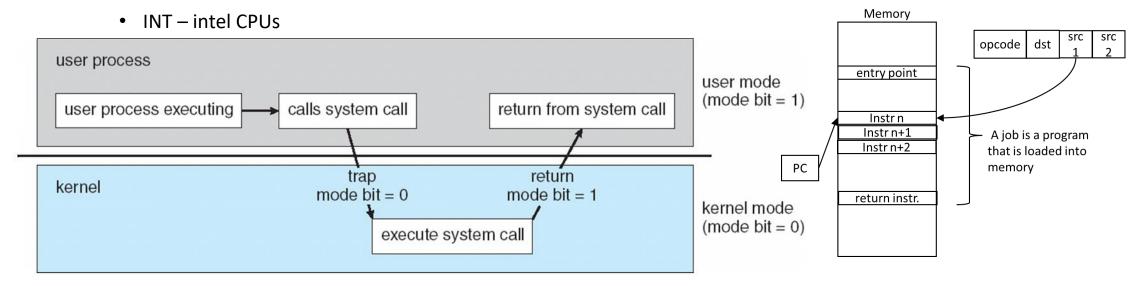


User Operating System Interface - GUI

- User-friendly desktop metaphor interface
 - Invented at Xerox PARC in 1970 (The first computer to use an early version of the desktop metaphor was the experimental Xerox Alto and the first commercial computer that adopted this kind of interface was the Xerox Alto and the first commercial computer that adopted this kind of interface was the Xerox Alto and the first commercial computer that adopted this kind of interface was the Xerox Alto.
 - Usually mouse, keyboard, and monitor
 - Icons represent files, programs, actions, etc
 - Clicking mouse buttons over objects in the interface cause different actions (provide information, options, execute function, open directory, etc.)
- Most of today's systems include both CLI and GUI interfaces
 - Microsoft Windows is GUI with CLI "command" shell
 - Apple Mac OS X is "Aqua" GUI interface with UNIX kernel underneath and shells available
 - Unix and Linux have CLI with optional GUI interfaces (CDE, KDE, GNOME)

2.3 System Calls

- User-mode program's interface to the services provided by the OS
 - User mode programs cannot directly call driver or operating system functions. Instead they
 need to use system calls.
 - System calls may also be referred to as "supervisor call", "trap" or sometimes "software interrupt"
 - The application program uses a special machine instruction to perform a system call:
 - SWI ARM CPUs



Transition from user mode to kernel mode (from Chapter 1)

System Calls – cont.

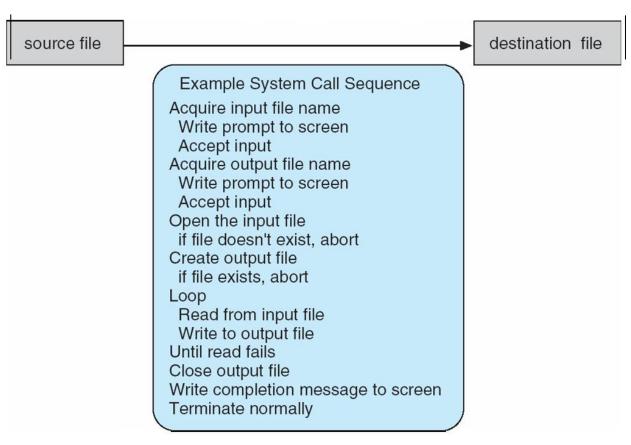
Mostly accessed by programs via a high-level Application Programming Interface
 (API) libraries (e.g. libc for unix/linux) rather than direct system call use

- Three common APIs are:
 - Win32 API for Windows
 - POSIX API for POSIX-based systems (including virtually all versions of UNIX, Linux, and Mac OS X)
 - Java API for the Java virtual machine (JVM)

Note that unless otherwise stated, the system-call names used throughout this course are generic

Example of System Calls

 The example below demonstrates the steps needed to copy the contents of one file to another file → A sequence of system calls results



Example of Standard API

EXAMPLE OF STANDARD API

As an example of a standard API, consider the read() function that is available in UNIX and Linux systems. The API for this function is obtained from the man page by invoking the command

man read

on the command line. A description of this API appears below:

```
#include <unistd.h>
ssize_t read(int fd, void *buf, size_t count)

return function parameters
value name
```

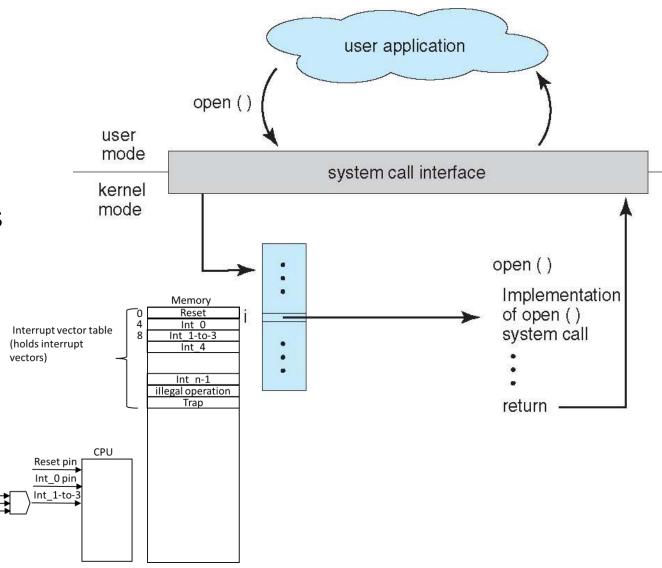
A program that uses the read() function must include the unistd.h header file, as this file defines the ssize_t and size_t data types (among other things). The parameters passed to read() are as follows:

- int fd—the file descriptor to be read
- void *buf—a buffer where the data will be read into
- size_t count—the maximum number of bytes to be read into the buffer

On a successful read, the number of bytes read is returned. A return value of 0 indicates end of file. If an error occurs, read() returns -1.

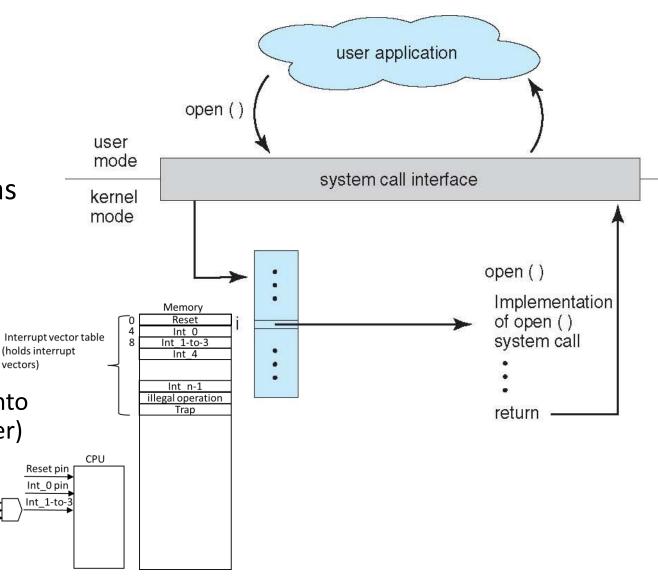
System Call Implementation

- Typically, a number associated with each system call
 - System-call interface
 maintains a table indexed
 according to these numbers
- The system call interface invokes the intended system call in OS kernel and returns status of the system call and any return values



System Call Implementation (cont.)

- The caller need not know anything about how the system call is implemented
 - Just needs to obey API and understand what OS will do as a result of the call
 - Most details of OS interface hidden from programmer by API
 - Managed by run-time support vectors)
 library (set of functions built into
 libraries included with compiler)

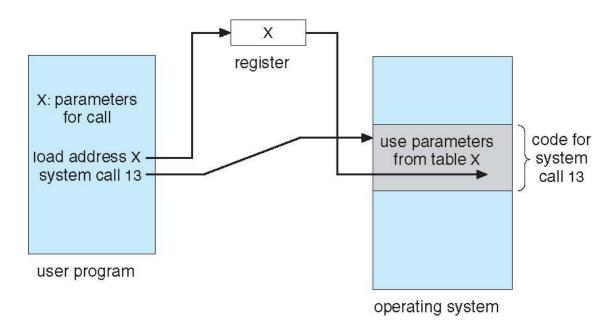


System Call Parameter Passing

- Often, more information is required than simply identity of desired system call
 - Exact type and amount of information vary according to system function called
- Three general methods used to pass parameters to the OS
 - 1. Simplest: pass the parameters in registers
 - Disadvantage: In some cases, may be more parameters than registers

System Call Parameter Passing – cont.

- 2. Parameters stored in a block in memory, and address of block/table passed as a parameter in a register
 - This approach taken by Linux and Solaris
- 3. Parameters placed, or pushed, onto the stack by the program and popped off the stack by the operating system
- Unlike the registers method, the block and stack methods do not limit the number or length of parameters being passed



Parameter Passing via memory block/table

2.4 Types of System Calls

- Process control (and support)
 - create process, terminate process, end or abort
 - load, execute
 - get process attributes, set process attributes
 - wait for time
 - wait event, signal event
 - allocate and free memory
 - Dump memory if error
 - Debugger for determining bugs in a program
 - Locks for managing access to shared data between processes

Types of System Calls (cont.)

- File management
 - create file, delete file
 - open, close file
 - read, write, reposition
 - get and set file attributes (e.g. filename, type, protection code, accounting info, etc.)
- Device management
 - request device, release device (to exclusive access to a device)
 - read, write, reposition
 - get device attributes, set device attributes
 - logically attach or detach devices (make it look like a file on the file system)

Types of System Calls (Cont.)

- Information
 - get system time or date, set time or date
 - get system data (e.g. OS version, number of users, memory or disk space, etc.).
 - Get the time profile of a process (via regular timer interrupts)
 - get and set process, file, or device attributes
- Communications
 - create, delete, open and close communication connection
 - In message passing model, processes can send and receive messages to host name or process name (name is first translated to a process ID (PID))
 - A process waiting for a connection request is a server or a Daemon
 - In Shared-memory model, processes create and gain access to memory regions shared with other processes.
 - Message passing is useful for small messages, while shared memory is preferred in larger messages.

Types of System Calls (Cont.)

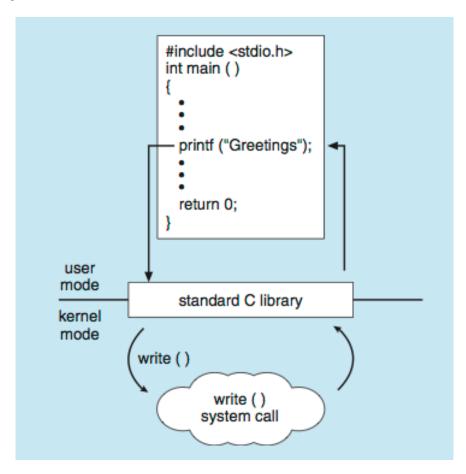
- Protection (of resources)
 - Control access to resources (e.g. files, disks, memory locations, etc.)
 - Get and set permissions of resources
 - Allow and deny user access of resources.

Examples of Windows and Unix System Calls

| | Windows | Unix |
|----------------------------|--|--|
| Process Control | <pre>CreateProcess() ExitProcess() WaitForSingleObject()</pre> | <pre>fork() exit() wait()</pre> |
| File Manipulation | <pre>CreateFile() ReadFile() WriteFile() CloseHandle()</pre> | <pre>open() read() write() close()</pre> |
| Device Manipulation | SetConsoleMode() ReadConsole() WriteConsole() | ioctl() read() write() |
| Information Maintenance | <pre>GetCurrentProcessID() SetTimer() Sleep()</pre> | <pre>getpid() alarm() sleep()</pre> |
| Communication | <pre>CreatePipe() CreateFileMapping() MapViewOfFile()</pre> | <pre>pipe() shmget() mmap()</pre> |
| Protection | SetFileSecurity() InitlializeSecurityDescriptor() SetSecurityDescriptorGroup() | chmod() umask() chown() |

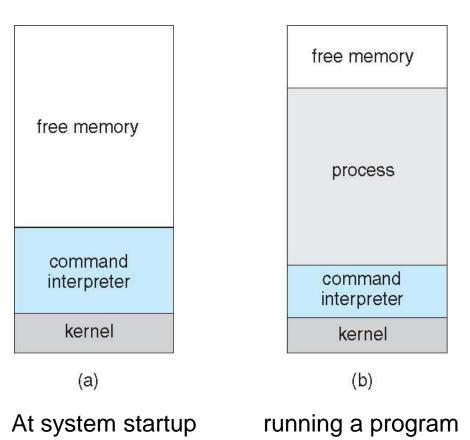
Standard C Library Example

 C program invoking printf() library call, which calls write() system call



Process control example - MS-DOS

- Single-tasking
- Shell invoked when system booted
- Simple method to run program
- Initial versions had a single memory space
- Loads program into memory, overwriting all but the kernel. Only a minimal set of shell routines are kept.
- Program exit -> remainder of shell reloaded



Process control example - FreeBSD

- Unix variant
- Multitasking
- User login -> invoke user's choice of shell
- Shell executes fork() system call to create process
 - Calls exec() to load program into process
 - Shell waits for process to terminate or continues with user commands
- Process exits with:
 - code = 0 no error
 - code > 0 error code

process D free memory process C interpreter process B kernel

2.5 System Programs and utilites

- Most users' view of the operation system is defined by system programs, not the actual system calls
 - Provide a convenient environment for program execution
 - Some of them are simply user interfaces to system calls; others are considerably more complex.
- File management Create, delete, copy, rename, print, dump, list, and generally manipulate files and directories

Status information

- Provide simple info such as date, time, amount of available memory, disk space or number of users
- May provide detailed info such as performance, logging, and debugging information
- Some systems implement a registry used to store and retrieve configuration information

System Programs (Cont.)

File modification

- Text editors to create and modify files
- Special commands to search contents of files or perform transformations of the text (e.g. grep)
- **Programming-language support** Compilers, assemblers, debuggers and interpreters sometimes provided. May also provide a debugging system (for higher level as well as machine language).
- **Program loading and execution** provides ability to load a program into main memory, as well as linking it to shared libraries (.dll in windows or .so in linux/unix)
- **Communications** Provide the **mechanism** for creating virtual connections among processes, users, and computer systems.

System Programs (Cont.)

Background Services

- These are system programs that are run automatically. Known as services, subsystems, daemons
- Some run at system startup (or boot) and terminate at some point later.
- Others run from system boot to shutdown
- Ex: A network daemon may be listening to connection requests, and then connects them to the appropriate service.
- Provide other facilities like disk checking, error logging, printing
- Run in user context, not kernel context

Application programs

- Don't pertain to system
- Run by users
- Not typically considered part of OS
- Launched by command line, mouse click, finger poke
- e.g. web browsers, email clients, word processors, games, etc.