## **EE599 HW5**

## **Runtime analysis**

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## 1. Find Maximum Depth

```
void BST::NonRecursivePrintInorder(TreeNode *node) {
 level = 1;
 MaxDepth = 1;
 TreeNode* current = node;
 while(current != NULL || path.empty() != true) {
   while (current != NULL) {
     path.push(current);
     current = current->left;
     if(current!=NULL) {
       level++;
       if(MaxDepth < level) {</pre>
         MaxDepth = level;
   std::cout << path.top()->val << " " ;</pre>
   current = path.top();
   if(current == root_) {
     level = 1;
   DFSpath.push_back(current->val); // push back the path into vector in order for GTEST
   path.pop();
   if(current->right == NULL && current->left == NULL) {
     level--;
   current = current->right;
   if(current!=NULL) {
       level++;
       if(MaxDepth < level) {</pre>
         MaxDepth = level;
```

Basically, I use Q2 Inorder to find my Height of tree.

Therefore, the time complexity of Inorder is O(n)

Since the time complexity of DFS in a graph G(E,V) is T(n) = O(E+V), which E represents the edges and V represents the vertices. BST is also a graph, therefore T(n) = O(n+(n-1)) = O(n)

2. Inorder, recursive and non-recursive

```
void BST::printInorder(TreeNode *node) { // recursive
  if(node == NULL) {
    return;
  }

  // recursive on left subtree
  printInorder(node->left);

std::cout << node->val << " ";
  DFSpath.push_back(node->val);

  // recursive on right subtree
  printInorder(node->right);
}
```

Recursive and non-recursive will visit every node, until it visit all the nodes. Therefore, it takes linear time, T(n) = O(n)