Lec 22. Orthogonal systems Projection

Inner product . i, i CIR

$$\vec{u} \cdot \vec{v} = \sum_{i=1}^{n} u_i v_i . \qquad ||\vec{u}||^2 = \vec{u} \cdot \vec{u}$$

$$\|\vec{u}\|^2 = \vec{u} \cdot \vec{u}$$

$$\omega\theta = \frac{u \cdot v}{|v||v|}$$

In Chap 4.

 $\mathbb{R}^{2 \text{ or } 3} \longrightarrow \mathbb{R}^{n} \longrightarrow \mathbb{C}$

In Chap 6.

equip vector space V by an additional structure (inner product) to describe geometry.





equip



(regular) vector Space. So far IR

Inner product



Inner product Space.

Def $\{\vec{v}_i, \dots, \vec{v}_k\}$ is orthogonal set If $\vec{v}_i \in \mathbb{R}^n$, $\vec{v}_i \neq \vec{o}$, $\vec{v}_i \neq \vec{o}$, $\vec{v}_i \perp \vec{v}_j$ for all $1 \leq i \neq j \leq k$

Orthonormal set

1) Orthogonal Set 2) $||\overrightarrow{U}_{i}||=1$, $\forall 1\leq i\leq k$.

$$\mathcal{E}_{x} \cdot \overrightarrow{v}_{1} = \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} \quad \overrightarrow{v}_{2} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \quad \overrightarrow{v}_{3} = \begin{bmatrix} -1 \\ -2 \\ 5 \end{bmatrix}$$

$$\overrightarrow{U}_1 \cdot \overrightarrow{U}_2 = 0$$
, $\overrightarrow{U}_1 \cdot \overrightarrow{U}_3 = 0$, $\overrightarrow{U}_2 \cdot \overrightarrow{U}_3 = -1 - 4 + 5 = 0$

$$\|\vec{v}_i\| = \sqrt{4+1} = \sqrt{5}$$
.

$$\overline{w}_1 = \sqrt{5} \overline{v}_1, \ \overline{w}_2 = \sqrt{5} \overline{v}_2, \ \overline{w}_3 = \sqrt{30} \overline{v}_3$$
orthonormal set!

Thm
$$\{\vec{v}_{i}, \dots, \vec{v}_{k}\}$$
 is an orthogonal set then $\{in. indep.\}$

Pf. $C_{i}\vec{v}_{i} + C_{k}\vec{v}_{k} + \dots + C_{k}\vec{v}_{k} = \vec{0}$

Pick any \vec{v}_{i} , $1 \le i \le k$.

 $\vec{v}_{i} \cdot (C_{i}\vec{v}_{i} + C_{k}\vec{v}_{k} + \dots + C_{k}\vec{v}_{k}) = \vec{0}$

Orthogonal set. $\vec{v}_{i} \cdot \vec{v}_{j} = \vec{0}$, for all $i \ne j$.

 $C_{i}\vec{v}_{i} \cdot \vec{v}_{i} = \vec{0}$ \Rightarrow $C_{i} = \vec{0}$

Def
$$\{\vec{v}_1, ..., \vec{v}_k\} \subseteq \mathbb{R}^n$$
 is an orthogonal basis (0B) of subspace $W \subseteq \mathbb{R}^n$
1) Orthogonal set

2) basis
$$\rightarrow \{\vec{v}_1, \vec{v}_2, \vec{v}_k\} \subseteq W$$

 $\dim W = k$

If orthonormals et => orthonormal basis

(ONB)

Why OB/ONB is useful?

Take W= 12".

B= {bi, ..., bn} is a basis

 $\overline{v} \in \mathbb{R}^{n}$. $[\overline{v}]_{\mathcal{B}}$.

Old method: Solve a lin. 545.

$$\begin{bmatrix} b_1 & b_2 & \cdots & b_n & \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v & v & v \\ v & v \end{bmatrix} \xrightarrow{\mathcal{V}} \begin{bmatrix} v$$

$$\begin{bmatrix} \mathcal{V} \end{bmatrix}_{\mathcal{B}} = \begin{bmatrix} \mathcal{C}_{1} \\ \vdots \\ \mathcal{C}_{n} \end{bmatrix}$$

$$\vec{v} = c_1 \vec{b}_1 + \cdots + c_n \vec{b}_n$$

$$\overrightarrow{b_i} \cdot \overrightarrow{\upsilon} = \overrightarrow{b_i} \cdot (c_i \overrightarrow{b_i} + \cdots + c_n \overrightarrow{b_n}) = c_i \overrightarrow{b_i} \cdot \overrightarrow{b_i}$$

$$\Rightarrow C_i = \frac{b_i \cdot v}{b_i \cdot b_i} \qquad 1 \leq i \leq n.$$

If ONB
$$\vec{b}_i \cdot \vec{b}_i = 1$$

$$C_i = b_i \cdot v$$

$$\mathcal{E}_{X}. \quad \vec{\mathcal{U}} = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \quad \vec{\mathcal{V}}_{z} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad \vec{\mathcal{V}}_{3} = \begin{bmatrix} -1 \\ -2 \\ 5 \end{bmatrix}$$

$$OB \quad of \quad \mathbb{R}^{3} \qquad \mathcal{B} = \{ \vec{\mathcal{U}}_{1}, \vec{\mathcal{V}}_{2}, \vec{\mathcal{V}}_{3} \}.$$

$$\vec{\mathcal{U}} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{find} \quad \begin{bmatrix} \vec{\mathcal{U}} \\ \vec{\mathcal{U}} \end{bmatrix} \mathcal{B}.$$

$$C_{1} = \frac{\vec{v}_{1} \cdot \vec{u}}{\vec{v}_{1} \cdot \vec{v}_{1}} = \frac{2}{5}$$

$$C_{2} = \frac{\vec{v}_{1} \cdot \vec{u}}{\vec{v}_{2} \cdot \vec{v}_{2}} = \frac{2}{6} = \frac{1}{3}.$$

$$C_{3} = \frac{-1+5}{30} = \frac{2}{15}.$$

Spoiler: set of arbitrary vectors.

reduce

Orthogonal set?

Gram-Schmidt process.

We need to first learn:

The
$$v = (v_2)$$

The projection of v

onto the $v_1 - axis$

$$u = \begin{bmatrix} v_1 \\ 0 \end{bmatrix}$$

$$\frac{2}{5} = \frac{1}{10} - \frac{1}{10} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \qquad \frac{1}{10} = \frac{2}{10} = 0.$$

$$\sum_{v=1}^{\infty} u = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \qquad u = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$v = du + z$$

$$v = du$$

$$\frac{3}{2} = \sqrt[3]{3} - \sqrt[3]{3} = \begin{bmatrix} \frac{3}{5} \\ -\frac{1}{5} \end{bmatrix}$$

In the example above.

$$W = Span \{\vec{u}\}.$$
 dim $W = 1$

$$\vec{v} = \left(\frac{\vec{u} \cdot \vec{v}}{\vec{v} \cdot \vec{u}}\right) \vec{u} + \vec{z}$$

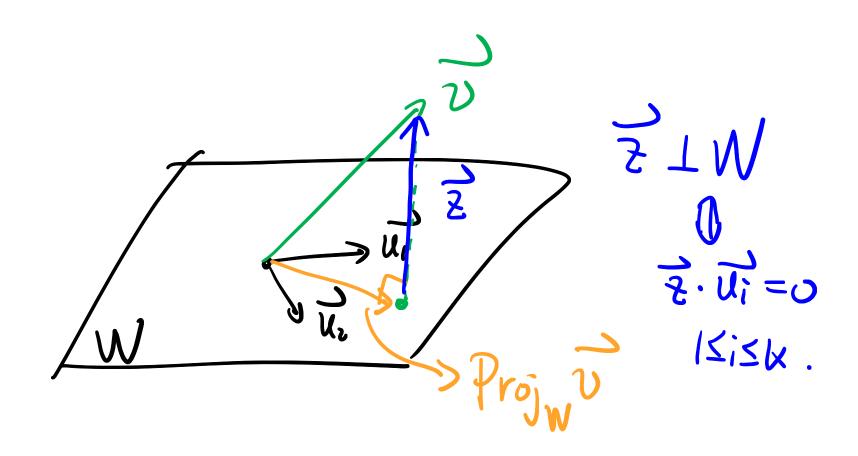
$$\vec{v} = \left(\frac{\vec{u} \cdot \vec{v}}{\vec{v} \cdot \vec{u}}\right) \vec{u} + \vec{z}$$

$$\vec{v} = \vec{v} \cdot \vec{v} \cdot \vec{v}$$

$$\vec{v} = \vec{v} \cdot \vec{v} \cdot \vec{v} \cdot \vec{v}$$

$$\exists \vec{v} = Proj_w \vec{v} + \vec{z}$$

$$W = span \left\{ \frac{1}{u_1, \dots, u_k} \right\} dim W = k$$



$$\overrightarrow{v} = \cancel{\alpha_1} \overrightarrow{u_1} + \cdots + \cancel{\alpha_k} \overrightarrow{u_k} + \frac{2}{2}$$

$$\overrightarrow{u_i} \cdot \overrightarrow{v} = \cancel{\alpha_i} \overrightarrow{u_i}$$

$$\overrightarrow{u_i} \cdot \overrightarrow{v} = \cancel{\alpha_i} \overrightarrow{u_i}$$
assumes DNB