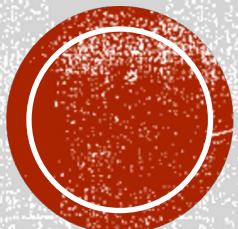


# PANDORA'S PROBLEM WITH NONOBLIGATORY INSPECTION: OPTIMAL STRUCTURE AND A PTAS

Linda Cai

Joint work with Hedyeh Beyhaghi



# OUR QUEST OF SEARCH

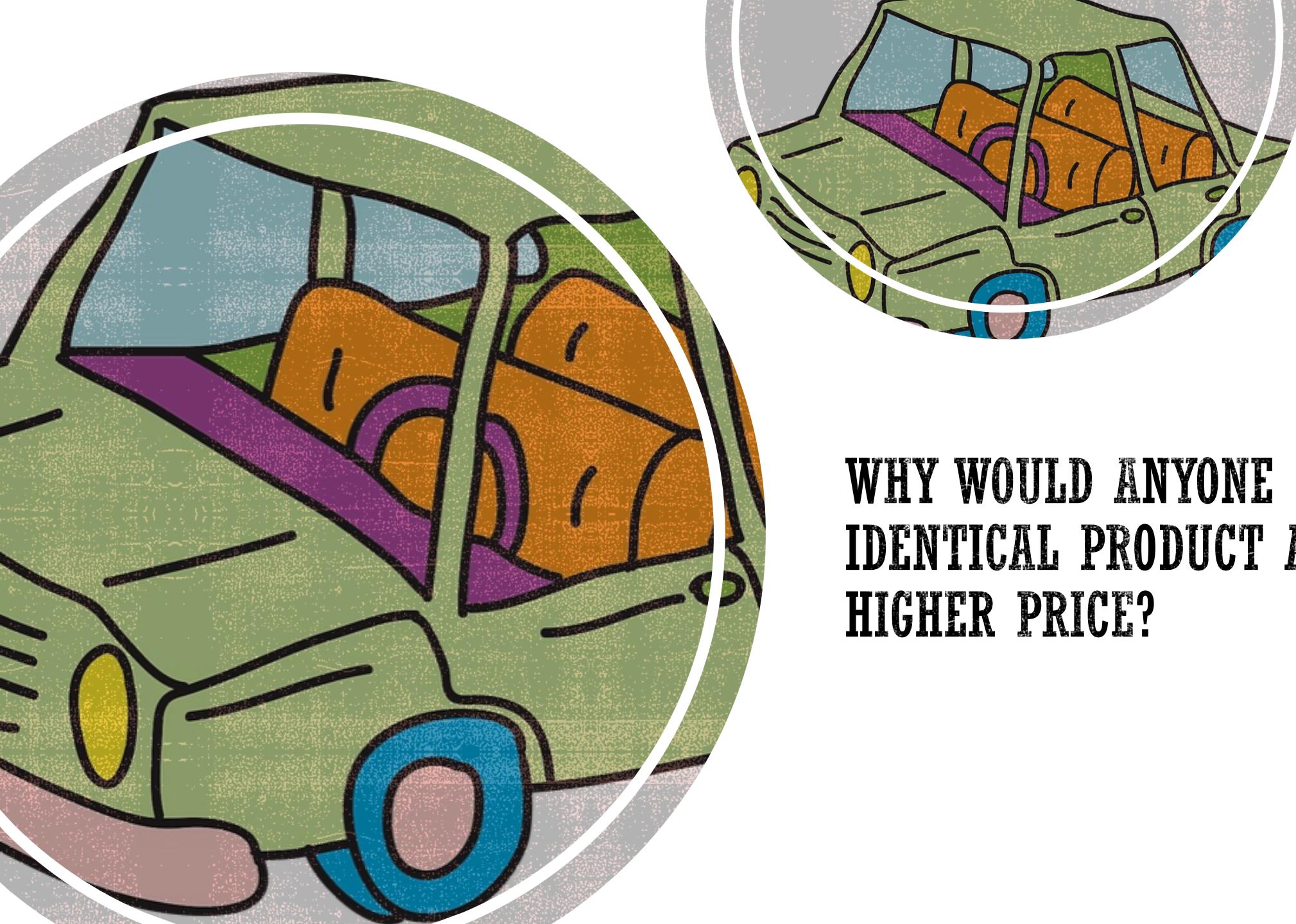


# OUR QUEST OF SEARCH



# OUR QUEST OF SEARCH





**WHY WOULD ANYONE BUY AN  
IDENTICAL PRODUCT AT A  
HIGHER PRICE?**



# **WEITZMAN'S ANSWER: SEARCH FRICTION**



# WEITZMAN'S ANSWER: SEARCH FRICTION

Buying from a car dealer: the cost of inspection is high



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Buying from a car dealer: the cost of inspection is high

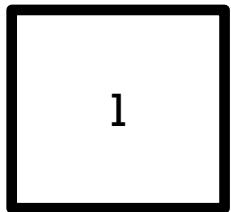


Buying from a trusted friend: the cost of inspection is low

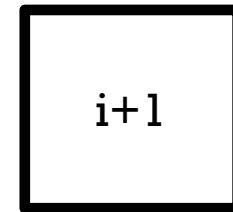
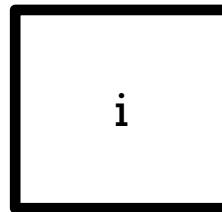


# PANDORA'S BOX PROBLEM

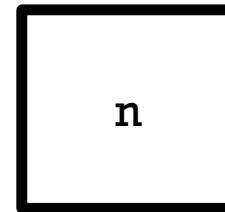
(Introduced by Weitzman79)



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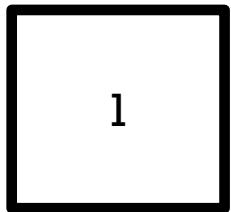


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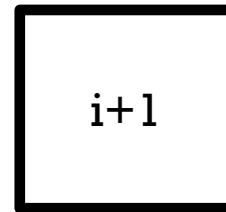
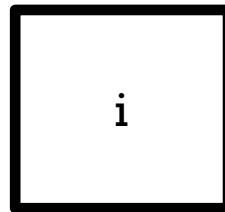


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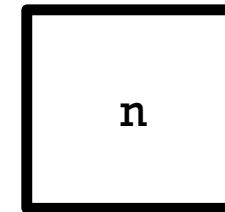
(Introduced by Weitzman79)



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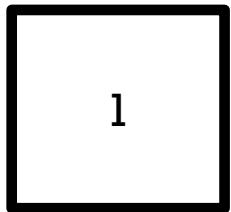


Value:  $v_i \sim D_i$

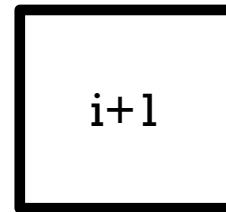
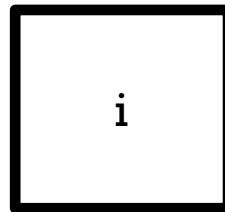


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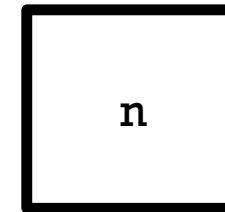
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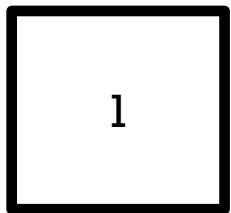
**Value:**  $v_i \sim D_i$

**Cost:**  $c_i$

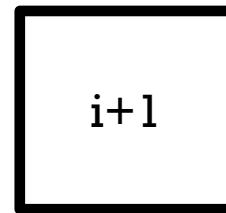
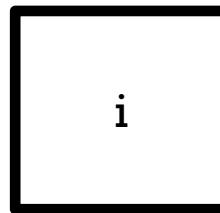


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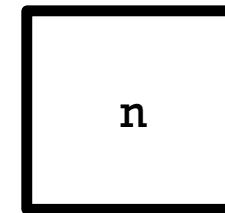
(Introduced by Weitzman79)



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**Value:**  $v_i \sim D_i$

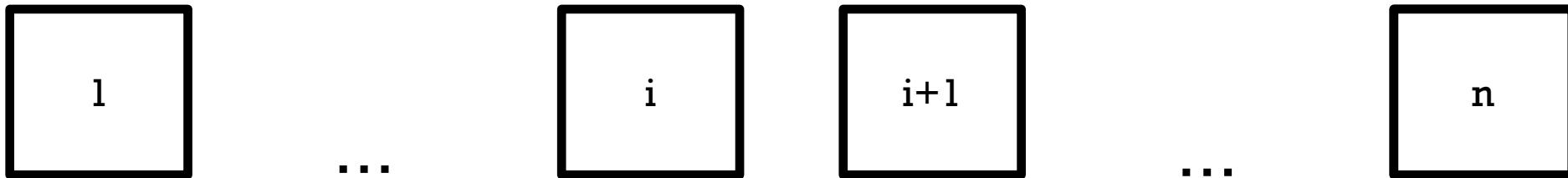
**Cost:**  $c_i$

The agent can inspect boxes in any order they like, and their goal is to maximize their  
Expected Utility =  $E[\text{value of selected box} - \text{sum of inspection costs}]$



# PANDORA'S BOX PROBLEM

(Introduced by Weitzman79)



**Value:**  $v_i \sim D_i$

**Cost:**  $c_i$

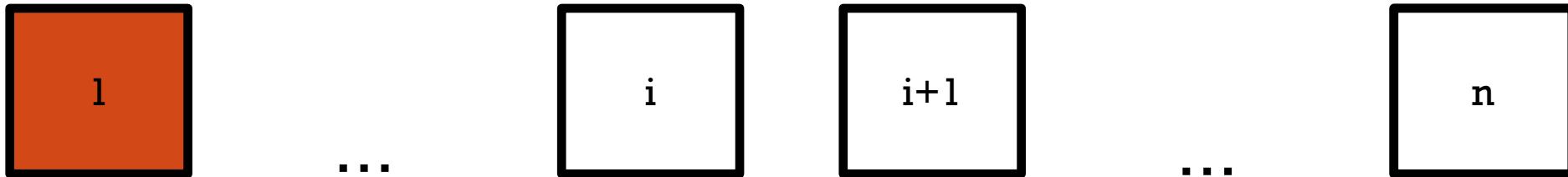
The agent can inspect boxes in any order they like, and their goal is to maximize their  
Expected Utility =  $E[\text{value of selected box} - \text{sum of inspection costs}]$

*The agent must inspect a box before selecting it*



# PANDORA'S BOX PROBLEM

(Introduced by Weitzman79)



value = 2

cost = 1

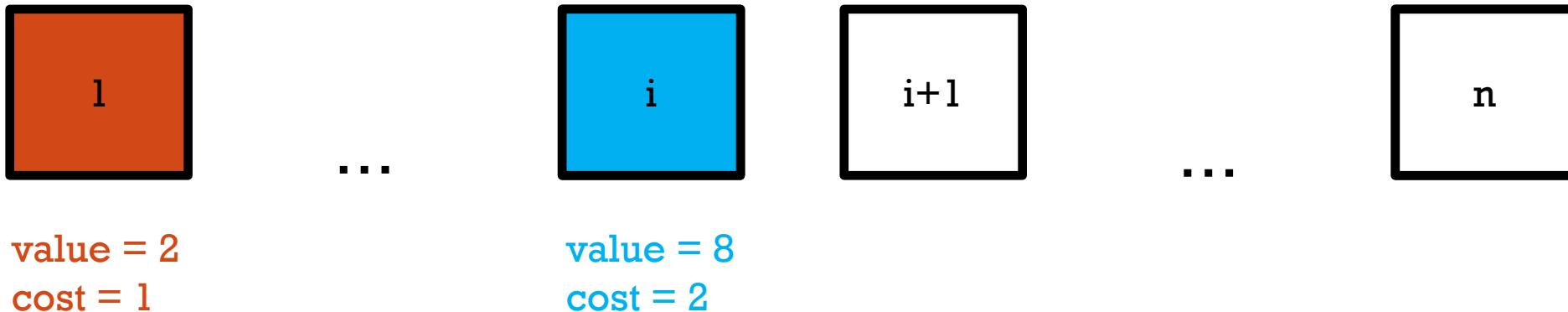
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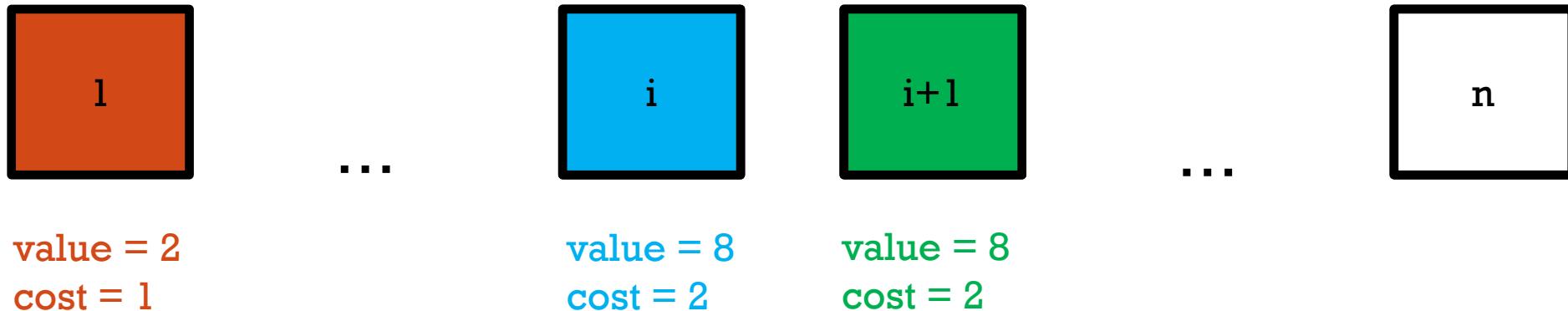
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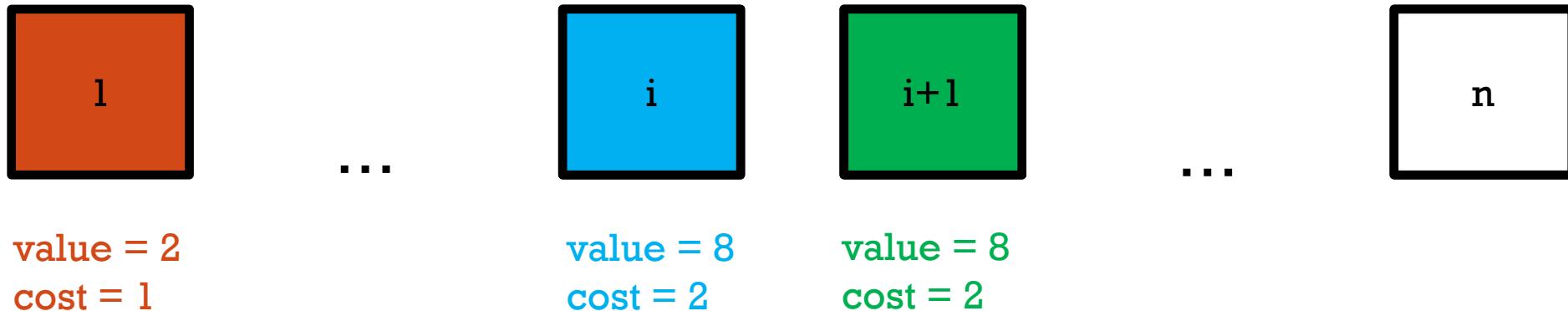
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Expected Utility =  $E[\text{value of selected box} - \text{sum of inspection costs}]$

*The agent must inspect a box before selecting it*



# PANDORA'S BOX PROBLEM

(Introduced by Weitzman79)



$$\text{Utility} = \max(\text{value}) - \sum(\text{cost}) = \max(2, 8, 8) - (1 + 2 + 2) = 3$$

The agent can inspect boxes in any order they like, and their goal is to maximize their  
Expected Utility =  $E[\text{value of selected box} - \sum \text{of inspection costs}]$

*The agent must inspect a box before selecting it*

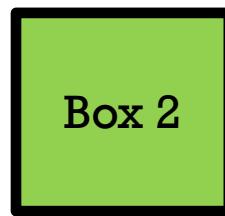


# PANDORA'S BOX: EXAMPLE



$$v_1 = \begin{cases} \frac{1}{\epsilon} \text{ w. p. } \epsilon \\ 0 \text{ w. p. } 1 - \epsilon \end{cases}$$

$$c_1 = 1/2$$



$$v_2 = \begin{cases} 1 \text{ w. p. } 1/2 \\ 0 \text{ w. p. } 1/2 \end{cases}$$

$$c_2 = \epsilon$$



# PANDORA'S BOX: EXAMPLE

$$\text{Box 1}$$
$$v_1 = \begin{cases} \frac{1}{\epsilon} \text{ w. p. } \epsilon \\ 0 \text{ w. p. } 1 - \epsilon \end{cases}$$
$$\text{Box 2}$$
$$v_2 = \begin{cases} 1 \text{ w. p. } \frac{1}{2} \\ 0 \text{ w. p. } \frac{1}{2} \end{cases}$$
$$c_1 = 1/2$$
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**Optimal algorithm:** open box 1 first, then open box 2 only when the value of box 1 is 0



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$$v_1 = \begin{cases} \frac{1}{\epsilon} & \text{w. p. } \epsilon \\ 0 & \text{w. p. } 1 - \epsilon \end{cases}$$
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$$v_2 = \begin{cases} 1 & \text{w. p. } \frac{1}{2} \\ 0 & \text{w. p. } \frac{1}{2} \end{cases}$$
$$c_1 = 1/2$$
$$c_2 = \epsilon$$

**Optimal algorithm:** open box 1 first, then open box 2 only when the value of box 1 is 0

## Observation:

- If we see a high value from box 1, there is no need to open box 2



# PANDORA'S BOX: EXAMPLE

The diagram illustrates the Pandora's Box problem with two boxes, Box 1 and Box 2. Box 1 is orange and Box 2 is green. The value distribution for Box 1 is given by  $v_1 = \begin{cases} \frac{1}{\epsilon} & \text{w. p. } \epsilon \\ 0 & \text{w. p. } 1 - \epsilon \end{cases}$ . The value distribution for Box 2 is given by  $v_2 = \begin{cases} 1 & \text{w. p. } \frac{1}{2} \\ 0 & \text{w. p. } \frac{1}{2} \end{cases}$ . Below the distributions, the costs are listed as  $c_1 = 1/2$  and  $c_2 = \epsilon$ .

$$v_1 = \begin{cases} \frac{1}{\epsilon} & \text{w. p. } \epsilon \\ 0 & \text{w. p. } 1 - \epsilon \end{cases}$$
$$c_1 = 1/2$$
$$v_2 = \begin{cases} 1 & \text{w. p. } \frac{1}{2} \\ 0 & \text{w. p. } \frac{1}{2} \end{cases}$$
$$c_2 = \epsilon$$

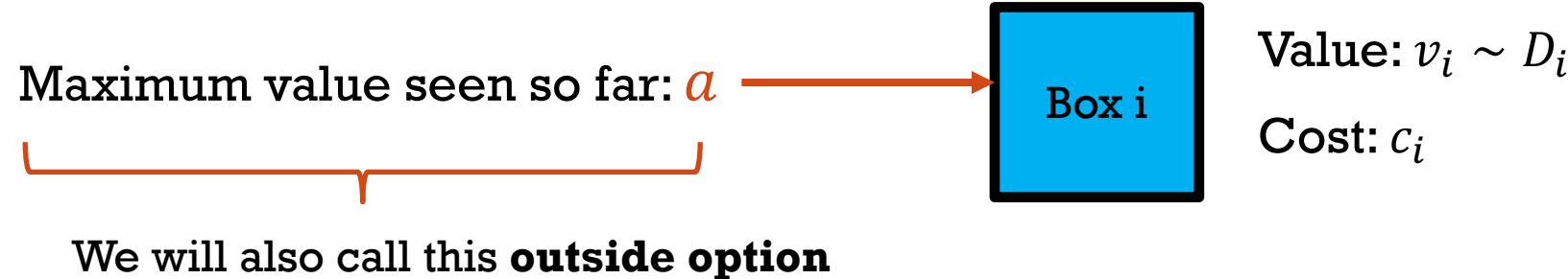
**Optimal algorithm:** open box 1 first, then open box 2 only when the value of box 1 is 0

## Observation:

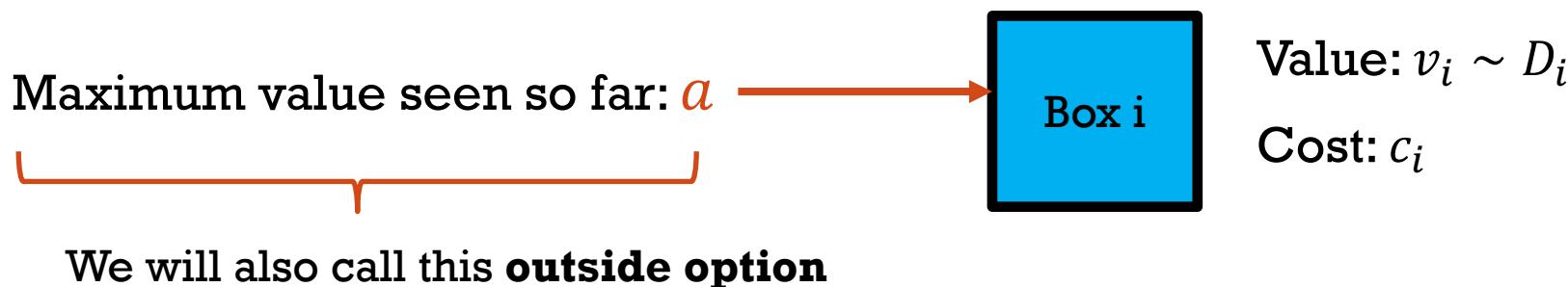
- If we see a high value from box 1, there is no need to open box 2
- No matter what value we see from box 2, we still want to open box 1



# PANDORA'S BOX: WHEN IS IT WORTH OPENING THE BOX



# PANDORA'S BOX: WHEN IS IT WORTH OPENING THE BOX



Observation: given the outside option  $a$ , we should open box  $i$  only when *the expected marginal increase in value exceeds the cost*.



# PANDORA'S BOX: WHEN IS IT WORTH OPENING THE BOX



We will also call this **outside option**

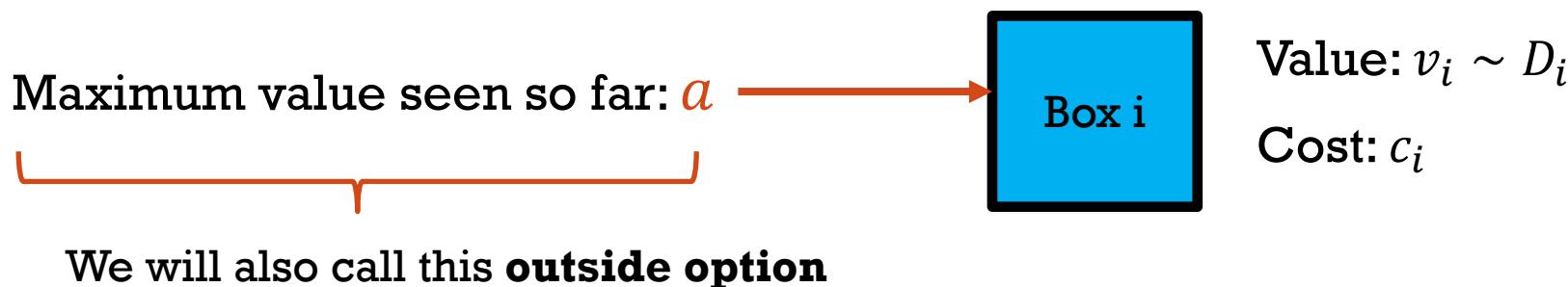
Observation: given the outside option  $a$ , we should open box  $i$  only when *the expected marginal increase in value exceeds the cost.*

If we don't open the box: value =  $a$

cost = 0



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If we open the box: value =  $\max(a, v_i)$   
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If we open the box: value =  $\max(a, v_i)$   
cost =  $c_i$

Box  $i$  is worth opening only when  $E[\max(v_i, a)] - a > c_i$   
 $\Leftrightarrow E[\max(v_i - a, 0)] = E[(v_i - a)^+] > c_i$



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 $\Leftrightarrow E[\max(v_i - a, 0)] = E[(v_i - a)^+] > c_i$

We will call  $\sigma_i$  such that  $E[(v_i - \sigma_i)^+] = c_i$  **the strike price**



# PANDORA'S BOX: OPTIMAL POLICY [WEITZ79]



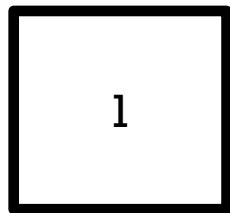
**Value:**  $v_i \sim D_i$

**Cost:**  $c_i$

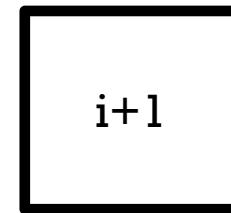
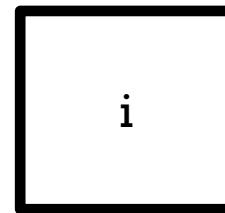
**Strike price:**  $\sigma_i$  such that  $E[(v_i - \sigma_i)^+] = c_i$



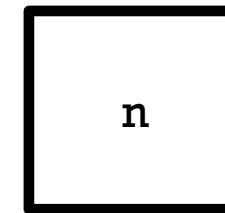
# PANDORA'S BOX: OPTIMAL POLICY [WEITZ79]



...



...



**Value:**  $v_i \sim D_i$

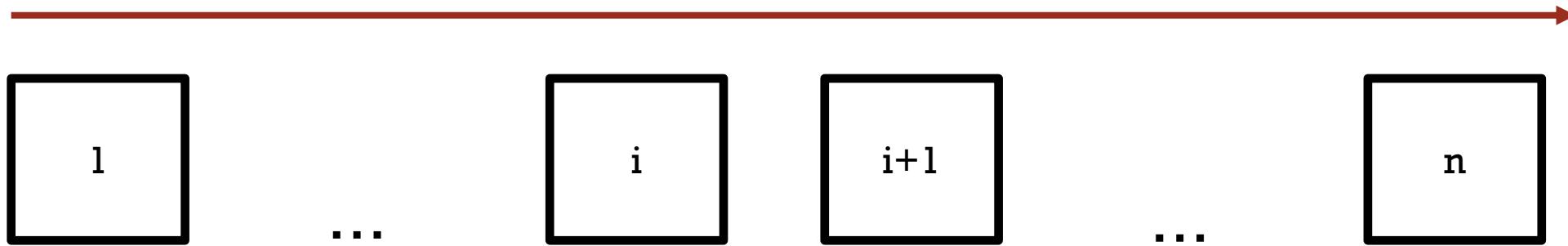
**Cost:**  $c_i$

**Strike price:**  $\sigma_i := E[(v_i - \sigma_i)^+] = c_i$



# PANDORA'S BOX: OPTIMAL POLICY [WEITZ79]

Reorder in decreasing value of **strike price**  $\sigma: \sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n$



**Value:**  $v_i \sim D_i$

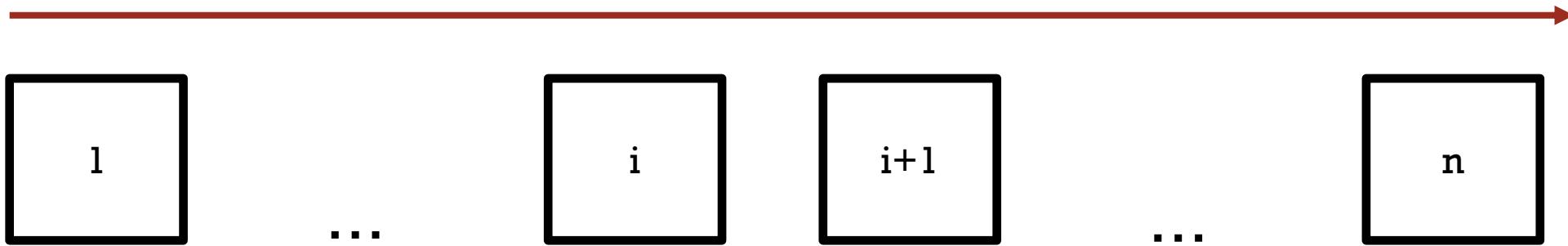
**Cost:**  $c_i$

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Reorder in decreasing value of **strike price**  $\sigma: \sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n$



Value:  $v_i \sim D_i$

Cost:  $c_i$

Strike price:  $\sigma_i := E[(v_i - \sigma_i)^+] = c_i$

Agent opens the boxes in sequential order until position  $k$  where  $\max_{i < k} v_i \geq \sigma_k$ ,  
in which case the agent stops and returns the maximum value they have seen so far.



# PANDORA'S BOX: IS INSPECTION NECESSARY?



# PANDORA'S BOX: IS INSPECTION NECESSARY?

Super busy person who needs a car the next day:



# PANDORA'S BOX: IS INSPECTION NECESSARY?

Super busy person who needs a car the next day:



What about just ... wing it?



# PANDORA'S BOX: IS INSPECTION NECESSARY?



# PANDORA'S BOX: IS INSPECTION NECESSARY?

International student: campus visits are too costly and time consuming



# PANDORA'S BOX: IS INSPECTION NECESSARY?

International student: campus visits are too costly and time consuming



**It's a great school, let's just go!**



# GIVING THE AGENT THE FREEDOM OF CHOICE



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- [GMS08] Information Acquisition and Exploitation in Multichannel Wireless Networks.



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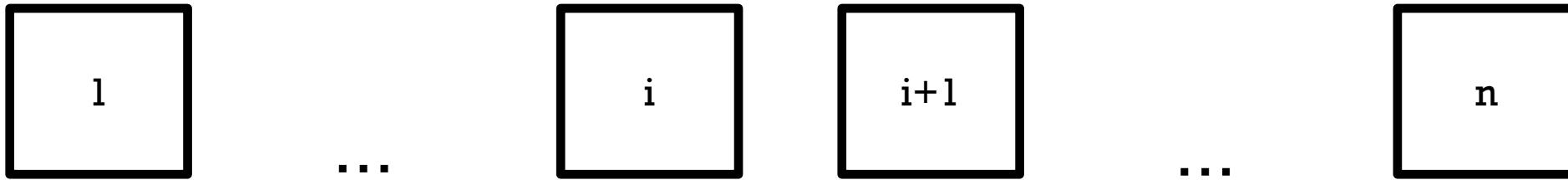
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## PANDORA'S BOX PROBLEM WITH NON-OBLIGATORY INSPECTION



# PANDORA'S BOX WITH NON-OBLIGATORY INSPECTION (PNOI)

(Introduced independently by GMS08, CL09, AKLS17, Dov18)



**Value:**  $v_i \sim D_i$

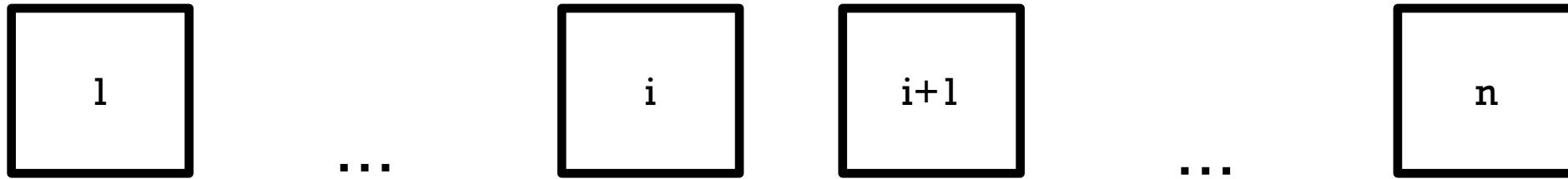
**Cost:**  $c_i$

The agent can inspect boxes in any order they like, and their goal is to maximize their  
Expected Utility =  $E[\text{Value of selected box} - \text{sum of inspection costs}]$



# PANDORA'S BOX WITH NON-OBLIGATORY INSPECTION (PNOI)

(Introduced independently by GMS08, CL09, AKLS17, Dov18)



**Value:**  $v_i \sim D_i$

**Cost:**  $c_i$

The agent can inspect boxes in any order they like, and their goal is to maximize their  
Expected Utility =  $E[\text{Value of selected box} - \text{sum of inspection costs}]$

*The agent can either inspect a box, or claim the box closed without inspection*

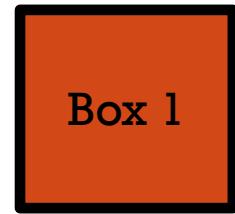


# PNOI: WHAT IS DIFFERENT

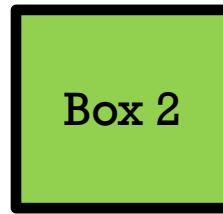
- Weitzman's policy is no longer optimal



# WEITZMAN'S POLICY IS NOT OPTIMAL



$$v_1 = \begin{cases} \frac{1}{\epsilon} \text{ w. p. } \epsilon \\ 0 \text{ w. p. } 1 - \epsilon \end{cases}$$



$$v_2 = \begin{cases} 1 \text{ w. p. } \frac{1}{2} \\ 0 \text{ w. p. } \frac{1}{2} \end{cases}$$

$$c_1 = 1/2$$

$$c_2 = \epsilon$$

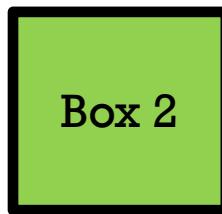


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$$c_1 = 1/2$$



$$v_2 = \begin{cases} 1 & \text{w. p. } 1/2 \\ 0 & \text{w. p. } 1/2 \end{cases}$$

$$c_2 = \epsilon$$

**Weitzman's policy:** open box 1 first, then open box 2 only when the value of box 1 is 0



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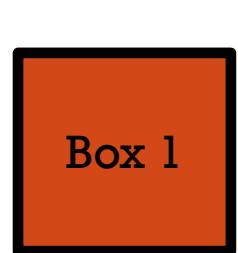
**Optimal policy in non-obligatory inspection:** open box 2 first,

$v_2 = 0 \rightarrow$  claim box 1 closed

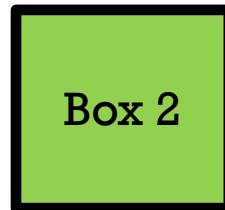
$v_2 = 1 \rightarrow$  open box 1



# WEITZMAN'S POLICY IS NOT OPTIMAL



$$v_1 = \begin{cases} \frac{1}{\epsilon} \text{ w. p. } \epsilon \\ 0 \text{ w. p. } 1 - \epsilon \end{cases}$$



$$v_2 = \begin{cases} 1 \text{ w. p. } \frac{1}{2} \\ 0 \text{ w. p. } \frac{1}{2} \end{cases}$$

$$c_1 = 1/2$$

$$c_2 = \epsilon$$

**Weitzman's policy:** open box 1 first, then open box 2 only when the value of box 1 is 0

$$\text{Agent Utility} = 1 - \frac{3\epsilon}{2} + \epsilon^2$$

**Optimal policy in non-obligatory inspection:** open box 2 first,

$$\text{Agent Utility} = \frac{5}{4} - \frac{3\epsilon}{2}$$

$v_2 = 0 \rightarrow$  claim box 1 closed  
 $v_2 = 1 \rightarrow$  open box 1

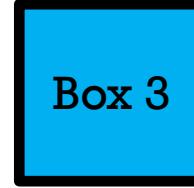
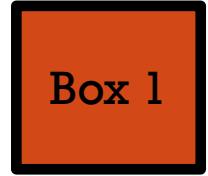


# PNOI: WHAT IS DIFFERENT

- Weitzman's policy is no longer optimal
- Adaptivity is required in the optimal policy



# ADAPTIVITY IS REQUIRED



$$v_1 = \begin{cases} \frac{1}{\epsilon} \text{ w. p. } \epsilon \\ 0 \text{ w. p. } 1 - \epsilon \end{cases}$$

$$c_1 = 1/2$$

$$v_2 = \begin{cases} 1 \text{ w. p. } \frac{1}{2} \\ 0 \text{ w. p. } \frac{1}{2} \end{cases}$$

$$c_2 = \epsilon$$

$$v_3 = \begin{cases} \frac{1}{\epsilon^2} \text{ w. p. } \epsilon^2 \\ 1 \text{ w. p. } \epsilon \\ 0 \text{ w. r. p} \end{cases}$$

$$c_3 = 1/2$$

Optimal policy in non-obligatory inspection: open box 3 first,

$$v_3 = 1/\epsilon^2 \rightarrow \text{stop}$$

$$v_3 = 1 \rightarrow \text{open box 1 first}$$

$$v_3 = 0 \rightarrow \text{open box 2 first}$$



# PNOI: WHAT IS DIFFERENT

- Weitzman's policy is no longer optimal
- Adaptivity is required in the optimal policy
- [FLL22] NP-Hardness

**Theorem** [FLL Arxiv Preprint 22\*]: Finding the optimal policy for the pandora box with non- obligatory inspection problem is NP-hard.

\*An updated version of Fu Li and Liu is accepted to STOC 2023 together with our paper.



# PNOI: APPROXIMATELY OPTIMAL

Theorem [GMS 08]:

There exists a polynomial time policy which 0.8 approximates the optimal policy.

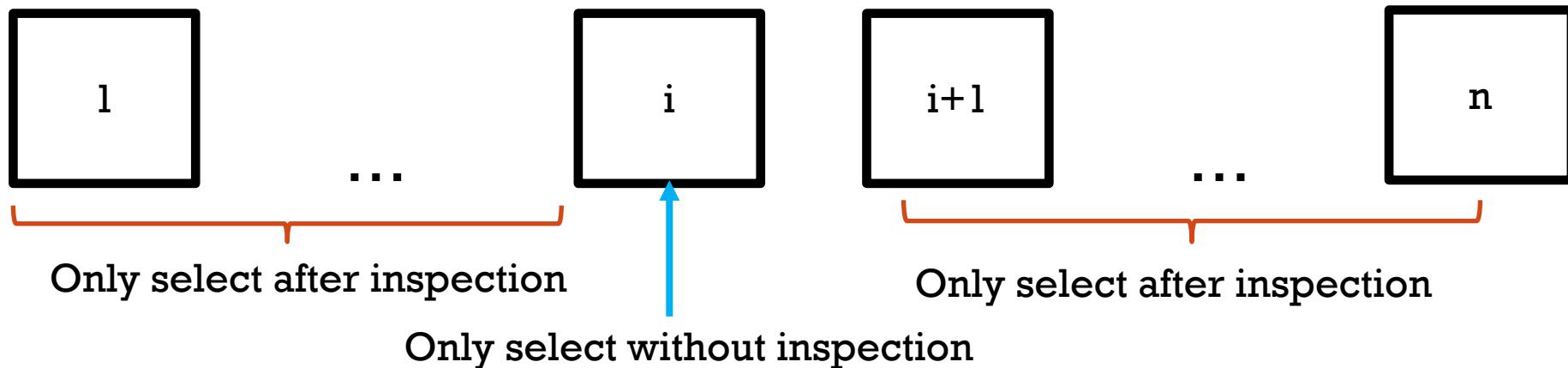


# PNOI: APPROXIMATELY OPTIMAL

Theorem [GMS 08]:

There exists a polynomial time policy which 0.8 approximates the optimal policy.

Non-adaptive order policy [BK19, GMS08]:



# PNOI: CAN WE SAY ANYTHING ABOUT THE OPTIMAL POLICY?



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Related NP-Hard problem with a structurally interesting optimal policy:

Theorem [ASZ20]:

- 1) Finding the optimal policy for the free order prophet inequality problem is NP-hard.
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- 1) Finding the optimal policy for the free order prophet inequality problem is NP-hard.
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We have just shown that for our problem adaptivity is required...

**Main Result 1\***: the optimal policy for PNOI consists of **two phases**, where in each phase, the order of visiting boxes is pre-determined and nonadaptive.

\*Also proven in an updated version of Fu Li and Liu (to appear in STOC 2023 jointly with our paper).

# PNOI: STRUCTURE OF THE OPTIMAL POLICY



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**Definition:** A **backup** box in a policy is a box that the policy sometimes claim closed without inspection.



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$$v_2 = \begin{cases} 1 \text{ w. p. } \frac{1}{2} \\ 0 \text{ w. p. } \frac{1}{2} \end{cases}$$

$$c_1 = 1/2$$

$$c_2 = \epsilon$$

Optimal policy in non-obligatory inspection: open box 2 first,

$v_2 = 0 \rightarrow$  claim box 1 closed

$v_2 = 1 \rightarrow$  open box 1



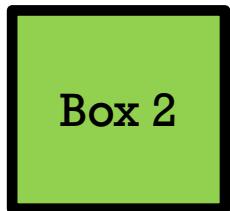
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backup box

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not a backup box

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# PNOI: STRUCTURE OF THE OPTIMAL POLICY

## **Structural Theorem [GMS08]**

There exists an optimal policy for PNOI that has *at most one* back up box.

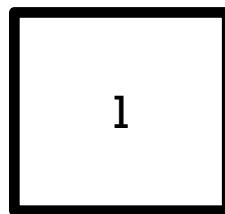


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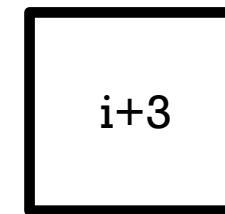
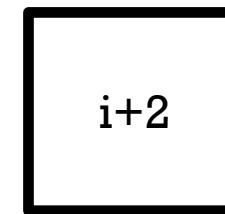
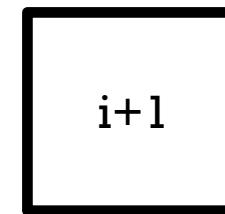
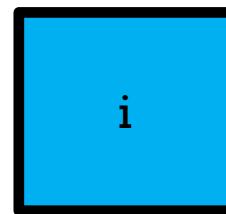
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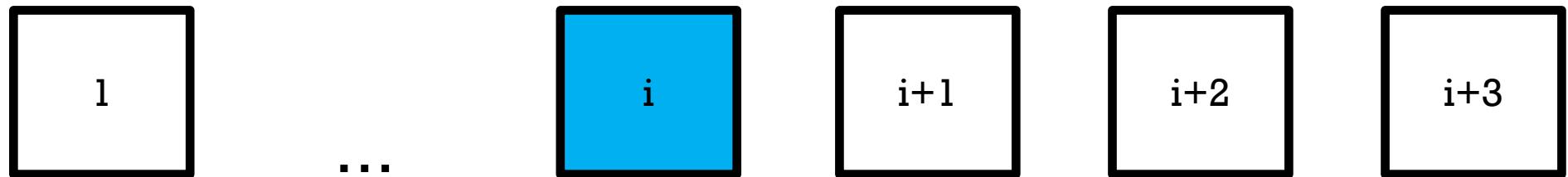


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Step two: find optimal policy given that box  $i$  is the unique backup box

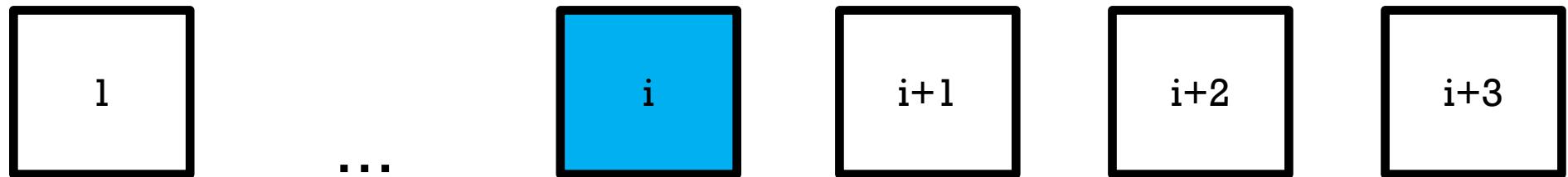


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**Note:** even after fixing the backup box, an adaptive policy could still have *exponential* number of branches, we are still not sure that PNOI is in NP



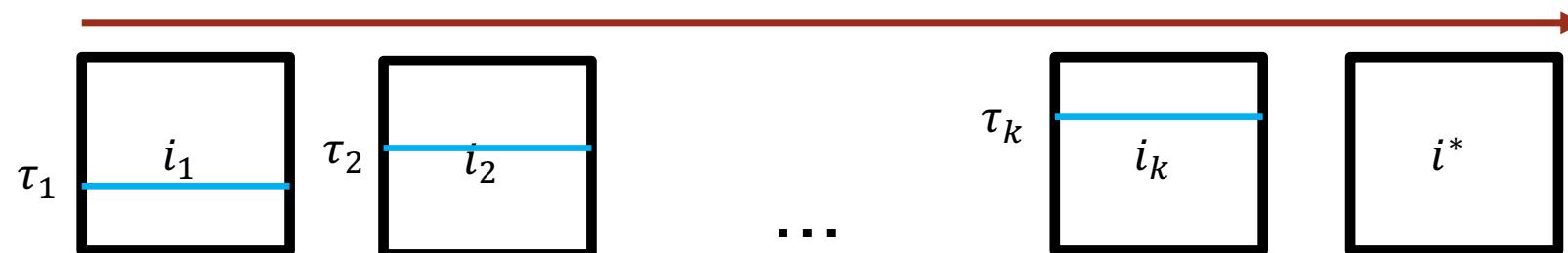
# PNOI: STRUCTURE OF THE OPTIMAL POLICY

**Main Result 1:** there exists an optimal policy in the form of the following two-phase policy.

## Policy selection:

Step one: select a back up box  $i^*$  (or choose no backup box)

Step two: fix an initial order of the boxes  $(i_1, \dots, i_k, i^*)$  and associated thresholds  $(\tau_1, \dots, \tau_k)$

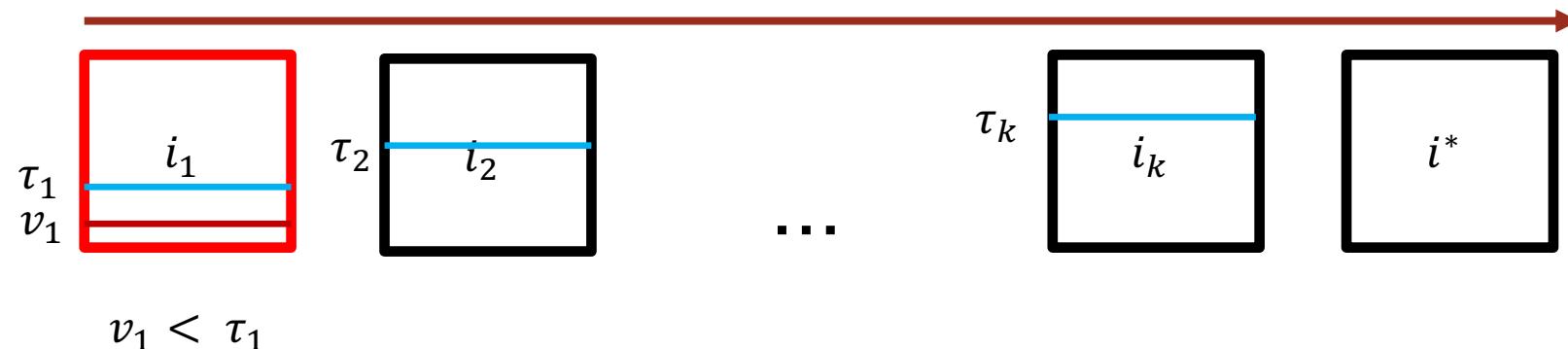


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Phase one: while all seen values are below the threshold, keep opening boxes in initial order

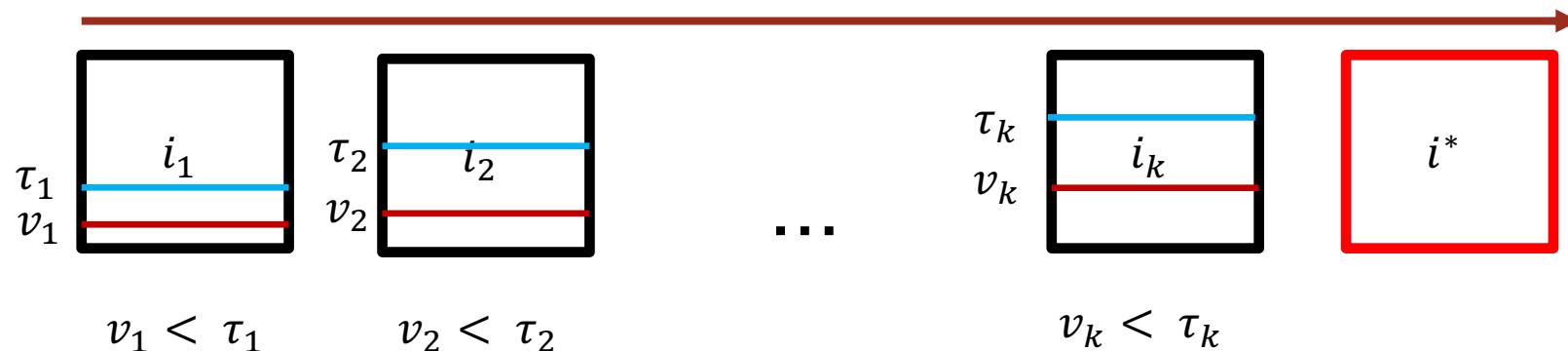


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If we reach the end of the order, claim the backup box closed without inspection.



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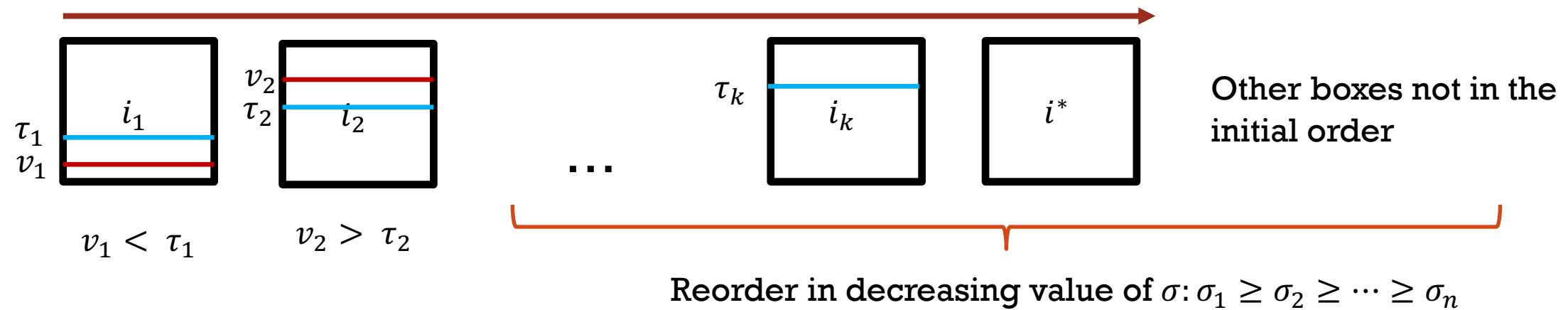


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Phase two : Once  $v_i > \tau_i$ , run Weitzman's policy on remaining boxes with outside option  $v_i$



# PNOI: STRUCTURE OF THE OPTIMAL POLICY

---

**Algorithm 1** Two-Phase Policy(InitialOrder= $i_1, \dots, i_k, i^*$ , Thresholds= $\tau_1, \dots, \tau_k$ )

---

- 1: **for**  $j = 1, \dots, k$  **do**
- 2:     Let  $\mathcal{U}_j = \mathcal{M} \setminus \{i_1, \dots, i_j\}$ .
- 3:     Open box  $i_j$ , observe value  $v_{i_j}$  from the box.
- 4:     **if**  $v_{i_j} > \tau_j$  **then**
- 5:         Run Weitzman's policy on remaining boxes from state  $(\mathcal{U}_j, v_{i_j})$ .
- 6:         **return**
- 7:     **end if**
- 8: **end for**
- 9: Claim box  $i^*$  closed.

---



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7:   end if
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**Corollary:** Pandora's box problem with non-obligatory inspection is in **NP**.



# **PROOF SKETCH OF OPTIMALITY**



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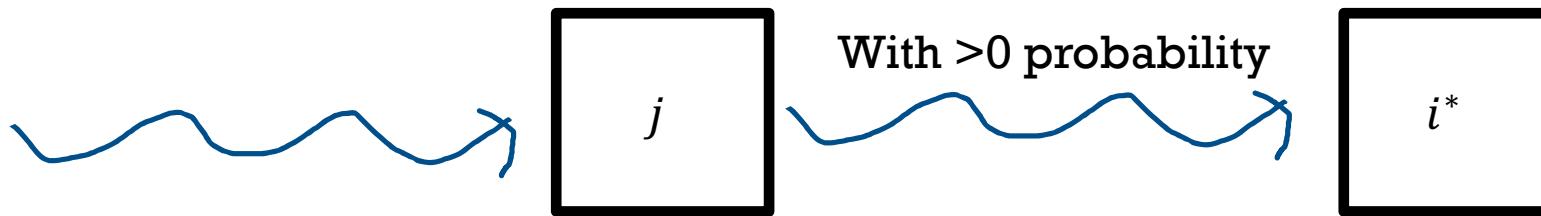
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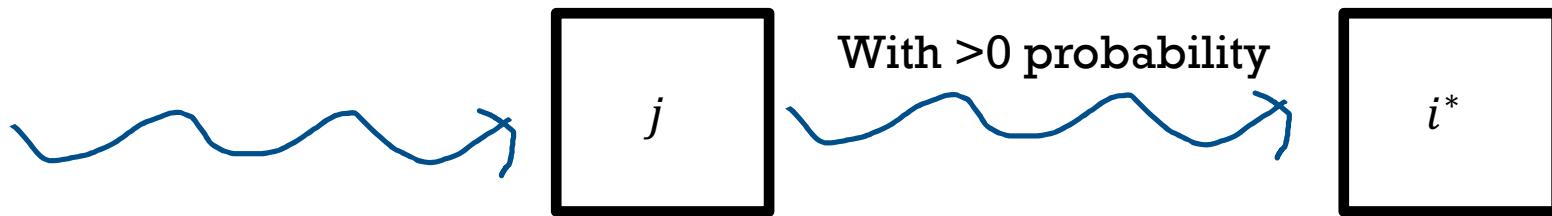
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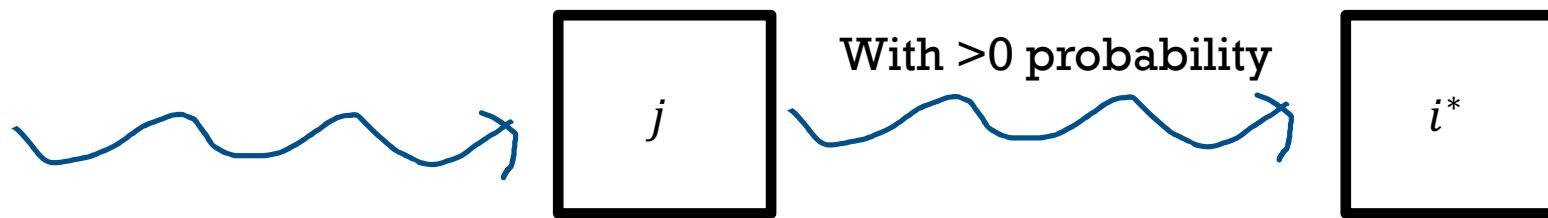
If after opening box  $j$ , we still may claim backup box closed with some probability, then:

- Either we see a value above  $v_j$  in the future
- Or we claim the box  $i^*$  closed



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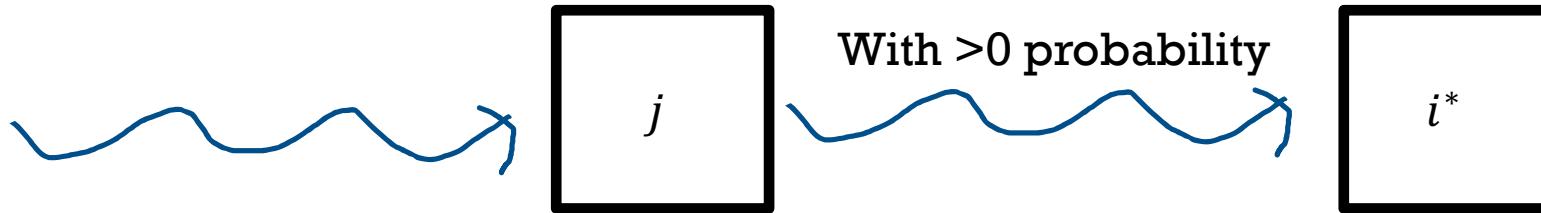
- Either we see a value above  $v_j$  in the future
- Or we claim the box  $i^*$  closed

The value of  $v_j$  is *irrelevant* to the final value we select, can pretend  $v_j = 0$



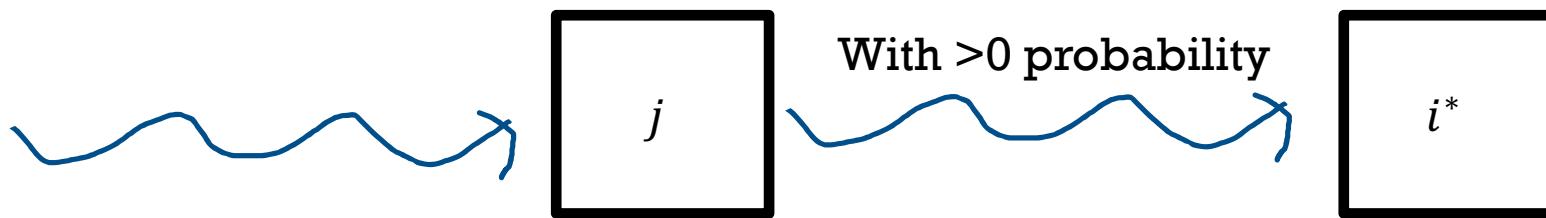
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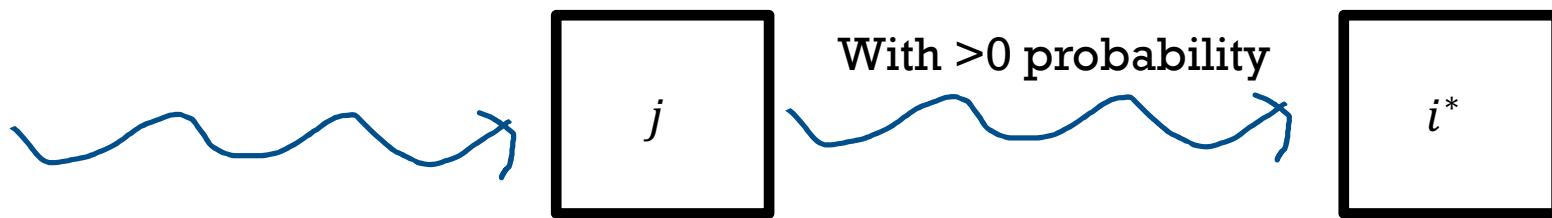


Let  $\tau_j$  be the maximum value of box  $j$  where we still sometimes claim backup box closed



# PROOF SKETCH OF OPTIMALITY

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- If the policy does not use backup box, then Weitzman policy is the optimal policy
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Let  $\tau_j$  be the maximum value of box  $j$  where we still sometimes claim backup box closed

There is an optimal policy where:

- For  $v_j \leq \tau_j$ , we always take the same future actions
- For  $v_j > \tau_j$ , backup box is NEVER claimed closed, use **Weitzman policy** for future boxes



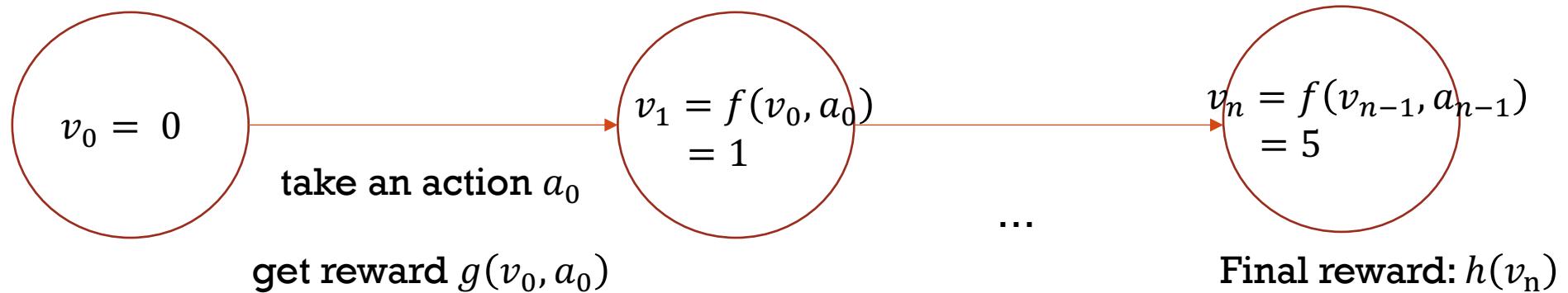
# PNOI: POLYNOMIAL TIME APPROXIMATION SCHEME

**Main result 2\***: There exists a PTAS for the Pandora's box with nonobligatory inspection problem.

- Stochastic dynamic program formulated in [FLX18] has a PTAS
- We restrict the search space to finding approximately optimal two-phase policy
- We can reduce our problem to stochastic dynamic program in [FLX18]

\*Also proven in an updated version of Fu Li and Liu (to appear in STOC 2023 jointly with our paper).

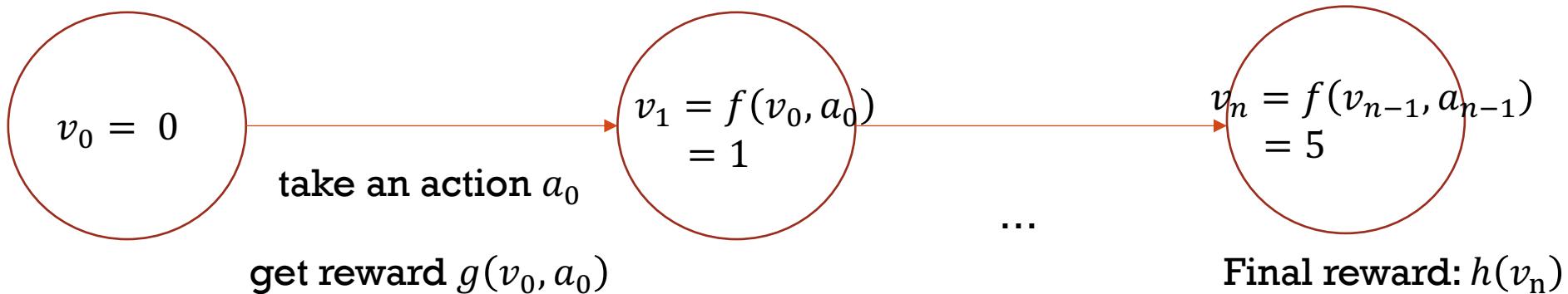
# STOCHASTIC DYNAMIC PROGRAM [FLX18]



Goal: maximize expected total reward  $\sum_{i=0}^{n-1} g(v_i, a_i) + h(v_n)$



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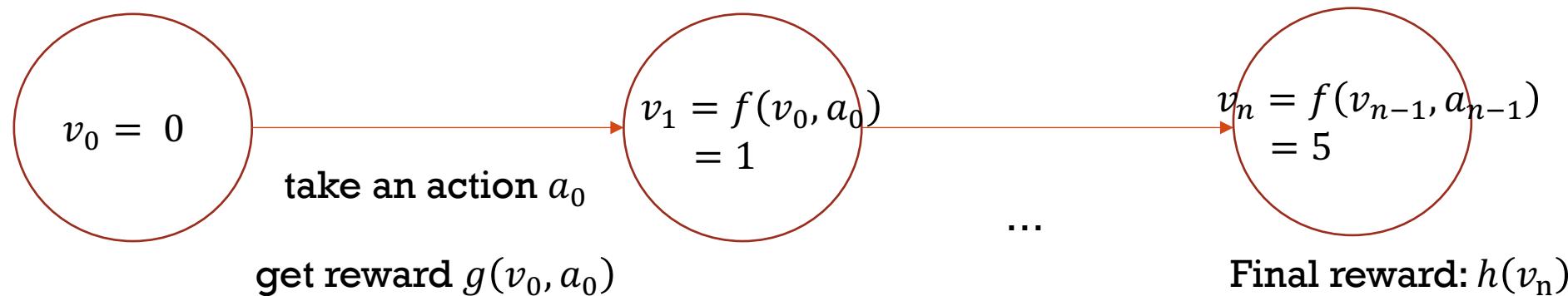
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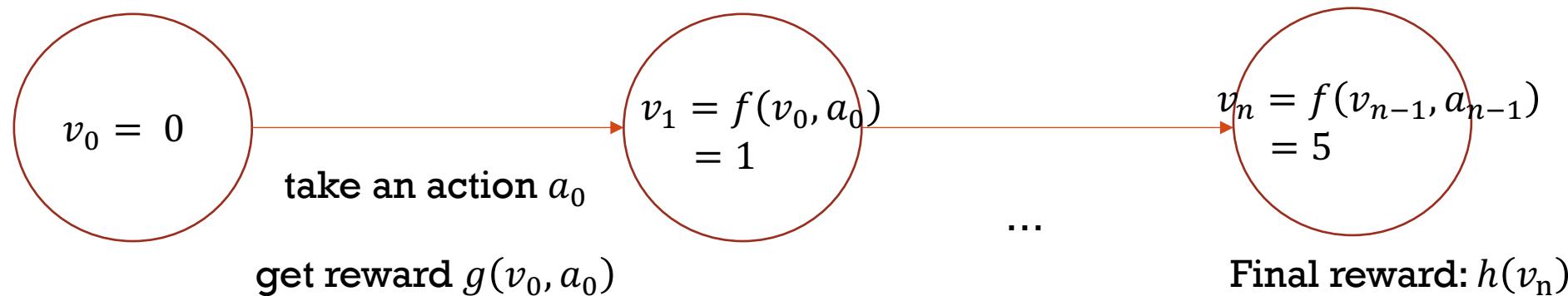
# REDUCING TO STOCHASTIC DYNAMIC PROGRAM



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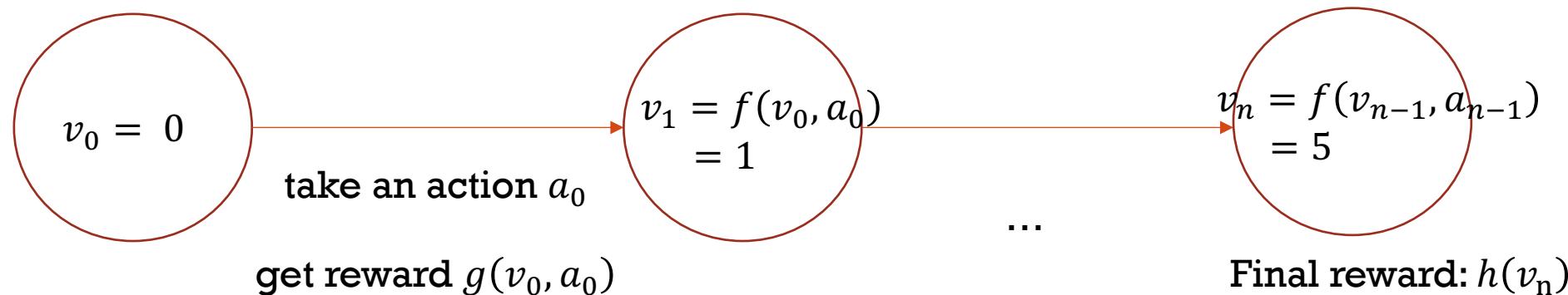


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Optimal policy can be described as  $(i_1, \dots, i_k, i^*, \tau_1, \dots, \tau_k)$



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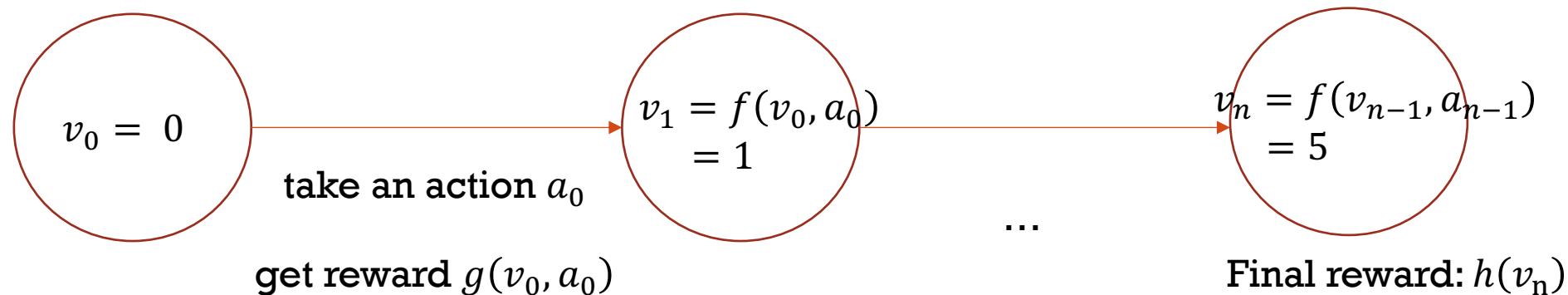
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- **Actions:** (phase one) open a box  $i$  with threshold  $\tau_i$
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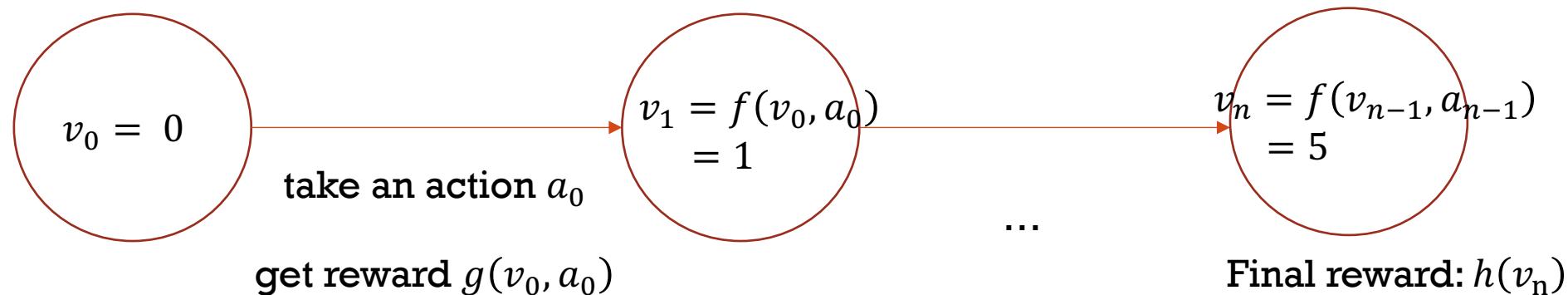
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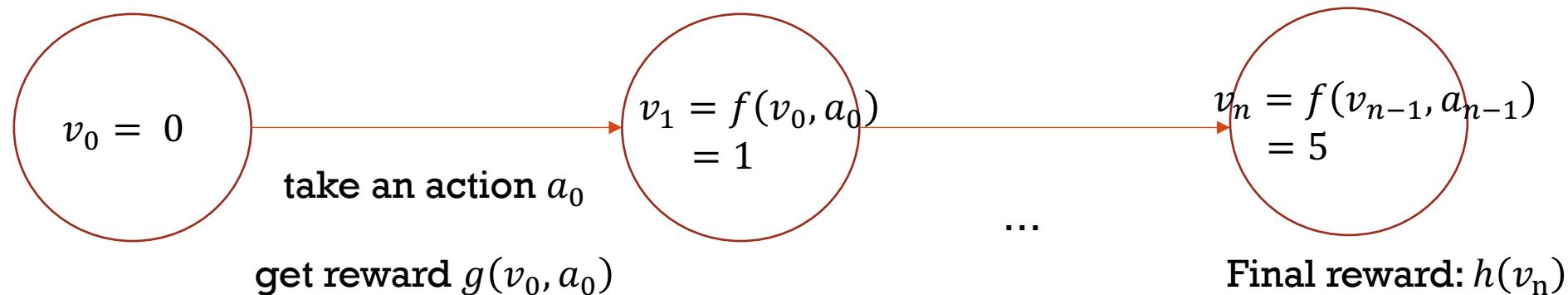
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- **Value:** the best value seen so far (0 if value is below the threshold)
- **Immediate Reward:**  $v_i - v_{\{i-1\}} - c_i$
- **Final reward:** (if we never reached phase two)  $E[v_{i^*}]$

[FLX18] There is a PTAS for any stochastic dynamic program such that

- $v_i$  increase as time step  $i$  increases
- Value and action space are of reasonable size (related to  $\epsilon$ )
- Immediate reward  $g(v_i, a_i)$  has expectation  $\geq 0$
- Final reward  $h(v_n) \geq 0$



# REDUCING TO STOCHASTIC DYNAMIC PROGRAM

Optimal policy can be described as  $(i_1, \dots, i_k, i^*, \tau_1, \dots, \tau_k)$

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- **Solution:** Reduce finding the optimal two-phase policy to an equivalent problem without cost



# REDUCING TO STOCHASTIC DYNAMIC PROGRAM

- **Challenge 1:** negative terms in reward function reflecting costs
- **Solution:** Reduce finding the optimal two-phase policy to an equivalent problem without cost
- **Challenge 2:** value space is too large to discretize in reasonable increment
- **Solution:**
  - 1) For any fixed initial ordering of boxes, we can discretize the values to a small set
  - 2) Only  $n^{\{poly(\frac{1}{\epsilon})\}}$  possible “small” sets of discretization, can try all of them



# CONCLUSION



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We show a simple two-phased structure of the optimal policy and provide a PTAS for the Pandora's box with nonobligatory inspection problem.



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- Could we model the fact that we could often inspect an option in different ways (e.g. online research, in person campus visit)?
- What would be the effect of risk aversion on the Pandora's box problem?



**THANK YOU FOR  
LISTENING!**

