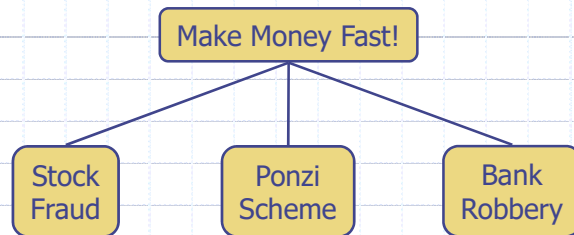


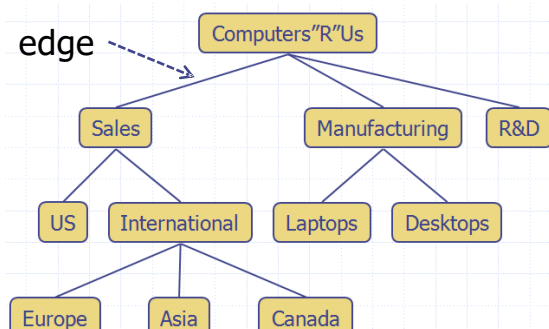
Trees



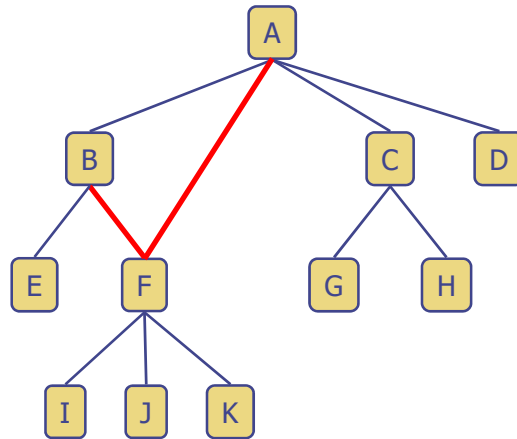
1

What is a Tree

- A tree is an abstract model of a hierarchical structure
- A tree T is a collection of nodes with nonlinear structure, called a **parent-child** relation
 - If nonempty, it has a special node, called the **root** of T , that has no parent
 - Each node v of T , except root, has a unique **parent** node w ; every node with parent w is a **child** of w
- A unique **path** exists from the root to every other node.
- Applications:
 - Organization charts
 - File systems



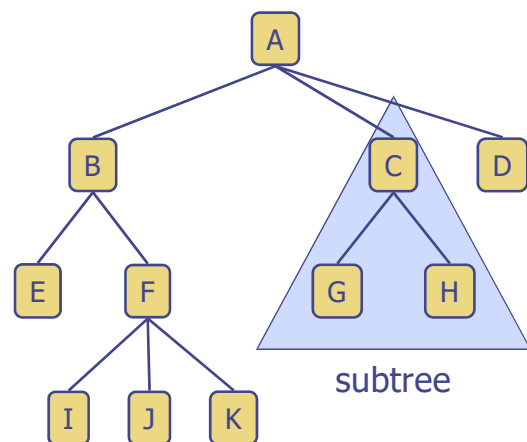
Not a Tree



3

Tree Terminology

- ❑ **Root:** node without parent (A)
- ❑ **Internal node:** node with at least one child (A, B, C, F)
- ❑ **External node** (a.k.a. **leaf**): node without children (E, I, J, K, G, H, D)
- ❑ **Ancestors** of a node: parent, grandparent, grand-grandparent, etc.
- ❑ **Descendants** of a node: child, grandchild, grand-grandchild, etc.
- ❑ **Subtree:** tree consisting of a node and its descendants
- ❑ **Ordered tree:** linear ordering defined for children of each node



4

Tree ADT

- We use positions to abstract nodes (same as node in tree)
- Generic methods:
 - integer **size()**
 - boolean **isEmpty()**
 - Iterator **iterator()**
 - Iterable **positions()**
- Accessor methods:
 - position **root()**
 - position **parent(p)**
 - Iterable **children(p)**
- ◆ Query methods:
 - boolean **isInternal(p)**
 - boolean **isExternal(p)**
 - boolean **isRoot(p)**
- ◆ Update method:
 - element **replace (p, o)**
- ◆ Additional update methods may be defined by data structures implementing the Tree ADT

5

Depth of a Node

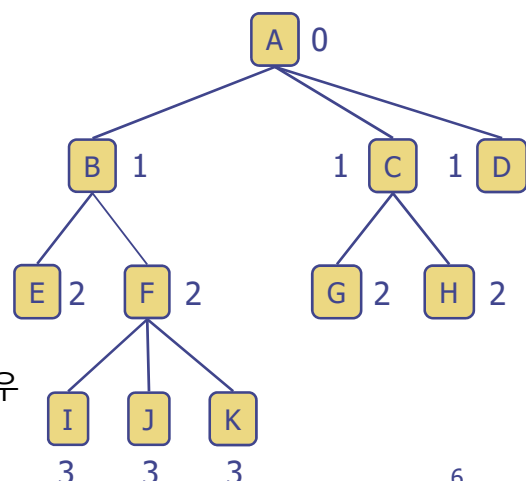
- The depth of a node is the number of its ancestors, excluding itself
 - $\text{depth}(A) = 0$, $\text{depth}(B) = 1$, $\text{depth}(J) = 3$

Algorithm *depth*(*T*, *v*)

```

if T.isRoot(v)
  return 0
else
  return 1 + depth(T, T.parent(v))
  
```

트리가 n 개의 노드로 구성되어 질 때,
worst case는 모든 노드의 child 가 하나일 경우
 $O(n)$ 이다.



6

Height of a Node

- The height(v) in a tree T is
 - If v is an external node, then $\text{height}(v) = 0$
 - Otherwise, $\text{height}(v) = 1 + \max.$ height of its children

Algorithm *height*(T, v)

if $T.\text{isExternal}(v)$

return 0

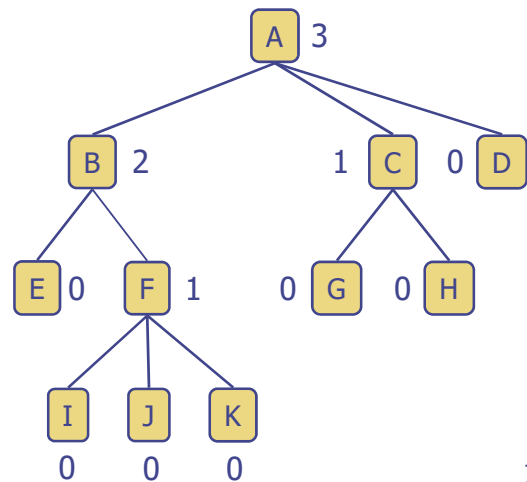
else

$h \leftarrow 0$

for each child w of v in T do

$h \leftarrow \max(h, \text{height}(T, w))$

return $1+h$



7

Height of a Tree

- The height of a tree T is the **height of the root**
- The height of a tree T is equal to the **maximum depth of a external node** of T

Algorithm *height*(T)

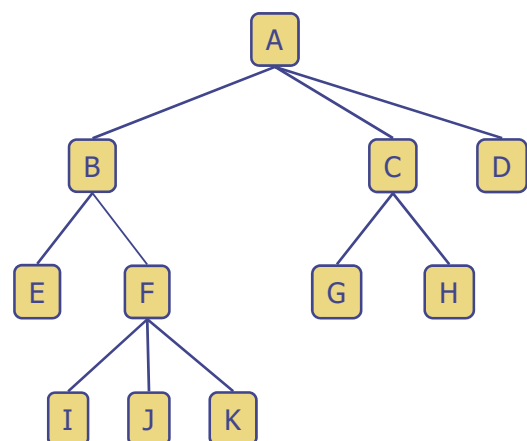
$h \leftarrow 0$

for each node v in T do

if $T.\text{isExternal}(v)$ then

$h \leftarrow \max(h, \text{depth}(T, v))$

return h

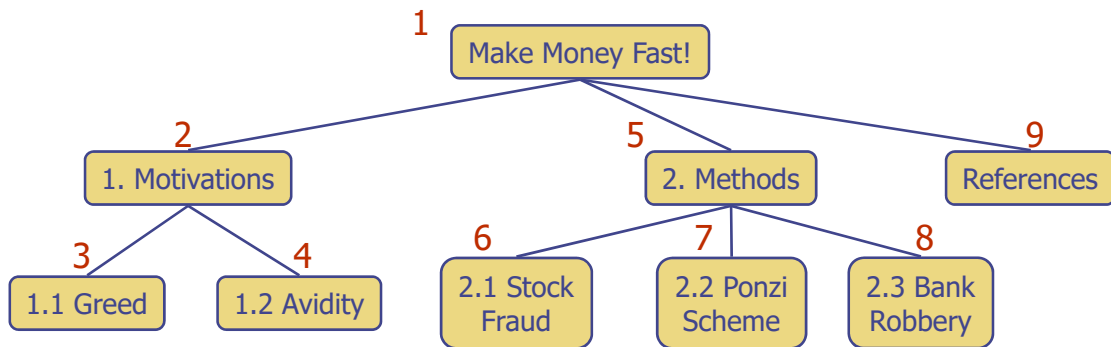


8

Preorder Traversal

- A traversal visits the nodes of a tree in a systematic manner
- In a preorder traversal, a node is visited before its descendants
- Application: print a structured document

Algorithm *preOrder(v)*
visit(v)
for each child *w* of *v*
preorder(w)

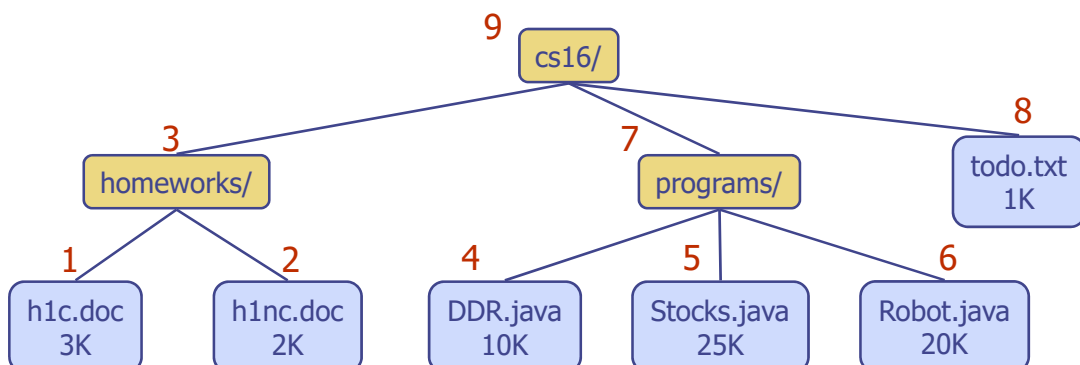


9

Postorder Traversal

- In a postorder traversal, a node is visited after its descendants
- Application: compute space used by files in a directory and its subdirectories

Algorithm *postOrder(v)*
for each child *w* of *v*
postOrder(w)
visit(v)



10

Breadth-First (or Level-order) Traversal

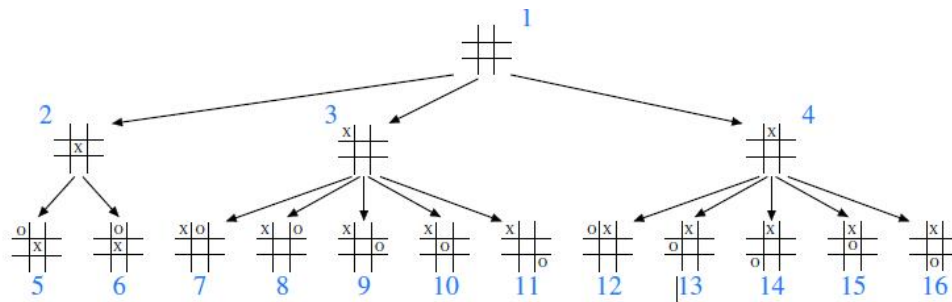


Figure 8.15: Partial game tree for Tic-Tac-Toe when ignoring symmetries; annotations denote the order in which positions are visited in a breadth-first tree traversal.

Algorithm breadthfirst():

Initialize queue Q to contain root()

while Q not empty **do**

$p = Q.dequeue()$ { p is the oldest entry in the queue }

 perform the “visit” action for position p

for each child c in children(p) **do**

$Q.enqueue(c)$ { add p ’s children to the end of the queue for later visits }

Code Fragment 8.14: Algorithm for performing a breadth-first traversal of a tree.

11

Table of Contents?

Paper
Title
Abstract
§1
§1.1
§1.2
§2
§2.1
...
(a)

Paper
Title
Abstract
§1
§1.1
§1.2
§2
§2.1
...
(b)

Electronics R’Us
1 R&D
2 Sales
 2.1 Domestic
 2.2 International
 2.2.1 Canada
 2.2.2 S. America

```

1  /** Prints preorder representation of subtree of T rooted at p having depth d. */
2  public static <E> void printPreorderIndent(Tree<E> T, Position<E> p, int d) {
3      System.out.println(spaces(2*d) + p.getElement());    // indent based on d
4      for (Position<E> c : T.children(p))
5          printPreorderIndent(T, c, d+1);                  // child depth is d+1
6  }
```

12

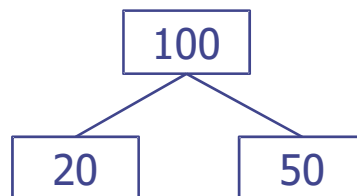
Computing Disk Space?

```

1  /** Returns total disk space for subtree of T rooted at p. */
2  public static int diskSpace(Tree<Integer> T, Position<Integer> p) {
3      int subtotal = p.getElement(); // we assume element represents space usage
4      for (Position<Integer> c : T.children(p))
5          subtotal += diskSpace(T, c);
6      return subtotal;
7  }

```

Code Fragment 8.25: Recursive computation of disk space for a tree. We assume that each tree element reports the local space used at that position.

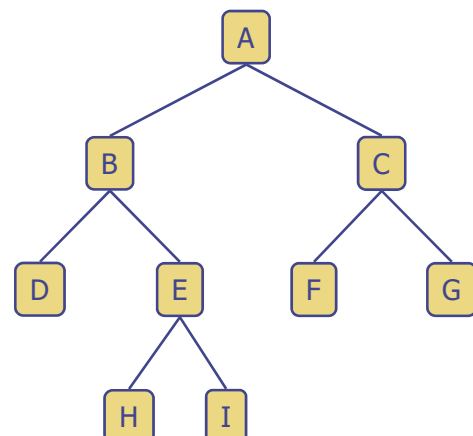


13

Binary Trees

- A binary tree is an **ordered tree** with the following properties:
 - Each internal node has at most two children (exactly two for **proper** binary trees)
 - The children of a node are an **ordered pair**
- We call the children of an internal node **left child** and **right child**
- Alternative recursive definition: a binary tree is either
 - a tree consisting of a single node, or
 - a tree whose root has an ordered pair of children, each of which is a binary tree

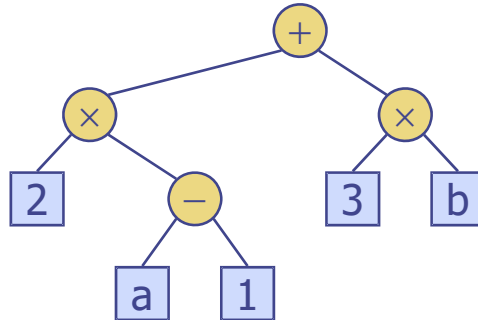
- Applications:
 - arithmetic expressions
 - decision processes
 - searching



14

Arithmetic Expression Tree

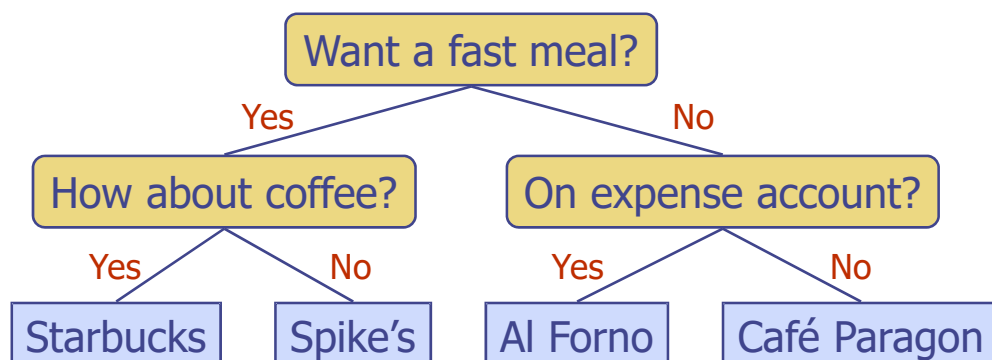
- Binary tree associated with an arithmetic expression
 - internal nodes: operators
 - external nodes: operands
- Example: arithmetic expression tree for the expression $(2 \times (a - 1) + (3 \times b))$



15

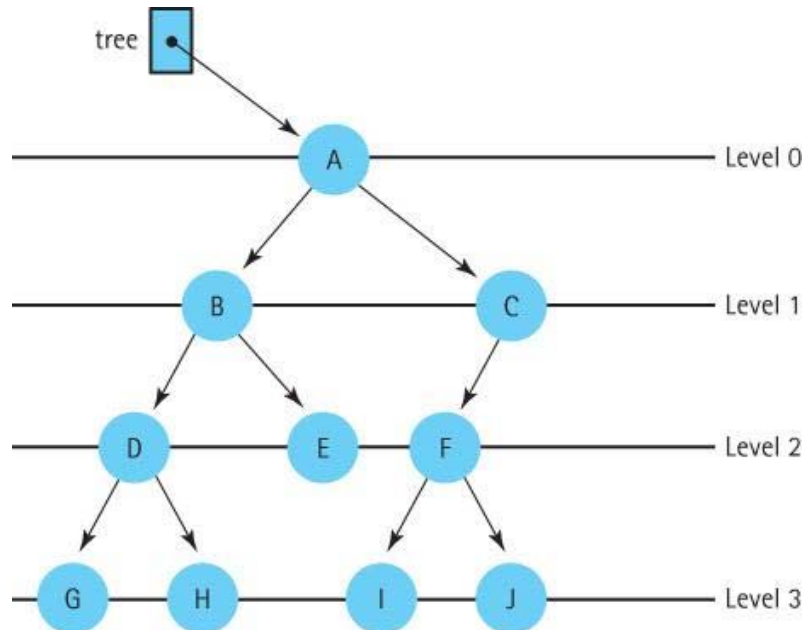
Decision Tree

- Binary tree associated with a decision process
 - internal nodes: questions with yes/no answer
 - external nodes: decisions
- Example: dining decision



16

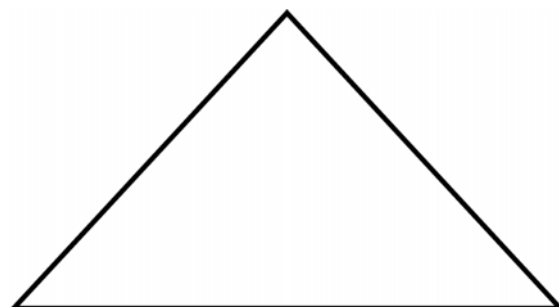
A Binary Tree and Levels



17

Full Binary Tree

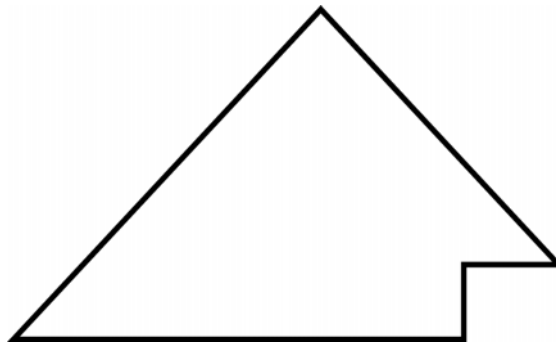
- **Full Binary Tree:** A binary tree in which all of the leaves are on the same level and every nonleaf node has two children



18

Complete Binary Tree

- **Complete Binary Tree:** A binary tree that is either full or full through the next-to-last level, with the leaves on the last level as far to the left as possible

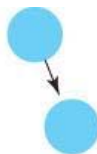


19

Examples of Different Types of Binary Trees



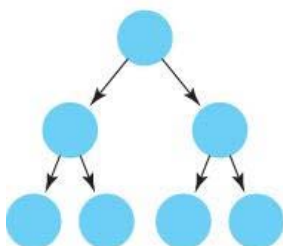
(a) Full and complete



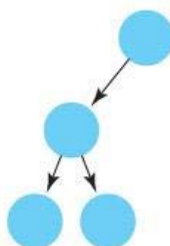
(b) Neither full nor complete



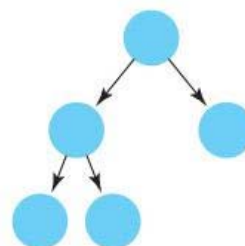
(c) Complete



(d) Full and complete



(e) Neither full nor complete



(f) Complete

20

Properties of Binary Trees

□ Notation

n number of nodes

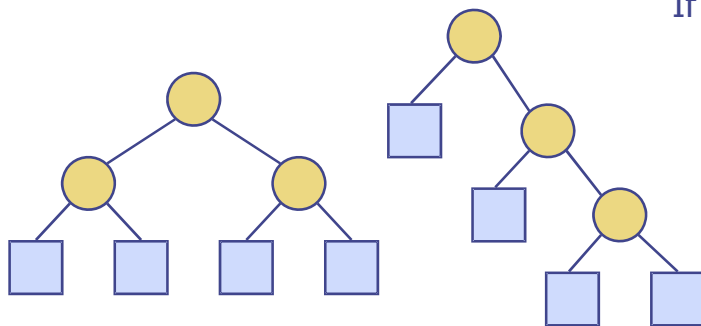
n_e number of external nodes

n_i number of internal nodes

h height

◆ Properties:

- $h+1 \leq n \leq 2^{h+1} - 1$
- $1 \leq n_e \leq 2^h$
- $h \leq n_i \leq 2^h - 1$
- $\log_2(n+1) - 1 \leq h \leq (n-1)$



If proper trees:

- $2h+1 \leq n \leq 2^{h+1} - 1$
- $h+1 \leq n_e \leq 2^h$
- $h \leq n_i \leq 2^h - 1$
- $\log_2(n+1) - 1 \leq h \leq (n-1)/2$
- $n_e = n_i + 1$

21

BinaryTree ADT

- The BinaryTree ADT extends the Tree ADT, i.e., it inherits all the methods of the Tree ADT
- Additional methods:
 - position **left**(p)
 - position **right**(p)
 - boolean **hasLeft**(p)
 - boolean **hasRight**(p)
- Update methods may be defined by data structures implementing the BinaryTree ADT

22

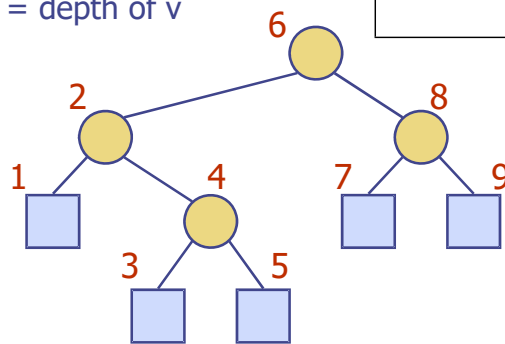
Inorder Traversal

- In an inorder traversal a node is visited after its left subtree and before its right subtree
- Application: draw a binary tree
 - $x(v)$ = inorder rank of v
 - $y(v)$ = depth of v

Algorithm *inOrder*(v)

```

if hasLeft ( $v$ )
    inOrder (left ( $v$ ))
visit( $v$ )
if hasRight ( $v$ )
    inOrder (right ( $v$ ))
    
```



23

Tree Drawing?

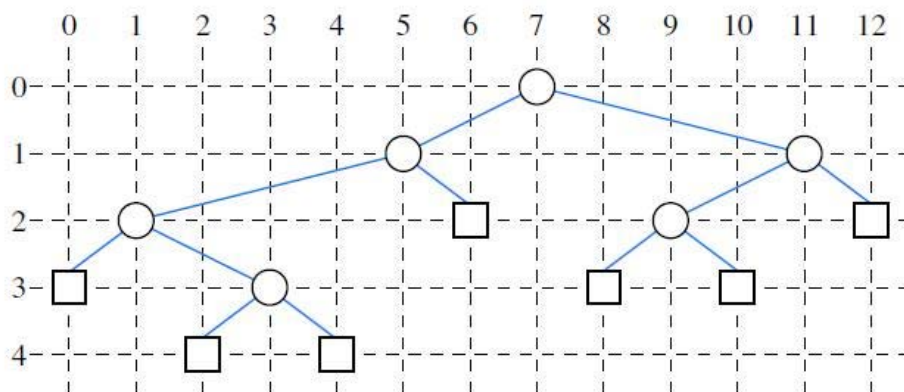
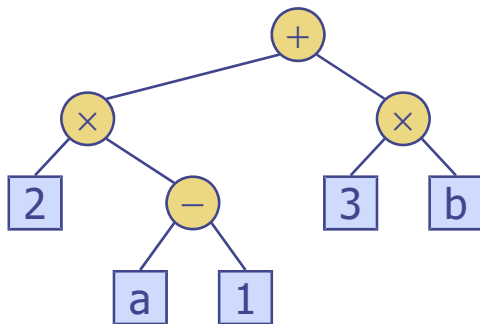


Figure 8.19: An inorder drawing of a binary tree.

24

Print Arithmetic Expressions

- Specialization of an inorder traversal
 - print operand or operator when visiting node
 - print "(" before traversing left subtree
 - print ")" after traversing right subtree



Algorithm *printExpression(v)*

```

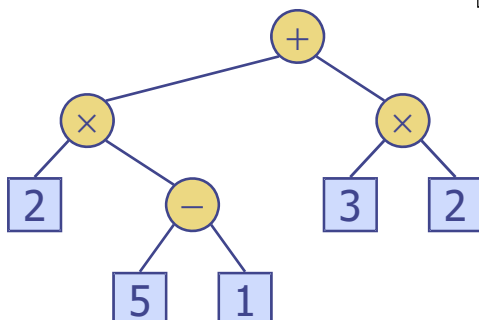
if hasLeft (v)
    print "("
    inOrder (left(v))
    print(v.element ())
if hasRight (v)
    inOrder (right(v))
    print ")"
    
```

$((2 \times (a - 1)) + (3 \times b))$

25

Evaluate Arithmetic Expressions

- Specialization of a postorder traversal
 - recursive method returning the value of a subtree
 - when visiting an internal node, combine the values of the subtrees



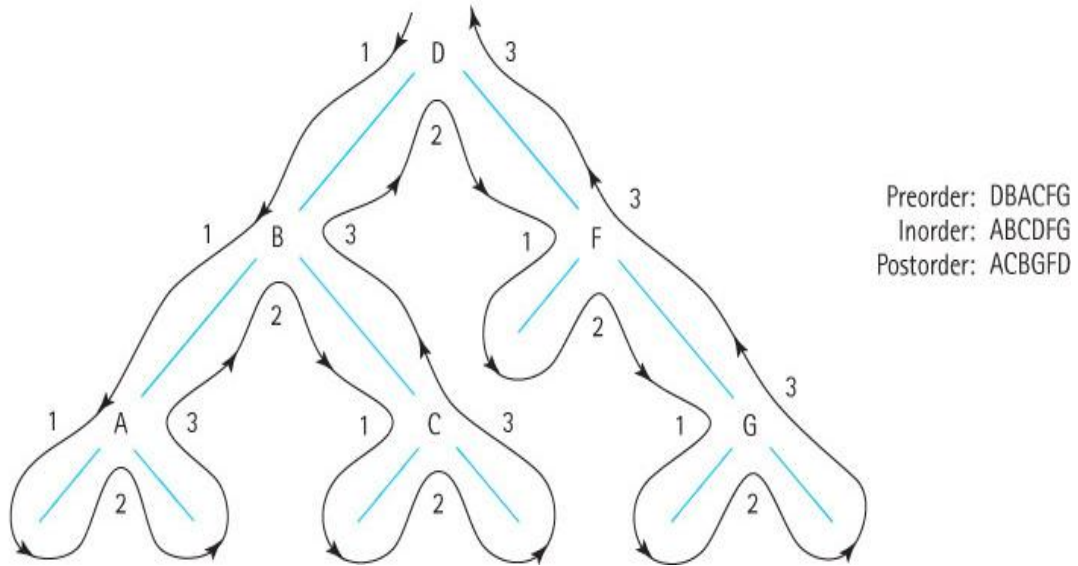
Algorithm *evalExpr(v)*

```

if isExternal (v)
    return v.element ()
else
     $x \leftarrow \text{evalExpr}(\text{leftChild}(v))$ 
     $y \leftarrow \text{evalExpr}(\text{rightChild}(v))$ 
     $\diamond \leftarrow$  operator stored at v
    return  $x \diamond y$ 
    
```

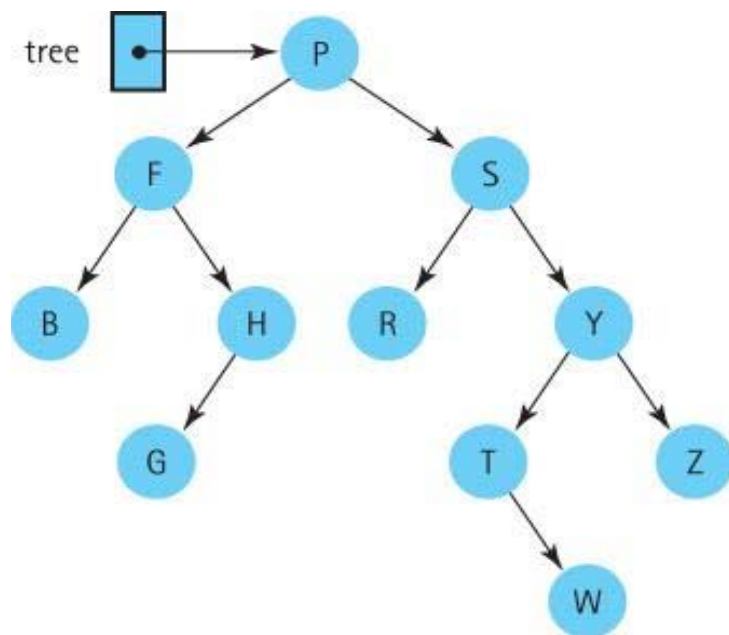
26

Euler Tour Traversal



27

Three Binary Tree Traversals

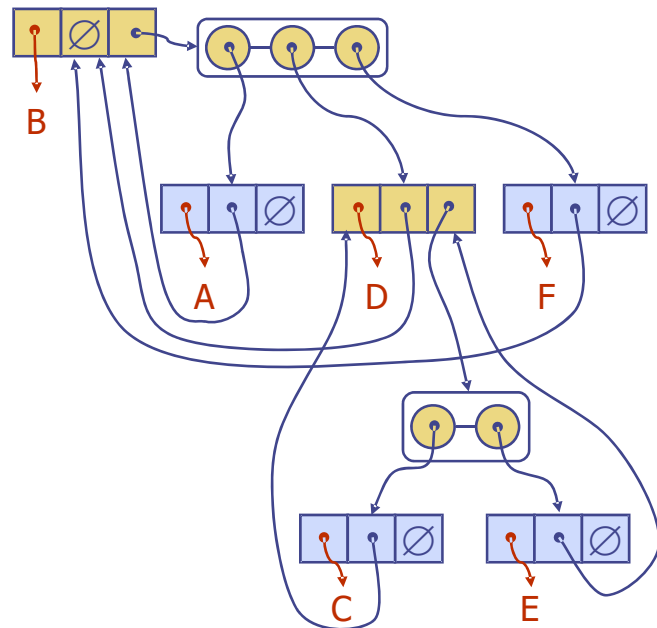
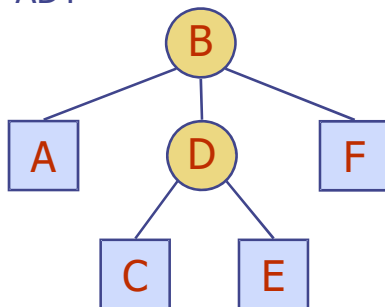


Inorder: B F G H P R S T W Y Z
Preorder: P F B H G S R Y T W Z
Postorder: B G H F R W T Z Y S P

28

Linked Structure for Trees

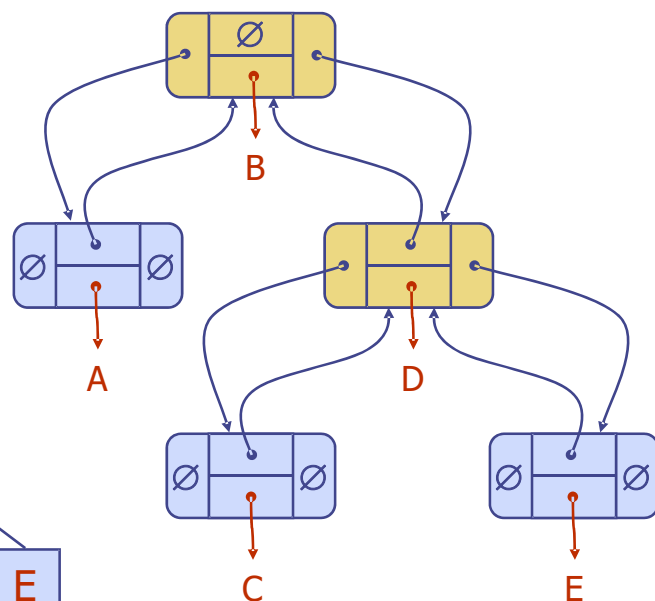
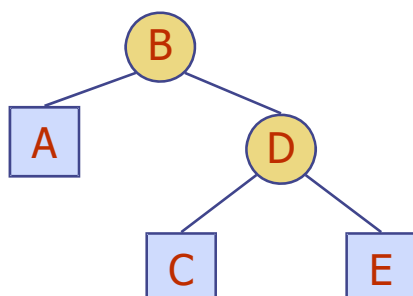
- A node is represented by an object storing
 - Element
 - Parent node
 - Sequence of children nodes
- Node objects implement the Position ADT



29

Linked Structure for Binary Trees

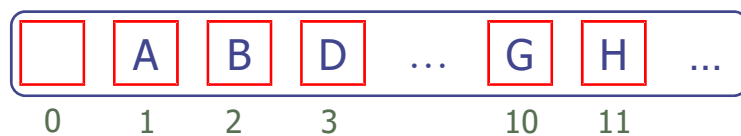
- A node is represented by an object storing
 - Element
 - Parent node
 - Left child node
 - Right child node
- Node objects implement the Position ADT



30

Array-Based Representation of Binary Trees

- Nodes are stored in an array A



- Node v is stored at $A[\text{rank}(v)]$

- rank(root) = 1
- if node is the left child of parent(node),
 $\text{rank}(\text{node}) = 2 \cdot \text{rank}(\text{parent}(\text{node}))$
- if node is the right child of parent(node),
 $\text{rank}(\text{node}) = 2 \cdot \text{rank}(\text{parent}(\text{node})) + 1$

