

Education

| | |
|--|--|
| Georgia Institute of Technology (Remote) | Jan 2024 – 2026 (expected) |
| Master of Science: Computer Science w/ Machine Learning Specialization | GPA: 4.0 |
| University of California, San Diego | Graduated: June 2021 |
| BS/MS: Chemical Engineering | GPA: BS – 3.93 (Magna Cum Laude) MS – 3.86 |

Work Experience

| | |
|---|----------------------|
| Illumina (Medical Device Manufacturing) | San Diego, CA |
| Process Development Engineer I, II | June 2021 – Present |
| <ul style="list-style-type: none">Developed Python scripts using pandas and NumPy to effectively parse large volumes of data from tool logs, enabling extraction of critical information to facilitate data-driven decision makingIntegrated scripts with Tableau for dynamic data visualization, collaborating with cross functional stakeholders to identify opportunities for dashboarding.Leveraged SQL to query manufacturing databases and extract relevant data, facilitating the investigation of production issues | |

School Projects

| | |
|---|-----------------|
| Warehouse Path Planner (CS7638, Robotics for AI) | Jul 2024 |
| Python | |
| <ul style="list-style-type: none">Modeled a 2D grid warehouse environment where a robot moves to pick up and deliver boxes to a designated drop-off point.Implemented the A* search algorithm to find optimal and efficient paths while avoiding obstacles such as walls and boxes.Accounted for collision and uneven motion costs, as well as stochastic motion for realistic robot behavior.Used dynamic programming to develop an optimal policy for the robot to follow from any starting location to deliver a single box.Integrated additional floor costs on top of motion costs into the policy to model the challenges of uneven terrain. | |
| Indiana Drones GraphSLAM (CS7638, Robotics for AI) | Jul 2024 |
| Python | |
| <ul style="list-style-type: none">Implemented linear GraphSLAM techniques to accurately localize a robot and map obstacles in a 2D grid system.Designed and implemented a path planning algorithm to route a robot to a known treasure location using the map generated from SLAM.Successfully accounted for noise in motion and measurement data, ensuring reliable localization and mapping.Modeled robot motion with a bicycle model to reflect realistic movement patterns.Integrated physical constraints, including maximum turning angles and distances, into the model to ensure realistic motion.Successfully extracted the treasure within the given time limit, efficiently avoiding obstacles and handling noise in sensor data. | |
| Machine Learning Financial Trading Strategy (CS7646, ML for Trading) | Apr 2024 |
| Python | |
| <ul style="list-style-type: none">Developed a machine learning-based trading strategy using real-world financial data and technical stock indicatorsUsed Python to implement a bag learner with random forest classification algorithms to predict optimal trading actions based on standardized and labeled indicator dataEvaluated strategy against a manual rule-based approach by comparing returns across both training and test datasetsTuned learner and indicator parameters through meticulous analysis of performance metrics such as returns and training timeSuccessfully achieved a 5% return over an unseen 1-year dataset | |

Personal Projects

| | |
|---|---|
| Shredders | May 2024 - Present |
| PostgreSQL, Express, React, Node, Tailwind CSS, Supabase, Render, Vite, React Router | https://shredders-client.onrender.com/ |
| <ul style="list-style-type: none">Developed a PERN stack web application to help snowboarders plan trips and identify overlapping trips with friends.Implemented JWT user authentication, friend search, and trip creation features, allowing users to manage RSVPs and discuss trip plans.Integrated PostgreSQL to support complex queries for structured data retrieval, ensuring efficient management of user, friend, and trip information. | |

- Designed a responsive UI using React and Tailwind CSS, optimized for both mobile and desktop screens.
- Deployed the frontend and backend to Render, with the database hosted on Supabase.

AllFields

Aug 2023 – Nov 2023

JavaScript, HTML, CSS, React.js, Firebase

<https://allfields-570a5.web.app/>

- Developed a CRUD web app inspired by AllTrails for soccer enthusiasts where users can look up soccer fields, post reviews about field conditions, and share images
- Created an interactive and responsive frontend with React and Styled Components, with filter views and a map display through integration with the Google Maps API
- Integrated user profiles with avatar customization, favoriting, and recent activity
- Utilized Firebase for the backend, including Authentication, Realtime Database for data management, and Cloud Storage for images

Where's Waldo

May 2023 – Jul 2023

JavaScript, HTML, CSS, React.js, Jest

<https://lindavid1998.github.io/wheres-waldo>

- Developed an interactive photo-tagging web game based on Where's Waldo
- Implemented Jest for comprehensive testing, ensuring robust functionality and minimizing bugs
- Leveraged React Redux for centralized state management

Skills

- | | | |
|---------------------|------------|----------------|
| • JavaScript | • JWT | • Python |
| • HTML/CSS/Tailwind | • Git | • Pandas/Numpy |
| • React | • Tableau | • CART |
| • Jest | • Jira | • Bag Learning |
| • Express/Node | • PgAdmin | • Q Learning |
| • Mongoose | • Supabase | • A* |
| • MongoDB | • Render | • GraphSLAM |
| • PostgreSQL | • Firebase | • Java |