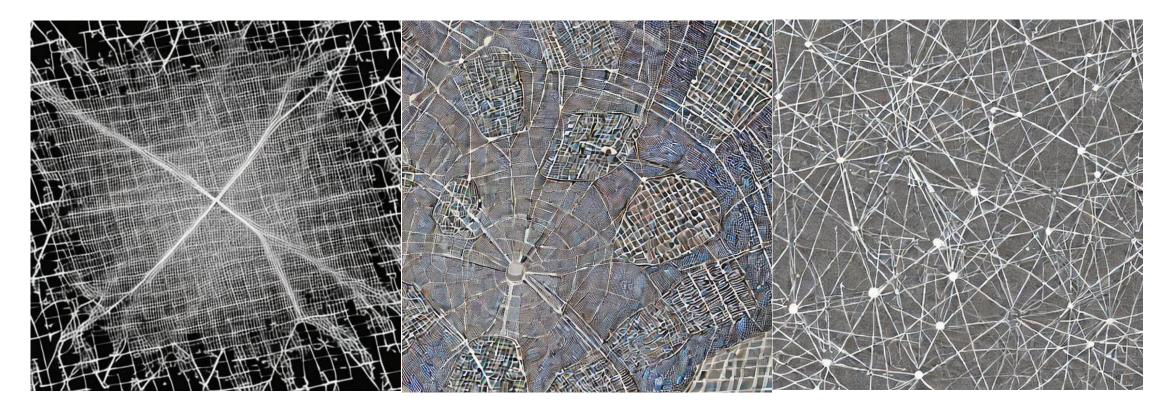
Connectivity in graphs

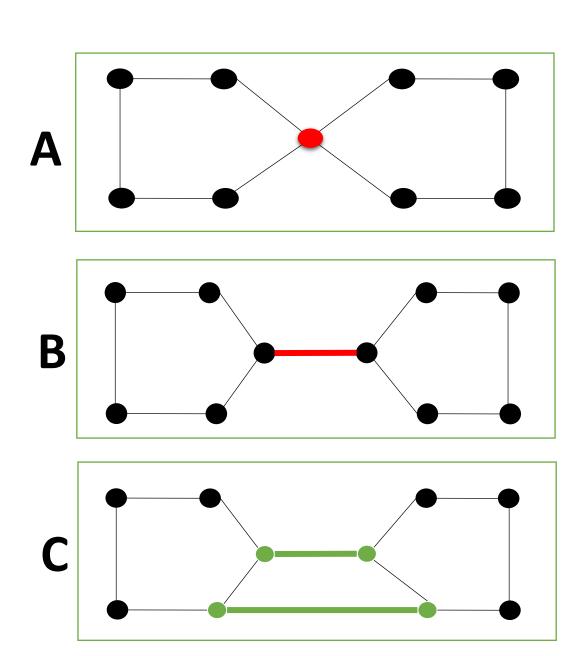
Mohammed Brahimi



Motivation example

- Communication networks represented by graphs A, B, C.
- Vertices are communication centres.
- Edges are communication channels.

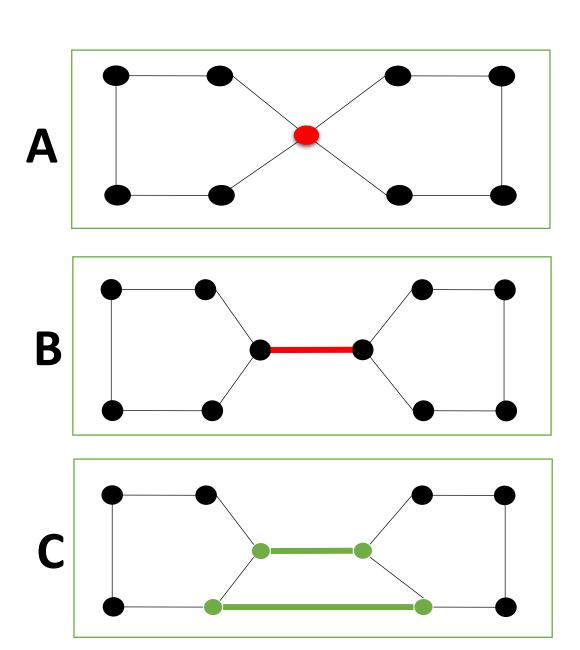
Which of these networks is better and why?



Motivation example

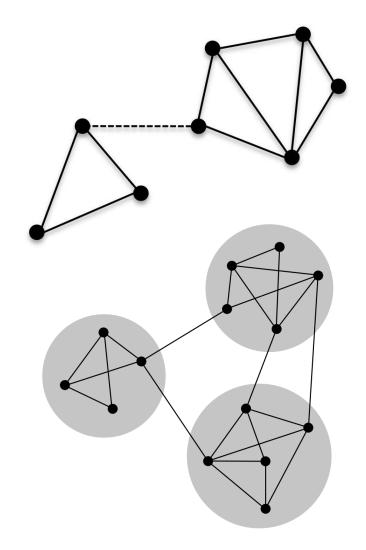
- Transport networks represented by graphs A, B, C.
- Vertices are cities.
- Edges are roads.

Which of these networks is better and why?



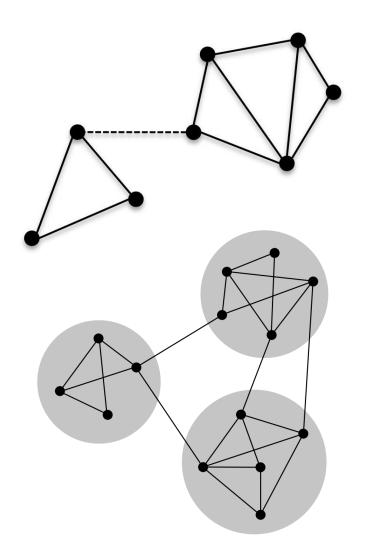
Why study connectivity in graphs?

- Connectivity serves as a basis for understanding the structure and behavior of various networks.
- Connectivity relates to a graph's ability to stay connected after removing vertices or edges.
- Disconnected graphs can hinder information/resource transmission between subgraphs.



Why study connectivity in graphs?

- Studying connectivity in graphs can help us answer questions such as:
 - How many components in the graph?
 - What is the minimum set of vertices/edges to disconnect a graph?
 - Is there a path between any two vertices in the graph?
 - How easily information / resources be transmitted through the graph?



Why study connectivity in graphs?

Network robustness

Resilience assessment.

Social network analysis

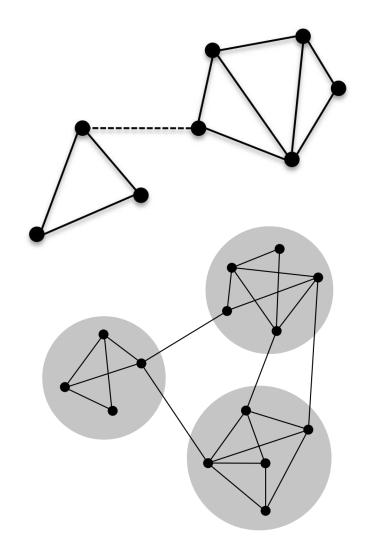
• Relationship strength evaluation.

Cluster detection

Identifying communities.

Real-world applications

 Crucial in diverse fields: biology, power grids, transport ...



Connectivity

Walk

General graph traversal without restrictions.

Trail

Walk with distinct edges.

Path

• Trail with distinct vertices $(v_0, v_1, ..., v_m)$, except possibly $v_0 = v_m$.

Closed Walk/Trail/Path:

• $v_0 = v_m$.

Cycle

Closed path with at least one edge.

Connectivity

Loop

• Cycle of length 1.

Multiple edges

• Cycle of length 2.

Triangle

Cycle of length 3.

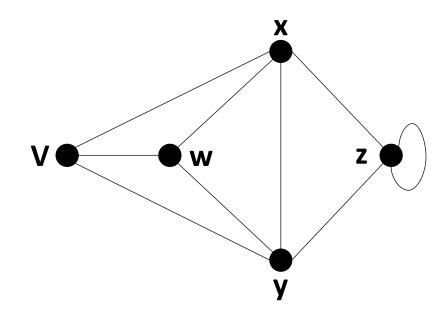
Connected Graph

• It exists a path between each pair of vertices.

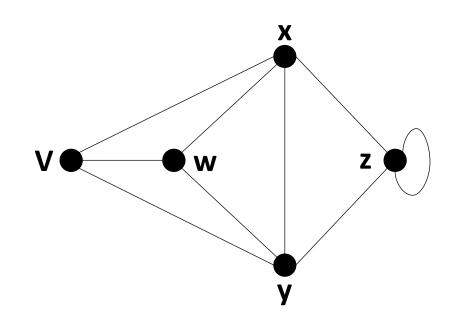
Disconnected Graph

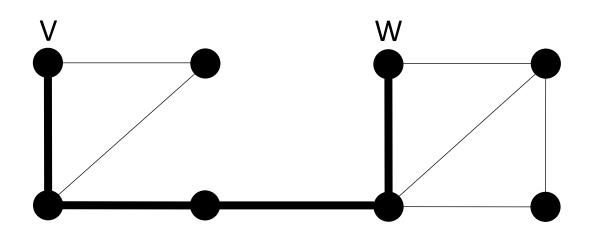
• Several disconnected subgraphs called **components**.

- $v \rightarrow w \rightarrow x \rightarrow y \rightarrow z \rightarrow z \rightarrow x$ is
- $v \rightarrow w \rightarrow x \rightarrow y \rightarrow z$ is
- $v \rightarrow w \rightarrow x \rightarrow y \rightarrow z \rightarrow x \rightarrow v$ is
- $v \rightarrow w \rightarrow x \rightarrow y \rightarrow v$ is
- $v \rightarrow w \rightarrow x \rightarrow v$ is

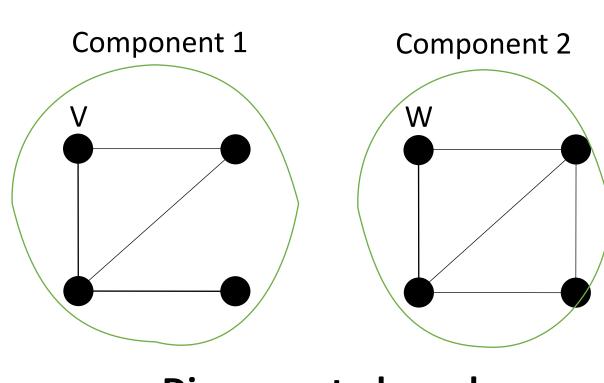


- $v \rightarrow w \rightarrow x \rightarrow y \rightarrow \underline{z} \rightarrow \underline{z} \rightarrow x$ is **Trail**
- $v \rightarrow w \rightarrow x \rightarrow y \rightarrow z$ is Path
- $v \rightarrow w \rightarrow \underline{\underline{x}} \rightarrow y \rightarrow z \rightarrow \underline{\underline{x}} \rightarrow v$ is **Closed trail**
- $v \rightarrow w \rightarrow x \rightarrow y \rightarrow v$ is Cycle (closed path)
- $v \rightarrow w \rightarrow x \rightarrow v$ is Triangle





Connected graph



Disconnected graph

Cycles and bipartite graphs

THEOREM 1

A graph G is bipartite **if and only if** every cycle of G has even length

Proof:

- The direction \rightarrow is easy, when we assume the graph is bipartite.
- The direction ← is tricky, proofing any bipartite graph should not contains cycles with odd length.

Proof of theorem 1:

If the graph is bipartite the each cycle should have even lenght

- Bipartite graphs can be split into two disjoint sets of vertices such that every edge connects a vertex from one set to another.
- If there is a cycle in a bipartite graph and we assume one vertex is in set A, then every other vertex in the cycle alternates between set A and set B.
- Since the cycle must end on a vertex in the opposite set, the length of the cycle must be even.

Proof of theorem 1:

If no even cycle exists then the graph is bipartite

- Take a vertex v
 - A: the set of vertices w for which the shortest path from v to w has even length.
 - B: the set of vertices w for which the shortest path from v to w has odd length.
- If vertices in set A (or set B) are adjacent ⇒ The shortest paths to vertex v have odd length cycle.
- Therefore, each edge of G connects a vertex in set A and a vertex in set B ⇒
 G is bipartite

Number of edges bounds

THEOREM 2

Let G be a simple graph on n vertices. If G has k components, then the number m of edges of G satisfies:

$$n-k \le m \le \frac{(n-k)(n-k+1)}{2}$$

Proof

- The intuition of the proof :
 - What is the minimum number of edges to keep k components?
 - Determine the minimum bound n-k
 - What is the maximum number of edges with k components?
 - Determine the maximum bound $\frac{(n-k)(n-k+1)}{2}$
- Proof by induction in the number of edges.

Number of edges bounds

COROLLARY 3

Any simple graph with n vertices and more than $\frac{(n-1)(n-2)}{2}$ edges is connected.

- By using this corollary, one can establish the connectivity of a graph by simply counting its edges.
- The number of edges can be readily determined from the graph's matrix representations

Edge/ Vertex Deleted Subgraphs

Let G(V, E) be a graph

- $F \subseteq E$ be a set of edges of G.
 - The graph G F is subgraph of G obtained by removing all **edges in F** from G.
 - $\bullet \ G F = (V, E F).$
- $W \subseteq V(G)$ be a set of vertices of G.
 - The graph G F is subgraph of G obtained by removing all **vertices in W** from G.
 - If a vertex is removed from a graph, its connected edges are also removed.
 - $\bullet \ G F = (V F, E').$

Removing edges and vertices

 An approach to study connected graphs is to assess the level of connectivity.

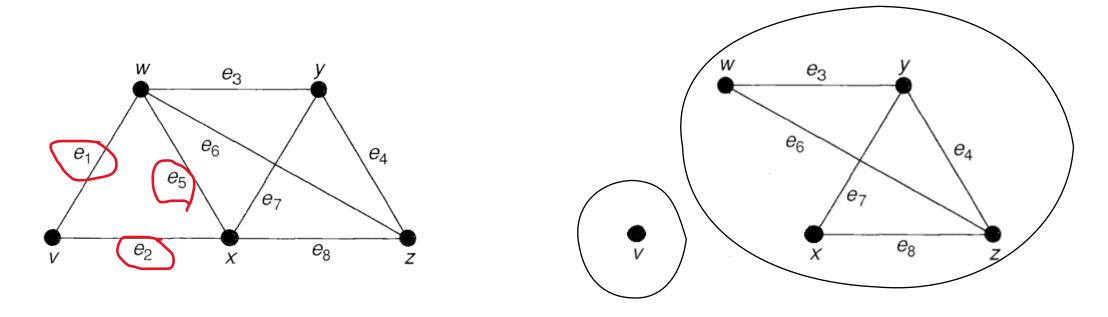
Study the vulnerability of certain networks, like transport networks.

• Determine the minimum number of **edges /vertices** that need to be out of service **for the network to become disconnected**.

Disconnecting/separating sets help in study these questions.

Removing edges: Disconnecting set

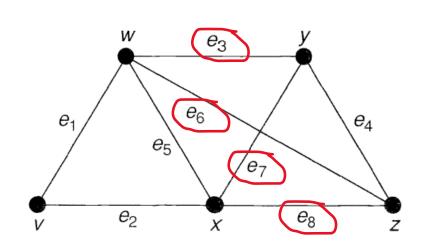
• Disconnecting set F in a connected graph G is a set of edges whose deletion disconnects G. G - F is disconnected.

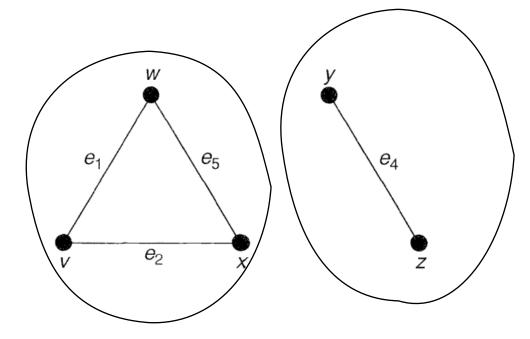


 $\{e_1, e_2, e_5\}$ is disconnecting set

Removing edges: Disconnecting set

• **Disconnecting set** in a connected graph G is a set of edges whose deletion disconnects G.

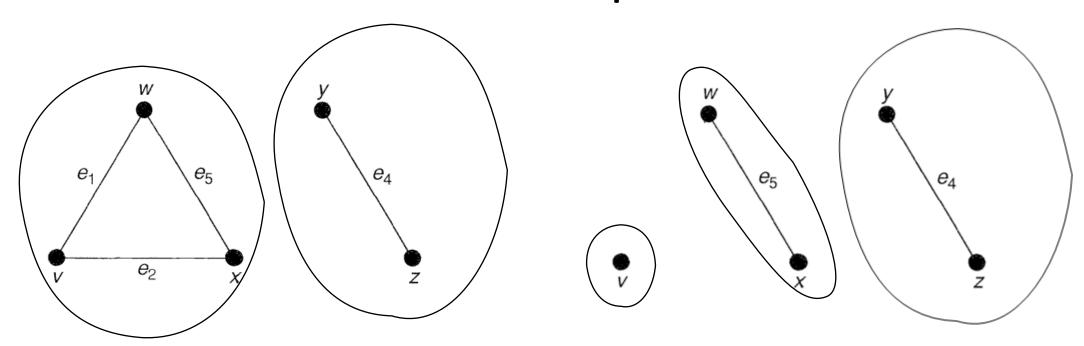




 $\{e_3, e_6, e_7, e_8\}$ is disconnecting set

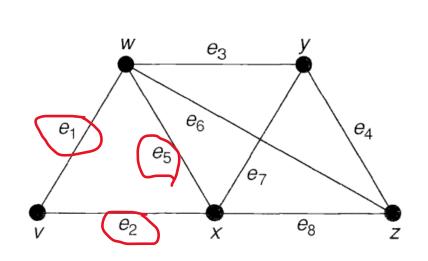
Disconnecting set in disconnected graph

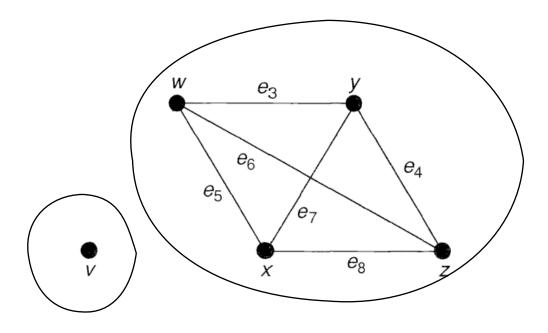
• A disconnecting set in a **disconnected graph** G is a set of edges whose deletion **increases the number of components** of G.



 $\{e_1, e_2\}$ is disconnecting set

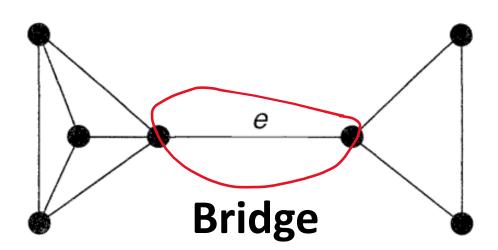
• **Cutset** is minimal disconnecting set, no proper subset of a cutset can disconnect the graph.





 $\{e_1, e_2, e_5\}$ isn't a cutest $\{e_1, e_2\}$ is a cutest

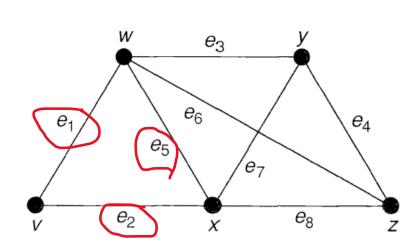
- **Cutset** is minimal disconnecting set, no proper subset of a cutset can disconnect the graph.
- If a cutset has **only one edge** *e*, we call e a **bridge**.

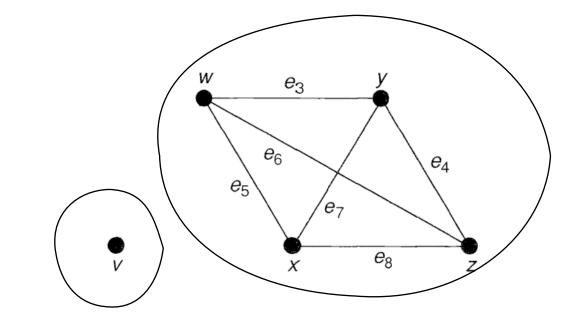


• If G is connected, its edge connectivity $\lambda(G)$ is the size of the **smallest** cutset in G.

• $\lambda(G)$ is the minimum number of edges that we need to delete in

order to disconnect G.

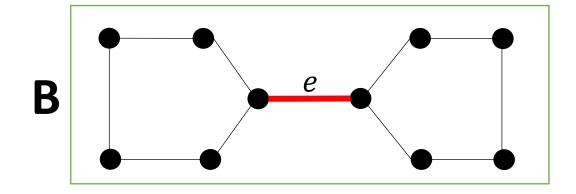




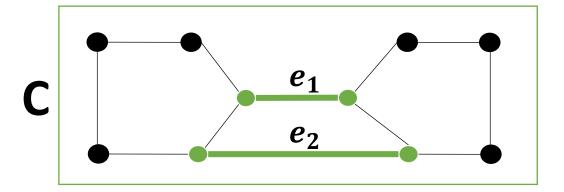
 $\{e_1, e_2\}$ is the smallest cutest

$$\lambda(G) = 2$$

- If G is connected, its edge connectivity $\lambda(G)$ is the size of the **smallest** cutset in G.
- $\lambda(G)$ is the minimum number of edges that we need to delete in order to disconnect G.

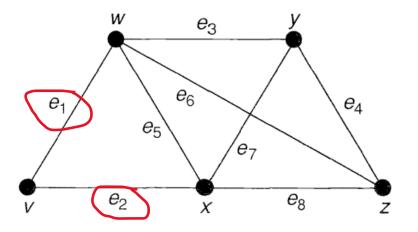


The bridge $\{e\}$ is the smallest cutest $\lambda(G) = 1$



 $\{e_1, e_2\}$ is one of the smallest cutsets $\lambda(G) = 2$

- If G is connected, its edge connectivity $\lambda(G)$ is the size of the **smallest** cutset in G.
- K-edge connected if $\lambda(G) \ge k$.



$$\lambda(G) = 2$$

G is 1-edge connected and 2-edge connected but

Examples of edge connectivity $\lambda(G)$

Graph type	$\lambda(G)$
Null graph (Trivial graph,)	
Complete graph K_n	
Path graph	
Cycle graph	
Complete bipartite graph K_{mn}	

Examples of edge connectivity $\lambda(G)$

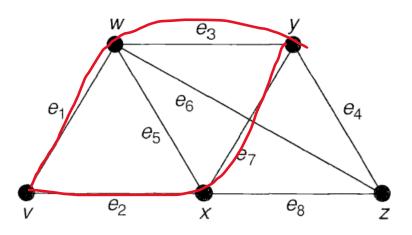
Graph type	$\lambda(G)$
Null graph (Trivial graph)	0
Complete graph K_n	n-1
Path graph	1
Cycle graph	2
Complete bipartite graph K_{mn}	$\min(m, n)$

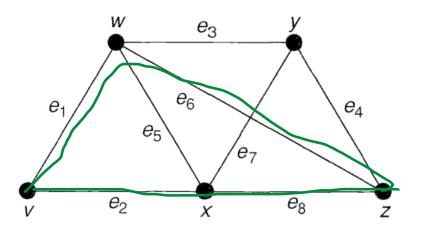
K-edge-connected: Menger's theorem

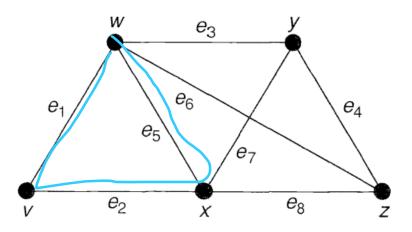
THEOREM 3

A graph G is K-edge-connected **if and if only if** any two distinct vertices are joined by at least k paths, no two of which have any edges in common.

• It can be proved that a graph is 2-edge-connected if and only if any two distinct vertices are joined by at least two paths with no edges in common.

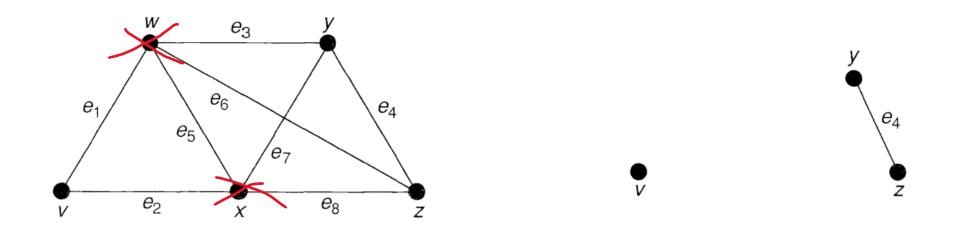






Removing vertices: Separating set

- Separating set W in a connected graph G is a set of vertices whose deletion disconnects G. G-W is disconnected.
- If a vertex is deleted, then its incident edges are also removed.



 $\{w, x\}$ isn't a separating set

Removing vertices: Separating set

- Separating set W in a connected graph G is a set of vertices whose deletion disconnects G. G-W is disconnected.
- Cut-vertex is Separating set with only one vertex



v is a cut-vertex

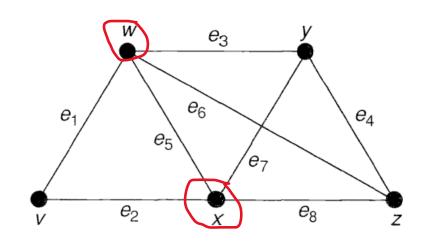
Removing vertices: Separating set

- Separating set W in a connected graph G is a set of vertices whose deletion disconnects G. G-W is disconnected.
- Cut-vertex is Separating set with only one vertex

This definition can be extended to disconnected graphs like Disconnecting edges

Separating sets and vertex connectivity

- (vertex) connectivity $\kappa(G)$ is the size of the smallest separating set in G.
- $\kappa(G)$ is the minimum number of vertices that we need to delete in order to disconnect G.
- k-connected if $\kappa(G) \ge \mathbf{k}$



$$\kappa(G) = 2$$

G is 1 connected and 2-edge connected

but not 3-edge connected

Examples of vertex connectivity $\kappa(G)$

Graph type	$\kappa(G)$
Null graph (Trivial graph)	
Complete graph K_n	
Path graph	
Cycle graph	
Complete bipartite graph K_{mn}	

Examples of vertex connectivity $\kappa(G)$

Graph type	$\kappa(G)$
Null graph (Trivial graph)	0
Complete graph K_n	n-1 (here the definition should be modified)
Path graph	1
Cycle graph	2
Complete bipartite graph K_{mn}	!!!!

K-connected: Menger's theorem

THEOREM 3

A graph G with at least k+1 is K-connected **if and if only if** any two vertices are joined by at least k paths, no two of which have any edges in common.

It can be proved that a graph with at least three vertices is 2-connected if and only if any two distinct vertices are joined by at least two paths with no edges in common (Exercise).

Edge connectivity VS vertex connectivity

$$\kappa(G) \leq \lambda(G) \leq \delta(G)$$

- The vertex connectivity is smaller than edge connectivity.
- $\delta(G)$: is the smallest vertex-degree in G.

Connectivity in digraphs

Walk

• Finite sequence of arcs without any restriction .

Trail

Walk with distinct arcs. It can contain the arcs vw and wv.

Path

• Trail with distinct vertices $(v_0, v_1, ..., v_m)$, except possibly $v_0 = v_m$.

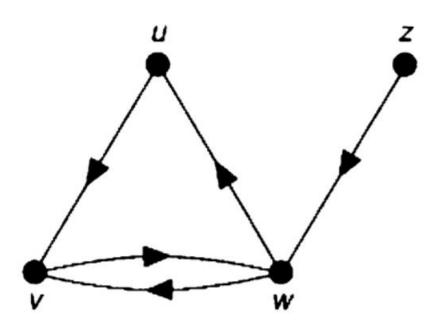
Closed Walk/Trail/Path:

• $v_0 = v_m$.

Cycle

Closed path with at least one arc.

- $z \rightarrow w \rightarrow v \rightarrow w \rightarrow u \rightarrow v \rightarrow w$ is
- $z \rightarrow w \rightarrow v \rightarrow w \rightarrow u$ is
- $z \rightarrow w \rightarrow v \rightarrow u$ is
- $w \rightarrow u \rightarrow v \rightarrow w \text{ is}$

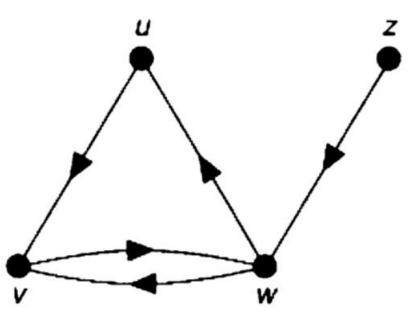


• $z \rightarrow w \rightarrow v \rightarrow w \rightarrow u \rightarrow v \rightarrow w$ is Walk.

• $z \rightarrow w \rightarrow v \rightarrow w \rightarrow u$ is **Trail**.

• $z \rightarrow w \rightarrow u \rightarrow v$ is **Path.**





Connectivity in digraphs

 Connectivity can be defined for digraphs, with two useful types corresponding to whether or not the directions of the arcs are considered.

Weak connectivity:

• A digraph D is connected if it underlying graph of D is connected.

• Strong connectivity:

 A digraph D is strongly connected if there is a directed path from any vertex to any other vertex.

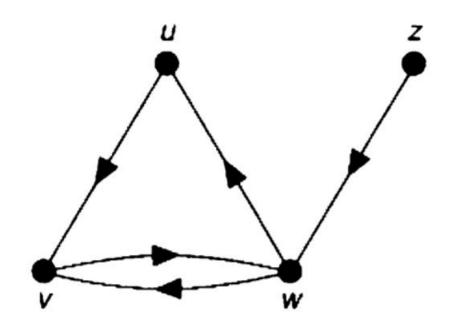
Connectivity in digraphs

- Every strongly connected digraph is connected, but not all connected digraphs are strongly connected.
- The distinction between connected and strongly connected digraphs can be illustrated with a one-way street map of a city.
- If the map is connected, we can drive from any part of the city to any other, ignoring one-way street directions.
- If it is strongly connected, we can drive from any part of the city to any other, following one-way street directions.

• This graph is **weakly connected** but not **strongly connected**.

• We can not find a path from **u** to **z**.

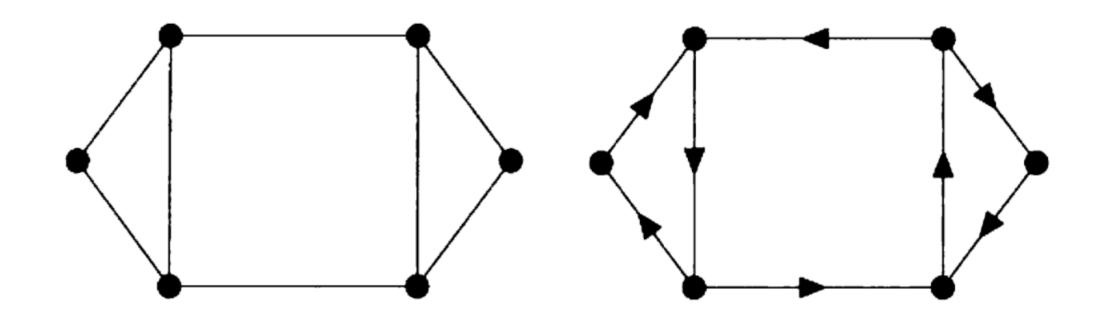
• If we add an arc from w to z, the graph becomes strongly connected.



Orientable undirected graphs

- Question:
 - Can a one-way system be implemented on an undirected graph in a way that enables driving from any part of the city to any other?
- It's not always possible
 - If a city consists of two parts connected by a single bridge.
 - If there are no bridges, then a one-way system can always be imposed.
- The presence of bridges may prevent the imposition of a one-way system, cutting off one part of the city.

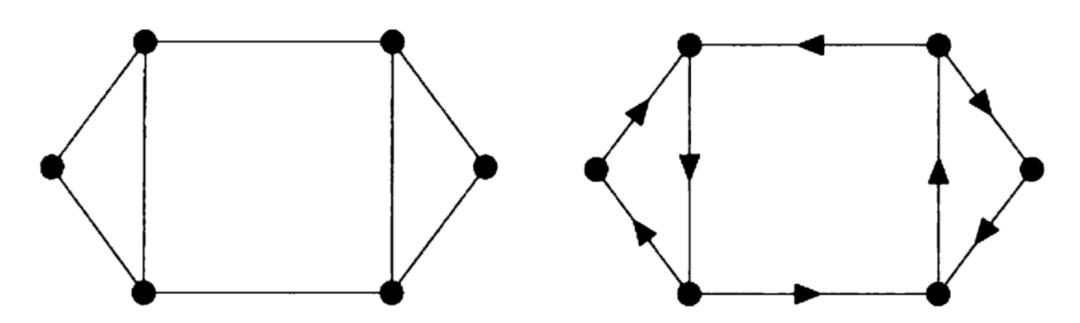
Convert this undirected graph to strongly connected directed graph



Orientable undirected graphs

THEOREM 4

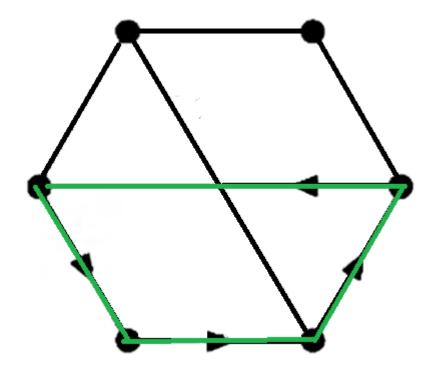
A connected G graph is orientable if and if only if each edge of G lies at least one cycle.



Proof

 The necessity of a condition is clear.

• If there is a directed path from u to v and another path from v to $u \Rightarrow$ There is a cycle in the underlying graph.

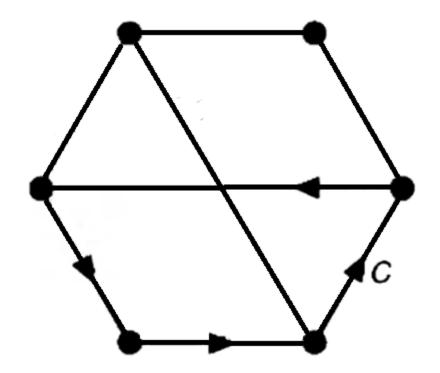


Proof

 The necessity of a condition is clear.

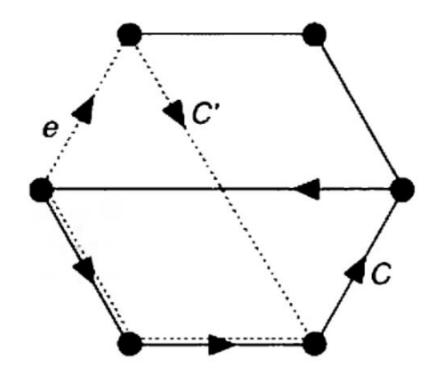
 To prove sufficiency, choose any cycle *C* and direct its edges cyclically.

• If each edge of *G* is in *C*, the proof is complete.



Proof

- If not, choose any edge e adjacent to an edge of C but not in C.
- By hypothesis, e is in some cycle C whose edges we may direct cyclically, except those already directed.
- Proceed this way, directing at least one new edge at each stage until all edges are directed
- The digraph must remain strongly connected at each stage
- Thus, the sufficiency of the condition is proved.



Reference text book

