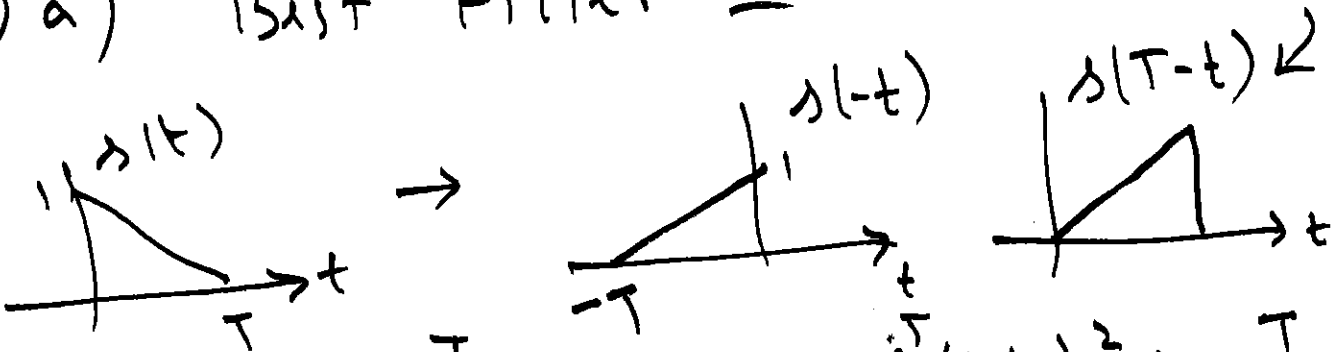
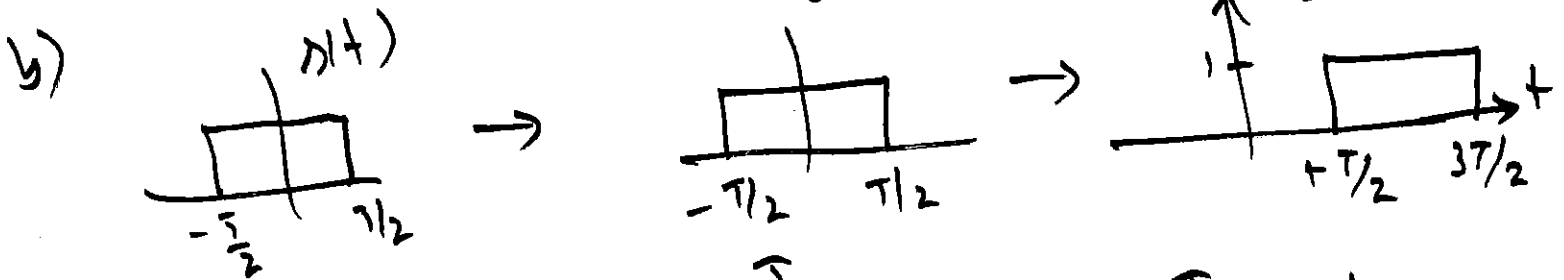


EL 6303  
HW #11 Solutions

1) a) Best Filter  $\equiv$  Matched Filter



$$SNR_{\max} = \frac{1}{\sigma^2} \int_0^T |s(t)|^2 dt = \frac{1}{\sigma^2} \int_0^T (t/T)^2 dt = \frac{T}{3\sigma^2}$$



$$SNR_{\max} = \frac{1}{\sigma^2} \int_{-T/2}^{T/2} 1^2 dt = \frac{T}{\sigma^2}$$

2)  $\hat{s} = H \underline{y} = H \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} ; \underline{y} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} s+n \\ s+n \end{pmatrix}$

a) Best Estimator:

$$H = R_{yy}^{-1} R_{sy}$$

$$R_{yy} = E(\underline{y} \underline{y}^T) = \begin{pmatrix} E(s+n)^2 & E(s^2 n) \\ E(s^2 n) & E(s^2 n^2) \end{pmatrix}$$

$$= \begin{pmatrix} \sigma_s^2 + \sigma_n^2 & M \sigma_s^2 \\ M \sigma_s^2 & \sigma_n^2 \end{pmatrix}$$

$$\underline{2} \quad R_{YY}^{-1} = \frac{1}{(\sigma_s^2 + \sigma_n^2) \sigma_n^2 - \mu^2 \sigma_s^4} \begin{pmatrix} \sigma_n^2 & -\mu \sigma_s^2 \\ -\mu \sigma_s^2 & \sigma_s^2 + \sigma_n^2 \end{pmatrix}$$

$$R_{SY} = E[SY^T] = E(sy_1, sy_2) \\ = [E(s(s+n)), E(s \cdot sn)] = [\sigma_s^2, \sigma_s^2 \mu]$$

$$H = R_{SY} R_{YY}^{-1} = \frac{\sigma_s^2}{\Delta} [\sigma_n^2, -\mu \sigma_s^2]$$

$$\text{where } \Delta = (\sigma_s^2 + \sigma_n^2) \sigma_n^2 - \mu^2 \sigma_s^4$$

H represents the best linear estimator for  $s$  based on  $Y = \begin{pmatrix} Y_1 \\ Y_2 \end{pmatrix}$ .

b) Minimum mean square error

$$\sigma_{min}^2 = R_{SS} - R_{SY} H^T \\ = \sigma_s^2 - \frac{\sigma_s^2}{\Delta} [\sigma_s^2 \sigma_n^2 - \mu^2 \sigma_s^4] \\ = \frac{\sigma_s^2}{\Delta} (\cancel{\sigma_s^2 \sigma_n^2} + \cancel{\sigma_n^4} - \mu^2 \cancel{\sigma_s^4} + \mu^2 \cancel{\sigma_s^4} + \sigma_s^2 \sigma_n^2)$$

### Problem 3

Let  $X_n = X(nT)$  represents a discrete-time W.S.S real stochastic process with auto-correlation function  $r_k = E(X_{n+k}X_n)$ . Suppose  $X_0$  is known, and  $X_1$  and  $X_2$  are unknowns.

- Determine the best estimator for the unknown  $X_1$  in terms of  $X_0$ . Find the associated minimum mean square error  $\sigma_1^2$ .
- Determine the best estimator for the unknown  $X_2$  in terms of  $X_0$ . Find the associated minimum mean square error  $\sigma_2^2$ .
- Show that  $\sigma_1^2 > \sigma_2^2$  in some cases and  $\sigma_1^2 < \sigma_2^2$  in other cases. Show an example where  $\sigma_2^2$  is smaller than  $\sigma_1^2$ .

**Solution:**

a.

$$\hat{X}_1 = a_0 X_0$$

$$\epsilon = X_1 - \hat{X}_1$$

$$E(\epsilon X_0) = 0 \text{ (Based on orthogonal principle)}$$

$$E(X_1 X_0) - a_0 E(X_0 X_0) = 0$$

$$a_0 = \frac{r_1}{r_0}$$

$$\therefore \text{the best estimator for } X_1 \text{ is } \hat{X}_1 = \frac{r_1}{r_0} X_0$$

$$\sigma_1^2 = E(|\epsilon|^2) = E(X_1^2) - 2a_0 E(X_1 X_0) + a_0^2 E(X_0^2) = r_0 \left( \frac{r_1^2}{r_0^2} + 1 \right) - 2 \frac{r_1}{r_0} \cdot r_1 = r_0 - \frac{r_1^2}{r_0}$$

b.

$$\begin{aligned}
\hat{X}_2 &= a_0 X_0 + a_1 X_1 \\
\epsilon &= X_2 - \hat{X}_2 \\
&\begin{cases} E(\epsilon X_0) = 0 \\ E(\epsilon X_1) = 0 \end{cases} \\
\Rightarrow &\begin{cases} r_2 - a_0 r_0 - a_1 r_1 = 0 \\ r_1 - a_0 r_1 - a_1 r_0 = 0 \end{cases} \\
\Rightarrow &\begin{cases} a_0 = \frac{r_1^2 - r_2 r_0}{r_1^2 - r_0^2} \\ a_1 = \frac{r_1(r_2 - r_0)}{r_1^2 - r_0^2} \end{cases} \\
&\therefore \text{the best estimator for } X_2 \text{ is:} \\
\hat{X}_2 &= \frac{r_1^2 - r_2 r_0}{r_1^2 - r_0^2} X_0 + \frac{r_1(r_2 - r_0)}{r_1^2 - r_0^2} X_1 \\
&= \frac{r_1^2 - r_2 r_0}{r_1^2 - r_0^2} X_0 + \frac{r_1(r_2 - r_0)}{r_1^2 - r_0^2} \cdot \frac{r_1}{r_0} X_1 \\
&= \frac{r_2}{r_0} X_0 \\
\sigma_2^2 &= E(|\epsilon|^2) \\
&= E(\epsilon X_2) - a_0 E(\epsilon X_0) - a_1 E(\epsilon X_1) \\
&= E(\epsilon X_2) \\
&= E(X_2^2) - 2 \frac{r_2}{r_0} E(X_2 X_0) + \frac{r_2^2}{r_0^2} E(X_0^2) \\
&= r_0 - \frac{r_2^2}{r_0}
\end{aligned}$$

c.

$$\begin{aligned}
\sigma_1^2 - \sigma_2^2 &= \frac{r_2^2}{r_0} - \frac{r_1^2}{r_0} \\
&= \frac{1}{r_0} (r_2^2 - r_1^2) \\
&= \frac{1}{r_0} (r_2 + r_1)(r_2 - r_1)
\end{aligned}$$

$\therefore$  when  $r_2 > r_1$ ,  $\sigma_1^2$  is larger and when  $r_2 < r_1$ ,  $\sigma_2^2$  is larger.

## Problem 4

Different versions of noisy data vs. a different take on the noise. Which is better?

i. Consider different versions of data

$$\begin{aligned}
Y_1 &= X + n \\
Y_2 &= X + w
\end{aligned}$$

versus

ii. another look at the noise

$$\begin{aligned} Y_1 &= X + n \\ Y_2 &= n + w \end{aligned}$$

Here  $X, n, w$  are zero mean uncorrelated random variables with variances  $\sigma_X^2$ ,  $\sigma_n^2$  and  $\sigma_w^2$  respectively.  $X$  is the desired unknown.

- Find the best estimator for  $X$  using  $Y_1$  and  $Y_2$  in the both cases (i) and (ii).
- Find the mean square error in the both cases above. Which set of data is preferable for estimating  $X$ ?

**Solution:**

$$\begin{pmatrix} Y_1 \\ Y_2 \end{pmatrix} = \begin{pmatrix} X + n \\ X + w \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} X + \begin{pmatrix} n \\ w \end{pmatrix}$$

$$R_{XY} = E[X(X + n), X(n + w)] = \sigma_X^2 [1, 1]$$

$$R_{YY} = \begin{bmatrix} \sigma_X^2 + \sigma_n^2 & \sigma_n^2 \\ \sigma_n^2 & \sigma_n^2 + \sigma_w^2 \end{bmatrix}$$

$$R_{YY}^{-1} = \frac{1}{(\sigma_X^2 + \sigma_n^2)\sigma_w^2 + \sigma_X^2\sigma_n^2} \begin{bmatrix} \sigma_X^2 + \sigma_w^2 & \sigma_X^2 \\ \sigma_X^2 & \sigma_X^2 + \sigma_n^2 \end{bmatrix}$$

$$H = R_{XY}R_{YY}^{-1} = \frac{\sigma_X^2}{(\sigma_w^2 + \sigma_n^2)\sigma_X^2 + \sigma_w^2\sigma_n^2} \begin{pmatrix} \sigma_w^2 \\ \sigma_n^2 \end{pmatrix}$$

$$\hat{X}_2 = HY = \frac{1}{(\sigma_n^2 + \sigma_w^2) + \frac{\sigma_n^2\sigma_w^2}{\sigma_X^2}} (\sigma_w^2 Y_1 + \sigma_n^2 Y_2)$$

$$\sigma_2^2 = R_{XX} - HR_{XY}$$

$$= \sigma_X^2 - \frac{\sigma_X^2(\sigma_w^2 + \sigma_n^2)\sigma_X^2}{\sigma_X^2(\sigma_n^2 + \sigma_w^2) + \sigma_n^2\sigma_w^2} = \frac{\sigma_X^2\sigma_w^2\sigma_n^2}{\sigma_X^2(\sigma_w^2 + \sigma_n^2) + \sigma_w^2\sigma_n^2}$$

$$= \frac{\sigma_X^2}{1 + \sigma_X^2\left(\frac{1}{\sigma_n^2} + \frac{1}{\sigma_w^2}\right)} < \sigma_1^2 = \frac{\sigma_X^2}{1 + \frac{\sigma_w^2}{\sigma_n^2}}$$

$$Y = \begin{pmatrix} Y_1 \\ Y_2 \end{pmatrix} = \begin{pmatrix} X + n \\ n + w \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} X + \begin{pmatrix} n \\ w + n \end{pmatrix}$$

$$R_{XY} = E[X(X + n), X(n + w)] = \sigma_X^2(1, 0)$$

$$R_{YY} = \begin{bmatrix} \sigma_X^2 + \sigma_n^2 & \sigma_n^2 \\ \sigma_n^2 & \sigma_n^2 + \sigma_w^2 \end{bmatrix}$$

$$R_{YY}^{-1} = \frac{1}{(\sigma_w^2 + \sigma_n^2)\sigma_X^2 + \sigma_n^2\sigma_w^2} \begin{bmatrix} \sigma_n^2 + \sigma_w^2 & \sigma_n^2 \\ \sigma_n^2 & \sigma_X^2 + \sigma_n^2 \end{bmatrix}$$

$$H = R_{XY}R_{YY}^{-1} = \frac{\sigma_X^2}{(\sigma_w^2 + \sigma_n^2)\sigma_X^2 + \sigma_n^2\sigma_w^2} \begin{pmatrix} \sigma_w^2 + \sigma_n^2 \\ -\sigma_n^2 \end{pmatrix}$$

$$\hat{X}_3 = HY = \frac{1}{1 + \frac{\sigma_n^2\sigma_w^2}{\sigma_X^2(\sigma_n^2 + \sigma_w^2)}} (Y_1 - \frac{\sigma_n^2}{\sigma_n^2 + \sigma_w^2} Y_2)$$

$$\begin{aligned} \sigma_3^2 &= R_{XX} - HR_{XY} \\ &= \sigma_X^2 - \frac{\sigma_X^2(\sigma_w^2 + \sigma_n^2)\sigma_X^2}{\sigma_X^2(\sigma_n^2 + \sigma_w^2) + \sigma_n^2\sigma_w^2} - \frac{\sigma_X^2\sigma_w^2\sigma_n^2}{\sigma_X^2(\sigma_w^2 + \sigma_n^2) + \sigma_w^2\sigma_n^2} \\ &= \frac{\sigma_X^2}{1 + \sigma_X^2(\frac{1}{\sigma_n^2} + \frac{1}{\sigma_w^2})} = \sigma_2^2 < \sigma_1^2 \end{aligned}$$

Both estimators have identical performance

## Problem 5

Let  $X, Y, Z$  be zero mean correlated random variables with common correlation coefficient equal to  $-\frac{1}{2}$  and all of the variances are equal to 1.

- Find the best linear estimate for  $Z$  in terms of  $X$  and  $Y$ .
- Find the best linear estimate for  $X$  in terms of  $Y$  and  $Z$ .
- What are the minimum mean square estimation errors in the above cases?

**Solution:**

a.

$$\hat{Z} = aX + bY$$

$$\epsilon = Z - \hat{Z} = Z - aX - bY$$

Othogonality principle says  $\epsilon$  perpendicular to data

$\epsilon$  perpendicular to X and  $\epsilon$  perpendicular to Y

$$\epsilon \text{ perpendicular to X} \rightarrow E(\epsilon X) = 0$$

$$E(\epsilon X) = E\{(Z - aX - bY)X\} = 0$$

$$aE(X^2) + bE(XY) = E(XZ) \quad (6)$$

$$\text{Similarly } \epsilon \text{ perpendicular to Y} \rightarrow E(\epsilon Y) = 0$$

$$E(\epsilon Y) = E\{(Z - aX - bY)Y\} = 0$$

$$aE(XY) + bE(Y^2) = E(ZY) \quad (7)$$

$$E(X^2) = E(Y^2) = E(Z^2) = 1$$

$$\text{Also } \rho = \frac{E(XY)}{\sigma_X \sigma_Y} = -\frac{1}{2} \rightarrow \rho = -\frac{1}{2}$$

$$E(XY) = E(YZ) = E(ZX) = \rho = -\frac{1}{2}$$

b.

Hence (6) and (7) becomes

$$a + \rho b = \rho \quad (8)$$

$$\rho a + b = \rho \quad (9)$$

Solving (8) and (9) we get

$$b(1 - \rho^2) = \rho - \rho^2 = \rho(1 - \rho)$$

$$b = \frac{\rho}{1 + \rho} = a \quad (10)$$

$$\hat{Z} = \frac{\rho}{1 + \rho}(X + Y) \quad (11)$$

$$\hat{X} = \frac{\rho}{1 + \rho}(Y + Z) \quad (12)$$

(11) and (12) are the best linear estimators.

c.

$$\begin{aligned}
E(\epsilon^2) &= E(\epsilon(Z - aX - bY)) = E(\epsilon Z) \\
\text{Since } E(\epsilon X) &= E(\epsilon Y) = 0 \\
E((Z - aX - bY)Z) &= E(Z^2 - aXZ - bYZ) \\
&= E(Z^2) - aE(XZ) - bE(YZ) \\
&= 1 - (a + b)\rho = 1 - \frac{\rho^2}{1 + \rho} \\
&= \frac{1 + \rho - \rho^2}{1 + \rho} > 0
\end{aligned}$$

## Problem 6

Given the datasets

$$Y_1 = s + n$$

and

$$Y_2 = s + w,$$

where  $s, n, w$  are zero mean independent random variables with variances  $\sigma_s^2$ ,  $\sigma_n^2$  and  $\sigma_w^2$ .

- Find the best estimator  $\hat{s}_1$  for  $s$  using  $Y_1$  and find the corresponding minimum mean square error  $\sigma_1^2$ .
- Find the best estimator  $\hat{s}_2$  for  $s$  using  $Y_1$  and  $Y_2$ , and find the corresponding minimum mean square error  $\sigma_2^2$ . Which one is smaller,  $\sigma_1^2$  or  $\sigma_2^2$ ?

**Solution:**

- Denote

$$Y = \begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix} = \begin{bmatrix} s + n \\ s + w \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} s + \begin{bmatrix} n \\ w \end{bmatrix}. \quad (1)$$

We know  $\mathbb{E}(w) = 0, \mathbb{E}(s) = 0, \mathbb{E}(n) = 0$ , so

$$R_{sY_1} = \sigma_s^2, \quad R_{Y_1 Y_1} = \sigma_s^2 + \sigma_n^2, \quad \Rightarrow H =; R_{sY_1}; R_{Y_1 Y_1}^{-1} = \frac{1}{1 + \frac{\sigma_n^2}{\sigma_s^2}}.$$

We know

$$s_1 = HY = \frac{1}{1 + \frac{\sigma_n^2}{\sigma_s^2}} Y_1$$

and the minimum MSE

$$\sigma_1^2 = \frac{\sigma_s^2}{1 + \frac{\sigma_n^2}{\sigma_s^2}} = \frac{\sigma_s^2 \sigma_n^2}{\sigma_n^2 + \sigma_s^2}$$



b. We know

$$\begin{aligned}
R_{sY} &= [s(s+n), s(s+w)] = \sigma_s^2[1, 1] \\
R_{YY} &= E(YY^*) \\
&= \begin{bmatrix} E((s+n)^2) & E((s+n)(s+w)) \\ E((s+w)(s+n)) & E((s+w)^2) \end{bmatrix} \\
&= \begin{bmatrix} \sigma_s^2 + \sigma_n^2 & \sigma_s^2 \\ \sigma_s^2 & \sigma_s^2 + \sigma_w^2 \end{bmatrix} \\
R_{YY}^{-1} &= \frac{1}{(\sigma_s^2 + \sigma_n^2)(\sigma_s^2 + \sigma_w^2) - \sigma_s^4} \begin{bmatrix} \sigma_s^2 + \sigma_n^2 & \sigma_s^2 \\ \sigma_s^2 & \sigma_s^2 + \sigma_w^2 \end{bmatrix} \\
H &= R_{XY} R_{YY}^{-1} = \frac{\sigma_s^2}{(\sigma_s^2 + \sigma_n^2)(\sigma_s^2 + \sigma_w^2) - \sigma_s^4} \begin{bmatrix} \sigma_w^2 \sigma_n^2 & \sigma_n^2 \end{bmatrix} \\
\hat{s}_2 &= HY = \frac{\sigma_s^2}{(\sigma_n^2 + \sigma_w^2) + \frac{\sigma_n^2 \sigma_w^2}{\sigma_s^2}} [\sigma_w^2 Y_1 + \sigma_n^2 Y_2] \\
\sigma_2^2 &= \sigma_s^2 - H R_{sY} \\
&= \sigma_s^2 - \frac{\sigma_s^4 (\sigma_w^2 + \sigma_n^2)}{(\sigma_n^2 + \sigma_w^2) + \frac{\sigma_n^2 \sigma_w^2}{\sigma_s^2}} \\
&= \frac{\sigma_s^2 \sigma_n^2 \sigma_w^2}{\sigma_n^2 \sigma_w^2 + \sigma_s^2 (\sigma_n^2 + \sigma_w^2)} \\
&= \frac{\sigma_s^2}{1 + \sigma_s^2 \left( \frac{1}{\sigma_n^2} + \frac{1}{\sigma_w^2} \right)} < \frac{\sigma_s^2}{1 + \frac{\sigma_s^2}{\sigma_n^2}} = \sigma_1^2
\end{aligned}$$

Therefore  $\sigma_2^2$  is smaller. So The second data estimator is better.