

*COMP9332 Network Routing and Switching*  
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# *Routing for Delay Tolerant Networks (DTNs)*

# *Lecture overview*

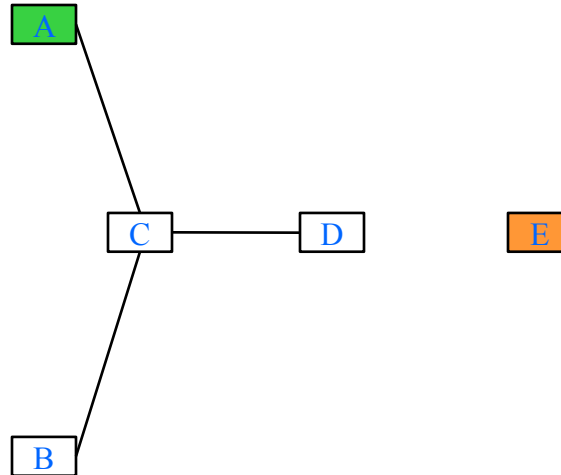
*This lecture examines the routing concepts for delivering packets even if no path exists between source and destination.*

# *Topics to be covered*

- Applications of DTN routing
- Basic DTN routing strategies
- RFC 6693

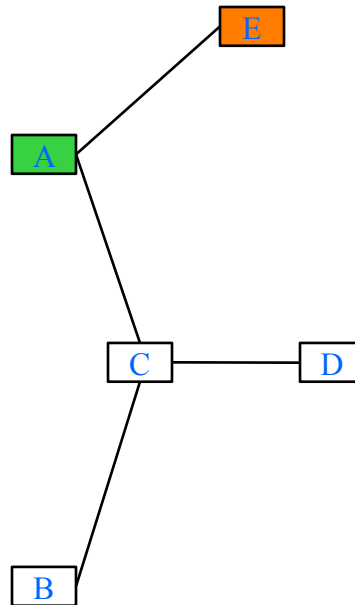
# *Connectivity at time $T_0$*

- Can A send a packet to E using traditional routing protocols?
- No, because no path exists between A and E



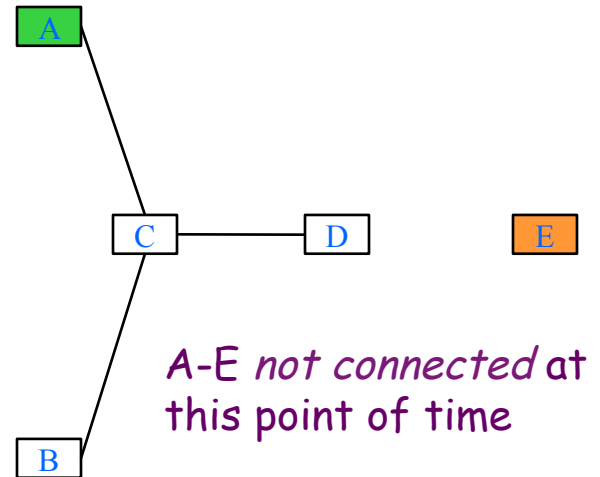
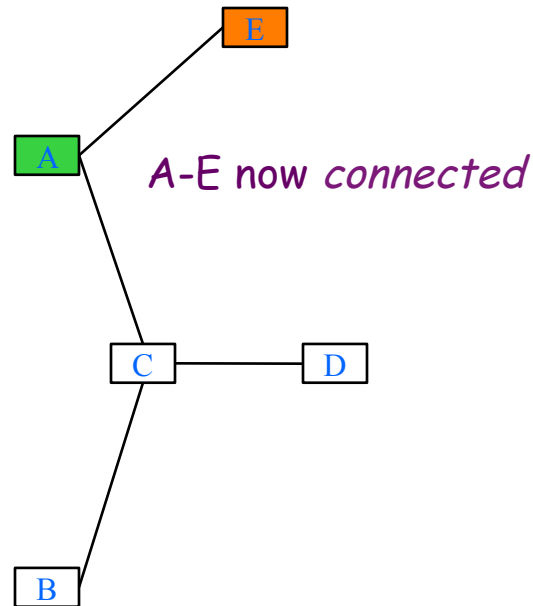
## *Connectivity at time $T1$*

- Can A send a packet to E?
- Yes, because A is directly connected to E



# What did we observe?

- Time-varying connectivity
- Just because no path exists NOW, does not mean there will be no path in the near future
- This is the motivation for DTN routing



# Contact Schedule

- For DTN routing to work, we have to have some prospect of future contacts between different nodes
- Contact schedule refers to how two nodes may come to contact in time
- Can be completely predictable or completely random and in-between



The time when two planets will come to within certain distance from each other is completely predictable

# *DTN Applications*

## ■ Off-Earth

- Inter-planetary communication
- Inter-satellite inter-space-station data transfer

## ■ On-Earth

- Internet access for remote regions
- Internet access to cars
- Data collection from sensors deployed in remote regions
- ZebraNet, and FlyingFoxNet



# *DTN Routing Strategies*

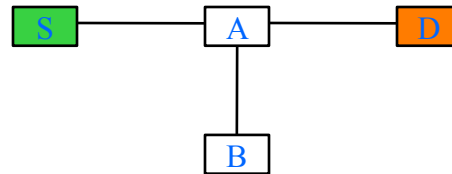
- Direct contact (Single-hop delivery)
- 2-hop relay
- Tree-based flooding
- Epidemic routing

# *Direct Contact*

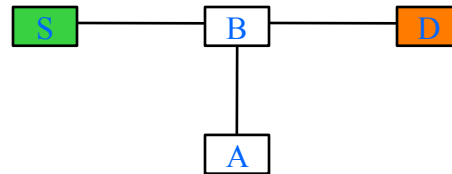
- *Source must come in contact with destination (single-hop delivery)*
- *Simplest, smallest cost*
- *Long delay*
- *Delivery probability = probability of source coming into contact with destination ( $p$ )*

# *Example of Direct Contact Delivery*

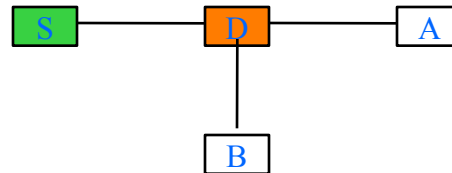
T0: Cannot deliver



T1: Cannot deliver



T2: Can deliver

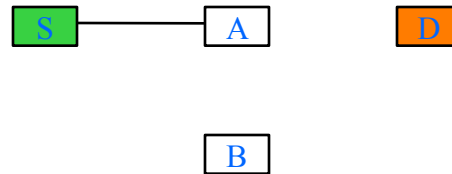


# 2-hop Relay

- Source **copies** message to  $n$  nodes it comes to contact with (none of these are destinations)
- These  $n$  nodes are called **relays** (relays are not allowed to copy the message to any other nodes except the destination)
- Source and  $n$  relays deliver the message to destination if they come in contact with the destination
- Delivery probability =  $1 - (1-p)^{n+1}$  (assuming each node contacts destination with an independent probability  $p$ )
  - Approx  $(n+1)p$  for small  $p$  (delivery prob. increases with  $n$ )

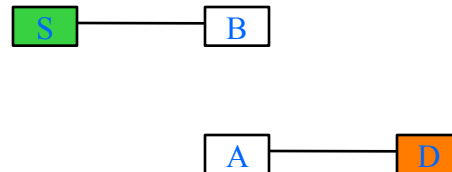
## Example of 2-hop Relay ( $n=1$ )

T0: S copies to A. Cannot yet deliver because A is not connected to D.



A works as a relay

T1: Can deliver now.

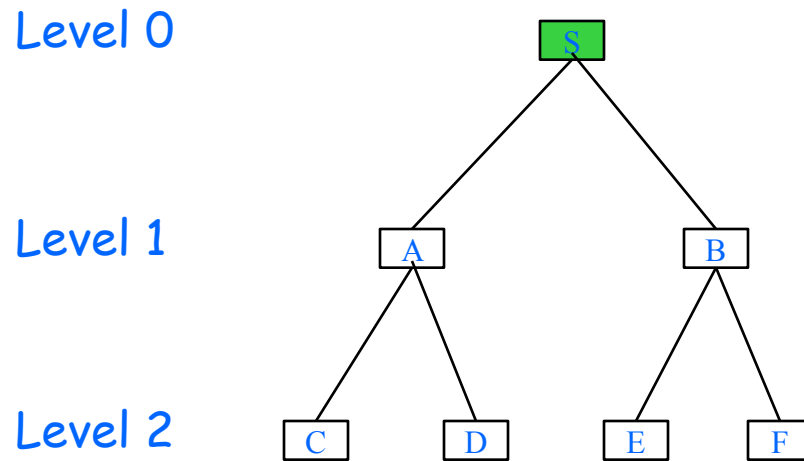


# Tree-based Flooding

- Extends 2-hop relay to  $n$ -hop ( $n > 2$ )
- Relays can copy to other relays (tree depth =  $n - 1$ )
- Both *breadth* and *depth* can be controlled
- Breadth= $m$  if each node is allowed to make a maximum of  $m$  copies
- Max copies =  $\sum_{i=0}^{n-1} m^i$

# *Example of Tree-based Flooding*

*$n=3$  (depth = 2),  $m=2$*



A to F are relays

# *Epidemic Routing*

- Replicate and synchronize when two nodes come in contact
  - Step 1: exchange only the summary vectors
  - Step 2: exchange only the messages that they do not have
  - Outcome: both nodes have identical database (synchronized)
- Eventually all nodes will receive every message!
- High message overhead, but high delivery probability, and low delay



*RFC 6693, August 2012*

# *Probabilistic Routing*

## ■ Motivation

- Epidemic routing has too much redundancy
- Contact probabilities could be learned and used to reduce redundant copies

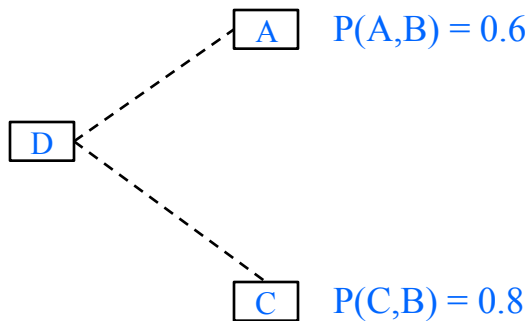
## ■ RFC 6693 - Probabilistic Routing Protocol for Intermittently Connected Networks

- released in August 2012
- Relays are selected based on their probabilities to deliver the message to the destination

# *Delivery Predictability Metric*

- It is a probability (a fraction between 0 and 1) assigned to each (relay) node
- Same node has different probabilities for different destinations
  - $P(A,B)$  is the delivery predictability for  $A$  delivering a message to  $B$
  - $P(A,C)$  is the delivery predictability for  $A$  delivering a message to  $C$
- It could be asymmetric
  - $P(A,B)$  could be different than  $P(B,A)$

# Reducing Relaying Overhead with Delivery Predictability



- If D has a message to send to B, it would select C as the relay node (message will NOT be copied to A saving overhead)

## *Delivery Predictability Vector*

- Each node maintains a delivery predictability for each destination
- If it does not have any current estimate for a given destination, it is assumed zero
- Delivery predictability to itself is 1
- Example of delivery predictability vector for node A
  - $B=0.1$ ,  $C=0.6$ ,  $D=0.7$  (currently it has estimates for three destinations, B, C, and D)

# *Delivery Predictability Exchange and Update*

- When two nodes come in contact, they first exchange their delivery predictability vectors and then update them for each other
- Nodes that often encounter each other, should have high delivery predictability for each other, and vice versa

## *Delivery Predictability Update for First Time Encounters*

- When meeting for the first time, or after a long time, the delivery predictability is set to 0.5
  - If  $P(A,B) < \text{threshold}$ ,  $P(A,B) = 0.5$
- There is an aging process, which would reduce this value (0.5) to a small value (smaller than the threshold) if not encountered for a long time.

# *Aging Delivery Predictability*

- Last encounter time is saved
- When encountering the same node next time, the time difference is used to age the delivery predictability first before exchanging it with the peer
- Aging formula ( $P'(A,B)$  is the old value of  $P(A,B)$ )
  - $P(A,B) = P'(A,B) \times \gamma^k$
  - Where  $k$  is time units passed since last encounter and  $0 < \gamma < 1$



# *Increasing Delivery Predictability with New Encounters*

$$P(A, B) = P'(A, B) + r[1 - \delta - P'(A, B)]$$

- $0 < r < 1$  is a scaling rate for increase
- Delta provides an upper bound for  $P(A, B)$  and is recommended a small value  $\delta = 0.01$
- Example (assume  $r = 0.3$  and  $(1 - \delta) = 0.99$ )
- Encounter 1:  $P(A, B) = 0.5$
- Encounter 2:  $P(A, B) = 0.5 + 0.3(0.99 - 0.5) = 0.5 + 0.147 = 0.647$
- Encounter 3:  $P(A, B) = 0.647 + 0.3(0.99 - 0.647) = 0.647 + 0.1029 = 0.7499$

## *Use of Transitivity for Updating Delivery Predictability*

- If A frequently encounters B, and B frequently encounters C, then B is a good choice for A to forward a message destined for C
- Therefore, when A meets B, A should also update  $P(A,C)$  based on what B says about  $P(B,C)$

$$P(A,C) = \max[P'(A,C), P(A,B)P(B,C)\beta]$$

$0 \leq \beta \leq 1$  is a scaling factor to control the impact of transitivity on delivery probability

# *Forwarding Strategy*

- Each nodes carries a number of messages for different destinations
- When A meets B, which messages it should forward to B
- A forwarding strategy is needed to make the forwarding decisions
- We shall examine three different forwarding strategies (taken from RFC 6693)
  - Assume that A meets B and A is making the forwarding decision

## *Forwarding Strategy 1*

- Forward the message only if  $P(B,D) > P(A,D)$ 
  - D is the destination of the message
- Note that this decision will be made for any node A encounters with
- Example: A encounters B, C, and F, where  $P(A,D)=0.5$ ,  $P(B,D)=0.6$ ,  $P(C,D)=0.4$ , and  $P(F,D)=0.45$
- Question: A will forward the message to which node(s)?

## Forwarding Strategy 2

- Forward the message only if  $P(B,D) > P(A,D)$  AND  $R < R_{\max}$ 
  - $R$  is the number of relays  $A$  has copied the message to so far
  - $R_{\max}$  is the maximum relays allowed
- Example:  $A$  encounters  $B, C, F$ , and  $G$  in order, where  $P(A,D)=0.5$ ,  $P(B,D)=0.6$ ,  $P(C,D)=0.65$ ,  $P(F,D)=0.52$ , and  $P(G,D)=0.45$  [ $R_{\max}=2$ ]
- Question:  $A$  will forward the message to which node(s)?

## *Forwarding Strategy 3*

- Forward the message only if  $P(B,D) > P(A,D)$  OR  $P(B,D) > \text{threshold}$
- This is similar to strategy 1 except the message is forwarded epidemically among nodes with very high delivery predictability (higher than a threshold)
- Example: A encounters B, C, and F, where  $P(A,D)=0.5$ ,  $P(B,D)=0.6$ ,  $P(C,D)=0.4$ , and  $P(F,D)=0.45$  [threshold=0.43]
- Question: A will forward the message to which node(s)?

# *Queuing Policy*

- A node may have to drop a message due to storage limitation
- Which message to drop?
- We need a queuing policy
- We shall examine two different queuing policies

## *First in First out (FIFO)*

- The message that was queued first will be dropped
- Simple to implement
- May not be the best strategy in terms of optimising the delivery rates
- Let us look at a slightly more complicated strategy that has a better prospect in improving delivery rate



## *Evict Most Forwarded First (MOFO)*

- The message that has been forwarded (copied to another relay node) the most number of times should be dropped first
- It would improve delivery rate, but it requires the node keep track of the number of times each message has been forwarded (one counter for each message)

# *Bibliography*

- Jones and Ward, “Routing Strategies for Delay-Tolerant Networks,” (available from course website)
- RFC 6693, August 2012