Maps



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Maps



- A map models a *searchable collection* of *key-value* entries
- The main operations of a map are for searching, inserting, and deleting items
- Multiple entries with the same key are not allowed
- Applications:
 - address book
 - student-record database

The Map ADT



- get(k): if the map M has an entry with key k, return its associated value; else, return null
- put(k, v): insert entry (k, v) into the map M; if key k is not already in M, then return null; else, return old value associated with k
- remove(k): if the map M has an entry with key k, remove it from M and return its associated value; else, return null
- size(), isEmpty()
- entrySet(): return an iterable collection of the entries in M
- keySet(): return an iterable collection of the keys in M
- values(): return an iterator of the values in M

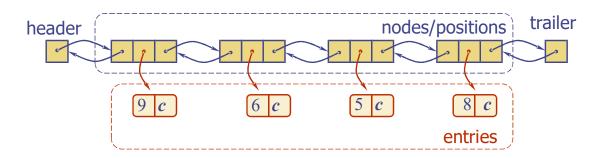
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Example

Operation	Output	Мар
isEmpty()	true	Ø
put(5,A)	null	(5 <i>,A</i>)
put(7 <i>,B</i>)	null	(5, <i>A</i>),(7, <i>B</i>)
put(2, <i>C</i>)	null	(5, <i>A</i>),(7, <i>B</i>),(2, <i>C</i>)
put(8, <i>D</i>)	null	(5,A),(7,B),(2,C),(8,D)
put(2 <i>,E</i>)	$\boldsymbol{\mathcal{C}}$	(5,A),(7,B),(2,E),(8,D)
get(7)	В	(5,A),(7,B),(2,E),(8,D)
get(4)	null	(5,A),(7,B),(2,E),(8,D)
get(2)	E	(5,A),(7,B),(2,E),(8,D)
size()	4	(5,A),(7,B),(2,E),(8,D)
remove(5)	A	(7, <i>B</i>),(2, <i>E</i>),(8, <i>D</i>)
remove(2)	E	(7 <i>,B</i>),(8 <i>,D</i>)
get(2)	null	(7,B),(8,D)
isEmpty()	false	(7,B),(8,D)

A Simple List-Based Map

- We can efficiently implement a map using an unsorted list
 - We store the items of the map in a list S (based on a doubly-linked list), in arbitrary order



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The get(k) Algorithm

The put(k,v) Algorithm

The remove(k) Algorithm

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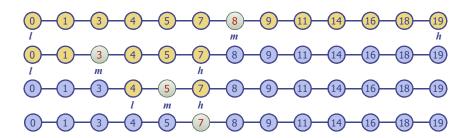
Performance of a List-Based Map

Performance:

- put takes O(1) time since we can insert the new item at the beginning or at the end of the sequence \rightarrow Really????
- get and remove take O(n) time since in the worst case (the item is not found) we traverse the entire sequence to look for an item with the given key
- The unsorted list implementation is effective only for maps of small size or for maps in which puts are the most common operations, while searches and removals are rarely performed (e.g., historical record of logins to a workstation)

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Dictionaries



Dictionary ADT

- The dictionary ADT models a searchable collection of keyelement entries
- The main operations of a dictionary are searching, inserting, and deleting items
- Multiple items with the same key *are* allowed
- Applications:
 - word-definition pairs
 - credit card authorizations
 - DNS mapping of host names (e.g., datastructures.net) to internet IP addresses (e.g., 128.148.34.101)

- Dictionary ADT methods:
 - get(k): if the dictionary has an entry with key k, returns it, else, returns null
 - getAll(k): returns an iterable collection of all entries with key k
 - put(k, o): inserts and returns the entry (k, o)
 - remove(e): remove the entry e from the dictionary
 - entrySet(): returns an iterable collection of the entries in the dictionary
 - size(), isEmpty()

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Example

Operation	Output	Dictionary
put(5,A)	(5,A)	(5,A)
put(7,B)	(7,B)	(5,A),(7,B)
put(2,C)	(2,C)	(5,A),(7,B),(2,C)
put(8,D)	(8,D)	(5,A),(7,B),(2,C),(8,D)
put(2,E)	(2,E)	(5,A),(7,B),(2,C),(8,D),(2,E)
get(7)	(7,B)	(5,A),(7,B),(2,C),(8,D),(2,E)
get(4)	null	(5,A),(7,B),(2,C),(8,D),(2,E)
get(2)	(2,C)	(5,A),(7,B),(2,C),(8,D),(2,E)
getAll(2)	(2,C),(2,E)	(5,A),(7,B),(2,C),(8,D),(2,E)
size()	5	(5,A),(7,B),(2,C),(8,D),(2,E)
remove(get(5))	(5,A)	(7,B),(2,C),(8,D),(2,E)
get(5)	null	(7,B),(2,C),(8,D),(2,E)

A List-Based Dictionary

- A log file or audit trail is a dictionary implemented by means of an unsorted sequence
 - We store the items of the dictionary in a sequence (based on a doubly-linked list or array), in arbitrary order
- Performance:
 - put takes O(1) time since we can insert the new item at the beginning or at the end of the sequence
 - get and remove take O(n) time since in the worst case (the item is not found) we traverse the entire sequence to look for an item with the given key
- The log file is effective only for dictionaries of small size or for dictionaries on which insertions are the most common operations, while searches and removals are rarely performed (e.g., historical record of logins to a workstation)

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The getAll and put Algorithms

```
Algorithm getAll(k)
Create an initially-empty list L
for e: D do
    if e.getKey() = k then
        L.addLast(e)
return L

Algorithm put(k,v)
Create a new entry e = (k,v)
D.addLast(e) {D is unordered}
n = n + 1
return e
```

The remove Algorithm

```
Algorithm remove(e):

B = D.positions()

while B.hasNext() do

p = B.next()

if p.element() = e then

D.remove(p)

n = n - 1

return e

return null {there is no entry e in D}
```

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Hash Table Implementation

- We can also create a hash-table dictionary implementation.
- If we use <u>separate chaining</u> to handle collisions, then each operation can be delegated to a list-based dictionary stored at each hash table cell.

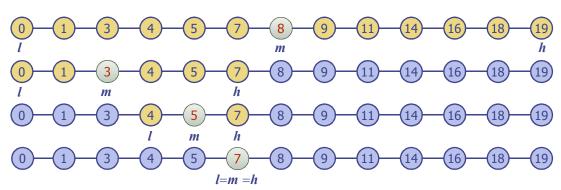
Search Table

- A search table is a dictionary implemented by means of a sorted array
 - We store the items of the dictionary in an array-based sequence, sorted by key
 - We use an external comparator for the keys
- Performance:
 - get takes $O(\log n)$ time, using binary search
 - put takes O(n) time since *in the worst case* we have to shift n/2 items to make room for the new item
 - remove takes O(n) time since *in the worst case* we have to shift n/2 items to compact the items after the removal
- A search table is effective only for dictionaries of small size or for dictionaries on which searches are the most common operations, while insertions and removals are rarely performed (e.g., credit card authorizations)

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Binary Search

- Binary search performs operation get(k) on a dictionary implemented by means of an array-based sequence, sorted by key
 - similar to the high-low game
 - at each step, the number of candidate items is halved
 - terminates after a logarithmic number of steps
- Example: get(7)



Binary Search Algorithm

```
Algorithm BinarySearch(S, k, low, high)

if low > high

return null

else

mid ← (low+high) div 2

e ← S.get(mid)

if k = e.getKey() then

return e

else if k < e.getKey() then

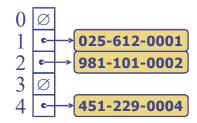
return BinarySearch(S, k, low, mid-1)

else

return BinarySearch(S, k, mid+1, high)
```

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Hash Tables



Recall the Map ADT



- get(k): if the map M has an entry with key k, return its associated value; else, return null
- put(k, v): insert entry (k, v) into the map M; if key k is not already in M, then return null; else, return old value associated with k
- remove(k): if the map M has an entry with key k, remove it from M and return its associated value; else, return null
- size(), isEmpty()
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Hash Functions and Hash Tables



- A hash table for a given key type consists of
 - Hash function h
 - Array (called table) of size $N \leftarrow Bucket Array$
- □ A hash function h maps keys of a given type to integers in a fixed interval [0, N-1]
- Example:

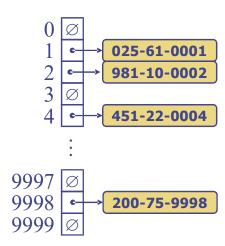
 $h(x) = x \mod N$

is a hash function for integer keys

- \Box The integer h(x) is called the hash value of key x
- □ When implementing a map with a hash table, the goal is to store item (k, o) at index i = h(k)

Example

- We design a hash table for a map storing entries as (SSN, Name), where SSN (social security number) is a nine-digit positive integer
- □ Our hash table uses an array of size N = 10,000 and the hash function h(x) = last four digits of x



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Hash Functions

 A hash function is usually specified as the composition of two functions:

Hash code:

 h_1 : keys \rightarrow integers

Compression function:

 h_2 : integers $\rightarrow [0, N-1]$



 The hash code is applied first, and the compression function is applied next on the result, i.e.,

$$\boldsymbol{h}(\boldsymbol{x}) = \boldsymbol{h}_2(\boldsymbol{h}_1(\boldsymbol{x}))$$

 The goal of the hash function is to "disperse" the keys in an apparently random way

Hash Functions

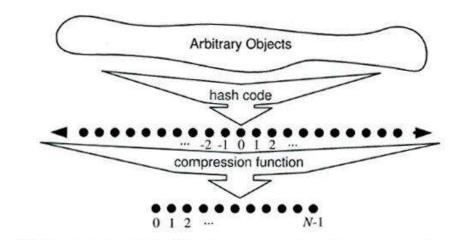


Figure 9.3: The two parts of a hash function: a hash code and a compression function.

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Hash Codes

Memory address:

- We reinterpret the memory address of the key object as an integer (default hash code of all Java objects)
- Good in general, except for numeric and string keys

Integer cast:

- We reinterpret the bits of the key as an integer
- Suitable for keys of length less than or equal to the number of bits of the integer type (e.g., byte, short, int and float in Java)



Component sum:

- We partition the bits of the key into components of fixed length (e.g., 16 or 32 bits) and we sum the components (ignoring overflows)
- Suitable for numeric keys of fixed length greater than or equal to the number of bits of the integer type (e.g., long and double in Java)

```
class Key implements Serializable {
    private long key;
    public Key(long val) { this.key = val; }
}
```

```
Key myKey = new Key(0x1234567890abcdefL);
System.out.println(hex(myKey.hashCode()));
System.out.println(myKey);
```

0x15db9742 ds.generics.Key@15db9742

```
class Key implements Serializable {
    private long key;

    public Key(long val) { this.key = val; }

    @Override
    public int hashCode() {

        int low = (int) (0x0ffffffff & key);
        System.out.println("low = " + HashCodeGen.hex(low));
        int high = (int) (0x0ffffffff & (key >>> 32));
        System.out.println("high = " + HashCodeGen.hex(high));
        int result = (low + high) & 0x7fffffff;
        System.out.println("result = " + HashCodeGen.hex(result));
        return result;
    }
}
```

```
low = 0x90abcdef
high = 0x12345678
result = 0x22e02467
ds.generics.Key@22e02467
```

Key myKey = new Key(0x1234567890abcdefL);

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Hash Codes (cont.)

Polynomial accumulation:

 We partition the bits of the key into a sequence of components of fixed length (e.g., 8, 16 or 32 bits)

$$a_0 a_1 \ldots a_{n-1}$$

We evaluate the polynomial

$$p(z) = a_0 + a_1 z + a_2 z^2 + ... + a_{n-1} z^{n-1}$$

at a fixed value z_n ignoring overflows

■ Especially suitable for strings (e.g., the choice z = 33 gives at most 6 collisions on a set of 50,000 English words)

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Hash Codes (cont.)

- □ Polynomial p(z) can be evaluated in O(n) time using Horner's rule:
 - The following polynomials are successively computed, each from the previous one in O(1) time

$$p(z) = a_3 z^3 + a_2 z^2 + a_1 z^1 + a_0 = ((a_3 z + a_2) z + a_1) z + a_0$$

Compression Functions



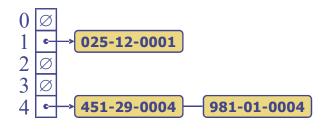
- Division:
 - $\bullet h_2(y) = y \bmod N$
 - The size N of the hash table is usually chosen to be a prime
 - The reason has to do with number theory and is beyond the scope of this course
- Multiply, Add and Divide (MAD):
 - $h_2(y) = (ay + b) \bmod N$
 - a and b are nonnegative integers such that
 a mod N≠ 0
 - Otherwise, every integer would map to the same value b

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Collision Handling



- Collisions occur when different elements are mapped to the same cell
- Separate Chaining: let each cell in the table point to a linked list of entries that map there



 Separate chaining is simple, but requires additional memory outside the table

Map with Separate Chaining

Delegate operations to a list-based map at each cell:

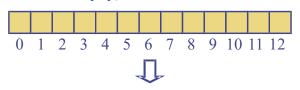
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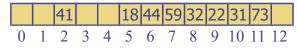
Linear Probing

- Open addressing: the colliding item is placed in a different cell of the table
- Linear probing: handles collisions by placing the colliding item in the next (circularly) available table cell
- Each table cell inspected is referred to as a "probe"
- Colliding items lump together, causing future collisions to cause a longer sequence of probes

Example:

- $h(x) = x \bmod 13$
- Insert keys 18(5),
 41(2), 22(9), 44(5),
 59(7), 32(6), 31(5),
 73(8), in this order





Search with Linear Probing



- Consider a hash table A that uses linear probing
- □ get(*k*)
 - We start at cell h(k)
 - We probe consecutive locations until one of the following occurs
 - An item with key k is found, or
 - An empty cell is found, or
 - N cells have been unsuccessfully probed

```
Algorithm get(k)
i \leftarrow h(k)
p \leftarrow 0
repeat
c \leftarrow A[i]
if c = \emptyset
return null
else if c.getKey() = k
return c.getValue()
else
i \leftarrow (i+1) \mod N
p \leftarrow p+1
until p = N
return null
```

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Updates with Linear Probing

- To handle insertions and deletions, we introduce a special object, called AVAILABLE, which replaces deleted elements
- \square remove(k)
 - We search for an entry with key k
 - If such an entry (k, o) is found, we replace it with the special item AVAILABLE and we return element o
 - Else, we return *null*

- \square put(k, o)
 - We throw an exception if the table is full
 - We start at cell h(k)
 - We probe consecutive cells until one of the following occurs
 - A cell *i* is found that is either empty or stores *AVAILABLE*, or
 - N cells have been unsuccessfully probed
 - We store (k, o) in cell i

Double Hashing

Double hashing uses a secondary hash function d(k) and handles collisions by placing an item in the first available cell of the series

$$(h(k) + jd(k)) \bmod N$$
for $j = 0, 1, \dots, N-1$

- The secondary hash function d(k) cannot have zero values
- The table size N must be a prime to allow probing of all the cells



 Common choice of compression function for the secondary hash function:

$$d_2(\mathbf{k}) = \mathbf{q} - \mathbf{k} \mod \mathbf{q}$$
 where

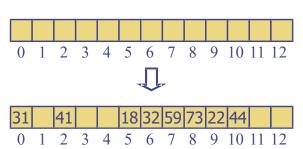
- q < N
- \blacksquare q is a prime
- □ The possible values for $d_2(k)$ are 1, 2, ..., q

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Example of Double Hashing

- Consider a hash table storing integer keys that handles collision with double hashing
 - N = 13
 - $h(k) = k \mod 13$
 - $d(k) = 7 k \mod 7$
- Insert keys 18, 41,22, 44, 59, 32, 31,73, in this order

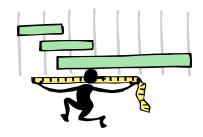
k h(k) d(k) Probes						
18	5	3	5			
41	2	1	2			
22	9	6	9			
44	5	5	5	10		
59	7	4	7			
18 41 22 44 59 32	6	3	6			
31	5	4	5	9	0	
73	8	4	8		•	



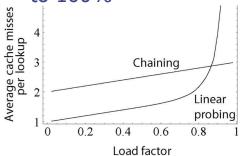
Performance of Hashing

- □ In the worst case, searches, insertions and removals on a hash table take O(n) time
- The worst case occurs when all the keys inserted into the map collide
- The load factor α = n/N
 affects the performance of a
 hash table
- Assuming that the hash values are like random numbers, it can be shown that the expected number of probes for an insertion with open addressing is

 $1/(1-\alpha)$



- □ The expected running time of all the dictionary ADT operations in a hash table is *O*(1)
- In practice, hashing is very fast provided the load factor is not close to 100%



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