

# 6.002 Math Review

Monday, September 12, 2016 7:04 AM

Linear First Order Constant Coefficient Differential Eqn.

$$Ax' + Bx = f(t) \quad A, B \text{ const}$$

(want to solve  $x(t)$ )

Superposition Principle

Suppose  $x_p$  is soln to ①  
 $\rightarrow Ax'_p + Bx_p = f(t)$

and  $x_h$  is homogeneous solution

$$Ax'_h + Bx_h = 0$$

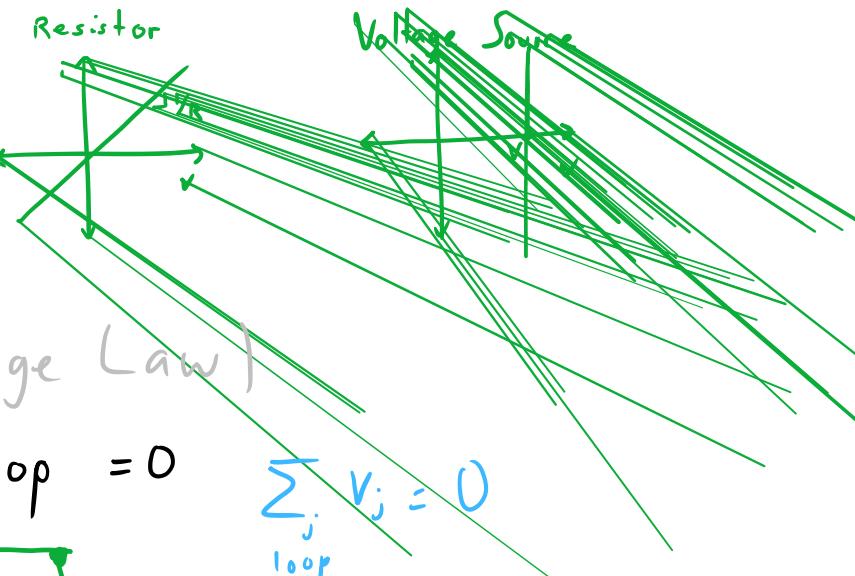
then  $x = x_p + x_h$  is solution to ①

# W1: Circuit Elements

Tuesday, September 13, 2016 10:12 AM

## Formulas:

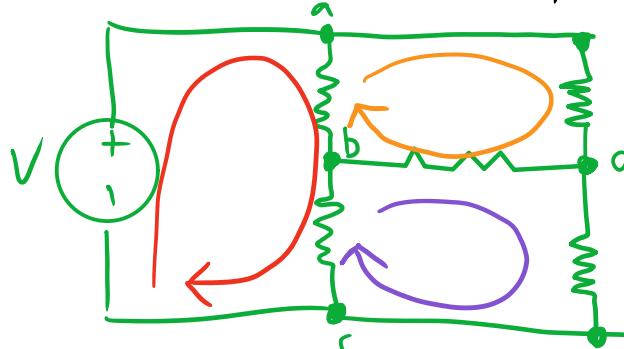
$$V = IR$$



**KVL** (Kirchoffs Voltage Law)

- Sum of voltages in loop = 0

$$\sum_j V_j = 0$$

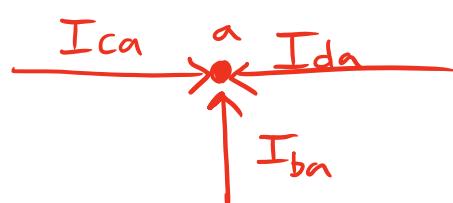


$$V_{ca} + V_{ab} + V_{bc} = 0$$

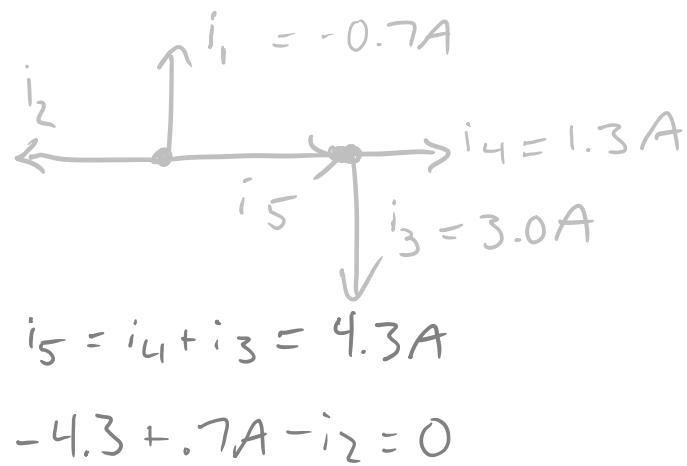
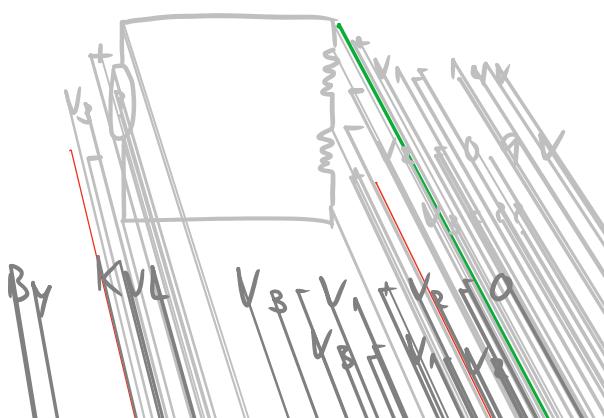
KCL

Sum of currents into node = 0

$$\sum_{\text{node}} i_i = 0$$



# Sample Problem

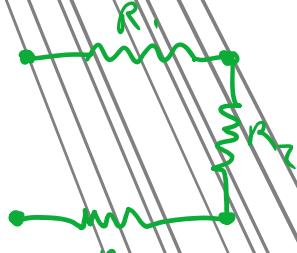


$V_B$ ,  $V_1$ ,  $V_2$

$$-4.3 + .7A - i_2 = 0$$

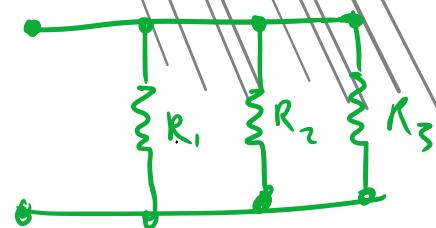
Resistors

Series:



$$R_T = R_1 + R_2 + R_3$$

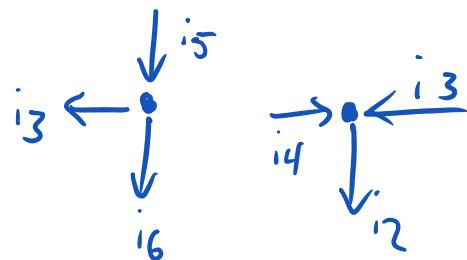
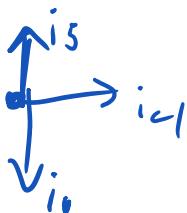
Parallel:



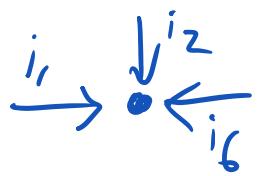
$$\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3}$$

Scratch Space

Given  $i_1, i_2, i_3$



$$-i_4 + i_2 - i_3 = 0$$
$$i_4 = i_2 - i_3$$



$$i_1 + i_2 + i_6 = 0$$

$$\Rightarrow i_6 = -i_1 - i_2$$

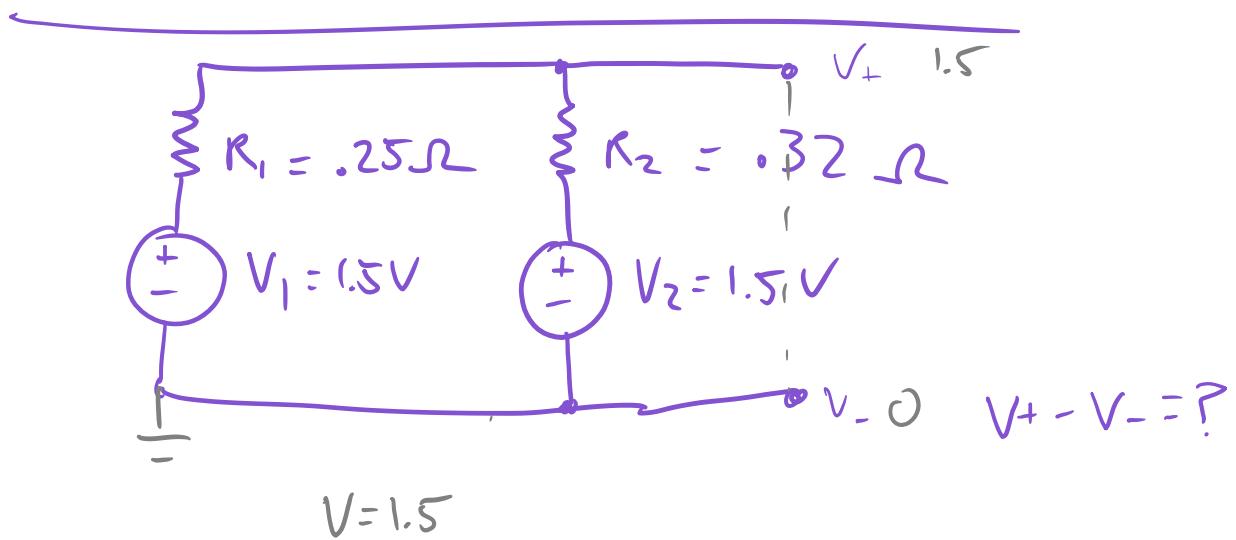
$$-i_6 = -i_1 - i_2$$

$$-i_5 - i_4 - i_6 = 0$$

$$i_5 = i_3 + i_1$$

$$i_5 = -i_4 - i_6$$

$$-i_2 + i_3 + i_1 + i_2$$



$$V = IR$$
$$I = R/V$$

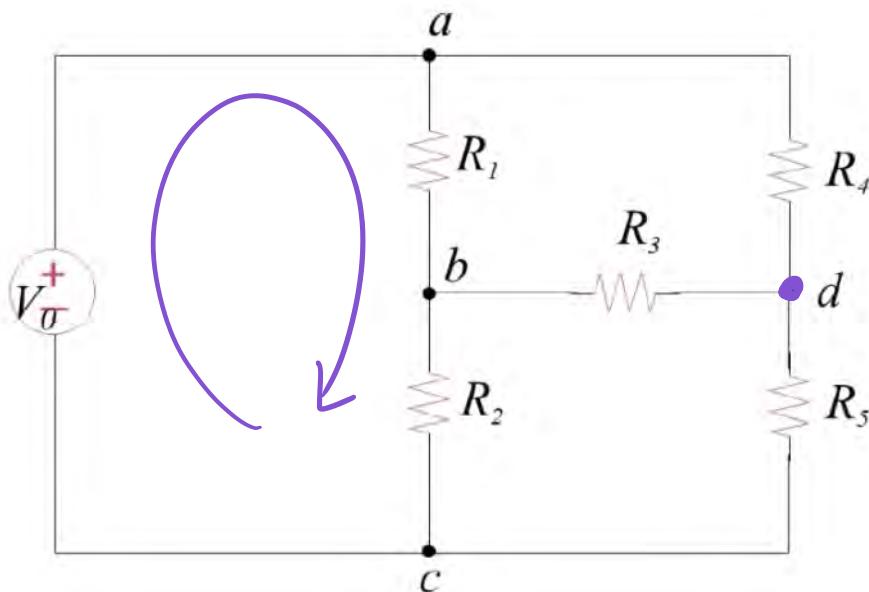
# W1: Circuit Analysis Toolset

Wednesday, September 14, 2016 1:29 PM

## Review

KVL:  $\sum_j v_j = 0$  For all loops

KCL:  $\sum_j i_j = 0$  For all nodes



KVL, KCL Method (Method 1)

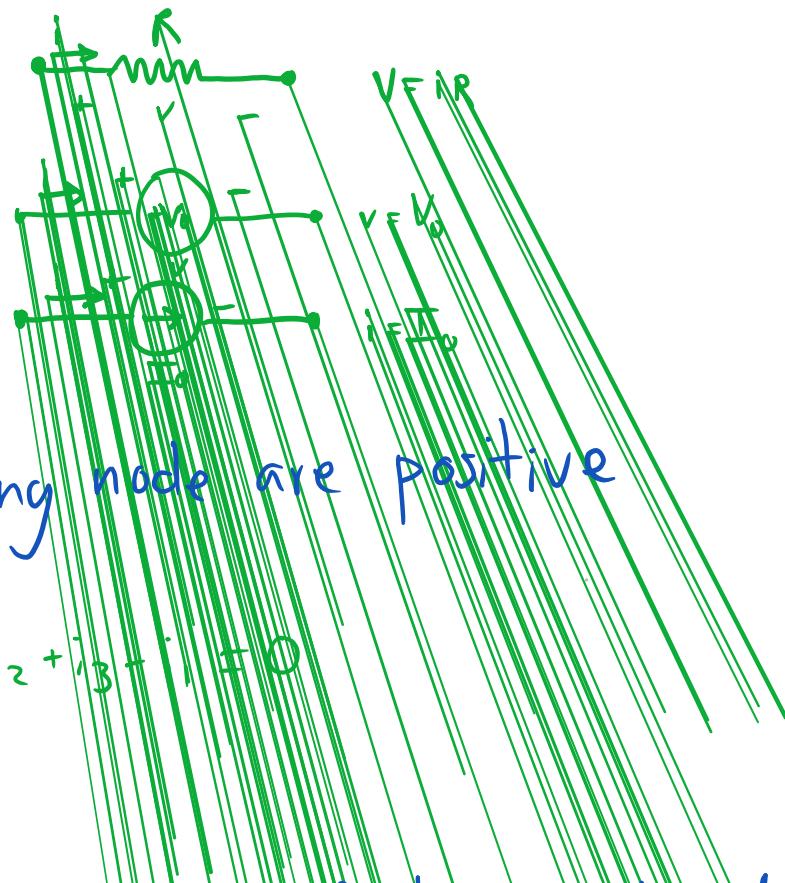
Goal: Find all elements  $v$ 's and  $i$ 's

- 1) Write element  $v-i$  relationships
- 2) Write KCL for all nodes
- 3) Write KVL for all loops
- 4) Solve eqns

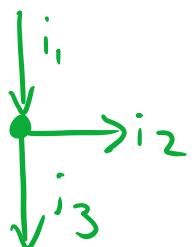
4) Solve eqns

## Conventions

Assign currents flowing into positive terminal

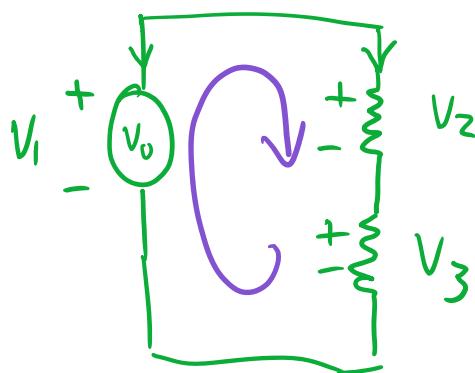


Currents leaving node are positive



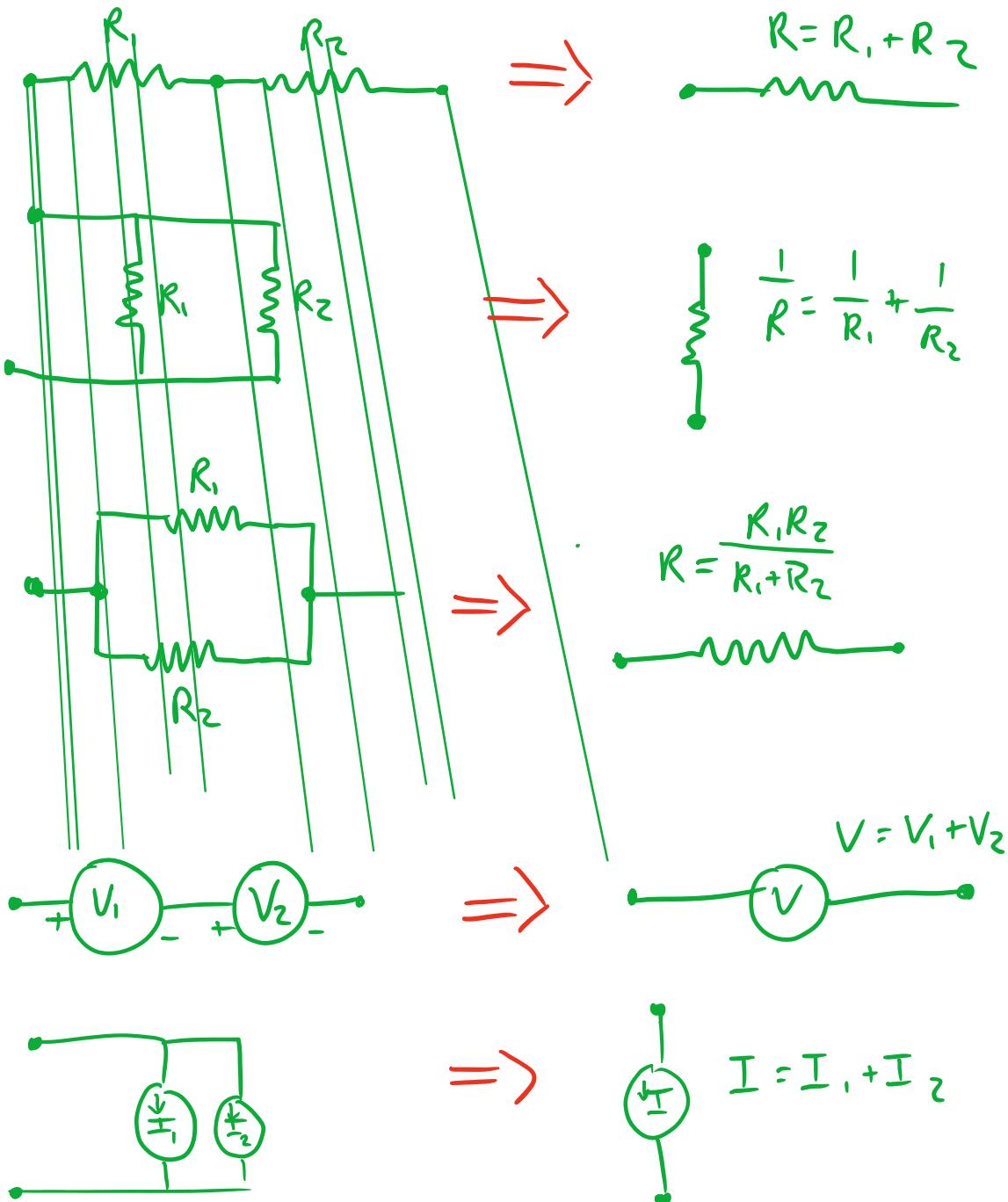
$$i_3 + i_R + i_1 \neq 0$$

In KVL, assign voltage to first encountered sign



$$-V_1 + V_2 + V_3 = 0$$

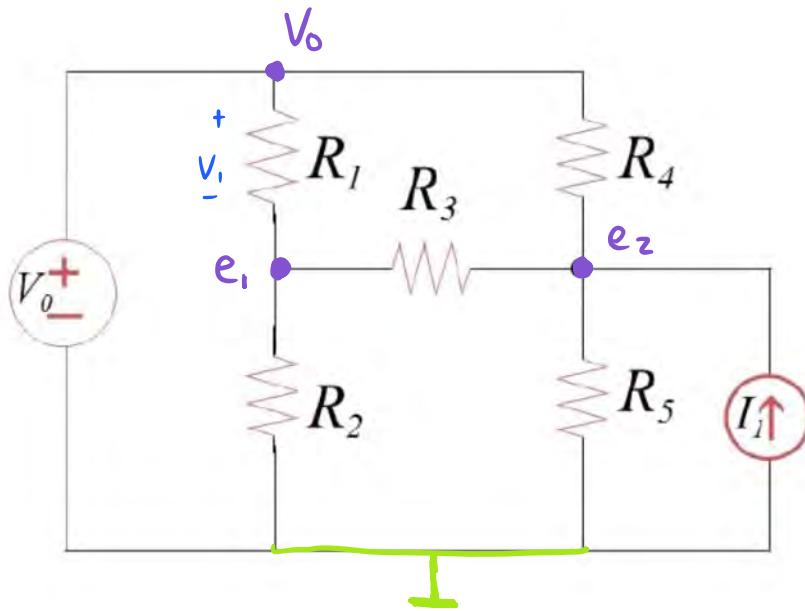
## Element Combinations (Method 2)



## Node Analysis (Method 3)

- 1) Select reference node  $\perp$  from which voltages are measured.
  - 2) Label voltages of remaining nodes w/  
respect to ground.  $\leftarrow$  primary unknowns
  - 3) Write KCL for all but ground node
  - 4) Solve for node voltages  $\begin{matrix} \text{(substituting} \\ \text{device law)} \\ \text{and KVL) } \end{matrix}$
  - 5) Back solve for branch voltages and currents
- zf5

Example:



- 1) Ground node  $\perp$

Tips: Pick with:

- Largest # of elements connected to it
- Largest # of sources connected to it

2) Label voltages .

3) Write KCL

For convenience:  $G_i = \frac{1}{R_i}$



(1)  $\underbrace{(e_1 - V_0)}_V G_1 + (e_1 - e_2) G_3 + (e_1 - 0) G_2 = 0$

$I = V/R$



(2)  $(e_2 - e_1) G_3 + (e_2 - V_0) G_4 + -I_1 + (e_2 - 0) G_5 = 0$

4) Solve voltages

1) Move constants to RHS

(1)  $e_1(G_1 + G_2 + G_3) + e_2(-G_3) = V_0 G_1$

(2)  $e_1(-G_3) + e_2(G_3 + G_4 + G_5) = V_0 G_4 + I_1$

5) Branch voltages

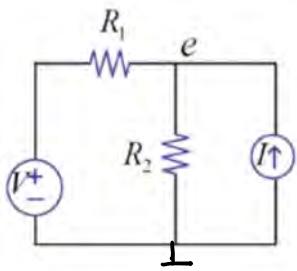
$$V_1 = V_0 - e_1$$

$$i_1 = \frac{V_1}{R_1} = \frac{V_0 - e_1}{R_1}$$

1<1

## W2: Linearity

Monday, September 19, 2016 6:45 PM



Node Method

$$\frac{e-V}{R_1} + \frac{e}{R_2} - I = 0 \quad \text{Linear!}$$

$$\Rightarrow \left[ \frac{1}{R_1} + \frac{1}{R_2} \right] e = \frac{V}{R_1} + I$$

$$\underbrace{\left[ \frac{1}{R_1} + \frac{1}{R_2} \right]}_{\text{Conductance Matrix } G} \underbrace{e}_{\text{sum of sources } S} = \underbrace{\frac{V}{R_1} + I}_{[::][::]=[::]}$$

$$e = \frac{R_2 V}{R_1 + R_2} + \frac{R_1 R_2 I}{R_1 + R_2}$$

$$e = a_1 V_1 + a_2 V_2 + \dots \quad \text{Linear}$$

Homogeneity



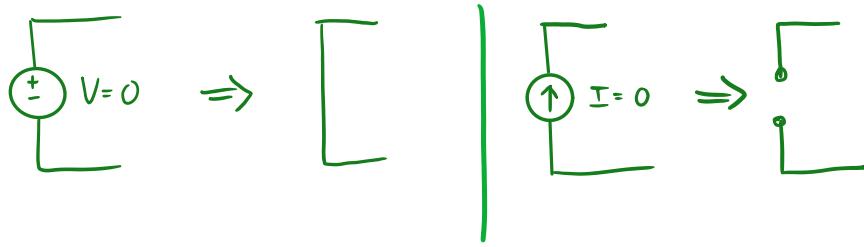
Superposition



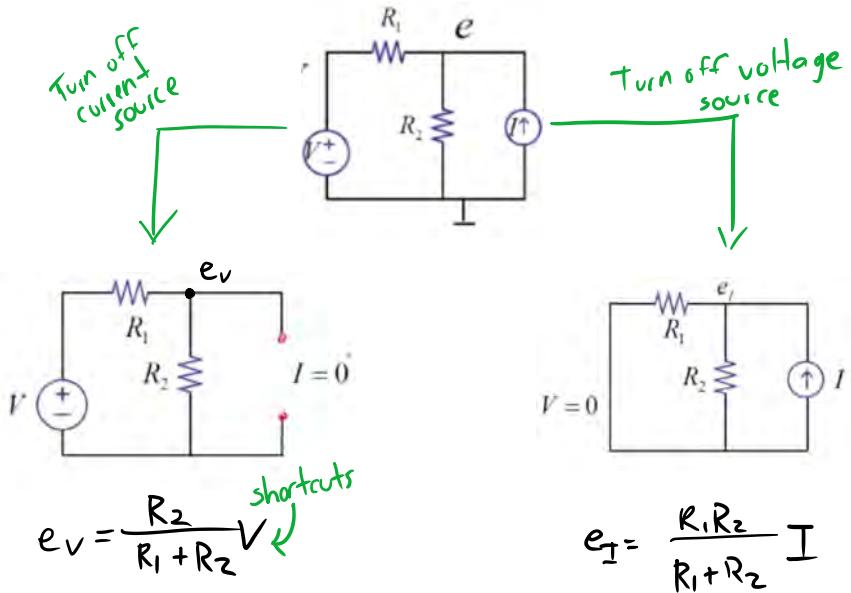
Superposition Method

1) Find responses to each source acting alone

2) Sum the individual responses

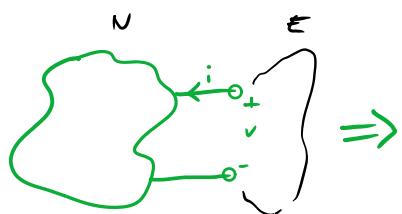


Example:



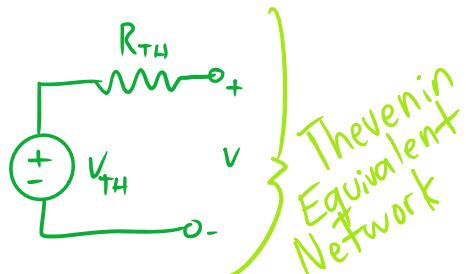
$$e = e_V + e_I = \frac{R_2}{R_1 + R_2} V + \frac{R_1 R_2}{R_1 + R_2} I$$

## Thevenin Method



$V_{TH}$

- Don't connect anything and measure voltage



$R_{TH}$

- Turn off sources and measure resistance

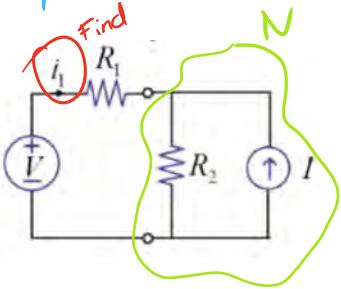
The easiest way to calculate the Thevenin resistance is to connect a short circuit to the output terminals and calculate the current through it.  $R_{th}$  is then  $V_{th}/I_{sc}$ , where  $I_{sc}$  is the short-circuit current.

- 1) Replace network N with Thevenin Equivalent
- 2) Solve external network E.

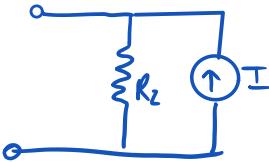
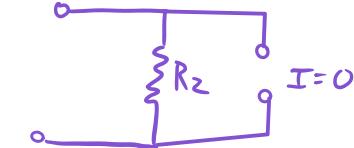
Example:

STEP 1

Example:

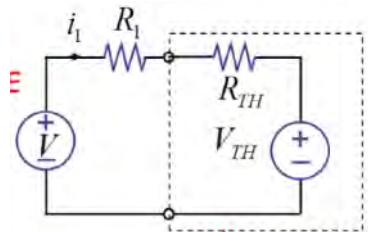


STEP 1



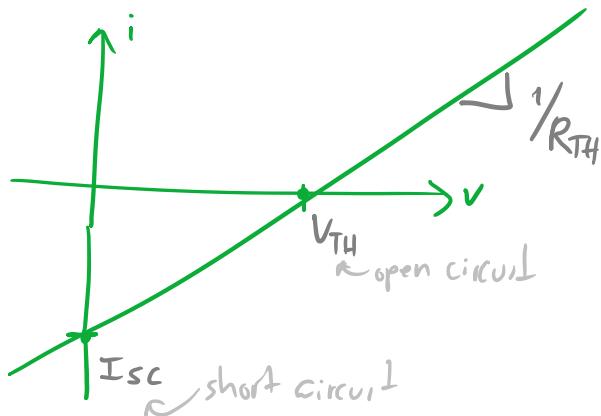
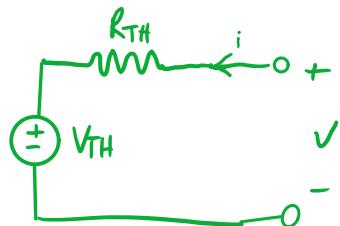
$$V_{TH} = R_2 I$$

$$R_{TH} = R_2$$

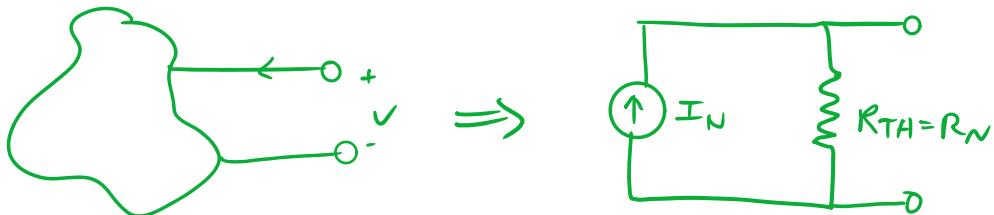


$$i_1 = \frac{V - V_{TH}}{R_1 + R_{TH}}$$

GRAPHICALLY



## Norton Method



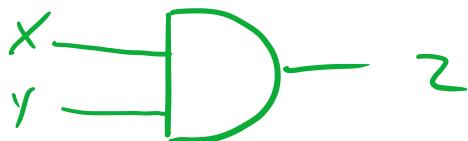
$I_N \rightarrow$  Short circuit current at port  
 $R_N \rightarrow$  Resistance seen from port with sources turned off

$\bar{R}_N$  → Resistance seen from port with sources turned off

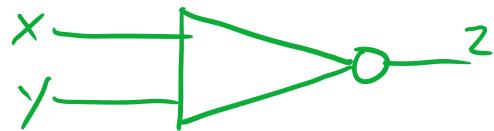
To calculate the Norton resistance, we first calculate the Thevenin voltage by leaving the output terminal as an open circuit. The circuit can be solved by the node method, but it is also possible to use the loop method. With the loop method, we get one equation for an assumed current "i" with its positive sign leaving the positive terminal of the independent source

# W2: Static Discipline and Boolean logic

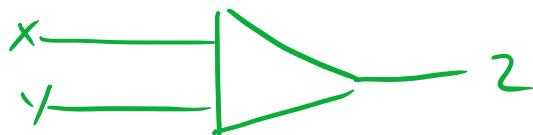
Tuesday, September 20, 2016 1:58 PM



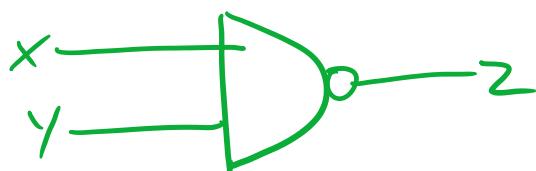
AND Gate



NOT Gate



BUFFER Gate



NAND



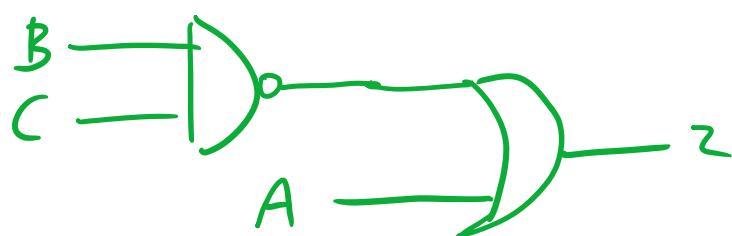
OR

Example

Implement

$$A + \overline{B \cdot C} = Z$$

NOT  
OR  
AND

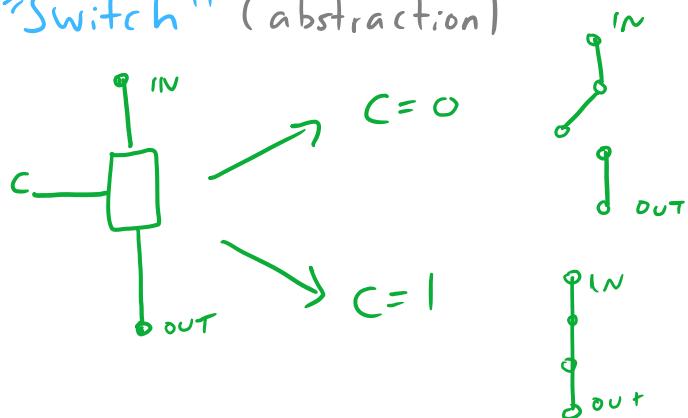


# W3: Gates

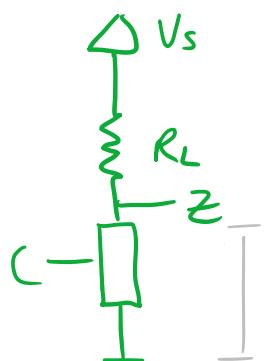
Wednesday, September 28, 2016 4:38 PM

How to build a digital gate

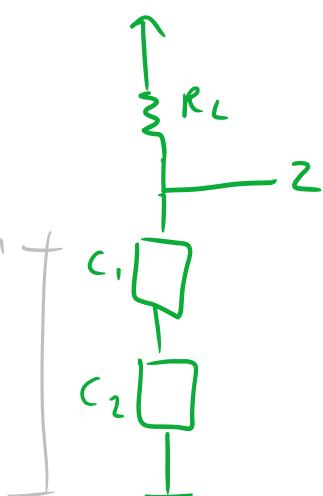
"Switch" abstraction



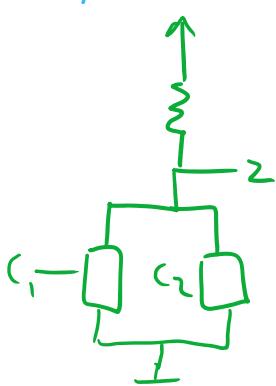
Inverter



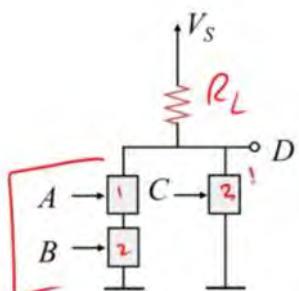
NAND



NOR



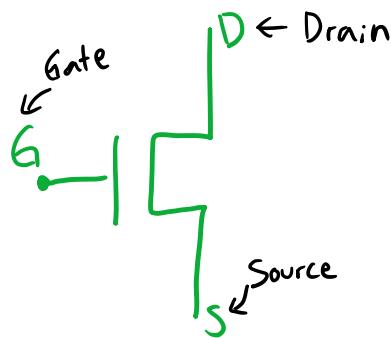
Compound Gate



$$D = \overline{(A \cdot B)} + C$$

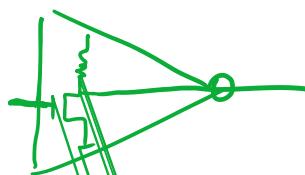
MOSFET  
Transistor

# MOSFET



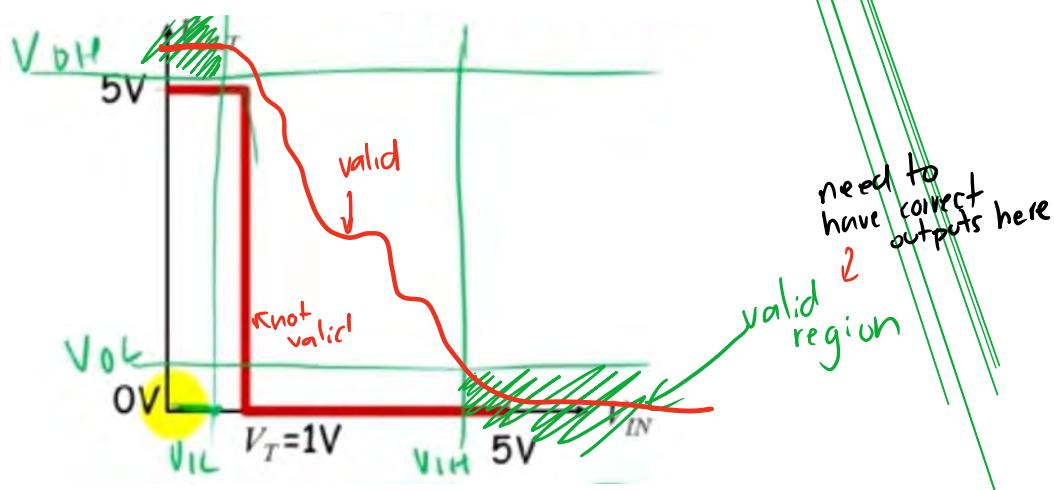
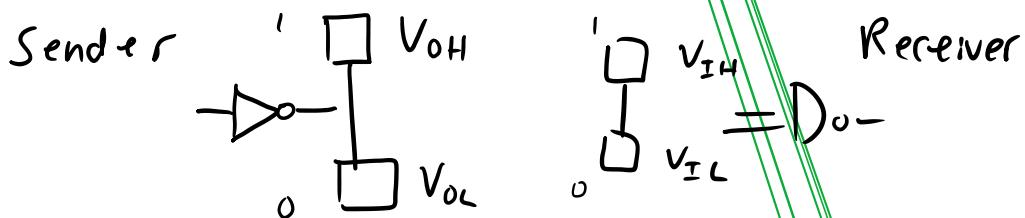
S-Model  
Can behave as a simple switch

## MosFet Inverter



## Static Discipline questions:

Make sure mosfet is "speaking the same language" so it can work with other components

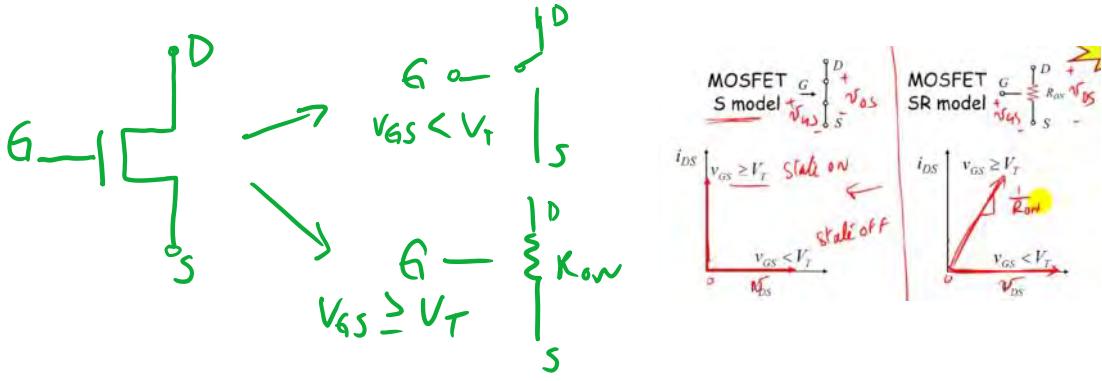


## SR- Model for MosFet

↳ More refined than S-Model

ID

↳ More refined than S-Model

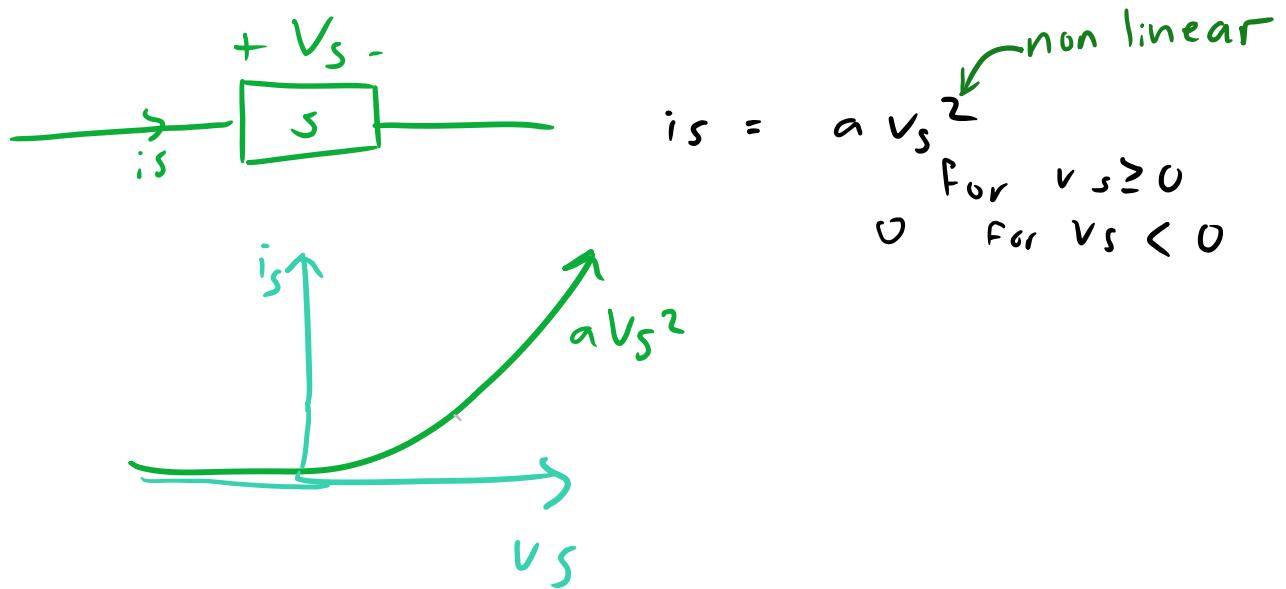


# W3: Nonlinear Elements

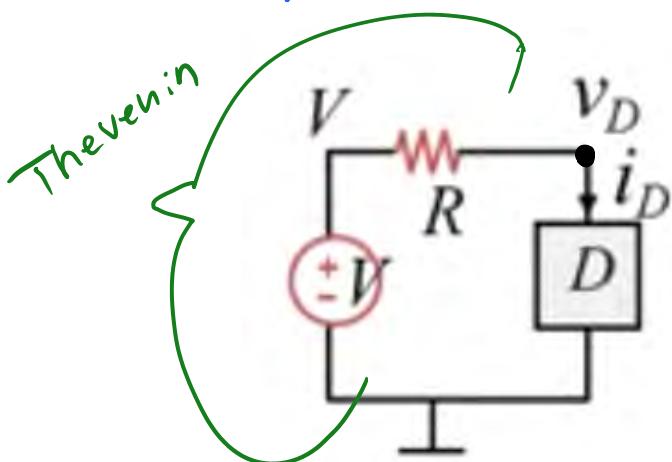
Friday, September 30, 2016 7:17 PM

Recall: Cannot use substitution or Thevenin/Norton

Non linear Element



Analytical Method (method 1)



Use Node Method

$$\frac{V_D - V}{R} + i_D \quad (1)$$

$$i_D = a e^{b v_D} \quad (2)$$

2) Solve by: Trial and error or numerical techniques

$$\Rightarrow V_D = 0.56V$$

$$i_D = a e^{b v_D}$$

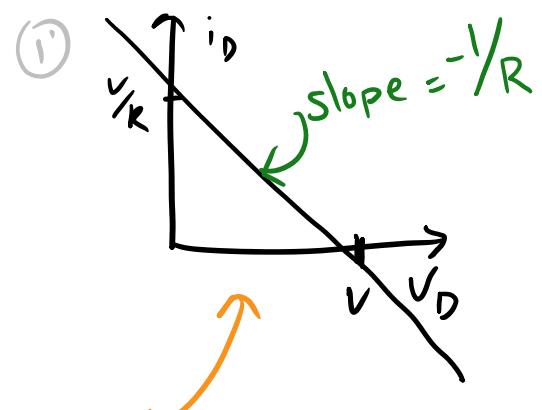
# Graphical Method (method 2)

1) Use Node Method and Graph

$$i_D = \frac{V}{R} - \frac{V_D}{R} \quad (1)$$

$$\frac{V_D - V}{R} + i_D \quad (1)$$

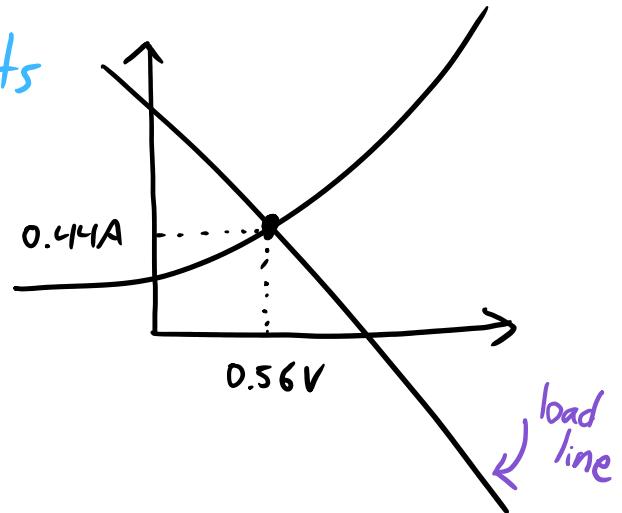
$$i_D = a e^{b V_D} \quad (2)$$



(Constraint on  $i_D$  and  $V_D$  by device)

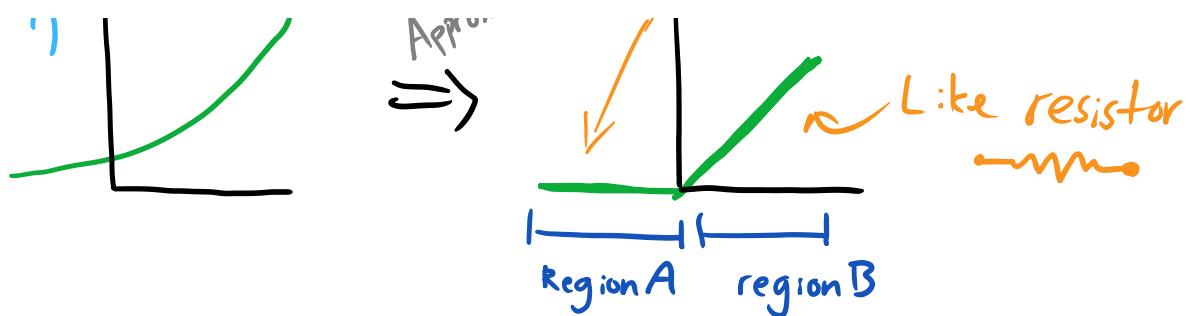
2) Combine constraints

"not as important for course"



# Piecewise Linear Method (Method 3)





- 2) Determine which of the linear region applies
- 3) Solve circuit assuming linear relation

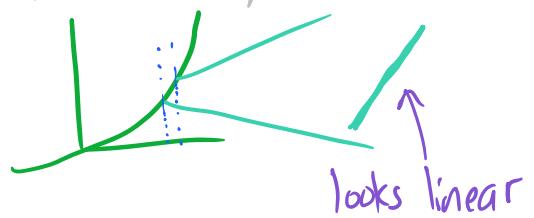
Incremental Method (method 4)  
 "small signal method"

# W4: Incremental Analysis

Saturday, October 1, 2016 8:10 PM

## Small signal Method

- Get a linear response from something non-linear by focusing on small region of operation  
Boost + Shrink

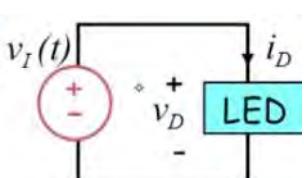


## Incremental Method

- 1) Operate at some DC offset  $V_D, I_D$
- 2) Superimpose small signal  $v_s$  on top of  $V_D$
- 3) Notice that response  $i_d$  to small signal  $v_s$  is approx linear

NOTATION:  $i_d = I_D + i_d$   
 $\uparrow \quad \uparrow$   $\curvearrowleft$  small superimposed  
Total signal DC offset signal

## Circuit View

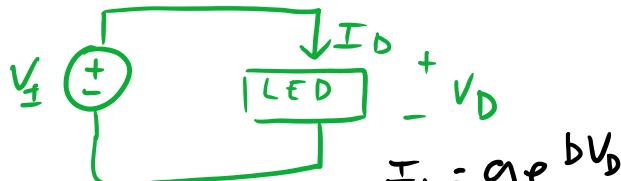


$$v_D = f(v_D) = a e^{b v_D}$$

$$I_D = a e^{b v_D}$$

$$i_d = I_D \cdot b \cdot v_d$$

- 1) Write large signal circuit



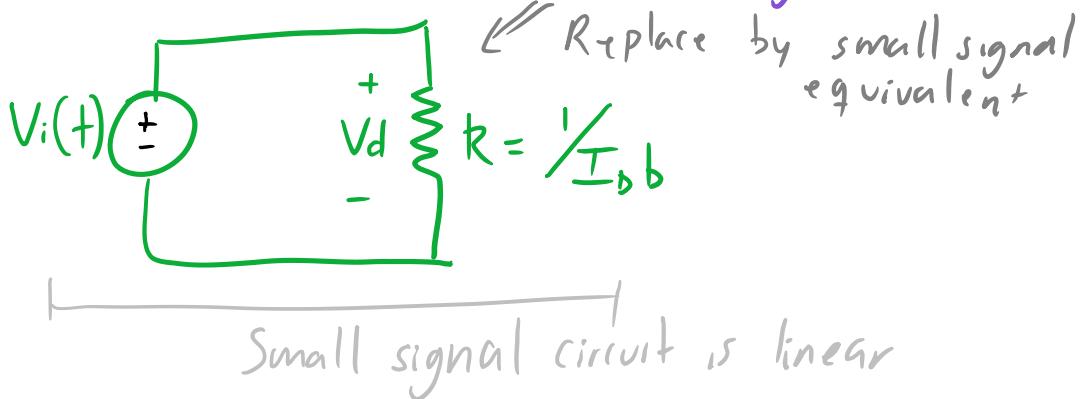
$I_D = a e^{b V_D}$   
may need to solve a  
non-linear circuit to get  $I_D$

## 2) Small Signal Response

$$i_d = I_D \cdot b \cdot V_d$$

$\Rightarrow R = \frac{1}{I_D b}$

$\Rightarrow$  device was behaving like a resistor for small signals



$$i_d = \frac{V_i}{R} = V_i \cdot \frac{1}{I_D b}$$

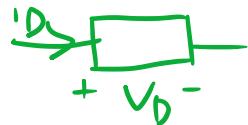
## Small Signal Circuit Method

- Find operating point using DC bias inputs from large signal circuit.

Non linear analysis

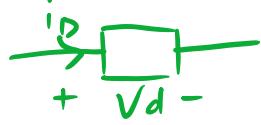
- Develop small signal (linearized) models for each element around the operating point.

Large Signal



$$i_D = f(V_D)$$

Small Signal



$$i_d = \left. \frac{\partial f(V_D)}{\partial V_D} \right|_{V_D=V_0} \cdot V_d$$

$$\frac{\delta V_D}{\delta i_s} \Big|_{i_s=I_s}$$

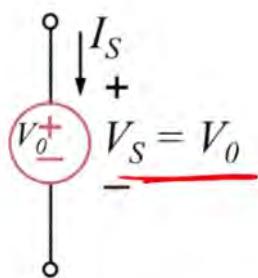
Derivative

3) Analyze linearized circuit to get small signal response

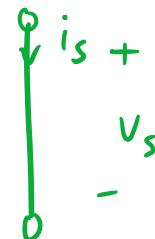
Step 2 for different Elements

Voltage Source

Large Signal



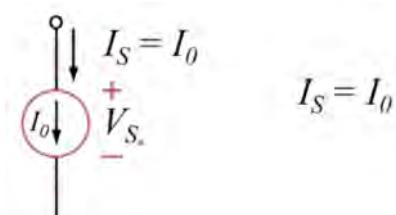
Small signal



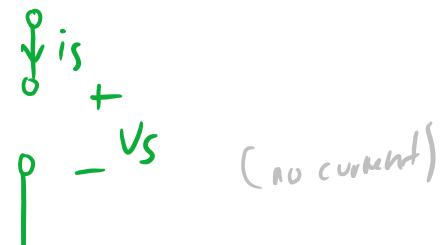
$$v_s = \frac{\delta V_o}{\delta i_s} \Big|_{i_s=I_s} = 0$$

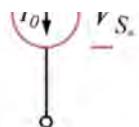
Current Source

Large Signal



Small Signal





$\text{---} \rightarrow$  (no current)

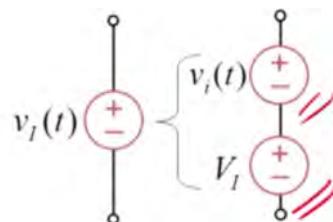
is does not change if  
 $v_s$  changes

$$i_s = \left. \frac{\delta F(v_s)}{\delta v_s} \right|_{v_s=V_s} \cdot v_s$$

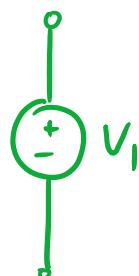
$$= \left. \frac{\delta I_o}{\delta v_s} \right|_{v_s=V_s} \cdot v_s$$

$$= 0$$

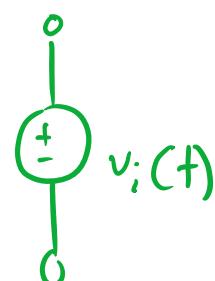
Voltage Source w DC and small signal



Large Signal



Small signal



Resistance

→ already linear element



Large Signal



Small Signal



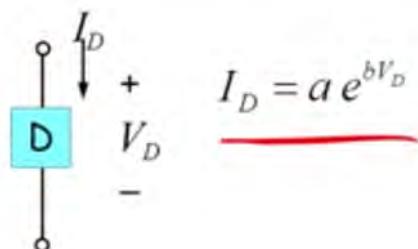
$$V = i_R R$$

$$v_r = i_r R$$

## Non-linear device

Large Signal

Small Signal



$$I_D = a e^{b V_D}$$

$$v_{D_+} + i_D R = \frac{\delta F(v_D)}{\delta (V_D)} \Big|_{v_D=v_0}$$

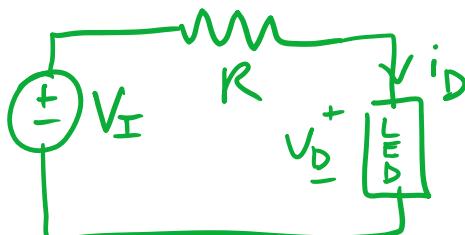
$$= a e^{b V_D} b \Big|_{v_D=v_0}$$

$$= a e^{b V_D} \cdot b v_d$$

$$i_D = \frac{I_D b}{V_D}$$

$$i_D = R V_d$$

Small Signal Example:



$$i_D = a e^{b V_D}$$

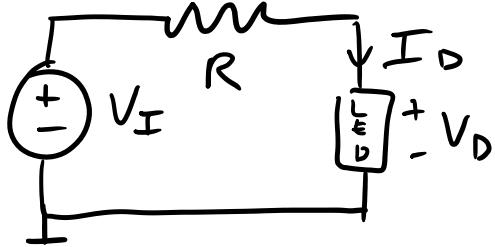
Find  $i_D$  for  $v$ :

$$R = 1/J_L \quad a = \frac{1}{c_L} A \quad b = 1/V^{-1}$$

bias point set at  $V_I = 1V$

i) Large Signal Analysis

## i) Large Signal Analysis



Analytical Method

$$\frac{V_D - V_I}{R} + \alpha e^{bV_D} = 0 \quad (\text{Node Method})$$

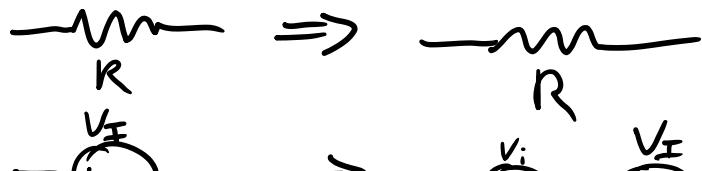
$$V_D - 1 + \frac{1}{4} e^{V_D} = 0 \quad (\text{Plug in})$$

$$V_D = 0.56 \text{ V}$$

$$I_D = 0.44 \text{ A}$$

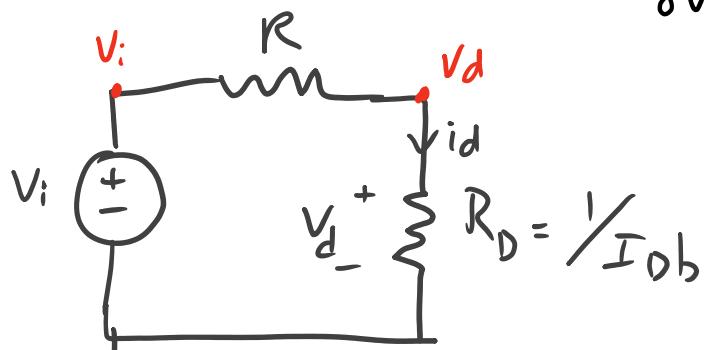
## z) Create Linearized Models

small signal



$$\text{For Diode: } i_D = \alpha e^{bV_D}$$

$$R_D = \left| \frac{\delta f(V_D)}{\delta V_D} \right|_{V_D=V_D} = \left| \frac{1}{\alpha e^{bV_D} b} \right| = \frac{1}{I_D b}$$





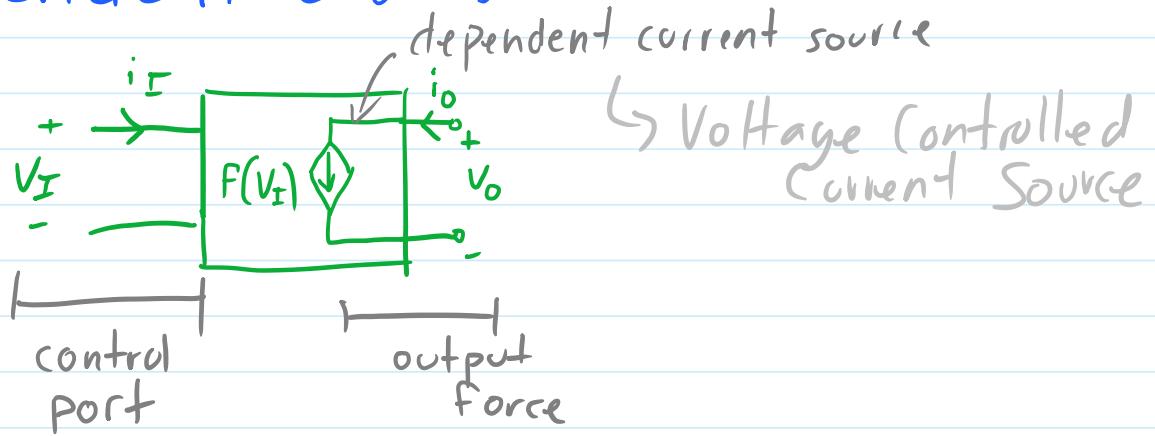
### 3) Solve

$$i_d = \frac{V_i}{R + R_d} = \boxed{\frac{V_i}{1 + \gamma I_{D_s} b}}$$

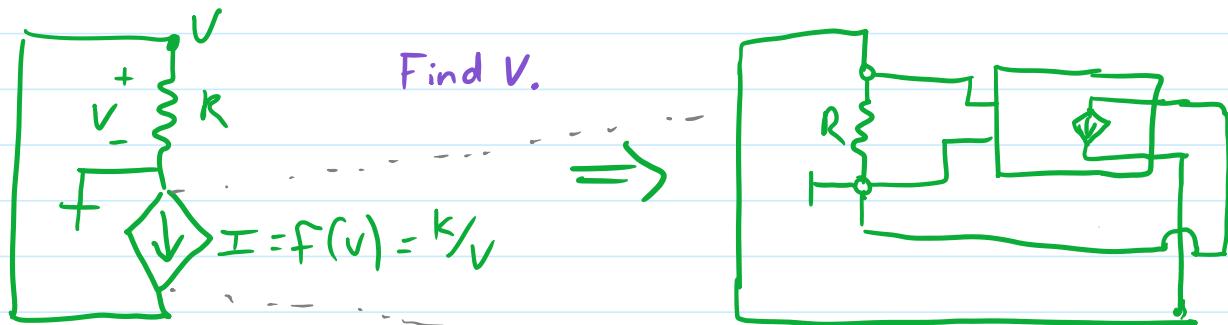
# W4: Dependent Sources and Amplifiers

Wednesday, October 5, 2016 7:20 PM

## Dependent Sources



## Example



## Node Method

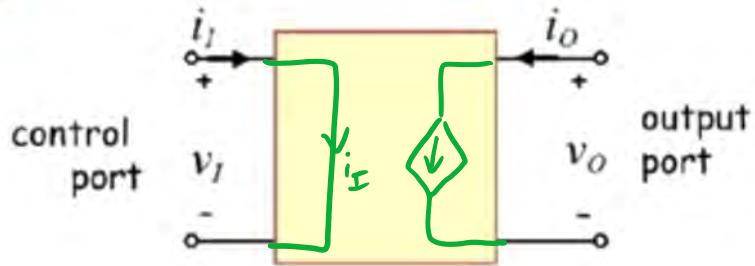
$$\frac{V}{R} - I = 0$$

$$V = IR$$

$$V = \frac{k}{V} R$$

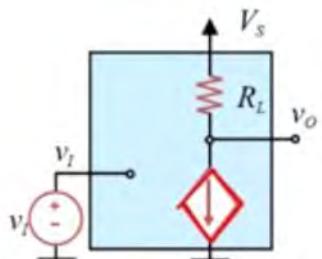
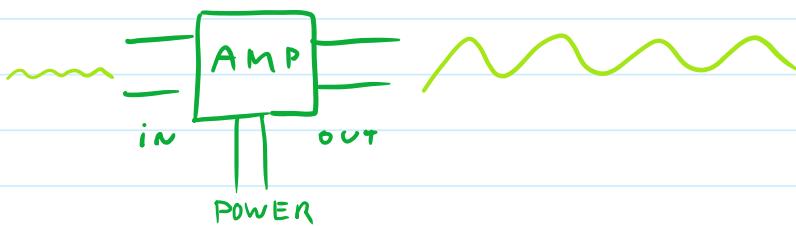
$$V^2 = kR$$

$$V = \sqrt{kR}$$



Current Controlled Current Source  
(CCCS)

## Amplifiers



### Node Method

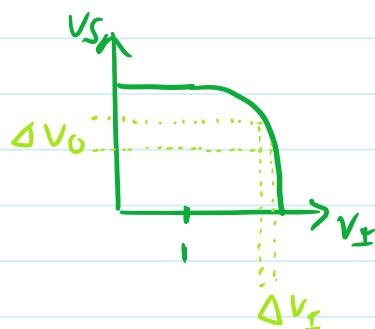
$$\frac{v_o - v_s}{R_L} + i_D = 0$$

$$v_o = v_s - i_D R_L$$

$$\Rightarrow v_o = \begin{cases} v_s - \frac{k}{2} (v_I - I)^2 R_L & \text{for } v_I \geq I \\ v_s & \text{for } v_I < I \end{cases}$$

$$i_D = \frac{k}{2} (v_{IN} - I)^2 \quad \text{for } v_{IN} \geq I$$

$$i_D = 0 \quad \text{otherwise}$$



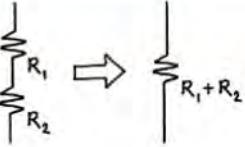
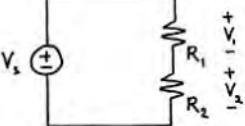
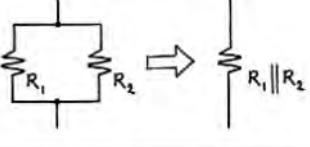
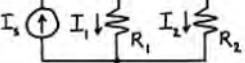
$$\frac{\partial v_o}{\partial v_i} > 1$$

$\Rightarrow$  Amplification

# Exam I Review

Wednesday, October 12, 2016 10:17 PM

## Common Shortcuts

Name	Diagram	Formulas
Series Resistors		Equivalent resistance = $R_1 + R_2$
Voltage Divider		$V_1 = \frac{R_1}{R_1 + R_2} V_s$ $V_2 = \frac{R_2}{R_1 + R_2} V_s$
Parallel Resistors		Equivalent resistance = $R_1    R_2 = \frac{R_1 R_2}{R_1 + R_2}$
Current Divider		$I_1 = \frac{R_2}{R_1 + R_2} I_s$ $I_2 = \frac{R_1}{R_1 + R_2} I_s$

$$V = R * I = \frac{P}{I} = \sqrt{P * R}$$

$$R = \frac{V}{I} = \frac{V^2}{P} = \frac{P}{I^2}$$

$$I = \frac{V}{R} = \frac{P}{V} = \sqrt{\frac{P}{R}}$$

$$P = V * I = R * I^2 = \frac{V^2}{R}$$

## Sample Problems

Q1

The power distribution network in a particular apparatus can be modeled by the circuit below.

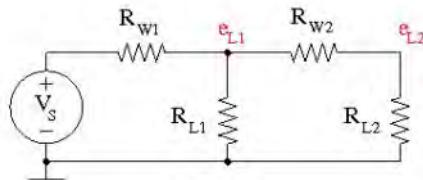


Figure 1-1

The power comes from a voltage source and is delivered to two loads. The loads are modeled by the resistors  $R_{L1}$  and  $R_{L2}$ . The resistances of the interconnects are modeled by the resistors  $R_{W1}$  and  $R_{W2}$ . The values of the element parameters are  $V_S = 4.0V$ ,  $R_{L1} = 15.0\Omega$ ,  $R_{L2} = 20.0\Omega$ ,  $R_{W1} = 1.0\Omega$ ,  $R_{W2} = 2.0\Omega$ .

16

## Node Method

$$V = IR$$

$$I = V/R$$

$$\frac{e_{L1} - V_s}{R_{W1}} + \frac{e_{L1} - e_{L2}}{R_{W2}} + \frac{e_{L1}}{R_{L1}} = 0 \quad (1)$$

$$\frac{e_{L2} - e_{L1}}{R_{W2}} + \frac{e_{L2}}{R_{L2}} = 0 \quad (2)$$

Plug in stuff

$$\frac{e_{L1} - 4}{1} + \frac{e_{L1} - e_{L2}}{2} + \frac{e_{L1}}{1} = 0$$

$$\frac{e_{L2} - e_{L1}}{2} + \frac{e_{L2}}{20} = 0$$

$$e_{L1} - 4 + \frac{1}{2}e_{L1} - \frac{1}{2}e_{L2} + e_{L1} = 0$$

$$2.5e_{L1} - \frac{1}{2}e_{L2} - 4 = 0 \quad (1)$$

$$e_{L1} = \frac{4 + \frac{1}{2}e_{L2}}{2.5} \quad \frac{1}{2}e_{L2} - \frac{1}{2}e_{L1} + \frac{1}{20}e_{L2} = 0$$

$$(2) \quad e_{L2} - \frac{4 + \frac{1}{2}e_{L2}}{2.5} + \frac{e_{L2}}{20} = 0 \quad \leftarrow \frac{1}{2}e_{L2} - \frac{1}{2}e_{L1} = 0$$

$$\frac{\frac{e_{L2}}{2.5}}{2} + \frac{e_{L2}}{20} = 0$$

$$\begin{bmatrix} -\frac{1}{2} & 0.55 \\ 2.5 & -\frac{1}{2} \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 4 \end{bmatrix} =$$

$$\frac{20e_{L2}}{2} - \frac{2(4 + \frac{1}{2}e_{L2})}{5} + \frac{e_{L2}}{20} = 0$$

$$\frac{1}{10}e_{L2} - 16 + 2e_{L2} + e_{L2} = 0$$

$$3\frac{1}{10}e_{L2} = 16$$

$$e_{L2} =$$

$$\begin{aligned} 2x + 3y - 2z &= 8 \\ x - 4z &= 1 \\ 2x - y - 6z &= 4 \end{aligned}$$

$$\begin{bmatrix} 2 & 3 & -2 \\ 1 & 0 & -4 \\ 2 & -1 & -6 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 8 \\ 1 \\ 4 \end{bmatrix}$$

coefficient matrix  
 A                      variable matrix  
 X                      constant matrix  
 B

Here's a short explanation of where this method comes from. Any system of equations can be written as the matrix equation,  $A * X = B$ . By pre-multiplying each side of the equation by  $A^{-1}$  and simplifying, you get the equation  $X = A^{-1} * B$ .

Using your calculator to find  $A^{-1} * B$  is a piece of cake. Just follow these steps:

- Enter the coefficient matrix, A.

Press [ALPHA][ZOOM] to create a matrix from scratch or press [2nd][ $x^{-1}$ ] to access a stored matrix. See the first screen.



2nd Try

$$\frac{e_{L1} - V_s}{R_{W1}} + \frac{e_{L1} - e_{L2}}{R_{W2}} + \frac{e_{L1}}{R_{L1}} = 0$$

$$\frac{e_{L1} - 4}{1} + \frac{e_{L1} - e_{L2}}{2} + \frac{e_{L1}}{15} = 0$$

$$e_{L1} - 4 + \frac{1}{2}e_{L1} - \frac{1}{2}e_{L2} + \frac{e_{L1}}{15} = 0$$

$\frac{47}{30}e_{L1} - \frac{1}{2}e_{L2} = 4$

$$\frac{e_{L2} - e_{L1}}{R_{W2}} + \frac{e_{L2}}{R_{L2}} = 0$$

$$\frac{1}{2}e_{L2} - \frac{1}{2}e_{L1} + \frac{e_{L2}}{20} = 0$$

$-\frac{1}{2}e_{L1} + .55e_{L2} = 0$

$$\begin{bmatrix} \frac{47}{30} & -\frac{1}{2} \\ -\frac{1}{2} & .55 \end{bmatrix}^{-1} \begin{bmatrix} 4 \\ 0 \end{bmatrix} = \begin{bmatrix} 3.59 \\ 3.26 \end{bmatrix}$$

$e_{L1}$   
 $e_{L2}$

$V = IR \quad I = V/R$

$$P = IV$$

$$P = \frac{V^2}{R} = \frac{(4 - 3.59)^2}{1} = .1681$$

$$= \underline{(3.59)^2} = .859$$

15

$$= \frac{(3.59 - 3.26)^2}{2} =$$
$$- \frac{(3.26)^2}{20}$$

Power through voltage source?

=



Q2

0 points possible (ungraded)

A resistive load is attached to a two-terminal "black box".

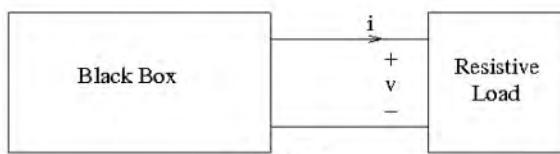


Figure 2-1

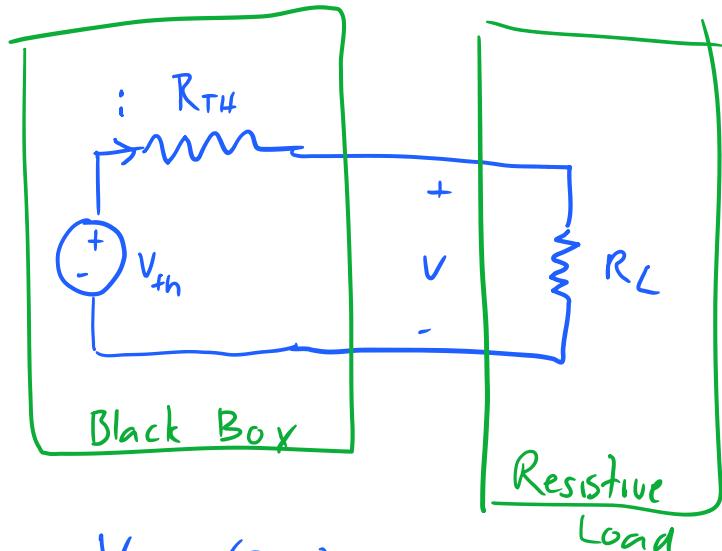
The "black box" contains only linear resistors and independent sources.

The voltage across the load is measured to be  $v = 3.0V$  when the current through the load is measured to be  $i = 22.0A$ .

The load is then changed and the voltage across the new load is measured to be  $v = 18.0V$  when the current through the load is measured to be  $i = 17.0A$ .

If the resistive load is replaced by a short circuit, what is the current, in Amperes, that flows through the short circuit?

If the resistive load is replaced by an open circuit, what is the voltage, in Volts, that appears across the open circuit?



$$V_{TH} = (R_{TH}) \cdot i + V$$

1st:

$$- \quad V_{TH} = R_{TH} (22) + 3$$

2nd:

$$V_{TH} = R_{TH} (17) + 18$$

1st - 2nd:

$$0 = 5R_{TH} - 15$$

$$\Rightarrow R_{TH} = 3$$

$$\Rightarrow V_{TH} = 3(22) + 3 = \boxed{69} \quad \checkmark$$

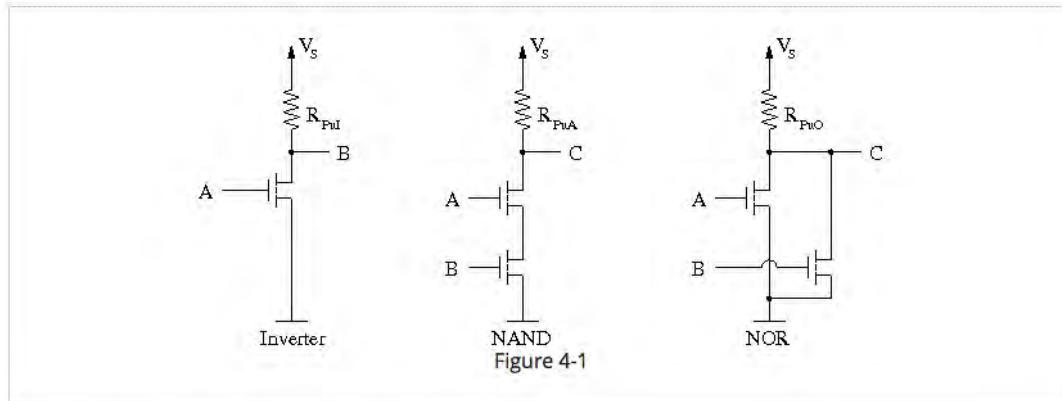
Short circuit  $\Rightarrow R_L = 0$

$$V_{TH} = i R_{TH}$$

$$i = \frac{V_{TH}}{R_{TH}} < \frac{69}{3} = \boxed{23} \quad \checkmark$$

For many purposes of gate design, we can model a MOSFET used as a switch simply as an ideal switch and an "on-state resistor"  $R_{ON}$ . This is the SR model.

Assuming this model for the MOSFET, consider the inverter in the figure. This inverter is intended to be used as an element in a logic family with NAND and NOR gates.



The static discipline required for this family is:

$$V_S = 5.0V, V_{OH} = 4.5V, V_{IH} = 4.0V, V_{IL} = 1.5V, V_{OL} = 1.0V.$$

Low noise margin

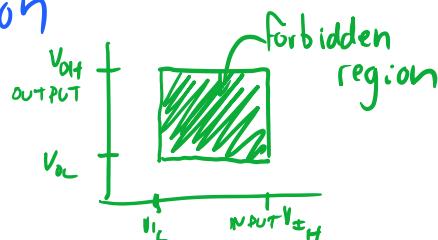
$$|V_{IL} - V_{OL}| = .5$$

High noise margin

$$|V_{IH} - V_{OH}| = .5$$

Width of forbidden region

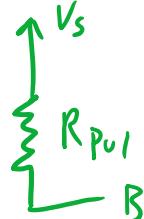
$$V_{IH} - V_{IL}$$



Suppose that the threshold voltage for the MOSFET is  $V_T = 2.0V$  and  $R_{ON} = 7000.0\Omega$ .

Min value of  $R_{puI}$  to obey static discipline in Inverter

If  $V_{GS} < V_T \Rightarrow$

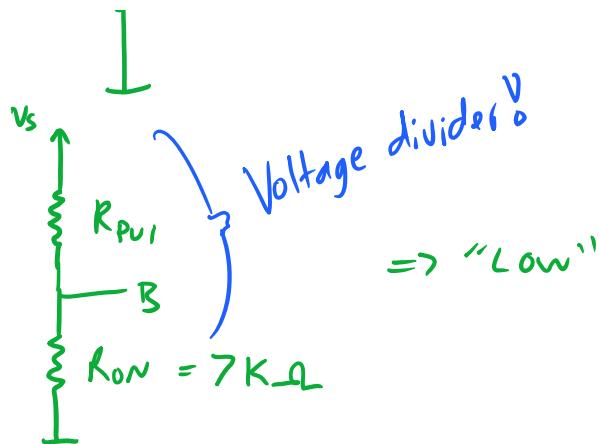


$\Rightarrow$  "HIGH"



..V

IF  $V_{GS} \geq V_T \Rightarrow$



$$B = \frac{R_{ON}}{R_{pu1} + R_{ON}} V_S$$

From static discipline  $B$  needs to be at least  $= V_{OL} = 1V$

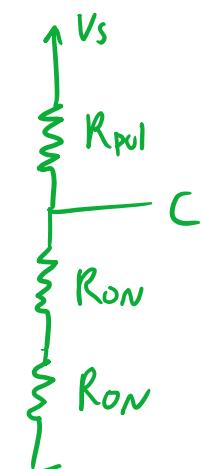
$$\Rightarrow \frac{1}{5} = \left( \frac{7000}{R_{pu1} + 7000} \right) \cancel{\$}$$

$$5(7000) = R_{pu1} + 7000$$

$$R_{pu1} = 4(7000) - \boxed{28K} \quad \checkmark$$

Min value of  $R_{pu1}$  to obey static discipline in NAND Gate

closed



$$C = \frac{2R_{ON}}{R_{pu1} + 2R_{ON}} V_S = 1$$

$$\frac{1}{5} = \left( \frac{14K}{R_{pu1} + 14K} \right) \cancel{\$}$$

$$(14K) \cancel{\frac{4}{5}} = R_{pu1} + \cancel{14K}$$

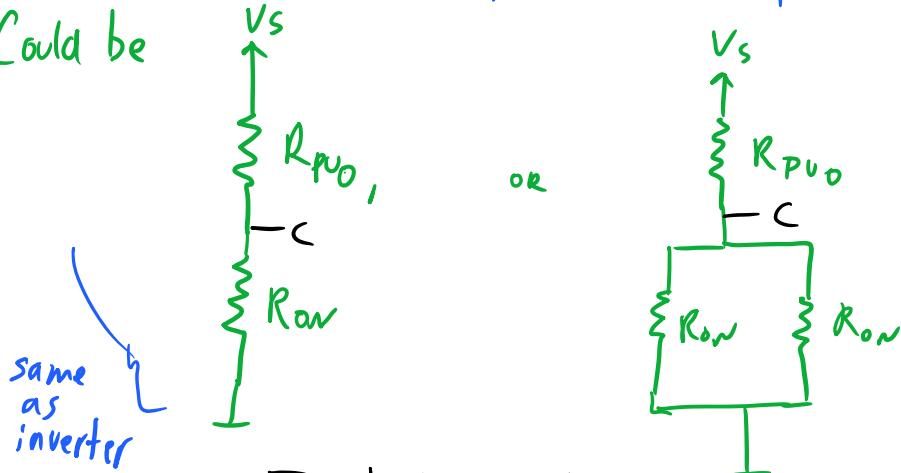
$$R_{pu1} = 4(14K)$$

$$\boxed{= 56k} \quad \checkmark$$

$$= 56 \text{ k}$$

Min value of  $R_{pvo}$  to obey static discipline in NOR Gate

Could be



Try both and take min  $R$

$$R_{pvo_1} = 28 \text{ k}$$

$$R_{pvo} = \max(R_{pvo_1}, R_{pvo_2})$$

$$\frac{R_{pvo_2}}{C} = 1$$

$$= \frac{R_{on} || R_{on}}{R_{p1} + R_{on} || R_{on}} \leq R_{on} || R_{on} = \frac{(R_{on})^2}{2R_{on}} = \frac{7\text{ k}^2}{14\text{ k}} = 3.5\text{ k}$$

$$\frac{1}{S} = \frac{3.5}{R_{pvo_2} + 3.5} \quad S = 3.5\text{ k}$$

$$S(3.5) = R_{pvo_2} + 3.5$$

$$R_{pvo_2} = 4(3.5) = 14\text{ k}$$

$$\Rightarrow R_{pvo} = 28\text{ k}$$

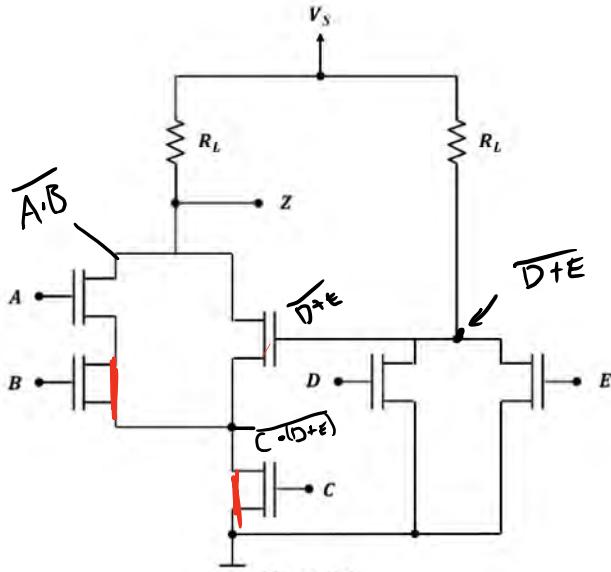


Figure 5-1

Write a boolean expression for  $Z$  in terms of  $A, B, C, D$ , and  $E$ . You need not simplify your expression. Use your expression to fill out the truth table below.

$$Z = \overline{(\overline{A} \cdot \overline{B})} + (\overline{D} + \overline{E}) \cdot C$$

How?

$A$	$B$	$C$	$D$	$E$	$Z$
1	0	1	0	1	1
1	1	1	1	1	0
0	0	1	1	0	1
0	1	1	0	0	0



A battery in combination with a dependent current source is connected to a lamp in the circuit shown below in Figure 6-1. The battery is modeled as a voltage source in series with a resistor,  $R_{bat}$ , and has an open circuit voltage of  $4V$ . The lamp turns on if the voltage across the lamp is greater than  $2V$ . When the lamp is on it has an internal resistance of  $10\Omega$ , and when it is off it acts like an open circuit.

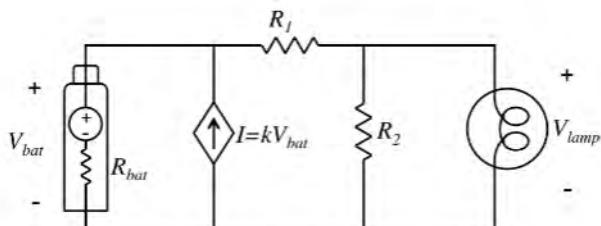


Figure 6-1

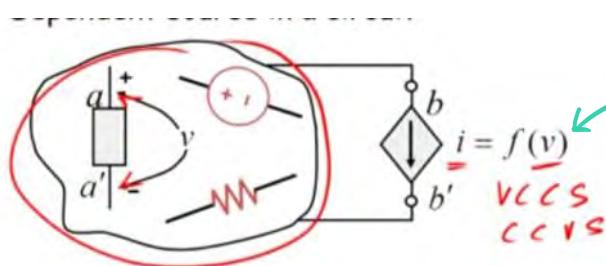
The elements in this circuit have the following values:  $R_1 = 5\Omega$ ,  $R_2 = 5\Omega$ , and  $k = 0.2$ .

# W1: MOSFET Large Signals

Friday, October 14, 2016 9:58 AM

## Review

### Dependent sources

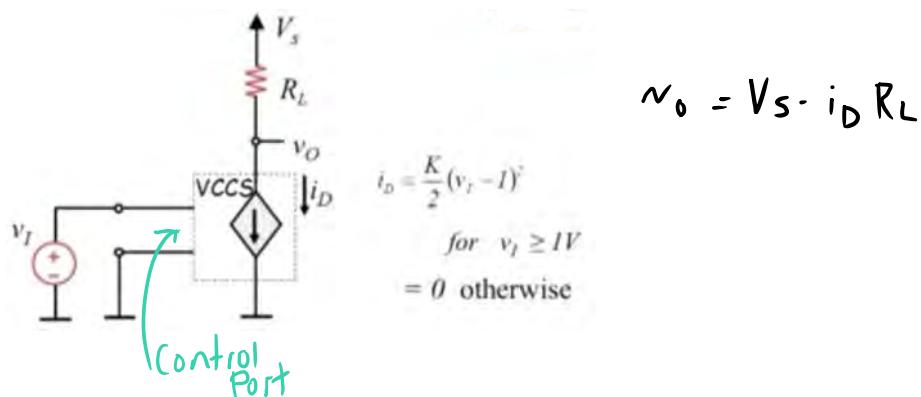


output depends  
on  $v$  somewhere  
else on the circuit

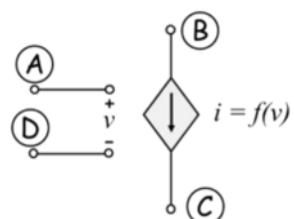
### Superposition w/ dependent sources

- leave all dependent sources in
- solve for independent source one at a time

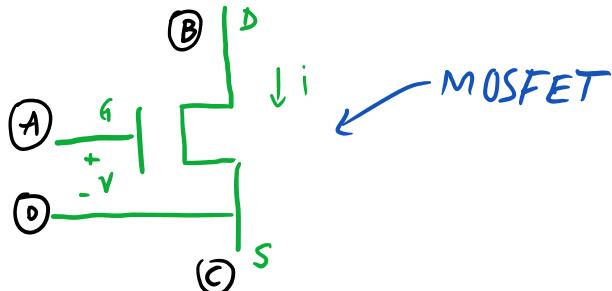
## Amplifier



What we need



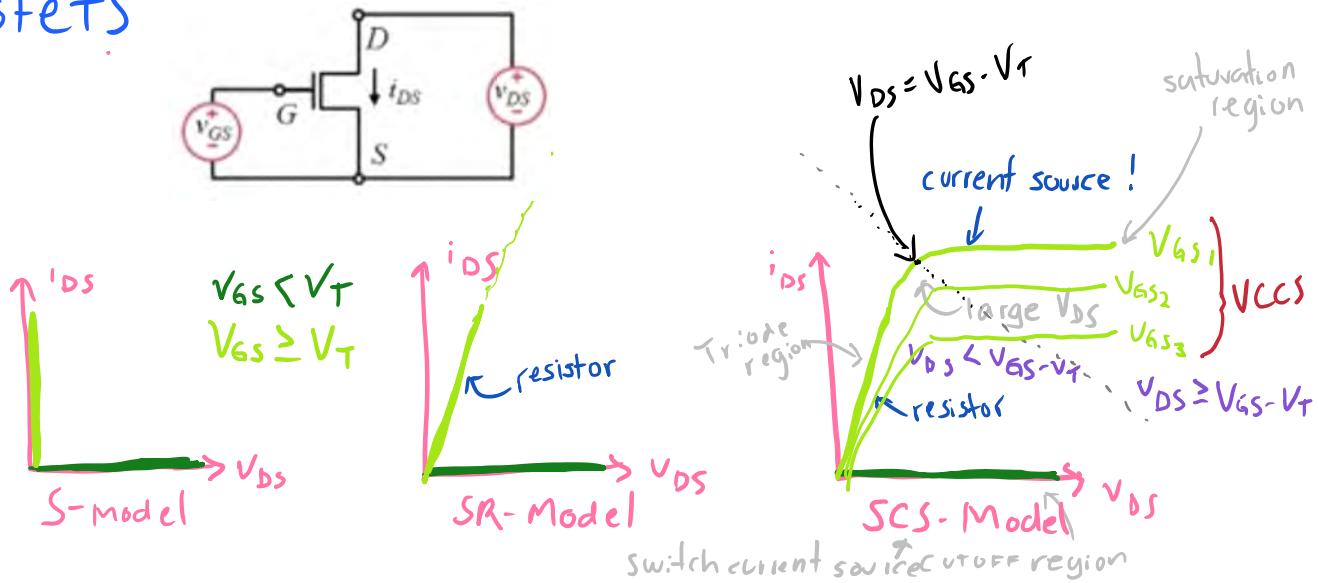
What we have



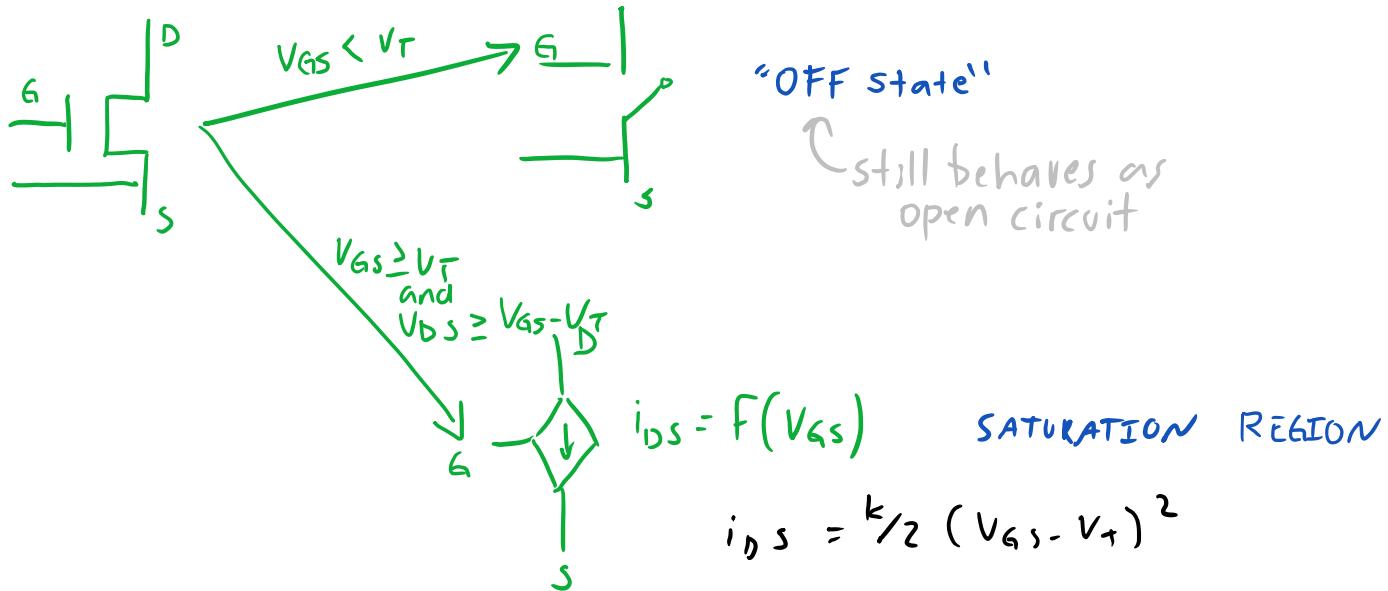
## Mosfets



# Mosfets

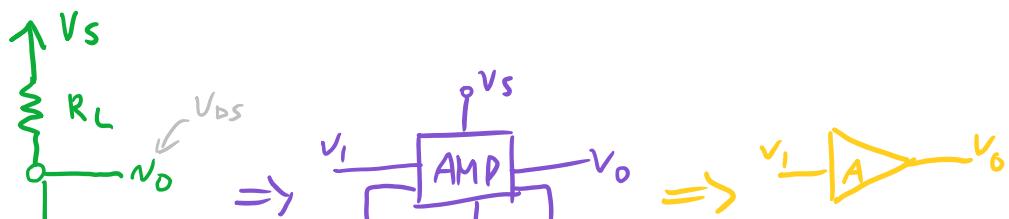


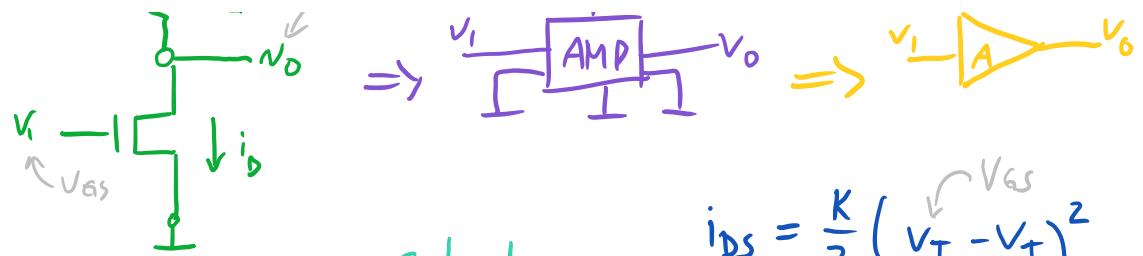
- On state behavior more complex than SR-Model!



Use SR-Model for digital designs and SCS-Model for analog designs

## Amplifier



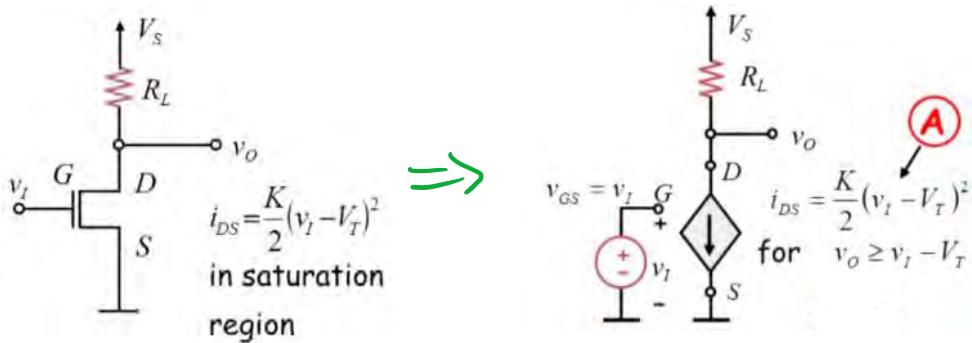


"In saturation region only!"

$$i_{DS} = \frac{K}{2} (v_I - V_T)^2$$

$$\begin{aligned} \textcircled{1} \quad & v_{GS} \geq V_T \\ \textcircled{2} \quad & v_{DS} \geq v_{GS} - V_T \\ & v_I \geq V_T \\ & v_O \geq V_T \end{aligned}$$

## Analysis



Analytical Method Find  $v_O$  vs  $v_I$

$$\frac{v_O - v_S}{R_L} + i_{DS} = 0 \quad (\text{Node Method})$$

$$\begin{aligned} v_O &= v_S - i_{DS} R_L \quad \textcircled{B} \\ \Rightarrow v_O &= v_S - \frac{K}{2} (v_I - V_T)^2 R_L \quad \text{saturation region} \\ &\leftarrow \text{For } v_I \geq V_T \text{ and } v_O \geq v_I - V_T \\ v_O &= 0 \quad \leftarrow \text{For } v_I < V_T \text{ Mosfet is off} \end{aligned}$$

## Graphical Method

$$\textcircled{A} \quad i_{DS} = \frac{K}{2} (v_I - V_T)^2$$

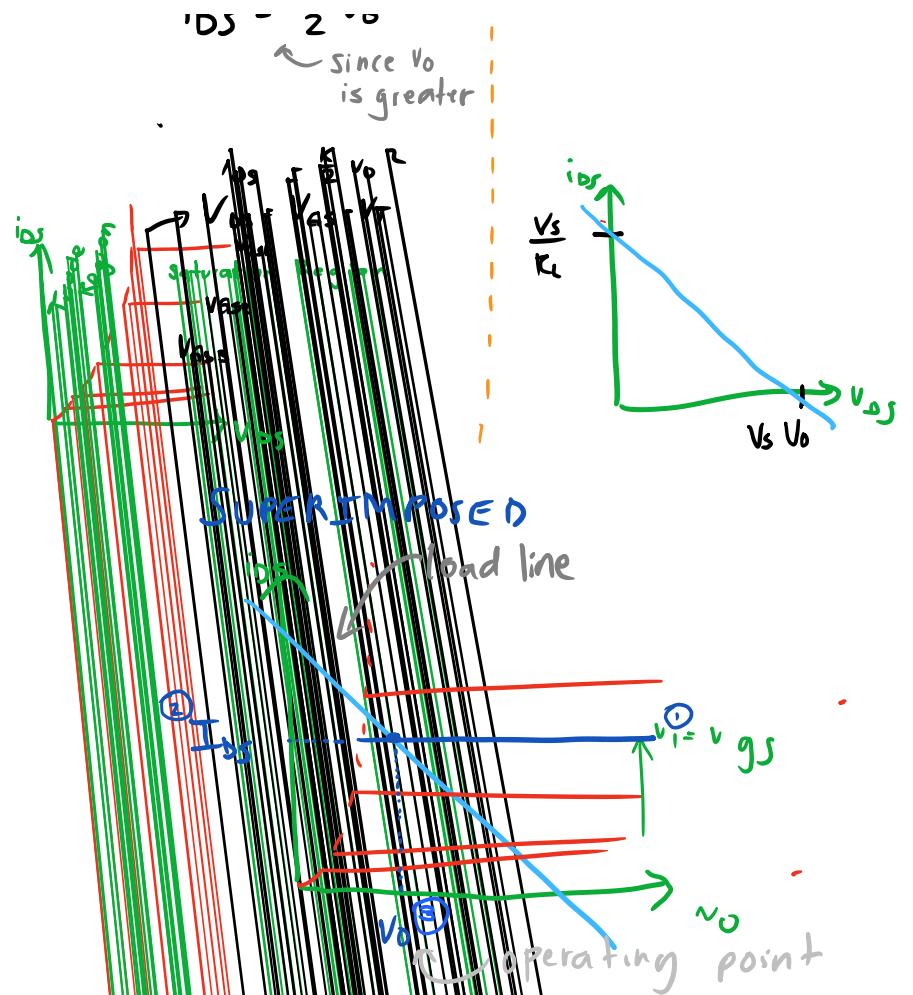
$$\text{Saturation begins: } v_O = \frac{v_I - V_T}{2}$$

$$i_{DS} \leq \frac{K}{2} v_O^2$$

Since  $v_O$  is greater

$$\textcircled{B} \quad v_O = v_S - i_{DS} R_L$$

$$\Rightarrow i_{DS} = \frac{v_S}{R_L} - \frac{v_O}{R_L}$$

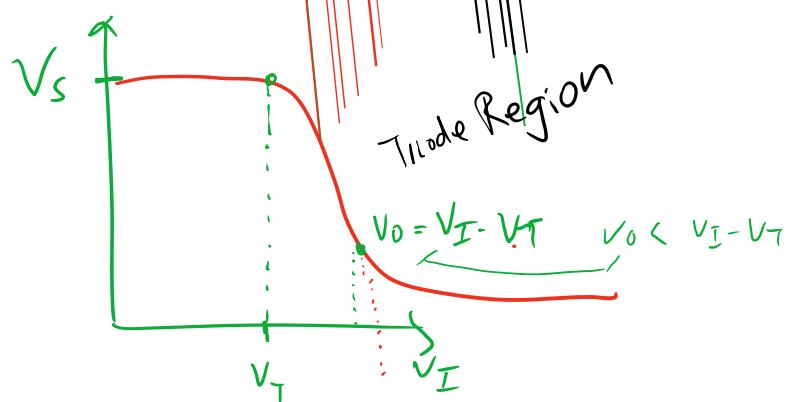


## Large Signal Analysis

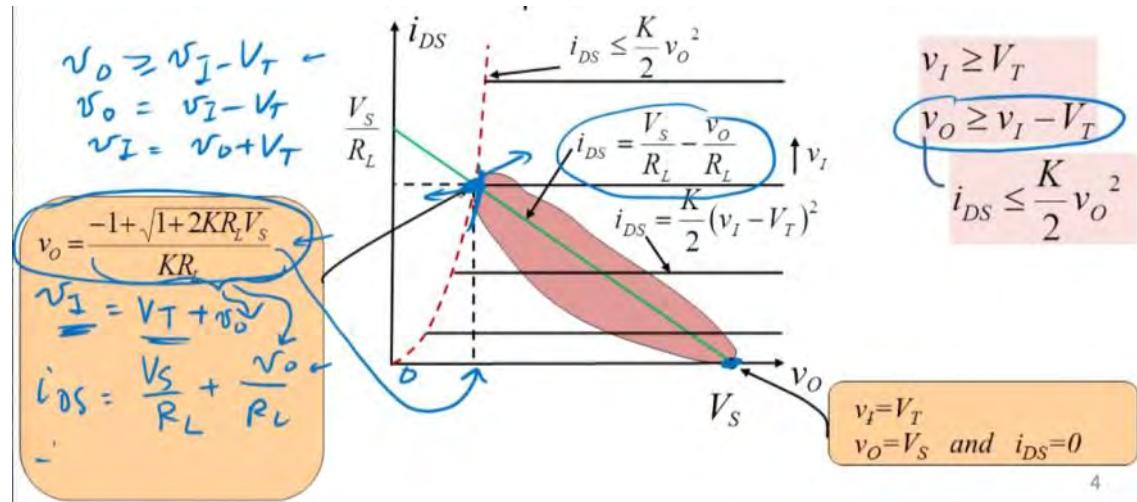
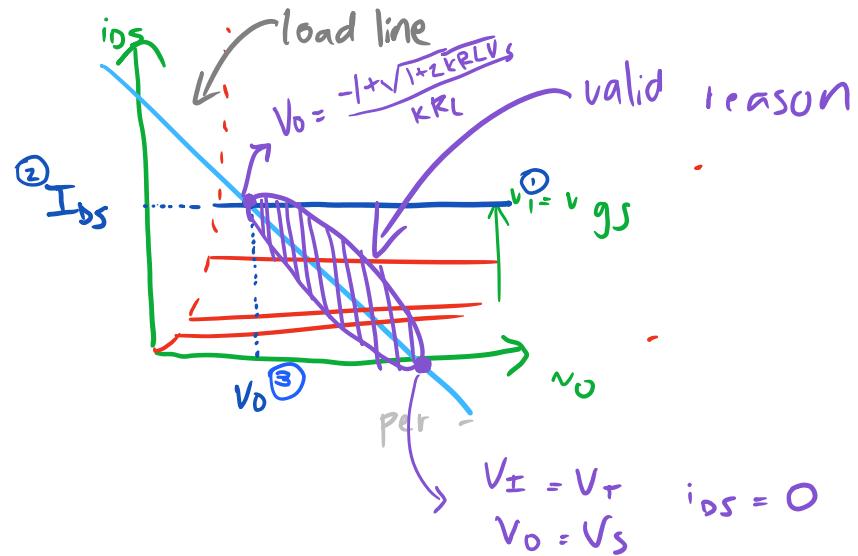
### ① $V_o$ versus $V_s$

$$V_o = V_s - \frac{k}{2} (V_I - V_T)^2 \cdot R_L \quad \text{for } V_I \leq V_T$$

$$V_o = V_s \quad \text{for } V_I \geq V_T$$



② Find valid operating ranges under static discipline



## Large Signal Analysis Summary

①  $v_o$  versus  $v_I$

$$v_o = V_s - \frac{k}{2} (v_I - v_T)^2 \cdot R_L$$

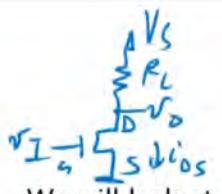
② Valid operating ranges under the saturation discipline?

→ Valid input range:

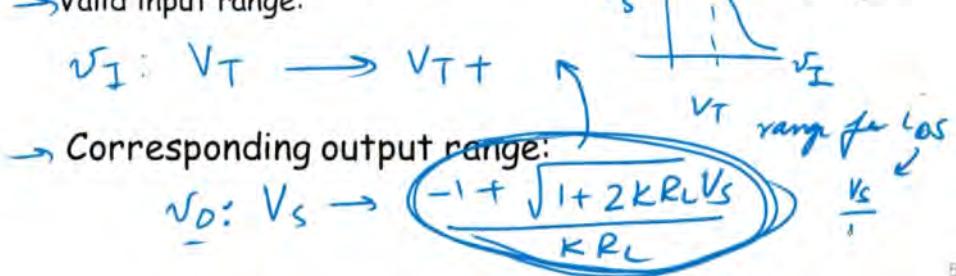
$$v_I: V_T \rightarrow V_T +$$

→ Corresponding output range:

$$v_o: V_s \rightarrow \frac{-1 + \sqrt{1 + 2kR_LV_s}}{kR_L}$$



We will look at another way of obtaining (2) shortly



# W1 : Amplifiers: small signal model

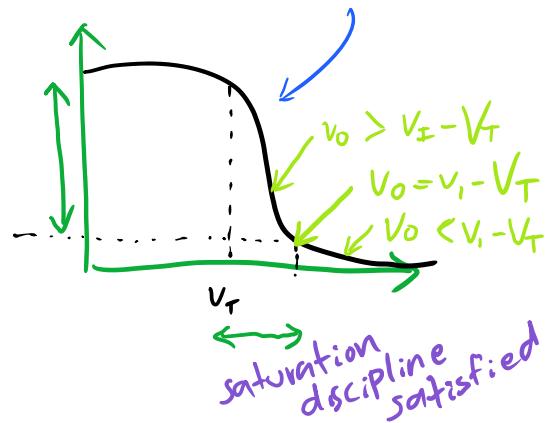
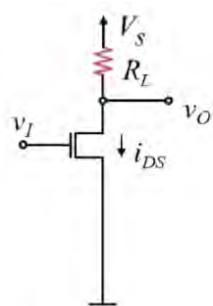
Monday, October 17, 2016 5:59 PM

## Large Signal Analysis Review

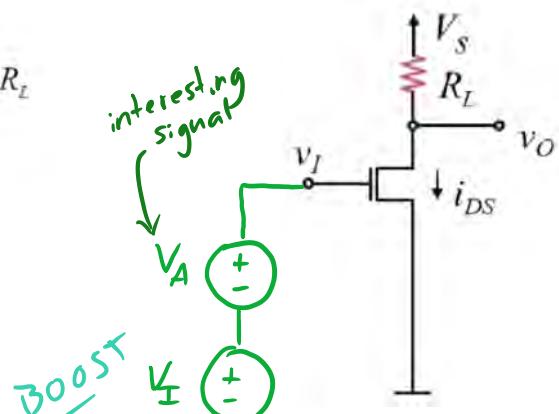
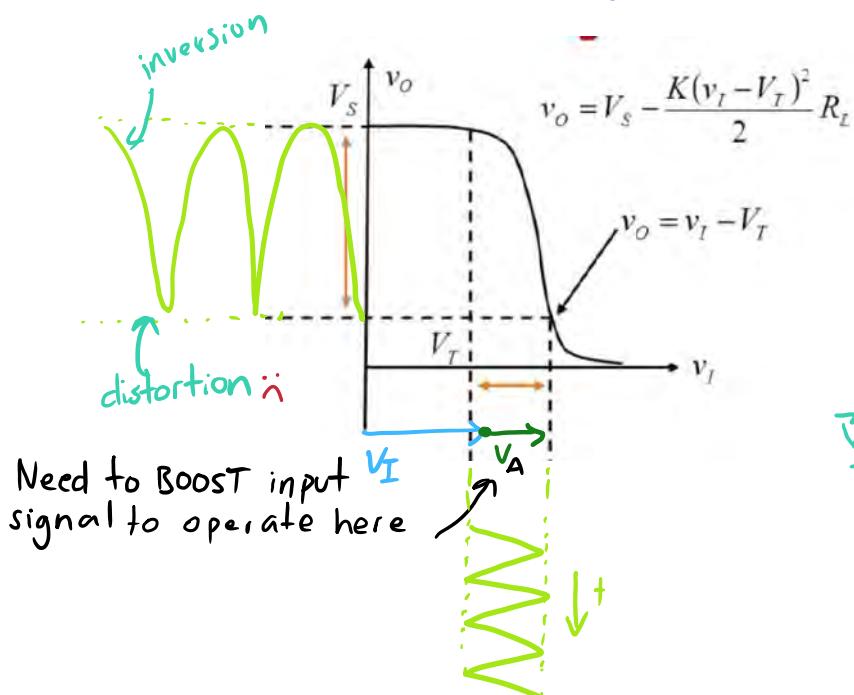
①  $V_o$  vs  $v_i$ :

$$V_o = V_s - \frac{K(v_i - V_T)^2}{2} R_L$$

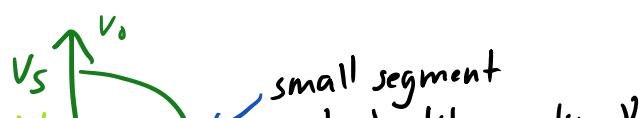
② Valid operating ranges



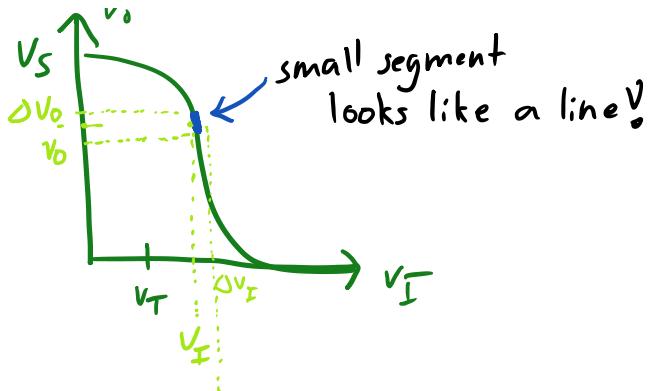
Operating in saturation region



Small Signal Trick



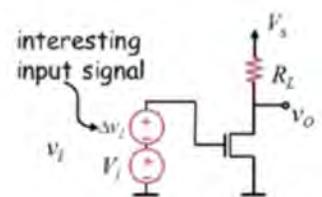
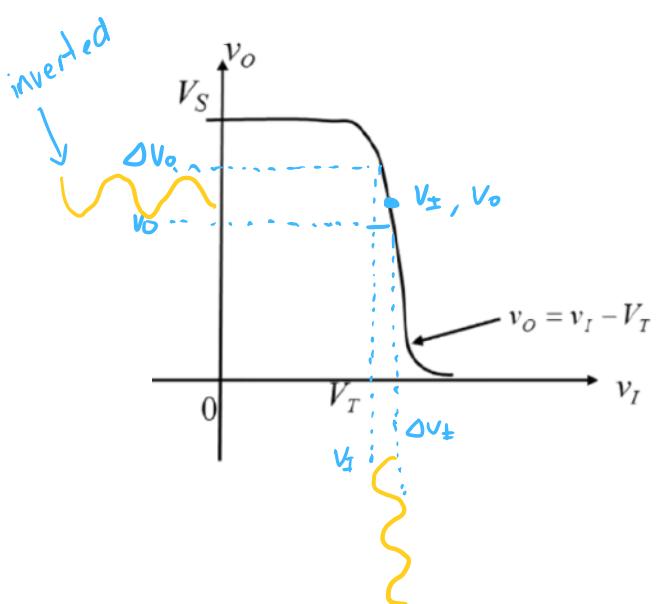
① Operate amp at  $V_i = V_o \rightarrow \text{"DC bias"}$



① Operate amp at  $V_T$   
 $V_I, V_O \rightarrow$  "DC bias"

② Superimpose small signal  
on top of  $V_I$

## Small Signal Method: Graphically



INPUT:  $v_I = V_I + \nu_i$       DC bias  
operating point voltage  
OUTPUT  $v_O = V_O + \nu_o$       small signal  $\Delta v_i$

## II Mathematically

$$v_O = V_S - \frac{R_L K}{2} (\nu_i - V_T)^2$$

substituting  $v_I = V_I + \nu_i$ ,  $\nu_i \ll V_I$

$$v_O = V_S - \frac{R_L K}{2} ([V_I + \nu_i] - V_T)^2$$

$$= V_S - \frac{R_L K}{2} ([V_I - V_T] + \nu_i)^2$$

$$\underline{\underline{v_O + \nu_o}} = \underline{\underline{V_S - \frac{R_L K}{2} ([V_I - V_T]^2 + 2[V_I - V_T]\nu_i + \nu_i^2)}}$$

From #  $\underline{\underline{v_O}} = \underline{\underline{A \nu_i}}$

$$v_O = -\frac{R_L K}{2} (2[V_I - V_T]\nu_i)$$

$$v_O = -\frac{R_L K}{2} (V_I - V_T) \nu_i = -\frac{R_L g_m \nu_i}{2} = \underline{\underline{K(V_I - V_T) \frac{\nu_i}{g_m}}}$$

Transconductance related to MOSFET parameters and  $V_I$

## W2: Small signal circuit model

Monday, October 17, 2016 8:03 PM

$$\text{Recall } v_o = \frac{-K(v_I - V_T)^2}{2} R_L$$

$$v_o = \frac{d}{dv_I} \left[ V_s - \frac{K}{2} (v_I - V_T)^2 R_L \right] \Big|_{v_I=V_I} \cdot v_i$$

$$v_o = -K(V_I - V_T) R_L \cdot v_i$$

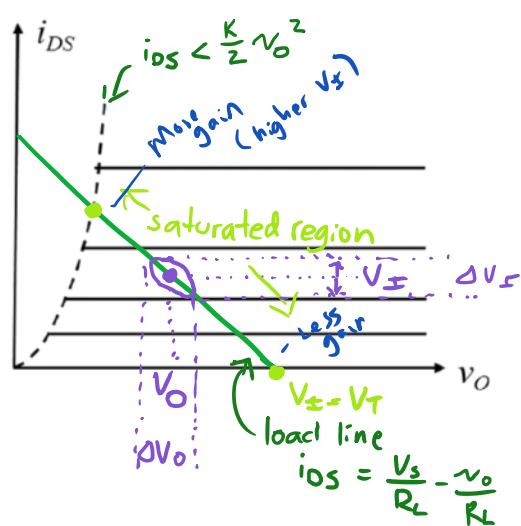
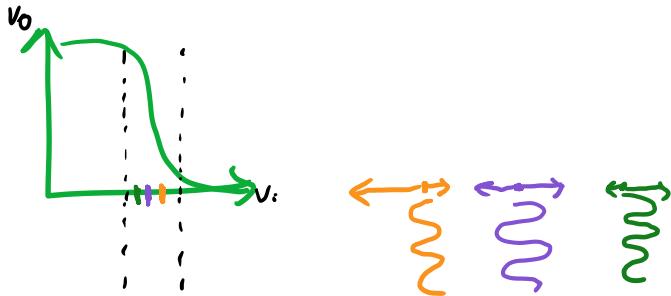
$\underbrace{K(V_I - V_T)}_{g_m}$  transductance

Recall Notation

$$v_A = V_A + v_a$$

↑ Total      ↑ Operating Point      Small Signal

How to choose operating point?



KEY PARTS

- 1) Gain  
 $g_m R_L$  since  $v_o = g_m R_L v_i$
- 2) Input swing  
Symmetric swing: closer to midpoint  
= larger input swing

Small Signal circuit view

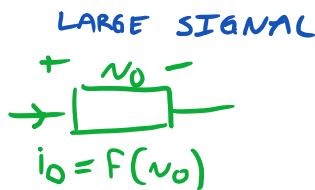
- Can derive small signal equivalent and conduct small signal analysis there

# small signal analysis trick

## Small Signal

- ① Find operating point using DC bias inputs using large signal model  $v_I \rightarrow v_0$
- ② Develop small signal models of elements
- ③ Replace original elements w/ small signal models  
 $\Rightarrow$  can use superposition to analyze!

## ② Linearized Model

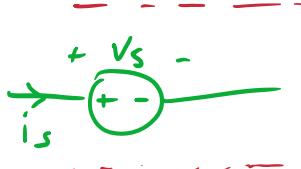


### SMALL SIGNAL

$$i_d = \frac{\delta F(v_d)}{\delta v_d} \Big|_{v_D=v_D} \cdot v_d$$

(constant)

$$R_d = \frac{1}{\frac{\delta F(v_d)}{\delta v_d}} \Big|_{v_D=v_D}$$



$\Rightarrow$



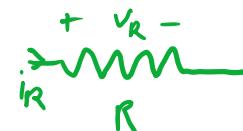
$$N_A = 0$$



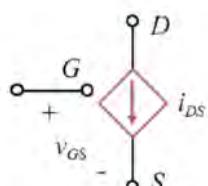
$\Rightarrow$



$\Rightarrow$



### MOSFET



$\Rightarrow$

$$i_{DS} = \frac{K}{2} (v_{GS} - V_T)^2$$

$$i_{DS} = \frac{K}{2} (v_{GS} - V_T)^2$$

$$i_{DS} = \frac{\delta}{\delta v_{GS}} \left[ \frac{K}{2} (v_{GS} - V_T)^2 \right] \Big|_{v_{GS}=V_{GS}} \cdot v_g$$

$$= \cancel{\frac{K}{2}} \cdot \cancel{(v_{GS} - V_T)} \Big|_{v_{GS}=V_{GS}}$$

$$i_{DS} = \frac{k}{2} (V_{GS} - V_T)$$

$$= \frac{k}{2} (V_{GS} - V_T) \Big|_{V_{GS}=V_{GS}}$$

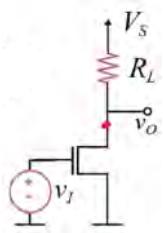
$$= K(V_{GS} - V_T) \cdot v_g$$

$i_{DS}$  is linear in  $v_{GS}$

$$i_{DS} = K(V_{GS} - V_T) \cdot v_g$$

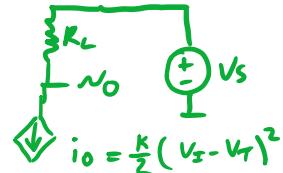
$V_{DS}$  linear

### EX: AMPLIFIER



$v_I$

Large Signal



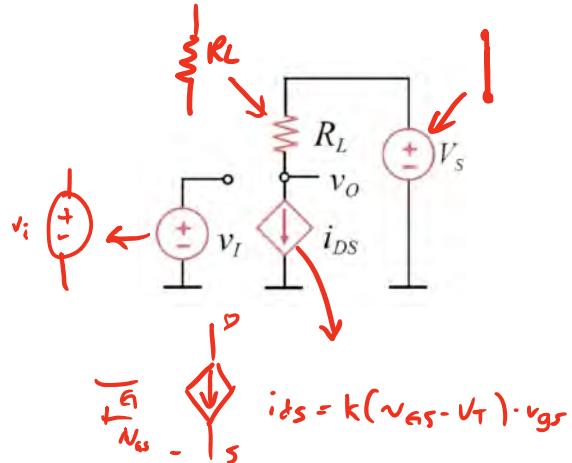
### ① Find operating point

Large signal Analysis

$$v_O = v_S - \frac{k}{2} (v_I - V_T)^2 R_L \quad (\text{node method})$$

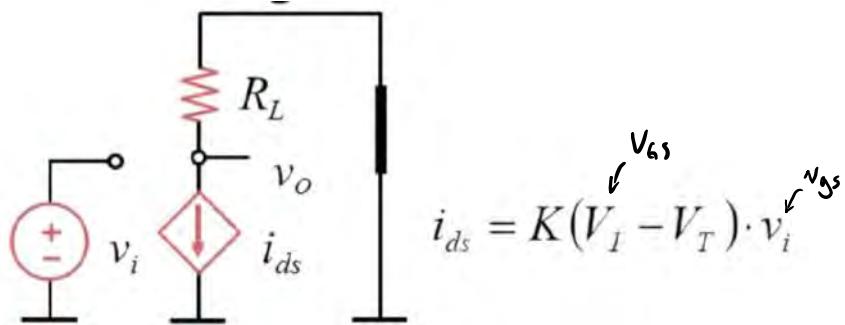
$$V_O \quad i_{DS} = \frac{k}{2} (v_I - V_T)^2$$

### ② Small signal model



### ③ Replace elements w/ small signal element

③ Replace elements w/ small signal element  
and analyze



### Node Method

$$\frac{v_o}{R_L} + i_{ds} = 0$$

$$v_o = -i_{ds} R_L$$

$$= -K(V_I - V_T) \cdot R_L v_i$$

$$= -g_m R_L v_i$$

Amplification ✓

need to do large signal analysis to get

### The Small Signal Circuit View - Foundations

KVL, KCL applied to some circuit C yields:

$$\dots + (V_A) + \dots + V_{OUT} + \dots + V_B + \dots = 0 \quad (1)$$

Replace total variables with operating point variables plus small signal variables

$$\dots + (V_A) v_a + \dots + (V_{out}) v_{out} + \dots + (V_B) v_b + \dots = 0$$

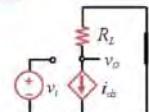
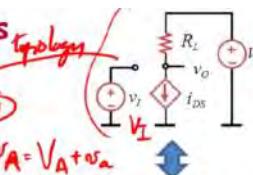
Operating point variables themselves satisfy the same KVL, KCL equations

$$\dots + V_A + \dots + V_{OUT} + \dots + V_B + \dots = 0 \quad (2)$$

so, we can cancel them out, leaving

$$\dots + (V_A) + \dots + V_{out} + \dots + (V_B) + \dots = 0 \quad (2)$$

But (2) is the same equation as (1) with small signal variables replacing total variables, so (2) must reflect same typology as in C, except that small signal models are used.



loopback  
① & ②

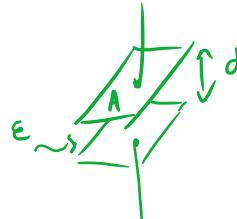
# W2: Capacitors and First order circuits

Friday, October 21, 2016 2:24 PM

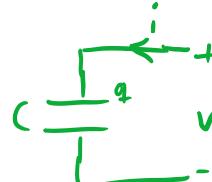
one energy storage element

MOSFET structure looks like a capacitor 

Capacitor  Parallel Plate



$$C = \frac{\epsilon A}{d}$$



Farads  
charge  
 $q = C V$   
Coulombs  
volts  
capacitance

We have just learned the v-i characteristic for a linear capacitor:

$$i = C \frac{dv}{dt}$$

So the power entering the capacitor (as in any two-terminal device) is:

$$P = vi = Cv \frac{dv}{dt}$$

If we integrate this between two times we get the energy change in the capacitor over the interval:

$$\Delta E = \int_{t_0}^{t_1} P(t) dt = \int_{t_0}^{t_1} Cv(t) \frac{dv(t)}{dt} dt = \frac{1}{2} C(v(t_1))^2 - \frac{1}{2} C(v(t_0))^2$$

So the energy stored in a capacitor, as a function of the voltage across it, is:

$$E = \frac{1}{2} Cv^2$$

$$i = \frac{dq}{dt} = \frac{d(Cv)}{dt} = C \frac{dv}{dt}$$

Assume  $C$  linear time invariant

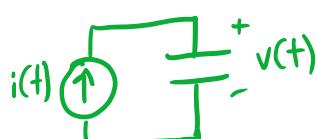
$$\rightarrow v = \frac{1}{C} \int_{-\infty}^{t_1} i dt$$

$$P = iV = VC \frac{dv}{dt} = \frac{d}{dt} \left( \frac{1}{2} Cv^2 \right)$$

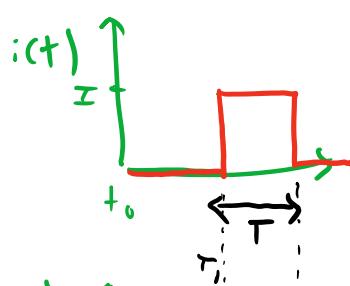
$$E = \frac{1}{2} Cv^2$$

Capacitor stores energy  $\rightarrow$  memory

## EXAMPLE



Given



Find  $v(t_0)$

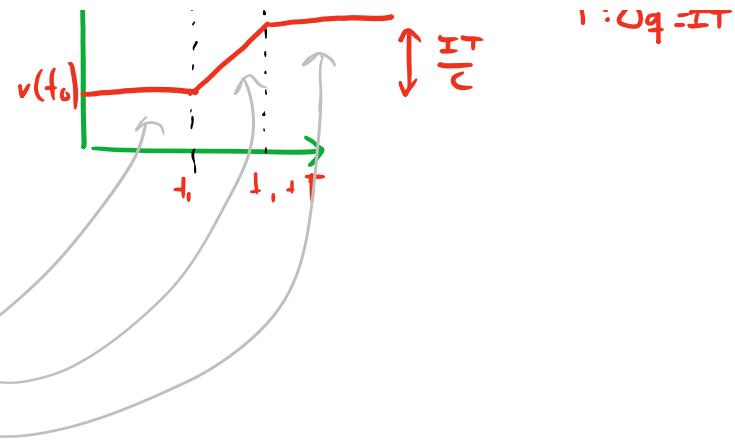
$$v = \frac{1}{C} \int_{-\infty}^{t_0} i dt$$



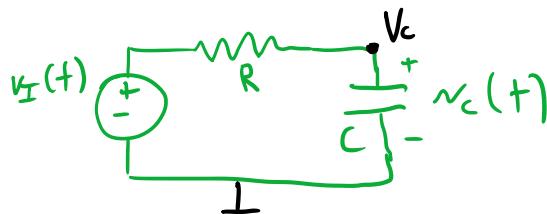
$$T: \Delta q = IT$$

$$\begin{aligned}
 V &= C \int_{-\infty}^t i dt \\
 &= \frac{1}{C} \int_{-\infty}^{t_0} i dt + \frac{1}{C} \int_{t_0}^t i dt \\
 &\underset{\text{given}}{=} v(t_0) + \frac{1}{C} \int_{t_0}^t i dt
 \end{aligned}$$

*split integral*



## RC Circuit



Node method

$$\frac{V_C - V_I}{R} + C \frac{dV_C}{dt} = 0$$

$$RC \frac{dV_C}{dt} + V_C = V_I \quad \textcircled{1}$$

first order differential equation

Given  $V_C(0) = V_0$

$V_I(t) = V_I$  Solve.

(use homogeneous and particular solutions method)

- ① Find Particular soln
  - ② Find homogeneous soln
  - ③ total soln = particular + homogeneous
- $$V_C(t) = V_{CH}(t) + V_{CP}(t)$$
- Homogeneous      Particular

### ① Particular Solution

Any solution that satisfies original equation

$$RC \frac{dV_{CP}}{dt} + V_{CP} = V_I$$

Guess:  $V_{CP} = V_I$

$$\text{Check: } RC \frac{dV_I}{dt} + V_I = V_I$$

0 since  $V_I$  constant ✓

$\frac{dV_{CH}}{dt} = 0$  since  $V_I$  constant ✓

② Homogeneous solution  
↳ solution to homogeneous equation set drive to 0

$$RC \frac{dV_{CH}}{dt} + V_{CH} = 0$$

Guess:  $V_{CH} = Ae^{st}$  need to find A and s  
Substitute:

$$RC \frac{dAe^{st}}{dt} + Ae^{st} = 0$$

$$RC \cancel{As} e^{st} + \cancel{Ae^{st}} = 0$$

$$\cancel{RCs} + 1 = 0 \quad \text{characteristic equation}$$

$$s = -1/RC \Rightarrow V_{CH} = A e^{-1/RC t}$$

③ Total solution

★  $V_C = V_{CP} + V_{CH}$   
 $V_C = V_I + A e^{-1/RC t}$

Find A using initial condition  
 $\text{Given } V_C = V_0 \text{ at } t=0$

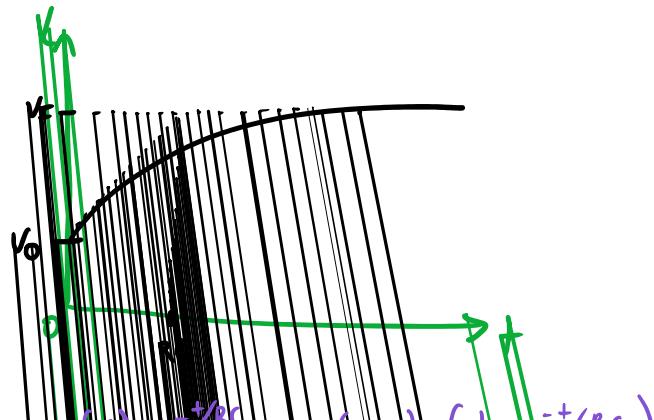
$$\Rightarrow V_0 = V_I + A$$

$$A = V_0 - V_I$$

$$\Rightarrow V_C = V_I + (V_0 - V_I) e^{-1/RC t}$$

□

$$i_C = C \frac{dV_C}{dt} = -\frac{1}{R} (V_0 - V_I) e^{-1/RC t}$$



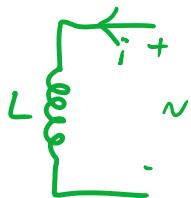
★  $v_c(t) = v_c(0) e^{-t/RC} + v_c(\infty) (1 - e^{-t/RC})$

general form

# W3: Inductors and First Order Circuits

Sunday, October 23, 2016 8:16 PM

## Inductors



$$\lambda = L_i$$

magnetic flux  
 inductance  
 current  
 Webers      Amperes

$$v = \frac{d\lambda}{dt}$$

$$= \frac{dL}{dt} \quad \begin{matrix} \text{Assume } L \\ \text{time invariant} \end{matrix}$$

Inductors and capacitors  
do not dissipate energy  
- they store it  
(or supply it)

$$v = L \frac{di}{dt}$$

$$i = \frac{1}{L} \int_{-\infty}^t v dt$$

$$P = Vi = i \frac{L di}{dt} = \frac{d}{dt} L \frac{i^2}{2}$$

$$E = \frac{1}{2} L i^2$$

<sup>stored in electric field</sup>

for capacitor

$$E = \frac{1}{2} C V^2$$

<sup>stored in magnetic field</sup>

We have just learned the v-i characteristic for a linear inductor:

$$v = L \frac{di}{dt}$$

So the power entering the inductor (as in any two-terminal device) is:

$$P = vi = Li \frac{di}{dt}$$

If we integrate this between two times we get the energy change in the inductor over the interval:

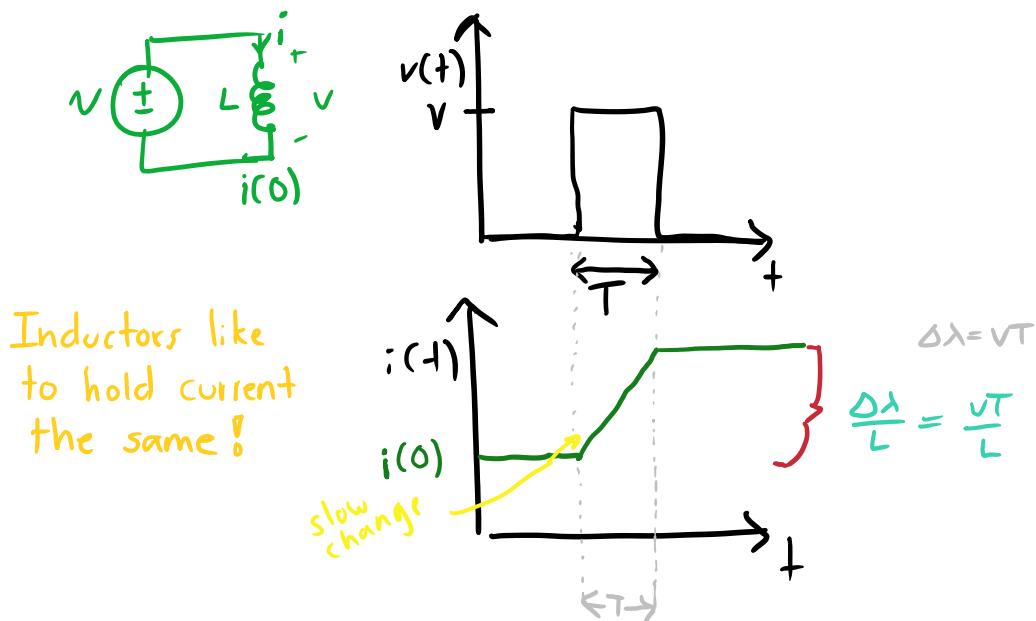
$$\Delta E = \int_{t_0}^{t_1} P(t) dt = \int_{t_0}^{t_1} Li(t) \frac{di(t)}{dt} dt = \frac{1}{2} L(i(t_1))^2 - \frac{1}{2} L(i(t_0))^2$$

So the energy stored in an inductor, as a function of the current through it, is:

$$E = \frac{1}{2} L \cdot i^2$$

## Inductor at voltage source

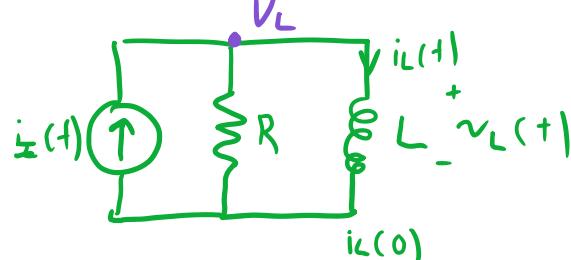
## Inductor at voltage source



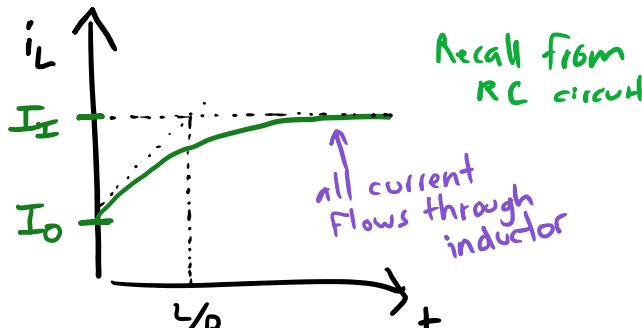
Inductor appears as open  
to external instantaneous  
current change  
 $\Rightarrow$  Voltage spike

Capacitors appears as short  
to external instant  
voltage change  
 $\Rightarrow$  current spike

## RL Circuit



$$\text{Pick: } i_I(t) = I_I \\ i_L(0) = I_0 \quad \text{given}$$



### Node Method

$$\begin{aligned} -i_I + \frac{v_L}{R} + i_L &= 0 \\ -i_I + \frac{L}{R} \frac{di_L}{dt} + i_L &= 0 \\ \frac{L}{R} \frac{di_L}{dt} + i_L &= 0 \quad \text{Time constant} \\ RC \frac{dV_L}{dt} + V_L &= V_I \\ V_C = V_I + (V_0 - V_I) e^{-t/RC} & \\ i_L = I_I + (I_0 - I_I) e^{-t/L} & \end{aligned}$$

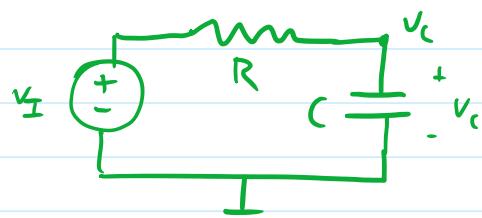
A circuit diagram showing a voltage source  $V$  connected in series with a resistor  $R$  and an inductor  $L$ . The current flows through the circuit in a clockwise direction.

$$i_L = I_I + (I_0 - I_I) e^{-t/\tau_R}$$

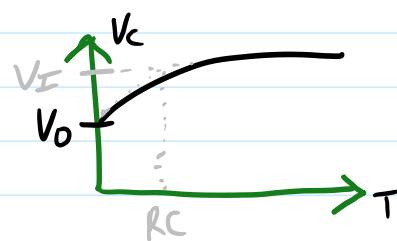
# W3: Speed of Digital Circuits

Monday, October 24, 2016 2:31 PM

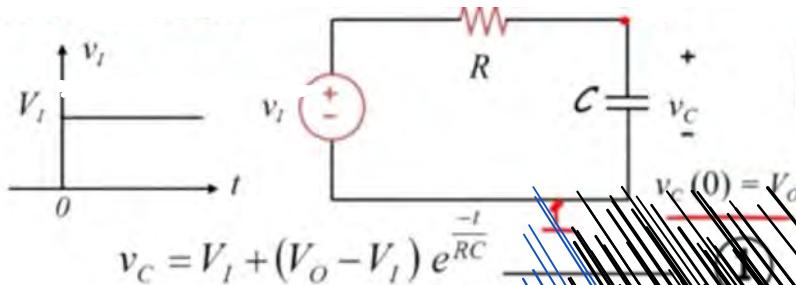
## Review



$$v_C = V_I + (V_0 - V_I) e^{-t/RC}$$



## Intuitive Approach



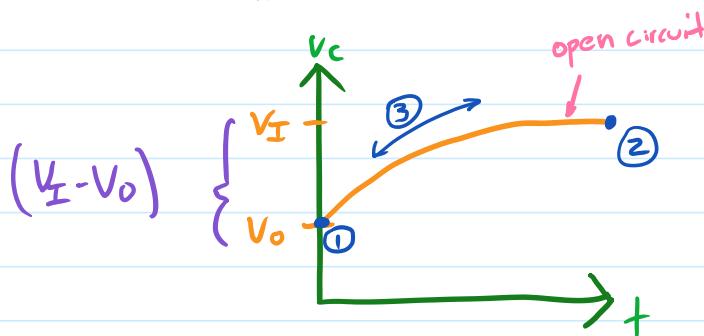
## Two Forms

$$e^{-t/RC}$$

Initial form  
Final point  
Draw line

$$1 - e^{-t/RC}$$

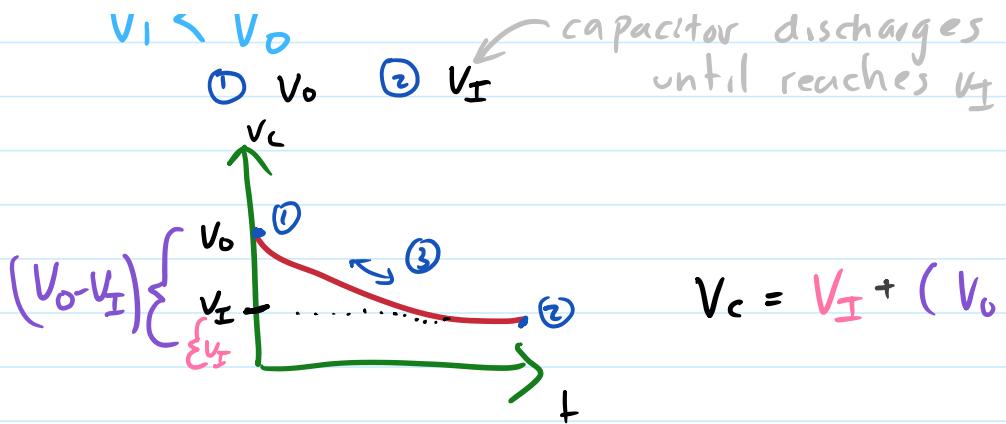
$$V_I > V_0$$



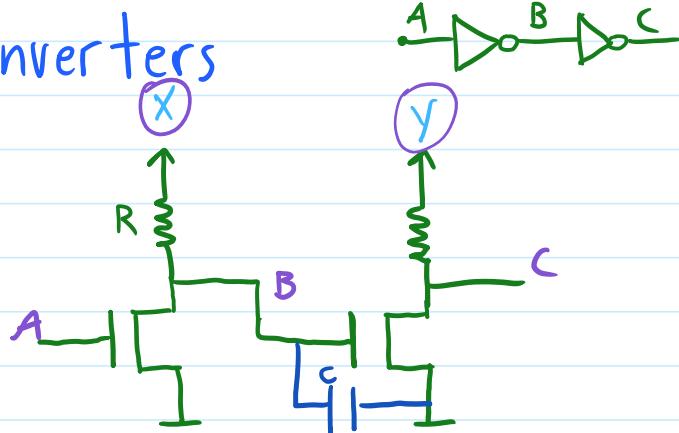
$$V_C = V_0 + (V_I - V_0)(1 - e^{-t/RC})$$

$$V_I < V_0$$

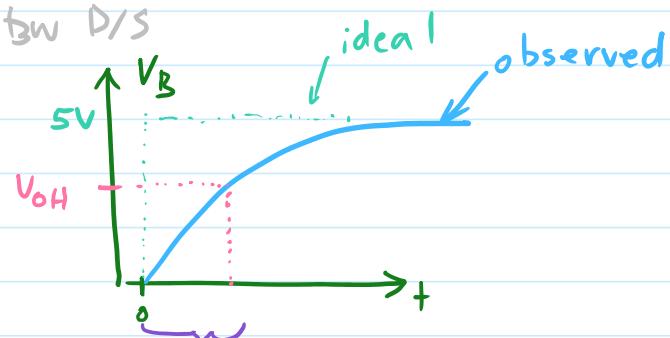
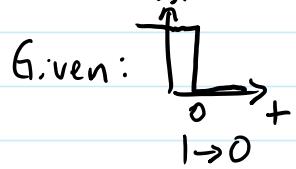
capacitor discharges until reaches V\_I



## Inverters



capacitance of mosfet  
b/w D/S



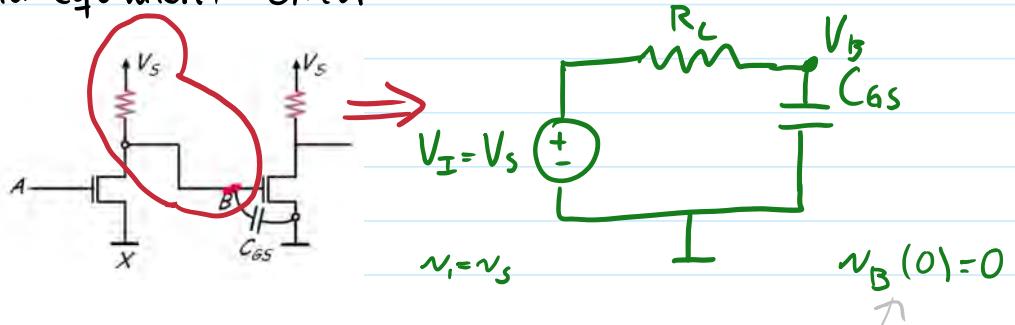
Find delay

time until valid logical value

rising delay  $t_r$  of inverter  $\otimes$

## Rising Delay

① Find equivalent circuit



$\dot{x}$

$C_{GS} \perp$

$v_i = v_s$

$\perp$

$v_B(0) = 0$

Since  $v_B(0) = 0$  capacitor voltage will begin to charge  $\Rightarrow$



$$1 - e^{-t/R_L C_{GS}}$$

$$v_B = V_s (1 - e^{-t/R_L C_{GS}})$$

initial value  $\uparrow$  (Final - Initial)

Sanity check:

$$t=0 \Rightarrow v_B = 0$$

$$t \rightarrow \infty \Rightarrow v_B = V_s \quad (\text{open circuit})$$

② Find rising delay  $t_r$

$$v_B = V_s - V_s e^{-t_r/R_L C_{GS}}$$

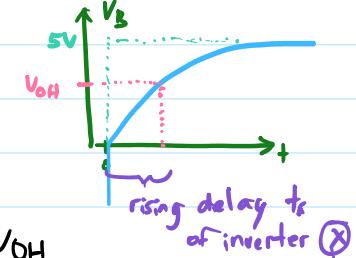
$t_r$ : value of  $t$  for which  $v_B$  reaches  $V_{OH}$

$$V_{OH} = V_s - V_s e^{-t_r/R_L C_{GS}}$$

$$V_s e^{t_r/R_L C_{GS}} = \frac{V_s - V_{OH}}{V_s}$$

$$\frac{-t_r}{R_L C_{GS}} = \ln \left( \frac{V_s - V_{OH}}{V_s} \right)$$

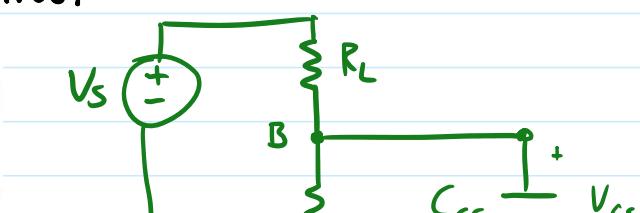
$$\Rightarrow t_r = -R_L C_{GS} \ln \left( \frac{V_s - V_{OH}}{V_s} \right)$$

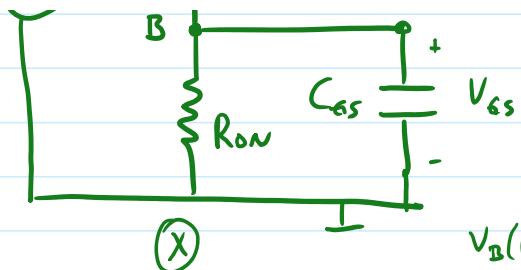
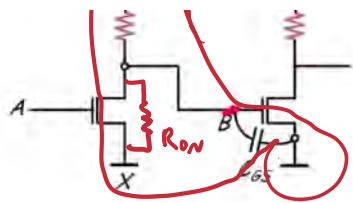


Falling Delay  $t_f$

$t_f$ : time for  $v_B$  to fall from  $V_s$  to  $V_{OL}$

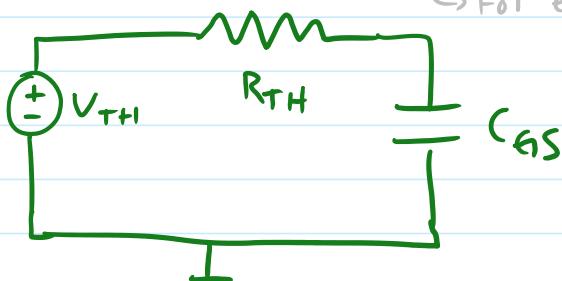
① Equivalent circuit





(1.5) Get Thevenin equivalent

(For easy analysis)



Recall

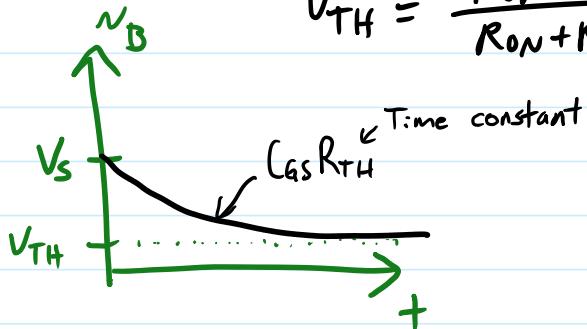
$R_{TH}$ : Turn off sources and find  $R$

$$R_{TH} = R_L \parallel K_{ON} = \frac{R_{ON} R_L}{R_{ON} + R_L}$$

$V_{TH}$ : open circuit voltage

in this case  $\Rightarrow$  voltage divider

$$V_{TH} = \frac{R_{ON}}{R_{ON} + R_L}$$



$$V_B = V_{TH} + (V_S - V_{TH}) e^{-t/R_{TH}C_{GS}}$$

initial value

(2) Find falling delay  $t_f$

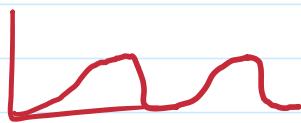
$$V_{OL} = V_{TH} + (V_S - V_{TH}) e^{-t_f/R_{TH}C_{GS}}$$

$$e^{-t_f/R_{TH}C_{GS}} = \frac{V_{OL} - V_{TH}}{V_S - V_{TH}}$$

$$t_f = -R_{TH} C_{GS} \cdot \ln \frac{V_{OL} - V_{TH}}{V_S - V_{TH}}$$

$$t_f = -R_{TH} C_{AS} \cdot \ln \frac{V_{OL} - V_{T,1}}{V_S - V_{TH}}$$

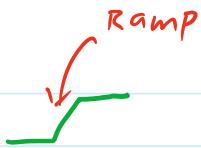
↑  
much smaller than rising delay



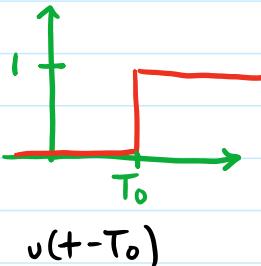
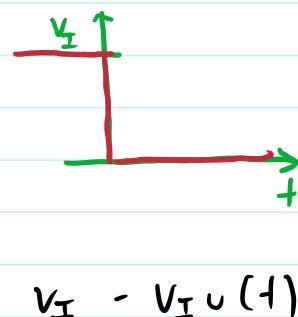
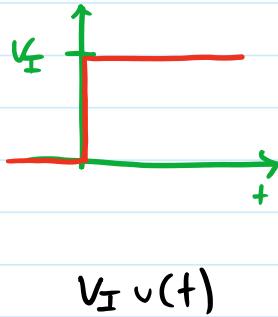
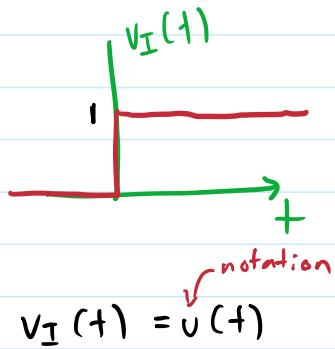
# W4: Ramps, Steps, Impulses

Friday, November 4, 2016 1:06 AM

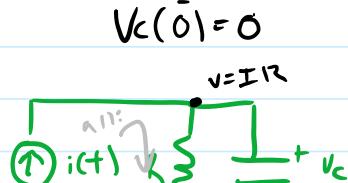
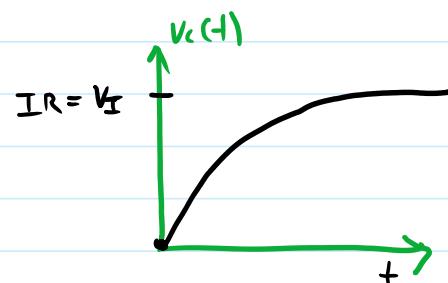
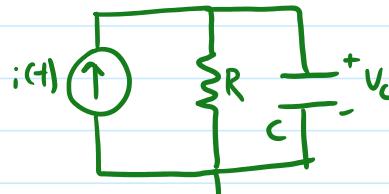
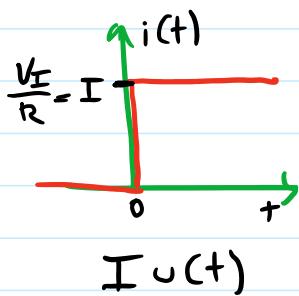
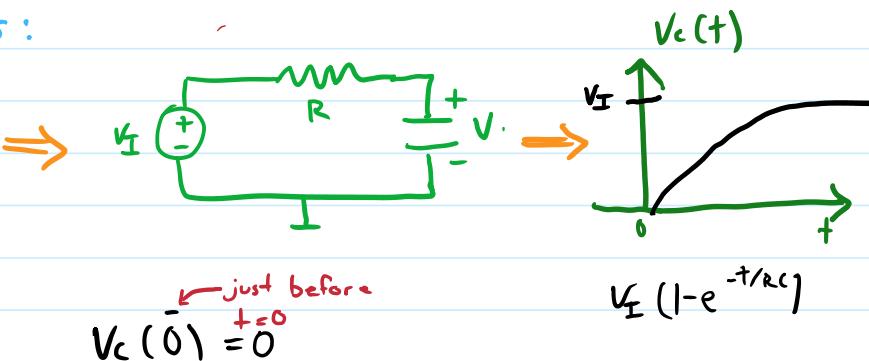
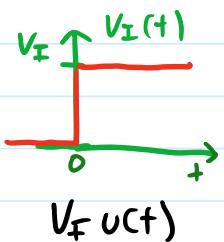
Recall: Trying to achieve  $\text{[step]}$  led to  $\text{[ramp]}$   
instead do



## Step Inputs

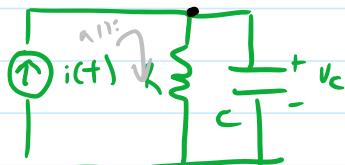


## Responses:





$$I - Iu(t)$$

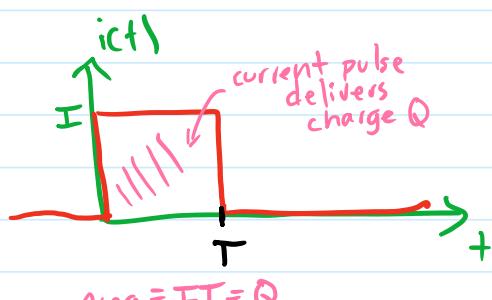
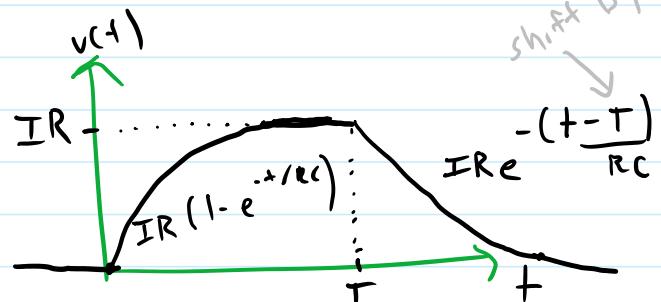
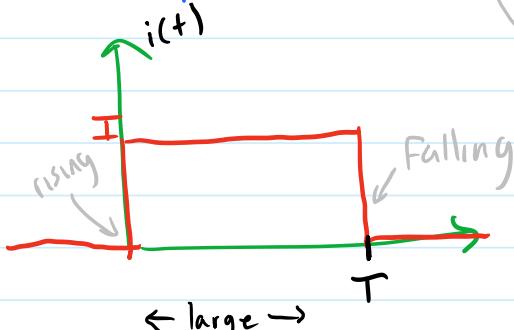


$$V_c(0) = IR$$

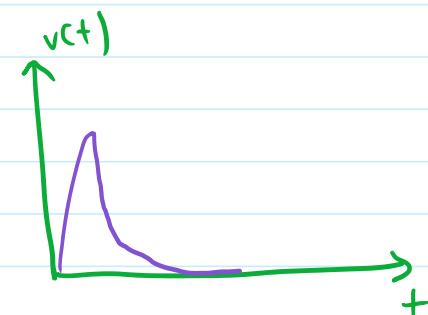
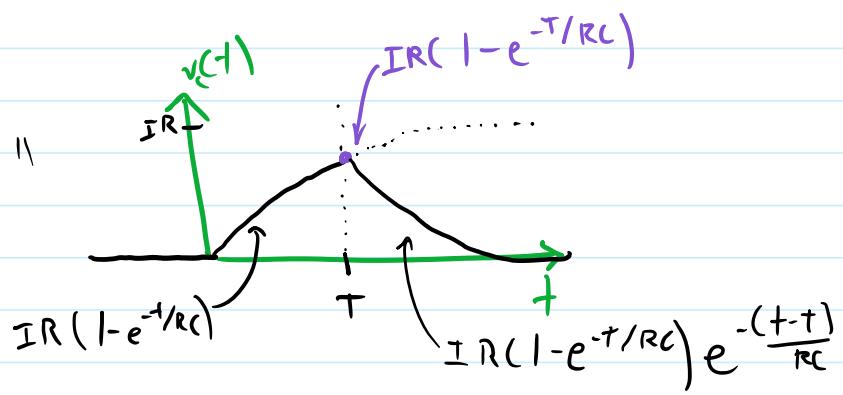
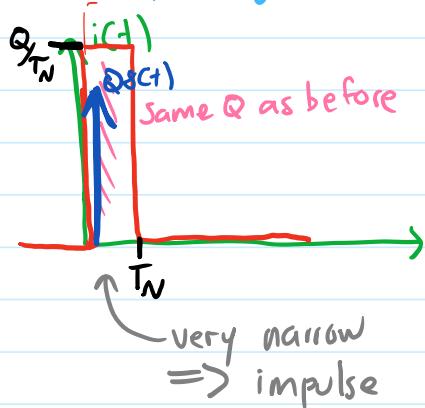
$\curvearrowleft$  capacitor acts as open circuit



Pulse input



Try "squeezing" pulse



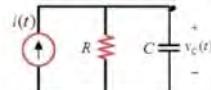
$IT = Q$  becomes impulse

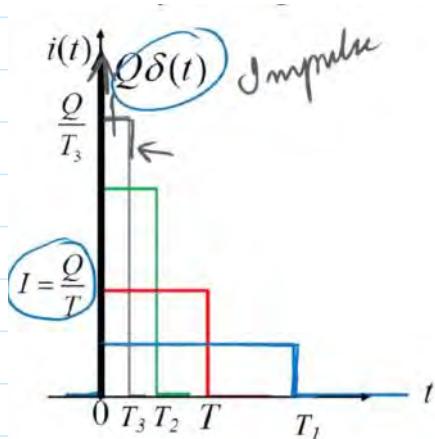
as  $T \rightarrow 0$

$\uparrow$  very tall to deliver same charge

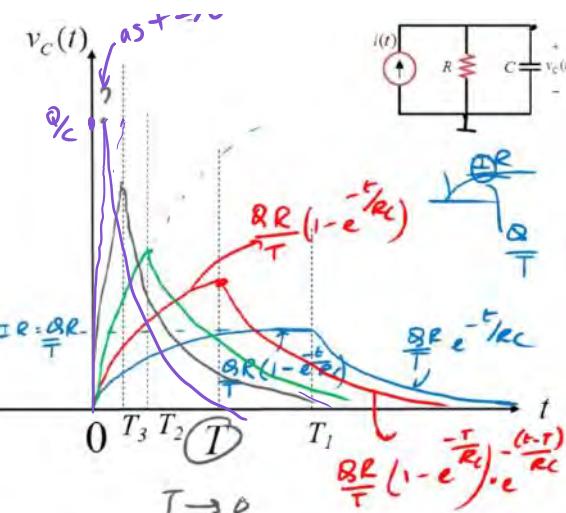
$i(t) \uparrow Q\delta(t)$  Impulse

$v_c(t) \uparrow$  as  $t \rightarrow 0$



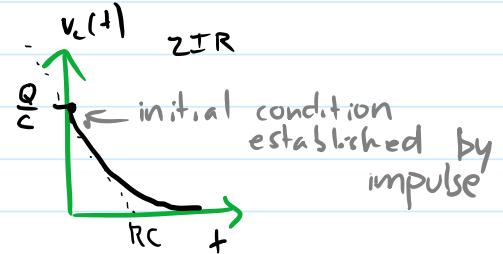
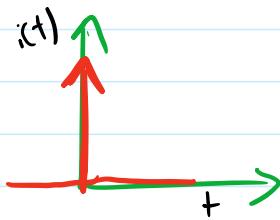


Becomes "impulse" as  $\lim T \rightarrow 0$   
Denoted by  $\delta(t)$   
Impulse is an important signal type



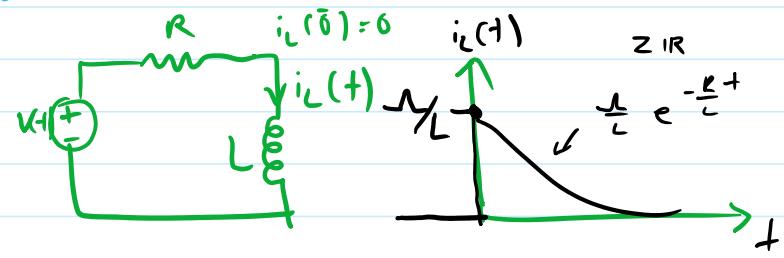
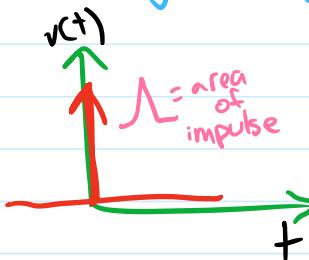
As  $T \rightarrow 0$  all charge deposited into capacitor  
instantaneously  
 $\Rightarrow$  capacitor looks like short

$\Rightarrow$  Impulse established an initial condition on the capacitor =  $Q/C$



- $v_C(t)$  independent of  $T$ .  
what matters is  $Q$ .
- capacitor behaves like short circuit  
for fast changes  $\Pi$
- all charge  $Q$  goes through capacitor

### Voltage Impulse



- Inductor behaves like instantaneous open circuit  
 $\Rightarrow$  all voltage spike across inductor

OPEN CIRCUIT  
⇒ all voltage spike across inductor

## Superposition

- Superposition does not apply when initial conditions exists

To solve:

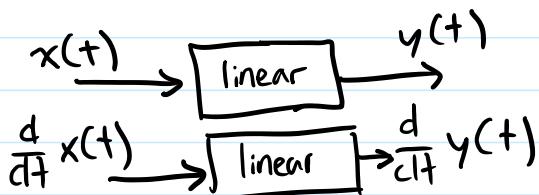
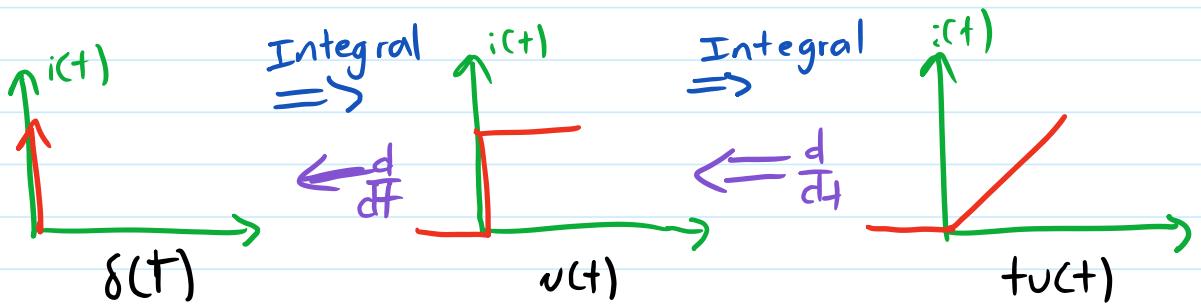
- Treat initial <sup>independent</sup> conditions like sources

① Turn off sources and set initial condts to zero

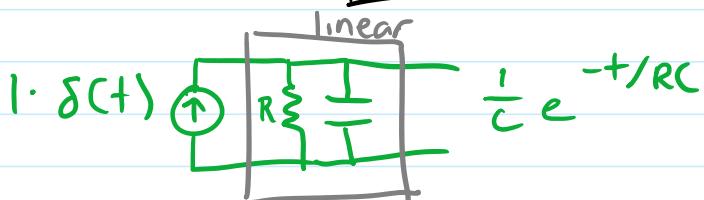
② Find response to each source acting alone

③ Sum up partial responses <sup>and initial condition</sup>

## Impulses, Steps and Ramps



$$\int x(t) \rightarrow \text{linear} \rightarrow \int y(t)$$



$$\int_{-\infty}^t \delta(t') dt' = u(t) \rightarrow \int_0^t \frac{1}{C} e^{-t'/RC} dt' = \frac{1}{C} \left( -\frac{1}{RC} \right) e^{-t/RC} \Big|_0^t = RC \left( 1 - e^{-t/RC} \right)$$

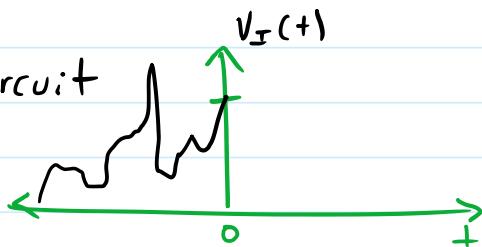
can find <sup>↑</sup> output of an input  
using output for another input ?



## W4: State and Memory

Tuesday, November 15, 2016 10:45 PM

Recall for RC circuit

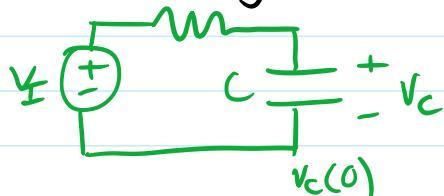


$V_I(0)$  captures entire history of  $V_I$  before  $t=0$

### State

↳ summary of past inputs relevant to predicting the future

state variable  
 $\downarrow$   
 $q = CV$  (for linear capacitors)



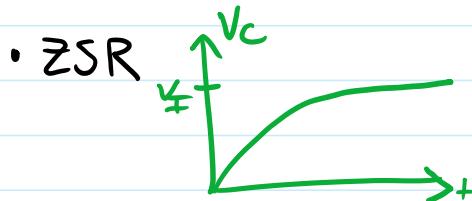
$$V_C = f(V_C(0), V_I(t))$$

$$= V_C(0) + (V_I - V_C(0))(1 - e^{-t/RC})$$

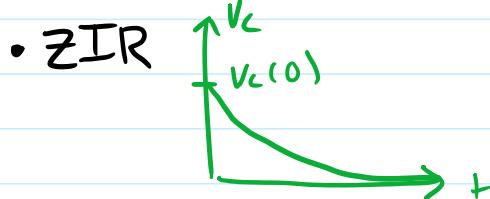
### ZIR and ZSR

↳ Zero Input Response ↳ Zero State Response

- ZS       $V_C(0) = 0$       state of capacitor is zero
- ZI       $V_I(t) = 0$       input is zero



$$V_I(1 - e^{-t/RC}) \quad (2)$$



$$V_C = V_C(0)e^{-t/RC} \quad (3)$$

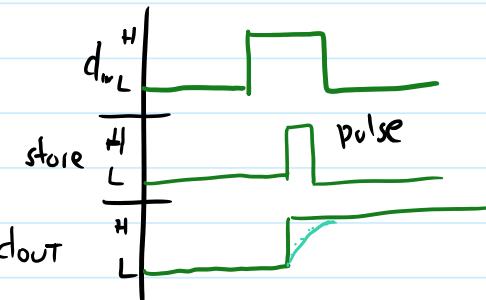
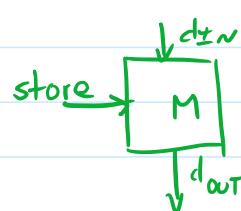
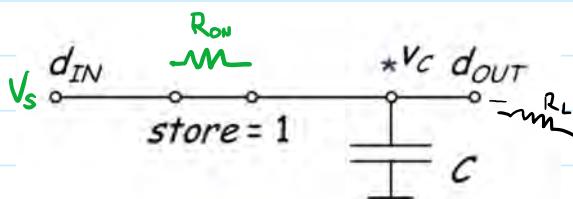
$$V_C = V_I + (V_C(0) - V_I) e^{-t/RC} \quad (1)$$

Note that  $\textcircled{1} = \textcircled{2} + \textcircled{3}$

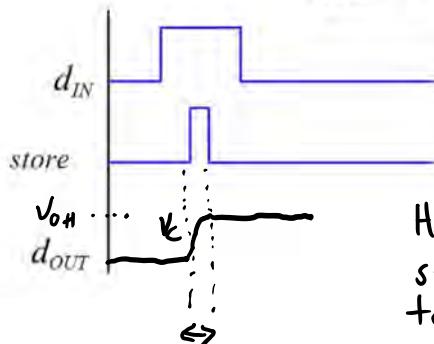
$\Rightarrow \text{Total Response} = ZSR + ZIR$

## Digital Memory

1 bit memory element



If store goes high change  
dout to whatever  $d_{IN}$  is



minimum pulse width

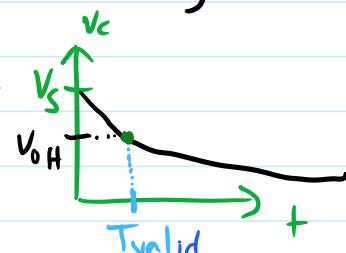
How long does  
store need  
to be on?

$$\text{Recall: } V_C = V_s(1 - e^{-t/R_{ON}C})$$

We need  $V_C$  to be at least  $V_{OH}$  so

$$V_{OH} = V_s(1 - e^{-T_{min}/R_{ON}C})$$

For how long will the capacitor  
store a "1" for?



$$ZIR: \quad V_C = V_s e^{-t/R_{LC}}$$

$$V_{OH} = V_s e^{-T_{valid}/R_{LC}}$$

$$\ln\left(\frac{V_{OH}}{V_s}\right) = -T_{valid}/R_{LC}$$

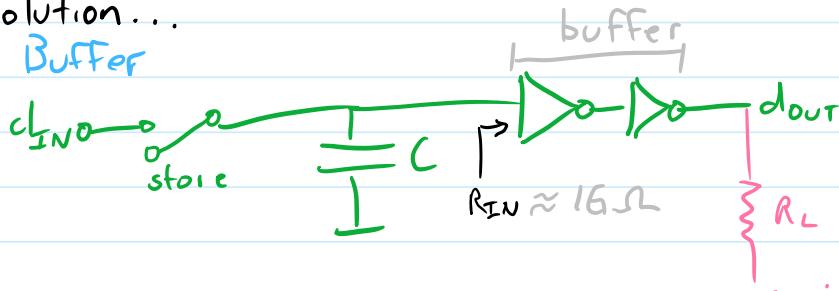
$$\Rightarrow T_{valid} = -R_{LC} \ln\left(\frac{V_{OH}}{V_s}\right)$$

Problem: storage node directly connected to output so  
memory does not hold for long...

Solution:

memory does not hold for long...

Solution...  
Add Buffer

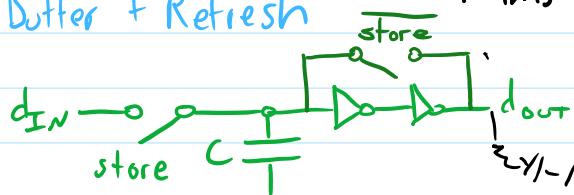


What is Tvalid now?

$$T_{valid} = -R_{IN}C \ln \frac{V_{OH}}{V_S} \approx 1ms$$

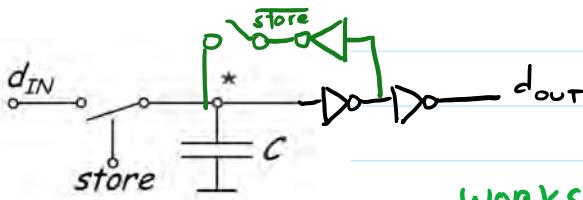
- can control  
↓  
 $R_{IN} \gg R_{on}$  cannot control

Add Buffer + Refresh



does not work since external value can influence storage node

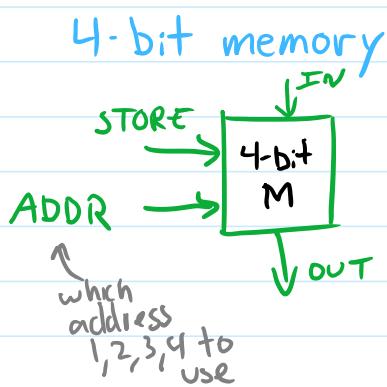
Buffer + decoupled Refresh



works!

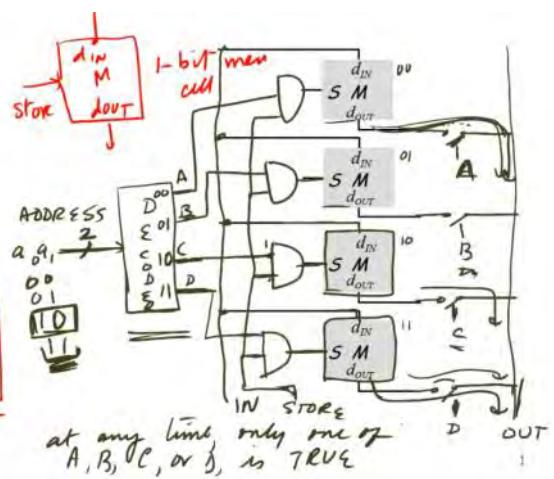
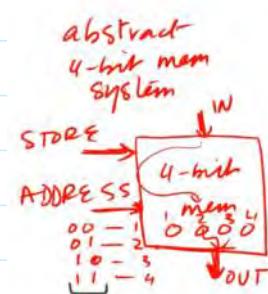
no way for output to affect storage node

Memory Array



A Memory Array

4-bit memory



This is how larger systems are built ☺

# Quiz Z Review

Friday, November 4, 2016 2:45 AM

*Saturation Region Operation of the MOSFET* A MOSFET operates in the saturation region when the following two conditions are met:

$$v_{GS} \geq V_T \quad (7.6)$$

and

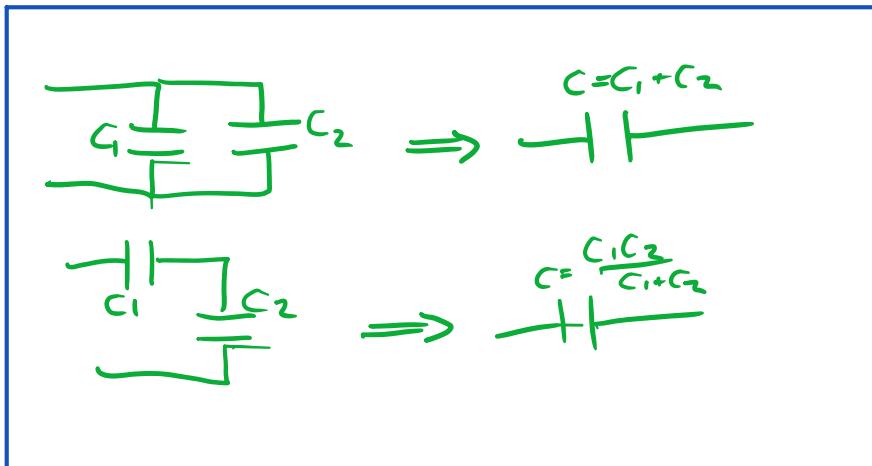
$$v_{DS} \geq v_{GS} - V_T. \quad (7.7)$$

## Transconductance

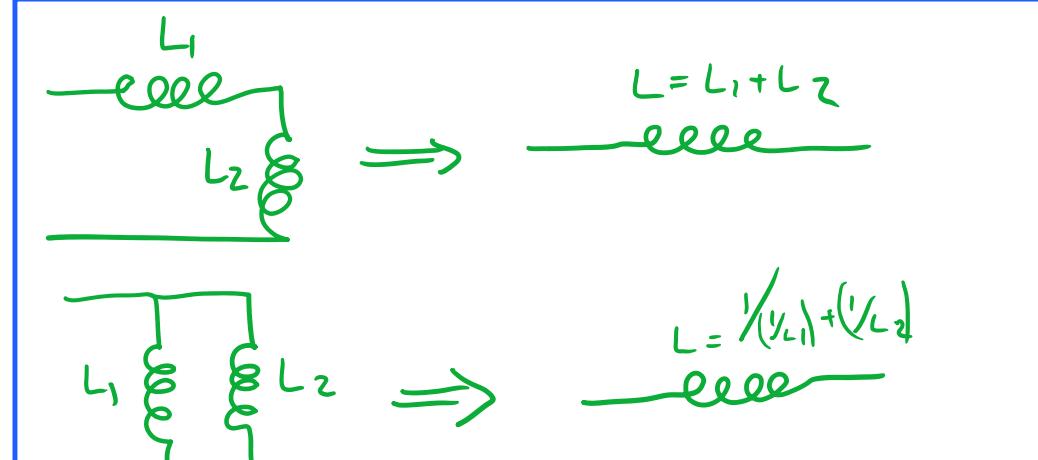
$$g_m = \frac{\partial i_D}{\partial V_{GS}}$$

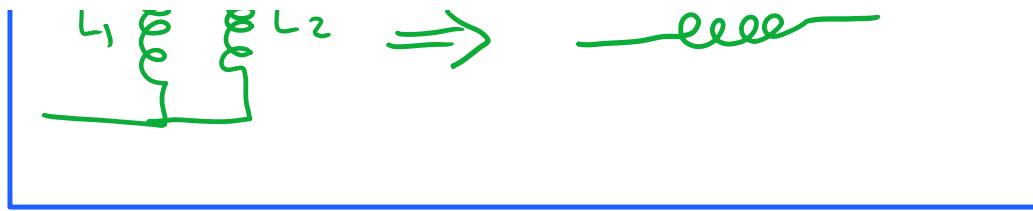
- Decay time constant =  $C_{in} R_{TOTAL}$

Metric prefixes in everyday use				
Text	Symbol	Factor	Power	
exa	E	1 000 000 000 000 000 000	10 <sup>18</sup>	
peta	P	1 000 000 000 000 000 000	10 <sup>15</sup>	
tera	T	1 000 000 000 000 000	10 <sup>12</sup>	
giga	G	1 000 000 000	10 <sup>9</sup>	
mega	M	1 000 000	10 <sup>6</sup>	
kilo	k	1 000	10 <sup>3</sup>	
hecto	h	100	10 <sup>2</sup>	
deca	da	10	10 <sup>1</sup>	
(none)	(none)	1	10 <sup>0</sup>	
deci	d	0.1	10 <sup>-1</sup>	
centi	c	0.01	10 <sup>-2</sup>	
milli	m	0.001	10 <sup>-3</sup>	
micro	μ	0.000 001	10 <sup>-6</sup>	
nano	n	0.000 000 001	10 <sup>-9</sup>	
pico	p	0.000 000 000 001	10 <sup>-12</sup>	
femto	f	0.000 000 000 000 001	10 <sup>-15</sup>	
atto	a	0.000 000 000 000 000 001	10 <sup>-18</sup>	



Current Impulse:  
Capacitor --> Short  
Voltage Impulse  
Inductor --> Open Circuit





Q1

0 points possible (ungraded)

The circuit shown below is called a "common gate amplifier": the input is applied to the source rather than the gate of the MOSFET. As usual, however, the MOSFET is biased so that it is operated in saturation.

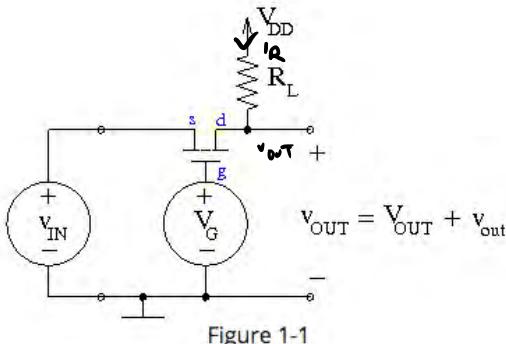


Figure 1-1

The MOSFET's parameters are:  $V_T = 0.9V$  and  $K = 0.018A/V^2$ . The resistance of the load resistor  $R_L = 220.0\Omega$ .

If in the application of this circuit the input voltage  $v_{IN}$  may swing between 1.0V and -2.0V, what is the minimum value of the bias voltage  $V_G$ , in Volts, needed to keep the MOSFET out of cutoff?

$$1.9V \checkmark$$

$$V_{GS} \geq V_T$$

$$V_G - V_{IN} \geq V_T$$

$$V_G - 2 \geq 0.9$$

or

$$V_G - 1 \geq 0.9 \quad \text{so} \quad V_G = 2.9$$

$$V_G = 1.9 \leftarrow \text{min}$$

b)

Assume  $V_G = 3.0V$ , and the input swing is as specified.

What is the minimum value of the power-supply voltage  $V_{DD}$ , in Volts, needed to keep the MOSFET in saturation?

Saturation when:  $V_{DS} \geq V_{GS} - V_T$

$$35.3838 \checkmark$$

c)

Choose the operating point where the input bias voltage  $V_{IN} = 0$ .

Now we go to a small-signal model: what is the transconductance  $g_m$ , in Amperes/Volt, of the MOSFET at the chosen operating point?

$$.0378 \checkmark$$

b) Saturation when:  $V_{DS} \geq V_{GS} - V_T$   $V_{IN} = 1 \text{ or } -2$

$$V_{DS} \geq V_G - V_{IN} - V_T$$

$$V_G = 3$$

$$V_T = .9$$

$$V_{DS} \geq V_a - V_{IN} - V_T \quad V_a = ? \\ V_T = .9$$

$$V_{DS} \geq 3 - 1 - .9 \quad \text{or} \quad V_{DS} \geq 3 + 2 - .9$$

$$V_{DS} \geq 1.1 \quad V_{IN} = 1$$

$$\text{OR} \\ V_{DS} \geq 4.1 \quad V_{IN} = -2 \quad V_{DS} = V_{OUT} - V_{IN}$$

~~$V = I R$~~   
 ~~$I = V/R$~~

$$i_{DS} = \frac{V_{DD}}{R_L} = \frac{k}{2} (V_{GS} - V_T)^2 \quad V_{GS} = V_a - V_{IN}$$

$$\frac{V_{DD}}{220} = \frac{.018}{2} (3 - V_{IN} - .9)^2$$

$$V_{DD} = 22.22 \quad , \text{F} \quad V_{IN} = 1$$

$$\text{OR} \quad V_{DD} = 22.22 \quad , \text{F} \quad V_{IN} = -2$$

$$V_{OUT} - 1 \geq 1.1 \Rightarrow V_{OUT} \geq 2.1 \quad V_{DS} = V_{OUT} - V_{IN}$$

$$V_{OUT} + 2 \geq 4.1 \Rightarrow V_{OUT} \geq 2.1 \quad V_{OUT} = V_{DD} - i_R R_L$$

$$V_{DD} - \frac{k}{2} (V_{GS} - V_T)^2 R_L \geq 2.1$$

$$i_R = i_{DS} = \frac{k}{2} (V_{GS} - V_T)^2$$

$$V_{DD} - \frac{.018}{2} (3 - V_{IN} - .9)^2 R_L \geq 2.1 \quad V_{GS} = V_a - V_{IN}$$

$$\text{IF } V_{IN} = 1$$

$$\text{IF } V_{IN} = -2$$

$$V_{DD} \geq 4.958$$

$$\boxed{V_{DD} \geq 35.3838} \quad \text{IF } V_{IN} = -2$$

$\Rightarrow V_{DD}$  must supply at least 35.38V to allow MOSFET to stay in saturation when  $V_{IN} = -2$

c) Recall:  $g_m = \frac{\partial i_D}{\partial V_{GS}} = \frac{(V_{GS} - V_T)(V_{GS} - V_T)}{2}$

$$\therefore -k/r_1, \dots, -2 - \frac{k}{2} (V_{GS}^2 - 2V_{GS}V_T - V_T^2)^2$$

v  
d vs

$$\begin{aligned}
 i_{DS} &= \frac{k}{2} (V_{GS} - V_T)^2 = \frac{k}{2} (V_{GS}^2 - 2V_{GS}V_T - V_T^2)^2 \\
 \frac{\partial}{\partial v_{GS}} &= \frac{k}{2} (V_{GS} - V_T)^2 = \frac{k}{2} (2V_{GS} - 2V_T)^2 \quad \text{mistake!} \\
 &= \frac{k}{2} (2(V_G - V_{IN})^0 - 2V_T)^2 \\
 &= \frac{0.018}{2} (6 - 2(0.9))^2 = \\
 i_{DS} &= \frac{k}{2} (V_{GS} - V_T)(V_{GS} - V_T) \\
 &= \frac{k}{2} (V_{GS}^2 - 2V_{GS}V_T - V_T^2) \\
 \frac{\partial i_{DS}}{\partial V_{GS}} &= \frac{k}{2} (2V_{GS} - 2V_T) \\
 &= \frac{0.018}{2} (2(V_G - V_{IN})^0 - 2(0.9)) \\
 &= \frac{0.018}{2} (6 - 2(0.9)) = \boxed{0.0378}
 \end{aligned}$$

What is the incremental gain  $\frac{v_{out}}{v_{in}}$  of this circuit at the chosen operating point?

Be careful with signs here.

\*

What is the equivalent incremental input resistance, in Ohms, of this small-signal model?

Note that the incremental input resistance is  $\frac{v_{in}}{i_{in}}$ , where  $i_{in}$  is the current taken from the input voltage source for the voltage  $v_{in}$ .

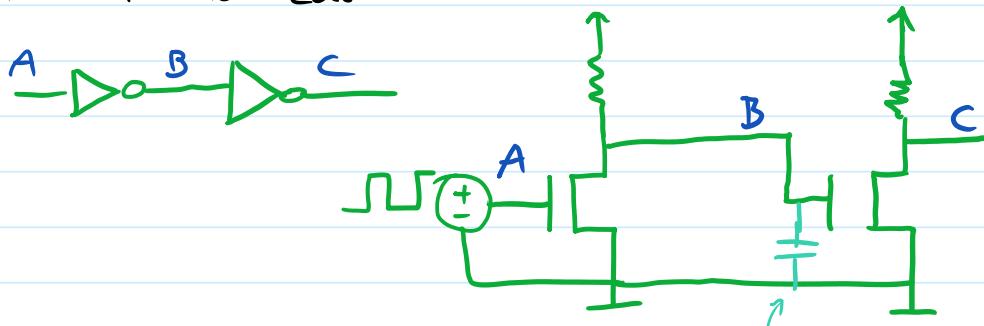
\*

# WI: Undamped Second Order Systems

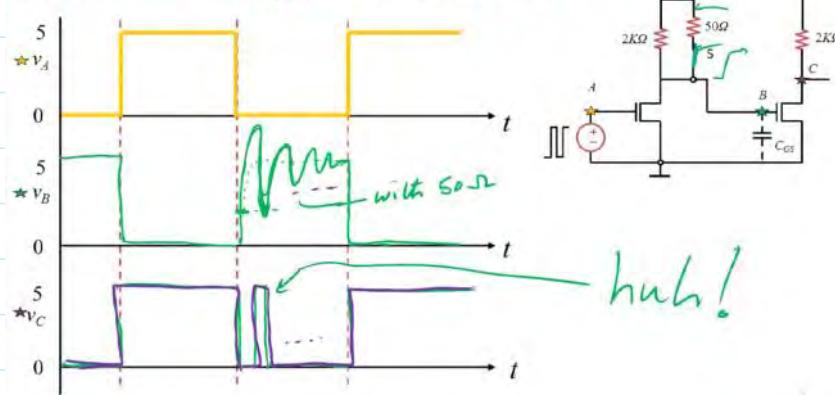
Sunday, November 20, 2016 10:35 AM

Review Complex Algebra  
↳ Appendix C

Recall Slow case

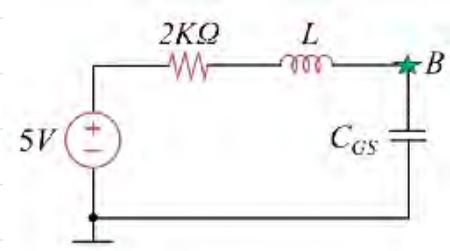
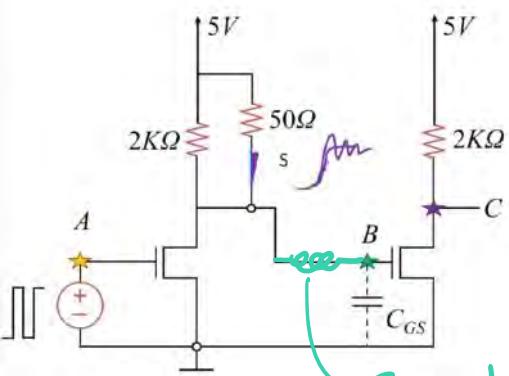


Observed Output - Fast Case

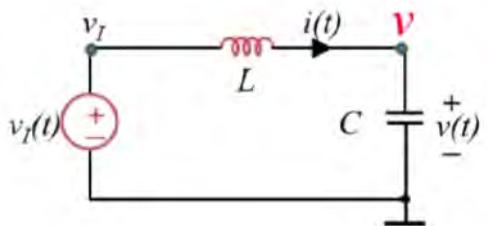


What is happening?

Relevant circuit



LC network      (simpler than RLC)



Node Method

$$i(t) = C \frac{dv}{dt}$$

$$V_I - V = L \frac{di}{dt} \quad \downarrow$$

$$\frac{1}{L} \int_{-\infty}^t (V_I - V) dt = i(t)$$

$$\rightarrow \frac{1}{L} \int_{-\infty}^t (V_I - V) dt = C \frac{dv}{dt}$$

$$\frac{1}{L} (V_I - V) = C \frac{d^2V}{dt^2}$$

$$LC \frac{d^2V}{dt^2} + V = V_I \quad \leftarrow \text{second order equation}$$

Solving second order differential equation

① Find particular solutions

② Find homogenous solution (4 steps)

③ Total solution = sum of particular and homogenous solution.

use initial conditions to solve for constants

① Any solution

$$LC \frac{d^2V}{dt^2} + V_p = V_I$$

Guess

$$V_p = V_I$$

and answer

Guess  
 $V_p = VI$

(2) Solution to  $LC \frac{d^2 V_H}{dt^2} + V_H = 0$  set drive to 0

(2a) Guess functions whose second derivative is same as function.

Guess:  $V_H = Ae^{st}$

Plug in  $\Rightarrow LC A s^2 e^{st} + Ae^{st} = 0$   $A, s = ??$   
 $LC s^2 + 1 = 0$  characteristic equation

(2b)  $s^2 = -1/LC$  characteristic eqtn

(2c) Roots of characteristic equations  $j = \sqrt{-1}$

$s = \pm j \sqrt{1/LC}$  Use  $\omega_0 = \sqrt{1/LC}$  frequency

$s = \pm j\omega_0$

(2d) General solution of homogeneous equation  
 $V_H = A_1 e^{j\omega_0 t} + A_2 e^{-j\omega_0 t}$

(3) Total Solution Given  $v(0)=0$   
 $i(0)=0$

$$V(t) = V_p(t) + V_h(t) \\ = VI + A_1 e^{j\omega_0 t} + A_2 e^{-j\omega_0 t}$$

Find  $A_1, A_2$  using initial conditions

$$V(0) = 0 \rightarrow 0 = VI + A_1 + A_2$$

$$i(0) = 0 \quad i(t) = C \frac{dv}{dt} = CA_1 j\omega_0 e^{j\omega_0 t} - CA_2 j\omega_0 e^{-j\omega_0 t}$$

$$0 = CA_1 j\omega_0 - CA_2 j\omega_0$$

$$\Rightarrow A_1 = A_2$$

$$A_1 = -\frac{VI}{2} = A_2$$

$$A_1 = \frac{-V_I}{Z} = A_2$$

$$v(t) = V_I - \frac{V_I}{Z} \left( e^{j\omega_0 t} + e^{-j\omega_0 t} \right)$$

$t \geq 0$

$$v(t) = V_I - V_I \cos(\omega_0 t)$$

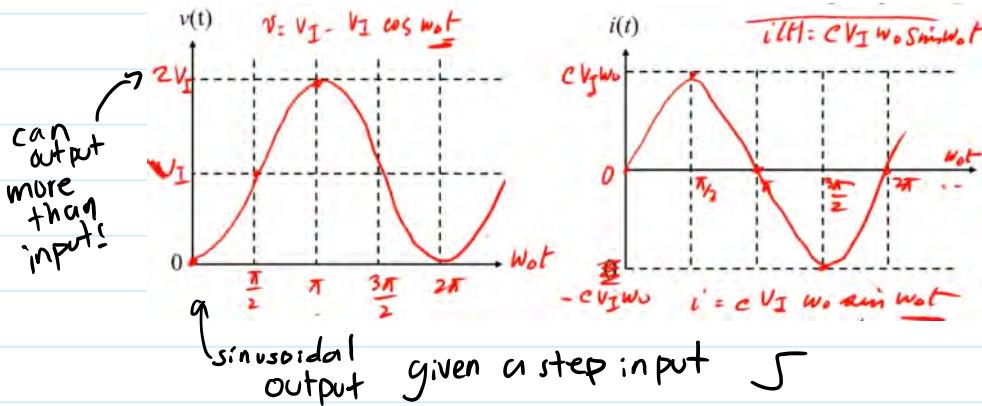
$$i(t) = C \frac{dv}{dt} = C V_I \omega_0 \sin(\omega_0 t)$$

$$e^{jx} = \cos x + j \sin x$$

Euler relation:

Algebraic shortcut

$$\frac{e^{jx} + e^{-jx}}{2} = \cos(x)$$

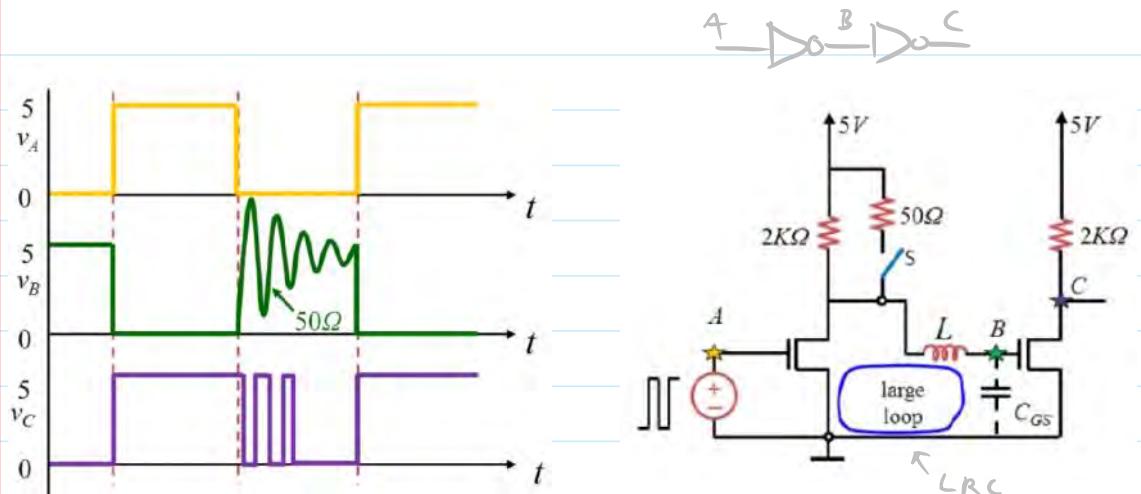


### Summary of Method

- ① Write DE for circuit by applying node method.
- ② Find particular solution  $v_p$  by guessing and trial & error.
- ③ Find homogeneous solution  $v_H$ 
  - A Assume solution of the form  $A e^{st}$ .
  - B Obtain characteristic equation.  $LCs^2 + 1 = 0$
  - C Solve characteristic equation for roots  $s_1, s_2$ .
  - D Form  $v_H$  by summing  $A_i e^{s_i t}$  terms.
- ④ Total solution is  $v_p + v_H$ , then solve for remaining constants using initial conditions.

# W1 : Damped Second Order Systems

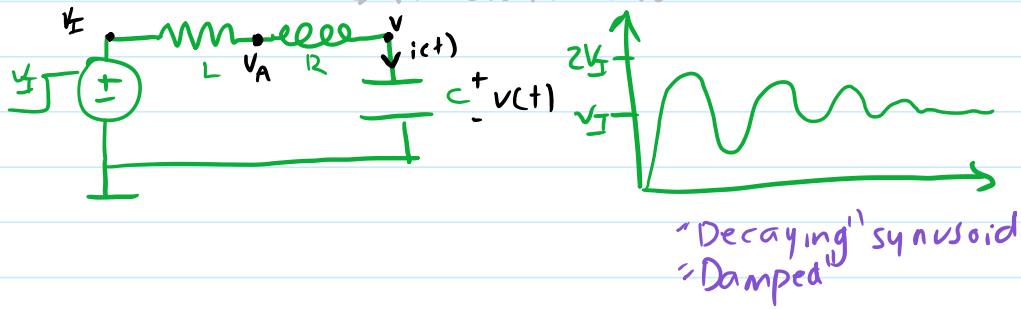
Tuesday, November 22, 2016 8:25 AM



LC Circuit (From last lecture)



LRC Circuit Relevant circuit



ATH 13.6

## Analysis

Node Method:

$$R: \frac{V_A - V}{R} = C \frac{dv}{dt}$$

$$V_A: \frac{1}{L} \int_{-\infty}^{+} (V_I - V_A) dt = \frac{V_A - V}{R}$$

want to get rid of  $V_A$  (to solve for  $v$ )

$$V: V_A = RC \frac{dv}{dt} + v$$

$$\frac{1}{L} \int_{-\infty}^{+} (v - v_A) dt = C \frac{dv}{dt}$$

Review:

$$L: V_L = \frac{L di_L}{dt}$$

$$\frac{1}{L} \int_{-\infty}^{+} v_L dt = i_L$$

$$C: i_C = C \frac{dv_C}{dt}$$

$$\frac{1}{C} \int_{-\infty}^{+} i_C dt = V_C$$

$$\frac{1}{L} \int_{-\infty}^{+\infty} (V_I - V_A) dt = C \frac{dv}{dt}$$

derivative of both sides

$$\frac{1}{L} (V_I - V_A) = C \frac{d^2 v}{dt^2}$$

$$\frac{1}{L} (V_I - V_A - RC \frac{dv}{dt} - v) = \frac{d^2 v}{dt^2}$$

$$\frac{d^2 v}{dt^2} + \frac{R}{L} \frac{dv}{dt} + \frac{v}{LC} = \frac{1}{LC} V_I$$

### Solving differential equation

- ① Find particular solution  $v_p(t)$
- ② Find homogenous solution  $v_h(t)$
- ③ Total solution  $= v_p(t) + v_h(t)$  and solve for constants using initial conditions

For input  $(V_I + v(t))$   $\rightarrow SR$   $v(0) = 0$   $i(0) = 0$

$$① \frac{d^2 v_p}{dt^2} + \frac{R}{L} \frac{dv_p}{dt} + \frac{1}{LC} v_p = \frac{1}{LC} V_I$$

Guess  $v_p = V_I$  ✓

$$② \text{ Solution } \frac{d^2 v_h}{dt^2} + \frac{R}{L} \frac{dv_h}{dt} + \frac{1}{LC} v_h = 0 \quad \boxed{\text{homogenous equation}}$$

$$2.a) \text{ Guess } v_h = A e^{-st} \quad A, s \text{ unknown}$$

Plug-in:

$$A \cdot s^2 e^{-st} + \frac{R}{L} A s e^{-st} + \frac{1}{LC} A e^{-st} = 0$$

$$| \quad s^2 + R/L + 1/RC = 0$$

**Characteristic Equation!!**

$$2.b) s^2 + 2\alpha s + \omega_0^2 = 0 \quad -\text{put } \alpha \text{ in canonical form}$$

$$\omega_0 = 1/\sqrt{LC}$$

$$\alpha = R/2L$$

2.c) Find Roots

$$s_{1,2} = \frac{-\alpha \pm \sqrt{(\alpha^2 - \omega_0^2)}}{2}$$

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$$

$$s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$

2.d) General Solution

$$v = A_+ e^{-s_1 t} + A_- e^{-s_2 t}$$

2d) General Solution

$$v_A = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$v_H = A_1 e^{-\alpha + \sqrt{\omega^2 - \omega_0^2}} t + A_2 e^{-\alpha - \sqrt{\omega^2 - \omega_0^2}} t$$

(3) Total solution:  $v(t) = v_p(t) + v_H(t)$

$$v(t) = V_I + A_1 e^{(-\alpha + \sqrt{\omega^2 - \omega_0^2})t} + A_2 e^{(-\alpha - \sqrt{\omega^2 - \omega_0^2})t}$$

Find  $A_1, A_2$ . We know  $v(0)=0$   $i(0)=0$

$$(1) 0 = V_I + A_1 + A_2 \quad i(t) = C \frac{dv}{dt}$$

$$i(t) = C A_1 (-\alpha + \sqrt{\omega^2 - \omega_0^2}) e^{-\alpha + \sqrt{\omega^2 - \omega_0^2} t} + C A_2 (-\alpha - \sqrt{\omega^2 - \omega_0^2}) e^{-\alpha - \sqrt{\omega^2 - \omega_0^2} t} = 0 \text{ when } t=0$$

$$(2) = (A_1 (-\alpha + \sqrt{\omega^2 - \omega_0^2}) + (A_2 (-\alpha - \sqrt{\omega^2 - \omega_0^2}))$$

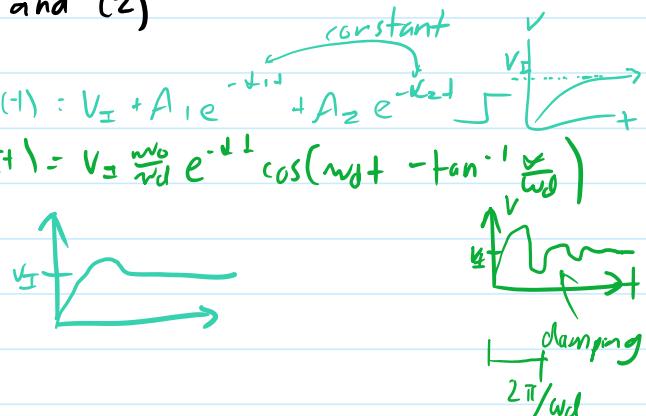
Solve for  $A_1, A_2$  using (1) and (2)

3 cases:

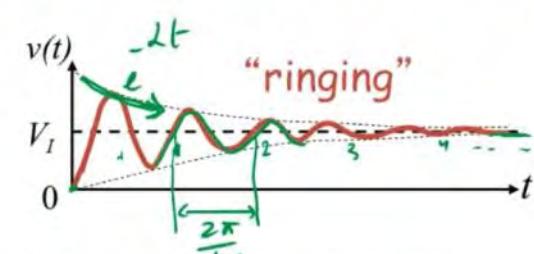
$\omega > \omega_0$ : overdamped :  $v(t) = V_I + A_1 e^{-\alpha_1 t} + A_2 e^{-\alpha_2 t}$

$\omega < \omega_0$ : underdamped :  $v(t) = V_I \frac{\omega_0}{2\pi} e^{-\frac{\alpha t}{2}} \cos(\omega_0 t - \tan^{-1} \frac{\alpha}{\omega_0})$

$\alpha = \omega_0$ : critically damped



Easy way: Characteristic equation tells the whole story!



Characteristic equation  
tells the story  
(for series RLC circuit)

$$s^2 + \frac{R}{L}s + \frac{1}{LC} = 0$$

$$s^2 + 2\zeta s + \omega_0^2 = 0$$

NO DIFF EQS!

from  
char-  
eq

$$\zeta = \frac{R}{2L}, \omega_0 = \frac{1}{\sqrt{LC}}$$

$$\omega_d = \sqrt{\omega_0^2 - \zeta^2}$$

↳ oscillation freq

$\zeta$  governs the rate of decay

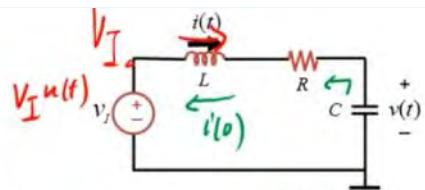
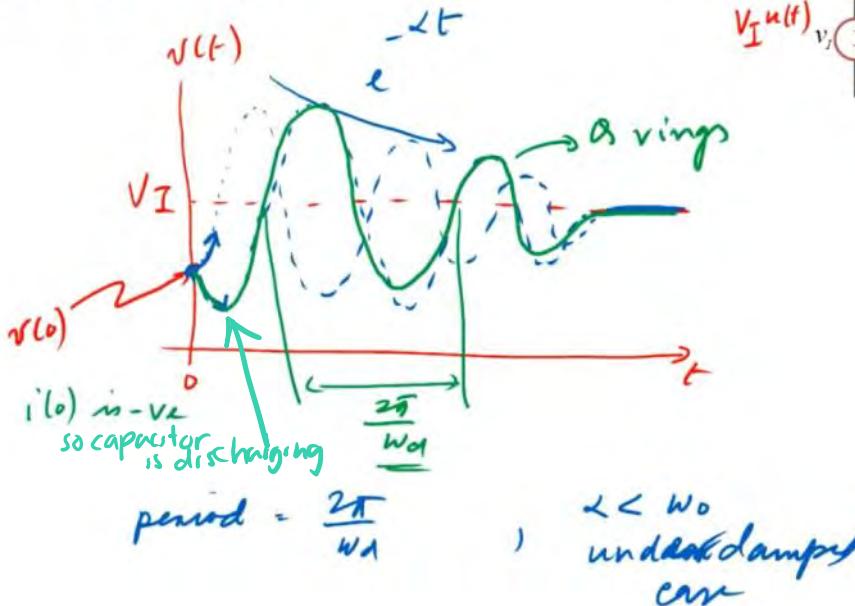
$V_I$  = final val

$v(0)$  = initial val

$Q = \frac{\omega_0}{2\zeta}$  Quality factor  
(approx the number of cycles of ringing)

See Sec. 12.7 of A&L textbook

## Intuitive Analysis



given

$i(0)$  -ve  
 $v(0)$  +ve

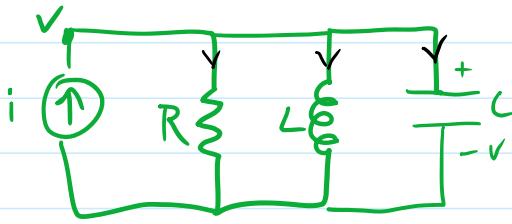
$$\omega = \frac{R}{2L}$$

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

$$\omega_d = \sqrt{\omega_0^2 - \omega^2}$$

$$Q = \frac{\omega_0}{2\omega}$$

## Parallel RLC



$$C \frac{dv}{dt} + \frac{V}{R} - i + \frac{1}{L} \int_{-\infty}^t v dt = 0$$

$$\frac{d^2v}{dt^2} + \frac{1}{RC} \frac{dv}{dt} + \frac{1}{LC} v = i$$

Set drive to 0 to get homogenous equation

$$s^2 + \frac{1}{RC} s + \frac{1}{LC} = 0$$

characteristic equation

$$\zeta = 1/2RC$$

$$\omega_0 = 1/\sqrt{LC}$$

$$\omega_d = \sqrt{\omega_0^2 - \zeta^2}$$

$$Q = \omega_0 / 2\zeta$$

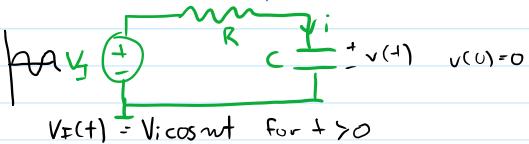
## W2: Sinusoidal Steady State

Tuesday, November 22, 2016 9:01 PM

13.1

- Any signal can be represented as a sum of sinusoids

### Sinusoidal Response of RC Network



Solution:

Could write out diff eq but it gets really hard instead...

- Find Particular solution to another input

$$\frac{RC}{dt} V_{ps} + V_{ps} = V_i e^{st} \quad \text{Related "sneaky path"}$$

$$RC \frac{dV_p e^{st}}{dt} + V_p e^{st} = V_i e^{st} \quad \text{real part of } V_i \cos(\omega t)$$

$$RC V_{ps} e^{st} + V_{ps} e^{st} = V_i e^{st} \quad \text{easy to find}$$

$$V_p (RC_s + 1) = V_i$$

$$V_p = \frac{V_i}{(RC_s + 1)}$$

so now we know:

$$V_p = \frac{V_i}{j\omega RC + 1} \cdot e^{j\omega t} \rightarrow \text{particular solution for } V_i e^{j\omega t} \quad s = j\omega$$

Inverse superposition: Real input  $\rightarrow$  Real output

so to find  $V_p$  from  $V_{ps}$  take the real part of  $V_{ps}$ .

$$V_p = \operatorname{Re}[V_{ps}] = \operatorname{Re}[V_p e^{j\omega t}] = \operatorname{Re}\left[\frac{V_i}{1 + j\omega RC} \cdot e^{j\omega t}\right]$$

complex conjugate

$$= \operatorname{Re}\left[\frac{V_i(1 - j\omega RC)}{1 + \omega^2 R^2 C^2} \cdot e^{j\omega t}\right] = \operatorname{Re}\left[\frac{V_i}{\sqrt{1 + \omega^2 R^2 C^2}} \cdot e^{j\omega t} e^{j\phi}\right] \quad \phi = \tan^{-1}(-\omega RC)$$

$$\Rightarrow V_p = \frac{V_i}{\sqrt{1 + \omega^2 R^2 C^2}} \cos(\omega t + \phi)$$

③ Find  $V_H$

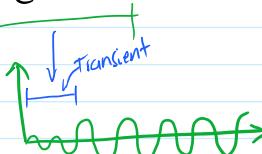
$$V_H = A e^{-t/RC}$$

④ Total Solution:

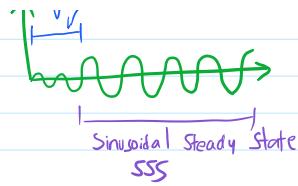
$$V = \frac{V_i}{\sqrt{1 + \omega^2 R^2 C^2}} \cos(\omega t + \phi) + A e^{-t/RC} \quad \tan^{-1}(-\omega RC)$$

Given  $v(0) = 0$

$$A = -V_i \cos(\phi) \quad \frac{\sqrt{1 + \omega^2 R^2 C^2}}{\sqrt{1 + \omega^2 R^2 C^2}}$$



$$A = \frac{-V_i \cos(\phi)}{\sqrt{1 + w^2 R^2 C^2}}$$



All info about SSS is contained in  $V_p$   
ie: step 3 and 4 are unnecessary

$$\frac{V_p}{V_i} = \frac{1}{1+jwRC} = \frac{1}{\sqrt{1+w^2R^2C^2}} e^{j\phi}$$

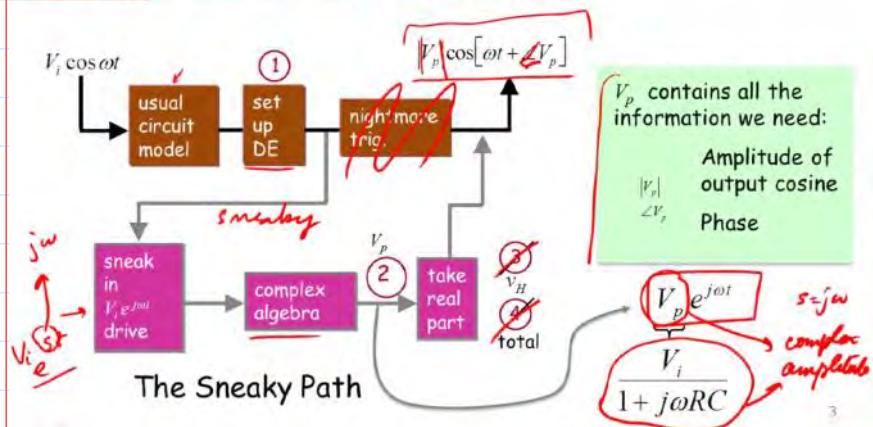
$\phi = j\omega n^{-1} - wRC$

↑  
phase  
magnitude form

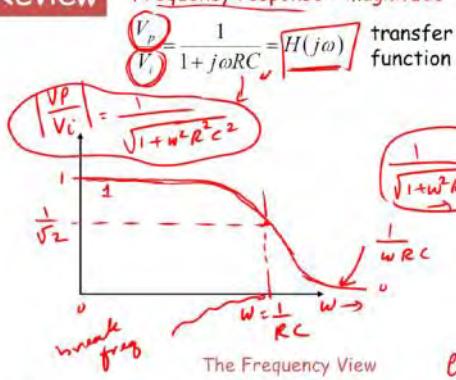
## W2: Impedance Model

Monday, November 28, 2016 6:32 PM

### Review Sinusoidal Steady State SSS Approach

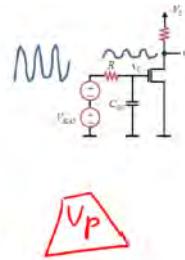
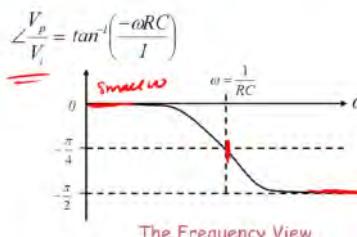


### Review Frequency response - magnitude



$$V_p = \frac{V_i}{1 + j\omega RC}$$

### Review Frequency response - phase

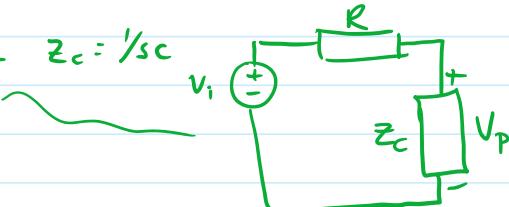


### Finding $V_p$ (more easily)

$$s = j\omega$$

$$\begin{aligned} V_p &= \frac{V_i}{1 + j\omega RC} \\ &= \frac{V_i}{1 + j\omega RC} \quad \text{divide by } 1/jC \\ &= \frac{V_i}{\frac{1}{jC} + R} \quad \text{looks like voltage divider} \end{aligned}$$

divide by  $1/jC$



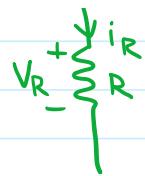
### The Impedance Model

Consider resistor

$$V_R + iR \approx R$$

$$\begin{aligned} i_R &= I_r e^{st} \\ \Rightarrow V_R &= V_r e^{st} \end{aligned}$$

$$\begin{aligned} V_R &= R i_R \\ V_r e^{st} &= R I_r e^{st} \end{aligned}$$



$$i_R = I_R e^{st}$$

$$\Rightarrow V_R = \underline{V_R} e^{st}$$

$$Z_R = R$$

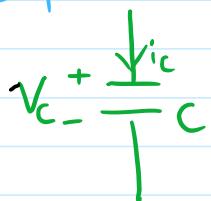
$$V_R = R i_R$$

$$V_R e^{st} = R I_R e^{st}$$

$$V_R = R I_R$$

complex amplitudes related according to ohms law !!

### Capacitor



$$i_C = \underline{I_C} e^{st}$$

$$V_C = V_C e^{st}$$

$$i_C = C \frac{dV_C}{dt}$$

$$I_C e^{st} = C V_C s e^{st}$$

$$I_C = C V_C s$$

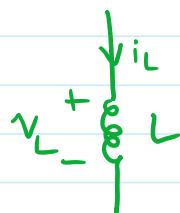
$$V_C = \frac{1}{sc} \cdot I_C$$

$$V_C = Z_C I_C$$

$Z_C$  ← Impedance

complex amplitudes are related by generalization of ohms law.

### Inductor



$$i_L = I_L e^{st}$$

$$V_L = V_L e^{st}$$

$$V_L = L \frac{di_L}{dt}$$

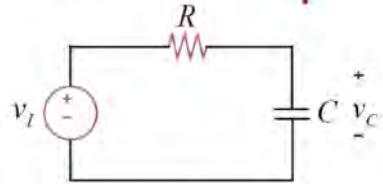
$$V_L e^{st} = L \cdot I_L s e^{st}$$

$$V_L = \frac{L s I_L}{Z_L}$$

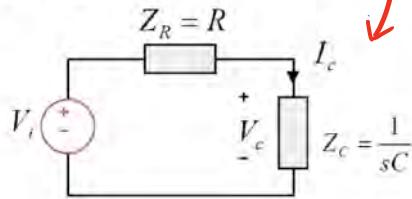
$$V_L = Z_L I_L$$



⇒ For a drive of the form  $V_C e^{st}$ , the complex amplitude  $V_C$  is related to the complex amplitude  $I_C$  by a generalization of ohms law.



Impedance model:



① Replace components with boxes and impedance.

Treat impedance like resistors

② Can solve algebraically!  
(no diff eq)

↳ KVL, KCL  
↳ superposition

$$V_C = \frac{\frac{1}{sC}}{\frac{1}{sC} + R} V_i \quad \text{voltage divider}$$

$$= \frac{1}{1 + sCR}$$

↳ characteristic equation!

## Signal notation pg 716

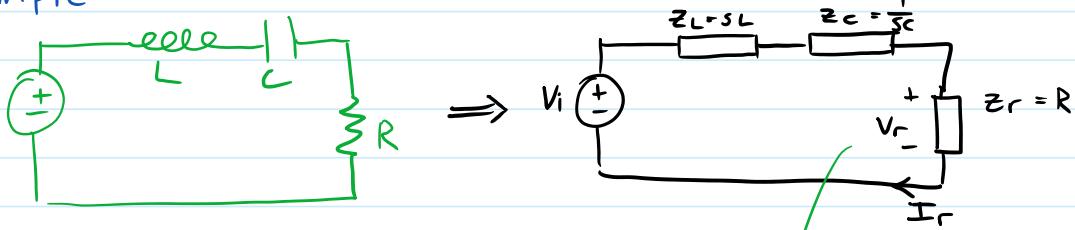
- $V_A$  - DC or operating point variables
- $v_A$  - Total instantaneous variables
- $v_a$  - Small signal / instantaneous variables
- $V_a$  - complex amplitudes

## Impedance Method Summary

1. First, replace the (sinusoidal) sources by their complex (or real) amplitudes. For example, the input voltage  $v_A = V_a \cos(\omega t)$  is replaced by its real amplitude  $V_a$ .
2. Replace circuit elements by their impedances, namely, resistors by  $R$  boxes, inductors by  $Ls$  boxes, and capacitors by  $1/Cs$  boxes. Here  $s = j\omega$ . The resulting diagram is called the *impedance model* of the network.
3. Now, determine the complex amplitudes of the voltages and currents in the circuit by any standard linear circuit analysis technique — Node method, Thévenin method, intuitive method based on series and parallel simplifications, etc.
4. Although this step is not usually necessary, we can then obtain the time variables from the complex amplitudes. For example, the time variable corresponding to node variable  $V_o$  is given by

$$v_O(t) = |V_o| \cos(\omega t + \angle V_o). \quad (13.41)$$

## Example LCR Circuit



$$V_r = \frac{V_i \cdot Z_R}{Z_L + Z_c + Z_R}$$

Voltage divider

$$= \frac{V_i R}{sL + \frac{1}{sC} + R} = \frac{V_i R s/L}{[s^2 + \frac{1}{LC} + \frac{R}{L}s]} \quad \text{characteristic equation}$$

Recall  $|V_r| \cos(\omega t + \angle V_r)$

Transfer function:

$$\frac{V_r}{V_i} = \frac{\frac{j\omega R}{L}}{\frac{1}{LC} + \frac{j\omega R}{L} - \omega^2}$$

Graphically

$$\left| \frac{V_r}{V_i} \right| = \frac{\omega RC}{\sqrt{(1-\omega^2 LC)^2 + (\omega RC)^2}}$$

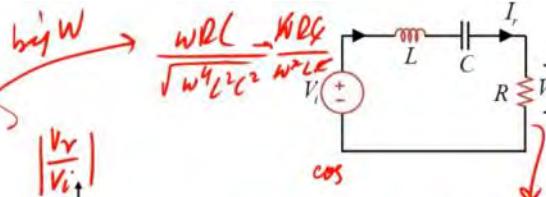
Observe  $\left| \frac{V_r}{V_i} \right|$

$$\text{Low } \omega: \approx \omega RC$$

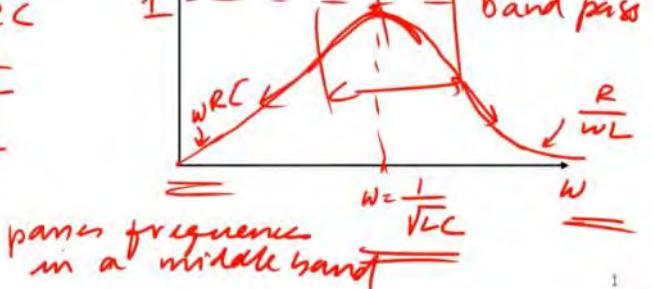
$$\text{High } \omega: \approx \frac{R}{\omega L}$$

$$\omega = \frac{1}{\sqrt{LC}}: \approx 1$$

"attenuates"



$$\left| \frac{V_r}{V_i} \right|$$



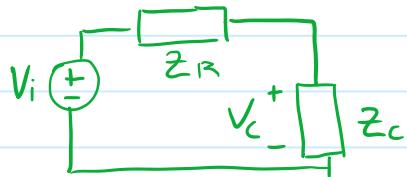
passes frequencies in a middle band

$$\omega = \frac{1}{\sqrt{LC}}$$

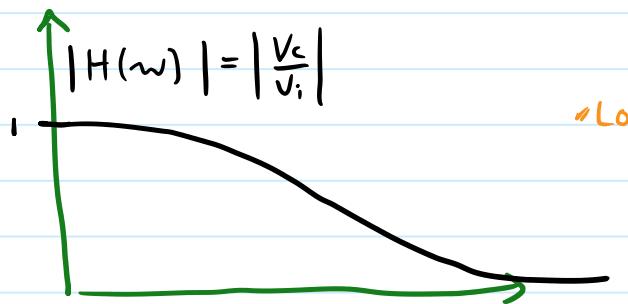
1

## W3: Filters

Wednesday, November 30, 2016 3:51 PM



$$\text{Transfer function} \quad \frac{V_c}{V_i} = \frac{Z_C}{Z_C + Z_R} = \frac{1}{1 + j\omega RC}$$

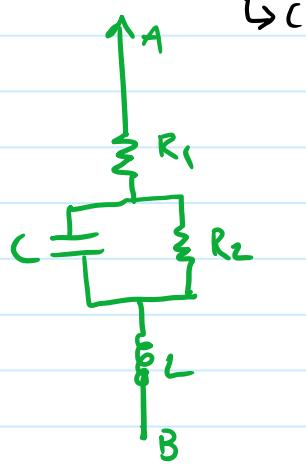


«Low Pass Filter»

- kills high frequency

Recall Impedance Model

↳ can treat impedance like resistor

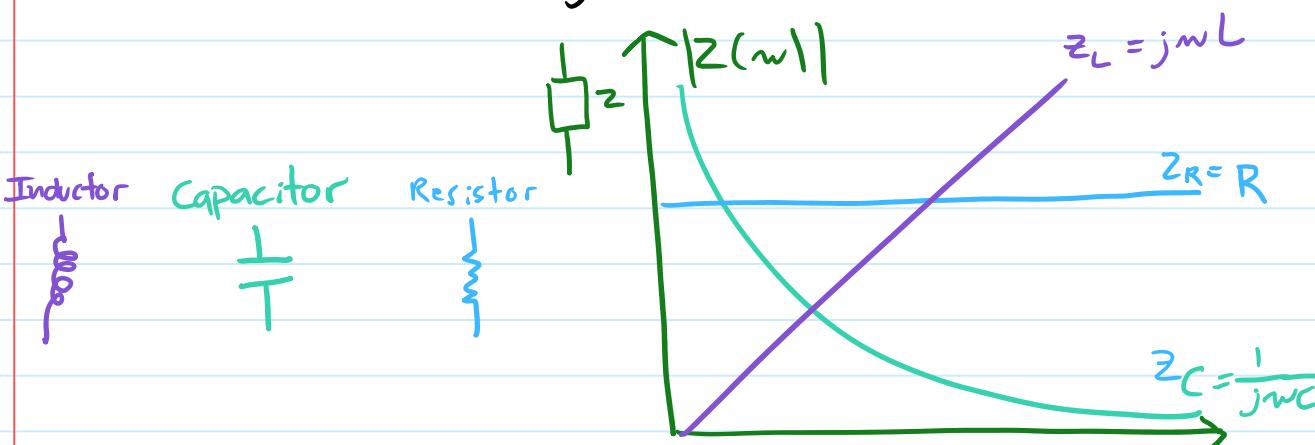


$$Z_{AB} = Z_{R1} + Z_C \parallel Z_{R2} + Z_L$$

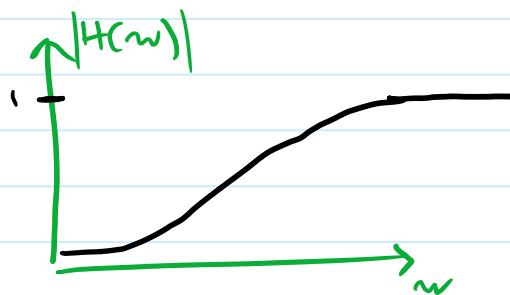
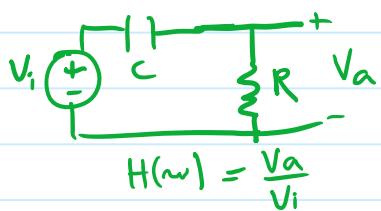
$$\begin{aligned} &= R_1 + \frac{1}{j\omega C} \parallel R_2 + j\omega L \\ &= R_1 + \frac{R_2}{1 + j\omega R_2 C} + j\omega L \end{aligned}$$

Building Filters

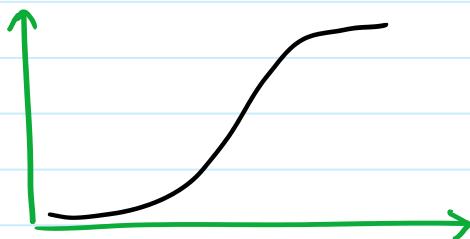
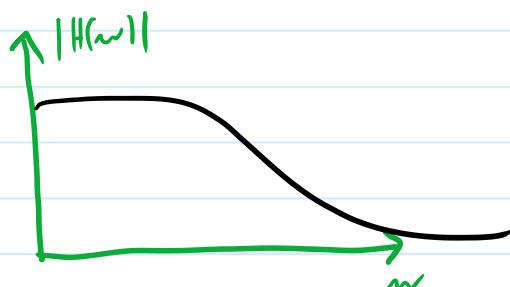
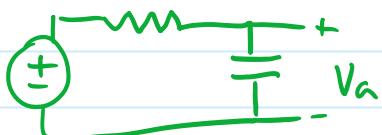
↳ By combining impedances



## High Pass Filter

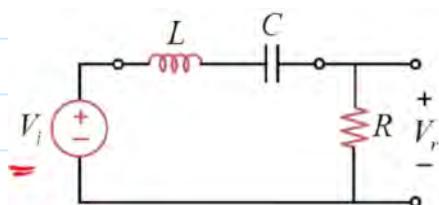


## Low Pass Filter

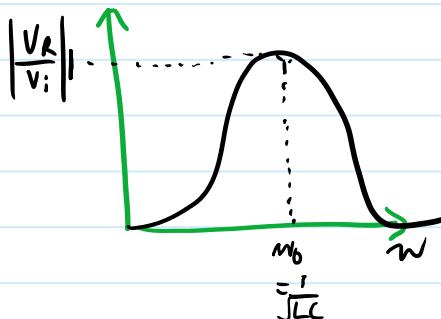


## Example

Find  $\frac{V_r}{V_i}$



$$\frac{V_r}{V_i} = \frac{R}{j\omega L + \frac{1}{j\omega C} + R}$$

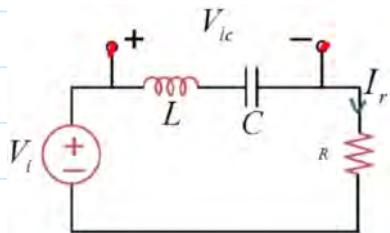


$$\left| \frac{V_r}{V_i} \right| = \frac{\omega R C}{\sqrt{(1-\omega^2 LC)^2 + (\omega R C)^2}}$$

real part      imaginary part

$V_{lc}$

$$Z_{lc} = j\omega L + \frac{1}{j\omega C} = j\omega L - j\frac{1}{\omega C}$$



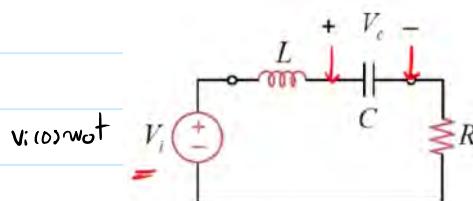
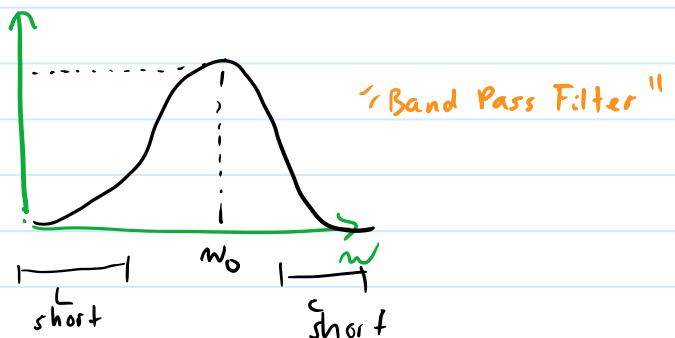
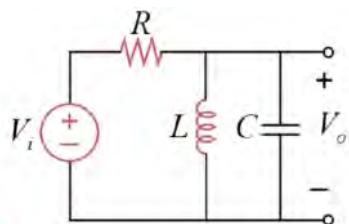
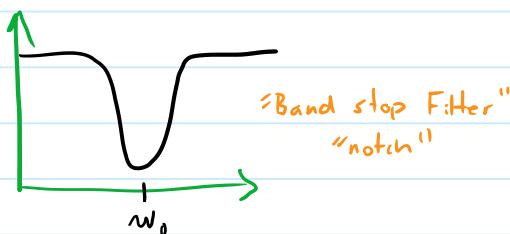
$$Z_{RL} = j\omega L + \frac{1}{j\omega C} = j\omega L - j\omega C$$

$$\text{Set } \omega = \omega_0 = 1/\sqrt{LC}$$

$$Z_{RL} = j\omega_0 L - j/\omega_0 C = j\sqrt{L} - j\sqrt{L} = 0$$

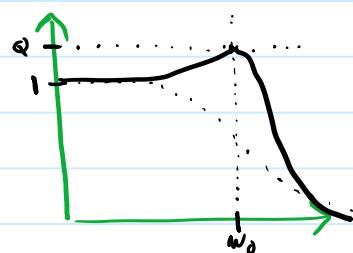
$$V_{LC} = V_L + V_C = I_r j\sqrt{\frac{L}{C}} - I_r j\sqrt{\frac{C}{L}} = 0$$

Drop across inductor = drop across capacitor



$$\frac{V_C}{V_i} = \frac{\frac{1}{j\omega C}}{j\omega L + \frac{1}{j\omega C} + R} = \frac{1}{1 - \omega^2 LC + j\omega RC}$$

$$\left| \frac{V_C}{V_i} \right| = \frac{1}{\sqrt{(1 - \omega^2 LC)^2 + (\omega RC)^2}}$$



$$\omega_0 = 1/\sqrt{LC}$$

$$2\alpha = R/L$$

$$s = j\omega$$

$$\frac{V_C}{V_i} = \frac{\frac{1}{sc}}{sl + \frac{1}{sc} + R} = \frac{1}{s^2 LC + 1 + sRC}$$

$$\frac{V_C}{V_i} \text{ at } s = j\omega_0$$

$$\frac{V_C}{V_i} = \frac{\omega_0^2}{(j\omega)^2 + \omega_0^2 + 2\alpha(j\omega)} = \frac{1/CL}{s^2 + 1/CL + sRC} = \frac{\omega_0^2}{s^2 + s^2 CL + \omega_0^2}$$

$$= \frac{\omega_0^2}{s^2 + 2\alpha s + \omega_0^2}$$

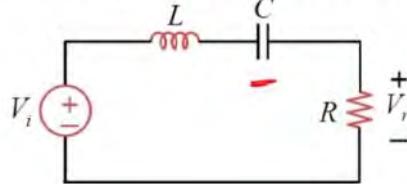
$$\left| \frac{V_C}{V_i} \right| = \frac{\omega_0^2}{2\alpha \omega_0} = \frac{\omega_0}{2\alpha} = Q$$

Characteristic Equation

Magnitude of response  $\left| \frac{V_C}{V_i} \right|$  when  
 $s = j\omega$

Magnitude of response  $\left| \frac{V_r}{V_i} \right|$  when  
 $s = j\omega_0$  is Q

**Selectivity: Look at series RLC in more detail**  
 Show you some fun stuff regarding Q!



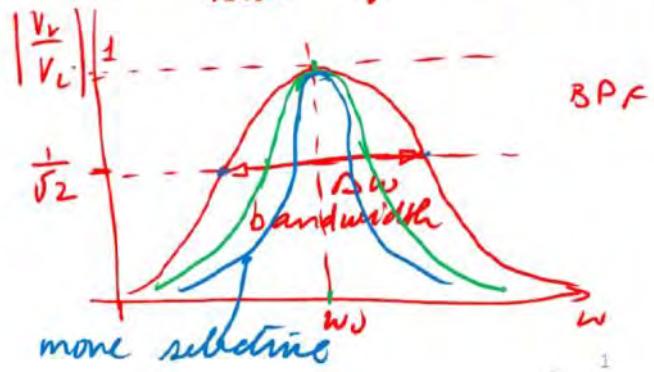
Recall

$$\frac{V_r}{V_i} = \frac{R}{R + j\omega L + \frac{1}{j\omega C}} = \frac{R}{\omega^2 LC + j\omega(RC - \frac{1}{\omega C})}$$

$$\omega = \omega_0 = \sqrt{\frac{1}{LC}}$$

$$j\omega_0 L + \frac{1}{j\omega_0 C} = 0$$

Selectivity  
 Look at  $\frac{\omega_0}{\Delta\omega} = \frac{\text{resonant freq}}{\text{bandwidth}}$   
 higher  $\frac{\omega_0}{\Delta\omega}$ , higher the selectivity



Selectivity

$$= \frac{\omega_0}{\Delta\omega} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

$$\Delta\omega = ?$$

↳ where transfer function  $\frac{V_r}{V_i}$  reaches  $1/\sqrt{2}$

$$\frac{V_r}{V_i} = \frac{R}{R + j\omega L + \frac{1}{j\omega C}}$$



$$= \frac{1}{1 + j\omega \frac{L}{R} - \frac{1}{\omega C R}} = \frac{1}{1 - j(\omega \frac{L}{R} - \frac{1}{\omega C R})}$$

$$\text{Note that magnitude} = \frac{1}{\sqrt{2}} \text{ when } \frac{V_r}{V_i} = \frac{1}{\sqrt{1 + (\omega \frac{L}{R} - \frac{1}{\omega C R})^2}}$$

$$= \frac{1}{1 + j\frac{1}{2}}$$

$$\Rightarrow \omega \frac{L}{R} - \frac{1}{\omega C R} = \pm \frac{1}{2}$$

$$\Rightarrow \omega_1 = \omega_0 \sqrt{1 + \frac{4}{\omega_0^2 R^2 C^2}} = \omega_0 \sqrt{1 + \frac{4}{\omega_0^2 L^2}}$$

$$\omega_2 = \omega_0 \sqrt{1 - \frac{4}{\omega_0^2 L^2}}$$

$$\Delta\omega = \omega_2 - \omega_1 = \frac{\omega_0}{\sqrt{LC}}$$

$$\text{Selectivity} = \frac{\omega_0}{RC} = \frac{\omega_0}{RL} = \frac{\omega_0}{\Delta\omega} = Q$$

High Q → high selectivity

→ more ringing

→ "peakyness" of voltage



We have now seen three definitions for the quality factor Q of a resonant circuit. The first, encountered in Chapter 12, was based on the ratio of the undamped resonant frequency to the damping factor for transient excitation (Equation 12.65):

$$Q = \frac{\omega_0}{2\alpha}. \quad (14.95)$$

The second, derived in this chapter (Equation 14.47), was based on the width of the resonant peak in the frequency response for sinusoidal excitation:

$$Q = \frac{\omega_0}{\omega_2 - \omega_1} \quad (14.96)$$

where  $\omega_2 - \omega_1$  is the bandwidth, and  $\omega_1$  and  $\omega_2$  are the frequencies where the response magnitude is down to 0.707 of its peak value.

The third is the relation in terms of stored and dissipated energy at resonance, Equation 14.91:

$$Q = \frac{\text{Stored energy}}{\text{Average energy dissipated per radian}}. \quad (14.97)$$

These definitions all reduce to the same value for second-order circuits, but they yield slightly different values in higher order circuits.

# W3: Time Domain vs Frequency Domain Analysis

Thursday, December 1, 2016 12:43 AM

13.63

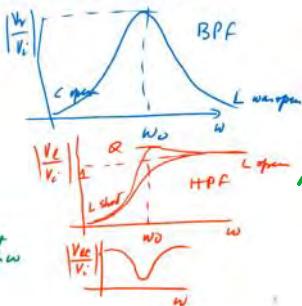
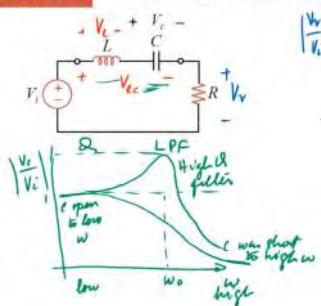
## Review

### Time domain



### Review

### One Circuit, Different Filters



### Filter view

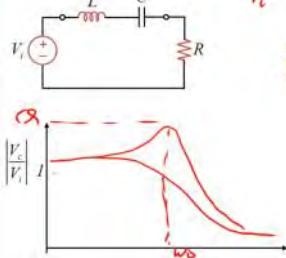
$$V_{in} \left( + \right) \xrightarrow{LPF} V_{out} = |V_{out}| \cos(\omega t + \angle V_{out})$$

complex amplitude

Process input according to frequencies



### Review Q indicates peakiness

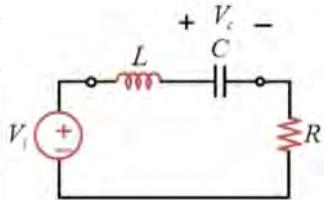


$$\frac{V_c}{V_i} = \frac{1}{sL + \frac{1}{sC} + R} = \frac{1}{s(L + \frac{1}{sC}) + R} = \frac{\omega_0^2}{\omega^2 + \alpha^2 + \omega_0^2}$$

for  $\omega = \omega_0$ , recalling  $s = j\omega$

$$\begin{aligned} \left| \frac{V_c}{V_i} \right| &= Q \\ Q &= \frac{\omega_0}{2\alpha} \\ 2\alpha &= \frac{R}{L} \\ \omega_0 &= \frac{1}{\sqrt{LC}} \end{aligned}$$

Impedance  $\Rightarrow$  Time domain



$$\frac{V_c}{V_i} = \frac{\omega_0^2}{s^2 + 2\alpha s + \omega_0^2}$$

① Replace s's with  $\frac{d}{dt}$

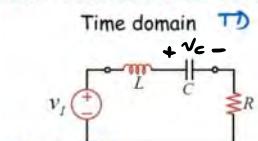
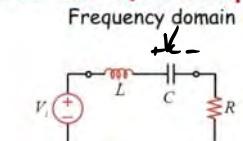
$$V_c(s^2 + 2\alpha s + \omega_0^2) = V \cdot \omega_0^2$$

$$\frac{d^2 V_c}{dt^2} + 2\alpha \frac{d V_c}{dt} + \omega_0^2 V_c = \omega_0^2 v(t)$$

for example step input

$$Q = \frac{\omega_0}{2\alpha} = \frac{\omega_0}{\gamma_L}$$

Let's use Q to compare time domain and frequency domain



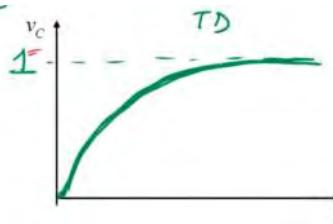
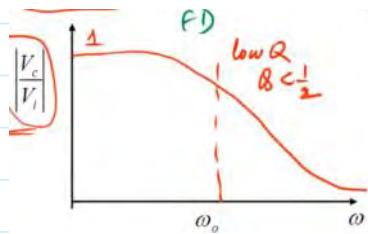
Sinusoid  
 $v_I = V_i \cos \omega t$

Unit step  
 $v_I = u(t)$

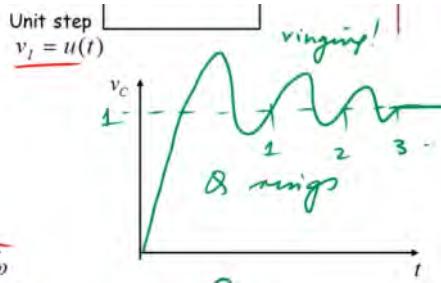
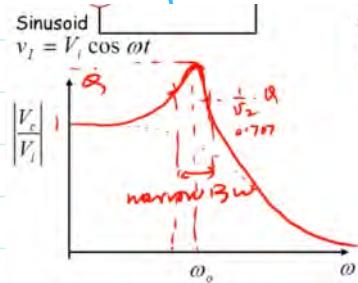
$$\begin{aligned} Q &= \frac{\omega_0}{2L} \\ \omega_0 &= \frac{1}{\sqrt{LC}} \\ 2L &= \frac{R}{Q} \end{aligned}$$

3 cases:  
 $\zeta > \omega_0$ , or  $Q = \frac{\omega_0}{2L} < \frac{1}{2}$  → over damped  
 $\zeta < \omega_0$ , or  $Q = \frac{\omega_0}{2L} > 1$  → under damped  
 $\zeta = \omega_0$ ,  $Q = \frac{1}{2}$  → critically damped

## Over damped case



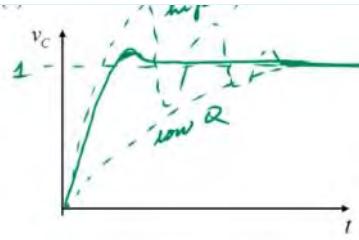
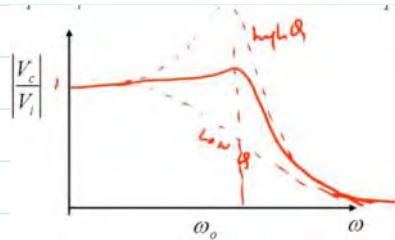
## Underdamped Case



Q: Peakiness

Q: ringiness

## Critically Damped Case



# W4: Operational Amplifier

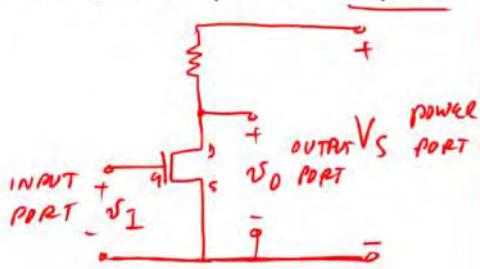
Monday, December 12, 2016 4:31 PM

"Op-amp"

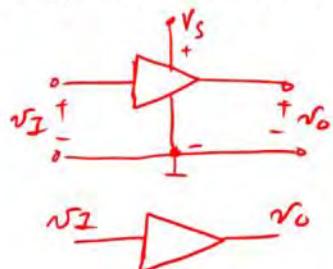
Chapter 15

## Review

- MOSFET amplifier - 3 ports

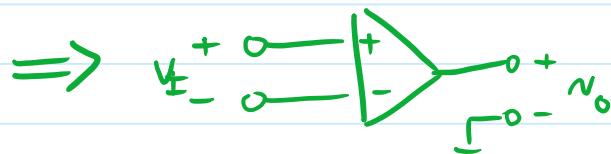
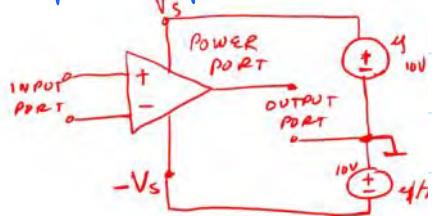


- Amplifier abstraction

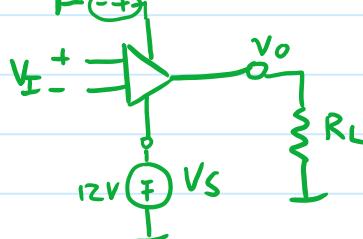
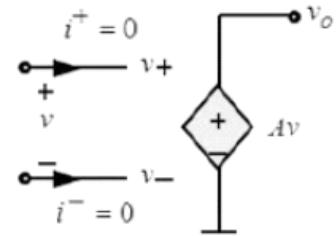


Basic Building block for analog circuits

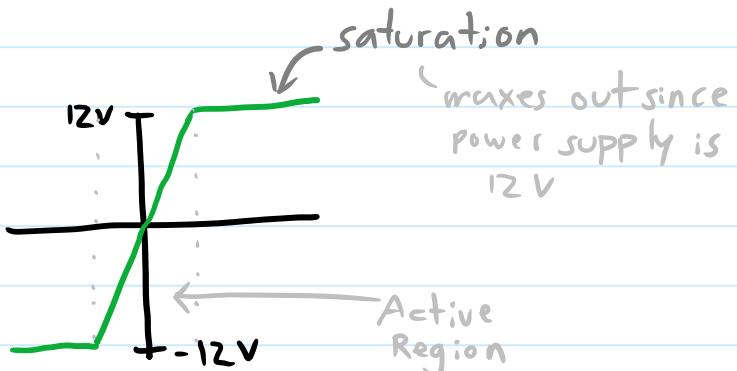
## Op Amp Abstraction



## Equivalent circuit



$A \sim \infty$



in reality,  $A$  is unstable aka not reliable

## Non-inverting Amplifier

negative feedback

Equivalent Circuit

## Analysis

① Find  $V_o$  in terms of  $V_I$

$$V_o = A(V^+ - V^-)$$

$V_I \leftarrow$        $\frac{V_o R_2}{R_1 + R_2} \right] \text{- Voltage divider}$

$$= A\left(V_I - \frac{V_o R_2}{R_1 + R_2}\right)$$

$$V_o \left(1 - \frac{A R_2}{R_1 + R_2}\right) = A V_I$$

$$V_o = \frac{A V_I}{1 - \frac{A R_2}{R_1 + R_2}}$$

when  $A$  is large

$$V_o \approx V_I \cdot \frac{R_1 + R_2}{R_2} \left[ \begin{array}{l} \text{- external components} \\ \text{Gain} \end{array} \right]$$

- not dependent on  $A$

## Negative Feedback

- If the output is perturbed the circuit will quickly pull up/down to "fix"

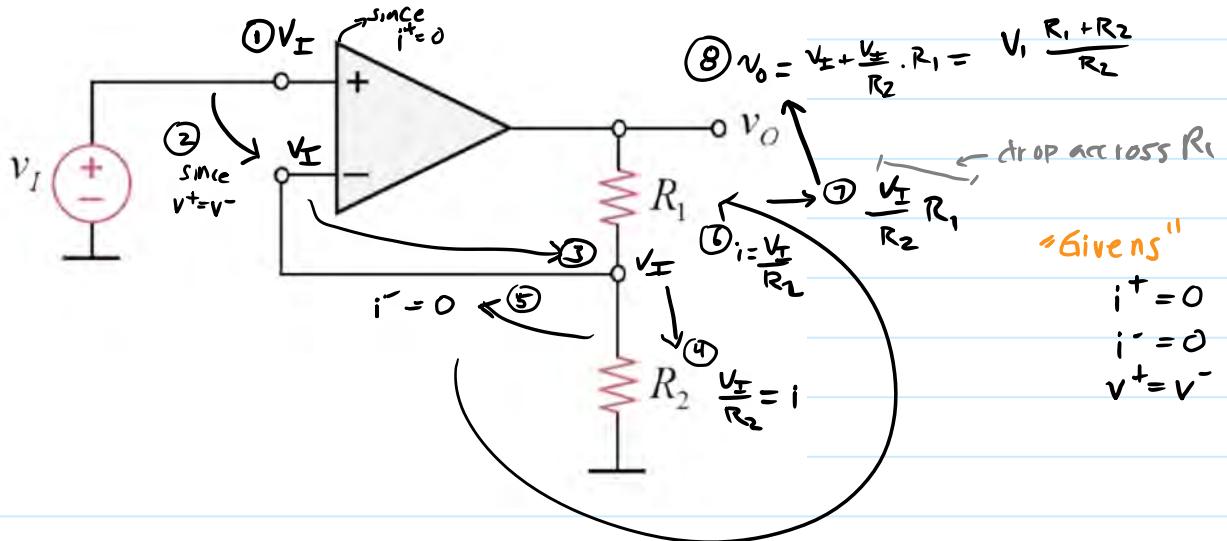
$\Rightarrow$  Output does not change

$$\Rightarrow V^+ - V^- = 0 \Rightarrow V^+ = V^-$$

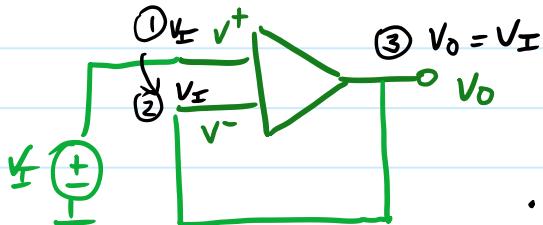
only under negative feedback

virtual short method

## Example (8 steps)



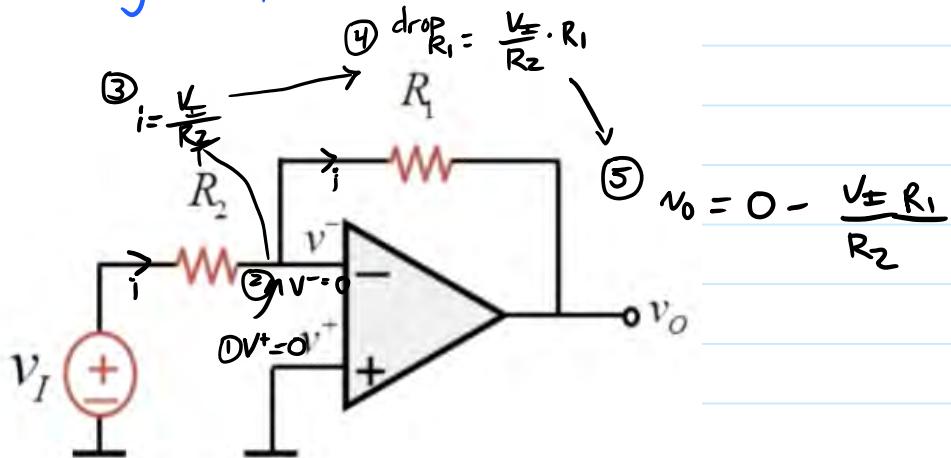
## Buffer Circuit



"Source Follower"

- Used to isolate sources from the rest of the system

## Inverting Amplifier



## Input Resistance

- Apply a  $V_I$  at input  $\rightarrow$  measure current  $i_I$   
 $\Rightarrow \text{Impedance} = \frac{V_I}{i_I} = R_{IN}$

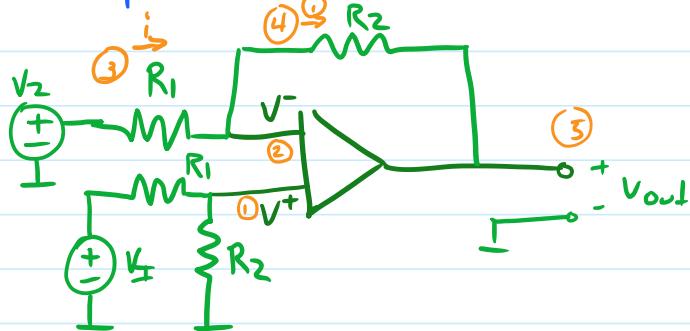
$$R_{IN} = \frac{V_T}{I} = \frac{V_T}{V_T/R_2} = R_2$$

if need as a function of A need  
to use equivalent circuit method

# W4: Operational Amplifier Circuits 15.5, 15.6

Tuesday, December 13, 2016 12:08 AM

## Op Amp Subtractor



$$\textcircled{1} \quad v^+ = V_1 \frac{R_2}{R_1 + R_2}$$

$$\textcircled{2} \quad v^+ = v^-$$

$$\textcircled{3} \quad i = \frac{V_i - V^-}{R_1}$$

$$\textcircled{4} \quad \downarrow = i$$

$$\textcircled{5} \quad V_{\text{out}} = V^- - iR_2$$

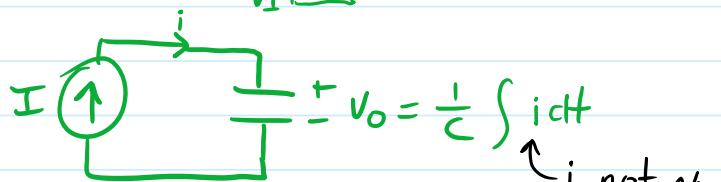
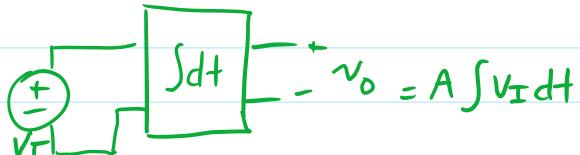
$$= V^- - \frac{V_2 - V^-}{R_1} \cdot R_2$$

$$= V_i \left( \frac{R_2}{R_1 + R_2} \right) \left( \frac{R_1 + R_2}{R_1} \right) - \frac{V_2 R_2}{R_1}$$

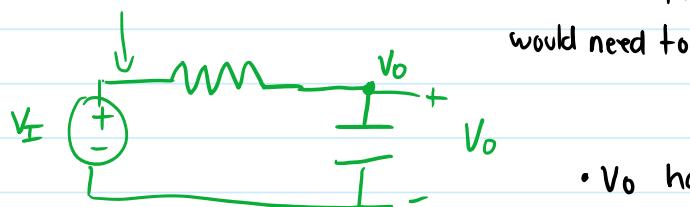
$$= \frac{R_2}{R_1} (V_i - V_2)$$

Subtracts  
two voltages!

## Integrator



i not  $v_i$ . would need to convert voltage  $v_i$  to current  $i$ :

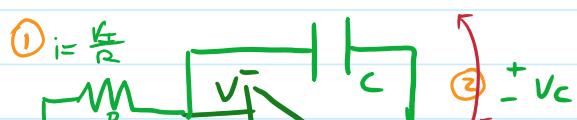


•  $V_o$  has to be very small!  
or  $i \neq \frac{V_i}{R}$

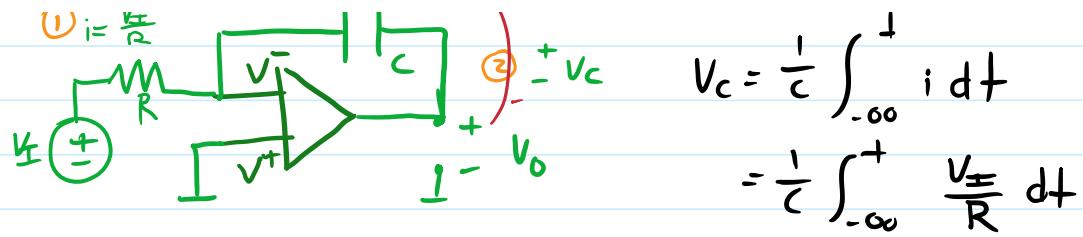
## OpAmp Integrator

$$\textcircled{1} \quad V_I \rightarrow i$$

$$\textcircled{2} \quad i \text{ through capacitor } C$$



$$V_C = \frac{1}{C} \int_{-\infty}^{+\infty} i dt$$

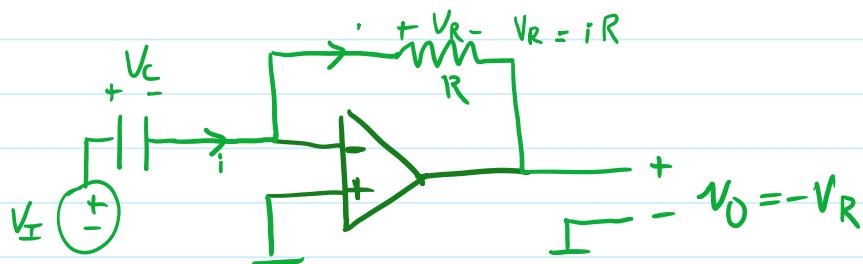


$$V_O = 0 - V_C$$

$$= -V_C$$

Differentiator  $V_I$   $\left[ \frac{d}{dt} \right] \rightarrow V_O = A \frac{d}{dt} V_I$

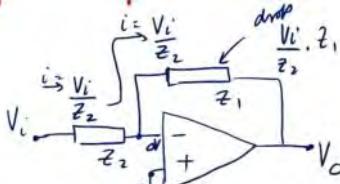
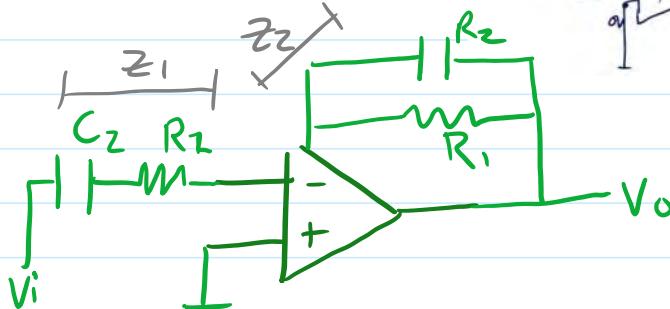
- ①  $V_I$  across capacitor  $i \sim \frac{dV_I}{dt}$
- ② convert  $i \rightarrow V_O$



$$i = C \frac{dV_I}{dt}$$

$$V_O = iR = -C \frac{dV_I}{dt} \cdot R$$

## Op Amp Filters



$$V_O = -\frac{Z_1}{Z_2} V_I$$

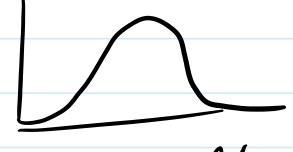
$$Z_1 = \frac{R_1 \frac{1}{sC_1}}{R_1 + V_o}$$

$$Z_2 = R_2 + \frac{1}{sC_2}$$

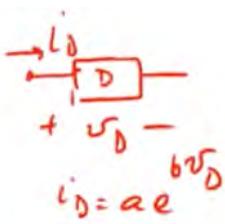
$$Z_1 = \frac{R_1 \cdot \frac{1}{sC_1}}{R_1 + \frac{1}{sC_1}} \quad Z_2 = R_2 + \frac{1}{sC_2}$$

$$V_0 = -\frac{R \cdot \frac{1}{sC_2}}{R + \frac{1}{sC_1}} \cdot V_1 = \frac{sR_1 C_2}{(1 + sR_2 C_2)(1 + sR_1 C_1)}$$

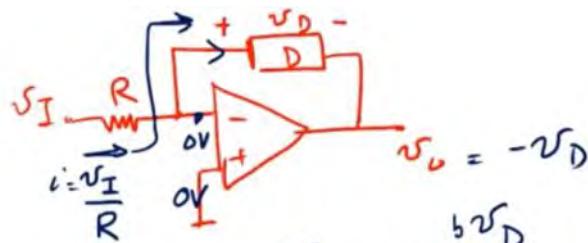
$|H(j\omega)|$   
"Band Pass Filter"



### Non-linear OpAmp Circuit L



$$i_D = a e^{b V_D}$$



$$i = \frac{V_I}{R} = a e^{b V_D}$$

$$\frac{V_I}{aR} = e^{b V_D}$$

$$\frac{1}{b} \ln \frac{V_I}{aR} = V_D$$

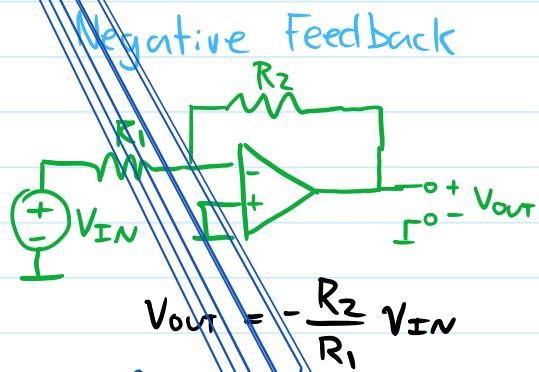
$$V_O = -\frac{1}{b} \ln \frac{V_I}{aR}$$

"log Amp"

# W5: OpAmp Positive Feedback

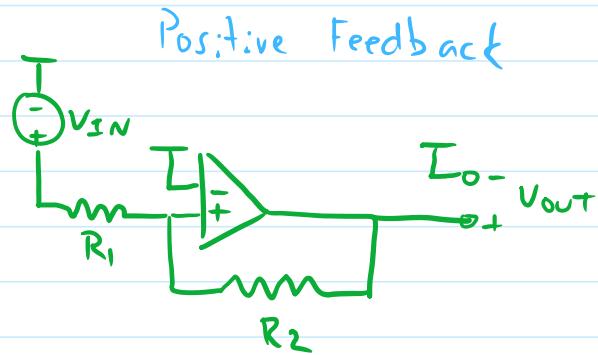
Tuesday, December 13, 2016 2:07 AM

## Negative vs Positive Feedback



$$V_{out} = -\frac{R_2}{R_1} V_{in}$$

↑ →  
(change in input)

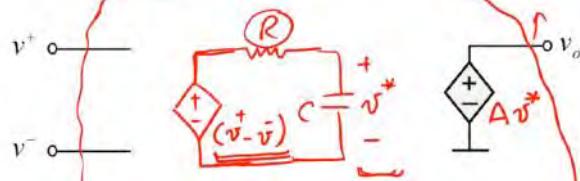
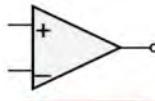


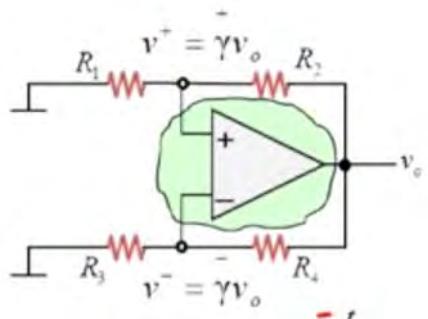
$$V_{out} = \frac{R_2}{R_1} V_{in}$$

↑ →  
drives opAmp into saturation

## Representing dynamics of op amp

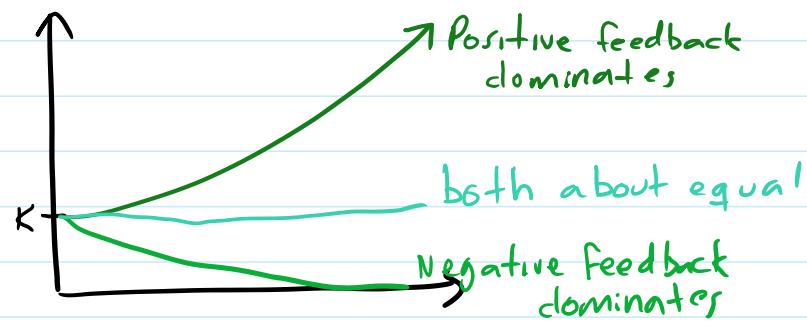
Need a better model to represent temporal behavior of op amp



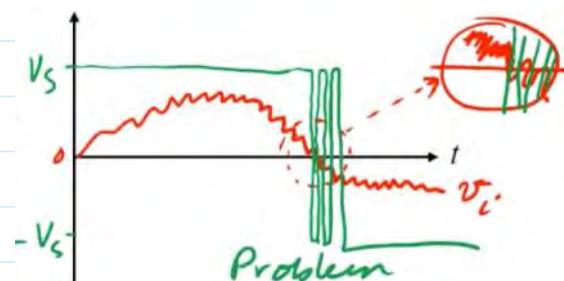
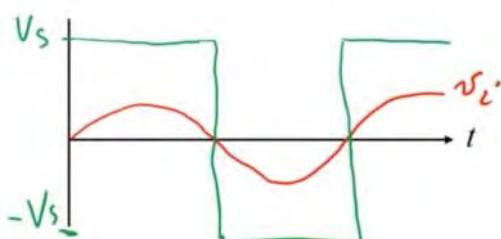
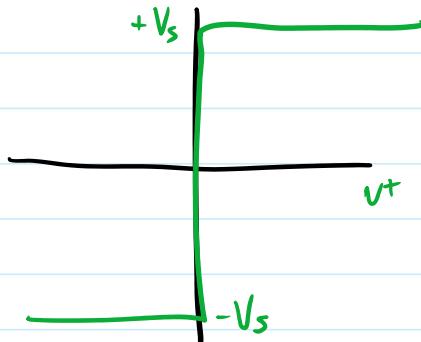
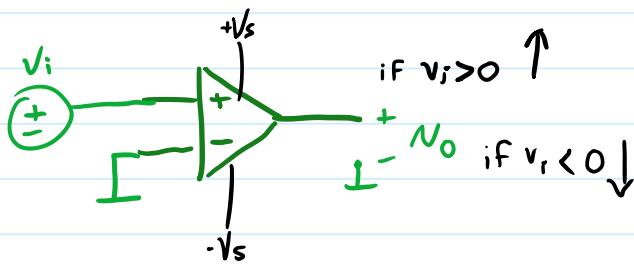


$$v_o = K e^{-\frac{t}{RC}}$$

$$\frac{RC}{A(\bar{\gamma} - \bar{\gamma})}$$

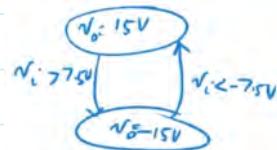
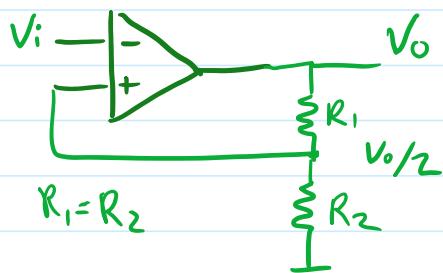


## OpAmp Comparator

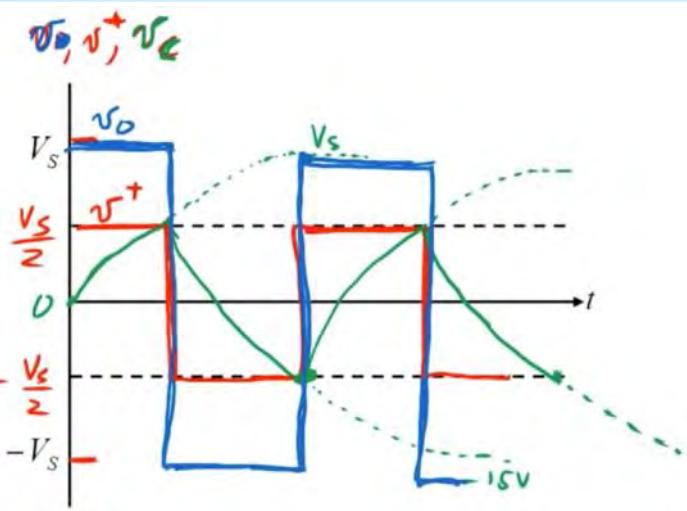
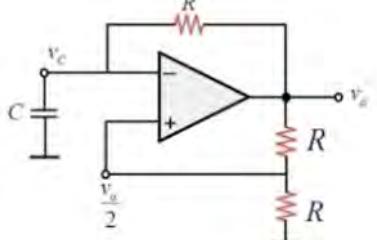


Better version - Hysteresis

→ circuit remembers the past



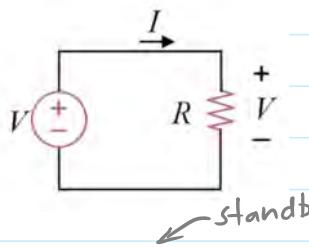
# OpAmp Oscillator



• find rising and falling time  
( see lecture )

# W5: Energy and Power

Tuesday, December 13, 2016 1:25 PM

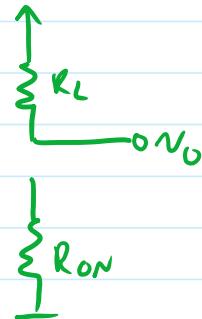
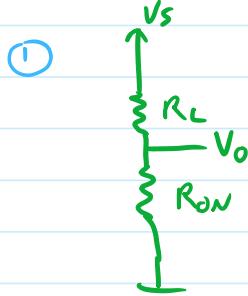
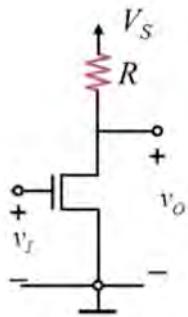


$$\text{Power } P = IV = \frac{V^2}{R}$$

$$\text{Energy dissipated in time } T$$

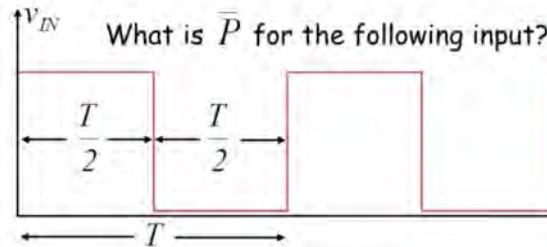
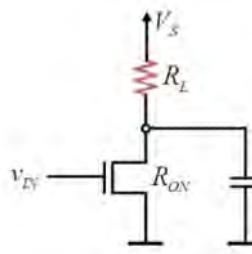
$$E = PT = IVT$$

Static Power for gate



$$P = \frac{V_s^2}{R_L + R_{on}}$$

$$P=0$$



$$T = \frac{1}{f}$$

Equivalent Circuit



from section 11.3

$$\bar{P} = \frac{V_s^2}{Z(R_L + R_{on})} + CV_s^2 f \frac{R_L^2}{(R_L + R_{on})^2}$$

if  $R_L \gg R_{on}$

$\frac{1}{2}$  since MOSFET is on for  $\frac{1}{2}$  of the time

$$\bar{P} = \frac{V_s^2}{2R_L} + CV_s^2 f$$

$P_{\text{static}}$

$\bar{P}_{\text{DYNAMIC}}$

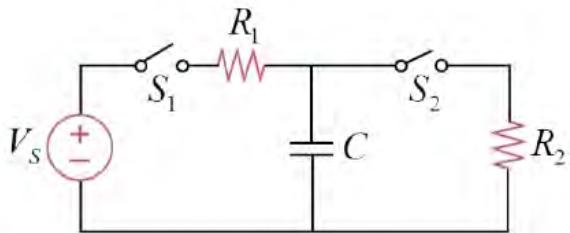
$\tau^{\text{static}}$   $\tau^{\text{dynamic}}$   
Vs matters a lot !

# W6: Energy and CMOS Design

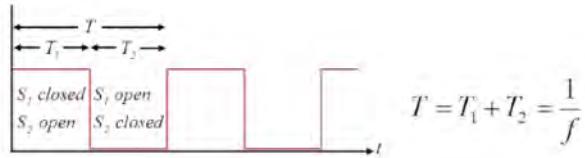
Tuesday, December 13, 2016 9:21 PM

~~Not  
ON  
FINAL~~

11.4  
11.5



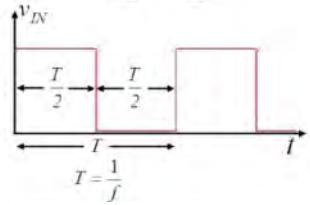
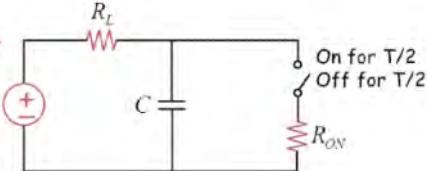
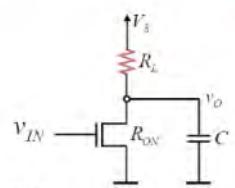
$$\bar{P} = CV_S^2 f$$



$$T = T_1 + T_2 = \frac{1}{f}$$

## Review Inverter

Equiv. ckt



$$\bar{P} = \frac{V_S^2}{2R_L} + CV_S^2 f$$

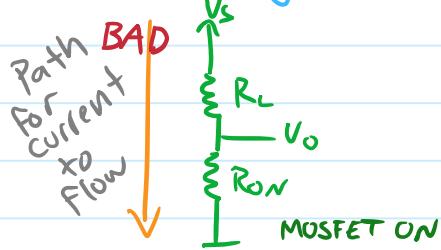
$\bar{P}_{\text{STATIC}}$

$\bar{P}_{\text{DYNAMIC}}$

Because there is a direct path through  $V_s \rightarrow R_s \rightarrow R_{ON}$

Get rid of static power

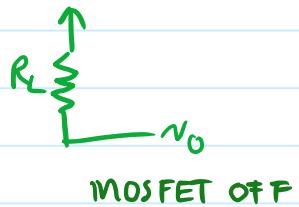
Input High



$$\bar{P} = \frac{V_S^2}{R_L + R_{ON}}$$

$V_s$

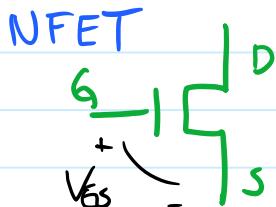
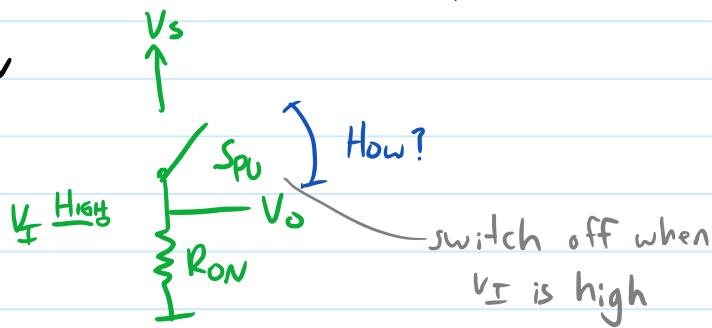
Input Low



$$\bar{P} = 0$$

$$P = \frac{V_s}{R_L + R_{ON}}$$

Solution

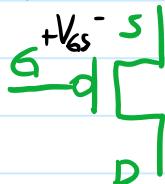


MOSFET we've seen before

$$V_{GS} \geq V_{TN} \Rightarrow \text{ON}$$

$$V_{GS} < V_{TN} \Rightarrow \text{OFF}$$

PFET



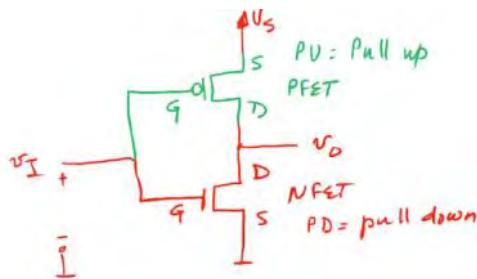
New MOSFET!!

Complementary to NFET

$$V_{GS} \leq V_{TP} \Rightarrow \text{ON}$$

$$V_{GS} > V_{TP} \Rightarrow \text{OFF}$$

New Inverter



consumes much less power since never a path from  $V_s \rightarrow \text{GND}$

"Complementary MOS" - CMOS logic

$$P_{\text{dynamic}} = C V_s^2 f$$

comes from switching capacitors

can still draw a lot of power for faster speeds

Reduce dynamic Power

- Reduce  $V_s$
- Shrink capacitors
- Clock gating

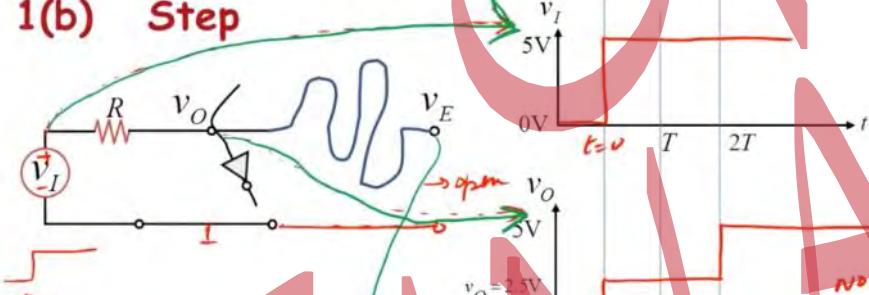
$L_{T_{\text{min}}}$  off clock for instance

- Clock gating
  - ↳ Turn off clock for systems not in use

# W6: Breaking The Abstraction Barrier

Tuesday, December 13, 2016 10:45 PM

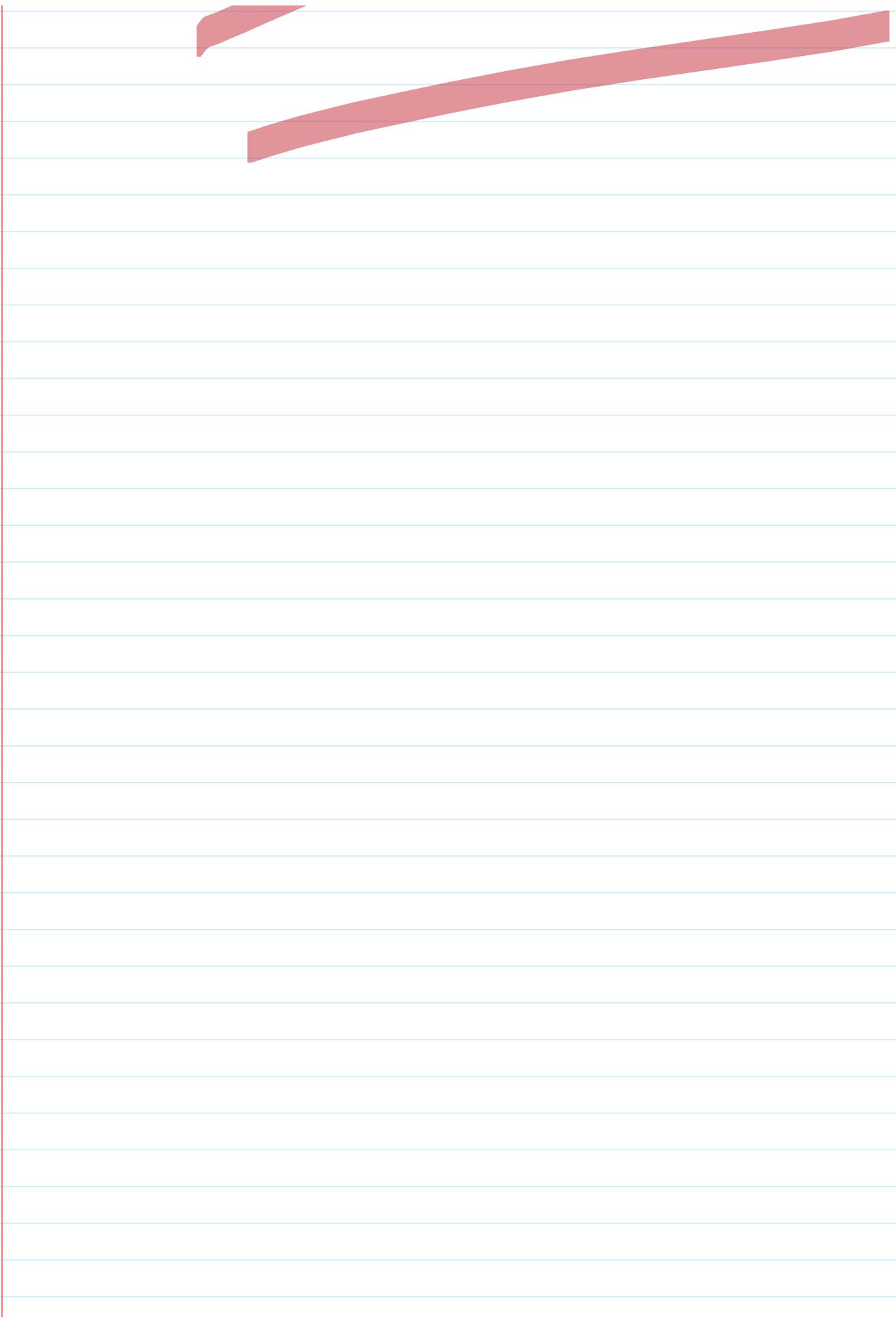
1(b) Step



So what is going on here?



looks ok!



# Final Review

Thursday, December 15, 2016 4:35 PM

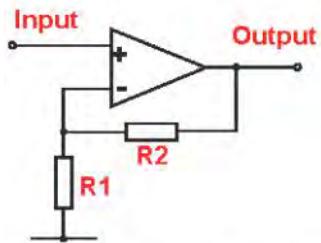
Impedance:  
ZR, ZC, ZL

$$Z_R = R \quad Z_C = \frac{1}{\omega C} \quad Z_L = L \omega$$

Low frequency --> Capacitor open circuit  
High Frequency --> Capacitor short circuit

## Basic non-inverting amplifier circuit

The basic non-inverting amplifier circuit using an op-amp is shown below. In this circuit the signal is applied to the non-inverting input of the amplifier. However the feedback is taken from the output via a resistor to the inverting input of the operational amplifier where another resistor is taken to ground. It is the value of these two resistors that govern the gain of the operational amplifier circuit.



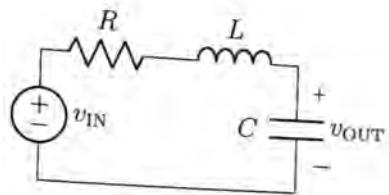
Basic non-inverting operational amplifier circuit

The gain of the non-inverting amplifier circuit for the operational amplifier is easy to determine. The calculation hinges around the fact that the voltage at both inputs is the same. This arises from the fact that the gain of the amplifier is exceedingly high. If the output of the circuit remains within the supply rails of the amplifier, then the output voltage divided by the gain means that there is virtually no difference between the two inputs.

As the input to the op-amp draws no current this means that the current flowing in the resistors R1 and R2 is the same. The voltage at the inverting input is formed from a potential divider consisting of R1 and R2, and as the voltage at both inputs is the same, the voltage at the inverting input must be the same as that at the non-inverting input. This means that  $V_{in} = V_{out} \times R_2 / (R_1 + R_2)$ . Hence the voltage gain of the circuit  $A_v$  can be taken as:

$$\frac{V_{out}}{V_{in}} = A_v = 1 + \frac{R_2}{R_1}$$

As an example, an amplifier requiring a gain of eleven could be built by making R2 47 k ohms and R1 4.7 k ohms.



(a) (20%) Find  $V_{\text{out}}$  and  $\phi$  as functions of  $R$ ,  $L$ ,  $C$ ,  $V_{\text{in}}$ , and  $\omega$ .

$$V_{\text{out}} = V_{\text{in}} \left| \frac{\frac{1}{j\omega C}}{\frac{1}{j\omega C} + j\omega L + R} \right| = \frac{V_{\text{in}}}{\sqrt{(1 - \omega^2 LC)^2 + (\omega RL)^2}}$$

In order to find  $\phi$ , we focus on the ratio of imaginary to real, and take the inverse tangent

in the transfer function

$$\phi = \tan^{-1} \left( \frac{-\omega RL}{1 - \omega^2 LC} \right)$$

FINAL

Friday, December 16, 2016 2:11 PM

$$i_D = \frac{\kappa}{2} V_{GS}^2$$

$$V_T=0$$

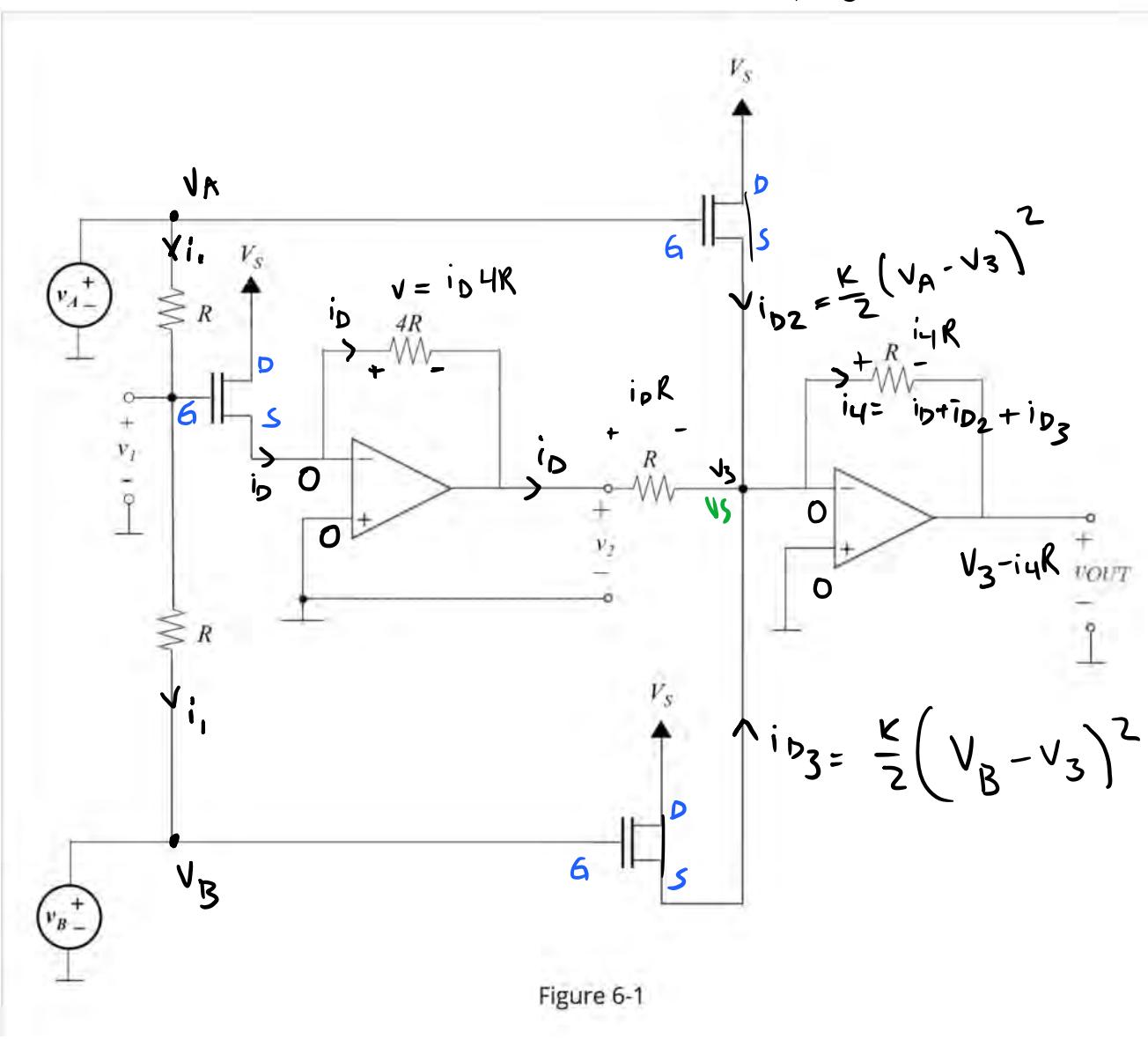


Figure 6-1

$$v_1 = v_A - i_1 R \Rightarrow i_1 R = v_A - v_1$$

$$v_1 = v_B + i_1 R$$

$$v_1 = v_B + v_A - v_1$$

$$\boxed{1.. - V_T + V_A}$$

$$v_1 = \frac{v_B + v_A}{2}$$

$$i_D = \frac{k}{2} v_{GS}^2$$

$$i_D = \frac{k}{2} v_1^2$$

$$v_2 = -i_D L R$$

$$v_2 = -\frac{k}{2} v_1^2 (L R)$$