數值分析

Chapter 6 Numerical Integration

授課教師:劉耀先

國立陽明交通大學 機械工程學系 EE464

yhliu@nctu.edu.tw

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Outline

- Background (6.1)
- Rectangle and midpoint method (6.2)
- Trapezoidal method (6.3)
- Simpson's method (6.4)
- Gauss quadrature (6.5)
- Evaluation of multiple integrals (6.6)
- MATLAB built-in functions (6.7)
- Complementary topics (6.8 6.11)

6.1 Background

Calculate the length of a curve:

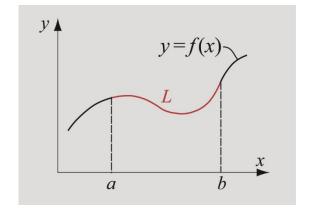
$$L = \int_a^b \sqrt{1 + \left[f'(x)\right]^2} \, dx$$

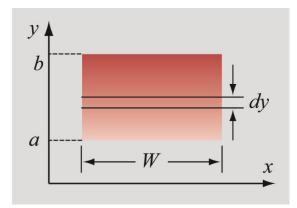
Heat flux through a rectangular cross section:

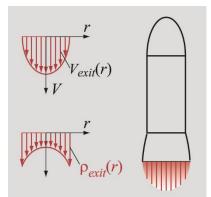
$$\dot{Q} = \int_{y=a}^{y=b} \dot{q}'' W dy$$

 Exhaust of a rocket engine thrust (T):

$$T = \int_0^R 2\pi \rho(r) V_{exit}^2(r) r dr$$

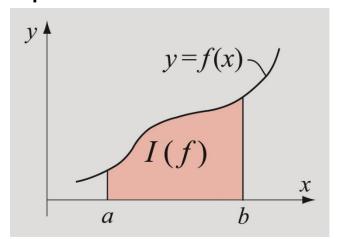




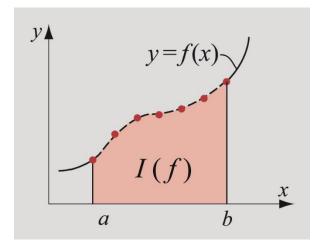


Overview of Numerical Integration

- The numerical integration is needed when
 - analytical integration is difficult or not possible
 - the integrand is given as a set of discrete points
- Calculate the integral over each subinterval and added together
- Numerical integration can also be done with discrete points



$$I_f = \int_a^b f(x) dx$$



Definition integral of f(x) between a and b

Finite number of points are used in numerical integration

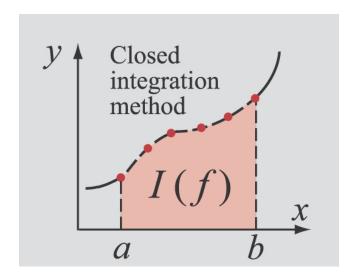
Closed and Open Method

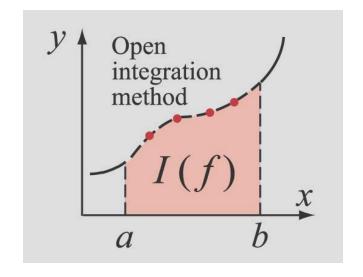
Closed method:

- the **endpoints** of the interval are used in the formula
- Trapezoidal (6.3) and Simpson's method (6.4)

Open method:

- the interval of integration extends beyond the range of the endpoints
- midpoint method (6.2) and Gauss quadrature(6.5)

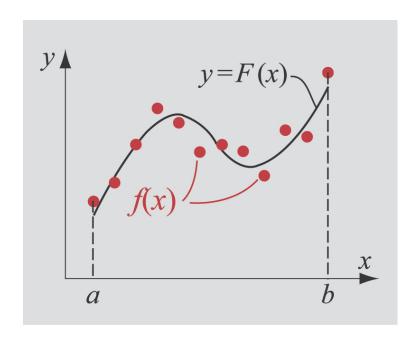




Newton-Cotes Integration Formulas

- Estimate the integrands between the discrete points using a function that can be integrated
 - For analytical function: replaced with a simpler function
 - For data points: interpolates the integrand between the points

$$I_f = \int_a^b f(x)dx \approx \int_a^b F(x)dx$$

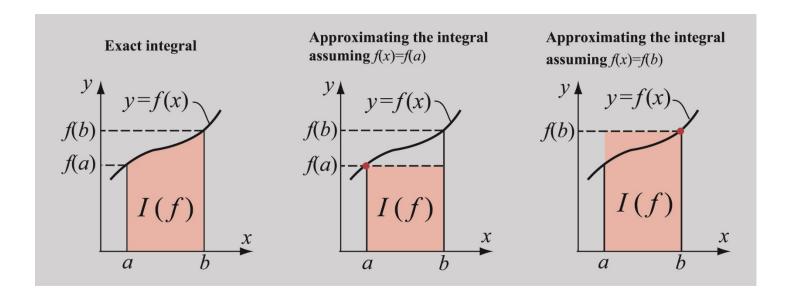


6.2 Rectangle and Midpoint Methods

 Take the value of f(x) over the interval [a,b] as a constant equal to the value of f(a) or f(b)

$$I_f = \int_a^b f(x)dx = f(a)(b-a)$$
 $I_f = \int_a^b f(x)dx = f(b)(b-a)$

- The integral is approximated by an area of a rectangle
- The error can be large



Composite Rectangle Method

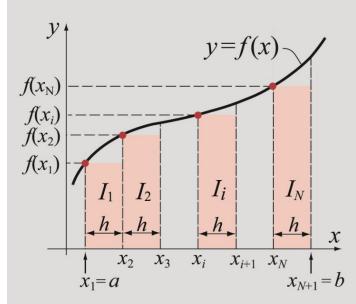
- When the analytical function is given, the error can be reduced with composite rectangle method
 - Divide the domain [a,b] into N subintervals
 - Calculate the integrand in each subinterval with rectangle method, and added together
- Smaller intervals can be used in regions where the integrand changes rapidly

$$I_f = \int_a^b f(x)dx \approx I_1 + I_2 + \dots + I_N$$

= $f(x_1)(x_2 - x_1) + f(x_2)(x_3 - x_2) + \dots$
+ $f(x_N)(x_{N+1} - x_N)$

If the intervals have the same h

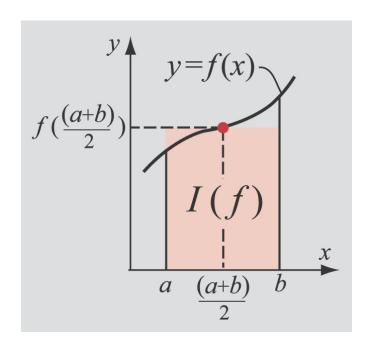
$$I_f = \int_a^b f(x)dx \approx h \sum_{i=1}^N f(x_i)$$



Midpoint Method

- An improve method over the rectangle method by using the value of the midpoint (a+b)/2
- This may still be not accurate enough
- The accuracy can be increased using a composite midpoint method

$$I_f = \int_a^b f(x)dx \approx \int_a^b f(\frac{a+b}{2})dx = f(\frac{a+b}{2})(b-a)$$



Composite Midpoint Method

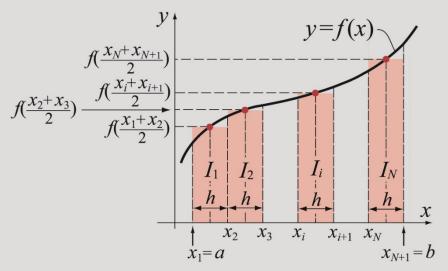
- Divide the domain [a,b] into N subintervals
- Calculate the integrand in each subinterval with midpoint method, and added together

$$I_{f} = \int_{a}^{b} f(x)dx \approx I_{1} + I_{2} + \dots + I_{N}$$

$$= f(\frac{x_{1} + x_{2}}{2})(x_{2} - x_{1}) + f(\frac{x_{2} + x_{3}}{2})(x_{3} - x_{2}) + \dots + f(\frac{x_{N} + x_{N+1}}{2})(x_{N+1} - x_{N})$$

$$\sum_{k=1}^{N} x_{k} + x_{k+1}$$

$$= h \sum_{i=1}^{N} f(\frac{x_i + x_{i+1}}{2})$$



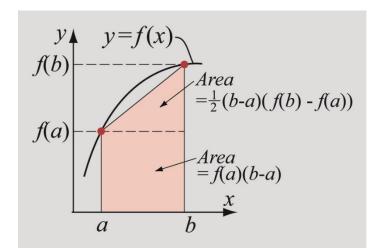
6.3 Trapezoidal Method

 A refinement over the simple rectangular and midpoint methods is to use a linear function to approximate the integrand over the interval

$$f(x) \approx f(a) + (x-a)f[a,b] = f(a) + (x-a)\frac{f(b) - f(a)}{b - a}$$

$$I_f \approx \int_a^b \left\{ f(a) + (x-a)\frac{f(b) - f(a)}{b - a} \right\} dx = f(a)(b-a) + \frac{1}{2}[f(b) - f(a)](b - a)$$

$$I_f \approx \frac{f(a) + f(b)}{2}(b - a)$$



Composite Trapezoidal Method

- Divide the domain [a,b] into N subintervals
- Calculate the integrand in each subinterval with trapezoidal method, and added together

$$I_f = \int_a^b f(x)dx \approx I_1 + I_2 + \dots + I_N = \sum_{i=1}^N \int_{x_i}^{x_{i+1}} f(x)dx$$

Using the trapezoidal method:

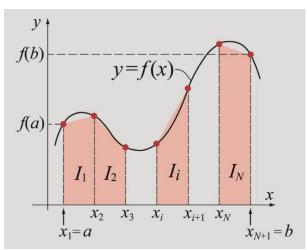
$$I_f = \int_a^b f(x)dx \approx \frac{1}{2} \sum_{i=1}^N [f(x_i) + f(x_{i+1})](x_{i+1} - x_i)$$

For the same subinterval h

$$I_{f} \approx \frac{h}{2} \sum_{i=1}^{N} [f(x_{i}) + f(x_{i+1})]$$

$$= \frac{h}{2} [f(a) + 2f(x_{2}) + 2f(x_{3}) + \dots + 2f(x_{N}) + f(b)]$$

$$= \frac{h}{2} [f(a) + f(b)] + h \sum_{i=2}^{N} f(x_{i})$$



Example 6-1

 Calculate the distance traveled by a decelerating airplane from v = 93m/s to 40 m/s:

$$mv\frac{dv}{dx} = -5v^2 - 570000$$
 m = 97,000 kg

This can be solved by the separation of variables

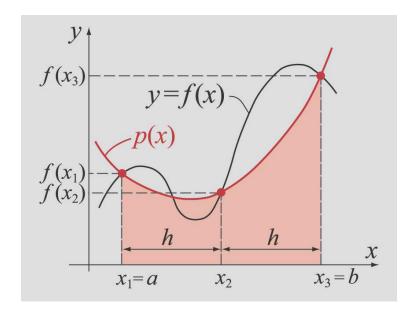
$$\frac{97000vdv}{-5v^2 - 570000} = dx$$

$$\int_0^x dx = -\int_{93}^{40} \frac{97000vdv}{5v^2 + 570000}$$

$$x = 574.1494m$$

6.4 Simpson's Method

- The trapezoidal method relies on approximating the integrand by a straight line
- A better approximation can be possibly obtained by approximating the integrand with a nonlinear function that can be easily integrated
 - Quadratic (Simpson's 1/3 method)
 - Cubic (Simpson's 3/8 method)

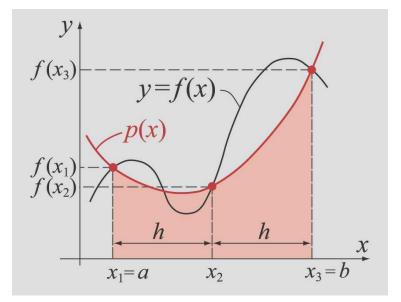


Simpson's 1/3 Method

- A quadratic (2nd order) polynomial is used to approximate the integrand
- The coefficients of a quadratic polynomial can be determined from three points x = a, x = b, and x = (a+b)/2

$$p(x) = \alpha + \beta(x - x_1) + \gamma(x - x_1)(x - x_2)$$

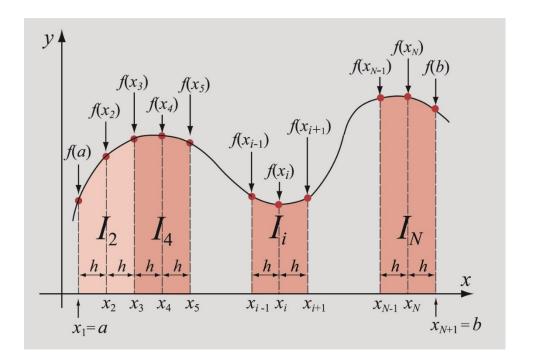
$$I = \int_{x_1}^{x_3} f(x) dx \approx \int_{x_1}^{x_3} p(x) dx = \frac{h}{3} \left[f(a) + 4f \left(\frac{a+b}{2} \right) + f(b) \right]$$



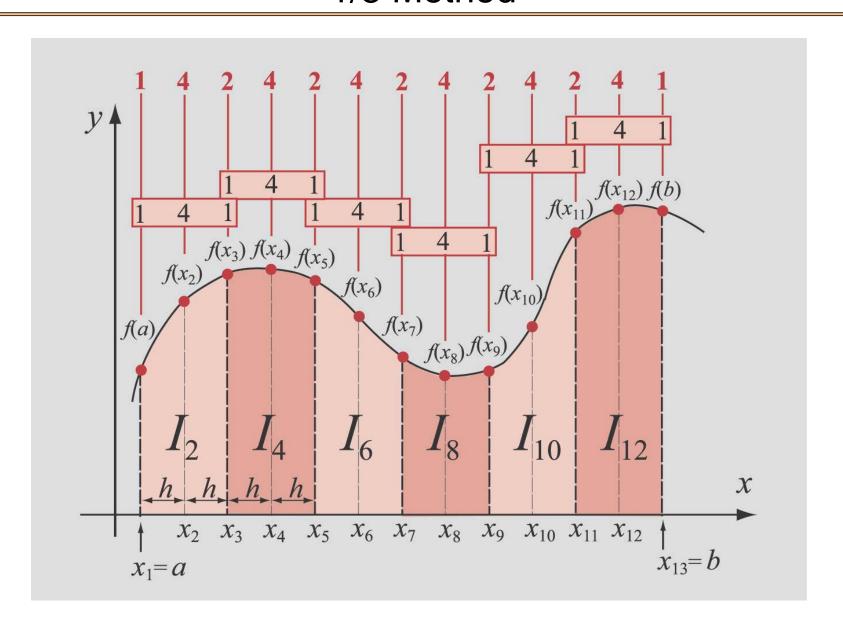
Composite Simpson's 1/3 Method

- The whole interval has to be divided into an even number of subintervals (since three points are required for each interval)
- For equally spaced interval h:

$$I = \int_{a}^{b} f(x)dx \approx \frac{h}{3} \left[f(a) + 4 \sum_{i=2,4,6}^{N} f(x_i) + 2 \sum_{j=3,5,7}^{N-1} f(x_j) + f(b) \right]$$



Weighted Addition with the Composite Simpson's 1/3 Method

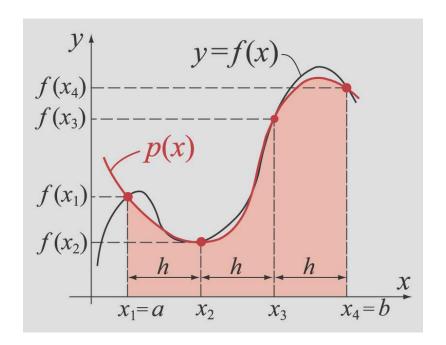


Simpson's 3/8 Method

- A cubic (3rd order) polynomial is used to approximate the integrand
- The coefficients of a quadratic polynomial can be determined from four points x₁ = a, x₂, x₃, and x₄ = b

$$p(x) = c_3 x^3 + c_2 x^2 + c_1 x + c_0$$

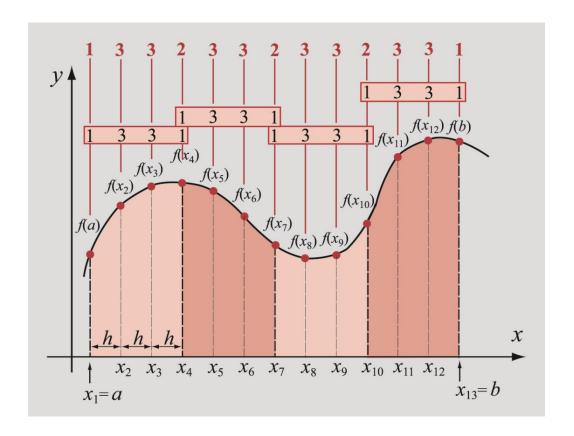
$$I = \int_{a}^{b} f(x)dx \approx \int_{x_{1}}^{x_{3}} p(x)dx = \frac{3h}{8} [f(a) + 3f(x_{2}) + 3f(x_{3}) + f(b)]$$



Composite Simpson's 3/8 Method

The number of subintervals that must be divisible by 3

$$I \approx \frac{3h}{8} \left[f(a) + 3 \sum_{i=2,5,8}^{N-1} [f(x_i) + f(x_{i+1})] + 2 \sum_{j=4,7,10}^{N-2} f(x_j) + f(b) \right]$$



6.5 Gauss Quadrature

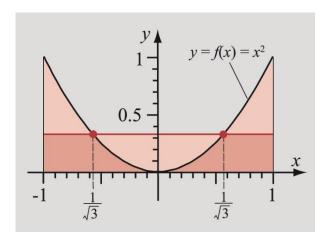
- The integral is also evaluated by using weighted addition of the values of f(x) at different points (Gauss points) within [a,b]
- The Gauss points are **not** equally spaced and do **not** include the end points
- General form:

$$\int_{a}^{b} f(x)dx \approx \sum_{i=1}^{n} C_{i}f(x_{i})$$

$$C_{i}: weights$$

$$x_{i}: points$$

 The value of the coefficients (C_i) and the location of points x_i depend on the values of n, a, and b



Gauss Quadrature

• For n = 2 and the domain [-1,1], f(x) = 1, x, x^2 , x^3 ,...

$$\int_{-1}^{1} f(x)dx \approx C_1 f(x_1) + C_2 f(x_2)$$

There are four cases:

$$f(x) = 1$$

$$\int_{-1}^{1} (1)dx = 2 = C_1 + C_2$$

$$f(x) = x$$

$$\int_{-1}^{1} x dx = 0 = C_1 x_1 + C_2 x_2$$

$$f(x) = x^2$$

$$\int_{-1}^{1} x^2 dx = \frac{2}{3} = C_1 x_1^2 + C_2 x_2^2$$

$$f(x) = x^3$$

$$\int_{-1}^{1} x^3 dx = 0 = C_1 x_1^3 + C_2 x_2^3$$

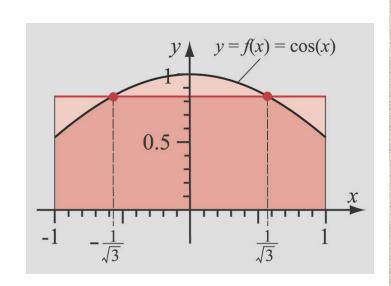
- Solve to get: $C_1 = 1$ $C_2 = 1$ $x_1 = -\frac{1}{\sqrt{3}}$ $x_2 = \frac{1}{\sqrt{3}}$
- For n=2, $\int_{-1}^{1} f(x)dx \approx f(-\frac{1}{\sqrt{3}}) + f(\frac{1}{\sqrt{3}})$

Gauss Quadrature

- Then f(x) is a function that is different from f(x) = 1, x, x^2 , x^3 , or any linear combination of these, Gauss quadrature gives an **approximate** value for the integral
- The accuracy of Gauss quadrature can be increased by using a higher value for n (Table 6-1)
- The interval can have any domain [a,b] by using a transformation

$$\int_{a}^{b} f(x)dx = \int_{-1}^{1} f(t)dt$$

$$\int_{a}^{b} f(x)dx = \int_{-1}^{1} f(\frac{(b-a)t+a+b}{2})(\frac{b-a}{2})dt$$



Example 6.2

Evaluate the following equations using four-pint Gauss quadrature

$$\int_0^3 e^{-x^2} dx$$

• Transform the equation into: $\int_{-1}^{1} f(t)dt$

$$x = \frac{1}{2}[t(b-a) + a + b] = \frac{1}{2}[t(3-0) + 0 + 3] = \frac{3}{2}(t+1)$$

$$dx = \frac{1}{2}(b-a)dt = \frac{1}{2}(3-1)dt = \frac{3}{2}dt$$

Therefore

$$I = \int_0^3 e^{-x^2} dx = \int_{-1}^1 f(t) dt = \int_{-1}^1 \frac{3}{2} e^{-\left[\frac{3}{2}(t+1)\right]^2} dt$$

$$I = \int_{-1}^{1} f(t)dt \approx C_1 f(t_1) + C_2 f(t_2) + C_3 f(t_3) + C_4 f(t_4)$$

6.6 Evaluation of Multiple Integrals

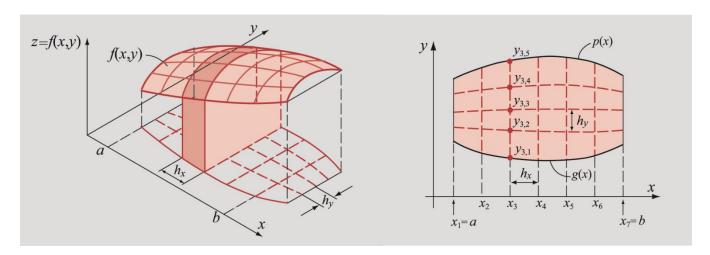
The double integration can be separated into two parts:

$$G(x) = \int_{y=g(x)}^{y=p(x)} f(x, y) dy \qquad I = \int_{a}^{b} G(x) dx$$

 The outer integral can be evaluated (ex. 1/3 Simpson's method):

$$I(G) \approx \frac{h_x}{3} \left\{ G(a) + 4 \left[G(x_2) + G(x_4) + G(x_6) \right] + 2 \left[G(x_3) + G(x_5) \right] + G(b) \right\}$$

$$h_x = (b - a)/6$$



6.7 MATLAB Built-inFunctions

- Command quad:
 - I = quad(function,a,b)
- Command quadl:
 - I = quadl(function,a,b)
- Command trapz:
 - q = trapz(x,y)
- Command dblquad:
 - I=dblquad(function,xmin,xmax,ymin,ymax)

6.8 Estimation of Error

As an example from the rectangle method, the error E is:

$$E = \int_a^b f(x)dx - f(a)(b-a)$$

Using one-term Taylor series expansion

$$f(x) = f(a) + f'(\xi)(x - a)$$

Using this in the calculation:

$$E = \int_{a}^{b} f(x)dx - f(a)(b - a) = \frac{1}{2}f'(\xi)(b - a)^{2}$$

 The error can be reduced with the composite method and when the small subinterval is used

Estimation of Error

For the case where h is the same:

$$E = \frac{1}{2}h^2 \sum_{i=1}^{N} f'(\xi_i)$$
 and the average value of the derivative
$$\overline{f'} \approx \frac{\sum_{i=1}^{N} f'(\xi_i)}{N}$$

• Since h = (b-a)/N, the above equation can be reduced to:

$$E = \frac{b-a}{2}h\overline{f'} = O(h)$$

The error in the other methods can also be estimated:

Composite midpoint method:
$$E = \frac{b-a}{24}h^2\overline{f''} = O(h^2)$$

Composite trapezoidal method:
$$E = -\frac{b-a}{12}h^2\overline{f''} = O(h^2)$$

Composite Simpson's 1/3 method:
$$E = -\frac{b-a}{180}h^4\overline{f'''} = O(h^4)$$

Composite Simpson's 3/8 method:
$$E = -\frac{b-a}{80}h^4\overline{f'''} = O(h^4)$$

6.9 Richardson's Extrapolation

- Obtain a more accurate estimate of an integral from two less accurate estimates
- If the integral I(f) with the error O(h²)is written as:

$$I(f) = I(f)_h + Ch^2 + Dh^4 + \dots$$

Two estimated using different intervals:

$$I(f) = I(f)_{h1} + Ch_1^2$$
 $I(f) = I(f)_{h2} + Ch_2^2$

• The I(f) can be solved with the error O(h⁴):

$$I(f) = \frac{I(f)_{h_1} - \left(\frac{h_1}{h_2}\right)^2 I(f)_{h_2}}{1 - \left(\frac{h_1}{h_2}\right)^2}$$

Richardson's Extrapolation

 Similarly, two estimates with error O(h⁴) can be used to calculate the estimate with the error O(h⁶):

$$I(f) = \frac{I(f)_{h1} - \left(\frac{h_1}{h_2}\right)^4 I(f)_{h_2}}{1 - \left(\frac{h_1}{h_2}\right)^4}$$

The Richardson's general extrapolation formula:

$$I = \frac{2^p I_{2n} - I_n}{2^p - 1}$$

- where
 - I_n is an estimate using n subintervals with error order h^p
 - I_{2n} is an estimate using 2n subintervals with error order h^p
 - The new estimate of the integral has the error order h^(p+2)

6.10 Romberg Integration

 Improving the accuracy by successive application of Richardson's extrapolation formula

