

Exercise 2

According to the French Flag model, morphogens form a gradient across a field of cells, and cells determine their fate according to the local concentration of the morphogen. In this exercise, you will solve two standard 1-component models for morphogen gradients that lead to either a linear or an exponential gradient.

1. Review Material from the Lecture

- Explain how the diffusion equation is derived!
- Describe the French Flag model!
- Why is it important to include a degradation term in the PDE?
- Why is it important to know the time to steady-state? What does this time depend on?

2. **Steady-state Gradient profiles.** Morphogen gradients are often considered to be stationary, i.e. their concentration profile is assumed to be in steady-state. We will now derive two standard steady-state gradient models.

Derive the (analytic) steady-state solutions of

$$\begin{aligned}\frac{\partial c}{\partial t} &= D\Delta c \\ c(x=0, t) &= c_0, \quad c(x=L, t) = 0\end{aligned}\tag{1}$$

and

$$\begin{aligned}\partial c / \partial t &= D\Delta c - k \cdot c \\ c(x=0, t) &= c_0, \quad c(x \rightarrow \infty) = 0\end{aligned}\tag{2}$$

Hint. The first case gives a linear, the second an exponential gradient. You can transform the second order ODEs into a set of two first order ODEs by writing $z = dc/dx$. You can then eliminate dx and solve the resulting equations by standard methods.

3. **Time-dependent Solution.** Use separation of variables to solve the 1D diffusion problem

$$\begin{aligned}\partial c / \partial t &= D\Delta c - k \cdot c \\ c(x=0, t) &= c_0, \quad c(x=L, t) = 0 \\ c(x=0, 0) &= c_0, \quad c(x>0, 0) = 0.\end{aligned}\tag{3}$$

Separation of variables is a powerful technique to solve initial-boundary-value problems (IBVPs), provided that

- the PDE is linear and homogeneous (coefficients do not necessarily have to be constant)

- the boundary conditions are linear and homogeneous.

Accordingly, you need to first transform the inhomogeneous boundary conditions into homogenous boundary conditions. Proceed as follows:

- i Determine the steady-state solution, c_s .
 - ii Solve the PDE for the function $u(x, t) = c(x, t) - c_s(x)$. Here, use the ansatz $u(x, t) = X(x) \cdot T(t)$ to separate the variables on both sides of the equation. Since the two equal expressions depend on different variables they have to be constant, say λ . This gives two linear, homogeneous ordinary differential equations for X and T that can be easily solved. Use the boundary and initial conditions to fix λ and the integration constants from the ODEs.
 - ii Determine $c(x, t) = c_s(x) + u(x, t)$.
 - iv What is the characteristic time to steady state?
4. **Numerical Solution.** Solve Eq. 3 numerically for $c_0 = 1$, $L = 50$, $D = 0.1$, $k = 10^{-5}$ and compare your results to the exact solution. Repeat the simulation for $k = 1$, for $D = 100$, and for $L = 500$. How do the solutions differ? Why? Now repeat your simulations with the initial parameterisation and $k = 0$, and discuss your solution. Finally, repeat your simulations for flux boundary conditions

$$\left. \frac{\partial c}{\partial x} \right|_{x=0} = -1, \quad \left. \frac{\partial c}{\partial x} \right|_{x=L} = 0, \quad (4)$$

with $k = 10^{-5}$ and $k = 0$. How do the solutions differ? Why?

Hint: Use the function `pdepe` in Matlab.