Proj4 - problem1



과목명 멀티코어컴퓨팅 02분반

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(a) environment

OS - window

CPU - 11th Gen Intel(R) Core(TM) i7-1195G7

GPU - Colab use.

(b) how to compile

openmp : using wsl and g++

\$g++ -fopenmp openmp_ray.cpp

cuda: using colab

>> !nvcc cuda_ray.cu

(c) how to execute

openmp: using wsl and g++

\$./a.out 8 result.ppm

cuda: using colab

>> !./a.out

openmp_ray.cpp source code

```
#include <string.h>
#include <math.h>
#include <omp.h>
#define CUDA 0
#define OPENMP 1
#define SPHERES 20
#define rnd( x ) (x * rand() / RAND_MAX)
#define INF 2e10f
#define DIM 2048
struct Sphere {
   float r,b,g;
float radius;
    float x,y,z;
        float dy = oy - y;
        if (dx*dx + dy*dy < radius*radius) {</pre>
             float dz = sqrtf( radius*radius - dx*dx - dy*dy );
             *n = dz / sqrtf( radius * radius );
             return dz + z;
         return -INF;
```

```
void ppm_write(unsigned char* bitmap, int xdim, int ydim, FILE* fp)

int i, x, y;
fprintf(fp, "P3\n");
fprintf(fp, "%d %d\n", xdim, ydim);
fprintf(fp, "255\n");
for (y = 0; y < ydim; y++) {
    for (x = 0; x < xdim; x++) {
        i = x + y * xdim;
        fprintf(fp, "%d %d %d ", bitmap[4 * i + 1], bitmap[4 * i + 2]);
}

fprintf(fp, "\n");
}

fprintf(fp, "\n");
}
</pre>
```

```
int main(int argc, char* argv[])
   int no_threads;
   int option;
   unsigned char* bitmap;
   srand(time(NULL));
   if (argc != 3) {
       printf("[option] 0: CUDA, 1~16: OpenMP using 1~16 threads\n");
      printf("for example, '> a.out 8 result.ppm' means executing OpenMP with 8 threads\n");
   FILE* fp = fopen(argv[2], "w");
   if (strcmp(argv[1], "0") == 0) option = CUDA;
     option = OPENMP;
       no_threads = atoi(argv[1]);
   omp_set_num_threads(no_threads);
   struct Sphere* temp_s = (struct Sphere*)malloc(sizeof(struct Sphere) * SPHERES);
   for (int i = 0; i < SPHERES; i++) {
      temp_s[i].r = rnd(1.0f);
       temp_s[i].g = rnd(1.0f);
      temp_s[i].b = rnd(1.0f);
      temp_s[i].x = rnd(2000.0f) - 1000;
      temp_s[i].y = rnd(2000.0f) - 1000;
      temp_s[i].z = rnd(2000.0f) - 1000;
       temp_s[i].radius = rnd(200.0f) + 40;
   //Allocate memory for the bitmap
   bitmap = (unsigned char*)malloc(sizeof(unsigned char) * DIM * DIM * 4);
```

cuda_ray.cu

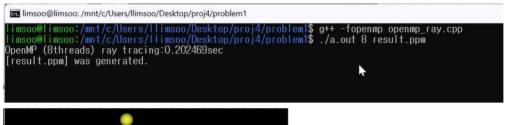
```
#include <stdio.h>
                                                                              ↑ ↓ ⊝ 目 ‡ 見 🔒 :
     #include <string.h>
     #include <stdlib.h>
     #include <time.h>
     #include <math.h>
     #include <sys/time.h>
     #include <cuda.h>
     #include <chrono>
     using namespace std::chrono;
     #define CUDA 0
     #define OPENMP 1
     #define SPHERES 20
     #define DIM 2048
     \texttt{\#define rnd(x) (x * rand() / RAND\_MAX)}
     #define INF 2e10f
     struct Sphere {
         float r, b, g;
         float radius;
         float x, y, z;
         float (*hit)(struct Sphere* s, float ox, float oy, float* n);
     };
     // CUDA
     __device__ float hit(struct Sphere* s, float ox, float oy, float* n) {
        float dx = ox - s \rightarrow x;
         float dy = oy - s -> y;
         if (dx * dx + dy * dy < s \rightarrow radius * s \rightarrow radius) {
             float dz = sqrtf(s\rightarrow radius * s\rightarrow radius - dx * dx - dy * dy);
             *n = dz / sqrtf(s->radius * s->radius);
             return dz + s->z;
        return -INF;
```

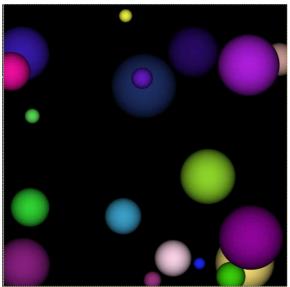
```
// CUDA kernel function
                                                                     ↑ ↓ ⊖ 目 ‡ ₪ 📋 :
 __global__ void kernel(struct Sphere* s, unsigned char* ptr) {
     int \times = blockldx.x * blockDim.x + threadldx.x;
     int y = blockldx.y * blockDim.y + threadldx.y;
     int offset = x + y * DIM;
    float ox = (x - DIM / 2);
    float oy = (y - DIM / 2);
    float r = 0, g = 0, b = 0;
    float maxz = -INF;
     for (int i = 0; i < SPHERES; i++) {
        float n;
         float t = hit(&s[i], ox, oy, &n);
         if (t > maxz) {
            float fscale = n;
            r = s[i].r * fscale;
            g = s[i].g * fscale;
            b = s[i].b * fscale;
            maxz = t;
        }
    }
    ptr[offset * 4 + 0] = (int)(r * 255);
    ptr[offset * 4 + 1] = (int)(g * 255);
    ptr[offset * 4 + 2] = (int)(b * 255);
    ptr[offset * 4 + 3] = 255;
void ppm_write(unsigned char* bitmap, int xdim, int ydim, FILE* fp) {
     int i, x, y;
     fprintf(fp, "P3₩n");
    fprintf(fp, "%d %d\n", \timesdim, ydim);
     fprintf(fp, "255₩n");
     for (y = 0; y < ydim; y++) {
        for (x = 0; x < xdim; x++) {
            i = x + y * xdim;
            fprintf(fp, "%d %d %d ", bitmap[4 * i], bitmap[4 * i + 1], bitmap[4 * i + 2]);
        fprintf(fp, "\mun");
```

```
int main(void) {
                                                                      ↑ ↓ © 目 ‡ 見 i :
    unsigned char* bitmap;
    srand(time(NULL));
    FILE* fp = fopen("cudaresult", "w");
    struct Sphere* temp_s = (struct Sphere*)malloc(sizeof(struct Sphere) * SPHERES);
    for (int i = 0; i < SPHERES; i++) {
        temp_s[i].r = rnd(1.0f);
        temp_s[i].g = rnd(1.0f);
        temp_s[i].b = rnd(1.0f);
        temp_s[i].x = rnd(2000.0f) - 1000;
        temp_s[i].y = rnd(2000.0f) - 1000;
        temp_s[i].z = rnd(2000.0f) - 1000;
        temp_s[i].radius = rnd(200.0f) + 40;
    bitmap = (unsigned char*)malloc(sizeof(unsigned char) * DIM * DIM * 4);
    auto start = high_resolution_clock::now();
    //Allocate memory on the GPU
    struct Sphere* dev_s;
    unsigned char* dev_bitmap;
    cudaMalloc((void**)&dev_s, sizeof(struct Sphere) * SPHERES);
    \verb|cudaMalloc|((\verb|void**|) & \verb|dev_bitmap|, sizeof(unsigned char) * DIM * DIM * 4);|\\
    // Copy data from CPU to GPU
    cudaMemcpy(dev_s, temp_s, sizeof(struct Sphere) * SPHERES, cudaMemcpyHostToDevice);
    // Lanch the CUDA kernel
    dim3 blocksPerGrid(DIM / 16, DIM / 16);
    dim3 threadsPerBlock(16, 16);
    kernel<<<blooksPerGrid, threadsPerBlock>>>(dev_s, dev_bitmap);
    //Copy the result image data from GPU to CPU
    cudaMemcpy(bitmap, dev_bitmap, sizeof(unsigned char) * DIM * DIM * 4, cudaMemcpyDeviceToHost);
   //Free GPU memory
   cudaFree(dev_s);
   cudaFree(dev_bitmap);
   auto stop = high_resolution_clock::now();
   auto duration = duration_cast<milliseconds>(stop - start);
   printf("CUDA ray tracing :%d sec",(int)duration.count());
   ppm_write(bitmap, DIM, DIM, fp);
   fclose(fp);
   printf("[cudaresult.ppm] was generated.");
   free(bitmap);
   free(temp_s);
   return 0;
```

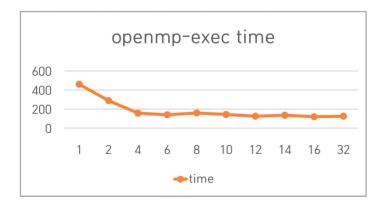
Test Result

OPENMP





# thread	1	2	4	6	8
time	460.114	287.943	157.142	139.684	158.794
# thread	10	12	14	16	32
time	143.624	124.994	135.345	120.164	124.558

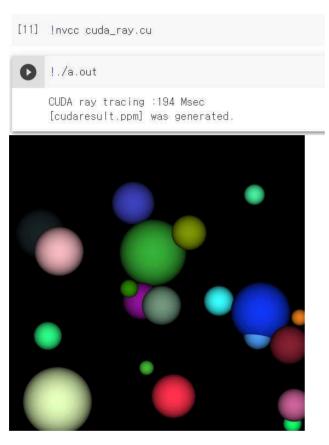


OpenMP is a programming model for multi-threading, making it easy to implement parallel tasks. Use the #pragmaompparallel for statement to run the kernel function as a multi-thread. This allows kernel functions to run simultaneously across multiple threads to parallelize calculations. This

reduces calculation time. Running with OpenMP took 460 msec when calculated with a single thread, but running time was reduced to 120 msec when calculated with a multi-thread using OpenMP. This shows that using OpenMP can improve computation speed through parallel processing.

CUDA

exec time: 194 msec



CUDA allows you to improve computation speed through parallel processing compared to the CPU. CUDA code leverages the parallel processing power of the GPU to accelerate image rendering.

In the given code, the kernel function runs as the CUDA kernel. The kernel function performs ray tracing for each pixel and calculates the intersection with each spear to determine the color. Because these calculations are processed in parallel, CUDA allows multiple threads to run simultaneously to speed up the calculation.