

Linear Algebra

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Review: Classification of n-alternating multilinear

• For an w-a<mark>lternating</mark> multilinear map



+1211-12-7=1

Review: Determinant

• Let u_i be the i-th row of $A = \lfloor a_{ij} \rfloor$. The determinant of A is

$$\det A = \sum_{\sigma \in S_n} \operatorname{sgn}(\sigma) \prod_{i=1}^n \alpha_{i\sigma(i)}.$$

Review: Properties of the Determinant

- 1. The determinant changes sign when two rows are exchanged.
- 2. The determinant of the identity matrix is 1.
- 3. The determinant depends linearly on the each row.
- If two rows of A are equal, then det A = 0.
- 5. Subtracting a multiple of one row from another row leaves the same determinant.
- 6. If A has a row of zeros, then $\det A=0$ since the map \det is za-multilinear.
- 7. If A is triangular then $\det A = a_{11}a_{22}\cdots a_{nn}$.
- 8. If A is singular, then $\det A=0.$ If A is invertible, then $\det A\neq 0.$
- 9. The transpose of A has the same determinant as A itself: $\det A = \det A^{\gamma}$.
- 10. The determinant of \overline{AB} is the product of det \overline{A} times det \overline{B} .
- 11. Let A be an invertible matrix. Then det $A \neq 0$.

LDU

de AB. Let B det AT = det A

Properties of the Determinant

12. Let $A \in M_r(\mathbb{R}), B \in M_{rs}(\mathbb{R})$ and $C \in M_s(\mathbb{R})$, then

$$\det \begin{vmatrix} \mathbf{A} & \mathbf{B} \\ 0 & C \end{vmatrix} = \det A \det C.$$

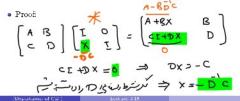
• Proof:

Properties of the Determinant

13. Let $A, B, C, D \in M_n(\mathbb{R})$. If CD = DC then

$$\det \begin{vmatrix} A & B \\ C & D \end{vmatrix} = \det(AD - BC).$$

• Note that it is also true if AC = CA or AB = BA or BD = DB.



Properties of the Determinant

14. (Schur formula) Let $A \in M_n(\mathbb{R})$, and

$$A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} =$$

$$\det A = (\det A_{11}) \det (A_{22} - A_{2}1A_{11}^{-1}A_{1}2).$$

Formulas for the Determinant

- If A is invertible, then PA = LDU
- $\det A = \pm \det L \times \det D \times \det U$.
- $\det L = \det U = 1$.
- $\det D = d_1 \cdots d_n$.
- det A = \(\frac{1}{4} \cdot \cdot d_n \).

Example

• We obtain:

2. Siv. D. in. [AB][PO]=

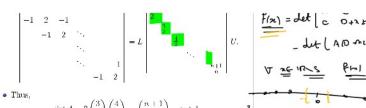
det [AB] det [

= طعل (AD -BC) طعل ا حیان D دارینزی است ک طعل ک ب زن کند م ۱۵ د که د ک ما یک D+XE دارزور بر

= = 50,60 H Iica)

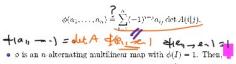
C(D+NT) SCD +AC

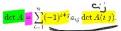
= det [A B D+2]
= det [A D AN - RC)



One more formula for the determinant

- Let $A \in M_n(\mathbb{R})$.
- \bullet Consider The submatrix A(i|j) that is defined by throwing away row i and column j.
- Let $\phi: \underbrace{V \times \cdots \times V} \to \mathbb{R}$ be given by





Cofactors of A

- \bullet Thus, For each $1\leqslant j\leqslant n,$ inner product of the j-th column of A



Adjoint A

• We obtain

$$C^TA = egin{bmatrix} c_{11} & \cdots & c_{n1} \\ \vdots & \cdots & \vdots \\ c_{1n} & \cdots & c_{nn} \end{bmatrix} egin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \cdots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{bmatrix} & egin{bmatrix} \det A \\ & \ddots \\ & & \det A \end{bmatrix}$$

· Thus.

$$C^TA = (\det A) L$$

 \bullet The matrix C^T is called the adjoint of A and is denoted by adj A.

$$(\operatorname{adj} A)A = (\det A)I$$

$\operatorname{adj} A$

- $\bullet \ \mbox{By } (\mbox{adj}\, A)A = (\det A)I,$ we have
 - $\bigcirc \ (\operatorname{adj} A^T)A^T = (\det A^T)I = (\det A)I.$
 - ② $(\text{adj } A)_{ij} = (-1)^{i+j} \det A(j|i).$
- It is easy to check that

$$(\operatorname{adj} A^T) = (\operatorname{adj} A)^T.$$

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Lecture #18

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Computation of A^{-1}

• If $A \in M_n(\mathbb{R})$ is invertible, then

$$A\left(\frac{\operatorname{adj} A}{\det A}\right) = \left(\frac{\operatorname{adj} A}{\det A}\right)A = I.$$

• Thus,

$$A^{-1} = \left(\frac{\operatorname{adj} A}{\det A}\right).$$

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Cramer's rule

- Let $A \in M_n(\mathbb{R})$ be invertible.
- The solution of Ax = b is $x = A^{-1}b$: just C^Tb divided by $\det A$.
- Cramer's rule: The jth component of $x = A^{-1}b$ is the ratio

$$x_j = \frac{\det B_j}{\det A}$$

where

$$B_j = \begin{bmatrix} a_{11} & a_{12} & \cdots & b_1 & \cdots & a_{1n} \\ \vdots & \vdots & \cdots & \vdots & \cdots & \vdots \\ a_{n1} & a_{n2} & \cdots & b_n & \cdots & a_{nn} \end{bmatrix}$$

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Chapter 5

$\begin{array}{c} Eigenvalues \ and \\ Eigenvectors \end{array}$

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Differential equations

• Consider a single equation

$$\frac{du}{dt} = au \quad \text{with} \quad u_0 = u(0).$$

 \bullet The solution to this equation is

$$u(t) = e^{at}u_0$$

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Lecture #:

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Differential equation systems

 \bullet Consider the differential equation system

$$\begin{cases} \frac{du_1}{dt} = 4u_1 - 5u_2\\ \frac{du_2}{dt} = 2u_1 - 3u_2 \end{cases}$$

with
$$\begin{cases} x_1 = u_1(0) \\ x_2 = u_2(0) \end{cases}$$

• Similar to a single equation, let

$$u_1(t) = e^{\lambda t} x_1$$

$$u_2(t) = e^{\lambda t} x_2$$

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Eigenvalue problem

 \bullet By substituting and cancellation of $e^{\lambda t},$ we obtain:

$$4x_1 - 5x_2 = \lambda x_1$$
$$2x_1 - 3x_2 = \lambda x_2$$

or

$$\begin{bmatrix} 4 & -5 \\ 2 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \lambda \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}.$$

• Eigenvalue equation:

$$Ax = \lambda x.$$

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Eigenvalues and Eigenvectors

- Eigenvectors are the directions along which a linear transformation acts simply by **stretching/compressing** and/or **flipping**.
- \bullet We will show how eigenvectors make understanding linear transformations easy.
- \bullet We want to have as many linearly independent eigenvectors as possible associated to a single linear transformation.

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Thank You!