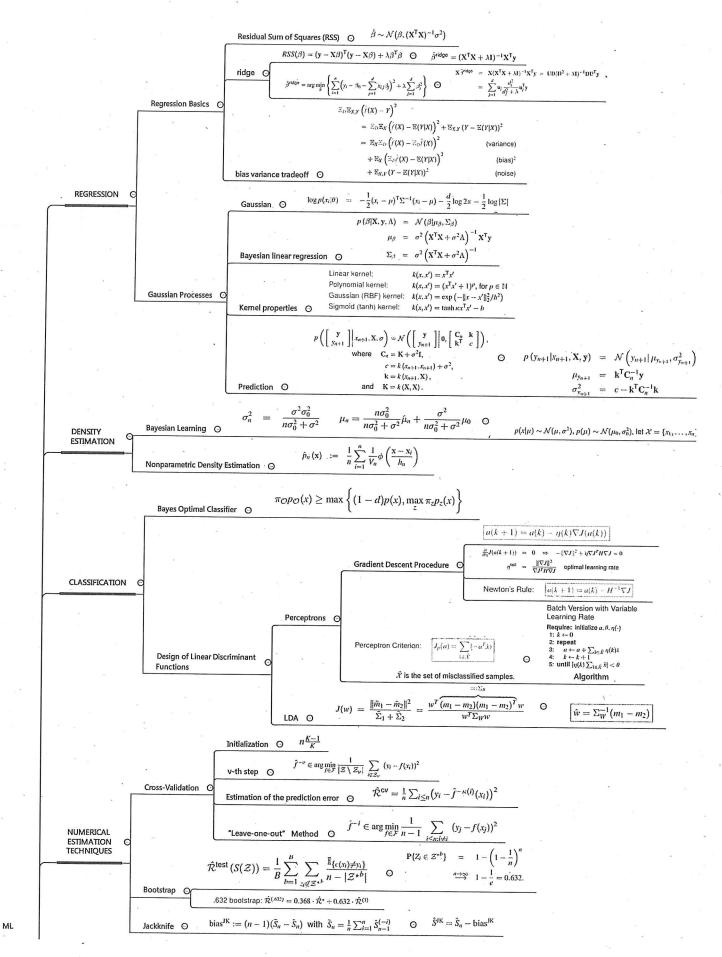
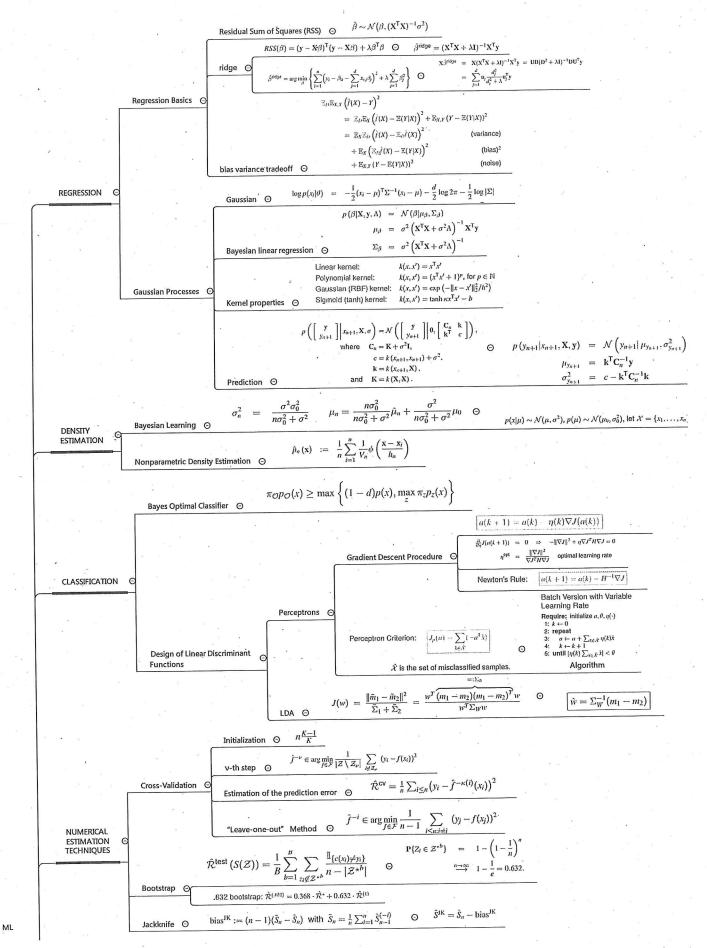
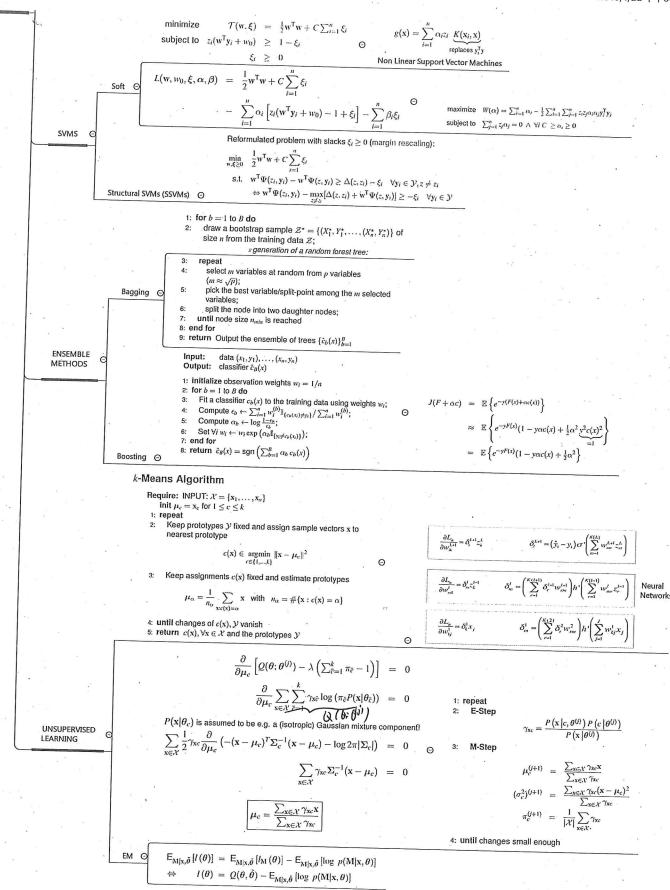
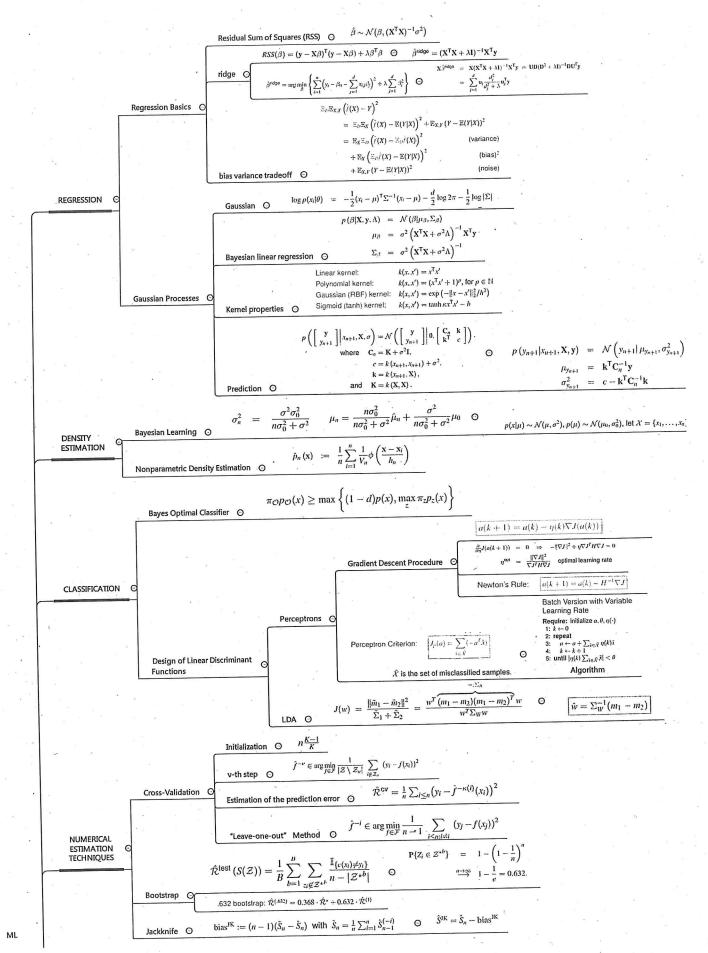
```
g(\mathbf{x}) = \sum_{i=1}^{n} \alpha_{i} z_{i} \underbrace{K(\mathbf{x}_{i}, \mathbf{x})}_{\text{roplaces } \mathbf{y}_{i}^{\mathsf{T}} \mathbf{y}}
                                                                                                                                   \mathcal{T}(\mathbf{w}, \boldsymbol{\xi}) = \frac{1}{2} \mathbf{w}^{\mathsf{T}} \mathbf{w} + C \sum_{i=1}^{n} \xi_{i}
                                                                                subject to z_i(\mathbf{w}^\mathsf{T}\mathbf{y}_i + w_0) \geq 1 - \xi_i
                                                                                                                                                                                                                                                            Non Linear Support Vector Machines
                                                                           L(\mathbf{w}, w_0, \xi, \alpha, \beta) = \frac{1}{2} \mathbf{w}^\mathsf{T} \mathbf{w} + C \sum_{i=1}^n \xi_i
                                         Soft C
                                                                                                                                  -\sum_{i=1}^{n} \alpha_i \left[ z_i(\mathbf{w}^\mathsf{T} \mathbf{y}_i + w_0) - 1 + \xi_i \right] - \sum_{i=1}^{n} \beta_i \xi_i
                                                                                                                                                                                                                                                                                                                     maximize W(\alpha) = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n z_i z_j \alpha_i \alpha_j y_i^{\mathsf{T}} y_j
                                                                                                                                                                                                                                                                                                                    subject to \sum_{i=1}^{n} \gamma_i \alpha_i = 0 \land \forall i \in C \ge \alpha_i \ge 0
                                                                                                                                      Reformulated problem with slacks \xi_i \ge 0 (margin rescaling):
SVMS
                                                                                                                                      \min_{\mathbf{w} \in \geq 0} \frac{1}{2} \mathbf{w}^{\mathsf{T}} \mathbf{w} + C \sum_{i=1}^{n} \xi_{i}
                                                                                                                                           \text{s.t.} \quad \boldsymbol{w}^\mathsf{T} \boldsymbol{\Psi}(\boldsymbol{z}_i, \boldsymbol{y}_i) - \boldsymbol{w}^\mathsf{T} \boldsymbol{\Psi}(\boldsymbol{z}, \boldsymbol{y}_i) \geq \Delta(\boldsymbol{z}, \boldsymbol{z}_i) - \boldsymbol{\xi}_l \quad \forall \boldsymbol{y}_i \in \mathcal{Y}, \boldsymbol{z} \neq \boldsymbol{z}_i
                                                                                                                                                            \Leftrightarrow \mathbf{w}^{\mathsf{T}} \Psi(z_i, \mathbf{y}_i) - \max_{z \in \mathcal{Z}} [\Delta(z, z_i) + \mathbf{w}^{\mathsf{T}} \Psi(z, \mathbf{y}_i)] \geq -\xi_i \quad \forall \mathbf{y}_i \in \mathcal{Y}
                                       Structural SVMs (SSVMs) (O
                                                                                                       1: for b = 1 to B do
                                                                                                                    draw a bootstrap sample \mathcal{Z}^* = \{(X_1^*, Y_1^*, \dots, (X_n^*, Y_n^*))\} of
                                                                                                                     size n from the training data Z;
                                                                                                                                                          n generation of a random forest tree:
                                                                                                                   repeat
                                                                                                                         select m variables at random from p variables
                                                                                                                         (m \approx \sqrt{p});
                                                                                                                         pick the best variable/split-point among the m selected
                                                      Bagging O
                                                                                                                         variables;
                                                                                                                 split the node into two daughter nodes; until node size n_{min} is reached
                                                                                                     9: return Output the ensemble of trees \{\hat{c}_h(x)\}_{h=1}^B
                                                                                                        Input: data (x_1, y_1), \dots, (x_n, y_n)
Output: classifier \delta_R(x)
ENSEMBLE
METHODS
                                                                                                        1: initialize observation weights w_l = 1/n
                                                                                                        2: for b = 1 to B do
                                                                                                                                                                                                                                                                                                           J(F + \alpha c) = \mathbb{E}\left\{e^{-y(F(x) + \alpha c(x))}\right\}
                                                                                                                    The a classifier c_b(x) to the training data using weights w_i; Compute c_b \leftarrow \sum_{i=1}^n w_i^{(b)} \frac{1}{2} \{c_b(x_i) \neq y_i\} / \sum_{i=1}^n w_i^{(b)}; Compute \alpha_b \leftarrow \log \frac{1-c_b}{2};
                                                                                                                                                                                                                                                                                                                                          \approx \mathbb{E}\left\{e^{-yF(x)}(1-y\alpha c(x)+\frac{1}{2}\alpha^2\underbrace{y^2c(x)^2}_{=1}\right\}
                                                                                                                    Set \forall i \ w_i \leftarrow w_i \exp \left(\alpha_h \mathbb{I}_{\{y_i \neq c_h(v_i)\}}\right);
                                                                                                        7: end for
                                                                                                        8: return \hat{c}_B(x) = \operatorname{sgn}\left(\sum_{b=1}^B \alpha_b c_b(x)\right)
                                                      Boosting ⊙
                                                                   k-Means Algorithm
                                                                                Require: INPUT: \mathcal{X} = \{x_1, \dots, x_n\}
                                                                                         init \mu_c = \mathbf{x}_c for 1 \le c \le k
                                                                                   1: repeat
                                                                                                Keep prototypes 3' fixed and assign sample vectors x to
                                                                                                                                                                                                                                                                                                                        \frac{\partial L_n}{\partial w_a^{l+1}} = \delta_i^{L+1} z_1^L \qquad \qquad \delta_i^{L+1} = \left(\hat{y}_i - y_i\right) O^{-1} \left(\sum_{m=1}^{K(L)} w_m^{L+1} z_m^L\right)
                                                                                                nearest prototype
                                                                                                                                           c(\mathbf{x}) \in \underset{c \in \{1,\dots,t\}}{\operatorname{argmin}} \|\mathbf{x} - \boldsymbol{\mu}_c\|^2
                                                                                                                                                                                                                                                                                                                        \frac{\partial L_s}{\partial w_{\rm est}^l} = \delta_a^l z_1^{l-1} \hspace{1cm} \delta_r^l = \left(\sum_{t=1}^{K(l+1)} \delta_r^{l+1} w_{im}^{l+1}\right) h^t \left(\sum_{r=1}^{K(l-1)} w_{uv}^l z_r^{l+1}\right) \hspace{1cm} \begin{array}{c} {\sf Neural} \\ {\sf Networkc} \end{array}
                                                                                               Keep assignments c(\mathbf{x}) fixed and estimate prototypes
                                                                                                               \mu_{\alpha} = \frac{1}{n_{\alpha}} \sum_{\mathbf{x} \in \mathbf{x} \mid \mathbf{x} = \alpha} \mathbf{x} \quad \text{with} \quad n_{\alpha} = \#\{\mathbf{x} : c(\mathbf{x}) = \alpha\}
                                                                                                                                                                                                                                                                                                                       \frac{\partial L_s}{\partial w_{ij}^1} = \delta_k^1 x_j \qquad \qquad \delta_m^1 = \left(\sum_{i=1}^{K(2)} \delta_i^2 w_{im}^2\right) h^i \left(\sum_{j=1}^{j} w_{kj}^1 x_j\right)
                                                                                  4: until changes of c(\mathbf{x}), \mathcal{Y} vanish
5: return c(\mathbf{x}), \forall \mathbf{x} \in \mathcal{X} and the prototypes \mathcal{Y}
                                                                                                                                                       \frac{\partial}{\partial \mu_{\epsilon}} \left[ Q(\theta; \theta^{(j)}) - \lambda \left( \sum_{i=1}^{k} \pi_{\epsilon} - 1 \right) \right] = 0
                                                                                                                                                                         \frac{\partial}{\partial \mu_c} \sum_{r \in \mathcal{X}} \sum_{i=1}^k \gamma_{Xi} \log \left( \pi_c P(\mathbf{x}|\boldsymbol{\theta}_c) \right) = 0
                                                                                                                                                                                                                                                                                                                                       t: repeat
                                                                                                                                                                                                                                                                                                                                                                                               \gamma_{xc} = \frac{P\left(\mathbf{x} \mid c, \theta^{(j)}\right) P\left(c \mid \theta^{(j)}\right)}{P\left(\mathbf{x} \mid \theta^{(j)}\right)}
                                                                                                \begin{split} P(\mathbf{x}|\theta_c) \text{ is assumed to be e.g. a (isotropic) Gaussian mixture component!} \\ \sum_{\mathbf{x} \in \mathcal{X}} \frac{1}{2} \gamma_{\mathbf{x}r} \frac{\partial}{\partial \mu_c} \left( -(\mathbf{x} - \mu_c)^T \Sigma_c^{-1} (\mathbf{x} - \mu_c) - \log 2\pi |\Sigma_c| \right) &= 0 \\ \sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x}c} \Sigma_c^{-1} (\mathbf{x} - \mu_c) &= 0 \end{split}
  UNSUPERVISED
                                                                                                                                                                                                                                                                                                                                                    M-Step
 LEARNING
                                                                                                                                                                                                                                                                                                                                                                                      \begin{array}{rcl} \boldsymbol{\mu}_{\mathrm{c}}^{(j+1)} &=& \frac{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} \mathbf{c}} \mathbf{x}}{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} \mathbf{c}}} \\ (\boldsymbol{\sigma}_{\mathrm{c}}^{2})^{(j+1)} &=& \frac{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} \mathbf{c}} (\mathbf{x} - \boldsymbol{\mu}_{\mathrm{c}})^{2}}{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} \mathbf{c}}} \\ \boldsymbol{\pi}_{\mathrm{c}}^{(j+1)} &=& \frac{1}{|\mathcal{X}|} \sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} \mathbf{c}} \end{array}
                                                                                                                                                                         \mu_c = \frac{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x}c} \mathbf{x}}{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x}c}}
                                                                                                                                                                                                                                                                                                                                        4: until changes small enough
                                                                                                       \mathsf{E}_{\mathsf{M}|\mathbf{x},\tilde{\boldsymbol{\theta}}}\left[l\left(\boldsymbol{\theta}\right)\right] \ = \ \mathsf{E}_{\mathsf{M}|\mathbf{x},\hat{\boldsymbol{\theta}}}\left[l_{\mathsf{M}}\left(\boldsymbol{\theta}\right)\right] - \mathsf{E}_{\mathsf{M}|\mathbf{x},\hat{\boldsymbol{\theta}}}\left[\log\ p(\mathsf{M}|\mathbf{x},\boldsymbol{\theta})\right]
                                                                   EM O
                                                                                                                             I(\theta) = Q(\theta, \tilde{\theta}) - \mathsf{E}_{\mathbf{M}|\mathbf{x}, \tilde{\theta}} [\log p(\mathbf{M}|\mathbf{x}, \theta)]
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minimize
                                                                                                                                                  \mathcal{T}(\mathbf{w}, \boldsymbol{\xi}) = \frac{1}{2} \mathbf{w}^{\mathsf{T}} \mathbf{w} + C \sum_{i=1}^{n} \xi_{i}
                                                                                                                                                                                                                                                                             g(\mathbf{x}) = \sum_{i=1}^{n} \alpha_{i} z_{i} \underbrace{K(\mathbf{x}_{i}, \mathbf{x})}_{\text{replaces } \mathbf{y}_{i}^{\mathsf{T}} \mathbf{y}}
                                                                                             subject to z_i(\mathbf{w}^\mathsf{T}\mathbf{y}_i + w_0) \geq 1 - \xi_i
                                                                                                                                                                                                                                                                          Non Linear Support Vector Machines
                                                                                        L(\mathbf{w}, w_0, \xi, \alpha, \beta) = \frac{1}{2} \mathbf{w}^\mathsf{T} \mathbf{w} + C \sum_{i=1}^{n} \xi_i
                                                     Soft C
                                                                                                                                                - \sum_{i=1}^{n} \alpha_i \left[ z_i (\mathbf{w}^\mathsf{T} \mathbf{y}_i + w_0) - 1 + \xi_i \right] - \sum_{i=1}^{n} \beta_i \xi_i
                                                                                                                                                                                                                                                                                                                                  maximize W(\alpha) = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n z_i z_j \alpha_i \alpha_j y_i^{\mathsf{T}} y_j
                                                                                                                                                                                                                                                                                                                                 subject to \sum_{j=1}^{n} z_{j}\alpha_{j} = 0 \land \forall i \in \{0, 1\} \geq 0
           SVMS
                                                                                                                                                   Reformulated problem with slacks \xi_i \geq 0 (margin rescaling):
                                                                                                                                                   \min_{\mathbf{w}, \xi \geq 0} \frac{1}{2} \mathbf{w}^{\mathsf{T}} \mathbf{w} + C \sum_{i=1}^{n} \xi_{i}
                                                                                                                                                      \begin{aligned} \text{s.t.} \quad & w^T \Psi(z_i, y_i) - w^T \Psi(z_i, y_i) \geq \Delta(z, z_i) - \xi_i \quad \forall y_i \in \mathcal{Y}, z \neq z_i \\ & \Leftrightarrow & w^T \Psi(z_i, y_i) - \max_{z \neq z_i} [\Delta(z, z_i) + w^T \Psi(z, y_i)] \geq -\xi_i \quad \forall y_i \in \mathcal{Y} \end{aligned}
                                                   1: for b = 1 to B do
                                                                                                                              draw a bootstrap sample \mathcal{Z}^* = \{(X_1^*, Y_1^*, \dots, (X_n^*, Y_n^*))\} of size n from the training data \mathcal{Z}^*.
                                                                                                                                                                    n generation of a random forest tree:
                                                                                                                                  select m variables at random from p variables
                                                                                                                                 (m \approx \sqrt{p}); pick the best variable/split-point among the m selected
                                                              Bagging
                                                                                                                                 variables:
                                                                                                                                 split the node into two daughter nodes;
                                                                                                                        until node size n<sub>min</sub> is reached
                                                                                                            9: return Output the ensemble of trees \{\hat{c}_b(x)\}_{b=1}^B
        ENSEMBLE
                                                                                                                Input: data (x_1, y_1), \dots, (x_n, y_n)
Output: classifier \hat{c}_B(x)
       METHODS
                                                                                                                1: initialize observation weights w_l = 1/n

    Initialize observation weights w<sub>i</sub> = 1/n
    for b = 1 to B do
    Fit a classifler c<sub>b</sub>(x) to the training data using weights w<sub>i</sub>;
    Compute c<sub>b</sub> ← ∑<sup>n</sup><sub>i=1</sub> w<sub>i</sub><sup>(b)</sup> ∑̄<sub>(r,h</sub>(x) ≠ y<sub>i</sub>) / ∑<sup>n</sup><sub>i=1</sub> w<sub>i</sub><sup>(b)</sup>;
    Compute α<sub>b</sub> ← log ½···c<sub>b</sub>;

                                                                                                                                                                                                                                                                                                                   J(F+\alpha c) \ = \ \mathbb{E}\left\{e^{-y(F(x)+\alpha c(x))}\right\}
                                                                                                                                                                                                                                                                                                                                                   \approx \mathbb{E}\left\{e^{-yF(x)}(1-\operatorname{vac}(x)+\tfrac{1}{2}\alpha^2\underbrace{y^2c(x)^2}_{=1}\right\}
                                                                                                                          Set \forall i \ w_i \leftarrow w_i \exp \left(\alpha_b \mathbb{I}_{\{y_i \neq c_b(v_i)\}}\right);
                                                                                                              8: return \hat{c}_B(x) = \operatorname{sgn}\left(\sum_{b=1}^B \alpha_b c_b(x)\right)
                                                           Boosting (
                                                                        k-Means Algorithm
                                                                                   Require: INPUT: \mathcal{X} = \{x_1, \dots, x_n\}
init \mu_c = x_c for 1 \le c \le k
                                                                                                   Keep prototypes {\cal Y} fixed and assign sample vectors {\bf x} to nearest prototype
                                                                                                                                                                                                                                                                                                                           \frac{\partial L_{s}}{\partial w_{s}^{t,t}} = \delta_{i}^{t-1} z_{t}^{t} \delta_{i}^{t,t} = \left(\hat{y}_{i} - y_{i}\right) \sigma^{t} \left(\sum_{m=1}^{K(t)} w_{m}^{t,t} z_{m}^{t}\right)
                                                                                                                                                c(\mathbf{x}) \in \underset{c \in \{1,\dots,k\}}{\operatorname{argmin}} \|\mathbf{x} - \boldsymbol{\mu}_c\|^2
                                                                                                  Keep assignments c(\mathbf{x}) fixed and estimate prototypes
                                                                                                                                                                                                                                                                                                                           \frac{\partial L_n}{\partial w_{sal}^l} \simeq \delta_m^l z_1^{l+1} \hspace{1cm} \delta_m^l = \left(\sum_{t=1}^{K(l+1)} \delta_t^{l+1} w_{sm}^{l+1}\right) h^t \left(\sum_{t=1}^{K(l+1)} w_{sm}^l z_t^{l+1}\right) \hspace{1cm} \text{Neural} \hspace{1cm} \text{Networks}
                                                                                                                 \mu_{\alpha} = \frac{1}{n_{\alpha}} \sum_{\mathbf{x} \in [\mathbf{x}] = \alpha} \mathbf{x} \quad \text{with} \quad n_{\alpha} = \#\{\mathbf{x} : c(\mathbf{x}) = \alpha\}
                                                                                                                                                                                                                                                                                                                        \frac{\partial L_{a}}{\partial w_{ij}^{1}} = \delta_{i}^{1} x_{i} \qquad \qquad \delta_{m}^{1} = \left(\sum_{i=1}^{K(2)} \delta_{i}^{2} w_{im}^{2}\right) h^{1} \left(\sum_{j=1}^{j} w_{kj}^{1} x_{j}\right)
                                                                                    4: until changes of c(x), \mathcal Y vanish
5: return c(x), \forall x \in \mathcal X and the prototypes \mathcal Y
                                                                                                                                                        \frac{\partial}{\partial \mu_{\epsilon}} \left[ \mathcal{Q}(\theta; \theta^{(j)}) - \lambda \left( \sum_{\tilde{\epsilon}=1}^k \pi_{\tilde{\epsilon}} - 1 \right) \right] \ = \ 0
                                                                                                                                                                        \frac{\partial}{\partial \mu_c} \sum_{\mathbf{x} \in \mathcal{X}} \sum_{\hat{c} = 1}^k \gamma_{\mathbf{x}\hat{c}} \log \left( \pi_{\hat{c}} P(\mathbf{x} | \boldsymbol{\theta}_{\hat{c}}) \right) = 0
                                                                                                                                                                                                                                                                                                                                       1: repeat
2: E-Step
                                                                                                                                                                                                                                                                                                                                                                                            \gamma_{xc} = \frac{P(\mathbf{x} | c, \theta^{(j)}) P(c | \theta^{(j)})}{P(\mathbf{x} | \theta^{(j)})}
                                                                                                P(\mathbf{x}|\theta_c) is assumed to be e.g. a (isotropic) Gaussian mixture component! \sum_{\mathbf{x}\in\mathcal{X}}\frac{1}{2}\gamma_{\mathbf{x}_c}\frac{\partial}{\partial\mu_c}\left(-(\mathbf{x}-\mu_c)^T\Sigma_c^{-1}(\mathbf{x}-\mu_c)-\log2\pi|\Sigma_c|\right) = 0 \quad \quad \bigcirc
 UNSUPERVISED
LEARNING
                                                                                                                                                                                                                                                                                                                                      3: M-Step
                                                                                                                                                                                                                                                                                                                                                                                   \begin{array}{rcl} \mu_c^{(j+1)} &=& \frac{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} c} \mathbf{x}}{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} c}} \\ (\sigma_c^2)^{(j+1)} &=& \frac{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} c} (\mathbf{x} - \mu_c)^2}{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} c}} \\ \pi_c^{(j+1)} &=& \frac{1}{|\mathcal{X}|} \sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} c} \end{array}
                                                                                                                                                                                                       \sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x} c} \Sigma_c^{-1} (\mathbf{x} - \mu_c) = 0
                                                                                                                                                                     \mu_{c} = \frac{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x}c} \mathbf{x}}{\sum_{\mathbf{x} \in \mathcal{X}} \gamma_{\mathbf{x}c}}
                                                                                                                                                                                                                                                                                                                                     4: until changes small enough
                                                                EM O
                                                                                                    \mathsf{E}_{\mathsf{M}|\mathsf{x},\tilde{\boldsymbol{\theta}}}\left[l\left(\boldsymbol{\theta}\right)\right] \ = \ \mathsf{E}_{\mathsf{M}|\mathsf{x},\tilde{\boldsymbol{\theta}}}\left[l_{\mathsf{M}}\left(\boldsymbol{\theta}\right)\right] - \mathsf{E}_{\mathsf{M}|\mathsf{x},\tilde{\boldsymbol{\theta}}}\left[\log\ p(\mathsf{M}|\mathsf{x},\boldsymbol{\theta})\right]
```

 $l(\theta) = Q(\theta, \tilde{\theta}) - \mathsf{E}_{\mathsf{M}[\mathsf{x}, \tilde{\theta}]}[\log p(\mathsf{M}|\mathsf{x}, \theta)]$