

CO233 - Computational Techniques

15th January 2020

Vector and Matrix Norms

An orthonormal basis of \mathbb{R}^n are unit vectors that are pairwise mutually perpendicular; such that for (e_1, \dots, e_n) ;

- $e_i \cdot e_i = 1$
- $e_i \cdot e_j = 0$, if $i \neq j$

The standard canonical basis of \mathbb{R}^3 are the i, j, k vectors, and similar in \mathbb{R}^2 . However, we can form another orthonormal basis of \mathbb{R}^2 by bisecting the angles as such;



If we take a vector $\mathbf{v} \in \mathbb{R}^n$, the Euclidean norm (or the ℓ_2 -norm) is defined as such;

$$\|\mathbf{v}\|_2 = \sqrt{\sum_{i=1}^n v_i^2}$$

A norm, a mapping $\|\cdot\| : \mathbb{R}^n \rightarrow \mathbb{R}^+$, must satisfy these 3 axioms;

- (i) $\|\mathbf{v}\| > 0$ given that $\mathbf{v} \neq \mathbf{0}$
- (ii) $\|\lambda \mathbf{v}\| = |\lambda| \|\mathbf{v}\|$
- (iii) $\|\mathbf{v} + \mathbf{w}\| \leq \|\mathbf{v}\| + \|\mathbf{w}\|$ (triangular inequality)

Some other (ℓ_p) norms are defined as follows;

$$\ell_1\text{-norm } \|\mathbf{v}\|_1 = \sum_{i=1}^n |v_i|$$

$$\ell_\infty\text{-norm } \|\mathbf{v}\|_\infty = \max\{|v_i| : 1 \leq i \leq n\}$$

$$\ell_p\text{-norm } \|\mathbf{v}\|_p = \left(\sum_{i=1}^n |v_i|^p \right)^{\frac{1}{p}}$$

In each dimension, we have the following;

- $n = 1$
 - $\|\mathbf{v}\|_1 = |v| = |v|$
 - $\|\mathbf{v}\|_2 = \sqrt{v^2} = |v|$
 - $\|\mathbf{v}\|_\infty = \max\{|v|\} = |v|$
- $n = 2$

We can represent this geometrically as such;



In our case $\|\mathbf{v}\|_\infty = \max\{|v_1|, |v_2|\} = |v_1|$, but the point is that it's either of the "sides" of the triangle. Obviously, $\|\mathbf{v}\|_2 \geq \|\mathbf{v}\|_\infty$, as it's the hypotenuse of the triangle, and similarly, $\|\mathbf{v}\|_1 \geq \|\mathbf{v}\|_2$, due to the triangle inequality. Therefore we have $\|\mathbf{v}\|_1 \geq \|\mathbf{v}\|_2 \geq \|\mathbf{v}\|_\infty$.

Even if the orthonormal base changes, the Euclidean norm stays the same, whereas the other norms can change. As such, we can say the ℓ_2 -norm is invariant under an **orthogonal transformation** (a basis change from an orthonormal bases to another orthonormal bases).

- $n = ?$ (general)

The goal is to prove $\|\mathbf{v}\|_\infty \leq \|\mathbf{v}\|_2 \leq \|\mathbf{v}\|_1$. If we first take the squares of all of them, such that we have the following;

$$\begin{aligned}\|\mathbf{v}\|_1^2 &= \left(\sum_{i=1}^n |v_i| \right)^2 \\ \|\mathbf{v}\|_2^2 &= \sum_{i=1}^n |v_i|^2 \\ \|\mathbf{v}\|_\infty^2 &= (\max\{|v_i| : 1 \leq i \leq n\})^2\end{aligned}$$

Since the ℓ_∞ -norm corresponds to a single v_i , it's obvious that the following inequality holds (since the ℓ_2 -norm squared has all the other terms squared, as well as the ℓ_∞ -norm squared);

$$\|\mathbf{v}\|_2^2 = \sum_{i=1}^n |v_i|^2 \geq (\max\{|v_i| : 1 \leq i \leq n\})^2 = \|\mathbf{v}\|_\infty^2 \Rightarrow \|\mathbf{v}\|_2 \geq \|\mathbf{v}\|_\infty$$

To prove the other inequality, we see that the square of the sum of absolutes is greater than the sum of the squares, as the square of the sum contains the cross terms (which will be positive).

$$\|\mathbf{v}\|_2^2 = \sum_{i=1}^n |v_i|^2 \leq \left(\sum_{i=1}^n |v_i| \right)^2 = \|\mathbf{v}\|_1^2 \Rightarrow \|\mathbf{v}\|_2 \leq \|\mathbf{v}\|_1$$

As such, we can conclude that $\|\mathbf{v}\|_\infty \leq \|\mathbf{v}\|_2 \leq \|\mathbf{v}\|_1$ in any dimension. ■

Tutorial Question

Find the locus of vectors such that $\|\mathbf{v}\|_p \leq 1$, for $p = 1, 2, \infty$ in $n = 2$;



Imagine they're all shaded from the border to the origin.

ℓ_p -norm

Our goal is to show that as $p \rightarrow \infty$, we get the definition of the ℓ_∞ -norm previously stated. Take a vector $\mathbf{v} \in \mathbb{R}^n$, where both \mathbf{v} and n are fixed.

$$\|\mathbf{v}\|_p^p = \sum_{i=1}^n |v_i|^p$$

Obviously, this is greater than or equal to $\|\mathbf{v}\|_\infty^p$, as it would only be a single $|v_i|^p$. Similarly, it must be less than or equal to $n|v_i|^p$, as v_i is the maximum of all the components.

$$\|\mathbf{v}\|_\infty^p \leq \|\mathbf{v}\|_p^p = \sum_{i=1}^n |v_i|^p \leq n\|\mathbf{v}\|_\infty^p$$

Taking everything to the power of $\frac{1}{p}$, we obtain the following result (note that $p > 0$ hence the signs don't change);

$$\|\mathbf{v}\|_\infty \leq \|\mathbf{v}\|_p \leq n^{\frac{1}{p}} \|\mathbf{v}\|_\infty$$

As $p \rightarrow \infty$, since $n \geq 2$ ($n = 1$ is shown to collapse to the same component), we have $n^{\frac{1}{p}} \rightarrow 1$, which sandwiches the middle term.

Some Proposition (ℓ_∞ -norm vs ℓ_2 -norm)

The proposition is as follows; for a vector $\mathbf{v} \in \mathbb{R}^n$, $\|\mathbf{v}\|_2 \leq \sqrt{n}\|\mathbf{v}\|_\infty$. To show this, we know that each of $|v_i|$ is less than or equal to $\|\mathbf{v}\|_\infty$, by definition of the maximum. The same can be said for $|v_i|^2$, vs $\|\mathbf{v}\|_\infty^2$. Taking square roots, we have the following;

$$\|\mathbf{v}\|_2^2 = \sum_{i=1}^n |v_i|^2 \leq n\|\mathbf{v}\|_\infty^2 \Rightarrow \|\mathbf{v}\|_2 \leq \sqrt{n}\|\mathbf{v}\|_\infty$$

To show this holds similarly for $\|\mathbf{v}\|_1 \leq \sqrt{n}\|\mathbf{v}\|_2$, we employ the Cauchy-Schwarz inequality, which states $|\mathbf{x} \cdot \mathbf{y}| \leq \|\mathbf{x}\|_2 \|\mathbf{y}\|_2$. The Cauchy-Schwarz inequality uses the fact that $\mathbf{x} \cdot \mathbf{y} = \|\mathbf{x}\|_2 \|\mathbf{y}\|_2 \cos \theta$. To do this, we need to define a sign function $\text{sgn} : \mathbb{R} \rightarrow \{1, -1\}$ as follows;

$$\text{sgn } x = \begin{cases} 1 & x \geq 0 \\ -1 & x < 0 \end{cases}$$

We also need to craft a vector \mathbf{w} , as follows;

$$\begin{aligned} w_i &= \frac{\text{sgn } v_i}{\sqrt{n}} & 1 \leq i \leq n \\ \mathbf{v} \cdot \mathbf{w} &= \sum_{i=1}^n v_i w_i \\ &= \sum_{i=1}^n \frac{v_i \cdot \text{sgn } v_i}{\sqrt{n}} & \text{product of same sign becomes positive} \\ &= \sum_{i=1}^n \frac{|v_i|}{\sqrt{n}} \\ &= \sqrt{n} \sum_{i=1}^n |v_i| \\ &= \sqrt{n} \|\mathbf{v}\|_1 \\ \|\mathbf{w}\|_2 &= \sum_{i=1}^n \frac{1}{\sqrt{n}} \\ &= \sum_{i=1}^n \frac{1}{n} \\ &= 1 \end{aligned}$$

By **Cauchy-Schwarz**, we get;

$$\sqrt{n} \|\mathbf{v}\|_1 = |\mathbf{v} \cdot \mathbf{w}| \leq \|\mathbf{v}\|_2 \|\mathbf{w}\|_2 = \|\mathbf{v}\|_2$$

16th January 2020

Note that this recording has **no audio**, and therefore will just be the board transcribed. I honestly have no idea what he was doing in this lecture, it seems to just jump from topic to topic.

Equivalence of Norms?

Take any two norms on \mathbb{R}^n ; $\|\cdot\|_a$, and $\|\cdot\|_b$.

$$\exists r, s \in \mathbb{R}^+ \forall \mathbf{v} \in \mathbb{R}^n [r\|\mathbf{v}\|_b \leq \|\mathbf{v}\|_a \leq s\|\mathbf{v}\|_b]$$

This means that norms in finite dimensional vector spaces are equivalent (no idea why, look it up).

Convergence of Vector Sequences

(\mathbf{r}_n) is a sequence of vectors, and $(a_{i,j})$ is the i, j^{th} entry of \mathbf{A} . For a vector $\mathbf{v}^{(m)} \in \mathbb{R}^n$, where $m = 0, 1, 2, \dots$

$$\mathbf{v}^{(m)} = \begin{bmatrix} v_1^{(m)} \\ v_2^{(m)} \\ \vdots \\ v_n^{(m)} \end{bmatrix}$$

For a vector sequence $\mathbf{v}^{(m)}$ to converge to some vector $\mathbf{v} \in \mathbb{R}^n$, the following must hold;

$$\mathbf{v}^{(m)} \rightarrow \mathbf{v} \in \mathbb{R}^n \Leftrightarrow \lim_{m \rightarrow \infty} \|\mathbf{v}^{(m)} - \mathbf{v}\| \rightarrow 0$$

This is componentwise convergence, such that $\forall i \in [1, n] [v_i^{(m)} \rightarrow v_i]$.

Matrix Norms

Vectors are a type of matrix. For a matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$, the following properties of its norms must hold, where $\|\cdot\| : \mathbb{R}^{m \times n} \rightarrow \mathbb{R}_{\geq 0}$;

- (i) $\|\mathbf{A}\| > 0$ given that $\mathbf{A} \neq \mathbf{0}$
- (ii) $\|\lambda \mathbf{A}\| = |\lambda| \|\mathbf{A}\|$
- (iii) $\|\mathbf{A} + \mathbf{B}\| \leq \|\mathbf{A}\| + \|\mathbf{B}\|$
- (iv) $\|\mathbf{BA}\| \leq \|\mathbf{B}\| \|\mathbf{A}\|$

$$\begin{array}{ccc} \mathbf{v} \in \mathbb{R}^n & \xrightarrow{\quad} & \boxed{\mathbf{A}} \xrightarrow{\quad} \mathbf{Av} \in \mathbb{R}^m \\ \|\cdot\|_a & & \|\cdot\|_b \end{array}$$

$$\|\mathbf{Av}\|_b \leq \|\mathbf{A}\| \|\mathbf{v}\|_a$$

For the following example, take $(a_{i,j}) = \mathbf{A} \in \mathbb{R}^{m \times n}$;

$$a_j = \begin{bmatrix} a_{1,j} \\ a_{2,j} \\ \vdots \\ a_{m,j} \end{bmatrix}$$

the j^{th} column of \mathbf{A}

$$a^i = [a_{i,1} \quad a_{i,2} \quad \cdots \quad a_{i,n}]$$

the i^{th} row of \mathbf{A}

We have the following norms on matrices;

$$\|\mathbf{A}\|_1 = \max\{\|a_j\|_1 : 1 \leq j \leq n\}$$

$$\|\mathbf{A}\|_\infty = \max\{\|(a^i)^\top\|_1 : 1 \leq i \leq m\}$$

$$\|\mathbf{A}\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n |a_{i,j}|^2} \quad \text{Frobenius norm}$$

$$\|\mathbf{A}\|_2 = \text{largest singular value of } \mathbf{A}$$

$$\text{let } \mathbf{A} = \begin{bmatrix} 2 & 3 & 1 & 4 \\ 1 & 3 & -1 & 5 \\ \sqrt{2} & 0 & -2 & 2 \end{bmatrix}$$

$$\begin{aligned} \|\mathbf{A}\|_1 &= \max\{3 + \sqrt{2}, 6, 4, 11\} \\ &= 11 \end{aligned}$$

$$\begin{aligned} \|\mathbf{A}\|_\infty &= \max\{10, 10, 4 + \sqrt{2}\} \\ &= 10 \end{aligned}$$

$$\begin{aligned} \|\mathbf{A}\|_F &= \sqrt{4 + 9 + 1 + 16 + 1 + 9 + 1 + 25 + 2 + 0 + 4 + 4} \\ &= 2\sqrt{19} \end{aligned}$$

Let there be two vector norms, $\|\cdot\|_a$ on \mathbb{R}^n and $\|\cdot\|_b$ on \mathbb{R} . If $\|\cdot\|$ (matrix norm) satisfies

$$\forall \mathbf{A} \in \mathbb{R}^{m \times n}, x \in \mathbb{R}^n \quad [\|\mathbf{A}x\|_b \leq \|\mathbf{A}\| \|\mathbf{x}\|_a]$$

then $\|\cdot\|$ is **consistent** with $\|\cdot\|_a$ and $\|\cdot\|_b$. Additionally if $a = b$, then $\|\cdot\|$ is **compatible** with $\|\cdot\|_a$. This gives us the following propositions;

- $\|\cdot\|_1$ (matrix norm) is compatible with $\|\cdot\|_1$ (vector norm)
- $\|\cdot\|_2$ (matrix norm) is compatible with $\|\cdot\|_2$ (vector norm)
- $\|\cdot\|_\infty$ (matrix norm) is compatible with $\|\cdot\|_\infty$ (vector norm)
- $\|\cdot\|_F$ (matrix norm) is compatible with $\|\cdot\|_2$ (vector norm) $\Rightarrow \|\mathbf{A}x\|_2 \leq \|\mathbf{A}\|_F \|\mathbf{x}\|_2$

Given a vector norm $\|\cdot\|$ on \mathbb{R}^n then the matrix norm $\|\cdot\|$ subordinate to vector norm $\|\cdot\|$ is defined by

$$\|\mathbf{A}\| = \max\{\|\mathbf{A}x\| : \|\mathbf{x}\| \leq 1\} = \max\{\|\mathbf{A}x\| : \|\mathbf{x}\| = 1\} = \max\{\|\mathbf{A} \frac{x}{\|\mathbf{x}\|}\| : \mathbf{x} \neq \mathbf{0}\}$$

Using this, we can prove property (iii) (see above). We claim that $\|\mathbf{A} + \mathbf{B}\| \leq \|\mathbf{A}\| + \|\mathbf{B}\|$ for matrix norm $\|\cdot\|$ subordinate to vector norm $\|\cdot\|$.

$$\begin{aligned} \|\mathbf{A} + \mathbf{B}\| &= \max\{\|(\mathbf{A} + \mathbf{B})x\| : \|\mathbf{x}\| \leq 1\} \\ &= \max\{\|\mathbf{A}x + \mathbf{B}x\| : \|\mathbf{x}\| \leq 1\} \\ &\leq \max\{\|\mathbf{A}x\| + \|\mathbf{B}x\| : \|\mathbf{x}\| \leq 1\} && \text{triangle inequality for } \|\cdot\| \\ &\leq \max\{\|\mathbf{A}x\| : \|\mathbf{x}\| \leq 1\} + \max\{\|\mathbf{B}x\| : \|\mathbf{x}\| \leq 1\} && \text{maximise independently} \\ &= \|\mathbf{A}\| + \|\mathbf{B}\| \end{aligned} \quad \blacksquare$$

We are also able to prove property (iv), which we claim to be $\|\mathbf{BA}\| \leq \|\mathbf{B}\| \|\mathbf{A}\|$.

$$\begin{aligned} \|\mathbf{BA}\| &= \max\{\|\mathbf{BA}x\| : \|\mathbf{x}\| \leq 1\} \\ \|\mathbf{BA}x\| &= \|\mathbf{B}(\mathbf{A}x)\| \\ \|\mathbf{A}x\| &\leq \|\mathbf{A}\| \|\mathbf{x}\| && \text{matrix norm subordinate to vector norm} \end{aligned}$$

To show the line above, we consider the two cases, $\mathbf{x} \neq \mathbf{0}$ and $\mathbf{x} = \mathbf{0}$. If $\mathbf{x} = \mathbf{0}$, no work needs to be done, as it is trivial. I have no idea why this works, but he wrote it.

$$\begin{aligned} \text{show } \left\| \mathbf{A} \frac{\mathbf{x}}{\|\mathbf{x}\|} \right\| &\leq \|\mathbf{A}\| \\ \text{but } \left\| \frac{\mathbf{x}}{\|\mathbf{x}\|} \right\| &= 1 \\ \|\mathbf{Ax}\| &\leq \|\mathbf{A}\| \|\mathbf{x}\| \end{aligned} \Rightarrow$$

Continuing on, we have

$$\begin{aligned} \|\mathbf{BAx}\| &= \|\mathbf{B}(\mathbf{Ax})\| \\ &\leq \|\mathbf{B}\| \|\mathbf{Ax}\| \\ &\leq \|\mathbf{B}\| \|\mathbf{A}\| \|\mathbf{x}\| \\ \|\mathbf{BA}\| &= \max\{\|\mathbf{BAx}\| : \|\mathbf{x}\| \leq 1\} \\ &\leq \max\{\|\mathbf{B}\| \|\mathbf{A}\| \|\mathbf{x}\| : \|\mathbf{x}\| \leq 1\} \\ &= \|\mathbf{B}\| \|\mathbf{A}\| \max\{\|\mathbf{x}\| : \|\mathbf{x}\| \leq 1\} && \text{obviously 1, as bounded on top} \\ &= \|\mathbf{B}\| \|\mathbf{A}\| && \blacksquare \end{aligned}$$

Complex Vectors

$$\mathbb{C}^n = \left\{ \mathbf{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} : v_i \in \mathbb{C} \right\}$$

$$\begin{aligned} z \in \mathbb{C} &= a + ib && a \in \mathbb{R}, b \in \mathbb{R}, i = \sqrt{-1} \\ z^* &= a - ib \\ |z| &= \sqrt{a^2 + b^2} \end{aligned}$$

Take a linear map $f : \mathbb{C}^n \rightarrow \mathbb{C}^m$, the same properties hold;

$$f(a\mathbf{v} + b\mathbf{w}) = af(\mathbf{v}) + bf(\mathbf{w}) \quad a, b \in \mathbb{C}$$

We also want to define something similar to the dot product in \mathbb{R}^n ;

$$\begin{aligned} \mathbf{v} \cdot \mathbf{w} &= \|\mathbf{v}\|_2 \|\mathbf{w}\|_2 \cos \theta_{\mathbf{v}, \mathbf{w}} \\ \mathbf{v} \cdot \mathbf{v} &= \sqrt{\|\mathbf{v}\|_2^2} \\ &= \|\mathbf{v}\|_2 \\ \langle \mathbf{v}, \mathbf{w} \rangle &= \sum_{i=1}^n v_i^* w_i \\ \langle \mathbf{v}, \mathbf{v} \rangle &= \sum_{i=1}^n v_i^* v_i \\ &= \sum_{i=1}^n |v_i|^2 \end{aligned}$$

The standard basis in \mathbb{R}^n is defined as $(\mathbf{e}_1, \dots, \mathbf{e}_n)$ where

$$\mathbf{e}_j = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} \begin{matrix} 1^{\text{st}} \\ 2^{\text{nd}} \\ \vdots \\ j^{\text{th}} \\ \vdots \\ n^{\text{th}} \end{matrix}$$

For any vector $\mathbf{v} \in \mathbb{C}^n$, it can be written in the standard basis as such;

$$\mathbf{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \\ = v_1 \mathbf{e}_1 + \cdots + v_n \mathbf{e}_n$$

Basis Change, Again

Let the linear map $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

$$\mathbf{B} = (\mathbf{b}_1, \dots, \mathbf{b}_n)$$

an ordered basis of \mathbb{R}^n

$$\mathbf{D} = (\mathbf{d}_1, \dots, \mathbf{d}_m)$$

an ordered basis of \mathbb{R}^m

Find the matrix \mathbf{A} ($\mathbf{A} := f_{\mathbf{D}\mathbf{B}}$) representing f with respect to (?) \mathbf{B} and \mathbf{D} .

$$\mathbf{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \quad \text{coordinates of a point } \mathbf{p} \in \mathbb{R}^n$$

$$\mathbf{p} = \sum_{j=1}^n v_j \mathbf{b}_j$$

$$\mathbf{A}\mathbf{v}$$

should be coordinate of $f(\mathbf{p}) \in \mathbb{R}^m$

$$f(\mathbf{p}) = \sum_{i=1}^m (\mathbf{A}\mathbf{v})_i \mathbf{d}_i$$

$$f(\mathbf{b}_j) \in \mathbb{R}^m = \sum_{i=1}^m a_{i,j} \mathbf{d}_i \quad 1 \leq j \leq n$$

Take $\mathbf{B} \in \mathbb{R}^{m \times n}$, where $\mathbf{B} = [\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n]$, and $\mathbf{e}_1, \dots, \mathbf{e}_m$ being the standard basis (see previous).

$$\mathbf{B}\mathbf{e}_j = \mathbf{B} \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \leftarrow j^{\text{th}}$$

$$= b_{1,j} \mathbf{e}_1 + \dots + b_{m,j} \mathbf{e}_m$$

Suppose $m = n$ and also $f = \text{id}$ (identity), but \mathbf{B} and \mathbf{D} are different. The matrix $(\text{id})_{\mathbf{D}\mathbf{B}}$ represents a change of basis from \mathbf{B} to \mathbf{D} . The point $\mathbf{p} \in \mathbb{R}^n$ has coordinates $\mathbf{x} \in \mathbb{R}^n$ with respect to \mathbf{B} , and $\mathbf{y} \in \mathbb{R}^n$ with respect to \mathbf{D} .

$$\mathbf{D}\mathbf{y} = \mathbf{p} = \mathbf{B}\mathbf{x} = x_1 \mathbf{b}_1 + \cdots + x_n \mathbf{b}_n$$

From this we gather $\mathbf{D}\mathbf{y} = \mathbf{B}\mathbf{x}$, therefore $\mathbf{y} = \mathbf{D}^{-1} \mathbf{B}\mathbf{x} = (\text{id})_{\mathbf{D}\mathbf{B}} \mathbf{x}$, which means that

$$(\text{id})_{\mathbf{D}\mathbf{B}} = \mathbf{D}^{-1} \mathbf{B}$$

Some stuff on functions between bases?

$$\begin{array}{ccccc} \mathbb{R}^n & \xrightarrow{f} & \mathbb{R}^m & \xrightarrow{g} & \mathbb{R}^k \\ \mathbf{B} & & \mathbf{C} & & \mathbf{D} \\ \mathbb{R}^n_{\mathbf{B}} & \xrightarrow{f_{\mathbf{C}\mathbf{B}}} & \mathbb{R}^m_{\mathbf{C}} & \xrightarrow{g_{\mathbf{D}\mathbf{C}}} & \mathbb{R}^k_{\mathbf{D}} \end{array}$$

$$g_{\mathbf{D}\mathbf{C}} f_{\mathbf{C}\mathbf{B}} = (g \circ f)_{\mathbf{D}\mathbf{B}}$$

This then goes into change of basis, but see last year's **CO145**.

22nd January 2020

Tutorial Question

$f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear map, and $\mathbf{E} = (\mathbf{e}_1, \mathbf{e}_2)$ is an ordered basis.

$$f(\mathbf{e}_1) = 5\mathbf{e}_1 - 6\mathbf{e}_2$$

$$f(\mathbf{e}_2) = 3\mathbf{e}_1 + \mathbf{e}_2$$

We only care about what the linear map does to the ordered basis, as anything else can be done by linearity.

- (i) Find $f_{\mathbf{E}\mathbf{E}}$, the matrix representation of f in \mathbf{E} - note that this has the same input space as the output space, but it can be different.

The first column can be done by reading the entry for $f(\mathbf{e}_1)$, and similarly for the second column as follows;

$$f_{\mathbf{E}\mathbf{E}} = \begin{bmatrix} 5 & 3 \\ -6 & 1 \end{bmatrix}$$

- (ii) If we have another ordered basis $\mathbf{D} = (\mathbf{d}_1, \mathbf{d}_2)$, where $\mathbf{d}_1 = \mathbf{e}_1 - \mathbf{e}_2$ and $\mathbf{d}_2 = \mathbf{e}_1 + \mathbf{e}_2$, find $f_{\mathbf{D}\mathbf{D}}$.

$$\begin{array}{ccc} \mathbb{R}_{\mathbf{E}}^2 & \xrightarrow{f_{\mathbf{E}\mathbf{E}}} & \mathbb{R}_{\mathbf{E}}^2 \\ \mathbf{I}_{\mathbf{E}\mathbf{D}} \uparrow & & \downarrow \mathbf{I}_{\mathbf{D}\mathbf{E}} = (\mathbf{I}_{\mathbf{E}\mathbf{D}})^{-1} \\ \mathbb{R}_{\mathbf{D}}^2 & \xrightarrow{f_{\mathbf{D}\mathbf{D}}} & \mathbb{R}_{\mathbf{D}}^2 \end{array}$$

$\mathbf{I}_{\mathbf{E}\mathbf{D}}$ can easily be obtained by reading the entries for \mathbf{d}_1 for the first column, and similarly for \mathbf{d}_2 in the second column;

$$\mathbf{I}_{\mathbf{E}\mathbf{D}} = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

$$\mathbf{I}_{\mathbf{D}\mathbf{E}} = (\mathbf{I}_{\mathbf{E}\mathbf{D}})^{-1}$$

$$= \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

$$f_{\mathbf{D}\mathbf{D}} = \mathbf{I}_{\mathbf{D}\mathbf{E}} f_{\mathbf{E}\mathbf{E}} \mathbf{I}_{\mathbf{E}\mathbf{D}}$$

$$= \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 5 & 3 \\ -6 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} 1 & 13 \\ -5 & 3 \end{bmatrix}$$

Eigenvalues + Generalised Eigenvectors

Working with a matrix $\mathbf{A} \in \mathbb{C}^{m \times m}$. For an eigenvector $\mathbf{v} \in \mathbb{C}^m \setminus \{\mathbf{0}\}$, and an eigenvalue $\lambda \in \mathbb{C}$, $\mathbf{A}\mathbf{v} = \lambda\mathbf{v} \Rightarrow (\mathbf{A} - \lambda\mathbf{I})\mathbf{v} = \mathbf{0} \Rightarrow |\mathbf{A} - \lambda\mathbf{I}| = 0 \Rightarrow P_{\mathbf{A}}(\lambda) = 0$ (characteristic polynomial). This complex polynomial will be of degree m , and it will have precisely m roots (including multiplicity). Suppose $P_{\mathbf{A}}(\lambda) = 0$, then $(\mathbf{A} - \lambda\mathbf{I})\mathbf{v} = \mathbf{0}$ has a solution where $\mathbf{v} \neq \mathbf{0}$.

Assume we have $\lambda_1, \dots, \lambda_t$ distinct eigenvalues, meaning that $P_{\mathbf{A}}(\lambda_i) = 0$ for $1 \leq i \leq t$. This means we can write the characteristic polynomial as;

$$P_{\mathbf{A}}(\lambda) = (\lambda - \lambda_1)^{m_1} (\lambda - \lambda_2)^{m_2} \dots (\lambda - \lambda_t)^{m_t}$$

Where m_i is the **algebraic multiplicity** of λ_i . $m_i \in \mathbb{N}$, and also $1 \leq m_i \leq m$, as it must not exceed the dimension of the matrix. On the other hand, the **geometric multiplicity** of λ_i is ℓ_i , which is the **nullity** of $(\mathbf{A} - \lambda_i \mathbf{I})$. The nullity is the dimension of the kernel / null-space. $1 \leq \ell_i \leq m_i$, as we already have at least one non-zero solution from $(\mathbf{A} - \lambda_i \mathbf{I})\mathbf{v} = \mathbf{0}$.

In the nice case, we have $\ell_i = m_i$, for $1 \leq i \leq t$, which means the matrix is diagonalisable. We have m_i linearly independent vectors $(\mathbf{v}_{i,1}, \mathbf{v}_{i,2}, \dots, \mathbf{v}_{i,m_i})$ which satisfy

$$\mathbf{A}\mathbf{v}_{i,j} = \lambda_i \mathbf{v}_{i,j} \text{ for } 1 \leq j \leq m_i$$

If we take these eigenvectors as an ordered basis;

$$\mathbf{B} = [\mathbf{v}_{1,1}, \mathbf{v}_{1,2}, \dots, \mathbf{v}_{1,m_1}, \mathbf{v}_{2,1}, \mathbf{v}_{2,2}, \dots, \mathbf{v}_{2,m_2}, \dots, \mathbf{v}_{t,1}, \mathbf{v}_{t,2}, \dots, \mathbf{v}_{t,m_t}]$$

We also want to note that $\sum_{i=1}^t m_i = m$, as that is the degree of the characteristic polynomial. Multiplying the basis by the original matrix, we get;

$$\mathbf{A}\mathbf{B} = [\lambda_1 \mathbf{v}_{1,1}, \lambda_1 \mathbf{v}_{1,2}, \dots, \lambda_1 \mathbf{v}_{1,m_1}, \lambda_2 \mathbf{v}_{2,1}, \lambda_2 \mathbf{v}_{2,2}, \dots, \lambda_2 \mathbf{v}_{2,m_2}, \dots, \lambda_t \mathbf{v}_{t,1}, \lambda_t \mathbf{v}_{t,2}, \dots, \lambda_t \mathbf{v}_{t,m_t}]$$

Since all the columns of \mathbf{B} are linearly independent, by our definition, the inverse \mathbf{B}^{-1} exists. Therefore, we can write

$$\mathbf{B}^{-1}\mathbf{A}\mathbf{B} = \begin{bmatrix} \lambda_1 & & & & & \\ & \ddots & & & & \\ & & \lambda_1 & & & \\ & & & \lambda_2 & & \\ & & & & \ddots & \\ & & & & & \lambda_2 \\ & & & & & & \ddots & \\ & & & & & & & \lambda_t \\ & & & & & & & & \ddots & \\ & & & & & & & & & \lambda_t \end{bmatrix} \quad (\text{everything else is } 0)$$

Which has m_1 instances of λ_1 , followed by m_2 instances of λ_2 , and so on, until m_t instances of λ_t .

Example for $\ell_i = m_i$

$$\mathbf{A} = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ 1 & 0 & 4 \end{bmatrix}$$

$$|\mathbf{A} - \lambda \mathbf{I}| = (\lambda - 3)^2(\lambda - 5)$$

$$\lambda_1 = 3$$

two linearly independent eigenvectors

$$\mathbf{v}_{1,1} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\mathbf{v}_{1,2} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$\lambda_2 = 5$$

$$\mathbf{v}_{2,1} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$$\mathbf{B} = \begin{bmatrix} 0 & -1 & 1 \\ 1 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix}$$

$$\mathbf{B}^{-1} = \frac{1}{2} \begin{bmatrix} -2 & 2 & -2 \\ -1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$\mathbf{B}^{-1}\mathbf{A}\mathbf{B} = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

Trivial Example for $\ell_i < m_i$

$$\mathbf{A} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$|\mathbf{A} - \lambda\mathbf{I}| = \lambda^2$$

$$\lambda_1 = 0$$

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

only solution, hence $\ell_1 = 1 < 2 = m_1$

$$(\mathbf{A} - 0\mathbf{I}) \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

although this vector is not mapped to zero, it is mapped to something that **will** be mapped to zero

$$(\mathbf{A} - 0\mathbf{I})^2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = (\mathbf{A} - 0\mathbf{I})(\mathbf{A} - 0\mathbf{I}) \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$= (\mathbf{A} - 0\mathbf{I}) \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= \mathbf{0}$$

We say $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ is a generalised eigenvector for $\lambda_1 = 0$. A vector which is not mapped by $(\mathbf{A} - \lambda\mathbf{I})$ to $\mathbf{0}$, but is $\mathbf{0}$ when iterated once more.

Less Trivial Example

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$|\mathbf{A} - \lambda\mathbf{I}| = (1 - \lambda)^3$$

$$\lambda_1 = 1$$

$$(\mathbf{A} - \mathbf{I})\mathbf{x} = \mathbf{0}$$

$$\begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \mathbf{x} = \mathbf{0}$$

$$m_1 = 3$$

$$\Leftrightarrow$$

this has rank 1, and therefore by rank-nullity theorem (rank + nullity = 3), has 2 linearly independent solutions, therefore $\ell_1 = 2 < 3 = m_1$

$$\mathbf{v}_1 = \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$$

$$\mathbf{v}_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

to find the generalised eigenvector \mathbf{v}_3 , we want to find some vector that is mapped by $(\mathbf{A} - 1\mathbf{I})$ to the eigenspace, which is some linear combination of \mathbf{v}_1 and \mathbf{v}_2

$$\begin{aligned} (\mathbf{A} - \mathbf{I})\mathbf{v}_3 &= \alpha_1\mathbf{v}_1 + \alpha_2\mathbf{v}_2 && \Leftrightarrow \\ \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ \alpha_1 \\ -\alpha_1 \end{bmatrix} + \begin{bmatrix} \alpha_2 \\ 0 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} x_2 + x_3 \\ 0 \\ 0 \end{bmatrix} && \Leftrightarrow \\ \alpha_1 &= 0 \\ x_2 + x_3 &= \alpha_2 && \text{let } x_2 = 0 \Rightarrow x_3 = \alpha_2 = 1 \\ \mathbf{v}_3 &= \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \\ \mathbf{B} &= [\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3] \\ &= \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ -1 & 0 & 1 \end{bmatrix} \\ \mathbf{B}^{-1}\mathbf{A}\mathbf{B} &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} && \text{the extra 1 is from } \mathbf{v}_2? \end{aligned}$$

This is in Jordan Normal Form. For some λ_i eigenvalue, and $\ell_i \leq m_i$, the sum of the sizes of the blocks is m_i , and the number of blocks is ℓ_i . If λ_i is an eigenvalue of \mathbf{A} with algebraic multiplicity m_i , then the nullity of $(\mathbf{A} - \lambda_i\mathbf{I})^{m_i} = m_i$.

Definition: $\mathbf{v} \in \mathbb{R}^m$ is a generalised eigenvector for λ_i if $(\mathbf{A} - \lambda_i\mathbf{I})^{m_i}\mathbf{v} = \mathbf{0}$. The maximum iterations is m_i , but can be less.

23rd January 2020

In general;

- $\forall j [\ell_j = m_j] \Rightarrow \mathbf{A}$ is diagonalisable
- $\exists j [\ell_j < m_j] \Rightarrow \mathbf{A}$ is diagonalisable or **almost** diagonalisable

The following is a very poor explanation of what the form looks like, because I don't know how to draw blocks in L^AT_EX. See Panopto at timestamp 13:17 for a proper drawing.

$$\begin{aligned} \mathbf{A} &= \begin{bmatrix} \mathbf{B}_{\lambda_1} & & \\ & \ddots & \\ & & \mathbf{B}_{\lambda_t} \end{bmatrix} \\ \mathbf{B}_j &= \begin{bmatrix} \mathbf{J}_j & & \\ & \ddots & \\ & & \mathbf{J}_j \end{bmatrix} \end{aligned} \quad \text{all } \mathbf{J}_j \text{ can be of different sizes, } \mathbf{B}_j \in \mathbb{R}^{m_j \times m_j}$$

$$\mathbf{J}_i = \begin{bmatrix} \lambda_i & 1 & & \\ & \lambda_i & \ddots & \\ & & \ddots & 1 \\ & & & \lambda_i \end{bmatrix}$$

Spectral Decomposition of Symmetric Matrices

In almost all areas of computer science, symmetric matrices are the dominant paradigm. All the eigenvalues of real symmetric matrices are real, and are always diagonalisable. A symmetric matrix is always a square matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$, which also satisfies $\mathbf{A}^\top = \mathbf{A}$, meaning it is symmetric along the diagonal (the elements above the diagonal determine the elements below, and vice versa). We are to prove the following properties;

- (i) All eigenvalues of \mathbf{A} are real.

First assume that $\mathbf{v} \in \mathbb{C}^n$, as we don't yet know that it is real, therefore we can have the case $\lambda \in \mathbb{C}$.

$$\begin{aligned} \mathbf{A}\mathbf{v} &= \lambda\mathbf{v} & \Rightarrow \\ \mathbf{v}^{*\top} \mathbf{A}\mathbf{v} &= \lambda \mathbf{v}^{*\top} \mathbf{v} \\ &= \lambda \|\mathbf{v}\|^2 \\ \mathbf{v}^{*\top} \mathbf{A}\mathbf{v} &= (\mathbf{v}^{*\top} \mathbf{A}) \mathbf{v} \\ &= ((\mathbf{A}\mathbf{v})^\top)^* \mathbf{v} \end{aligned} \tag{1}$$

briefly proving the above;

$$\begin{aligned} ((\mathbf{A}\mathbf{v})^\top)^* &= (\mathbf{v}^\top \mathbf{A}^\top)^* & \text{taking the transpose inside the bracket} \\ &= (\mathbf{v}^\top)^* \mathbf{A}^* & \text{taking the conjugate inside and } \mathbf{A}^\top = \mathbf{A} \\ &= (\mathbf{v}^\top)^* \mathbf{A} & \mathbf{A} \text{ is real valued matrix} \end{aligned}$$

continuing on;

$$\begin{aligned} &= ((\lambda\mathbf{v})^\top)^* \mathbf{v} & \mathbf{v} \text{ is an eigenvector} \\ &= \lambda^* (\mathbf{v}^\top)^* \mathbf{v} & \text{transposing a scalar does nothing} \\ &= \lambda^* \|\mathbf{v}\|^2 & (2) \end{aligned}$$

By comparing results, (1) = (2), hence $\lambda^* = \lambda$ (dividing through by $\|\mathbf{v}\|^2$ is allowed, since we know it is non-zero by properties of vector norms, and $\mathbf{v} \neq \mathbf{0}$ by properties of eigenvectors). As the complex conjugate of λ is the same as λ , we can conclude that $\lambda \in \mathbb{R}$.

- (ii) Eigenvectors corresponding to different eigenvalues of \mathbf{A} are perpendicular.

Note that with the above result, we know that $\mathbf{v} \in \mathbb{R}^n$, as there is no possible way to obtain complex values with a real valued matrix and a real valued eigenvalue.

$$\begin{aligned} \mathbf{A}\mathbf{v}_1 &= \lambda_1 \mathbf{v}_1 \\ \mathbf{A}\mathbf{v}_2 &= \lambda_2 \mathbf{v}_2 \\ \lambda_1 &\neq \lambda_2 \\ \mathbf{v}_2^\top \mathbf{A}\mathbf{v}_1 &= \lambda_1 \mathbf{v}_2^\top \mathbf{v}_1 \\ &= \lambda_1 (\mathbf{v}_1 \cdot \mathbf{v}_2) & (1) \\ \mathbf{v}_2^\top \mathbf{A}\mathbf{v}_1 &= (\mathbf{v}_2^\top \mathbf{A}) \mathbf{v}_1 \\ &= (\mathbf{A}\mathbf{v}_2)^\top \mathbf{v}_1 & \text{adding a transpose and } \mathbf{A}^\top = \mathbf{A} \\ &= \lambda_2 \mathbf{v}_2^\top \mathbf{v}_1 & \mathbf{v}_2 \text{ is an eigenvector} \\ &= \lambda_2 (\mathbf{v}_1 \cdot \mathbf{v}_2) & (2) \end{aligned}$$

Similarly, comparing results (1) and (2), we get

$$\begin{aligned}
 \lambda_1(\mathbf{v}_1 \cdot \mathbf{v}_2) &= \lambda_2(\mathbf{v}_1 \cdot \mathbf{v}_2) && \Leftrightarrow \\
 \lambda_1(\mathbf{v}_1 \cdot \mathbf{v}_2) - \lambda_2(\mathbf{v}_1 \cdot \mathbf{v}_2) &= 0 \\
 (\lambda_1 - \lambda_2)(\mathbf{v}_1 \cdot \mathbf{v}_2) &= 0 && \Leftrightarrow \\
 \lambda_1 &= \lambda_2 \\
 \text{or } \mathbf{v}_1 \cdot \mathbf{v}_2 &= 0
 \end{aligned}$$

The former is not possible due to the condition that they are different eigenvalues, therefore $\mathbf{v}_1 \cdot \mathbf{v}_2 = 0$. As neither are the zero vector, by definition of eigenvectors, $\cos \theta = 0$, therefore they are perpendicular.

(iii) (Tutorial 3) If λ_j is an eigenvalue of \mathbf{A} then $\ell_j = m_j$, therefore \mathbf{A} is diagonalisable.

Come back to this in two weeks?

To conclude, we get all the eigenvectors and we normalise them (divide by the ℓ_2 -norm), and we can assume they are pairwise orthogonal. There is an orthonormal basis for \mathbb{R}^n consisting of eigenvectors of \mathbf{A} ; $(\mathbf{v}_1, \dots, \mathbf{v}_n)$, where $\mathbf{v}_j \in \mathbb{R}^n$. This has the following properties;

- $\mathbf{A}\mathbf{v}_j = \lambda_j\mathbf{v}_j$
- $\mathbf{v}_i \perp \mathbf{v}_j$, when $i \neq j$ perpendicular
- $\|\mathbf{v}_i\| = 1$ for $i = 1, \dots, n$

Examples

For an example in $\mathbb{R}^{2 \times 2}$;

$$\begin{aligned}
 \mathbf{A} &= \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \\
 |\mathbf{A} - \lambda \mathbf{I}| &= (1 - \lambda)^2 - 4 \\
 \lambda_1 &= 3 \\
 \lambda_2 &= -1 \\
 \mathbf{v}_1 &= \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} && \text{normalise straight away} \\
 \mathbf{v}_2 &= \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \\
 \mathbf{V} &= [\mathbf{v}_1, \mathbf{v}_2] && \text{orthonormal basis of } \mathbb{R}^2 \\
 &= \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \\
 \mathbf{A}\mathbf{V} &= [\mathbf{A}\mathbf{v}_1, \mathbf{A}\mathbf{v}_2] \\
 &= [3\mathbf{v}_1, -\mathbf{v}_2]
 \end{aligned}$$

For a symmetric matrix, if we have a matrix \mathbf{V} representing the orthonormal basis of the eigenvectors, $\mathbf{V}^{-1} = \mathbf{V}^\top$

$$\begin{aligned}
 \mathbf{V}^{-1}\mathbf{A}\mathbf{V} &= \mathbf{V}^\top \mathbf{A}\mathbf{V} \\
 &= \mathbf{V}^\top [3\mathbf{v}_1, -\mathbf{v}_2] \\
 &= \begin{bmatrix} \mathbf{v}_1^\top \\ \mathbf{v}_2^\top \end{bmatrix} [3\mathbf{v}_1, -\mathbf{v}_2] \\
 &= \begin{bmatrix} 3 & 0 \\ 0 & -1 \end{bmatrix} && \text{dot product with unit length } (\mathbf{v}_1 \perp \mathbf{v}_2)
 \end{aligned}$$

For an example in $\mathbb{R}^{3 \times 3}$,

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 3 \\ 1 & 3 & 1 \\ 3 & 1 & 1 \end{bmatrix}$$

now he just shows some intuition on getting an eigenvalue?

$$\begin{aligned} |\mathbf{A} - \lambda \mathbf{I}| &= \begin{vmatrix} 1 - \lambda & 1 & 3 \\ 1 & 3 - \lambda & 1 \\ 3 & 1 & 1 - \lambda \end{vmatrix} \\ &= \begin{vmatrix} 5 - \lambda & 1 & 3 \\ 5 - \lambda & 3 - \lambda & 1 \\ 5 - \lambda & 1 & 1 - \lambda \end{vmatrix} \\ &= 0 \end{aligned}$$

$$\lambda_1 = 5$$

$$\text{trace}(\mathbf{A}) = \lambda_1 + \lambda_2 + \lambda_3$$

$$= 5$$

\Rightarrow

$$\lambda_2 + \lambda_3 = 0$$

$$|\mathbf{A}| = \lambda_1 \lambda_2 \lambda_3$$

$$= -20$$

\Rightarrow

$$\lambda_2 \lambda_3 = -4$$

$$\lambda_2 = 2$$

$$\lambda_3 = -2$$

$$\mathbf{v}_1 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\mathbf{v}_2 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

$$\mathbf{v}_3 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\mathbf{V} = [\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3]$$

$$\mathbf{V}^{-1} = \mathbf{V}^\top$$

$$\mathbf{V}^{-1} \mathbf{A} \mathbf{V} = \mathbf{V}^\top \mathbf{A} \mathbf{V}$$

$$= \begin{bmatrix} 5 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

spectral decomposition of a symmetric matrix

Proof of $\mathbf{V}^{-1} = \mathbf{V}^\top$

We define $\mathbf{B} \in \mathbb{R}^{n \times n}$ as an **orthogonal matrix** if all columns \mathbf{b}_j for $1 \leq j \leq n$ form an orthonormal basis of \mathbb{R}^n , such that the two properties hold;

- $\mathbf{b}_j \cdot \mathbf{b}_i = 0$ when $i \neq j$
- $\mathbf{b}_j \cdot \mathbf{b}_j = 1$

We want to prove that $B^{-1} = B^\top$:

$$\begin{aligned}
B &= [b_1, \dots, b_n] \\
B^\top &= \begin{bmatrix} b_1^\top \\ \vdots \\ b_n^\top \end{bmatrix} \\
B^\top B &= \begin{bmatrix} b_1^\top \\ \vdots \\ b_n^\top \end{bmatrix} [b_1, \dots, b_n] \\
&= \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & 1 \end{bmatrix} \\
&= I_n
\end{aligned}$$

Preservation of Length

The length of a vector \mathbf{x} is preserved under orthogonal transformation;

$$\begin{aligned}
(\mathbf{V}\mathbf{x}) \cdot (\mathbf{V}\mathbf{x}) &= (\mathbf{V}\mathbf{x})^\top (\mathbf{V}\mathbf{x}) \\
&= \mathbf{x}^\top \mathbf{V}^\top \mathbf{V} \mathbf{x} \\
&= \mathbf{x}^\top \mathbf{V}^{-1} \mathbf{V} \mathbf{x} \\
&= \mathbf{x}^\top \mathbf{x} \\
&= \mathbf{x} \cdot \mathbf{x}
\end{aligned}$$

Geometric Intuition

Take a real symmetric matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$, such that $\mathbf{A}^\top = \mathbf{A}$. Assume we have processed it to get the eigenvalues $\lambda_1, \dots, \lambda_n$, such that $\mathbf{V}^\top \mathbf{A} \mathbf{V} = \text{diag}(\lambda_1, \dots, \lambda_n)$, and \mathbf{V} is an orthonormal matrix formed of the eigenvectors.

Take a vector \mathbf{x} from the input space, to $\mathbf{A}\mathbf{x}$ in the output space, mapped by \mathbf{A} ;

$$\begin{array}{ccc}
\text{input space} & \xrightarrow{\mathbf{A} = f_{EE}} & \text{output space} \\
\mathbf{x} & \xrightarrow{\quad} & \mathbf{A}\mathbf{x} \\
\mathbb{R}_E^n & \xrightarrow{f_{EE} = \mathbf{A}} & \mathbb{R}_E^n \\
\uparrow I_{EV} = \mathbf{V} & & \downarrow I_{VE} = (\mathbf{I}_{ED})^{-1} = \mathbf{V}^{-1} \\
\mathbb{R}_V^n & \xrightarrow{f_{DD} = \mathbf{V}^{-1} \mathbf{A} \mathbf{V}} & \mathbb{R}_V^n
\end{array}$$

Consider a unit sphere, created by $\|\mathbf{x}\| = 1$, where $\mathbf{x} \in \mathbb{R}^3$. The transformations $\mathbf{V}^{-1} = \mathbf{V}^\top$ and \mathbf{V} are rotations as they preserve length. Take a point \mathbf{x} on the surface of this unit sphere, applying \mathbf{V}^{-1} to it simply rotates it to another point on the surface of the sphere (going from \mathbb{R}_E^3 to \mathbb{R}_V^3) in the input space. Let this point have coordinates \mathbf{u} with respect to \mathbf{V} . Under the diagonal map $\text{diag}(\lambda_1, \dots, \lambda_n)$, we get the following;

$$u_1 \mathbf{v}_1 + \dots + u_n \mathbf{v}_n \mapsto \lambda_1 u_1 \mathbf{v}_1 + \dots + \lambda_n u_n \mathbf{v}_n$$

As \mathbf{u} is on the sphere, we can say;

$$\|\mathbf{u}\|_2^2 = u_1^2 + \dots + u_n^2 = 1$$

Therefore, the mapped point \mathbf{y} can be written as $\begin{bmatrix} \lambda_1 u_1 \\ \vdots \\ \lambda_n u_n \end{bmatrix}$, satisfying (in three dimensions);

$$\frac{y_1^2}{\lambda_1^2} + \frac{y_2^2}{\lambda_2^2} + \frac{y_3^2}{\lambda_3^2} = 1$$

This gives a locus of an ellipsoid.

Rank-Nullity Theorem

Take a matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$.

$$\text{Im}(\mathbf{A}) \subseteq \mathbb{R}^m = \{\mathbf{A}\mathbf{x} : \mathbf{x} \in \mathbb{R}^n\}$$

$$\dim(\text{Im}(\mathbf{A})) = \text{column rank of } \mathbf{A}$$

$$\text{Null}(\mathbf{A}) \subseteq \mathbb{R}^n = \{\mathbf{v} : \mathbf{A}\mathbf{v} = \mathbf{0}\} \quad \text{same as kernel}$$

$$\text{rk}(\text{column space}) = \text{rk}(\text{row space})$$

$$\text{row space } \mathbf{A} = \text{column space } \mathbf{A}^\top$$

For elementary row operations, we have the following property;

(I) they are invertible.

If there is one of the three elementary row operations R that takes $\mathbf{A} \rightsquigarrow \mathbf{B}$, then $\exists R^{-1}$ that takes $\mathbf{B} \rightsquigarrow \mathbf{A}$.

If $\mathbf{A} \rightsquigarrow \mathbf{B}$, then $\mathbf{B} = \mathbf{M}_R \mathbf{A}$. We obtain \mathbf{M}_R by applying R to \mathbf{I}_m , such that $\mathbf{I}_m \rightsquigarrow \mathbf{M}_R$.

A reduction to row echelon form can be written as follows (with $-$ as a pivot, and \times being any number);

$$\mathbf{A} \xrightarrow{R_1} \dots \xrightarrow{R_t} \mathbf{C} = \begin{bmatrix} - & \times & \times & \times & \times & \times \\ 0 & - & \times & \times & \times & \times \\ 0 & 0 & 0 & - & \times & \times \\ 0 & 0 & 0 & 0 & - & \times \\ 0 & 0 & 0 & 0 & 0 & - \\ \hline 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

In general it creates a staircase of the pivots, and everything below it is 0. Note that the example above is just a random example, as long as the general structure remains, it's fine.

An ERO doesn't change the row space, as it is operating on the rows. Swapping rows, multiplying by a non-zero number, and adding rows will not change anything. The claim is that while the column space can change, the rank of the column space doesn't change.

$$\mathbf{A} = [\mathbf{a}_1, \dots, \mathbf{a}_n]$$

$$\mathbf{A} \xrightarrow{R} \mathbf{M}_R \mathbf{A} = [\mathbf{M}_R \mathbf{a}_1, \dots, \mathbf{M}_R \mathbf{a}_n]$$

$$\mathbf{M}_{R^{-1}} = (\mathbf{M}_R)^{-1} \quad \text{therefore } \mathbf{M}_R \text{ is invertible}$$

taking some linear combination of the vectors in \mathbf{A}

$$\lambda_1 \mathbf{a}_{i_1} + \dots + \lambda_t \mathbf{a}_{i_t} = \mathbf{0} \quad \Leftrightarrow$$

$$\mathbf{M}_R(\lambda_1 \mathbf{a}_{i_1} + \dots + \lambda_t \mathbf{a}_{i_t}) = \mathbf{0}$$

This is due to the fact that multiplying a set of linearly independent vectors by an invertible matrix preserves independence. From this it follows that the dimension of the columns of \mathbf{A} is equal to the dimension of the columns of $\mathbf{M}_R \mathbf{A}$, since \mathbf{M}_R is invertible. Therefore neither the row rank nor the column rank changes.

Since \mathbf{C} is in REF, the row rank is equal to the column rank, which is equal to the number of pivots, let it be r , then $\text{rk}(\mathbf{A}) = r$.