

# Fast Edge-Preserving PatchMatch for Large Displacement Optical Flow

## Supplementary Material

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This document contains supplementary material for the paper “Fast Edge-Preserving Patch-Match for Large Displacement Optical Flow” to be appeared in CVPR 2014. The list of items included here are:

1. Screenshot of MPI Sintel benchmark.
2. Screenshot of KITTI benchmark.
3. Screenshot of Middlebury benchmark.
4. More results on MPI Sintel benchmark.
5. More results on KITTI benchmark.

Besides, a **binary executable demo** for Windows operating systems is provided together with this document (in order to run the program, you should have a CUDA-enabled NVIDIA GPU).

Final Clean

	EPE all	EPE matched	EPE unmatched	d0-10	d10-60	d60-140	s0-10	s10-40	s40+	
GroundTruth [1]	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	<a href="#">Visualize Results</a>
DeepFlow [2]	5.377	1.771	34.751	4.519	1.534	0.837	0.960	2.730	33.701	<a href="#">Visualize Results</a>
IVANN [3]	5.386	1.397	37.896	2.722	1.341	1.004	0.683	2.245	36.342	<a href="#">Visualize Results</a>
MDP-Flow2 [4]	5.837	1.869	38.158	3.210	1.913	1.441	0.640	2.603	39.459	<a href="#">Visualize Results</a>
EPPM [5]	6.494	2.675	37.632	4.997	2.422	1.948	1.402	3.446	39.152	<a href="#">Visualize Results</a>
S2D-Matching [6]	6.510	2.792	36.785	5.523	3.018	1.546	0.622	3.012	44.187	<a href="#">Visualize Results</a>
Classic+NLP [7]	6.731	2.949	37.545	5.573	3.291	1.648	0.638	3.296	45.290	<a href="#">Visualize Results</a>
FC-2Layers-FF [8]	6.781	3.053	37.144	5.841	3.390	1.688	0.580	3.308	45.962	<a href="#">Visualize Results</a>
LDOF [9]	7.563	3.432	41.170	5.353	3.284	2.454	0.936	2.908	51.696	<a href="#">Visualize Results</a>
Classic+NL [10]	7.961	3.770	42.079	6.191	3.911	2.509	0.573	2.694	57.374	<a href="#">Visualize Results</a>
Classic++ [11]	8.721	4.259	45.047	6.983	4.494	2.753	0.902	3.295	60.645	<a href="#">Visualize Results</a>
Horn+Schunck [12]	8.739	4.525	43.032	7.542	5.045	2.891	1.141	3.860	58.243	<a href="#">Visualize Results</a>
Classic+NL-fast [13]	9.129	4.725	44.956	7.157	4.974	3.331	0.558	2.812	66.935	<a href="#">Visualize Results</a>
SimpleFlow [14]	12.617	7.848	51.435	10.693	8.422	6.170	0.711	8.411	81.786	<a href="#">Visualize Results</a>
AnisoHuber.L1 [15]	12.642	7.983	50.472	10.457	8.675	6.320	0.753	9.976	77.835	<a href="#">Visualize Results</a>
AtrousFlow [16]	14.200	9.584	51.758	11.964	10.338	7.926	1.702	12.440	80.185	<a href="#">Visualize Results</a>

Final Clean

	EPE all	EPE matched	EPE unmatched	d0-10	d10-60	d60-140	s0-10	s10-40	s40+	
GroundTruth [1]	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	<a href="#">Visualize Results</a>
DeepFlow [2]	5.377	1.771	34.751	4.519	1.534	0.837	0.960	2.730	33.701	<a href="#">Visualize Results</a>
IVANN [3]	5.386	1.397	37.896	2.722	1.341	1.004	0.683	2.245	36.342	<a href="#">Visualize Results</a>
EPPM [4]	6.494	2.675	37.632	4.997	2.422	1.948	1.402	3.446	39.152	<a href="#">Visualize Results</a>
MDP-Flow2 [5]	5.837	1.869	38.158	3.210	1.913	1.441	0.640	2.603	39.459	<a href="#">Visualize Results</a>
S2D-Matching [6]	6.510	2.792	36.785	5.523	3.018	1.546	0.622	3.012	44.187	<a href="#">Visualize Results</a>
Classic+NLP [7]	6.731	2.949	37.545	5.573	3.291	1.648	0.638	3.296	45.290	<a href="#">Visualize Results</a>
FC-2Layers-FF [8]	6.781	3.053	37.144	5.841	3.390	1.688	0.580	3.308	45.962	<a href="#">Visualize Results</a>
LDOF [9]	7.563	3.432	41.170	5.353	3.284	2.454	0.936	2.908	51.696	<a href="#">Visualize Results</a>
Classic+NL [10]	7.961	3.770	42.079	6.191	3.911	2.509	0.573	2.694	57.374	<a href="#">Visualize Results</a>
Horn+Schunck [11]	8.739	4.525	43.032	7.542	5.045	2.891	1.141	3.860	58.243	<a href="#">Visualize Results</a>
Classic++ [12]	8.721	4.259	45.047	6.983	4.494	2.753	0.902	3.295	60.645	<a href="#">Visualize Results</a>
Classic+NL-fast [13]	9.129	4.725	44.956	7.157	4.974	3.331	0.558	2.812	66.935	<a href="#">Visualize Results</a>
AnisoHuber.L1 [14]	12.642	7.983	50.472	10.457	8.675	6.320	0.753	9.976	77.835	<a href="#">Visualize Results</a>
AtrousFlow [15]	14.200	9.584	51.758	11.964	10.338	7.926	1.702	12.440	80.185	<a href="#">Visualize Results</a>
SimpleFlow [16]	12.617	7.848	51.435	10.693	8.422	6.170	0.711	8.411	81.786	<a href="#">Visualize Results</a>

Figure 1: Average endpoint error (EPE) ranking on MPI Sintel benchmark – clean pass (captured on Oct 30th, 2013). The second figure is the ranking by only considering large displacement motions (flow velocity larger than 40 pixels per frame)

[Final](#) [Clean](#)

	EPE all	EPE matched	EPE unmatched	d0-10	d10-60	d60-140	s0-10	s10-40	s40+	
GroundTruth [1]	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	<a href="#">Visualize Results</a>
DeepFlow [2]	7.212	3.336	38.781	5.650	3.144	2.208	1.284	4.107	44.118	<a href="#">Visualize Results</a>
IVANN [3]	7.249	2.973	42.088	4.896	2.817	2.218	1.159	4.183	44.866	<a href="#">Visualize Results</a>
S2D-Matching [4]	7.872	3.918	40.093	5.975	3.815	2.851	1.172	4.695	48.782	<a href="#">Visualize Results</a>
FC-2Layers-FF [5]	8.137	4.261	39.723	6.537	4.257	2.946	1.034	4.835	51.349	<a href="#">Visualize Results</a>
Classic+NLP [6]	8.291	4.287	40.925	6.520	4.265	2.984	1.208	5.090	51.162	<a href="#">Visualize Results</a>
<b>EPPM [7]</b>	<b>8.377</b>	<b>4.286</b>	<b>41.695</b>	<b>6.556</b>	<b>4.024</b>	<b>3.323</b>	<b>1.834</b>	<b>4.955</b>	<b>49.083</b>	<a href="#">Visualize Results</a>
MDP-Flow2 [8]	8.445	4.150	43.430	5.703	3.925	3.406	1.420	5.449	50.507	<a href="#">Visualize Results</a>
LDOF [9]	9.116	5.037	42.344	6.849	4.928	4.003	1.485	4.839	57.296	<a href="#">Visualize Results</a>
Classic+NL [10]	9.153	4.814	44.509	7.215	4.822	3.427	1.113	4.496	60.291	<a href="#">Visualize Results</a>
Horn+Schunck [11]	9.610	5.419	43.734	7.950	5.658	3.976	1.882	5.335	58.274	<a href="#">Visualize Results</a>
Classic++ [12]	9.959	5.410	47.000	8.072	5.554	3.750	1.403	5.098	64.135	<a href="#">Visualize Results</a>
Classic+NL-fast [13]	10.088	5.659	46.145	8.010	5.738	4.160	1.092	4.666	67.801	<a href="#">Visualize Results</a>
AnisoHuber.L1 [14]	11.927	7.323	49.366	9.464	7.692	5.929	1.155	7.966	74.796	<a href="#">Visualize Results</a>
SimpleFlow [15]	13.364	8.620	51.949	10.872	8.884	7.171	1.475	9.582	81.350	<a href="#">Visualize Results</a>
AtrousFlow [16]	14.173	9.573	51.548	11.511	10.027	8.092	2.011	12.052	79.484	<a href="#">Visualize Results</a>

[Final](#) [Clean](#)

	EPE all	EPE matched	EPE unmatched	d0-10	d10-60	d60-140	s0-10	s10-40	s40+	
GroundTruth [1]	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	<a href="#">Visualize Results</a>
DeepFlow [2]	7.212	3.336	38.781	5.650	3.144	2.208	1.284	4.107	44.118	<a href="#">Visualize Results</a>
IVANN [3]	7.249	2.973	42.088	4.896	2.817	2.218	1.159	4.183	44.866	<a href="#">Visualize Results</a>
S2D-Matching [4]	7.872	3.918	40.093	5.975	3.815	2.851	1.172	4.695	48.782	<a href="#">Visualize Results</a>
<b>EPPM [5]</b>	<b>8.377</b>	<b>4.286</b>	<b>41.695</b>	<b>6.556</b>	<b>4.024</b>	<b>3.323</b>	<b>1.834</b>	<b>4.955</b>	<b>49.083</b>	<a href="#">Visualize Results</a>
MDP-Flow2 [6]	8.445	4.150	43.430	5.703	3.925	3.406	1.420	5.449	50.507	<a href="#">Visualize Results</a>
Classic+NLP [7]	8.291	4.287	40.925	6.520	4.265	2.984	1.208	5.090	51.162	<a href="#">Visualize Results</a>
FC-2Layers-FF [8]	8.137	4.261	39.723	6.537	4.257	2.946	1.034	4.835	51.349	<a href="#">Visualize Results</a>
LDOF [9]	9.116	5.037	42.344	6.849	4.928	4.003	1.485	4.839	57.296	<a href="#">Visualize Results</a>
Horn+Schunck [10]	9.610	5.419	43.734	7.950	5.658	3.976	1.882	5.335	58.274	<a href="#">Visualize Results</a>
Classic+NL [11]	9.153	4.814	44.509	7.215	4.822	3.427	1.113	4.496	60.291	<a href="#">Visualize Results</a>
Classic++ [12]	9.959	5.410	47.000	8.072	5.554	3.750	1.403	5.098	64.135	<a href="#">Visualize Results</a>
Classic+NL-fast [13]	10.088	5.659	46.145	8.010	5.738	4.160	1.092	4.666	67.801	<a href="#">Visualize Results</a>
AnisoHuber.L1 [14]	11.927	7.323	49.366	9.464	7.692	5.929	1.155	7.966	74.796	<a href="#">Visualize Results</a>
AtrousFlow [15]	14.173	9.573	51.548	11.511	10.027	8.092	2.011	12.052	79.484	<a href="#">Visualize Results</a>
SimpleFlow [16]	13.364	8.620	51.949	10.872	8.884	7.171	1.475	9.582	81.350	<a href="#">Visualize Results</a>

Figure 2: Average endpoint error (EPE) ranking on MPI Sintel benchmark – final pass (captured on Oct 30th, 2013). The second figure is the ranking by only considering large displacement motions (flow velocity larger than 40 pixels per frame).

Error threshold 5 pixels Evaluation area All pixels

## Optical Flow Evaluation

This table ranks general optical flow methods, performing a full 2D search, as compared to the motion stereo methods below.

Rank	Method	Setting	Code	Out-Noc	Out-All	Avg-Noc	Avg-All	Density	Runtime	Environment	Compare
1	SceneFlow	ms	code	1.83 %	3.59 %	0.8 px	1.3 px	100.00 %	6 min	4 cores @ 3.0 Ghz (Matlab + C/C++)	<input type="checkbox"/>
Anonymous submission											
2	PR-SfE	ms	code	2.34 %	4.79 %	0.9 px	1.7 px	100.00 %	200 s	4 cores @ 3.0 Ghz (Matlab + C/C++)	<input type="checkbox"/>
C. Vogel, S. Roth and K. Schindler: <i>Piecewise Rigid Scene Flow</i> , International Conference on Computer Vision (ICCV) 2013.											
3	PCBP-Flow	ms	code	2.58 %	6.26 %	0.9 px	2.2 px	100.00 %	3 min	4 cores @ 2.5 Ghz (Matlab + C/C++)	<input type="checkbox"/>
K. Yamaguchi, D. McAllester and R. Urtasun: <i>Robust Monocular Epipolar Flow Estimation</i> , CVPR 2013.											
4	PR-Sceneflow	ms	code	2.65 %	1.2 px	1.0 px	2.0 px	100.00 %	150 sec	4 core @ 3.0 Ghz (Matlab + C/C++)	<input type="checkbox"/>
C. Vogel, S. Roth and K. Schindler: <i>Piecewise Rigid Scene Flow</i> , International Conference on Computer Vision (ICCV) 2013.											
5	MotionSLIC	ms	code	2.74 %	8.12 %	1.0 px	2.7 px	100.00 %	11 s	1 core @ 3.0 Ghz (C/C++)	<input type="checkbox"/>
K. Yamaguchi, D. McAllester and R. Urtasun: <i>Robust Monocular Epipolar Flow Estimation</i> , CVPR 2013.											
6	gtRF-DF	ms	code	4.52 %	10.45 %	1.6 px	4.3 px	100.00 %	1 min	1 core @ 2.5 Ghz (Matlab + C/C++)	<input type="checkbox"/>
Anonymous submission											
7	TGV2ADCSIFT	ms	code	4.71 %	12.19 %	1.6 px	4.5 px	100.00 %	12s	GPU @ 2.4 Ghz (C/C++)	<input type="checkbox"/>
8	TVL1-HOG	ms	code	5.37 %	15.54 %	2.0 px	6.1 px	100.00 %	180 s	2 cores @ 3.0 Ghz (Matlab)	<input type="checkbox"/>
H. Rashwan, M. Mohamed, M. Garcia, B. Mertsching and D. Polle: <i>Illumination Robust Optical Flow Model Based on Histogram of Oriented Gradients</i> , German Conference on Pattern Recognition 2013 .											
9	DeepFlow	ms	code	5.38 %	14.70 %	1.5 px	5.8 px	100.00 %	17 s	1 core @ 3.6GHz (Python + C/C++)	<input type="checkbox"/>
P. Weinzaepfel, J. Renaud, Z. Harachou and C. Schmidt: <i>DeepFlow: Large displacement optical flow with deep matching</i> , IEEE International Conference on Computer Vision (ICCV) 2013.											
10	Data-Flow	ms	code	5.44 %	11.77 %	1.9 px	5.5 px	100.00 %	3 min	2 cores @ 2.5 Ghz (Matlab + C/C++)	<input type="checkbox"/>
C. Vogel, S. Roth and K. Schindler: <i>An Evaluation of Data Costs for Optical Flow</i> , German Conference on Pattern Recognition (GCPR) 2013.											
11	DescFlow	ms	code	6.26 %	15.59 %	2.1 px	5.7 px	100.00 %	9.0 s	GPU @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
Anonymous submission											
12	MLDP-OF	ms	code	6.87 %	15.91 %	2.5 px	6.7 px	100.00 %	160 s	2 cores @ 2.5 Ghz (Matlab)	<input type="checkbox"/>
Anonymous submission											
13	CRTflow	ms	code	6.90 %	15.02 %	2.7 px	6.5 px	100.00 %	18 s	GPU @ 1.0 Ghz (C/C++)	<input type="checkbox"/>
O. Denenz, D. Harfew and J. Weickert: <i>The Complete Rank Transform: A Tool for Accurate and Morphologically Invariant Matching of Structure</i> , Proc. - British Machine Vision Conference 2013 (BMVC) 2013.											
14	C++	ms	code	8.04 %	17.14 %	2.6 px	7.1 px	100.00 %	8.5 min	1 core @ 3.0 Ghz (Matlab)	<input type="checkbox"/>
D. Sun, S. Roth and M. Back: <i>A Quantitative Analysis of Current Practices in Optical Flow Estimation and The Principles Behind Them</i> , 2013.											
15	IVANN	ms	code	8.33 %	17.92 %	2.7 px	7.4 px	100.00 %	1073 s	1 core @ 2.5 Ghz (Matlab)	<input type="checkbox"/>
Anonymous submission											
16	CnL	ms	code	8.34 %	17.35 %	2.8 px	7.2 px	100.00 %	14.8 min	1 core @ 3.0 Ghz (Matlab)	<input type="checkbox"/>
D. Sun, S. Roth and M. Back: <i>A Quantitative Analysis of Current Practices in Optical Flow Estimation and The Principles Behind Them</i> , 2013.											
17	FSGM	ms	code	8.44 %	20.63 %	3.2 px	12.2 px	100.00 %	60 s	1 core @ 2.4 Ghz (C/C++)	<input type="checkbox"/>
S. Hermann and R. Klette: <i>Hierarchical Scan Line Dynamic Programming for Optical Flow using Semi-Global Matching</i> , ACCV Workshops 2012.											
18	EPPM	ms	code	8.62 %	18.86 %	2.5 px	9.2 px	100.00 %	0.25 s	GPU @ 1.0 Ghz (C/C++)	<input type="checkbox"/>
Anonymous submission											
19	TGV2CENSUS	ms	code	9.19 %	15.68 %	2.9 px	6.6 px	100.00 %	4 s	GPU+CPU @ 3.0 Ghz (Matlab + C/C++)	<input type="checkbox"/>
M. Werberger: <i>Convex Approaches for High Performance Video Processing</i> , 2012.											
20	C+NL-fast	ms	code	10.13 %	19.07 %	3.2 px	7.8 px	100.00 %	2.9 min	1 core @ 3.0 Ghz (Matlab)	<input type="checkbox"/>
D. Sun, S. Roth and M. Back: <i>A Quantitative Analysis of Current Practices in Optical Flow Estimation and The Principles Behind Them</i> , 2013.											
21	HS	ms	code	12.47 %	21.00 %	4.0 px	9.0 px	100.00 %	2.6 min	1 core @ 3.0 Ghz (Matlab)	<input type="checkbox"/>
D. Sun, S. Roth and M. Back: <i>A Quantitative Analysis of Current Practices in Optical Flow Estimation and The Principles Behind Them</i> , 2013.											
22	IQFlow	ms	code	14.23 %	23.53 %	3.6 px	8.8 px	100.00 %	60 s	4 cores @ 3.5 Ghz (C/C++)	<input type="checkbox"/>
Anonymous submission											
23	GC-BM-Bino	ms	code	15.31 %	25.80 %	5.0 px	12.0 px	83.73 %	1.3 s	2 cores @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
B. Kitt and H. Lateghan: <i>Trinocular Optical Flow Estimation for Intelligent Vehicle Applications</i> , ITSC 2012.											
24	GC-BM-Mono	ms	code	15.42 %	25.93 %	5.0 px	12.1 px	84.33 %	1.3 s	2 cores @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
B. Kitt and H. Lateghan: <i>Trinocular Optical Flow Estimation for Intelligent Vehicle Applications</i> , ITSC 2012.											
25	eFolkI	ms	code	16.52 %	25.60 %	5.2 px	10.8 px	100.00 %	0.026 s	GPU @ 700 Mhz (C/C++)	<input type="checkbox"/>
Anonymous submission											
26	C+NL-M	ms	code	17.22 %	24.34 %	7.4 px	14.5 px	100.00 %	5 min	2 cores @ 2.5 Ghz (Matlab)	<input type="checkbox"/>
Anonymous submission											
27	HMM	ms	code	18.21 %	27.83 %	7.2 px	15.0 px	100.00 %	10 min	1 core @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
Anonymous submission											
28	ALD	ms	code	18.34 %	27.22 %	10.9 px	16.0 px	100.00 %	110 s	1 core @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
M. Stoll, S. Volt and A. Bruhn: <i>Adaptive Integration of Feature Matches into Variational Optical Flow Methods</i> , ACCV 2012.											
29	RSRS-Flow	ms	code	18.65 %	27.13 %	6.2 px	12.1 px	100.00 %	4 min	1 core @ 2.5 Ghz (Matlab)	<input type="checkbox"/>
P. Ghosh and B. Menonjith: <i>Robust Simultaneous Registration and Segmentation with Sparse Error Reconstruction</i> , PAMI 2012.											
30	LDOF	ms	code	18.72 %	27.97 %	5.5 px	12.4 px	100.00 %	1 min	1 core @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
T. Brox, J. Malik: <i>Large Displacement Optical Flow: Descriptor Matching in Variational Motion Estimation</i> , PAMI 2011.											
31	GCSF	ms	code	26.33 %	35.64 %	7.0 px	15.3 px	48.27 %	2.4 s	1 core @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
J. Cech, J. Sanchez-Riera and R. Horaud: <i>Scene Flow Estimation by Growing Correspondence Seeds</i> , CVPR 2011.											
32	DB-TV-L1	ms	code	26.50 %	35.10 %	7.8 px	14.6 px	100.00 %	16 s	1 core @ 2.5 Ghz (Matlab)	<input type="checkbox"/>
C. Zach, T. Pock and H. Bischof: <i>A Duality Based Approach for Realtime TV-L1 Optical Flow</i> , DAGM 2007.											
33	BERLOF	ms	code	30.63 %	39.00 %	8.5 px	16.2 px	15.26 %	0.231 s	GPU @ 700 Mhz (C/C++) GeForce GTX 680	<input type="checkbox"/>
T. Senst, J. Geistert, I. Keller and T. Skorup: <i>Robust Local Optical Flow Estimation using Bilinear Equations for Sparse Motion Estimation</i> , 20th IEEE International Conference on Image Processing 2013.											
34	RLOF	ms	code	31.49 %	39.83 %	8.7 px	16.5 px	14.76 %	0.488 s	GPU @ 700 Mhz (C/C++) GeForce GTX 680	<input type="checkbox"/>
T. Senst, V. Esterlin and T. Skorup: <i>Robust Local Optical Flow for Feature Tracking</i> , TCSVT 2012.											
35	HAOF	ms	code	32.48 %	40.12 %	11.1 px	18.2 px	100.00 %	16.2 s	1 core @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
T. Brox, A. Bruhn, N. Papenberg and J. Weickert: <i>High accuracy optical flow estimation based on a theory for warping</i> , ECCV 2004.											
36	PolyExpand	ms	code	44.53 %	51.03 %	17.2 px	25.2 px	100.00 %	1 s	1 core @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
G. Farneback: <i>Two-Frame Motion Estimation Based on Polynomial Expansion</i> , SCIA 2003.											
37	Pyramidal-LR	ms	code	57.22 %	62.72 %	21.7 px	33.1 px	99.90 %	1.5 min	1 core @ 2.5 Ghz (Matlab)	<input type="checkbox"/>
J. Bouquet: <i>Pyramidal implementation of the Lucas Kanade feature tracker</i> , Int'l2000.											
38	OCV-BM	ms	code	60.41 %	65.49 %	24.4 px	33.3 px	100.00 %	1.5 min	1 core @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
G. Bradski: <i>The OpenCV Library</i> , Dr. Dobb's Journal of Software Tools 2000.											
39	MEDIAN	ms	code	66.55 %	71.52 %	16.0 px	23.9 px	99.94 %	0.01 s	1 core @ 2.5 Ghz (C/C++)	<input type="checkbox"/>
C. Zach, T. Pock and H. Bischof: <i>Scene Flow Estimation by Growing Correspondence Seeds</i> , CVPR 2011.											
40	AVERAGE	ms	code	67.92 %	72.68 %	16.3 px	24.6 px	99.94 %	0.01 s	1 core @ 2.5 Ghz (C/C++)	<input type="checkbox"/>

[This table as LaTeX](#)

The settings column describes additional assumptions made / information used by the methods:

■ ms = motion stereo: Usage of the epipolar geometry to restrict the search problem to 1D

Figure 3: Bad pixel ranking (threshold 5 pixels) on KITTI benchmark (captured on Oct 30th, 2013). Note that in the “setting” column, more than one icon means the method is not a pure optical flow estimation method.

### Optical flow evaluation results

Show images:  below table  above table  in window

**Statistics:** Average SD R0.5 R1.0 R2.0 A50 A75 A95  
**Error type:** endpoint angle interpolation normalized interpolation

Average endpoint error	Army (Hidden texture)	Mequon (Hidden texture)	Schefflera (Hidden texture)	Wooden (Hidden texture)	Grove (Synthetic)	Urban (Synthetic)	Yosemite (Synthetic)	Teddy (Stereo)
avg rank	GT im0 im1 all disc untext	GT im0 im1 all disc untext	GT im0 im1 all disc untext	GT im0 im1 all disc untext	GT im0 im1 all disc untext	GT im0 im1 all disc untext	GT im0 im1 all disc untext	GT im0 im1 all disc untext
MANN [91]	2.6	<b>0.07</b> <b>0.20</b> <b>0.05</b> <b>0.15</b> <b>0.51</b> <b>0.125</b>	<b>0.18</b> <b>0.37</b> <b>0.14</b> <b>0.10</b> <b>0.49</b> <b>0.06</b>	<b>0.41</b> <b>0.61</b> <b>0.21</b> <b>0.23</b> <b>0.66</b> <b>0.19</b>	<b>0.10</b> <b>0.128</b> <b>0.17</b> <b>0.34</b> <b>0.80</b> <b>0.23</b>			
OFLAF [80]	6.6	<b>0.08</b> <b>0.21</b> <b>0.06</b> <b>0.16</b> <b>0.53</b> <b>0.125</b>	<b>0.19</b> <b>0.37</b> <b>0.14</b> <b>0.14</b> <b>0.77</b> <b>0.07</b>	<b>0.51</b> <b>0.78</b> <b>0.25</b> <b>0.31</b> <b>0.76</b> <b>0.25</b>	<b>0.11</b> <b>0.128</b> <b>0.21</b> <b>0.42</b> <b>0.78</b> <b>0.63</b>			
MDP-flow2 [69]	7.5	<b>0.08</b> <b>0.21</b> <b>0.07</b> <b>0.15</b> <b>0.46</b> <b>0.111</b>	<b>0.20</b> <b>0.40</b> <b>0.14</b> <b>0.15</b> <b>0.80</b> <b>0.08</b>	<b>0.63</b> <b>0.93</b> <b>0.43</b> <b>0.43</b> <b>0.26</b> <b>0.11</b>	<b>0.26</b> <b>0.76</b> <b>0.23</b> <b>0.11</b> <b>0.128</b> <b>0.17</b>	<b>0.11</b> <b>0.128</b> <b>0.17</b> <b>0.38</b> <b>0.79</b> <b>0.44</b>	<b>0.11</b> <b>0.128</b> <b>0.17</b> <b>0.38</b> <b>0.79</b> <b>0.44</b>	<b>0.11</b> <b>0.128</b> <b>0.17</b> <b>0.38</b> <b>0.79</b> <b>0.44</b>
NN-field [72]	8.3	<b>0.08</b> <b>0.22</b> <b>0.05</b> <b>0.17</b> <b>0.56</b> <b>0.13</b>	<b>0.19</b> <b>0.39</b> <b>0.15</b> <b>0.15</b> <b>0.98</b> <b>0.05</b>	<b>0.69</b> <b>0.94</b> <b>0.45</b> <b>0.45</b> <b>0.21</b> <b>0.11</b>	<b>0.41</b> <b>0.61</b> <b>0.20</b> <b>0.52</b> <b>0.64</b> <b>0.26</b>	<b>0.13</b> <b>0.126</b> <b>0.20</b> <b>0.35</b> <b>0.35</b> <b>0.21</b>	<b>0.13</b> <b>0.126</b> <b>0.20</b> <b>0.35</b> <b>0.35</b> <b>0.21</b>	<b>0.13</b> <b>0.126</b> <b>0.20</b> <b>0.35</b> <b>0.35</b> <b>0.21</b>
Epistemic [81]	9.6	<b>0.07</b> <b>0.21</b> <b>0.05</b> <b>0.16</b> <b>0.56</b> <b>0.125</b>	<b>0.20</b> <b>0.44</b> <b>0.15</b> <b>0.11</b> <b>0.65</b> <b>0.06</b>	<b>0.76</b> <b>1.07</b> <b>0.50</b> <b>0.53</b> <b>0.26</b> <b>0.13</b>	<b>0.26</b> <b>0.76</b> <b>0.28</b> <b>0.16</b> <b>0.18</b> <b>0.12</b>	<b>0.11</b> <b>0.136</b> <b>0.15</b> <b>0.41</b> <b>0.88</b> <b>0.54</b>	<b>0.11</b> <b>0.136</b> <b>0.15</b> <b>0.41</b> <b>0.88</b> <b>0.54</b>	<b>0.11</b> <b>0.136</b> <b>0.15</b> <b>0.41</b> <b>0.88</b> <b>0.54</b>
TCF-Flow [79]	14.3	<b>0.07</b> <b>0.21</b> <b>0.05</b> <b>0.19</b> <b>0.68</b> <b>0.125</b>	<b>0.28</b> <b>0.66</b> <b>0.14</b> <b>0.14</b> <b>0.86</b> <b>0.07</b>	<b>0.67</b> <b>0.98</b> <b>0.49</b> <b>0.49</b> <b>0.22</b> <b>0.11</b>	<b>0.22</b> <b>0.85</b> <b>0.19</b> <b>0.19</b> <b>0.41</b> <b>0.11</b>	<b>0.11</b> <b>0.111</b> <b>0.30</b> <b>0.46</b> <b>0.50</b> <b>0.14</b>	<b>0.11</b> <b>0.111</b> <b>0.30</b> <b>0.46</b> <b>0.50</b> <b>0.14</b>	<b>0.11</b> <b>0.111</b> <b>0.30</b> <b>0.46</b> <b>0.50</b> <b>0.14</b>
Layers++ [37]	15.6	<b>0.08</b> <b>0.21</b> <b>0.07</b> <b>0.19</b> <b>0.56</b> <b>0.174</b>	<b>0.20</b> <b>0.40</b> <b>0.18</b> <b>0.13</b> <b>0.54</b> <b>0.07</b>	<b>0.48</b> <b>0.70</b> <b>0.33</b> <b>0.29</b> <b>0.101</b> <b>0.33</b>	<b>0.14</b> <b>0.128</b> <b>0.17</b> <b>0.48</b> <b>0.88</b> <b>0.72</b>			
ADP [66]	15.7	<b>0.08</b> <b>0.22</b> <b>0.06</b> <b>0.18</b> <b>0.62</b> <b>0.14</b>	<b>0.29</b> <b>0.71</b> <b>0.17</b> <b>0.17</b> <b>0.61</b> <b>0.09</b>	<b>0.18</b> <b>0.91</b> <b>0.37</b> <b>0.37</b> <b>0.48</b> <b>0.12</b>	<b>0.12</b> <b>0.128</b> <b>0.20</b> <b>0.43</b> <b>0.88</b> <b>0.63</b>			
LME [71]	15.9	<b>0.08</b> <b>0.22</b> <b>0.05</b> <b>0.15</b> <b>0.49</b> <b>0.111</b>	<b>0.20</b> <b>0.40</b> <b>0.14</b> <b>0.15</b> <b>0.78</b> <b>0.09</b>	<b>0.15</b> <b>0.80</b> <b>0.26</b> <b>0.08</b> <b>0.63</b> <b>0.11</b>	<b>0.26</b> <b>0.76</b> <b>0.25</b> <b>0.23</b> <b>0.64</b> <b>0.11</b>	<b>0.11</b> <b>0.128</b> <b>0.17</b> <b>0.48</b> <b>0.88</b> <b>0.63</b>	<b>0.11</b> <b>0.128</b> <b>0.17</b> <b>0.48</b> <b>0.88</b> <b>0.63</b>	<b>0.11</b> <b>0.128</b> <b>0.17</b> <b>0.48</b> <b>0.88</b> <b>0.63</b>
iROF++ [58]	16.5	<b>0.08</b> <b>0.23</b> <b>0.07</b> <b>0.14</b> <b>0.62</b> <b>0.14</b>	<b>0.21</b> <b>0.48</b> <b>0.18</b> <b>0.17</b> <b>0.63</b> <b>0.09</b>	<b>0.15</b> <b>0.73</b> <b>0.19</b> <b>0.19</b> <b>0.60</b> <b>0.12</b>	<b>0.10</b> <b>0.89</b> <b>0.42</b> <b>0.42</b> <b>0.21</b> <b>0.12</b>	<b>0.10</b> <b>0.128</b> <b>0.18</b> <b>0.41</b> <b>0.87</b> <b>0.62</b>	<b>0.10</b> <b>0.128</b> <b>0.18</b> <b>0.41</b> <b>0.87</b> <b>0.62</b>	<b>0.10</b> <b>0.128</b> <b>0.18</b> <b>0.41</b> <b>0.87</b> <b>0.62</b>
nLayers [57]	16.7	<b>0.07</b> <b>0.19</b> <b>0.06</b> <b>0.22</b> <b>0.59</b> <b>0.19</b>	<b>0.25</b> <b>0.54</b> <b>0.20</b> <b>0.19</b> <b>0.64</b> <b>0.08</b>	<b>0.15</b> <b>0.84</b> <b>0.29</b> <b>0.08</b> <b>0.53</b> <b>0.14</b>	<b>0.22</b> <b>0.84</b> <b>0.34</b> <b>0.44</b> <b>0.22</b> <b>0.12</b>	<b>0.13</b> <b>0.136</b> <b>0.20</b> <b>0.29</b> <b>0.54</b> <b>0.13</b>	<b>0.13</b> <b>0.136</b> <b>0.20</b> <b>0.29</b> <b>0.54</b> <b>0.13</b>	<b>0.13</b> <b>0.136</b> <b>0.20</b> <b>0.29</b> <b>0.54</b> <b>0.13</b>
FC-2Layers-FF [76]	16.8	<b>0.07</b> <b>0.21</b> <b>0.07</b> <b>0.19</b> <b>0.62</b> <b>0.174</b>	<b>0.21</b> <b>0.50</b> <b>0.18</b> <b>0.17</b> <b>0.66</b> <b>0.07</b>	<b>0.15</b> <b>0.76</b> <b>0.20</b> <b>0.17</b> <b>0.53</b> <b>0.14</b>	<b>0.23</b> <b>0.87</b> <b>0.37</b> <b>0.44</b> <b>0.23</b> <b>0.12</b>	<b>0.12</b> <b>0.128</b> <b>0.20</b> <b>0.43</b> <b>0.88</b> <b>0.63</b>	<b>0.12</b> <b>0.128</b> <b>0.20</b> <b>0.43</b> <b>0.88</b> <b>0.63</b>	<b>0.12</b> <b>0.128</b> <b>0.20</b> <b>0.43</b> <b>0.88</b> <b>0.63</b>
Correlation Flow [78]	18.7	<b>0.07</b> <b>0.23</b> <b>0.07</b> <b>0.14</b> <b>0.58</b> <b>0.11</b>	<b>0.24</b> <b>0.57</b> <b>0.18</b> <b>0.15</b> <b>0.63</b> <b>0.07</b>	<b>0.14</b> <b>0.74</b> <b>0.21</b> <b>0.15</b> <b>0.59</b> <b>0.14</b>	<b>0.21</b> <b>0.87</b> <b>0.38</b> <b>0.44</b> <b>0.21</b> <b>0.13</b>	<b>0.15</b> <b>0.98</b> <b>0.36</b> <b>0.36</b> <b>0.41</b> <b>0.14</b>	<b>0.14</b> <b>0.128</b> <b>0.27</b> <b>0.45</b> <b>0.85</b> <b>0.62</b>	<b>0.14</b> <b>0.128</b> <b>0.27</b> <b>0.45</b> <b>0.85</b> <b>0.62</b>
AGIF-OF [89]	20.2	<b>0.08</b> <b>0.22</b> <b>0.07</b> <b>0.14</b> <b>0.53</b> <b>0.13</b>	<b>0.23</b> <b>0.51</b> <b>0.18</b> <b>0.18</b> <b>0.63</b> <b>0.07</b>	<b>0.14</b> <b>0.70</b> <b>0.19</b> <b>0.08</b> <b>0.57</b> <b>0.13</b>	<b>0.27</b> <b>0.86</b> <b>0.38</b> <b>0.41</b> <b>0.27</b> <b>0.14</b>	<b>0.14</b> <b>0.97</b> <b>0.34</b> <b>0.34</b> <b>0.40</b> <b>0.15</b>	<b>0.13</b> <b>0.136</b> <b>0.22</b> <b>0.43</b> <b>0.89</b> <b>0.64</b>	<b>0.13</b> <b>0.136</b> <b>0.22</b> <b>0.43</b> <b>0.89</b> <b>0.64</b>
TC-Flow [24]	21.6	<b>0.07</b> <b>0.21</b> <b>0.06</b> <b>0.15</b> <b>0.55</b> <b>0.11</b>	<b>0.25</b> <b>0.58</b> <b>0.19</b> <b>0.19</b> <b>0.64</b> <b>0.07</b>	<b>0.17</b> <b>0.71</b> <b>0.20</b> <b>0.18</b> <b>0.58</b> <b>0.14</b>	<b>0.27</b> <b>0.86</b> <b>0.39</b> <b>0.44</b> <b>0.27</b> <b>0.15</b>	<b>0.14</b> <b>0.98</b> <b>0.35</b> <b>0.35</b> <b>0.41</b> <b>0.16</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>
FESL [74]	21.7	<b>0.07</b> <b>0.21</b> <b>0.07</b> <b>0.14</b> <b>0.54</b> <b>0.12</b>	<b>0.25</b> <b>0.58</b> <b>0.19</b> <b>0.19</b> <b>0.63</b> <b>0.07</b>	<b>0.17</b> <b>0.71</b> <b>0.20</b> <b>0.18</b> <b>0.57</b> <b>0.14</b>	<b>0.27</b> <b>0.86</b> <b>0.39</b> <b>0.44</b> <b>0.27</b> <b>0.15</b>	<b>0.14</b> <b>0.98</b> <b>0.35</b> <b>0.35</b> <b>0.41</b> <b>0.16</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>
Classic+CPF [87]	21.7	<b>0.07</b> <b>0.23</b> <b>0.07</b> <b>0.14</b> <b>0.53</b> <b>0.12</b>	<b>0.22</b> <b>0.59</b> <b>0.19</b> <b>0.19</b> <b>0.62</b> <b>0.07</b>	<b>0.17</b> <b>0.72</b> <b>0.20</b> <b>0.18</b> <b>0.56</b> <b>0.14</b>	<b>0.27</b> <b>0.86</b> <b>0.39</b> <b>0.44</b> <b>0.27</b> <b>0.15</b>	<b>0.14</b> <b>0.98</b> <b>0.35</b> <b>0.35</b> <b>0.41</b> <b>0.16</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>
ALD-Flow [67]	21.8	<b>0.07</b> <b>0.21</b> <b>0.07</b> <b>0.14</b> <b>0.53</b> <b>0.12</b>	<b>0.21</b> <b>0.59</b> <b>0.19</b> <b>0.19</b> <b>0.61</b> <b>0.07</b>	<b>0.17</b> <b>0.72</b> <b>0.20</b> <b>0.18</b> <b>0.55</b> <b>0.14</b>	<b>0.27</b> <b>0.86</b> <b>0.39</b> <b>0.44</b> <b>0.27</b> <b>0.15</b>	<b>0.14</b> <b>0.98</b> <b>0.35</b> <b>0.35</b> <b>0.41</b> <b>0.16</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>
SCR [73]	21.8	<b>0.08</b> <b>0.23</b> <b>0.07</b> <b>0.14</b> <b>0.53</b> <b>0.12</b>	<b>0.22</b> <b>0.60</b> <b>0.19</b> <b>0.19</b> <b>0.61</b> <b>0.07</b>	<b>0.17</b> <b>0.73</b> <b>0.20</b> <b>0.18</b> <b>0.56</b> <b>0.14</b>	<b>0.27</b> <b>0.86</b> <b>0.39</b> <b>0.44</b> <b>0.27</b> <b>0.15</b>	<b>0.14</b> <b>0.98</b> <b>0.35</b> <b>0.35</b> <b>0.41</b> <b>0.16</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>
COFM [59]	22.1	<b>0.08</b> <b>0.26</b> <b>0.06</b> <b>0.15</b> <b>0.58</b> <b>0.14</b>	<b>0.20</b> <b>0.56</b> <b>0.18</b> <b>0.19</b> <b>0.62</b> <b>0.07</b>	<b>0.15</b> <b>0.76</b> <b>0.21</b> <b>0.17</b> <b>0.58</b> <b>0.14</b>	<b>0.27</b> <b>0.85</b> <b>0.38</b> <b>0.44</b> <b>0.27</b> <b>0.15</b>	<b>0.14</b> <b>0.98</b> <b>0.34</b> <b>0.34</b> <b>0.40</b> <b>0.15</b>	<b>0.14</b> <b>0.128</b> <b>0.28</b> <b>0.45</b> <b>0.89</b> <b>0.66</b>	<b>0.14</b> <b>0.128</b> <b>0.28</b> <b>0.45</b> <b>0.89</b> <b>0.66</b>
SparseNon-Sparse [56]	22.3	<b>0.08</b> <b>0.23</b> <b>0.07</b> <b>0.14</b> <b>0.53</b> <b>0.12</b>	<b>0.22</b> <b>0.62</b> <b>0.17</b> <b>0.17</b> <b>0.63</b> <b>0.07</b>	<b>0.13</b> <b>0.73</b> <b>0.19</b> <b>0.18</b> <b>0.59</b> <b>0.14</b>	<b>0.27</b> <b>0.86</b> <b>0.39</b> <b>0.44</b> <b>0.27</b> <b>0.15</b>	<b>0.14</b> <b>0.98</b> <b>0.35</b> <b>0.35</b> <b>0.41</b> <b>0.16</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>	<b>0.14</b> <b>0.128</b> <b>0.25</b> <b>0.45</b> <b>0.87</b> <b>0.65</b>
Efficient-NL [60]	22.5	<b>0.08</b> <b>0.22</b> <b>0.06</b> <b>0.15</b> <b>0.53</b> <b>0.12</b>	<b>0.21</b> <b>0.67</b> <b>0.17</b> <b>0.17</b> <b>0.63</b> <b>0.07</b>	<b>0.12</b> <b>0.74</b> <b>0.19</b> <b>0.18</b> <b>0.59</b> <b>0.14</b>	<b>0.26</b> <b>0.85</b> <b>0.36</b> <b>0.44</b> <b>0.26</b> <b>0.14</b>	<b>0.13</b> <b>0.98</b> <b>0.33</b> <b>0.33</b> <b>0.40</b> <b>0.15</b>	<b>0.13</b> <b>0.128</b> <b>0.26</b> <b>0.46</b> <b>0.88</b> <b>0.67</b>	<b>0.13</b> <b>0.128</b> <b>0.26</b> <b>0.46</b> <b>0.88</b> <b>0.67</b>
LSM [39]	23.8	<b>0.08</b> <b>0.23</b> <b>0.07</b> <b>0.14</b> <b>0.53</b> <b>0.12</b>	<b>0.22</b> <b>0.69</b> <b>0.18</b> <b>0.18</b> <b>0.62</b> <b>0.07</b>	<b>0.18</b> <b>0.74</b> <b>0.19</b> <b>0.19</b> <b>0.56</b> <b>0.14</b>	<b>0.27</b> <b>0.86</b> <b>0.39</b> <b>0.44</b> <b>0.27</b> <b>0.15</b>	<b		



Frame 1

Frame 2

Ground truth

Ours (clean pass)

Ours (final pass)

Figure 5: Our results on MPI Sintel benchmark.

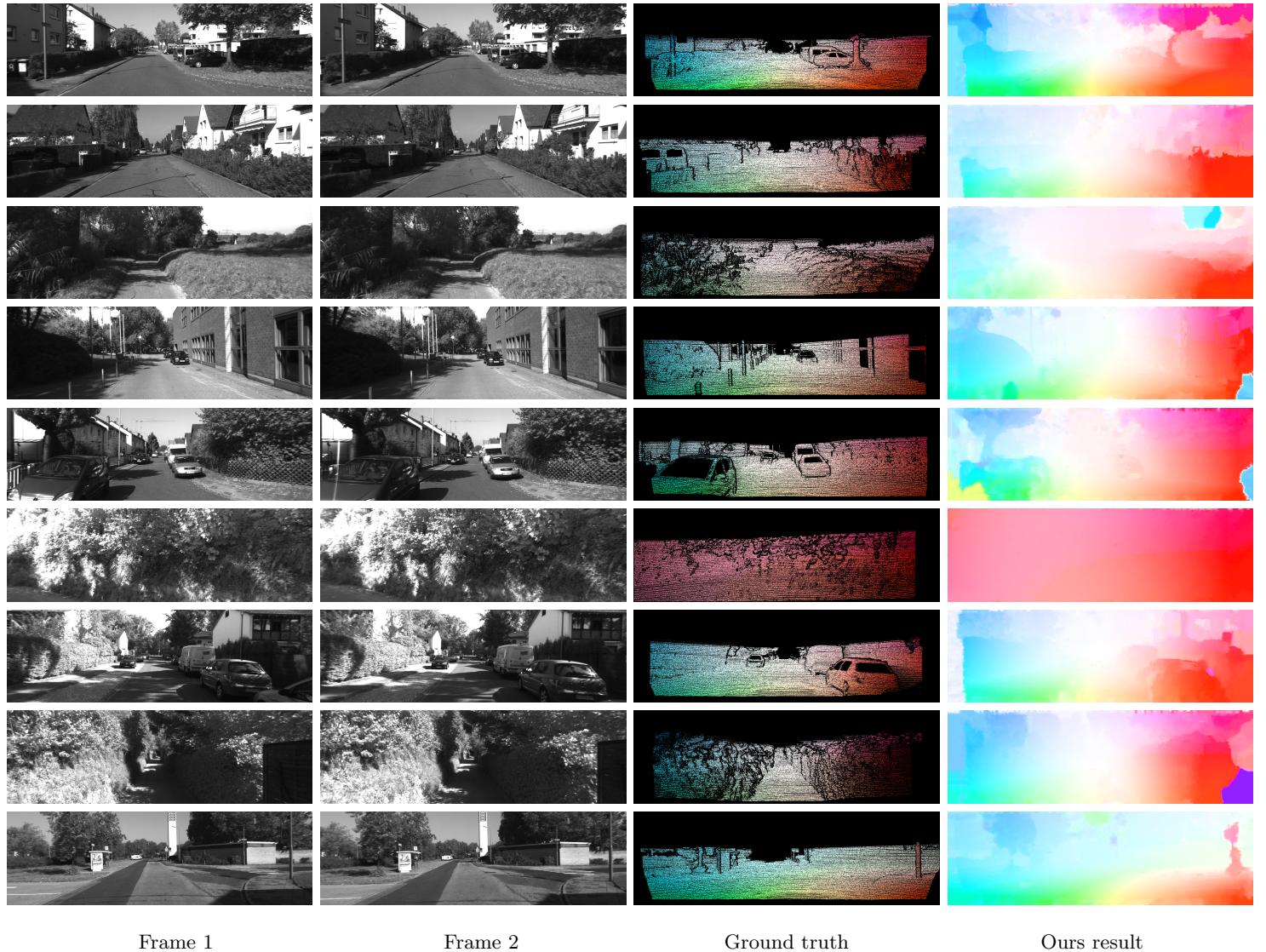


Figure 6: Our results on KITTI benchmark (with MPI Sintel color coding for visual show).