

Deep Generative Models II

Generative Adversarial Networks – Part I

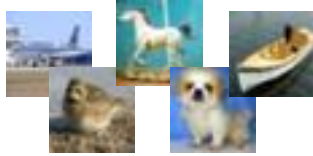
Machine Perception

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23 April 2020

Generative Modelling

Given training data, generate new samples, drawn from “same” distribution



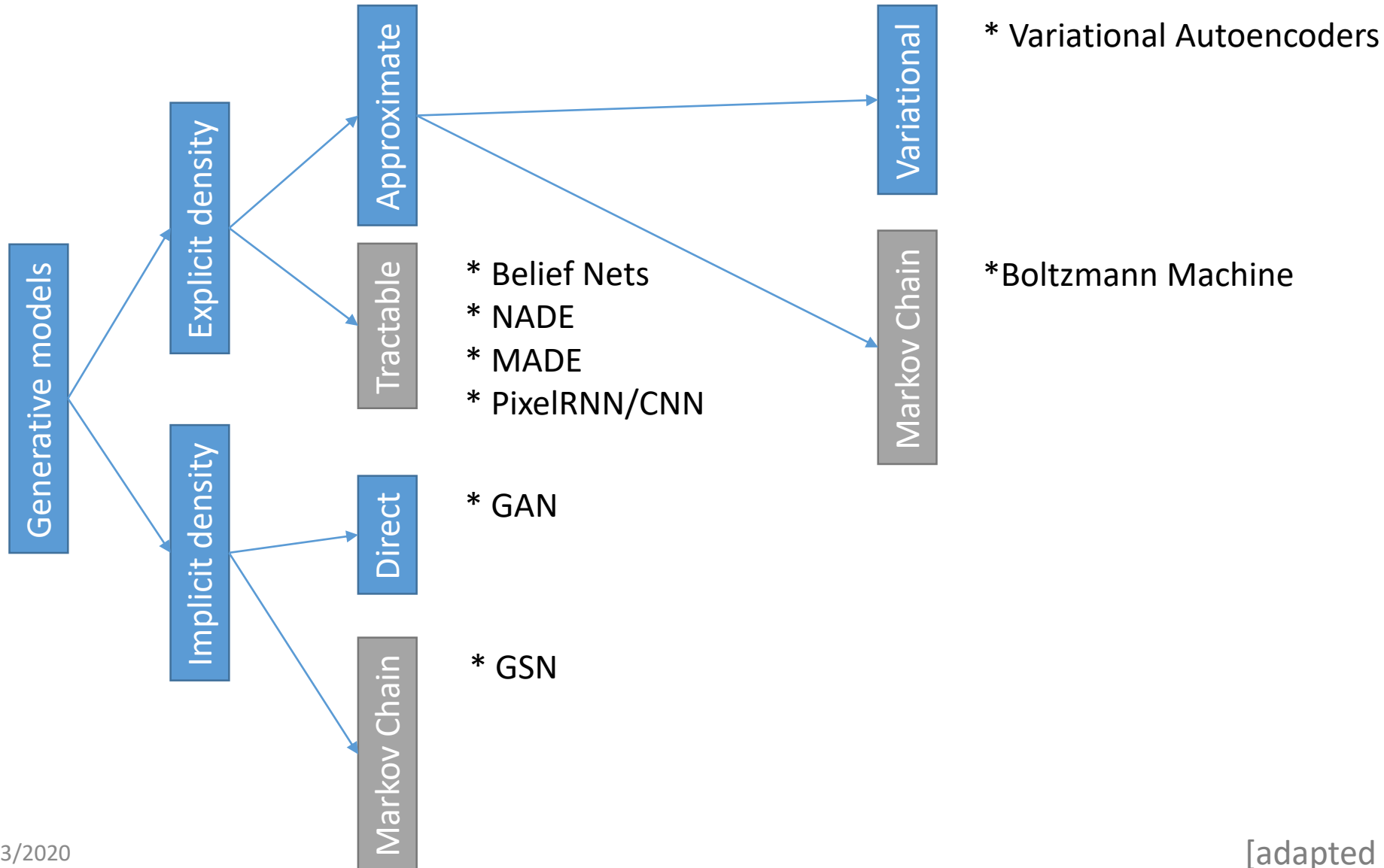
Training samples $\sim p_{data}(x)$



Generated samples $\sim p_{model}(x)$

We want $p_{model}(x)$ to be similar to $p_{data}(x)$

Taxonomy of Generative Models



Generative Adversarial Nets: Intuition

Want: Ability to sample high-dimensional data points (e.g., images) from true data distribution (inaccessible).

Issue: No direct way of achieving this

Solution: Draw from simple distribution (i.e., random noise) and use neural network to learn transformation into realistic image



Output:
Sample from
training
distribution

Generator NN

z

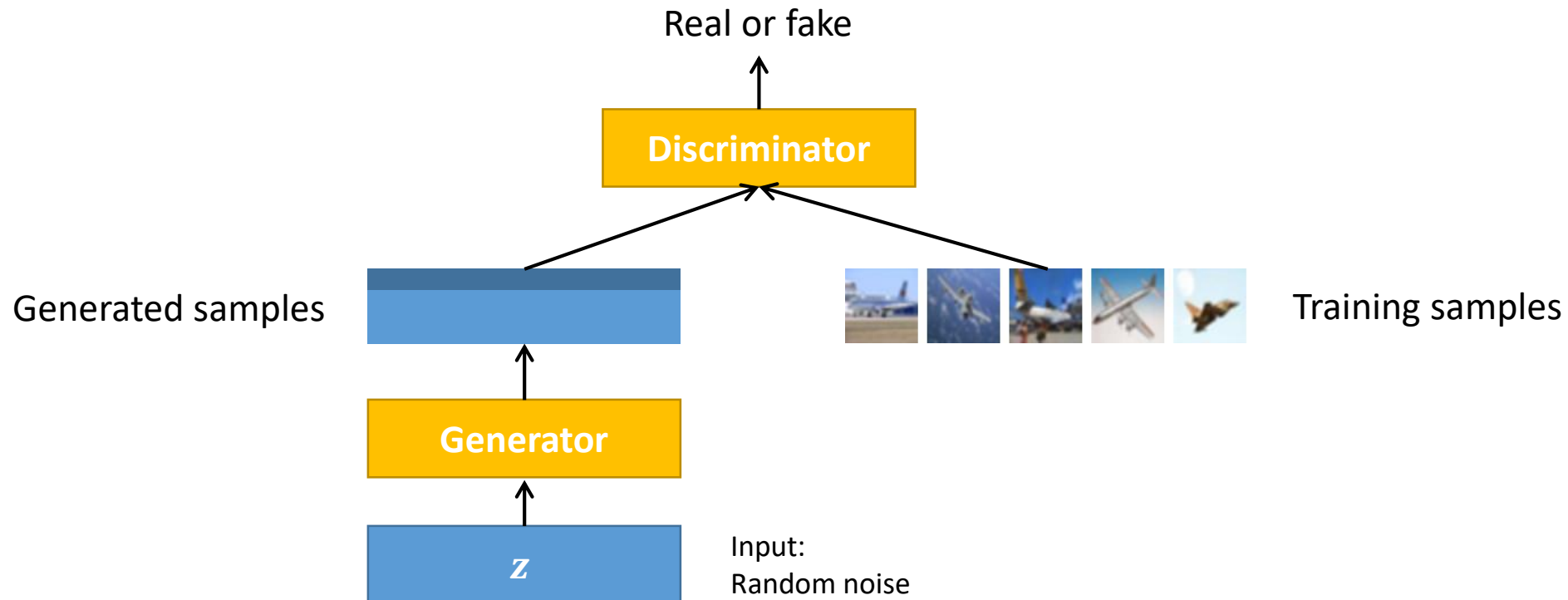
Input:
Random noise

Training GANs: Intuition

General idea is to have **two networks play a two-player game**

Generator: try to fool the discriminator by generating real-looking images

Discriminator: try to distinguish between real and fake images



Training GANs: Definitions

Let X be the signal space and D the latent space dimension.

Generator:

$$G: \mathbb{R}^D \rightarrow X$$

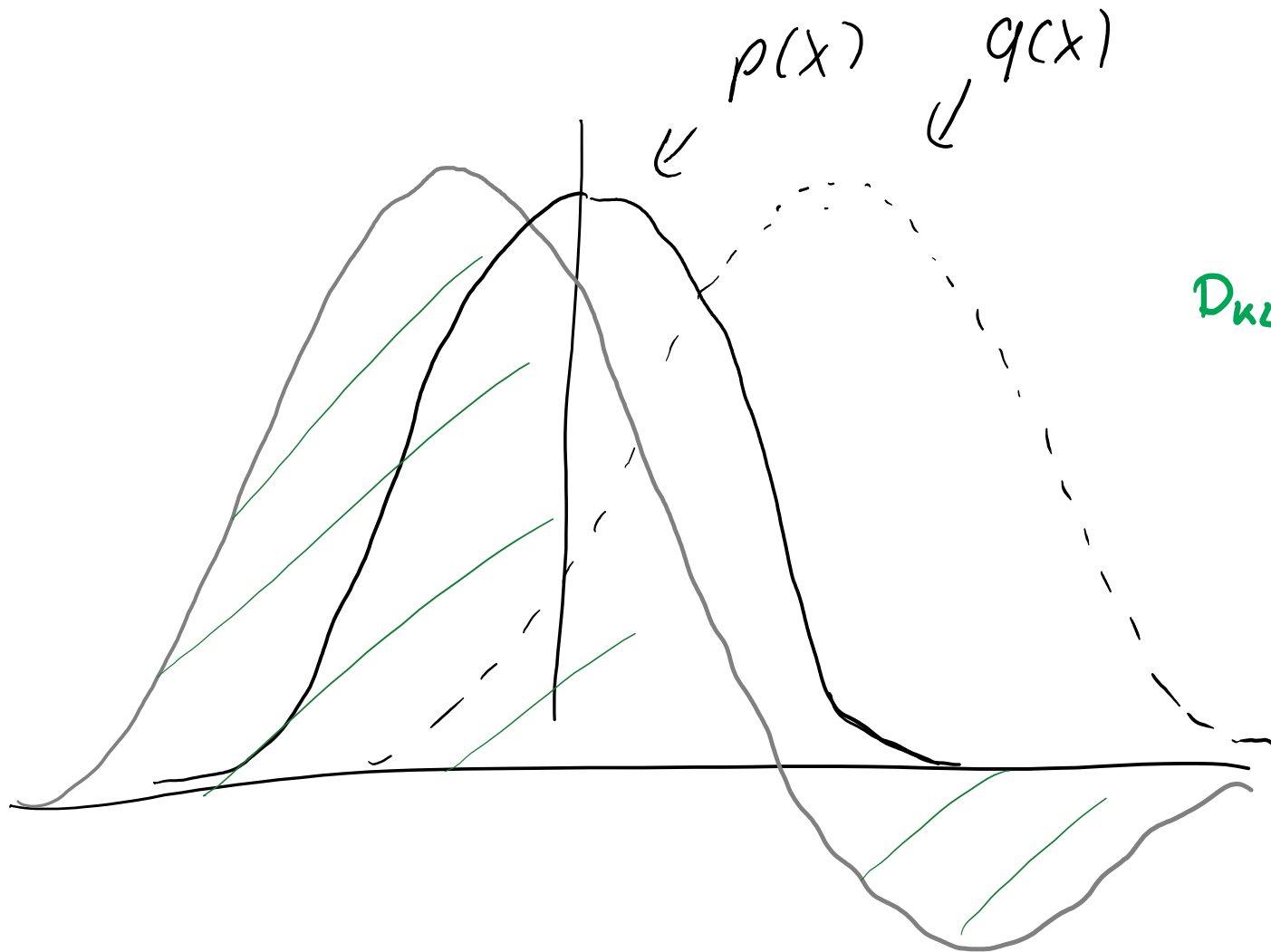
is trained to [ideally] map random normal-distributed inputs, drawn from Z , to a sample following the data distribution as output.

Discriminator:

$$D: X \rightarrow [0,1]$$

is trained to classify samples as genuine or fake.

Kullback-Leibler divergence



$$D_{KL}(P||Q) = \int_x p(x) \log \frac{p(x)}{q(x)} dx$$

特点: 1: 非负
2: 不对称
3: un-bounded

JS-Divergence

$$\mathcal{D}_{KL}(p \parallel q) = \int_x p(x) \log \frac{p(x)}{q(x)} dx$$
$$\mathcal{D}_{JS}(p \parallel q) = \frac{1}{2} \mathcal{D}_{KL}\left(p \parallel \frac{p+q}{2}\right) + \frac{1}{2} \mathcal{D}_{KL}\left(q \parallel \frac{p+q}{2}\right)$$



对称

bounded

Training GANs: Objective

Assuming G is fixed, to train D given a set of real samples:

$$x^n \sim p_d, \quad n = 1, \dots, N$$

We generate

$$z^n \sim \mathcal{N}(0,1), \quad n = 1, \dots, N$$

and form a training dataset

$$\mathbb{D} = \{(x^{(1)}, 1), \dots, (x^{(n)}, 1), (G(z^{(1)}), 0), \dots, G(z^{(n)}), 0)\}$$

Training GANs: Objective – Part II

Assuming G is fixed, to train D given training data \mathbb{D} :
(this will be on the blackboard)

TODO:

- ☐ Derive GAN objective
- ☐ Analyze behavior at optimum
- ☐ Show that objective minimizes JS-Divergence

Part I: Derive the GAN objective

a) Considering only D (G is static):

$$\mathcal{L}(D) = -\frac{1}{2N} \left(\sum_i^N (y^{(i)}) \log(D(x^{(i)})) + \sum_i^N (1-y^{(i)}) \log(1-D(x^{(i)})) \right)$$

for Discriminator only

We know that $\frac{1}{2}$ of samples $y=1$ & $\frac{1}{2}$ $y=0$

b) we leverage this to train D & G jointly

$$= -\frac{1}{2} \left(\mathbb{E}_{x \sim p_d} [\log(D(x))] + \mathbb{E}_{z \sim p_z} [\log(1-D(G(z)))] \right)$$

\Rightarrow Good G maximizes $\mathcal{L}(D)$

Part I: Derive the GAN objective

c) to find G we define:

$$V(G, D) = \mathbb{E}_{x \sim p_d} [\log(D(x))] + \mathbb{E}_{z \sim p_z} [\log(1 - D(G(z)))]$$

$\Rightarrow G^*$ will fool any D

$$G^* = \arg \min_G \max_D V(G, D)$$

...hence G tries to minimize V and D tries to maximize



Note the change in sign between $\mathcal{L}(D)$ in (b) and $V(G, D)$ in (c)...

Part II: Analyze equilibrium point wrt D

Equilibrium of $V(\cdot, \cdot)$

Let $D^* = \arg \max_D V(G, D)$

Optimum of $V(G, D)$ iff $p_d(x) = p_g(x)$

$$\min_G \max_D V(D, G) = \mathbb{E}_{x \sim p_{\text{data}}(x)} [\log D(x)] + \mathbb{E}_{z \sim p_z(z)} [\log(1 - D(G(z)))]$$

Proposition: if $p_d = p_g$ then $D^* = \frac{p_d}{p_d + p_g}$

Proof: $V(G, D) = \int_x p_d(x) \log(D(x)) dx + \int_z p_z(z) \log(1 - D(G(z))) dz$

$$= \int_x p_d(x) \log(D(x)) + p_g(x) \log(1 - D(x)) dx$$

Optimal D: $\forall a, b \in [0, 1] \quad f(y) = a \log y + b \log(1 - y)$

$$f'(y) = 0 \Rightarrow \frac{a}{y} - \frac{b}{1-y} = 0 \Rightarrow y = \frac{a}{a+b} \quad \text{maximum}$$

$$\text{if } a, b \neq 0 \quad f''\left(\frac{a}{a+b}\right) = -\frac{a}{\left(\frac{a}{a+b}\right)^2} - \frac{b}{\left(1 - \frac{a}{a+b}\right)^2} < 0 \text{ with } a, b \in [0, 1]$$

$$\Rightarrow D^* = \frac{p_d}{p_d + p_g}$$

Note: D is unique but can't be calculated in practice (dep. p_d)

$$-\frac{a}{y^2} - \frac{b}{(1-y)^2} \Big|_{y=\frac{a}{a+b}}$$

Part III: Analyze equilibrium point w.r.t. G

finding the best G

with D^* the obj. becomes

$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))]$$

$$G^* = \underset{G}{\operatorname{argmin}} V(G, D^*)$$

$$V(G, D^*) = \mathbb{E}_{\mathbf{x} \sim p_d} \left[\log \frac{p_d}{p_d + p_g} \right] + \mathbb{E}_{\mathbf{x} \sim p_g} \left[\log \left(1 - \frac{p_d}{p_d + p_g} \right) \right]$$

Part III: Analyze equilibrium point w.r.t. G

Theorem: global min is achieved if $p_d = p_g$
and at min $V(\cdot, \cdot) = -\log 4$

$$G^* = \arg \min_G V(G, D^*)$$

$$V(G, D^*) = \mathbb{E}_{x \sim p_d} \left[\log \frac{p_d}{p_d + p_g} \right] + \mathbb{E}_{x \sim p_g} \left[\log \left(1 - \frac{p_d}{p_d + p_g} \right) \right]$$

Proof: $1 - \frac{p_d}{p_d + p_g} = \frac{p_d + p_g}{p_d + p_g} - \frac{p_d}{p_d + p_g} = \frac{p_g}{p_d + p_g}$

$$\Rightarrow \mathbb{E}_{x \sim p_d} \left[\log \frac{p_d}{p_d + p_g} \right] + \mathbb{E}_{x \sim p_g} \left[\log \frac{p_g}{p_d + p_g} \right]$$

$$= -\log(2) + \mathbb{E}_{x \sim p_d} \left[\log \frac{2p_d}{p_d + p_g} \right] - \log(2) + \mathbb{E}_{x \sim p_g} \left[\log \frac{2p_g}{p_d + p_g} \right]$$

$$= -\log(4) + D_{KL} \left(p_d \parallel \frac{p_d + p_g}{2} \right) + D_{KL} \left(p_g \parallel \frac{p_d + p_g}{2} \right)$$

$$= -\log(4) + \underbrace{2 D_{JS} (p_d \parallel p_g)}$$

$$\geq 0; \quad 0 \text{ iff } p_d = p_g \quad \square$$

JS-Divergence

$$D_{KL} (p \parallel q) = \int p(x) \log \frac{p(x)}{q(x)} dx$$
$$D_{JS} (p \parallel q) = \frac{1}{2} D_{KL} \left(p \parallel \frac{p+q}{2} \right) + \frac{1}{2} D_{KL} \left(q \parallel \frac{p+q}{2} \right)$$

Next week

Generating high-quality images

Applications

