## **David Lin**

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### **Education**

**University of California, Berkeley** 

Aug, 2015 - May, 2019

Major B.S. Electrical Engineering and Computer Sciences (EECS)

Junior

Holmdel High School, NJ

GPA: 4.7/4.0

Sept, 2011 - June, 2015

#### Skills

Languages Skills Java, Python, SQL, C, Scheme, PHP, Ruby/Rails, JavaScript, HTML, CSS, LaTex Databases, AWS (EB, SQS, SNS, RDS), REST APIs, MapReduce, NumPy, Scikit-learn

Sel. Courses Artificial

Artificial Intelligence (A-), Applied Data Science (IP), Natural Language Processing (IP)

## **Work Experience**

Software Engineer Intern, Backend/Data - Quantcast, San Francisco

May, 2017 - Aug, 2017

- Automate weekly service to find 1000+ publisher site statuses with 100% accuracy (up from 60%)
- Uses cloud infrastructure (Terraform, AWS), data access layer (HikariCP, SQL), REST APIs (Spark)
- MapReduce jobs on terabytes of cookie metadata to determine campaign reporting start/end dates

**Undergraduate Researcher** – Berkeley DeepDrive, UC Berkeley

Sept, 2017 - Present

Develop a fully autonomous driving system with industry sponsors, faculty, and researchers

Online Manager – The Daily Californian, Berkeley

July, 2017 - Present

Manage newspaper's online/mobile dept serving thousands daily and website redesign dev team

Researcher and System Administrator – AUTOLAB, UC Berkeley

Jan, 2016 - May, 2017

- Research and software dev under Prof Ken Goldberg for autonomous driving and explainable Aln
- Maintenance/on-call for two Linux servers (20+ sites/databases) for lab of 30+ grad/ug students

Data Analyst Intern – GT Nexus (acquired by Infor), Hong Kong

July, 2015 - August, 2015

• Implement intranet Google Analytics tracking, perform A/B tests, and customize adoption reports

# **Projects**

**Dynamic Object 3D Reconstruction** – Computer Vision, Research

Sept, 2017 - Present

- Reconstruct a 3D model of the dynamic scene from autonomous vehicle's lidar point cloud data
- Understand the 3D position of other vehicles and pedestrians while the vehicle is driving

First Order Driving Simulator – PyGame Graphics, Research

Oct, 2016 - May, 2017

- Open-source 2D driving simulator on a customizable track with multiple terrains and friction levels
- OpenAl Gym compatibility to analyze performance of reinforcement and deep learning algorithms

**EchoBot** – Automation Assistant, Research

Aug, 2016 - Nov, 2016

- Interfaces Amazon Echo to the ABB YuMi industrial robot to facilitate human-robot data collection
- Converts speech to test and provides continuous speech explanations to the user during operation