#### **ASSIGNMENT-4**

Date	30 October 2022
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Maximum Marks	2 Marks

## **Problem Statement:**

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cm send "alert" to IBM cloud and display in device recent events.

#### CODE:

```
esp32-blink.ino ● diagram.json ●
                                           libraries txt 

                                                              Library Manager
         pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
         pinMode(LED, OUTPUT);
         delay(10);
         wificonnect();
         mqttconnect();
         void loop()// Recursive Function
          digitalWrite(trig,LOW);
           digitalWrite(trig,HIGH);
           delayMicroseconds(10);
digitalWrite(trig,LOW);
           float dur = pulseIn(echo,HIGH);
           float dist = (dur * 0.0343)/2;
Serial.print ("Distancein cm");
Serial.println(dist);
           PublishData(dist);
           delay(1000);
if (!client.loop()) {
             mqttconnect();
         void PublishData(float dist) {
           mqttconnect();//function call for connecting to ibm
```

```
esp32-blink.ino
                   diagram.json •
                                     libraries.txt ●
                                                     Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
            delay(500);
            Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
Serial.println("IP address: ");
          Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
            Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
 148
         for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

OUTPUT:



# Data send to the IBM cloud device when the object is far

#

8

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## when object is near to the ultrasonic sensor



# Data sent to the IBM Cloud Device when the object is near

