ASL to Audio

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Agenda

Background + Dataset

Recorded Demo

Pipeline

Cloud

Edge

Live Demo

Next Step

Background + Dataset

ASL Challenge: Communication requires both parties (or multiple participants) to understand and use sign languages as the prerequisite.

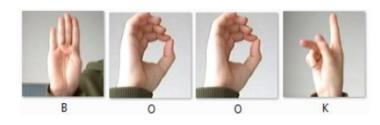
Project Goal: The Autobot team wants to overcome challenges for the deaf-mute community, by converting the sign languages directly to audio.

Dataset Options: word-level vs. alphabet-level

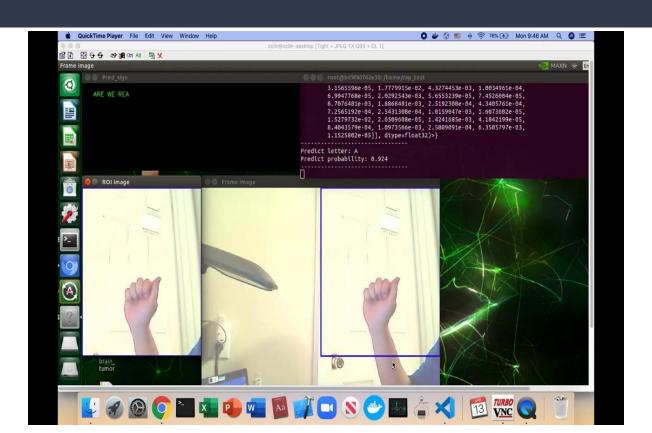
Word level



Letter level



Recorded Demo



Dataset selection and implementation plan

Cloud:

Dataset: ASL Alphabet (1.2 GB; 87000 images; 29 classes)

Cloud VM (Model training: VGG16, Resnet 50, Custom Vision, AutoML)

Edge (Jetson TX2):

USB camera Inference on Edge (pretrained model: Keras, OpenCV)

Pipelines:

- 1. Real-time video capturing
- 2. Hand sign image collection
- 3. Sign prediction
- 4. Text printing
- 5. Save the audio of a sentence

CLOUD

Cloud - Model Architecture

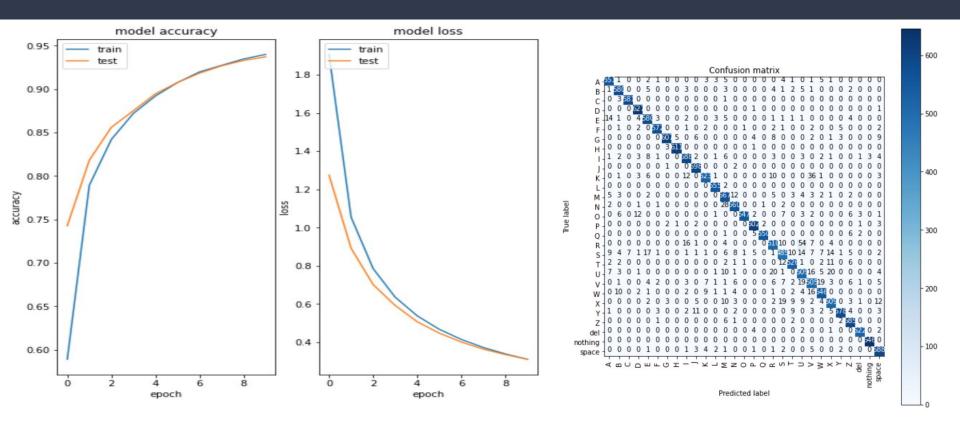
Approach	Strengths	Weakness
Build from scratch	 Most flexible architecture Freedom to tune parameters Shot at greatness (SatyaNet) 	 Longer development time Computational resource limitation Reinventing the wheel
Bottleneck features (SOTA)	 Leverage features trained on ImageNet Performant Faster dev time 	 Higher Accuracy but can go higher Features may not be relevant
Fine-tune top layer (SOTA)	 Highest Model Accuracy Fastest dev time Incentivized by HW9 losses 	 Incompatible pre-trained weights Overfitting by powerful networks

VGG-16 Transfer Learning

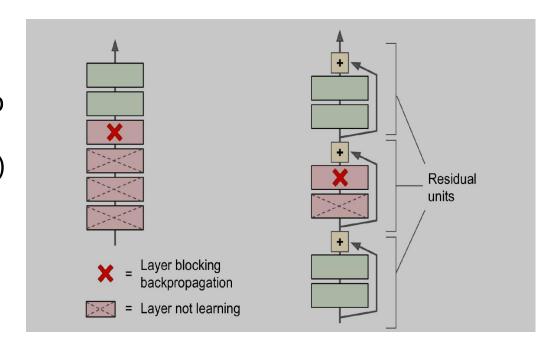


- Large kernel sized filters replaced by multiple small 3X3 filters
- Trained with 87000 50X50 sized ASL images. Labels were One Hot encoded
- Dimension ordered pre-trained VGG-16 weights used without top layer
- Categorical Cross entropy loss, Adam optimizer
- Total params: 14, 729, 565 Trainable Prams: 14, 877

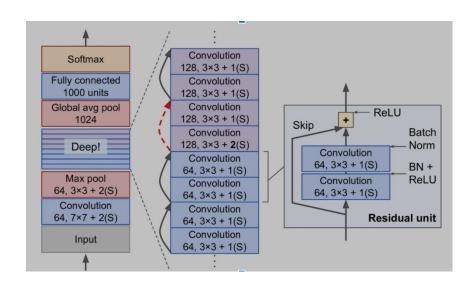
Key Metrics



- Residual Network with 50 layers
- Deep network that uses skip connection strategy
- Stack of residual units (RUs) where each unit is a small neural network with a skip connection



- Deep stack of simple residual units
- Each unit is composed of 2 convolutional layers (no pooling layer)
- Batch Normalization and ReLU activation
- 3x3 Kernels
- Preserves spatial dimensions (stride=1, "same" padding)



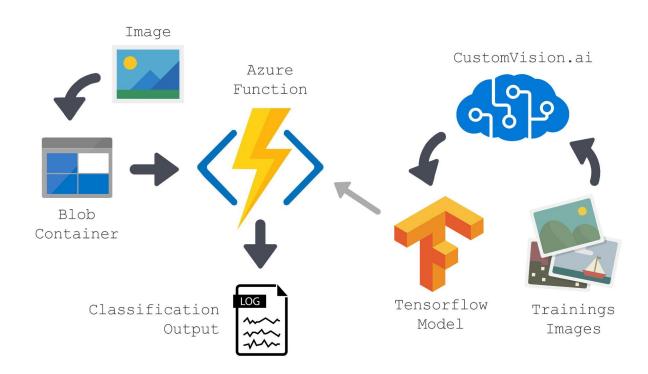
Training Strategy

- Image was pre-processed to a size of 224 x 224 and augmented
- Top layer of the network was replaced with our Pool and Dense layers
- Two runs of 10 epochs each were executed
- First run
 - Weights of pretrained layers were frozen
 - Learning rate = 0.2 and decay = 0.01
 - Accuracy = 65%
- Second run
 - Weights of pretrained layers were not frozen
 - Learning rate = 0.01 and decay = 0.001
 - Accuracy = 98%

```
Epoch 1/10
Epoch 2/10
2446/2446 [========================== ] - 455s 186ms/step - loss: 0.0033 - accuracy: 0.9997 - val loss: 0.0535 - val accuracy: 0.9837
Epoch 3/10
2446/2446 [================ ] - 455s 186ms/step - loss: 0.0018 - accuracy: 0.9999 - val loss: 0.0586 - val accuracy: 0.9823
Epoch 4/10
2446/2446 [============================== ] - 455s 186ms/step - loss: 0.0015 - accuracy: 0.9999 - val loss: 0.0518 - val accuracy: 0.9844
Epoch 5/10
2446/2446 [============================ ] - 455s 186ms/step - loss: 0.0011 - accuracy: 1.0000 - val loss: 0.0571 - val accuracy: 0.9828
Epoch 6/10
2446/2446 [=============================== ] - 455s 186ms/step - loss: 0.0011 - accuracy: 0.9999 - val loss: 0.0548 - val accuracy: 0.9832
Epoch 7/10
Epoch 8/10
Epoch 9/10
2446/2446 [===========] - 454s 186ms/step - loss: 8.5705e-04 - accuracy: 1.0000 - val loss: 0.0553 - val accuracy: 0.9829
Epoch 10/10
2446/2446 [===============] - 454s 186ms/step - loss: 7.6152e-04 - accuracy: 0.9999 - val loss: 0.0534 - val accuracy: 0.9838
```

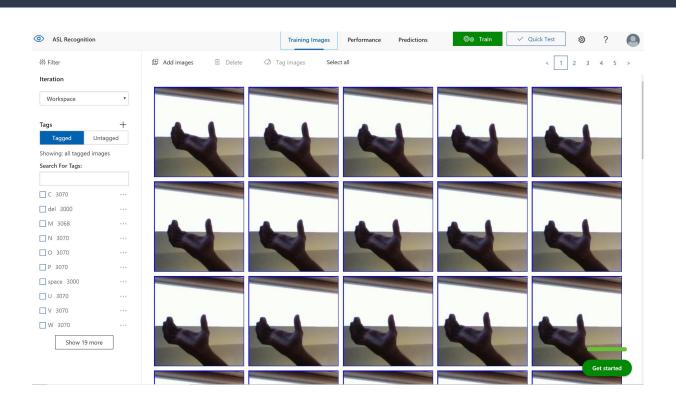
Cloud - Custom Vision (Azure)





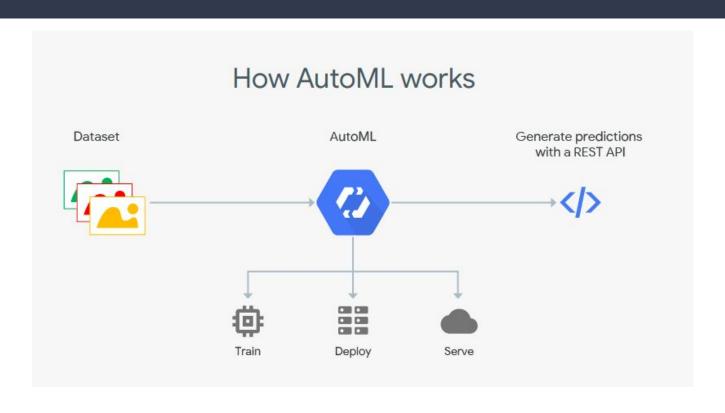






Cloud - AutoML (GCP)





Cloud - AutoML (GCP)



Set up process

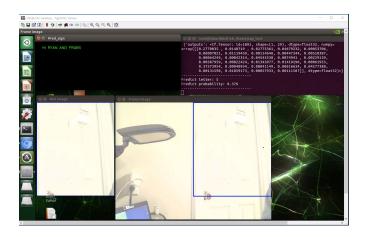
- Copy a set of images into Google Cloud Storage.
- Create a CSV listing the images and their labels.
- Use AutoML Vision to create your dataset, train a custom AutoML Vision Edge model, and make a prediction.
- Export and deploy the AutoML Vision Edge model.

EDGE

Edge-pipelines

Edge (Jetson TX2):

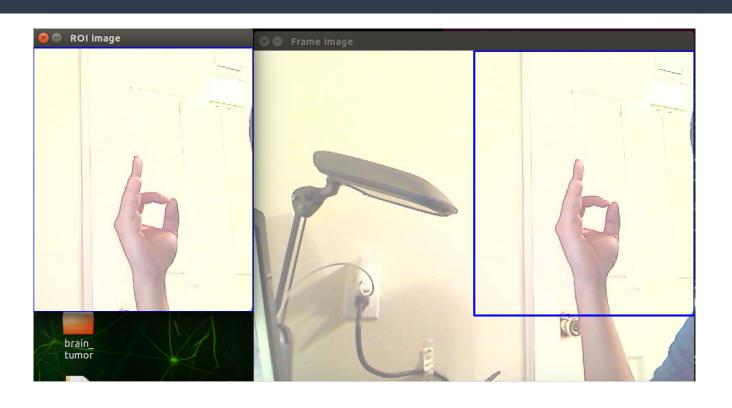




The pipeline has five major steps:

- Read the real-time video input
- Cut out the hands portion from the frame
- Conduct inference on the hands picture
- Return the text
- Return the audio of a sentence

Interface-Windows of image capturing



Interface-Prediction results

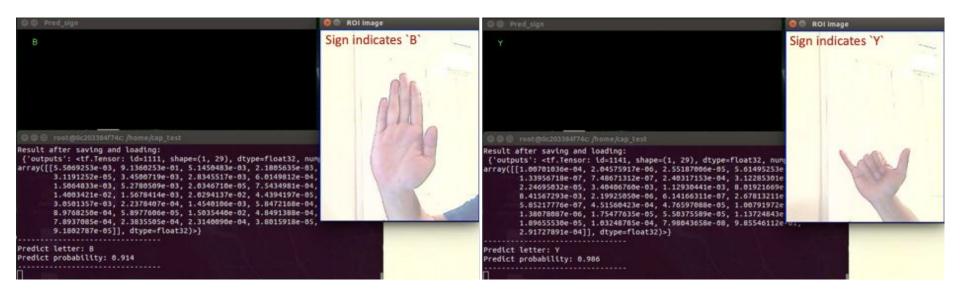
```
□ root@0c203384f74c: /home/cap test
Result after saving and loading:
{'outputs': <tf.Tensor: id=2861, shape=(1, 29), dtype=float32, numpy=
array([[3.6763038e-05, 8.1548101e-04, 1.1495011e-02, 8.7623578e-01,
       1.9593233e-05, 1.1486478e-05, 6.7616485e-02, 1.3816097e-05,
       8.8108945e-06, 2.7282885e-03, 4.8795091e-06, 9.8892802e-04,
       4.9960795e-03, 2.0433907e-05, 1.0951474e-04, 1.4912941e-05,
       2.7519494e-02, 1.0796617e-03, 1.9500379e-05, 6.8796013e-05,
       3.4988641e-06, 8.9157716e-04, 2.9054610e-04, 9.9610743e-06,
       2.1294598e-03, 1.6401726e-04, 2.6805883e-03, 8.8748948e-06,
       1.7797596e-05]], dtype=float32)>}
Predict letter: D
Predict probability: 0.876
```

Interface-Sign language to text and audio





Prediction



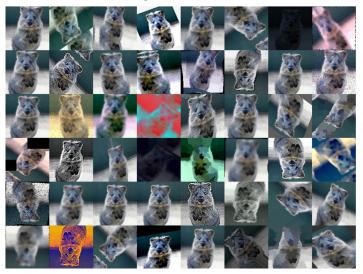
Issue of misclassification



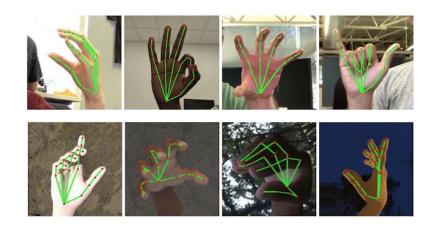
Live Demo

Next Steps-Improvement of prediction

Image preprocessing Image augmentation Photo auto-tuning



Palm Detection



Next Steps-Expansion with word-level signs



Next Steps-Mobile Apps

Mobile App



Thank You

Reference

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