# Linear Algebra

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#### Review

#### • Gaussian Elimination

$$\begin{bmatrix} 1 & 2 & 3 & 6 \\ 2 & -1 & 4 & 8 \\ -1 & 8 & 2 & 12 \end{bmatrix} \quad R_2 - 2R_1$$

$$R_3 + R_1$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 3 & 6 \\ 0 & -5 & -2 & -4 \\ 0 & 10 & 5 & 18 \end{bmatrix} \quad R_3 + 2R_2$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 3 & 6 \\ 0 & -5 & -2 & -4 \\ 0 & 0 & 1 & 10 \end{bmatrix} \quad x_3 = 10, \quad x_2 = -\frac{16}{5}, \quad x_1 = -\frac{88}{5}$$

### The Breakdown of Elimination

- Under what circumstances could the process break down?
- Example:

$$\begin{bmatrix} 1 & 1 & 1 & b_1 \\ 2 & 2 & 5 & b_2 \\ 4 & 6 & 8 & b_3 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & 1 & b_1 \\ 0 & 0 & 3 & -2b_1 + b_2 \\ 0 & 2 & 4 & -4b_1 + b_3 \end{bmatrix}.$$

So

$$\Rightarrow \begin{bmatrix} 1 & 1 & 1 & b_1 \\ 0 & 2 & 4 & -4b_1 + b_3 \\ 0 & 0 & 3 & -2b_1 + b_2 \end{bmatrix}$$

• The system is now triangular, and back-substitution will solve it. The system is called Nonsingular system.

#### The Breakdown of Elimination

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• The system is called singular system.

#### Permutation Matrices

• The simplest permutations exchange two rows.

• Other permutations exchange more rows.

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

• A 3 by 3 permutation matrix P with  $P^3 = I$ :

$$\underbrace{\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}}_{B}^{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

• Some power of a permutation matrix is the identity.

#### Permutation Matrices

#### Definition

P be a square matrix of order n. If P is a binary matrix (every entry in it is either 0 or 1, also called 0-1 matrix or (0, 1) matrix) and there is a unique "1" in its every row and every column, then P is called a permutation matrix .

• Some power of a permutation matrix is the identity.

#### Problem

• If  $P_1$  and  $P_2$  are permutation matrices, so is  $P_1P_2$ . This still has the rows of I in some order. Give examples with  $P_1P_2 \neq P_2P_1$  and  $P_3P_4 = P_4P_3$ .

#### The Breakdown of Elimination

- If elimination can be completed with the help of row exchanges, then:
  - Those exchanges are done first (by P).
  - The matrix PA will not need row exchanges.
  - PA allows the standard factorization into L times U.
- In the nonsingular case:
  - There is a permutation matrix P that reorders the rows of A to avoid zeros in the pivot positions.
  - Then Ax = b has a unique solution.
  - ullet With the rows reordered in advance, PA can be factored into LU.
- In the singular case, no P can produce a full set of pivots: elimination fails.

### Uniqueness

• In the nonsingular case: The *LDU* factorization and the *LU* factorization are uniquely determined by A.

## **Block Matrix Multiplication**

• It is often convenient to partition a matrix M into smaller matrices called blocks.

$$\begin{bmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 0 \\ 7 & 8 & 9 & 1 \\ \hline 0 & 1 & 2 & 0 \end{bmatrix} = \begin{bmatrix} A & B \\ \hline C & D \end{bmatrix}$$

• Matrix operations on block matrices can be carried out by treating the blocks as matrix entries.

$$M^{2} = \begin{bmatrix} A & B \\ \hline C & D \end{bmatrix} \begin{bmatrix} A & B \\ \hline C & D \end{bmatrix} = \begin{bmatrix} A^{2} + BC & AB + BD \\ \hline CA + DC & CB + D^{2} \end{bmatrix}$$

#### Inverse Matrices

- The matrix A is invertible if there exists a matrix B such that AB = BA = I.
- Not all matrices have inverses.
- If AB = I and CA = I, then B = C (prove!). Therefore inverse matrix is unique. We denote it by  $A^{-1}$ .
- The matrix A is invertible if and only if AX = b has one and only solution for a given b.
- The matrix A is invertible if and only if A = LU where LU is a triangular factorization of A with no zeros on the diagonal of U.

### The Calculation of $A^{-1}$

The inverse of A is written  $A^{-1}$  in which  $AA^{-1} = I$ . Let

$$A = \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix}$$

We want to find  $A^{-1}$  such that  $AA^{-1} = I$ , so consider the columns of  $A^{-1}$  as  $x_1, x_2, x_3$ , that means  $A^{-1} = \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix}$ .

$$AA^{-1} = I$$

$$A \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} = \begin{bmatrix} e_1 & e_2 & e_3 \end{bmatrix}$$

$$\begin{bmatrix} Ax_1 & Ax_2 & Ax_3 \end{bmatrix} = \begin{bmatrix} e_1 & e_2 & e_3 \end{bmatrix}$$

So

 $Ax_1 = e_1$   $Ax_2 = e_2$   $Ax_3 = e_3$ 

#### The Gauss-Jordan Method

- Thus we have three systems of equations (or n systems).
- They all have the same coefficient matrix A.
- The right-hand sides  $e_1, e_2, e_3$  are different, but elimination is possible on all systems simultaneously.

 $A^{-1}$ 

$$\begin{bmatrix} 2 & 1 & 1 & 1 & 0 & 0 \\ 4 & -6 & 0 & 0 & 1 & 0 \\ -2 & 7 & 2 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 & 1 & 1 & 0 & 0 \\ 4 & -6 & 0 & 0 & 1 & 0 \\ -2 & 7 & 2 & 0 & 0 & 1 \end{bmatrix} \qquad \begin{bmatrix} 2 & 1 & 1 & 1 & 0 & 0 \\ 0 & -8 & -2 & -2 & 1 & 0 \\ 0 & 8 & 3 & 1 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix}
2 & 1 & 1 & 1 & 0 & 0 \\
0 & -8 & -2 & -2 & 1 & 0 \\
0 & 0 & 1 & -1 & 1 & 1
\end{bmatrix}$$

• We have

$$\left[\begin{array}{c|c}U&L^{-1}\end{array}\right]$$

$$\begin{bmatrix} 2 & 1 & 1 & 1 & 0 & 0 \\ 0 & -8 & -2 & -2 & 1 & 0 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 & 0 & \frac{12}{8} & -\frac{5}{8} & -\frac{6}{8} \\ 0 & -8 & 0 & -4 & 3 & 2 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix}
2 & 1 & 1 & 1 & 0 & 0 \\
0 & -8 & -2 & -2 & 1 & 0 \\
0 & 0 & 1 & -1 & 1 & 1
\end{bmatrix}$$

$$\begin{bmatrix}
2 & 1 & 0 & 2 & -1 & -1 \\
0 & -8 & 0 & -4 & 3 & 2 \\
0 & 0 & 1 & -1 & 1 & 1
\end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 & 0 & \frac{12}{8} & -\frac{5}{8} & -\frac{6}{8} \\ 0 & -8 & 0 & -4 & 3 & 2 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix} \qquad \begin{bmatrix} 1 & 0 & 0 & \frac{12}{16} & -\frac{5}{16} & -\frac{6}{16} \\ 0 & 1 & 0 & \frac{4}{8} & -\frac{3}{8} & -\frac{2}{8} \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix}$$

. . .

# Thank You!