

# Define, Evaluate, and Improve Task-Oriented Cognitive **Capabilities for Instruction Generation Models**

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#### **Problem**

- ➡ Build speaker models that generate language instructions to guide humans in 3D environments
- → Instructions generated by vanilla speaker models fail to communicate well with humans
- → How to generate better instructions by **reasoning pragmatically**?
- → How to evaluate cognitive capabilities of instruction generation (*speaker*) models?

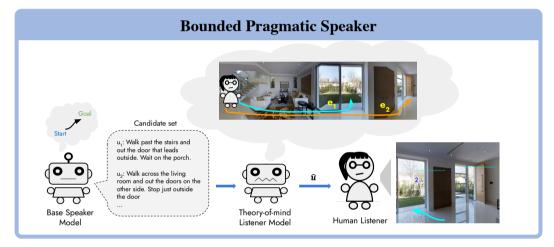


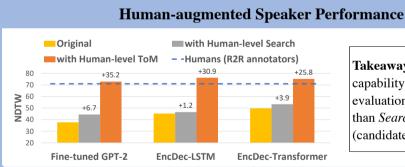
Vanilla Speaker: Exit the bathroom and turn left. Walk past the bed and wait by the two chairs. [Correct destination is next to the chairs in the outdoor area]

Pragmatic Speaker: Walk out of the bathroom and make a left. Walk through the bedroom and continue straight towards the red chair. Stop at the chair before getting to the front of

## **Contributions**

- A new scheme for evaluating taskoriented cognitive capabilities in instruction generation models
- An 11% success rate improvement in guiding real humans in photorealistic environment, by equipping vanilla speakers with theory-of-mind capabilities
- A call to construct better theory-of-mind models for improving the instruction generation models





Takeaway: Pragmatic capability (theory-of-mind evaluation) is more deficient than Search capability (candidate generation).

## **Cognitive Evaluation** Bounded pragmatic speaker (i) Generate candidate (search capability) $u_i \sim S_{base}(\cdot \mid e^*)$ (ii) Evaluate candidate (**pragmatic** capability) $score(u_i) = L_{ToM}(e^* \mid u_i)$ Return $\operatorname{argmax}_{u \in D} \operatorname{score}(u)$ , $D = \{ u_1, ..., u_N \}$ Human-level capability Search capability (b) Human-level - pragmatic capability Pragmatic capability Recommendation: ullet Large $\Delta_{ ext{search}}$ , small $\Delta_{ ext{pragmatic}} \Rightarrow$ improve inference algorithm $\bullet$ Large $\Delta_{\rm pragmatic}$ , small $\Delta_{\rm search}$ $\Rightarrow$ enhance model of listener

## Improving Pragmatic Capability with Ensemble Theory-of-Mind Listener

ToM listener $L_{ToM}$	Base speaker $S_{ m base}$		
	Fine-tuned GPT-2	EncDec-LSTM	EncDec-Transformer
None	<b>37.7</b> (▲ 0.0)	<b>45.3</b> ( <b>a</b> 0.0)	<b>49.4</b> ( <b>A</b> 0.0)
Single VLN-BERT (Majumdar et al., 2020)	38.9 (▲ 1.2)	39.8 (▼ 5.5)	46.2 (▼ 3.2)
Ensemble of 10 EnvDrop-CLIP (Shen et al., 2022)	<b>37.8</b> ( <b>▲</b> 0.1)	<b>53.1</b> <sup>†</sup> (▲ 7.8)	57.3 <sup>†</sup> (▲ 7.9)
Ensemble of 10 VLN © BERT (Hong et al., 2021)	<b>43.4</b> ( <b>▲</b> 5.7)	<b>56.4</b> <sup>‡</sup> (▲ 11.1)	<b>54.2</b> (▲ 4.8)
Humans (skyline)	<b>72.9</b> <sup>‡</sup> ( <b>▲</b> 35.2)	76.2 <sup>‡</sup> (▲ 30.9)	<b>75.2</b> <sup>‡</sup> (▲ 25.8)

## Takeaways:

- Using ensemble followers as theory-ofmind model can improve vanilla speakers significantly to communicate with humans
- Better task-oriented theory-of-mind is needed to bridge the communication gap between AI and humans

## **Experimental Settings**

### ✓ Training data:

➤ Matterport Room-to-Room (reverse task)

### **√**Models:

Fine-tuned GPT-2

- ▶ EncDec-LSTM
- ▶ EncDec-Transformer
- ▶ Pragmatic Speakers

## ✓ Evaluation:

- ▶ Give instructions to real
- humans
  Measure similarity between human-generated and intended paths: normalized Dynamic Time Warping (NDTW)

#### **Key References**

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