

EE2211 Pre-Tutorial 10

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Agenda

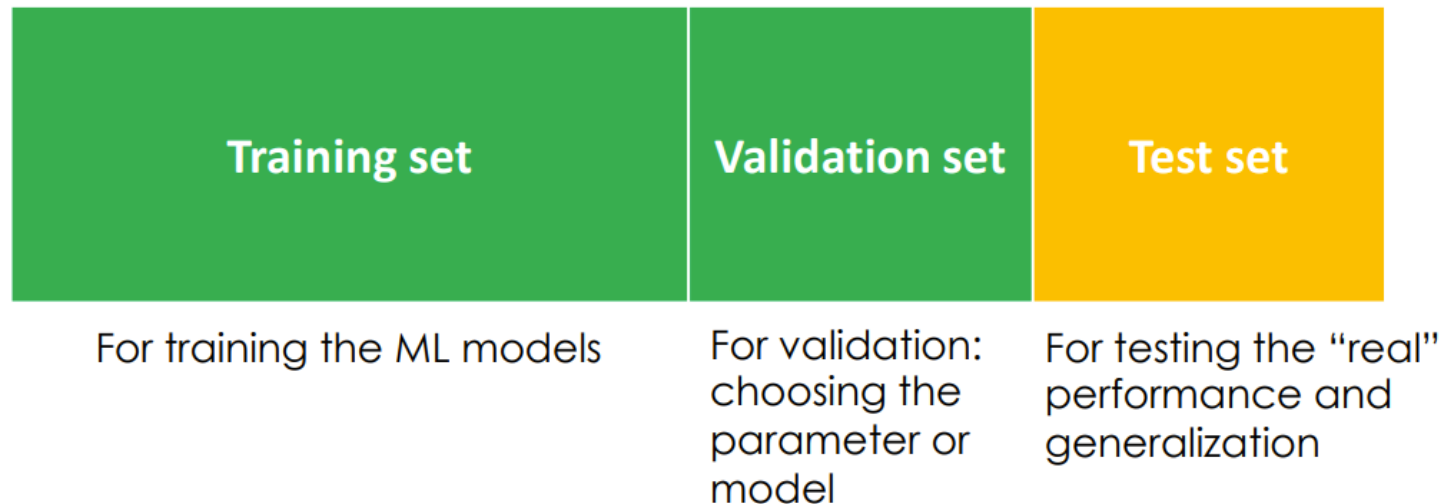
- Recap
- Self-learning
- Tutorial 10



Recap

- Dataset Partition:
 - Training/Validation/Testing
- Cross Validation
- Evaluation Metrics
 - Evaluating the quality of a trained machine learning system
 - Mean Square Error
 - Mean Absolute Error
 - Confusion Matrix
 - Cost Matrix

Training, Validation, Test



Example of hyper-parameters, which are set before the training process begins:

- Order of polynomial
- Regularization parameters (λ)
- Tree depth (decision trees, random forests)
- Number of trees (random forests)

K-fold Cross Validation

- In practice, we do the **k-fold cross validation**

4-fold cross validation

Test

Step 1: take out *test set* from the dataset

K-fold Cross Validation

- In practice, we do the **k-fold cross validation**

Test

4-fold cross validation



Step 2: We partition the *remaining part of the dataset* (after taking out the test set), into k equal parts (equal in terms of number of samples).

K-fold Cross Validation

- In practice, we do the **k-fold cross validation**

Test

4-fold cross validation

Fold 1	Train	Train	Train	Validation
Fold 2	Train	Train	Validation	Train
Fold 3	Train	Validation	Train	Train
Fold 4	Validation	Train	Train	Train

Order of the samples are kept the same across all folds.

Step 3: We run *k folds* (i.e., k times) of experiments.

Within each fold, we use *one part* as *validation set*, and the *k-1 remaining parts* as *training set*. We use different validation sets for different folds.

K-fold Cross Validation

- In practice, we do the **k-fold cross validation**

4-fold cross validation					Classifiers Trained
Test					
Fold 1	Train	Train	Train	Validation	C_1^1 C_2^1
Fold 2	Train	Train	Validation	Train	C_1^2 C_2^2
Fold 3	Train	Validation	Train	Train	C_1^3 C_2^3
Fold 4	Validation	Train	Train	Train	C_1^4 C_2^4

1) C_1 : Random Forest with 100 trees

2) C_2 : Random Forest with 200 trees

Step 3.1: Within each fold, if we have n parameter/model candidates, we will train n models, and we check their validation performance.

K-fold Cross Validation

- In practice, we do the **k-fold cross validation**

Test

4-fold cross validation

Classifiers
Trained

Fold 1	Train	Train	Train	Validation	C_1^1 C_2^1
Fold 2	Train	Train	Validation	Train	C_1^2 C_2^2
Fold 3	Train	Validation	Train	Train	C_1^3 C_2^3
Fold 4	Validation	Train	Train	Train	C_1^4 C_2^4

Example: which one to select for test?

	Fold 1 Accuracy on Validation Set 1	Fold 2 Accuracy on Validation Set 2	Fold 3 Accuracy on Validation Set 3	Fold 4 Accuracy on Validation Set 4	Average Accuracy on All Validation Sets
Classifier with Param1 (e.g. 100 trees)	88% C_1^1	89% C_1^2	93% C_1^3	92% C_1^4	90.5%
Classifier with Param2 (e.g. 200 trees)	90% C_2^1	88% C_2^2	91% C_2^3	91% C_2^4	90%

Step 4: We select the parameter/model with best average validation performance over k folds.

Evaluation Metrics

Regression

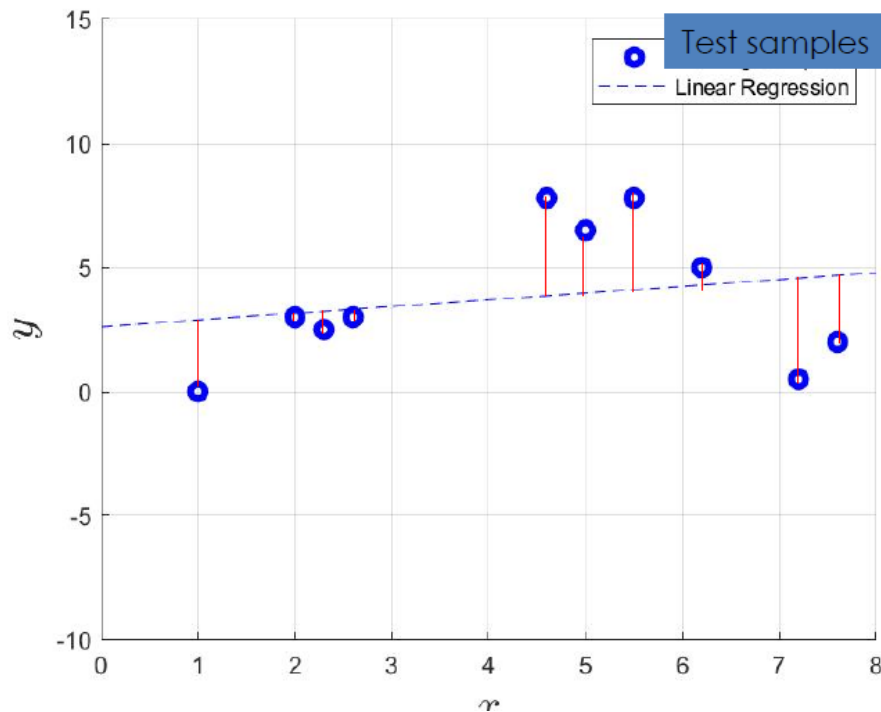
Mean Square Error

$$(\text{MSE} = \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n})$$

Mean Absolute Error

$$(\text{MAE} = \frac{\sum_{i=1}^n |y_i - \hat{y}_i|}{n})$$

where y_i denotes the target output and \hat{y}_i denotes the predicted output for sample i .



Evaluation Metrics

Classification

(True Positive Rate) $TPR = TP/(TP+FN)$ **Recall**
(False Negative Rate) $FNR = FN/(TP+FN)$

(True Negative Rate) $TNR = TN/(FP+TN)$
(False Positive Rate) $FPR = FP/(FP+TN)$

$TPR + FNR = 1$ (100% of positive-class data)
 $TNR + FPR = 1$ (100% of negative-class data)

Confusion Matrix for Binary Classification

	\hat{P} (predicted)	\hat{N} (predicted)	
P (actual)	TP	FN	Recall $TP/(TP+FN)$
N (actual)	FP	TN	
	Precision $TP/(TP+FP)$	Accuracy $(TP+TN)/(TP+TN+FP+FN)$	

Evaluation Metrics

Classification

Cost Matrix for Binary Classification

	\hat{P} (predicted)	\hat{N} (predicted)
P (actual)	$C_{p,p} * TP$	$C_{p,n} * FN$
N (actual)	$C_{n,p} * FP$	$C_{n,n} * TN$

Total cost:

$$\begin{aligned} &C_{p,p} * TP + \\ &C_{p,n} * FN + \\ &C_{n,p} * FP + \\ &C_{n,n} * TN \end{aligned}$$

Main Idea: To assign different **penalties** for different entries. Higher penalties for more severe results. Smaller costs are preferred.

Usually, $C_{p,p}$ and $C_{n,n}$ are set to 0; $C_{n,p}$ and $C_{p,n}$ may and may not equal

Evaluation Metrics

- Example of cost matrix
 - Assume we would like to develop a self-driving car system
 - We have an ML system that detects the pedestrians using camera, by conducting a binary classification
 - When it detects a person (positive class), the car should stop
 - When no person is detected (negative class), the car keeps going

True Positive (cost $C_{p,p}$)

There is person, ML detects person and car stops

True Negative (cost $C_{n,n}$)

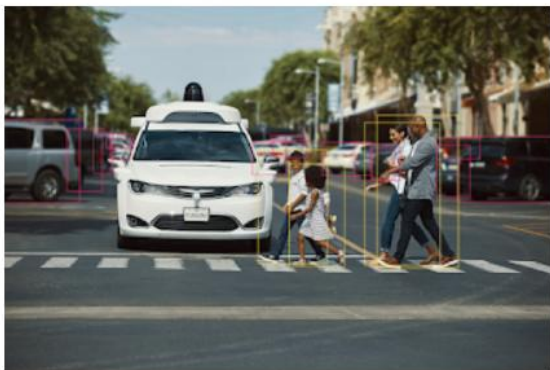
There is no person, car keeps going

False Positive (cost $C_{n,p}$)

There is no person, ML detects person and car stops

False Negative (cost $C_{p,n}$)

There is person, ML fails to detect person and car keeps going



Credit: [automotiveworld.com](https://www.automotiveworld.com)

$$C_{n,p} \stackrel{?}{=} C_{p,n} (>, <, \text{ or } =)$$

Evaluation Metrics

- For unbalanced data...

- Assume we have 1000 samples, of which 10 are positive and 990 are negative

- Accuracy = $990/1000=0.99$!
Very high number!

- Yet, half of the Class-1 are
Classified to Class-2!

	Class-1 (predicted)	Class-2 (predicted)
Class-1 (actual)	5 (TP)	5 (FN)
Class-2 (actual)	5 (FP)	985 (TN)

The goal is to highlight the problems of the results!


In this case, we shall

- 1) Use cost matrix, assign different costs for each entry
- 2) Use Precision and Recall! Precision = 0.5 and Recall = 0.5

Evaluation Metrics

Classification

Prediction function $y = f(x)$



sample	N1	N2	P1	N3	P2	P3
input x	-4	-3	-2.5	-2	-1.5	-0.5
Prediction y	-1.1	-0.5	-0.1	0.2	0.6	0.9
Actual Label	-1	-1	1	-1	1	1

If threshold set to be $y=0$,
N3, P2, P3 will be taken as +1
P1, N2, N1 will be taken as -1


	\hat{p} (predicted)	\hat{N} (predicted)
\hat{p} (actual)	$TP = 2$	$FN = 1$
\hat{N} (actual)	$FP = 1$	$TN = 2$

Evaluation Metrics

Classification

Prediction function $y = f(x)$

We can change the threshold!



sample	N1	N2	P1	N3	P2	P3
input x	-4	-3	-2.5	-2	-1.5	-0.5
Prediction y	-1.1	-0.5	-0.1	0.2	0.6	0.9
Actual Label	-1	-1	1	-1	1	1

If threshold set to be $y=0.4$,
P2, P3 will be taken as +1
N3, P1, N2, N1 will be taken as -1

	\hat{P} (predicted)	\hat{N} (predicted)
P (actual)	$TP = 2$	$FN = 1$
N (actual)	$FP = 0$	$TN = 3$

Evaluation Metrics

Classification:

TP, FP, FN, TN will change wrt thresholds!

If threshold set to be $y=0$,
N3, P2, P3 will be taken as +1
P1, N2, N1 will be taken as -1

	\hat{P} (predicted)	\hat{N} (predicted)
P (actual)	$TP = 2$	$FN = 1$
N (actual)	$FP = 1$	$TN = 2$

If threshold set to be $y=0.4$,
P2, P3 will be taken as +1
N3, P1, N2, N1 will be taken as -1

	\hat{P} (predicted)	\hat{N} (predicted)
P (actual)	$TP = 2$	$FN = 1$
N (actual)	$FP = 0$	$TN = 3$

Evaluation Metrics

Classification

Confusion Matrix for Multicategory Classification

	$P_{\hat{1}}$ (predicted)	$P_{\hat{2}}$ (predicted)		$P_{\hat{C}}$ (predicted)
P_1 (actual)	$P_{1,\hat{1}}$	$P_{1,\hat{2}}$...	$P_{1,\hat{C}}$
P_2 (actual)	$P_{2,\hat{1}}$	$P_{2,\hat{2}}$...	$P_{2,\hat{C}}$
\vdots	\vdots	\vdots	\ddots	\vdots
P_C (actual)	$P_{C,\hat{1}}$	$P_{C,\hat{2}}$		$P_{C,\hat{C}}$



THANK YOU