

Caffe

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# Chapter 1

## Namespace Index

### 1.1 Namespace List

Here is a list of all documented namespaces with brief descriptions:

<a href="#">boost</a>	.....	13
<a href="#">caffe</a>		
	A layer factory that allows one to register layers. During runtime, registered layers can be called by passing a LayerParameter protobuffer to the CreateLayer function: .....	13
<a href="#">caffe::SolverAction</a>		
	Enumeration of actions that a client of the <a href="#">Solver</a> may request by implementing the <a href="#">Solver</a> 's action request function, which a client may optionally provide in order to request early termination or saving a snapshot without exiting. In the executable caffe, this mechanism is used to allow the snapshot to be saved when stopping execution with a SIGINT (Ctrl-C) .....	29





## Chapter 2

# Hierarchical Index

### 2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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caffe::BatchReindexLayer< Dtype > . . . . .	75
caffe::BiasLayer< Dtype > . . . . .	80
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## Chapter 3

# Class Index

### 3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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Computes $y =  x $ . . . . .	
<a href="#">caffe::AccuracyLayer&lt; Dtype &gt;</a>	36
Computes the classification accuracy for a one-of-many classification task . . . . .	
<a href="#">caffe::AdaDeltaSolver&lt; Dtype &gt;</a>	43
<a href="#">caffe::AdaGradSolver&lt; Dtype &gt;</a>	46
<a href="#">caffe::AdamSolver&lt; Dtype &gt;</a>	48
<a href="#">AdamSolver</a> , an algorithm for first-order gradient-based optimization of stochastic objective functions, based on adaptive estimates of lower-order moments. Described in [1] . . . . .	
<a href="#">caffe::ArgMaxLayer&lt; Dtype &gt;</a>	51
Compute the index of the $K$ max values for each datum across all dimensions ( $C \times H \times W$ ) . . . . .	
<a href="#">caffe::BaseConvolutionLayer&lt; Dtype &gt;</a>	57
Abstract base class that factors out the BLAS code common to <a href="#">ConvolutionLayer</a> and <a href="#">DeconvolutionLayer</a> . . . . .	
<a href="#">caffe::BaseDataLayer&lt; Dtype &gt;</a>	63
Provides base for data layers that feed blobs to the <a href="#">Net</a> . . . . .	
<a href="#">caffe::BasePrefetchingDataLayer&lt; Dtype &gt;</a>	67
<a href="#">caffe::Batch&lt; Dtype &gt;</a>	69
<a href="#">caffe::BatchNormLayer&lt; Dtype &gt;</a>	70
Normalizes the input to have 0-mean and/or unit (1) variance across the batch . . . . .	
<a href="#">caffe::BatchReindexLayer&lt; Dtype &gt;</a>	75
Index into the input blob along its first axis . . . . .	
<a href="#">caffe::BiasLayer&lt; Dtype &gt;</a>	80
Computes a sum of two input Blobs, with the shape of the latter <a href="#">Blob</a> "broadcast" to match the shape of the former. Equivalent to tiling the latter <a href="#">Blob</a> , then computing the elementwise sum . . . . .	
<a href="#">caffe::BilinearFiller&lt; Dtype &gt;</a>	86
Fills a <a href="#">Blob</a> with coefficients for bilinear interpolation . . . . .	
<a href="#">caffe::Blob&lt; Dtype &gt;</a>	88
A wrapper around <a href="#">SyncedMemory</a> holders serving as the basic computational unit through which <a href="#">Layers</a> , <a href="#">Nets</a> , and <a href="#">Solvers</a> interact . . . . .	
<a href="#">caffe::BlockingQueue&lt; T &gt;</a>	94
<a href="#">caffe::BNLLayer&lt; Dtype &gt;</a>	95
Computes $y = x + \log(1 + \exp(-x))$ if $x > 0$ ; $y = \log(1 + \exp(x))$ otherwise . . . . .	
<a href="#">caffe::Caffe</a>	100
<a href="#">caffe::Net&lt; Dtype &gt;::Callback</a>	101

<a href="#">caffe::Solver&lt; Dtype &gt;::Callback</a>	102
<a href="#">caffe::ClipLayer&lt; Dtype &gt;</a>	
Clip: $y = \max(\min, \min(\max, x))$	103
<a href="#">caffe::ConcatLayer&lt; Dtype &gt;</a>	
Takes at least two <a href="#">Blobs</a> and concatenates them along either the num or channel dimension, outputting the result	107
<a href="#">caffe::ConstantFiller&lt; Dtype &gt;</a>	
Fills a <a href="#">Blob</a> with constant values $x = 0$	112
<a href="#">caffe::ContrastiveLossLayer&lt; Dtype &gt;</a>	
Computes the contrastive loss $E = \frac{1}{2N} \sum_{n=1}^N (y) d^2 + (1 - y) \max(\text{margin} - d, 0)^2$ where $d = \ a_n - b_n\ _2$ . This can be used to train siamese networks	114
<a href="#">caffe::ConvolutionLayer&lt; Dtype &gt;</a>	
Convolve the input image with a bank of learned filters, and (optionally) adds biases	119
<a href="#">caffe::CPUTimer</a>	124
<a href="#">caffe::CropLayer&lt; Dtype &gt;</a>	
Takes a <a href="#">Blob</a> and crop it, to the shape specified by the second input <a href="#">Blob</a> , across all dimensions after the specified axis	126
<a href="#">caffe::db::Cursor</a>	130
<a href="#">caffe::DataLayer&lt; Dtype &gt;</a>	131
<a href="#">caffe::DataTransformer&lt; Dtype &gt;</a>	
Applies common transformations to the input data, such as scaling, mirroring, subtracting the image mean..	134
<a href="#">caffe::db::DB</a>	138
<a href="#">caffe::DeconvolutionLayer&lt; Dtype &gt;</a>	
Convolve the input with a bank of learned filters, and (optionally) add biases, treating filters and convolution parameters in the opposite sense as <a href="#">ConvolutionLayer</a>	138
<a href="#">caffe::DropoutLayer&lt; Dtype &gt;</a>	
During training only, sets a random portion of $x$ to 0, adjusting the rest of the vector magnitude accordingly	141
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<a href="#">caffe::EltwiseLayer&lt; Dtype &gt;</a>	
Compute elementwise operations, such as product and sum, along multiple input Blobs	151
<a href="#">caffe::ELULayer&lt; Dtype &gt;</a>	
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<a href="#">caffe::EmbedLayer&lt; Dtype &gt;</a>	
A layer for learning "embeddings" of one-hot vector input. Equivalent to an <a href="#">InnerProductLayer</a> with one-hot vectors as input, but for efficiency the input is the "hot" index of each column itself	159
<a href="#">caffe::EuclideanLossLayer&lt; Dtype &gt;</a>	
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An interface for the units of computation which can be composed into a <a href="#">Net</a> . . . . .	233
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Parameterized Rectified Linear Unit non-linearity $y_i = \max(0, x_i) + a_i \min(0, x_i)$ . The differences from <a href="#">ReLULayer</a> are 1) negative slopes are learnable though backprop and 2) negative slopes can vary across channels. The number of axes of input blob should be greater than or equal to 2. The 1st axis (0-based) is seen as channels . . . . .	308
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<a href="#">caffe::SplitLayer&lt; Dtype &gt;</a>	
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<a href="#">caffe::SPPLayer&lt; Dtype &gt;</a>	
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<a href="#">caffe::TanHLayer&lt; Dtype &gt;</a>	
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<a href="#">caffe::ThresholdLayer&lt; Dtype &gt;</a>	
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## Chapter 4

# Namespace Documentation

### 4.1 boost Namespace Reference

#### 4.1.1 Detailed Description

Forward declare `boost::thread` instead of including `boost/thread.hpp` to avoid a boost/NVCC issues (#1009, #1010) on OSX.

### 4.2 caffe Namespace Reference

A layer factory that allows one to register layers. During runtime, registered layers can be called by passing a `LayerParameter` protobuffer to the `CreateLayer` function:

#### Namespaces

- [SolverAction](#)

*Enumeration of actions that a client of the [Solver](#) may request by implementing the [Solver](#)'s action request function, which a client may optionally provide in order to request early termination or saving a snapshot without exiting. In the executable `caffe`, this mechanism is used to allow the snapshot to be saved when stopping execution with a `SIGINT` (Ctrl-C).*

#### Classes

- class [AbsValLayer](#)

*Computes  $y = |x|$ .*

- class [AccuracyLayer](#)

*Computes the classification accuracy for a one-of-many classification task.*

- class [AdaDeltaSolver](#)

- class [AdaGradSolver](#)

- class [AdamSolver](#)

*[AdamSolver](#), an algorithm for first-order gradient-based optimization of stochastic objective functions, based on adaptive estimates of lower-order moments. Described in [1].*

- class [ArgMaxLayer](#)

- Compute the index of the  $K$  max values for each datum across all dimensions ( $C \times H \times W$ ).
- class [BaseConvolutionLayer](#)
  - Abstract base class that factors out the BLAS code common to [ConvolutionLayer](#) and [DeconvolutionLayer](#).
- class [BaseDataLayer](#)
  - Provides base for data layers that feed blobs to the [Net](#).
- class [BasePrefetchingDataLayer](#)
- class [Batch](#)
- class [BatchNormLayer](#)
  - Normalizes the input to have 0-mean and/or unit (1) variance across the batch.
- class [BatchReindexLayer](#)
  - Index into the input blob along its first axis.
- class [BiasLayer](#)
  - Computes a sum of two input Blobs, with the shape of the latter [Blob](#) "broadcast" to match the shape of the former. Equivalent to tiling the latter [Blob](#), then computing the elementwise sum.
- class [BilinearFiller](#)
  - Fills a [Blob](#) with coefficients for bilinear interpolation.
- class [Blob](#)
  - A wrapper around [SyncedMemory](#) holders serving as the basic computational unit through which [Layers](#), [Nets](#), and [Solvers](#) interact.
- class [BlockingQueue](#)
- class [BNLLayer](#)
  - Computes  $y = x + \log(1 + \exp(-x))$  if  $x > 0$ ;  $y = \log(1 + \exp(x))$  otherwise.
- class [Caffe](#)
- class [ClipLayer](#)
  - Clip:  $y = \max(\min, \min(\max, x))$ .
- class [ConcatLayer](#)
  - Takes at least two [Blobs](#) and concatenates them along either the num or channel dimension, outputting the result.
- class [ConstantFiller](#)
  - Fills a [Blob](#) with constant values  $x = 0$ .
- class [ContrastiveLossLayer](#)
  - Computes the contrastive loss  $E = \frac{1}{2N} \sum_{n=1}^N (y) d^2 + (1 - y) \max(\text{margin} - d, 0)^2$  where  $d = \|a_n - b_n\|_2$ . This can be used to train siamese networks.
- class [ConvolutionLayer](#)
  - Convolve the input image with a bank of learned filters, and (optionally) adds biases.
- class [CPUTimer](#)
- class [CropLayer](#)
  - Takes a [Blob](#) and crop it, to the shape specified by the second input [Blob](#), across all dimensions after the specified axis.
- class [DataLayer](#)
- class [DataTransformer](#)
  - Applies common transformations to the input data, such as scaling, mirroring, subtracting the image mean...
- class [DeconvolutionLayer](#)
  - Convolve the input with a bank of learned filters, and (optionally) add biases, treating filters and convolution parameters in the opposite sense as [ConvolutionLayer](#).
- class [DropoutLayer](#)
  - During training only, sets a random portion of  $x$  to 0, adjusting the rest of the vector magnitude accordingly.
- class [DummyDataLayer](#)
  - Provides data to the [Net](#) generated by a [Filler](#).
- class [EltwiseLayer](#)
  - Compute elementwise operations, such as product and sum, along multiple input Blobs.
- class [ELULayer](#)

Exponential Linear Unit non-linearity  $y = \begin{cases} x & \text{if } x > 0 \\ \alpha(\exp(x) - 1) & \text{if } x \leq 0 \end{cases}$ .

- class [EmbedLayer](#)

A layer for learning "embeddings" of one-hot vector input. Equivalent to an [InnerProductLayer](#) with one-hot vectors as input, but for efficiency the input is the "hot" index of each column itself.

- class [EuclideanLossLayer](#)

Computes the Euclidean (L2) loss  $E = \frac{1}{2N} \sum_{n=1}^N \|\hat{y}_n - y_n\|_2^2$  for real-valued regression tasks.

- class [ExpLayer](#)

Computes  $y = \gamma^{\alpha x + \beta}$ , as specified by the scale  $\alpha$ , shift  $\beta$ , and base  $\gamma$ .

- class [Filler](#)

Fills a [Blob](#) with constant or randomly-generated data.

- class [FilterLayer](#)

Takes two+ Blobs, interprets last [Blob](#) as a selector and filter remaining Blobs accordingly with selector data (0 means that the corresponding item has to be filtered, non-zero means that corresponding item needs to stay).

- class [FlattenLayer](#)

Reshapes the input [Blob](#) into flat vectors.

- class [GaussianFiller](#)

Fills a [Blob](#) with Gaussian-distributed values  $x = a$ .

- class [HDF5DataLayer](#)

Provides data to the [Net](#) from HDF5 files.

- class [HDF5OutputLayer](#)

Write blobs to disk as HDF5 files.

- class [HingeLossLayer](#)

Computes the hinge loss for a one-of-many classification task.

- class [Im2colLayer](#)

A helper for image operations that rearranges image regions into column vectors. Used by [ConvolutionLayer](#) to perform convolution by matrix multiplication.

- class [ImageDataLayer](#)

Provides data to the [Net](#) from image files.

- class [InfogainLossLayer](#)

A generalization of [SoftmaxWithLossLayer](#) that takes an "information gain" (infogain) matrix specifying the "value" of all label pairs.

- class [InnerProductLayer](#)

Also known as a "fully-connected" layer, computes an inner product with a set of learned weights, and (optionally) adds biases.

- class [InputLayer](#)

Provides data to the [Net](#) by assigning tops directly.

- class [InternalThread](#)

- class [Layer](#)

An interface for the units of computation which can be composed into a [Net](#).

- class [LayerRegisterer](#)

- class [LayerRegistry](#)

- class [LogLayer](#)

Computes  $y = \log_{\gamma}(\alpha x + \beta)$ , as specified by the scale  $\alpha$ , shift  $\beta$ , and base  $\gamma$ .

- class [LossLayer](#)

An interface for [Layers](#) that take two [Blobs](#) as input – usually (1) predictions and (2) ground-truth labels – and output a singleton [Blob](#) representing the loss.

- class [LRNLayer](#)

Normalize the input in a local region across or within feature maps.

- class [LSTMLayer](#)

Processes sequential inputs using a "Long Short-Term Memory" (LSTM) [1] style recurrent neural network (RNN). Implemented by unrolling the LSTM computation through time.

- class [LSTMUnitLayer](#)  
A helper for [LSTMLayer](#): computes a single timestep of the non-linearity of the LSTM, producing the updated cell and hidden states.
- class [MemoryDataLayer](#)  
Provides data to the [Net](#) from memory.
- class [MSRAFiller](#)  
Fills a [Blob](#) with values  $x \sim N(0, \sigma^2)$  where  $\sigma^2$  is set inversely proportional to number of incoming nodes, outgoing nodes, or their average.
- class [MultinomialLogisticLossLayer](#)  
Computes the multinomial logistic loss for a one-of-many classification task, directly taking a predicted probability distribution as input.
- class [MVNLayer](#)  
Normalizes the input to have 0-mean and/or unit (1) variance.
- class [NesterovSolver](#)
- class [Net](#)  
Connects [Layers](#) together into a directed acyclic graph (DAG) specified by a [NetParameter](#).
- class [NeuronLayer](#)  
An interface for layers that take one blob as input ( $x$ ) and produce one equally-sized blob as output ( $y$ ), where each element of the output depends only on the corresponding input element.
- class [ParameterLayer](#)
- class [PoolingLayer](#)  
Pools the input image by taking the max, average, etc. within regions.
- class [PositiveUnitballFiller](#)  
Fills a [Blob](#) with values  $x \in [0, 1]$  such that  $\forall i \sum_j x_{ij} = 1$ .
- class [PowerLayer](#)  
Computes  $y = (\alpha x + \beta)^\gamma$ , as specified by the scale  $\alpha$ , shift  $\beta$ , and power  $\gamma$ .
- class [PReLULayer](#)  
Parameterized Rectified Linear Unit non-linearity  $y_i = \max(0, x_i) + a_i \min(0, x_i)$ . The differences from [ReLULayer](#) are 1) negative slopes are learnable though backprop and 2) negative slopes can vary across channels. The number of axes of input blob should be greater than or equal to 2. The 1st axis (0-based) is seen as channels.
- class [PythonLayer](#)
- class [RecurrentLayer](#)  
An abstract class for implementing recurrent behavior inside of an unrolled network. This [Layer](#) type cannot be instantiated – instead, you should use one of its implementations which defines the recurrent architecture, such as [RNNLayer](#) or [LSTMLayer](#).
- class [ReductionLayer](#)  
Compute "reductions" – operations that return a scalar output [Blob](#) for an input [Blob](#) of arbitrary size, such as the sum, absolute sum, and sum of squares.
- class [ReLULayer](#)  
Rectified Linear Unit non-linearity  $y = \max(0, x)$ . The simple max is fast to compute, and the function does not saturate.
- class [ReshapeLayer](#)
- class [RMSPropSolver](#)
- class [RNNLayer](#)  
Processes time-varying inputs using a simple recurrent neural network (RNN). Implemented as a network unrolling the RNN computation in time.
- class [ScaleLayer](#)  
Computes the elementwise product of two input Blobs, with the shape of the latter [Blob](#) "broadcast" to match the shape of the former. Equivalent to tiling the latter [Blob](#), then computing the elementwise product. Note: for efficiency and convenience, this layer can additionally perform a "broadcast" sum too when `bias_term: true` is set.
- class [SGDSolver](#)  
Optimizes the parameters of a [Net](#) using stochastic gradient descent (SGD) with momentum.
- class [SigmoidCrossEntropyLossLayer](#)

- Computes the cross-entropy (logistic) loss  $E = \frac{-1}{n} \sum_{n=1}^N [p_n \log \hat{p}_n + (1 - p_n) \log(1 - \hat{p}_n)]$ , often used for predicting targets interpreted as probabilities.
- class [SigmoidLayer](#)  
Sigmoid function non-linearity  $y = (1 + \exp(-x))^{-1}$ , a classic choice in neural networks.
  - class [SignalHandler](#)
  - class [SilenceLayer](#)  
Ignores bottom blobs while producing no top blobs. (This is useful to suppress outputs during testing.)
  - class [SliceLayer](#)  
Takes a [Blob](#) and slices it along either the num or channel dimension, outputting multiple sliced [Blob](#) results.
  - class [SoftmaxLayer](#)  
Computes the softmax function.
  - class [SoftmaxWithLossLayer](#)  
Computes the multinomial logistic loss for a one-of-many classification task, passing real-valued predictions through a softmax to get a probability distribution over classes.
  - class [Solver](#)  
An interface for classes that perform optimization on [Nets](#).
  - class [SolverRegisterer](#)
  - class [SolverRegistry](#)
  - class [SplitLayer](#)  
Creates a "split" path in the network by copying the bottom [Blob](#) into multiple top [Blobs](#) to be used by multiple consuming layers.
  - class [SPPLayer](#)  
Does spatial pyramid pooling on the input image by taking the max, average, etc. within regions so that the result vector of different sized images are of the same size.
  - class [SwishLayer](#)  
Swish non-linearity  $y = x\sigma(\beta x)$ . A novel activation function that tends to work better than ReLU [1].
  - class [SyncedMemory](#)  
Manages memory allocation and synchronization between the host (CPU) and device (GPU).
  - class [TanHLayer](#)  
TanH hyperbolic tangent non-linearity  $y = \frac{\exp(2x)-1}{\exp(2x)+1}$ , popular in auto-encoders.
  - class [ThresholdLayer](#)  
Tests whether the input exceeds a threshold: outputs 1 for inputs above threshold; 0 otherwise.
  - class [TileLayer](#)  
Copy a [Blob](#) along specified dimensions.
  - class [Timer](#)
  - class [UniformFiller](#)  
Fills a [Blob](#) with uniformly distributed values  $x \sim U(a, b)$ .
  - class [WindowDataLayer](#)  
Provides data to the [Net](#) from windows of images files, specified by a window data file. This layer is DEPRECATED and only kept for archival purposes for use by the original R-CNN.
  - class [XavierFiller](#)  
Fills a [Blob](#) with values  $x \sim U(-a, +a)$  where  $a$  is set inversely proportional to number of incoming nodes, outgoing nodes, or their average.

## Typedefs

- typedef boost::function< SolverAction::Enum()> [ActionCallback](#)  
Type of a function that returns a [Solver](#) Action enumeration.
- typedef boost::mt19937 **rng\_t**

## Functions

- void **GlobalInit** (int \*pargc, char \*\*\*pargv)
- template<typename Dtype >  
**Filler**< Dtype > \* **GetFiller** (const FillerParameter &param)  
*Get a specific filler from the specification given in FillerParameter.*
- void **CaffeMallocHost** (void \*\*ptr, size\_t size, bool \*use\_cuda)
- void **CaffeFreeHost** (void \*ptr, bool use\_cuda)
- const char \* **cublasGetErrorString** (cublasStatus\_t error)
- const char \* **curandGetErrorString** (curandStatus\_t error)
- int **CAFFE\_GET\_BLOCKS** (const int N)
- std::string **format\_int** (int n, int numberOfLeadingZeros=0)
- template<typename Dtype >  
void **im2col\_nd\_cpu** (const Dtype \*data\_im, const int num\_spatial\_axes, const int \*im\_shape, const int \*col\_shape, const int \*kernel\_shape, const int \*pad, const int \*stride, const int \*dilation, Dtype \*data\_col)
- template<typename Dtype >  
void **im2col\_cpu** (const Dtype \*data\_im, const int channels, const int height, const int width, const int kernel\_h, const int kernel\_w, const int pad\_h, const int pad\_w, const int stride\_h, const int stride\_w, const int dilation\_h, const int dilation\_w, Dtype \*data\_col)
- template<typename Dtype >  
void **col2im\_nd\_cpu** (const Dtype \*data\_col, const int num\_spatial\_axes, const int \*im\_shape, const int \*col\_shape, const int \*kernel\_shape, const int \*pad, const int \*stride, const int \*dilation, Dtype \*data\_im)
- template<typename Dtype >  
void **col2im\_cpu** (const Dtype \*data\_col, const int channels, const int height, const int width, const int kernel\_h, const int kernel\_w, const int pad\_h, const int pad\_w, const int stride\_h, const int stride\_w, const int dilation\_h, const int dilation\_w, Dtype \*data\_im)
- template<typename Dtype >  
void **im2col\_nd\_gpu** (const Dtype \*data\_im, const int num\_spatial\_axes, const int col\_size, const int \*im\_shape, const int \*col\_shape, const int \*kernel\_shape, const int \*pad, const int \*stride, const int \*dilation, Dtype \*data\_col)
- template<typename Dtype >  
void **im2col\_gpu** (const Dtype \*data\_im, const int channels, const int height, const int width, const int kernel\_h, const int kernel\_w, const int pad\_h, const int pad\_w, const int stride\_h, const int stride\_w, const int dilation\_h, const int dilation\_w, Dtype \*data\_col)
- template<typename Dtype >  
void **col2im\_nd\_gpu** (const Dtype \*data\_col, const int num\_spatial\_axes, const int im\_size, const int \*im\_shape, const int \*col\_shape, const int \*kernel\_shape, const int \*pad, const int \*stride, const int \*dilation, Dtype \*data\_im)
- template<typename Dtype >  
void **col2im\_gpu** (const Dtype \*data\_col, const int channels, const int height, const int width, const int kernel\_h, const int kernel\_w, const int pad\_h, const int pad\_w, const int stride\_h, const int stride\_w, const int dilation\_h, const int dilation\_w, Dtype \*data\_im)
- void **InsertSplits** (const NetParameter &param, NetParameter \*param\_split)
- void **ConfigureSplitLayer** (const string &layer\_name, const string &blob\_name, const int blob\_idx, const int split\_count, const float loss\_weight, LayerParameter \*split\_layer\_param)
- string **SplitLayerName** (const string &layer\_name, const string &blob\_name, const int blob\_idx)
- string **SplitBlobName** (const string &layer\_name, const string &blob\_name, const int blob\_idx, const int split\_idx)
- void **MakeTempDir** (string \*temp\_dirname)
- void **MakeTempFilename** (string \*temp\_filename)
- bool **ReadProtoFromTextFile** (const char \*filename, Message \*proto)
- bool **ReadProtoFromTextFile** (const string &filename, Message \*proto)
- void **ReadProtoFromTextFileOrDie** (const char \*filename, Message \*proto)
- void **ReadProtoFromTextFileOrDie** (const string &filename, Message \*proto)
- void **WriteProtoToTextFile** (const Message &proto, const char \*filename)
- void **WriteProtoToTextFile** (const Message &proto, const string &filename)



- bool **ReadProtoFromBinaryFile** (const char \*filename, Message \*proto)
- bool **ReadProtoFromBinaryFile** (const string &filename, Message \*proto)
- void **ReadProtoFromBinaryFileOrDie** (const char \*filename, Message \*proto)
- void **ReadProtoFromBinaryFileOrDie** (const string &filename, Message \*proto)
- void **WriteProtoToBinaryFile** (const Message &proto, const char \*filename)
- void **WriteProtoToBinaryFile** (const Message &proto, const string &filename)
- bool **ReadFileToDatum** (const string &filename, const int label, Datum \*datum)
- bool **ReadFileToDatum** (const string &filename, Datum \*datum)
- bool **ReadImageToDatum** (const string &filename, const int label, const int height, const int width, const bool is\_color, const std::string &encoding, Datum \*datum)
- bool **ReadImageToDatum** (const string &filename, const int label, const int height, const int width, const bool is\_color, Datum \*datum)
- bool **ReadImageToDatum** (const string &filename, const int label, const int height, const int width, Datum \*datum)
- bool **ReadImageToDatum** (const string &filename, const int label, const bool is\_color, Datum \*datum)
- bool **ReadImageToDatum** (const string &filename, const int label, Datum \*datum)
- bool **ReadImageToDatum** (const string &filename, const int label, const std::string &encoding, Datum \*datum)
- bool **DecodeDatumNative** (Datum \*datum)
- bool **DecodeDatum** (Datum \*datum, bool is\_color)
- template<typename Dtype >  
void **caffe\_cpu\_gemm** (const CBLAS\_TRANSPOSE TransA, const CBLAS\_TRANSPOSE TransB, const int M, const int N, const int K, const Dtype alpha, const Dtype \*A, const Dtype \*B, const Dtype beta, Dtype \*C)
- template<typename Dtype >  
void **caffe\_cpu\_gemv** (const CBLAS\_TRANSPOSE TransA, const int M, const int N, const Dtype alpha, const Dtype \*A, const Dtype \*x, const Dtype beta, Dtype \*y)
- template<typename Dtype >  
void **caffe\_axpy** (const int N, const Dtype alpha, const Dtype \*X, Dtype \*Y)
- template<typename Dtype >  
void **caffe\_cpu\_axpby** (const int N, const Dtype alpha, const Dtype \*X, const Dtype beta, Dtype \*Y)
- template<typename Dtype >  
void **caffe\_copy** (const int N, const Dtype \*X, Dtype \*Y)
- template<typename Dtype >  
void **caffe\_set** (const int N, const Dtype alpha, Dtype \*X)
- void **caffe\_memset** (const size\_t N, const int alpha, void \*X)
- template<typename Dtype >  
void **caffe\_add\_scalar** (const int N, const Dtype alpha, Dtype \*X)
- template<typename Dtype >  
void **caffe\_scal** (const int N, const Dtype alpha, Dtype \*X)
- template<typename Dtype >  
void **caffe\_sqr** (const int N, const Dtype \*a, Dtype \*y)
- template<typename Dtype >  
void **caffe\_sqrt** (const int N, const Dtype \*a, Dtype \*y)
- template<typename Dtype >  
void **caffe\_add** (const int N, const Dtype \*a, const Dtype \*b, Dtype \*y)
- template<typename Dtype >  
void **caffe\_sub** (const int N, const Dtype \*a, const Dtype \*b, Dtype \*y)
- template<typename Dtype >  
void **caffe\_mul** (const int N, const Dtype \*a, const Dtype \*b, Dtype \*y)
- template<typename Dtype >  
void **caffe\_div** (const int N, const Dtype \*a, const Dtype \*b, Dtype \*y)
- template<typename Dtype >  
void **caffe\_powx** (const int n, const Dtype \*a, const Dtype b, Dtype \*y)
- unsigned int **caffe\_rng\_rand** ()
- template<typename Dtype >  
Dtype **caffe\_nextafter** (const Dtype b)

- `template<typename Dtype >`  
`void caffe_rng_uniform (const int n, const Dtype a, const Dtype b, Dtype *r)`
- `template<typename Dtype >`  
`void caffe_rng_gaussian (const int n, const Dtype mu, const Dtype sigma, Dtype *r)`
- `template<typename Dtype >`  
`void caffe_rng_bernoulli (const int n, const Dtype p, int *r)`
- `template<typename Dtype >`  
`void caffe_rng_bernoulli (const int n, const Dtype p, unsigned int *r)`
- `template<typename Dtype >`  
`void caffe_exp (const int n, const Dtype *a, Dtype *y)`
- `template<typename Dtype >`  
`void caffe_log (const int n, const Dtype *a, Dtype *y)`
- `template<typename Dtype >`  
`void caffe_abs (const int n, const Dtype *a, Dtype *y)`
- `template<typename Dtype >`  
`Dtype caffe_cpu_dot (const int n, const Dtype *x, const Dtype *y)`
- `template<typename Dtype >`  
`Dtype caffe_cpu_strided_dot (const int n, const Dtype *x, const int incx, const Dtype *y, const int incy)`
- `template<typename Dtype >`  
`Dtype caffe_cpu_asum (const int n, const Dtype *x)`
- `template<typename Dtype >`  
`int8_t caffe_sign (Dtype val)`
- `DEFINE_CAFFE_CPU_UNARY_FUNC (sgnbit, y[i]=static_cast< bool >((std::signbit)(x[i])))` `template<`  
`typename Dtype > void caffe_cpu_scale(const int n`
- `template<typename Dtype >`  
`void caffe_gpu_gemm (const CBLAS_TRANSPOSE TransA, const CBLAS_TRANSPOSE TransB, const int M, const int N, const int K, const Dtype alpha, const Dtype *A, const Dtype *B, const Dtype beta, Dtype *C)`
- `template<typename Dtype >`  
`void caffe_gpu_gemv (const CBLAS_TRANSPOSE TransA, const int M, const int N, const Dtype alpha, const Dtype *A, const Dtype *x, const Dtype beta, Dtype *y)`
- `template<typename Dtype >`  
`void caffe_gpu_axpy (const int N, const Dtype alpha, const Dtype *X, Dtype *Y)`
- `template<typename Dtype >`  
`void caffe_gpu_axpby (const int N, const Dtype alpha, const Dtype *X, const Dtype beta, Dtype *Y)`
- `void caffe_gpu_memcpy (const size_t N, const void *X, void *Y)`
- `template<typename Dtype >`  
`void caffe_gpu_set (const int N, const Dtype alpha, Dtype *X)`
- `void caffe_gpu_memset (const size_t N, const int alpha, void *X)`
- `template<typename Dtype >`  
`void caffe_gpu_add_scalar (const int N, const Dtype alpha, Dtype *X)`
- `template<typename Dtype >`  
`void caffe_gpu_scal (const int N, const Dtype alpha, Dtype *X)`
- `template<typename Dtype >`  
`void caffe_gpu_scal (const int N, const Dtype alpha, Dtype *X, cudaStream_t str)`
- `template<typename Dtype >`  
`void caffe_gpu_add (const int N, const Dtype *a, const Dtype *b, Dtype *y)`
- `template<typename Dtype >`  
`void caffe_gpu_sub (const int N, const Dtype *a, const Dtype *b, Dtype *y)`
- `template<typename Dtype >`  
`void caffe_gpu_mul (const int N, const Dtype *a, const Dtype *b, Dtype *y)`
- `template<typename Dtype >`  
`void caffe_gpu_div (const int N, const Dtype *a, const Dtype *b, Dtype *y)`
- `template<typename Dtype >`  
`void caffe_gpu_abs (const int n, const Dtype *a, Dtype *y)`
- `template<typename Dtype >`  
`void caffe_gpu_exp (const int n, const Dtype *a, Dtype *y)`

- `template<typename Dtype >`  
void **caffe\_gpu\_log** (const int n, const Dtype \*a, Dtype \*y)
- `template<typename Dtype >`  
void **caffe\_gpu\_powx** (const int n, const Dtype \*a, const Dtype b, Dtype \*y)
- `template<typename Dtype >`  
void **caffe\_gpu\_sqrt** (const int n, const Dtype \*a, Dtype \*y)
- void **caffe\_gpu\_rng\_uniform** (const int n, unsigned int \*r)
- `template<typename Dtype >`  
void **caffe\_gpu\_rng\_uniform** (const int n, const Dtype a, const Dtype b, Dtype \*r)
- `template<typename Dtype >`  
void **caffe\_gpu\_rng\_gaussian** (const int n, const Dtype mu, const Dtype sigma, Dtype \*r)
- `template<typename Dtype >`  
void **caffe\_gpu\_rng\_bernoulli** (const int n, const Dtype p, int \*r)
- `template<typename Dtype >`  
void **caffe\_gpu\_dot** (const int n, const Dtype \*x, const Dtype \*y, Dtype \*out)
- `template<typename Dtype >`  
void **caffe\_gpu\_asum** (const int n, const Dtype \*x, Dtype \*y)
- `template<typename Dtype >`  
void **caffe\_gpu\_sign** (const int n, const Dtype \*x, Dtype \*y)
- `template<typename Dtype >`  
void **caffe\_gpu\_sgnbit** (const int n, const Dtype \*x, Dtype \*y)
- `template<typename Dtype >`  
void **caffe\_gpu\_fabs** (const int n, const Dtype \*x, Dtype \*y)
- `template<typename Dtype >`  
void **caffe\_gpu\_scale** (const int n, const Dtype alpha, const Dtype \*x, Dtype \*y)
- `rng_t * caffe_rng ()`
- `template<class RandomAccessIterator, class RandomGenerator >`  
void **shuffle** (RandomAccessIterator begin, RandomAccessIterator end, RandomGenerator \*gen)
- `template<class RandomAccessIterator >`  
void **shuffle** (RandomAccessIterator begin, RandomAccessIterator end)
- bool **NetNeedsUpgrade** (const NetParameter &net\_param)
- bool **UpgradeNetAsNeeded** (const string &param\_file, NetParameter \*param)
- void **ReadNetParamsFromTextFileOrDie** (const string &param\_file, NetParameter \*param)
- void **ReadNetParamsFromBinaryFileOrDie** (const string &param\_file, NetParameter \*param)
- bool **NetNeedsV0ToV1Upgrade** (const NetParameter &net\_param)
- bool **UpgradeV0Net** (const NetParameter &v0\_net\_param, NetParameter \*net\_param)
- void **UpgradeV0PaddingLayers** (const NetParameter &param, NetParameter \*param\_upgraded\_pad)
- bool **UpgradeV0LayerParameter** (const V1LayerParameter &v0\_layer\_connection, V1LayerParameter \*layer\_param)
- V1LayerParameter\_LayerType **UpgradeV0LayerType** (const string &type)
- bool **NetNeedsDataUpgrade** (const NetParameter &net\_param)
- void **UpgradeNetDataTransformation** (NetParameter \*net\_param)
- bool **NetNeedsV1ToV2Upgrade** (const NetParameter &net\_param)
- bool **UpgradeV1Net** (const NetParameter &v1\_net\_param, NetParameter \*net\_param)
- bool **UpgradeV1LayerParameter** (const V1LayerParameter &v1\_layer\_param, LayerParameter \*layer\_param)
- const char \* **UpgradeV1LayerType** (const V1LayerParameter\_LayerType type)
- bool **NetNeedsInputUpgrade** (const NetParameter &net\_param)
- void **UpgradeNetInput** (NetParameter \*net\_param)
- bool **NetNeedsBatchNormUpgrade** (const NetParameter &net\_param)
- void **UpgradeNetBatchNorm** (NetParameter \*net\_param)
- bool **SolverNeedsTypeUpgrade** (const SolverParameter &solver\_param)
- bool **UpgradeSolverType** (SolverParameter \*solver\_param)
- bool **UpgradeSolverAsNeeded** (const string &param\_file, SolverParameter \*param)
- void **ReadSolverParamsFromTextFileOrDie** (const string &param\_file, SolverParameter \*param)
- **INSTANTIATE\_CLASS** (Blob)

- `int64_t cluster_seedgen` (void)
- **INstantiate\_Class** ([DataTransformer](#))
- **INstantiate\_Class** ([Layer](#))
- `template<typename Dtype >`  
`shared_ptr< Layer< Dtype > >` **GetConvolutionLayer** (const LayerParameter &param)
- **REGISTER\_LAYER\_CREATOR** (Convolution, GetConvolutionLayer)
- `template<typename Dtype >`  
`shared_ptr< Layer< Dtype > >` **GetDeconvolutionLayer** (const LayerParameter &param)
- **REGISTER\_LAYER\_CREATOR** (Deconvolution, GetDeconvolutionLayer)
- `template<typename Dtype >`  
`shared_ptr< Layer< Dtype > >` **GetPoolingLayer** (const LayerParameter &param)
- **REGISTER\_LAYER\_CREATOR** (Pooling, GetPoolingLayer)
- `template<typename Dtype >`  
`shared_ptr< Layer< Dtype > >` **GetLRNLayer** (const LayerParameter &param)
- **REGISTER\_LAYER\_CREATOR** (LRN, GetLRNLayer)
- `template<typename Dtype >`  
`shared_ptr< Layer< Dtype > >` **GetReLULayer** (const LayerParameter &param)
- **REGISTER\_LAYER\_CREATOR** (ReLU, GetReLULayer)
- `template<typename Dtype >`  
`shared_ptr< Layer< Dtype > >` **GetSigmoidLayer** (const LayerParameter &param)
- **REGISTER\_LAYER\_CREATOR** (Sigmoid, GetSigmoidLayer)
- `template<typename Dtype >`  
`shared_ptr< Layer< Dtype > >` **GetSoftmaxLayer** (const LayerParameter &param)
- **REGISTER\_LAYER\_CREATOR** (Softmax, GetSoftmaxLayer)
- `template<typename Dtype >`  
`shared_ptr< Layer< Dtype > >` **GetTanHLayer** (const LayerParameter &param)
- **REGISTER\_LAYER\_CREATOR** (TanH, GetTanHLayer)
- **INstantiate\_Class** ([AbsValLayer](#))
- **REGISTER\_LAYER\_CLASS** (AbsVal)
- **INstantiate\_Class** ([AccuracyLayer](#))
- **REGISTER\_LAYER\_CLASS** (Accuracy)
- **INstantiate\_Class** ([ArgMaxLayer](#))
- **REGISTER\_LAYER\_CLASS** (ArgMax)
- **INstantiate\_Class** ([BaseConvolutionLayer](#))
- **INstantiate\_Class** ([BaseDataLayer](#))
- **INstantiate\_Class** ([BasePrefetchingDataLayer](#))
- **INstantiate\_Class** ([BatchNormLayer](#))
- **REGISTER\_LAYER\_CLASS** (BatchNorm)
- **INstantiate\_Class** ([BatchReindexLayer](#))
- **REGISTER\_LAYER\_CLASS** (BatchReindex)
- **INstantiate\_Class** ([BiasLayer](#))
- **REGISTER\_LAYER\_CLASS** (Bias)
- **INstantiate\_Class** ([BNLLayer](#))
- **REGISTER\_LAYER\_CLASS** (BNLL)
- **INstantiate\_Class** ([ClipLayer](#))
- **REGISTER\_LAYER\_CLASS** (Clip)
- **INstantiate\_Class** ([ConcatLayer](#))
- **REGISTER\_LAYER\_CLASS** (Concat)
- **INstantiate\_Class** ([ContrastiveLossLayer](#))
- **REGISTER\_LAYER\_CLASS** (ContrastiveLoss)
- **INstantiate\_Class** ([ConvolutionLayer](#))
- **INstantiate\_Class** ([CropLayer](#))
- **REGISTER\_LAYER\_CLASS** (Crop)
- **INstantiate\_Class** ([DataLayer](#))
- **REGISTER\_LAYER\_CLASS** (Data)

- `INstantiate_Class` ([DeconvolutionLayer](#))
- `Instantiate_Class` ([DropoutLayer](#))
- `Register_Layer_Class` (Dropout)
- `Instantiate_Class` ([DummyDataLayer](#))
- `Register_Layer_Class` (DummyData)
- `Instantiate_Class` ([EltwiseLayer](#))
- `Register_Layer_Class` (Eltwise)
- `Instantiate_Class` ([ELULayer](#))
- `Register_Layer_Class` (ELU)
- `Instantiate_Class` ([EmbedLayer](#))
- `Register_Layer_Class` (Embed)
- `Instantiate_Class` ([EuclideanLossLayer](#))
- `Register_Layer_Class` (EuclideanLoss)
- `Instantiate_Class` ([ExpLayer](#))
- `Register_Layer_Class` (Exp)
- `Instantiate_Class` ([FilterLayer](#))
- `Register_Layer_Class` (Filter)
- `Instantiate_Class` ([FlattenLayer](#))
- `Register_Layer_Class` (Flatten)
- `Instantiate_Class` ([HingeLossLayer](#))
- `Register_Layer_Class` (HingeLoss)
- `Instantiate_Class` ([Im2colLayer](#))
- `Register_Layer_Class` (Im2col)
- `Instantiate_Class` ([InfogainLossLayer](#))
- `Register_Layer_Class` (InfogainLoss)
- `Instantiate_Class` ([InnerProductLayer](#))
- `Register_Layer_Class` (InnerProduct)
- `Instantiate_Class` ([InputLayer](#))
- `Register_Layer_Class` (Input)
- `Instantiate_Class` ([LogLayer](#))
- `Register_Layer_Class` (Log)
- `Instantiate_Class` ([LossLayer](#))
- `Instantiate_Class` ([LRNLayer](#))
- `Instantiate_Class` ([LSTMLayer](#))
- `Register_Layer_Class` (LSTM)
- `template<typename Dtype >`  
`Dtype sigmoid (Dtype x)`
- `template<typename Dtype >`  
`Dtype tanh (Dtype x)`
- `Instantiate_Class` ([LSTMUnitLayer](#))
- `Register_Layer_Class` (LSTMUnit)
- `Instantiate_Class` ([MemoryDataLayer](#))
- `Register_Layer_Class` (MemoryData)
- `Instantiate_Class` ([MultinomialLogisticLossLayer](#))
- `Register_Layer_Class` (MultinomialLogisticLoss)
- `Instantiate_Class` ([MVNLayer](#))
- `Register_Layer_Class` (MVN)
- `Instantiate_Class` ([NeuronLayer](#))
- `Instantiate_Class` ([ParameterLayer](#))
- `Register_Layer_Class` (Parameter)
- `Instantiate_Class` ([PoolingLayer](#))
- `Instantiate_Class` ([PowerLayer](#))
- `Register_Layer_Class` (Power)
- `Instantiate_Class` ([PReLULayer](#))
- `Register_Layer_Class` (PReLU)

- **INstantiate\_Class** ([RecurrentLayer](#))
- **Instantiate\_Class** ([ReductionLayer](#))
- **Register\_Layer\_Class** (Reduction)
- **Instantiate\_Class** ([ReLULayer](#))
- **Instantiate\_Class** ([ReshapeLayer](#))
- **Register\_Layer\_Class** (Reshape)
- **Instantiate\_Class** ([RNNLayer](#))
- **Register\_Layer\_Class** (RNN)
- **Instantiate\_Class** ([ScaleLayer](#))
- **Register\_Layer\_Class** (Scale)
- **Instantiate\_Class** ([SigmoidCrossEntropyLossLayer](#))
- **Register\_Layer\_Class** (SigmoidCrossEntropyLoss)
- **Instantiate\_Class** ([SigmoidLayer](#))
- **Instantiate\_Class** ([SilenceLayer](#))
- **Register\_Layer\_Class** (Silence)
- **Instantiate\_Class** ([SliceLayer](#))
- **Register\_Layer\_Class** (Slice)
- **Instantiate\_Class** ([SoftmaxLayer](#))
- **Instantiate\_Class** ([SoftmaxWithLossLayer](#))
- **Register\_Layer\_Class** (SoftmaxWithLoss)
- **Instantiate\_Class** ([SplitLayer](#))
- **Register\_Layer\_Class** (Split)
- **Instantiate\_Class** ([SPPLayer](#))
- **Register\_Layer\_Class** (SPP)
- **Instantiate\_Class** ([SwishLayer](#))
- **Register\_Layer\_Class** (Swish)
- **Instantiate\_Class** ([TanHLayer](#))
- **Instantiate\_Class** ([ThresholdLayer](#))
- **Register\_Layer\_Class** (Threshold)
- **Instantiate\_Class** ([TileLayer](#))
- **Register\_Layer\_Class** (Tile)
- **Instantiate\_Class** ([Net](#))
- `template<typename Dtype >`  
`void LoadNetWeights (shared_ptr< Net< Dtype > > net, const std::string &model_list)`
- **Instantiate\_Class** ([Solver](#))
- `template<typename Dtype >`  
`void adadelta_update_gpu (int N, Dtype *g, Dtype *h, Dtype *h2, Dtype momentum, Dtype delta, Dtype local_rate)`
- **Instantiate\_Class** ([AdaDeltaSolver](#))
- **Register\_Solver\_Class** (AdaDelta)
- `template<typename Dtype >`  
`void adagrad_update_gpu (int N, Dtype *g, Dtype *h, Dtype delta, Dtype local_rate)`
- **Instantiate\_Class** ([AdaGradSolver](#))
- **Register\_Solver\_Class** (AdaGrad)
- `template<typename Dtype >`  
`void adam_update_gpu (int N, Dtype *g, Dtype *m, Dtype *v, Dtype beta1, Dtype beta2, Dtype eps_hat, Dtype corrected_local_rate)`
- **Instantiate\_Class** ([AdamSolver](#))
- **Register\_Solver\_Class** (Adam)
- `template<typename Dtype >`  
`void nesterov_update_gpu (int N, Dtype *g, Dtype *h, Dtype momentum, Dtype local_rate)`
- **Instantiate\_Class** ([NesterovSolver](#))
- **Register\_Solver\_Class** (Nesterov)
- `template<typename Dtype >`  
`void rmsprop_update_gpu (int N, Dtype *g, Dtype *h, Dtype rms_decay, Dtype delta, Dtype local_rate)`

- **INstantiate\_CLASS** ([RMSPropSolver](#))
- **REGISTER\_SOLVER\_CLASS** (RMSProp)
- `template<typename Dtype >`  
`void sgd_update_gpu (int N, Dtype *g, Dtype *h, Dtype momentum, Dtype local_rate)`
- **INstantiate\_CLASS** ([SGDSolver](#))
- **REGISTER\_SOLVER\_CLASS** (SGD)
- `bool is_a_ge_zero_and_a_lt_b (int a, int b)`
- `template void im2col_cpu< float > (const float *data_im, const int channels, const int height, const int width, const int kernel_h, const int kernel_w, const int pad_h, const int pad_w, const int stride_h, const int stride_w, const int dilation_h, const int dilation_w, float *data_col)`
- `template void im2col_cpu< double > (const double *data_im, const int channels, const int height, const int width, const int kernel_h, const int kernel_w, const int pad_h, const int pad_w, const int stride_h, const int stride_w, const int dilation_h, const int dilation_w, double *data_col)`
- `template<typename Dtype >`  
`void im2col_nd_core_cpu (const Dtype *data_input, const bool im2col, const int num_spatial_axes, const int *im_shape, const int *col_shape, const int *kernel_shape, const int *pad, const int *stride, const int *dilation, Dtype *data_output)`
- `template void im2col_nd_cpu< float > (const float *data_im, const int num_spatial_axes, const int *im_shape, const int *col_shape, const int *kernel_shape, const int *pad, const int *stride, const int *dilation, float *data_col)`
- `template void im2col_nd_cpu< double > (const double *data_im, const int num_spatial_axes, const int *im_shape, const int *col_shape, const int *kernel_shape, const int *pad, const int *stride, const int *dilation, double *data_col)`
- `template void col2im_cpu< float > (const float *data_col, const int channels, const int height, const int width, const int kernel_h, const int kernel_w, const int pad_h, const int pad_w, const int stride_h, const int stride_w, const int dilation_h, const int dilation_w, float *data_im)`
- `template void col2im_cpu< double > (const double *data_col, const int channels, const int height, const int width, const int kernel_h, const int kernel_w, const int pad_h, const int pad_w, const int stride_h, const int stride_w, const int dilation_h, const int dilation_w, double *data_im)`
- `template void col2im_nd_cpu< float > (const float *data_col, const int num_spatial_axes, const int *im_shape, const int *col_shape, const int *kernel_shape, const int *pad, const int *stride, const int *dilation, float *data_im)`
- `template void col2im_nd_cpu< double > (const double *data_col, const int num_spatial_axes, const int *im_shape, const int *col_shape, const int *kernel_shape, const int *pad, const int *stride, const int *dilation, double *data_im)`
- `template<>`  
`void caffe_cpu_gemm< float > (const CBLAS_TRANSPOSE TransA, const CBLAS_TRANSPOSE TransB, const int M, const int N, const int K, const float alpha, const float *A, const float *B, const float beta, float *C)`
- `template<>`  
`void caffe_cpu_gemm< double > (const CBLAS_TRANSPOSE TransA, const CBLAS_TRANSPOSE TransB, const int M, const int N, const int K, const double alpha, const double *A, const double *B, const double beta, double *C)`
- `template<>`  
`void caffe_cpu_gemv< float > (const CBLAS_TRANSPOSE TransA, const int M, const int N, const float alpha, const float *A, const float *x, const float beta, float *y)`
- `template<>`  
`void caffe_cpu_gemv< double > (const CBLAS_TRANSPOSE TransA, const int M, const int N, const double alpha, const double *A, const double *x, const double beta, double *y)`
- `template<>`  
`void caffe_axpy< float > (const int N, const float alpha, const float *X, float *Y)`
- `template<>`  
`void caffe_axpy< double > (const int N, const double alpha, const double *X, double *Y)`
- `template void caffe_set< int > (const int N, const int alpha, int *Y)`
- `template void caffe_set< float > (const int N, const float alpha, float *Y)`
- `template void caffe_set< double > (const int N, const double alpha, double *Y)`
- `template<>`  
`void caffe_add_scalar (const int N, const float alpha, float *Y)`

- `template<>`  
void **caffe\_add\_scalar** (const int N, const double alpha, double \*Y)
- `template void caffe_copy< int >` (const int N, const int \*X, int \*Y)
- `template void caffe_copy< unsigned int >` (const int N, const unsigned int \*X, unsigned int \*Y)
- `template void caffe_copy< float >` (const int N, const float \*X, float \*Y)
- `template void caffe_copy< double >` (const int N, const double \*X, double \*Y)
- `template<>`  
void **caffe\_scal**< float > (const int N, const float alpha, float \*X)
- `template<>`  
void **caffe\_scal**< double > (const int N, const double alpha, double \*X)
- `template<>`  
void **caffe\_cpu\_axpby**< float > (const int N, const float alpha, const float \*X, const float beta, float \*Y)
- `template<>`  
void **caffe\_cpu\_axpby**< double > (const int N, const double alpha, const double \*X, const double beta, double \*Y)
- `template<>`  
void **caffe\_add**< float > (const int n, const float \*a, const float \*b, float \*y)
- `template<>`  
void **caffe\_add**< double > (const int n, const double \*a, const double \*b, double \*y)
- `template<>`  
void **caffe\_sub**< float > (const int n, const float \*a, const float \*b, float \*y)
- `template<>`  
void **caffe\_sub**< double > (const int n, const double \*a, const double \*b, double \*y)
- `template<>`  
void **caffe\_mul**< float > (const int n, const float \*a, const float \*b, float \*y)
- `template<>`  
void **caffe\_mul**< double > (const int n, const double \*a, const double \*b, double \*y)
- `template<>`  
void **caffe\_div**< float > (const int n, const float \*a, const float \*b, float \*y)
- `template<>`  
void **caffe\_div**< double > (const int n, const double \*a, const double \*b, double \*y)
- `template<>`  
void **caffe\_powx**< float > (const int n, const float \*a, const float b, float \*y)
- `template<>`  
void **caffe\_powx**< double > (const int n, const double \*a, const double b, double \*y)
- `template<>`  
void **caffe\_sqr**< float > (const int n, const float \*a, float \*y)
- `template<>`  
void **caffe\_sqr**< double > (const int n, const double \*a, double \*y)
- `template<>`  
void **caffe\_sqrt**< float > (const int n, const float \*a, float \*y)
- `template<>`  
void **caffe\_sqrt**< double > (const int n, const double \*a, double \*y)
- `template<>`  
void **caffe\_exp**< float > (const int n, const float \*a, float \*y)
- `template<>`  
void **caffe\_exp**< double > (const int n, const double \*a, double \*y)
- `template<>`  
void **caffe\_log**< float > (const int n, const float \*a, float \*y)
- `template<>`  
void **caffe\_log**< double > (const int n, const double \*a, double \*y)
- `template<>`  
void **caffe\_abs**< float > (const int n, const float \*a, float \*y)
- `template<>`  
void **caffe\_abs**< double > (const int n, const double \*a, double \*y)
- `template float caffe_nextafter` (const float b)



- template double **caffe\_nextafter** (const double b)
- template void **caffe\_rng\_uniform**< float > (const int n, const float a, const float b, float \*r)
- template void **caffe\_rng\_uniform**< double > (const int n, const double a, const double b, double \*r)
- template void **caffe\_rng\_gaussian**< float > (const int n, const float mu, const float sigma, float \*r)
- template void **caffe\_rng\_gaussian**< double > (const int n, const double mu, const double sigma, double \*r)
- template void **caffe\_rng\_bernoulli**< double > (const int n, const double p, int \*r)
- template void **caffe\_rng\_bernoulli**< float > (const int n, const float p, int \*r)
- template void **caffe\_rng\_bernoulli**< double > (const int n, const double p, unsigned int \*r)
- template void **caffe\_rng\_bernoulli**< float > (const int n, const float p, unsigned int \*r)
- template<>  
float **caffe\_cpu\_strided\_dot**< float > (const int n, const float \*x, const int incx, const float \*y, const int incy)
- template<>  
double **caffe\_cpu\_strided\_dot**< double > (const int n, const double \*x, const int incx, const double \*y, const int incy)
- template float **caffe\_cpu\_dot**< float > (const int n, const float \*x, const float \*y)
- template double **caffe\_cpu\_dot**< double > (const int n, const double \*x, const double \*y)
- template<>  
float **caffe\_cpu\_asum**< float > (const int n, const float \*x)
- template<>  
double **caffe\_cpu\_asum**< double > (const int n, const double \*x)
- template<>  
void **caffe\_cpu\_scale**< float > (const int n, const float alpha, const float \*x, float \*y)
- template<>  
void **caffe\_cpu\_scale**< double > (const int n, const double alpha, const double \*x, double \*y)
- void **UpgradeSnapshotPrefixProperty** (const string &param\_file, SolverParameter \*param)

## Variables

- const float **kLOG\_THRESHOLD** = 1e-20
- const int **CAFFE\_CUDA\_NUM\_THREADS** = 512
- const Dtype **alpha**
- const Dtype const Dtype \* **x**
- const Dtype const Dtype Dtype \* **y**
- const float **kBNLL\_THRESHOLD** = 50.

### 4.2.1 Detailed Description

A layer factory that allows one to register layers. During runtime, registered layers can be called by passing a LayerParameter protobuffer to the CreateLayer function:

A solver factory that allows one to register solvers, similar to layer factory. During runtime, registered solvers could be called by passing a SolverParameter protobuffer to the CreateSolver function:

```
LayerRegistry<Dtype>::CreateLayer(param);
```

There are two ways to register a layer. Assuming that we have a layer like:

```
template <typename dtype>=""> class MyAwesomeLayer : public Layer<dtype> { // your implementations };
```

and its type is its C++ class name, but without the "Layer" at the end ("MyAwesomeLayer" -> "MyAwesome").

If the layer is going to be created simply by its constructor, in your c++ file, add the following line:

```
REGISTER_LAYER_CLASS(MyAwesome);
```

Or, if the layer is going to be created by another creator function, in the format of:

```
template <typename dtype>=""> Layer<Dtype*> GetMyAwesomeLayer(const LayerParameter& param) { // your implementation }
```

(for example, when your layer has multiple backends, see `GetConvolutionLayer` for a use case), then you can register the creator function instead, like

```
REGISTER_LAYER_CREATOR(MyAwesome, GetMyAwesomeLayer)
```

Note that each layer type should only be registered once.

```
SolverRegistry<Dtype>::CreateSolver(param);
```

There are two ways to register a solver. Assuming that we have a solver like:

```
template <typename dtype>=""> class MyAwesomeSolver : public Solver<Dtype> { // your implementations };
```

and its type is its C++ class name, but without the "Solver" at the end ("MyAwesomeSolver" -> "MyAwesome").

If the solver is going to be created simply by its constructor, in your C++ file, add the following line:

```
REGISTER_SOLVER_CLASS(MyAwesome);
```

Or, if the solver is going to be created by another creator function, in the format of:

```
template <typename dtype>=""> Solver<Dtype*> GetMyAwesomeSolver(const SolverParameter& param) { // your implementation }
```

then you can register the creator function instead, like

```
REGISTER_SOLVER_CREATOR(MyAwesome, GetMyAwesomeSolver)
```

Note that each solver type should only be registered once.

## 4.2.2 Function Documentation

### 4.2.2.1 GetFiller()

```
template<typename Dtype >
Filler<Dtype*> caffe::GetFiller (
    const FillerParameter & param )
```

Get a specific filler from the specification given in `FillerParameter`.

Ideally this would be replaced by a factory pattern, but we will leave it this way for now.

## 4.3 `caffe::SolverAction` Namespace Reference

Enumeration of actions that a client of the `Solver` may request by implementing the `Solver`'s action request function, which a client may optionally provide in order to request early termination or saving a snapshot without exiting. In the executable `caffe`, this mechanism is used to allow the snapshot to be saved when stopping execution with a SIGINT (Ctrl-C).

### Enumerations

- enum `Enum` { `NONE` = 0, `STOP` = 1, `SNAPSHOT` = 2 }

#### 4.3.1 Detailed Description

Enumeration of actions that a client of the `Solver` may request by implementing the `Solver`'s action request function, which a client may optionally provide in order to request early termination or saving a snapshot without exiting. In the executable `caffe`, this mechanism is used to allow the snapshot to be saved when stopping execution with a SIGINT (Ctrl-C).



## Chapter 5

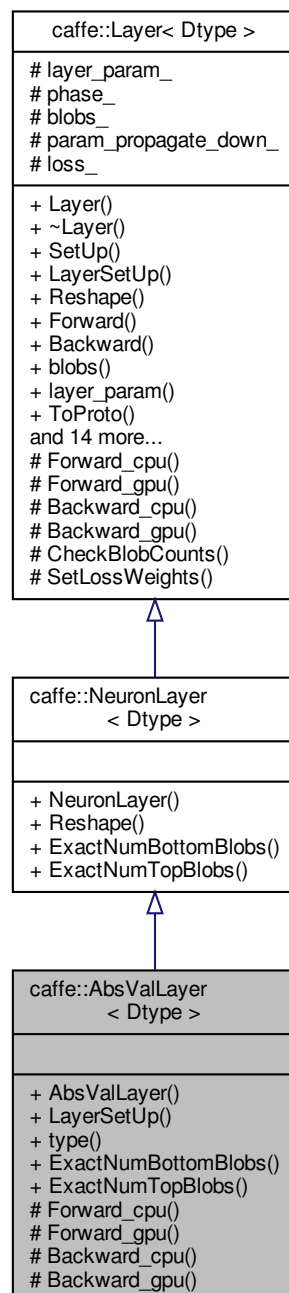
# Class Documentation

### 5.1 `caffe::AbsValLayer< Dtype >` Class Template Reference

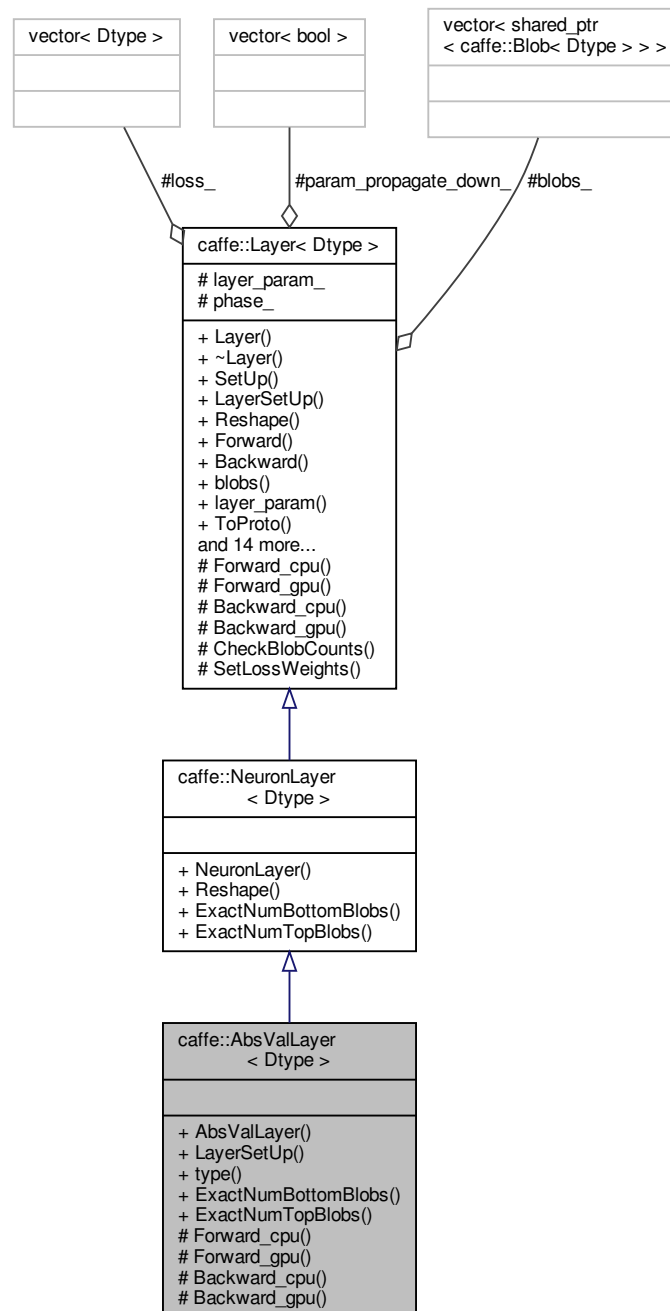
Computes  $y = |x|$ .

```
#include <absval_layer.hpp>
```

Inheritance diagram for `caffe::AbsValLayer< Dtype >`:



Collaboration diagram for caffe::AbsValLayer< Dtype >:



## Public Member Functions

- **AbsValLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual const char \* **type** () const  
*Returns the layer type.*

- virtual int [ExactNumBottomBlobs](#) () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int [ExactNumTopBlobs](#) () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Computes  $y = |x|$ .*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Computes the error gradient w.r.t. the absolute value inputs.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Additional Inherited Members

### 5.1.1 Detailed Description

```
template<typename Dtype>
class caffe::AbsValLayer< Dtype >
```

Computes  $y = |x|$ .

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y =  x $

### 5.1.2 Member Function Documentation

#### 5.1.2.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::AbsValLayer< Dtype >::Backward_cpu (
```



```
const vector< Blob< Dtype > *> & top,
const vector< bool > & propagate_down,
const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the absolute value inputs.

#### Parameters

<i>top</i>	output <code>Blob</code> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times H \times W)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <code>Layer::Backward</code> .
<i>bottom</i>	input <code>Blob</code> vector (length 2) 1. $(N \times C \times H \times W)$ the inputs $x$ ; Backward fills their diff with gradients $\frac{\partial E}{\partial x} = \text{sign}(x) \frac{\partial E}{\partial y}$ if <code>propagate_down[0]</code>

Implements `caffe::Layer< Dtype >`.

#### 5.1.2.2 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::AbsValLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::NeuronLayer< Dtype >`.

#### 5.1.2.3 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::AbsValLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from `caffe::NeuronLayer< Dtype >`.

#### 5.1.2.4 Forward\_cpu()

```
template<typename Dtype >
void caffe::AbsValLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

Computes  $y = |x|$ .

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y =  x $

Implements [caffe::Layer< Dtype >](#).

## 5.1.2.5 LayerSetUp()

```
template<typename Dtype >
void caffe::AbsValLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > \*> & bottom,
    const vector< Blob< Dtype > \*> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

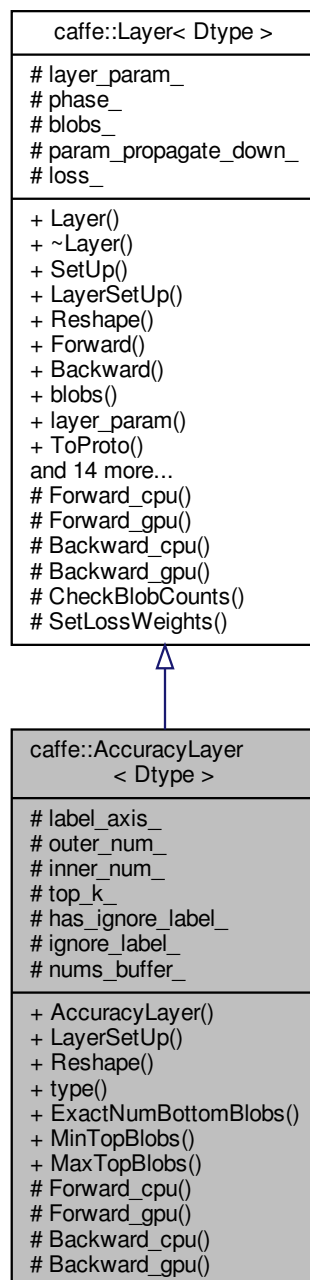
- include/caffe/layers/absval\_layer.hpp
- src/caffe/layers/absval\_layer.cpp

5.2 [caffe::AccuracyLayer< Dtype >](#) Class Template Reference

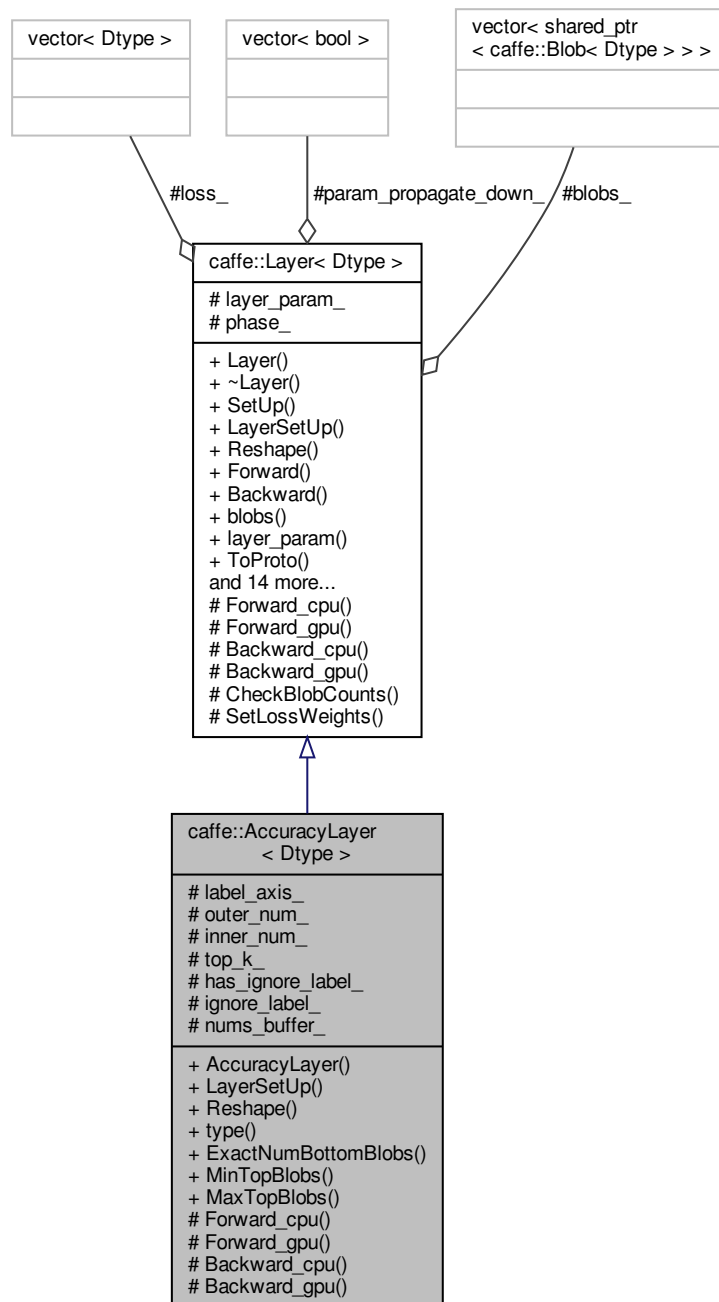
Computes the classification accuracy for a one-of-many classification task.

```
#include <accuracy_layer.hpp>
```

Inheritance diagram for caffe::AccuracyLayer< Dtype >:



Collaboration diagram for `caffe::AccuracyLayer< Dtype >`:



## Public Member Functions

- [AccuracyLayer](#) (const LayerParameter &param)
- virtual void [LayerSetUp](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as [Reshape](#).
- virtual void [Reshape](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

- virtual const char \* [type](#) () const  
*Returns the layer type.*
- virtual int [ExactNumBottomBlobs](#) () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int [MinTopBlobs](#) () const  
*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*
- virtual int [MaxTopBlobs](#) () const  
*Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.*

### Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Not implemented – [AccuracyLayer](#) cannot be used as a loss.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

### Protected Attributes

- int [label\\_axis\\_](#)
- int [outer\\_num\\_](#)
- int [inner\\_num\\_](#)
- int [top\\_k\\_](#)
- bool [has\\_ignore\\_label\\_](#)  
*Whether to ignore instances with a certain label.*
- int [ignore\\_label\\_](#)  
*The label indicating that an instance should be ignored.*
- [Blob](#)< Dtype > [nums\\_buffer\\_](#)  
*Keeps counts of the number of samples per class.*

## 5.2.1 Detailed Description

```
template<typename Dtype>
class caffe::AccuracyLayer< Dtype >
```

Computes the classification accuracy for a one-of-many classification task.

## 5.2.2 Constructor & Destructor Documentation

### 5.2.2.1 AccuracyLayer()

```
template<typename Dtype >
caffe::AccuracyLayer< Dtype >::AccuracyLayer (
    const LayerParameter & param ) [inline], [explicit]
```

## Parameters

<i>param</i>	provides AccuracyParameter accuracy_param, with <a href="#">AccuracyLayer</a> options: <ul style="list-style-type: none"> <li>top_k (<b>optional</b>, default 1). Sets the maximum rank <math>k</math> at which a prediction is considered correct. For example, if <math>k = 5</math>, a prediction is counted correct if the correct label is among the top 5 predicted labels.</li> </ul>
--------------	--

## 5.2.3 Member Function Documentation

## 5.2.3.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::AccuracyLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer](#)< Dtype >.

## 5.2.3.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::AccuracyLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the predictions <math>x</math>, a <a href="#">Blob</a> with values in <math>[-\infty, +\infty]</math> indicating the predicted score for each of the <math>K = CHW</math> classes. Each <math>x_n</math> is mapped to a predicted label <math>\hat{l}_n</math> given by its maximal index: <math>\hat{l}_n = \arg \max_k x_{nk}</math></li> <li><math>(N \times 1 \times 1 \times 1)</math> the labels <math>l</math>, an integer-valued <a href="#">Blob</a> with values <math>l_n \in [0, 1, 2, \dots, K - 1]</math> indicating the correct class label among the <math>K</math> classes</li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> the computed accuracy: <math>\frac{1}{N} \sum_{n=1}^N \delta\{\hat{l}_n = l_n\}</math>, where             <math display="block">\delta\{\text{condition}\} = \begin{cases} 1 &amp; \text{if condition} \\ 0 &amp; \text{otherwise} \end{cases}</math> </li> </ol>

Implements [caffe::Layer< Dtype >](#).

### 5.2.3.3 LayerSetUp()

```
template<typename Dtype >
void caffe::AccuracyLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

#### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.2.3.4 MaxTopBlobs()

```
template<typename Dtype >
virtual int caffe::AccuracyLayer< Dtype >::MaxTopBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.2.3.5 MinTopBlobs()

```
template<typename Dtype >
virtual int caffe::AccuracyLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.2.3.6 Reshape()

```
template<typename Dtype >
void caffe::AccuracyLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

#### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements `caffe::Layer< Dtype >`.

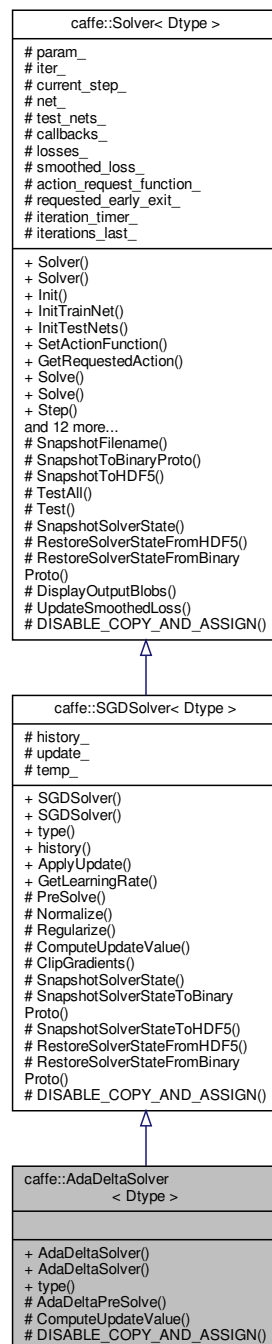
The documentation for this class was generated from the following files:

- `include/caffe/layers/accuracy_layer.hpp`
- `src/caffe/layers/accuracy_layer.cpp`

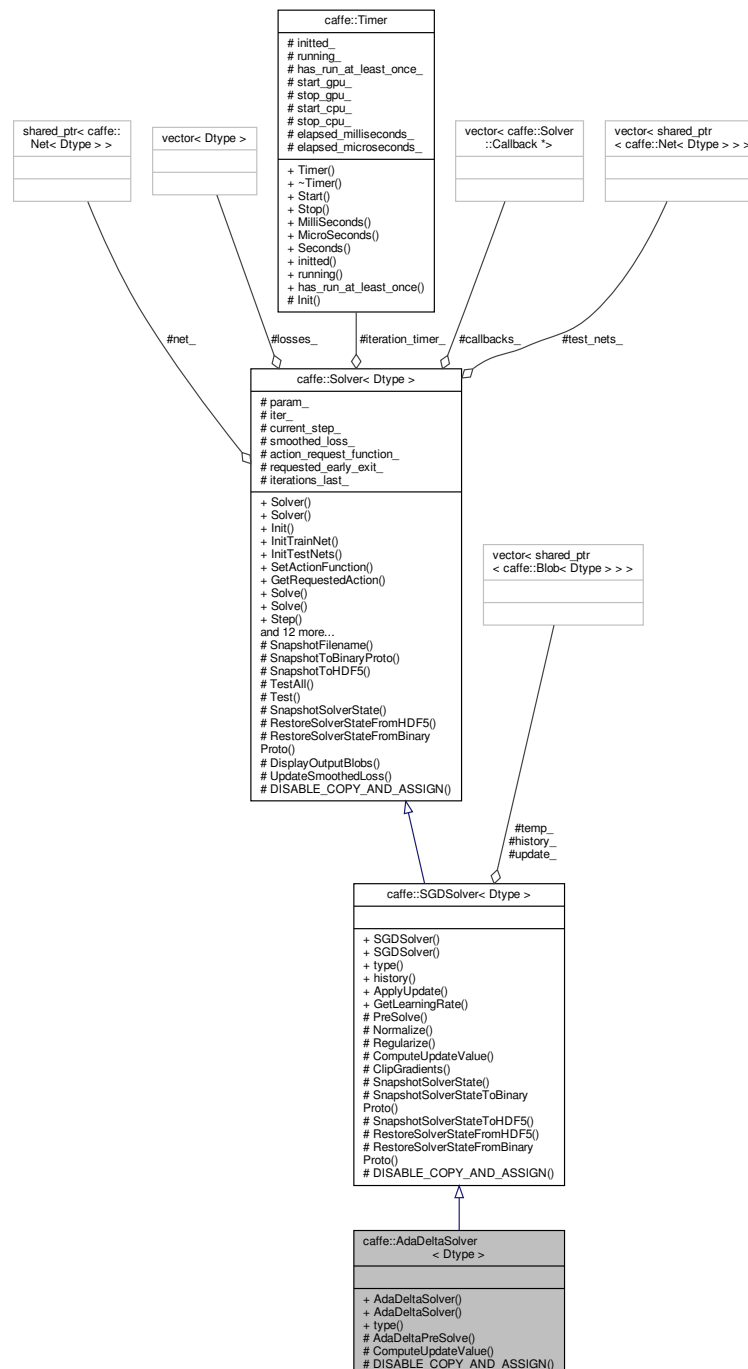


### 5.3 caffe::AdaDeltaSolver< Dtype > Class Template Reference

Inheritance diagram for caffe::AdaDeltaSolver< Dtype >:



Collaboration diagram for `caffe::AdaDeltaSolver< Dtype >`:



## Public Member Functions

- **AdaDeltaSolver** (const SolverParameter &param)
- **AdaDeltaSolver** (const string &param\_file)
- virtual const char \* **type** () const

Returns the solver type.

### Protected Member Functions

- void **AdaDeltaPreSolve** ()
- virtual void **ComputeUpdateValue** (int param\_id, Dtype rate)
- **DISABLE\_COPY\_AND\_ASSIGN** ([AdaDeltaSolver](#))

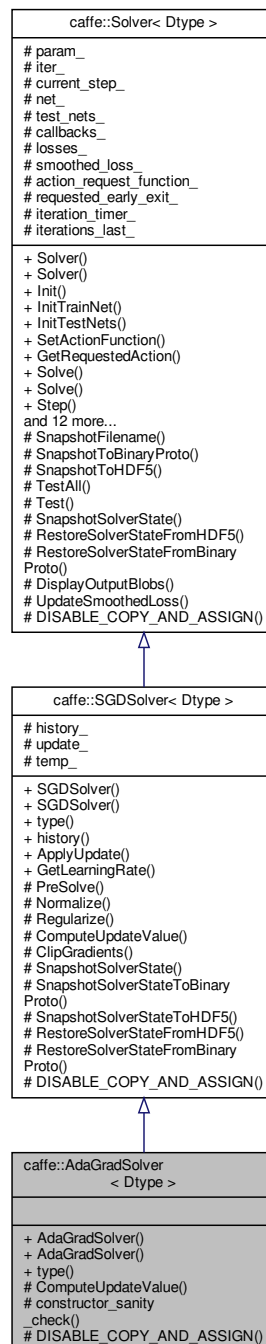
### Additional Inherited Members

The documentation for this class was generated from the following files:

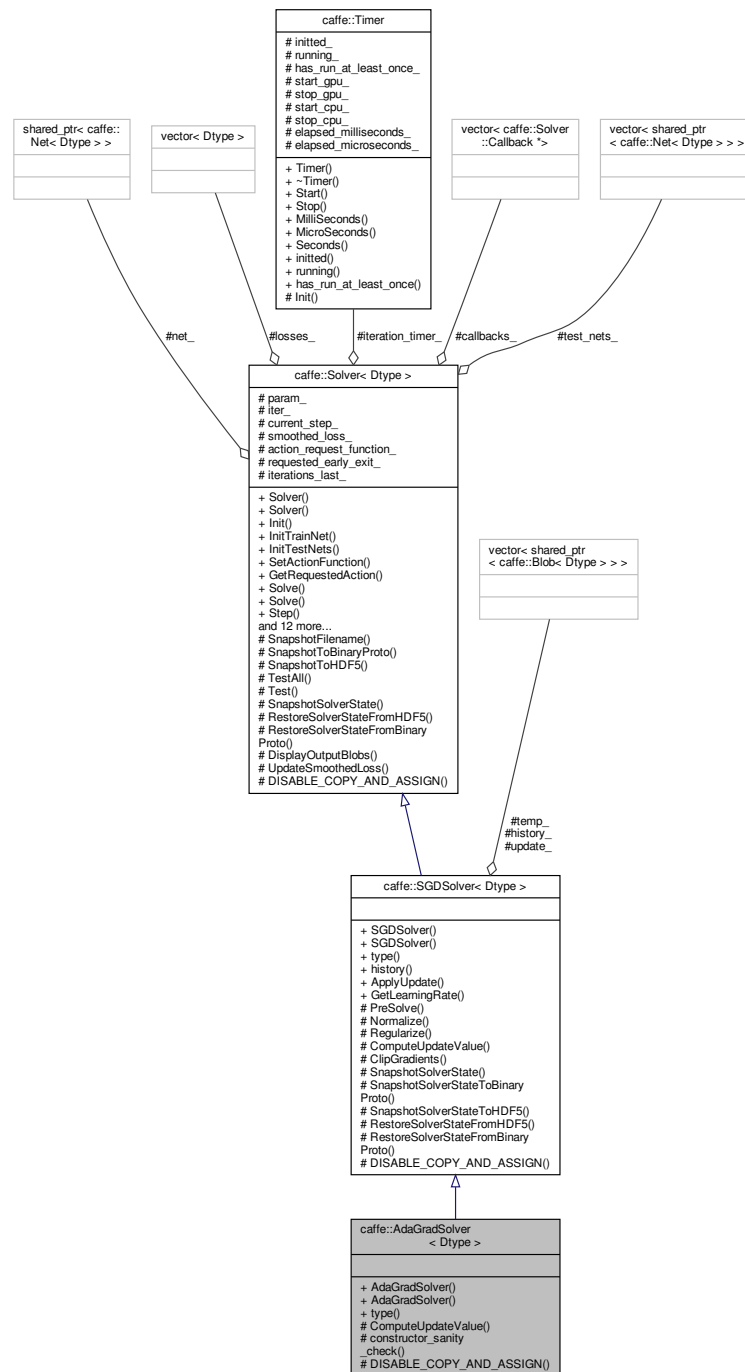
- `include/caffe/sgd_solvers.hpp`
- `src/caffe/solvers/adadelta_solver.cpp`

## 5.4 caffe::AdaGradSolver< Dtype > Class Template Reference

Inheritance diagram for caffe::AdaGradSolver< Dtype >:



Collaboration diagram for caffe::AdaGradSolver< Dtype >:



## Public Member Functions

- **AdaGradSolver** (const SolverParameter &param)
- **AdaGradSolver** (const string &param\_file)
- virtual const char \* **type** () const

Returns the solver type.

### Protected Member Functions

- virtual void **ComputeUpdateValue** (int param\_id, Dtype rate)
- void **constructor\_sanity\_check** ()
- **DISABLE\_COPY\_AND\_ASSIGN** ([AdaGradSolver](#))

### Additional Inherited Members

The documentation for this class was generated from the following files:

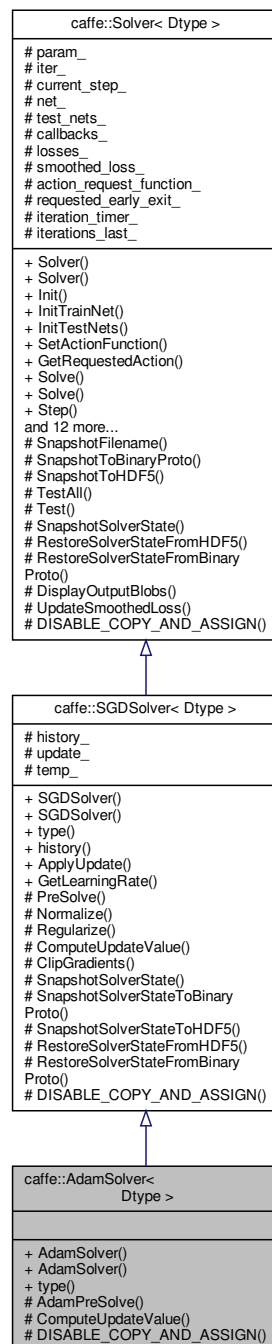
- include/caffe/sgd\_solvers.hpp
- src/caffe/solvers/adagrad\_solver.cpp

## 5.5 `caffe::AdamSolver< Dtype >` Class Template Reference

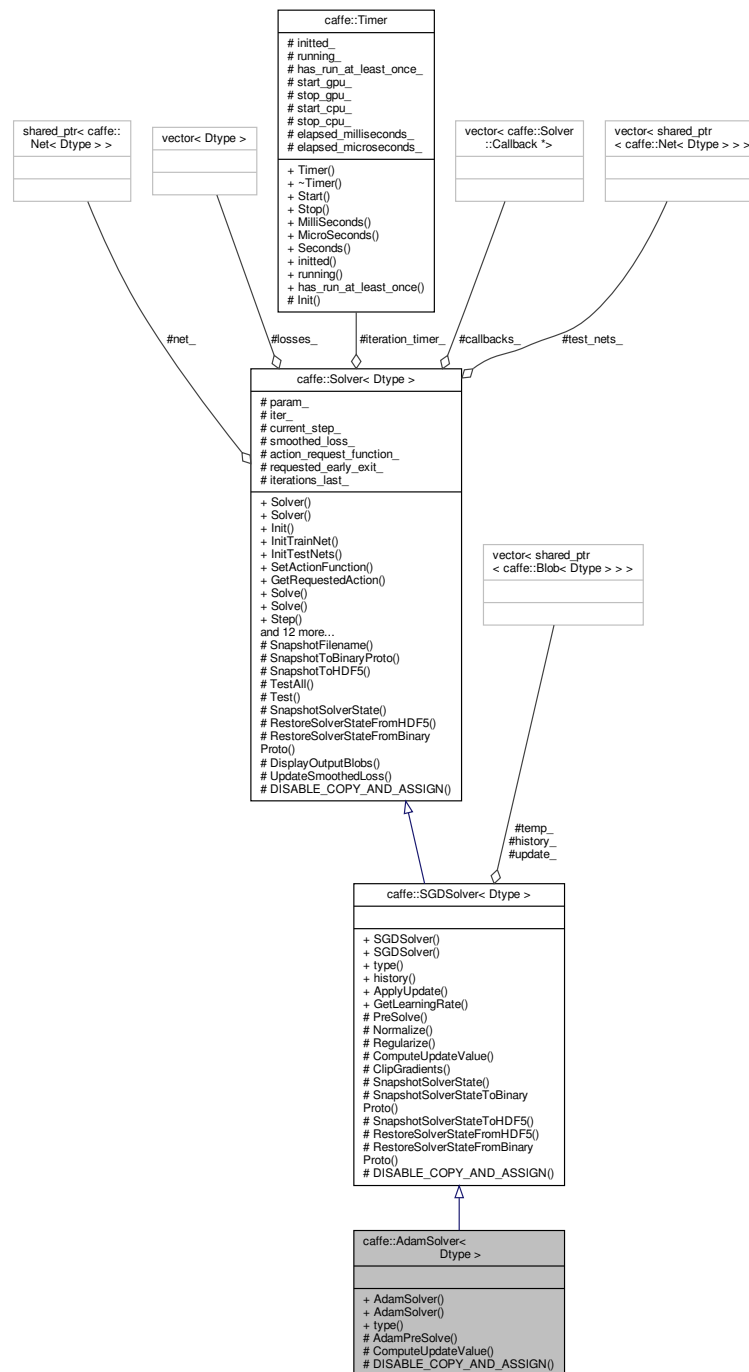
[AdamSolver](#), an algorithm for first-order gradient-based optimization of stochastic objective functions, based on adaptive estimates of lower-order moments. Described in [1].

```
#include <sgd_solvers.hpp>
```

Inheritance diagram for caffe::AdamSolver< Dtype >:



Collaboration diagram for `caffe::AdamSolver< Dtype >`:



## Public Member Functions

- **AdamSolver** (const SolverParameter &param)
- **AdamSolver** (const string &param\_file)
- virtual const char \* **type** () const

Returns the solver type.



### Protected Member Functions

- void **AdamPreSolve** ()
- virtual void **ComputeUpdateValue** (int param\_id, Dtype rate)
- **DISABLE\_COPY\_AND\_ASSIGN** ([AdamSolver](#))

### Additional Inherited Members

#### 5.5.1 Detailed Description

```
template<typename Dtype>
class caffe::AdamSolver< Dtype >
```

[AdamSolver](#), an algorithm for first-order gradient-based optimization of stochastic objective functions, based on adaptive estimates of lower-order moments. Described in [1].

[1] D. P. Kingma and J. L. Ba, "ADAM: A Method for Stochastic Optimization." arXiv preprint arXiv:1412.6980v8 (2014).

The documentation for this class was generated from the following files:

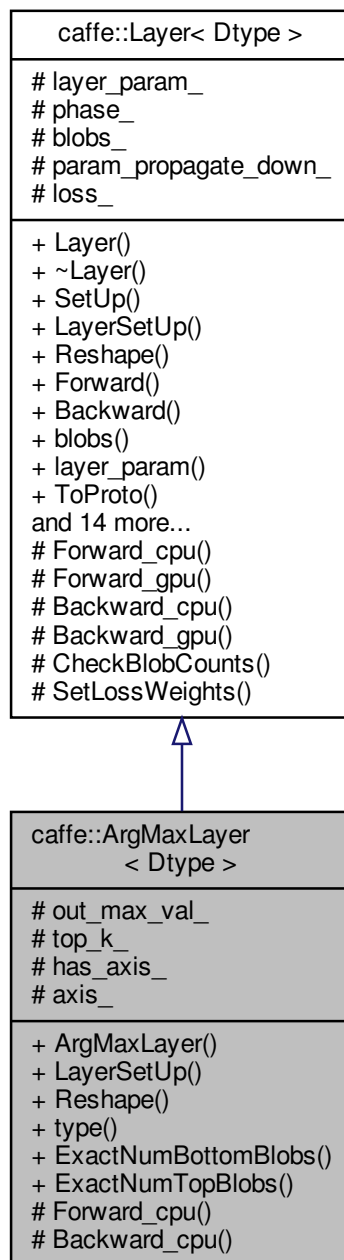
- include/caffe/sgd\_solvers.hpp
- src/caffe/solvers/adam\_solver.cpp

## 5.6 caffe::ArgMaxLayer< Dtype > Class Template Reference

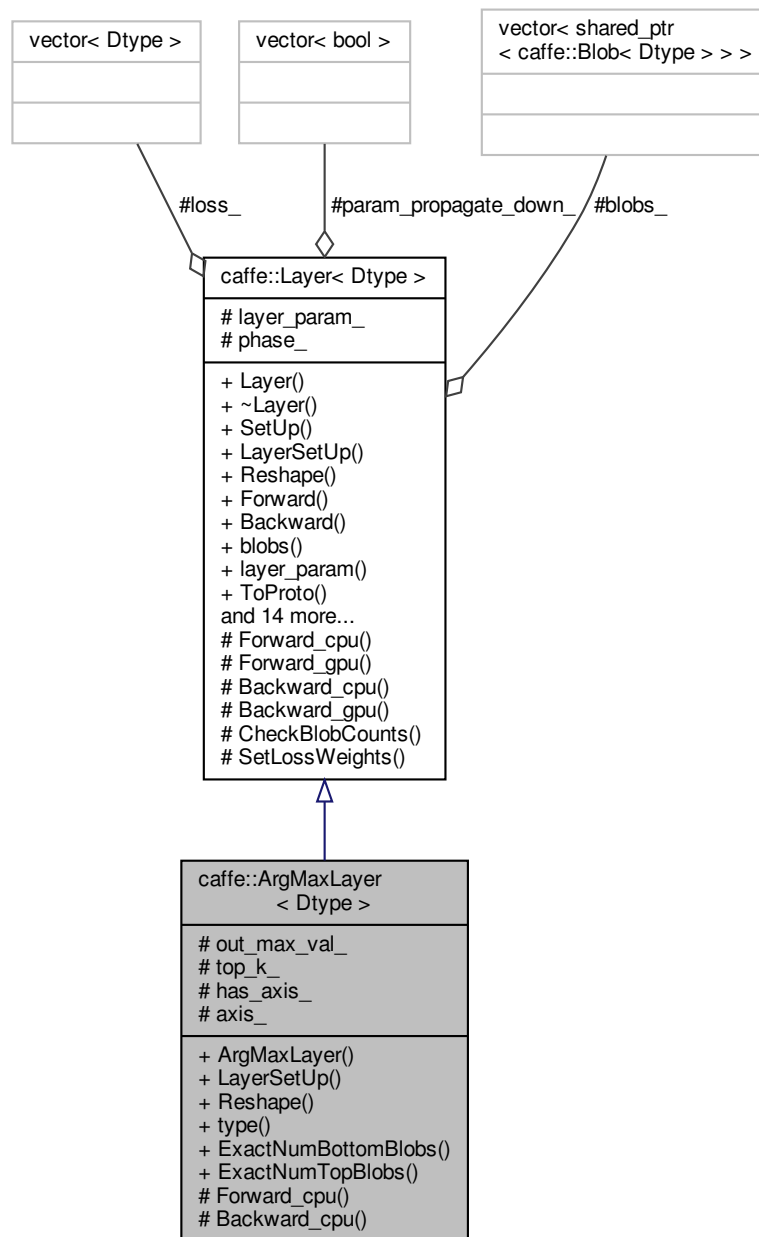
Compute the index of the  $K$  max values for each datum across all dimensions ( $C \times H \times W$ ).

```
#include <argmax_layer.hpp>
```

Inheritance diagram for `caffe::ArgMaxLayer< Dtype >`:



Collaboration diagram for caffe::ArgMaxLayer< Dtype >:



## Public Member Functions

- [ArgMaxLayer](#) (const LayerParameter &param)
- virtual void [LayerSetUp](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
Does layer-specific setup: your layer should implement this function as well as Reshape.
- virtual void [Reshape](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.
- virtual const char \* [type](#) () const

*Returns the layer type.*

- virtual int [ExactNumBottomBlobs](#) () const

*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*

- virtual int [ExactNumTopBlobs](#) () const

*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Not implemented (non-differentiable function)*

## Protected Attributes

- bool **out\_max\_val\_**
- size\_t **top\_k\_**
- bool **has\_axis\_**
- int **axis\_**

### 5.6.1 Detailed Description

```
template<typename Dtype>
class caffe::ArgMaxLayer< Dtype >
```

Compute the index of the  $K$  max values for each datum across all dimensions ( $C \times H \times W$ ).

Intended for use after a classification layer to produce a prediction. If parameter out\_max\_val is set to true, output is a vector of pairs (max\_ind, max\_val) for each image. The axis parameter specifies an axis along which to maximise.

NOTE: does not implement Backwards operation.

### 5.6.2 Constructor & Destructor Documentation

#### 5.6.2.1 ArgMaxLayer()

```
template<typename Dtype >
caffe::ArgMaxLayer< Dtype >::ArgMaxLayer (
    const LayerParameter & param ) [inline], [explicit]
```

## Parameters

<i>param</i>	provides ArgMaxParameter <code>argmax_param</code> , with <a href="#">ArgMaxLayer</a> options: <ul style="list-style-type: none"> <li><code>top_k</code> (<b>optional</b> uint, default 1). the number <math>K</math> of maximal items to output.</li> <li><code>out_max_val</code> (<b>optional</b> bool, default false). if set, output a vector of pairs (<code>max_ind</code>, <code>max_val</code>) unless <code>axis</code> is set then output <code>max_val</code> along the specified axis.</li> <li><code>axis</code> (<b>optional</b> int). if set, maximise along the specified axis else maximise the flattened trailing dimensions for each index of the first / num dimension.</li> </ul>
--------------	---

## 5.6.3 Member Function Documentation

5.6.3.1 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::ArgMaxLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

5.6.3.2 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::ArgMaxLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

5.6.3.3 `Forward_cpu()`

```
template<typename Dtype >
void caffe::ArgMaxLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times 1 \times K)$ or, if <code>out_max_val</code> $(N \times 2 \times K)$ unless axis set than e.g. $(N \times K \times H \times W)$ if <code>axis == 1</code> the computed outputs $y_n = \arg \max_i x_{ni}$ (for $K = 1$ ).

Implements [caffe::Layer< Dtype >](#).

## 5.6.3.4 LayerSetUp()

```
template<typename Dtype >
void caffe::ArgMaxLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.6.3.5 Reshape()

```
template<typename Dtype >
void caffe::ArgMaxLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

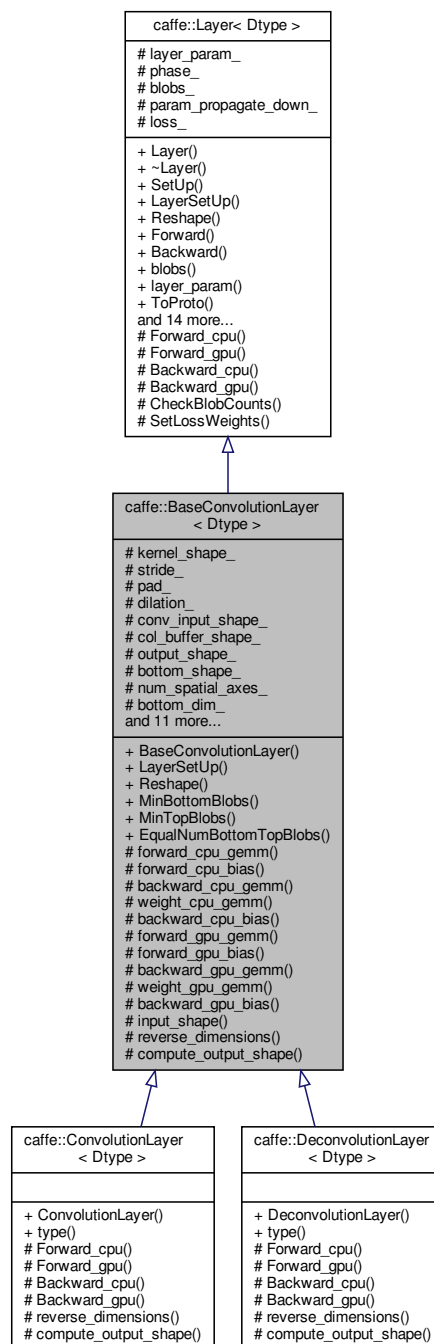
- `include/caffe/layers/argmax_layer.hpp`
- `src/caffe/layers/argmax_layer.cpp`

## 5.7 `caffe::BaseConvolutionLayer< Dtype >` Class Template Reference

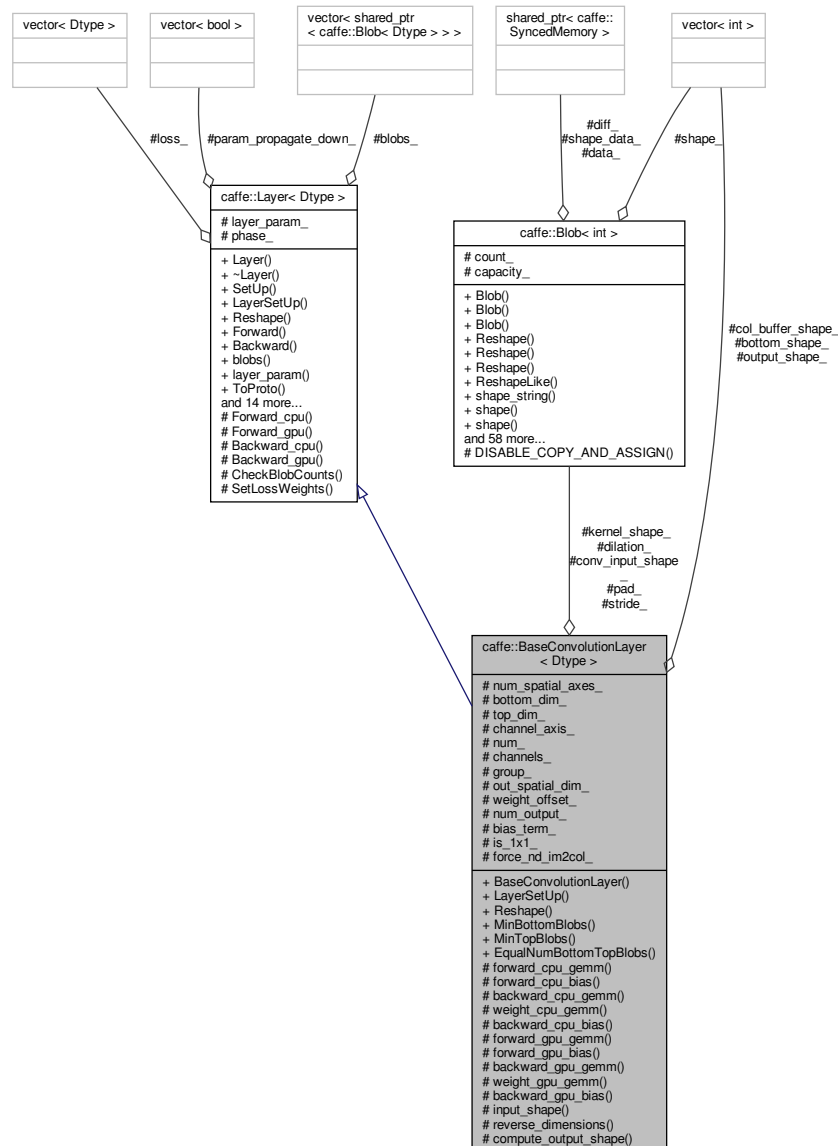
Abstract base class that factors out the BLAS code common to [ConvolutionLayer](#) and [DeconvolutionLayer](#).

```
#include <base_conv_layer.hpp>
```

Inheritance diagram for `caffe::BaseConvolutionLayer< Dtype >`:







- **BaseConvolutionLayer**

- Generated by Doxygen

## Protected Member Functions

- void **forward\_cpu\_gemm** (const Dtype \*input, const Dtype \*weights, Dtype \*output, bool skip\_im2col=false)
- void **forward\_cpu\_bias** (Dtype \*output, const Dtype \*bias)
- void **backward\_cpu\_gemm** (const Dtype \*input, const Dtype \*weights, Dtype \*output)
- void **weight\_cpu\_gemm** (const Dtype \*input, const Dtype \*output, Dtype \*weights)
- void **backward\_cpu\_bias** (Dtype \*bias, const Dtype \*input)
- void **forward\_gpu\_gemm** (const Dtype \*col\_input, const Dtype \*weights, Dtype \*output, bool skip\_im2col=false)
- void **forward\_gpu\_bias** (Dtype \*output, const Dtype \*bias)
- void **backward\_gpu\_gemm** (const Dtype \*input, const Dtype \*weights, Dtype \*col\_output)
- void **weight\_gpu\_gemm** (const Dtype \*col\_input, const Dtype \*output, Dtype \*weights)
- void **backward\_gpu\_bias** (Dtype \*bias, const Dtype \*input)
- int **input\_shape** (int i)  
*The spatial dimensions of the input.*
- virtual bool **reverse\_dimensions** ()=0
- virtual void **compute\_output\_shape** ()=0

## Protected Attributes

- Blob< int > **kernel\_shape\_**  
*The spatial dimensions of a filter kernel.*
- Blob< int > **stride\_**  
*The spatial dimensions of the stride.*
- Blob< int > **pad\_**  
*The spatial dimensions of the padding.*
- Blob< int > **dilation\_**  
*The spatial dimensions of the dilation.*
- Blob< int > **conv\_input\_shape\_**  
*The spatial dimensions of the convolution input.*
- vector< int > **col\_buffer\_shape\_**  
*The spatial dimensions of the col\_buffer.*
- vector< int > **output\_shape\_**  
*The spatial dimensions of the output.*
- const vector< int > \* **bottom\_shape\_**
- int **num\_spatial\_axes\_**
- int **bottom\_dim\_**
- int **top\_dim\_**
- int **channel\_axis\_**
- int **num\_**
- int **channels\_**
- int **group\_**
- int **out\_spatial\_dim\_**
- int **weight\_offset\_**
- int **num\_output\_**
- bool **bias\_term\_**
- bool **is\_1x1\_**
- bool **force\_nd\_im2col\_**

### 5.7.1 Detailed Description

```
template<typename Dtype>
class caffe::BaseConvolutionLayer< Dtype >
```

Abstract base class that factors out the BLAS code common to [ConvolutionLayer](#) and [DeconvolutionLayer](#).

### 5.7.2 Member Function Documentation

#### 5.7.2.1 `EqualNumBottomTopBlobs()`

```
template<typename Dtype >
virtual bool caffe::BaseConvolutionLayer< Dtype >::EqualNumBottomTopBlobs ( ) const [inline],
[virtual]
```

Returns true if the layer requires an equal number of bottom and top blobs.

This method should be overridden to return true if your layer expects an equal number of bottom and top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.7.2.2 `LayerSetUp()`

```
template<typename Dtype >
void caffe::BaseConvolutionLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

##### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.7.2.3 MinBottomBlobs()

```
template<typename Dtype >
virtual int caffe::BaseConvolutionLayer< Dtype >::MinBottomBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.7.2.4 MinTopBlobs()

```
template<typename Dtype >
virtual int caffe::BaseConvolutionLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.7.2.5 Reshape()

```
template<typename Dtype >
void caffe::BaseConvolutionLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

#### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

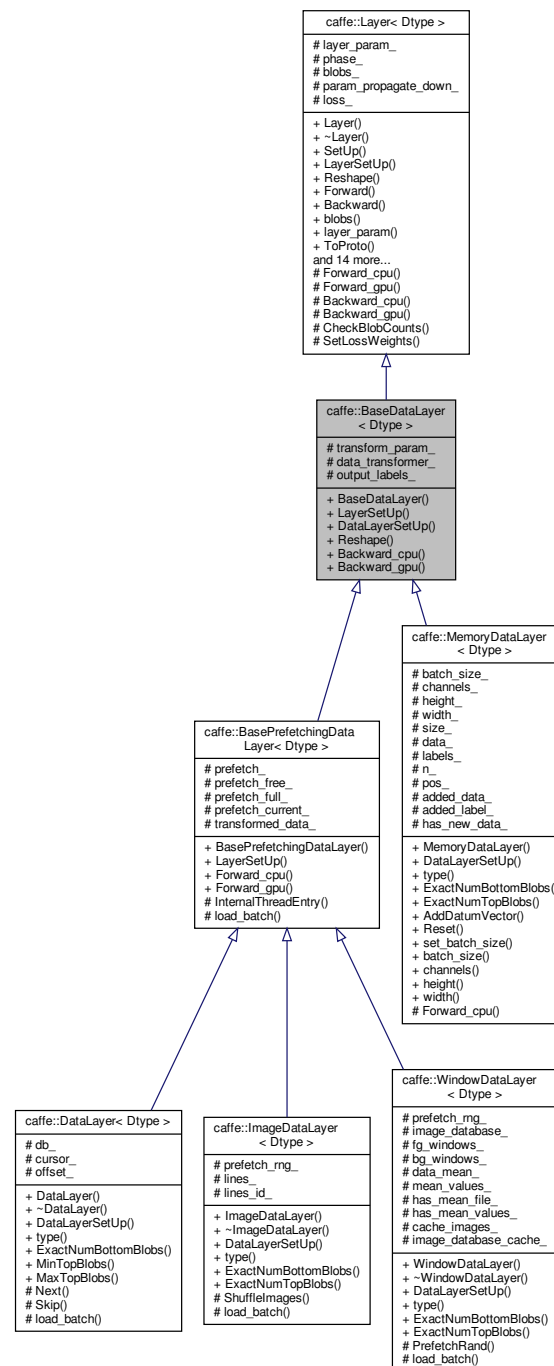
- include/caffe/layers/base\_conv\_layer.hpp
- src/caffe/layers/base\_conv\_layer.cpp

## 5.8 caffe::BaseDataLayer< Dtype > Class Template Reference

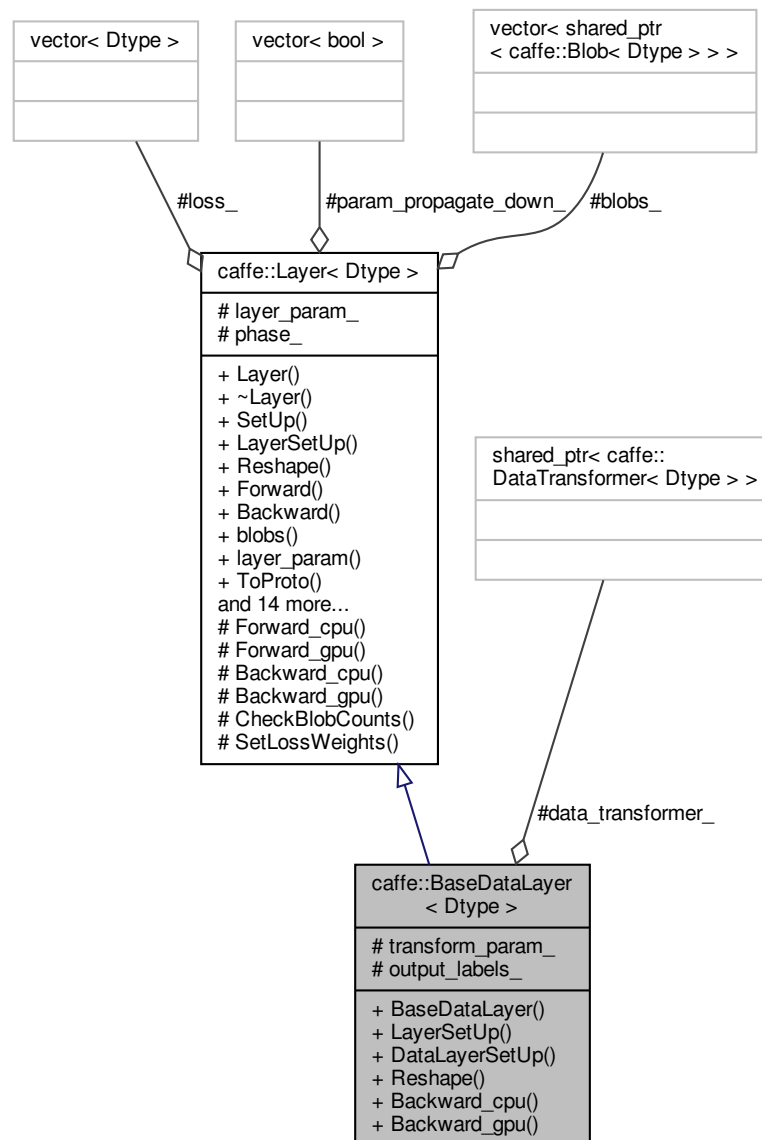
Provides base for data layers that feed blobs to the [Net](#).

```
#include <base_data_layer.hpp>
```

Inheritance diagram for caffe::BaseDataLayer< Dtype >:



Collaboration diagram for `caffe::BaseDataLayer< Dtype >`:



## Public Member Functions

- **BaseDataLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **DataLayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual void **Backward\_cpu** (const vector< Blob< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< Blob< Dtype > \* > &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

*Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- TransformationParameter **transform\_param\_**
- shared\_ptr< [DataTransformer](#)< Dtype > > **data\_transformer\_**
- bool **output\_labels\_**

## Additional Inherited Members

### 5.8.1 Detailed Description

```
template<typename Dtype>
class caffe::BaseDataLayer< Dtype >
```

Provides base for data layers that feed blobs to the [Net](#).

TODO(dox): thorough documentation for Forward and proto params.

### 5.8.2 Member Function Documentation

#### 5.8.2.1 LayerSetUp()

```
template<typename Dtype >
void caffe::BaseDataLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

#### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

Reimplemented in [caffe::BasePrefetchingDataLayer< Dtype >](#).

### 5.8.2.2 Reshape()

```
template<typename Dtype >
virtual void caffe::BaseDataLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [inline], [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

#### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements `caffe::Layer< Dtype >`.

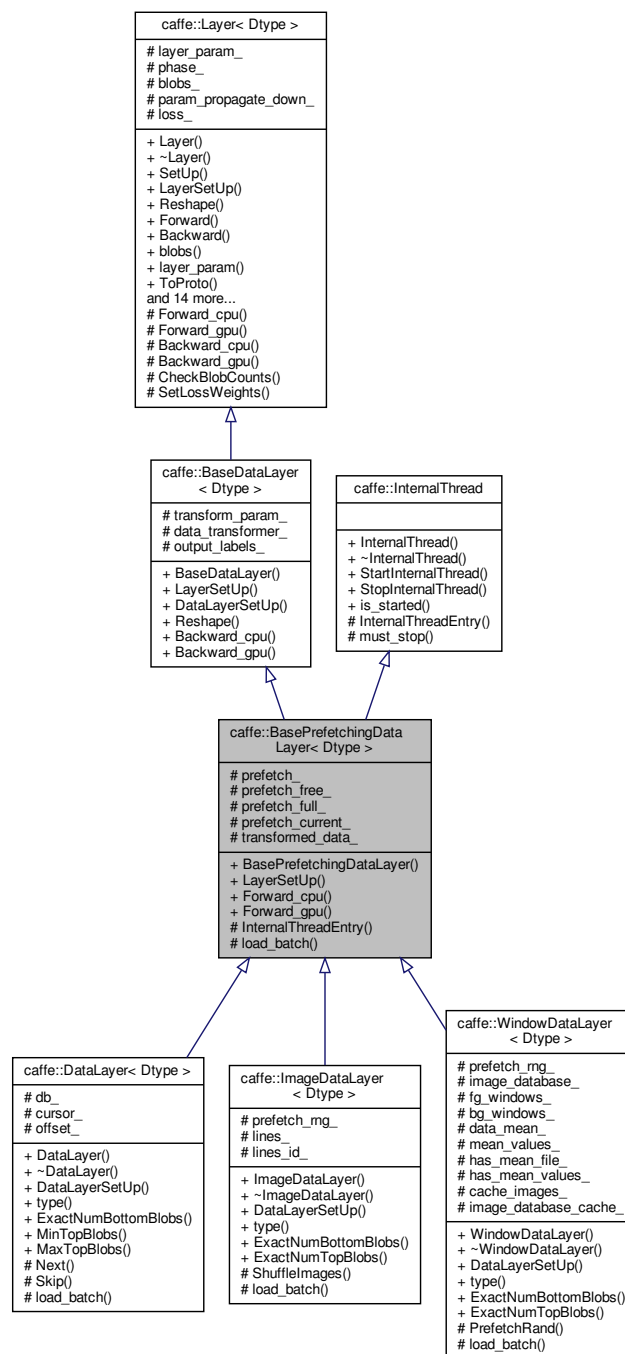
The documentation for this class was generated from the following files:

- `include/caffe/layers/base_data_layer.hpp`
- `src/caffe/layers/base_data_layer.cpp`

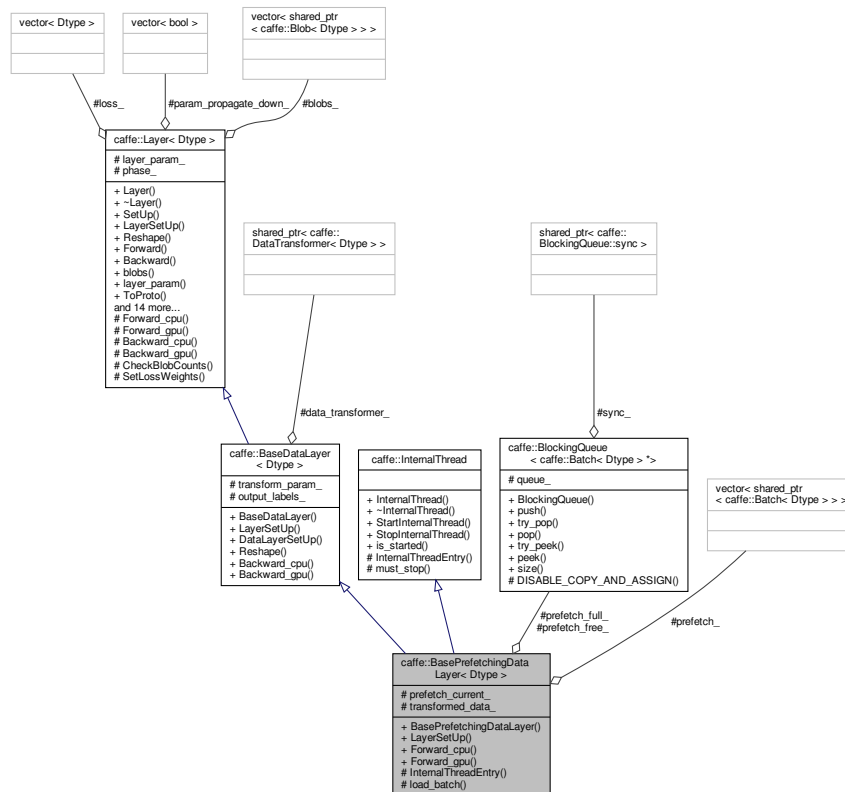


## 5.9 caffe::BasePrefetchingDataLayer&lt; Dtype &gt; Class Template Reference

Inheritance diagram for caffe::BasePrefetchingDataLayer< Dtype > :



Collaboration diagram for `caffe::BasePrefetchingDataLayer< Dtype >`:



## Public Member Functions

- **BasePrefetchingDataLayer** (const LayerParameter &param)
- void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Forward\_cpu** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Using the CPU device, compute the layer output.*
- virtual void **Forward\_gpu** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to **Forward\_cpu()** if unavailable.*

## Protected Member Functions

- virtual void **InternalThreadEntry** ()
- virtual void **load\_batch** (Batch< Dtype > \*batch)=0

## Protected Attributes

- vector< shared\_ptr< Batch< Dtype > > > **prefetch\_**
- BlockingQueue< Batch< Dtype > \* > **prefetch\_free\_**
- BlockingQueue< Batch< Dtype > \* > **prefetch\_full\_**
- Batch< Dtype > \* **prefetch\_current\_**
- Blob< Dtype > **transformed\_data\_**

### 5.9.1 Member Function Documentation

#### 5.9.1.1 `LayerSetUp()`

```
template<typename Dtype >
void caffe::BasePrefetchingDataLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

#### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

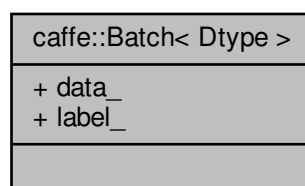
Reimplemented from `caffe::BaseDataLayer< Dtype >`.

The documentation for this class was generated from the following files:

- `include/caffe/layers/base_data_layer.hpp`
- `src/caffe/layers/base_data_layer.cpp`

## 5.10 `caffe::Batch< Dtype >` Class Template Reference

Collaboration diagram for `caffe::Batch< Dtype >`:



## Public Attributes

- [Blob](#)< Dtype > **data\_**
- [Blob](#)< Dtype > **label\_**

The documentation for this class was generated from the following file:

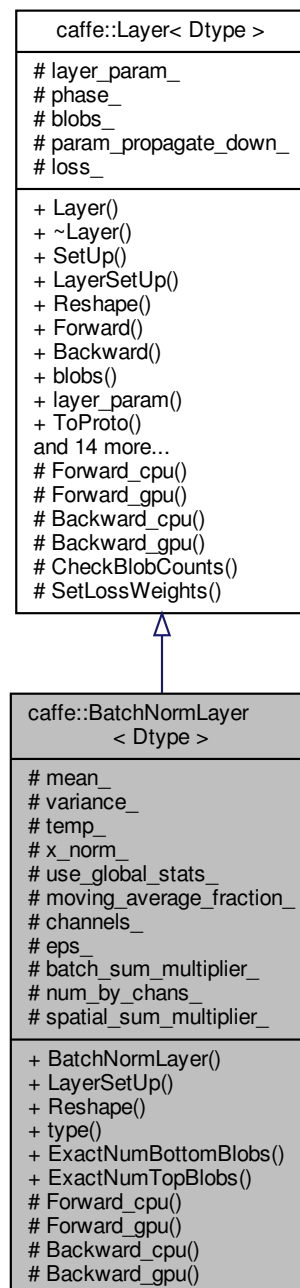
- include/caffe/layers/base\_data\_layer.hpp

## 5.11 `caffe::BatchNormLayer< Dtype >` Class Template Reference

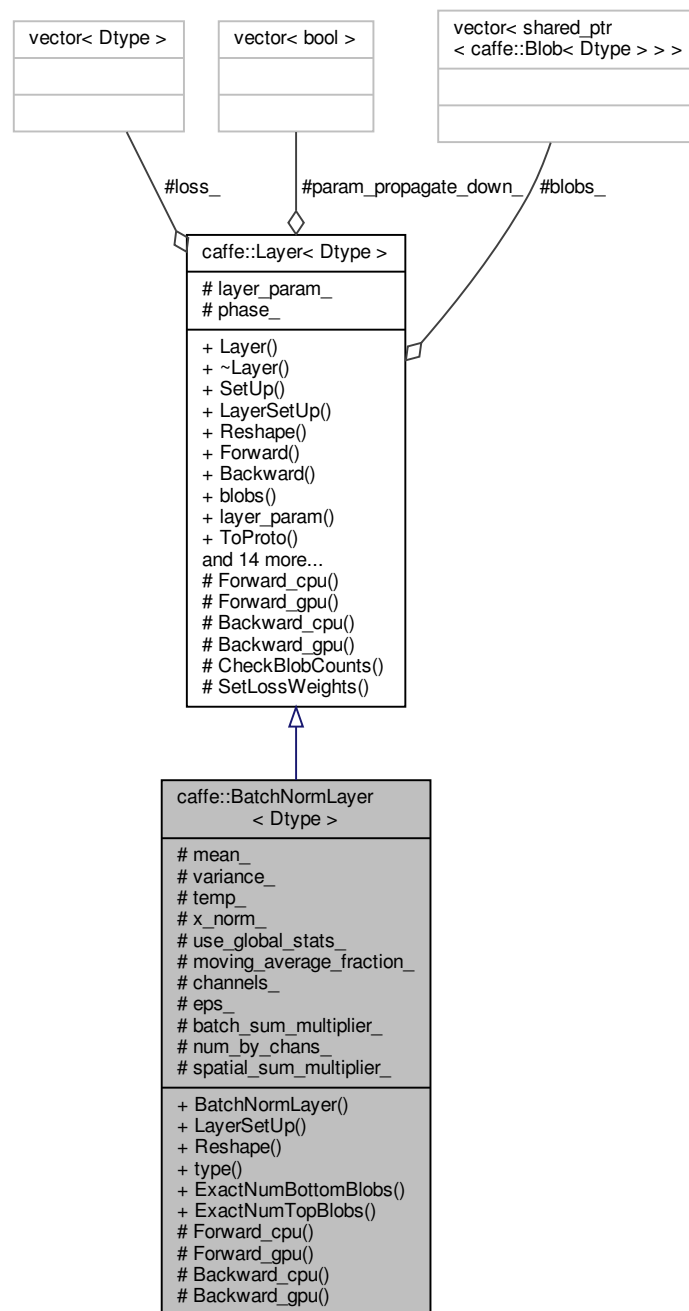
Normalizes the input to have 0-mean and/or unit (1) variance across the batch.

```
#include <batch_norm_layer.hpp>
```

Inheritance diagram for caffe::BatchNormLayer< Dtype >:



Collaboration diagram for `caffe::BatchNormLayer< Dtype >`:



## Public Member Functions

- **BatchNormLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*

- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

### Protected Member Functions

- virtual void **Forward\_cpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Using the CPU device, compute the layer output.*
- virtual void **Forward\_gpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to **Forward\_cpu()** if unavailable.*
- virtual void **Backward\_cpu** (const vector< **Blob**< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< **Blob**< Dtype > \* > &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void **Backward\_gpu** (const vector< **Blob**< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< **Blob**< Dtype > \* > &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to **Backward\_cpu()** if unavailable.*

### Protected Attributes

- **Blob**< Dtype > **mean\_**
- **Blob**< Dtype > **variance\_**
- **Blob**< Dtype > **temp\_**
- **Blob**< Dtype > **x\_norm\_**
- bool **use\_global\_stats\_**
- Dtype **moving\_average\_fraction\_**
- int **channels\_**
- Dtype **eps\_**
- **Blob**< Dtype > **batch\_sum\_multiplier\_**
- **Blob**< Dtype > **num\_by\_chans\_**
- **Blob**< Dtype > **spatial\_sum\_multiplier\_**

#### 5.11.1 Detailed Description

```
template<typename Dtype>
class caffe::BatchNormLayer< Dtype >
```

Normalizes the input to have 0-mean and/or unit (1) variance across the batch.

This layer computes **Batch** Normalization as described in [1]. For each channel in the data (i.e. axis 1), it subtracts the mean and divides by the variance, where both statistics are computed across both spatial dimensions and across the different examples in the batch.

By default, during training time, the network is computing global mean/variance statistics via a running average, which is then used at test time to allow deterministic outputs for each input. You can manually toggle whether the

network is accumulating or using the statistics via the `use_global_stats` option. For reference, these statistics are kept in the layer's three blobs: (0) mean, (1) variance, and (2) moving average factor.

Note that the original paper also included a per-channel learned bias and scaling factor. To implement this in [Caffe](#), define a [ScaleLayer](#) configured with `bias_term: true` after each [BatchNormLayer](#) to handle both the bias and scaling factor.

[1] S. Ioffe and C. Szegedy, "Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift." arXiv preprint arXiv:1502.03167 (2015).

TODO(dox): thorough documentation for Forward, Backward, and proto params.

## 5.11.2 Member Function Documentation

### 5.11.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::BatchNormLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.11.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::BatchNormLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.11.2.3 LayerSetUp()

```
template<typename Dtype >
void caffe::BatchNormLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.



## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from `caffe::Layer< Dtype >`.

5.11.2.4 `Reshape()`

```
template<typename Dtype >
void caffe::BatchNormLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following files:

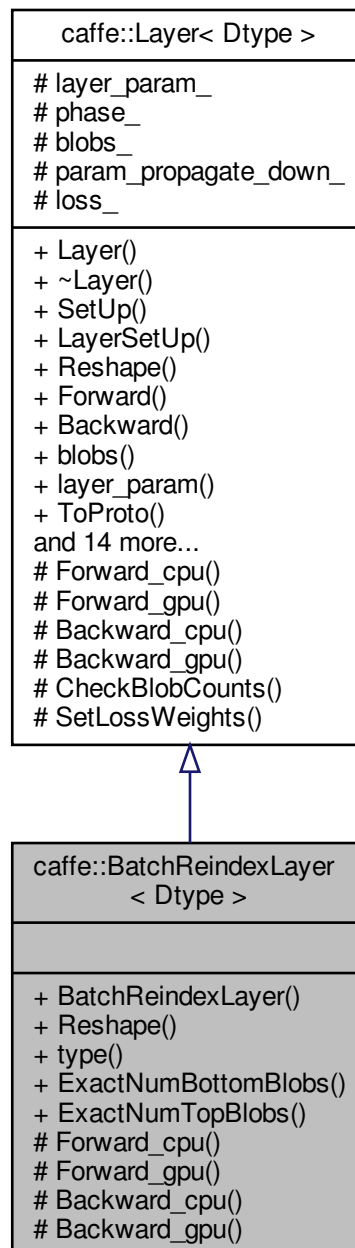
- `include/caffe/layers/batch_norm_layer.hpp`
- `src/caffe/layers/batch_norm_layer.cpp`

5.12 `caffe::BatchReindexLayer< Dtype >` Class Template Reference

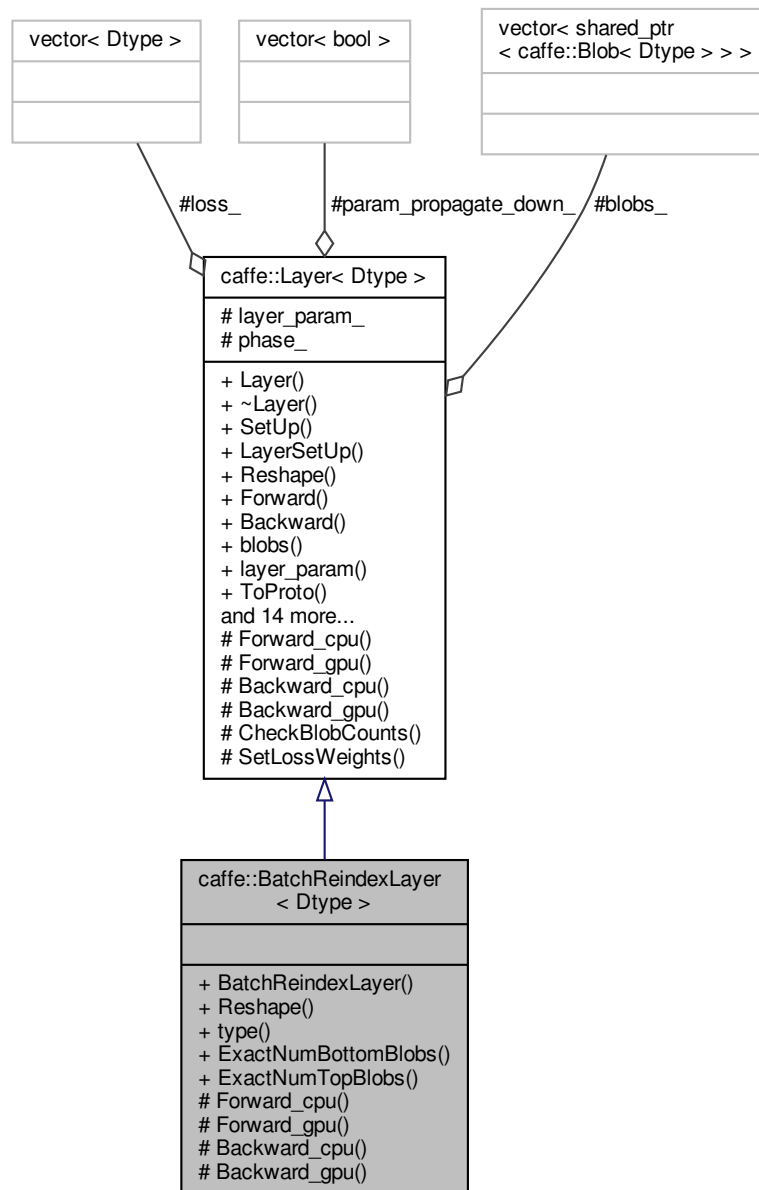
Index into the input blob along its first axis.

```
#include <batch_reindex_layer.hpp>
```

Inheritance diagram for `caffe::BatchReindexLayer< Dtype >`:



Collaboration diagram for caffe::BatchReindexLayer< Dtype >:



## Public Member Functions

- **BatchReindexLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the error gradient w.r.t. the reordered input.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Additional Inherited Members

### 5.12.1 Detailed Description

```
template<typename Dtype>
class caffe::BatchReindexLayer< Dtype >
```

Index into the input blob along its first axis.

This layer can be used to select, reorder, and even replicate examples in a batch. The second blob is cast to int and treated as an index into the first axis of the first blob.

### 5.12.2 Member Function Documentation

#### 5.12.2.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::BatchReindexLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the reordered input.

#### Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(M \times \dots)$ : containing error gradients $\frac{\partial E}{\partial y}$ with respect to concatenated outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 2): <ul style="list-style-type: none"> <li>• <math>\frac{\partial E}{\partial y}</math> is de-indexed (summing where required) back to the input <math>x_1</math></li> </ul>
	<ul style="list-style-type: none"> <li>• This layer cannot backprop to <math>x_2</math>, i.e. <code>propagate_down[1]</code> must be false.</li> </ul>

Implements `caffe::Layer< Dtype >`.

#### 5.12.2.2 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::BatchReindexLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.12.2.3 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::BatchReindexLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.12.2.4 `Forward_cpu()`

```
template<typename Dtype >
void caffe::BatchReindexLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

##### Parameters

<i>bottom</i>	input <code>Blob</code> vector (length 2+) <ol style="list-style-type: none"> <li>1. <math>(N \times \dots)</math> the inputs <math>x_1</math></li> <li>2. <math>(M)</math> the inputs <math>x_2</math></li> </ol>
<i>top</i>	output <code>Blob</code> vector (length 1) <ol style="list-style-type: none"> <li>1. <math>(M \times \dots)</math>: the reindexed array <math>y = x_1[x_2]</math></li> </ol>

Implements `caffe::Layer< Dtype >`.

### 5.12.2.5 Reshape()

```
template<typename Dtype >
void caffe::BatchReindexLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

#### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

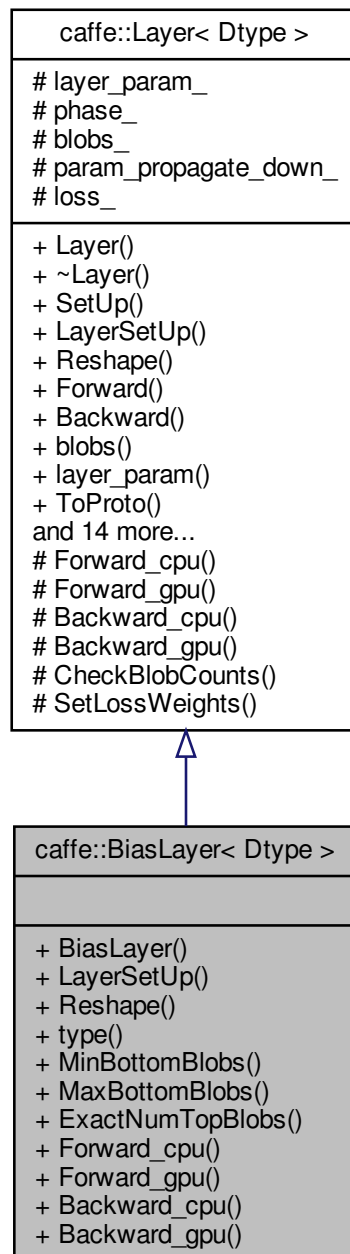
- include/caffe/layers/batch\_reindex\_layer.hpp
- src/caffe/layers/batch\_reindex\_layer.cpp

## 5.13 caffe::BiasLayer< Dtype > Class Template Reference

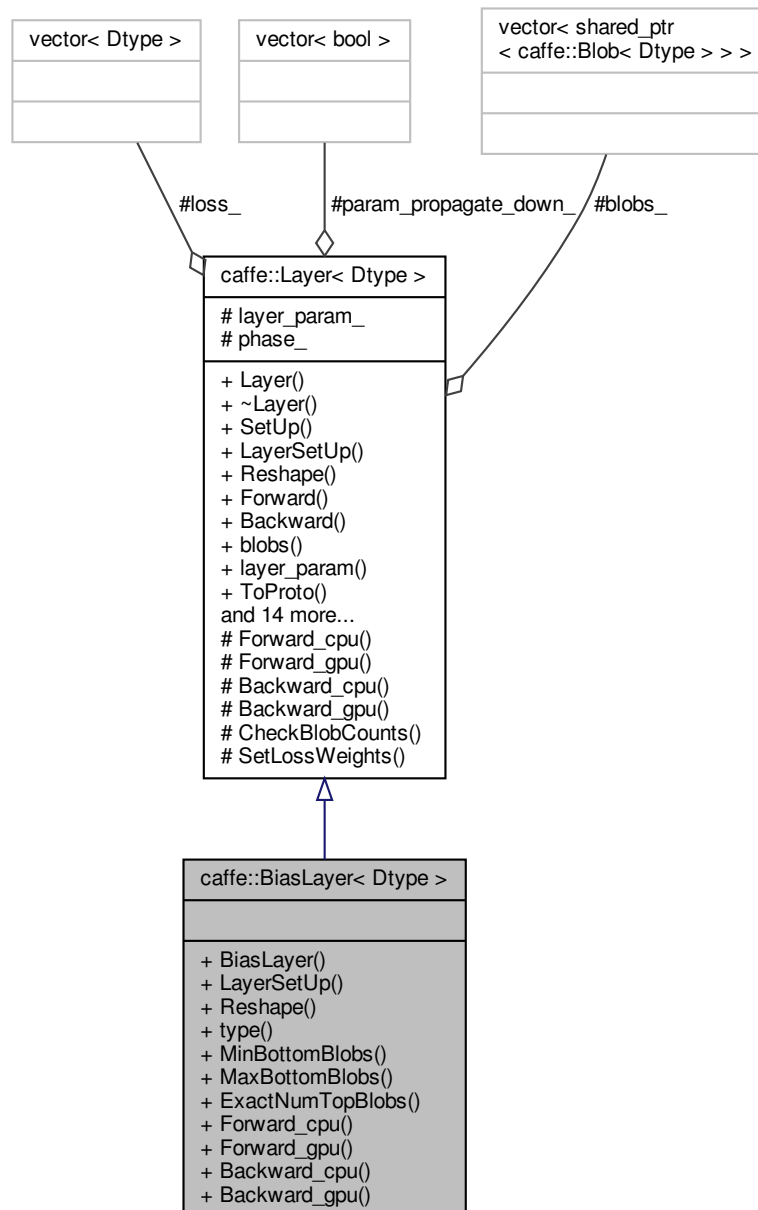
Computes a sum of two input Blobs, with the shape of the latter [Blob](#) "broadcast" to match the shape of the former. Equivalent to tiling the latter [Blob](#), then computing the elementwise sum.

```
#include <bias_layer.hpp>
```

Inheritance diagram for caffe::BiasLayer< Dtype >:



Collaboration diagram for `caffe::BiasLayer< Dtype >`:



## Public Member Functions

- **BiasLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as *Reshape*.
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.
- virtual const char \* **type** () const  
Returns the layer type.



- virtual int [MinBottomBlobs](#) () const  
*Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.*
- virtual int [MaxBottomBlobs](#) () const  
*Returns the maximum number of bottom blobs required by the layer, or -1 if no maximum number is required.*
- virtual int [ExactNumTopBlobs](#) () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*
- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Additional Inherited Members

### 5.13.1 Detailed Description

```
template<typename Dtype>
class caffe::BiasLayer< Dtype >
```

Computes a sum of two input Blobs, with the shape of the latter [Blob](#) "broadcast" to match the shape of the former. Equivalent to tiling the latter [Blob](#), then computing the elementwise sum.

The second input may be omitted, in which case it's learned as a parameter of the layer. Note: in case bias and scaling are desired, both operations can be handled by [ScaleLayer](#) configured with `bias_term: true`.

### 5.13.2 Member Function Documentation

#### 5.13.2.1 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::BiasLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.13.2.2 LayerSetUp()

```
template<typename Dtype >
void caffe::BiasLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from `caffe::Layer< Dtype >`.

5.13.2.3 `MaxBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::BiasLayer< Dtype >::MaxBottomBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of bottom blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.13.2.4 `MinBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::BiasLayer< Dtype >::MinBottomBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.13.2.5 `Reshape()`

```
template<typename Dtype >
void caffe::BiasLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

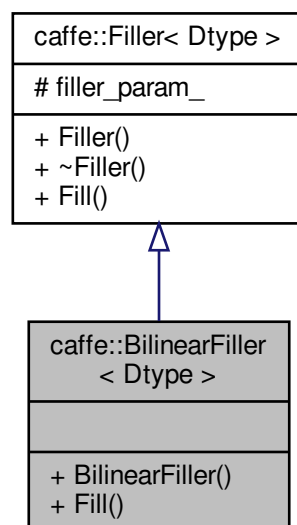
- include/caffe/layers/bias\_layer.hpp
- src/caffe/layers/bias\_layer.cpp

## 5.14 [caffe::BilinearFiller< Dtype >](#) Class Template Reference

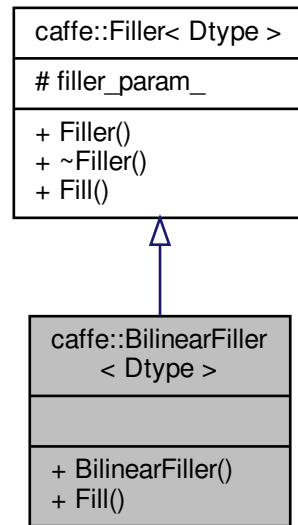
Fills a [Blob](#) with coefficients for bilinear interpolation.

```
#include <filler.hpp>
```

Inheritance diagram for [caffe::BilinearFiller< Dtype >](#):



Collaboration diagram for caffe::BilinearFiller< Dtype >:



## Public Member Functions

- **BilinearFiller** (const FillerParameter &param)
- virtual void **Fill** ([Blob](#)< Dtype > \*blob)

## Additional Inherited Members

### 5.14.1 Detailed Description

```
template<typename Dtype>
class caffe::BilinearFiller< Dtype >
```

Fills a [Blob](#) with coefficients for bilinear interpolation.

A common use case is with the [DeconvolutionLayer](#) acting as upsampling. You can upsample a feature map with shape of (B, C, H, W) by any integer factor using the following proto.

```
layer {
  name: "upsample", type: "Deconvolution"
  bottom: "{{bottom_name}}" top: "{{top_name}}"
  convolution_param {
    kernel_size: {{2 * factor - factor % 2}} stride: {{factor}}
    num_output: {{C}} group: {{C}}
    pad: {{ceil((factor - 1) / 2.0)}}
    weight_filler: { type: "bilinear" } bias_term: false
  }
  param { lr_mult: 0 decay_mult: 0 }
}
```

Please use this by replacing `{{}}` with your values. By specifying `num_output: {{C}}` `group: {{C}}`, it behaves as channel-wise convolution. The filter shape of this deconvolution layer will be  $(C, 1, K, K)$  where  $K$  is `kernel_size`, and this filler will set a  $(K, K)$  interpolation kernel for every channel of the filter identically. The resulting shape of the top feature map will be  $(B, C, \text{factor} * H, \text{factor} * W)$ . Note that the learning rate and the weight decay are set to 0 in order to keep coefficient values of bilinear interpolation unchanged during training. If you apply this to an image, this operation is equivalent to the following call in Python with Scikit.Image.

```
out = skimage.transform.rescale(img, factor, mode='constant', cval=0)
```

The documentation for this class was generated from the following file:

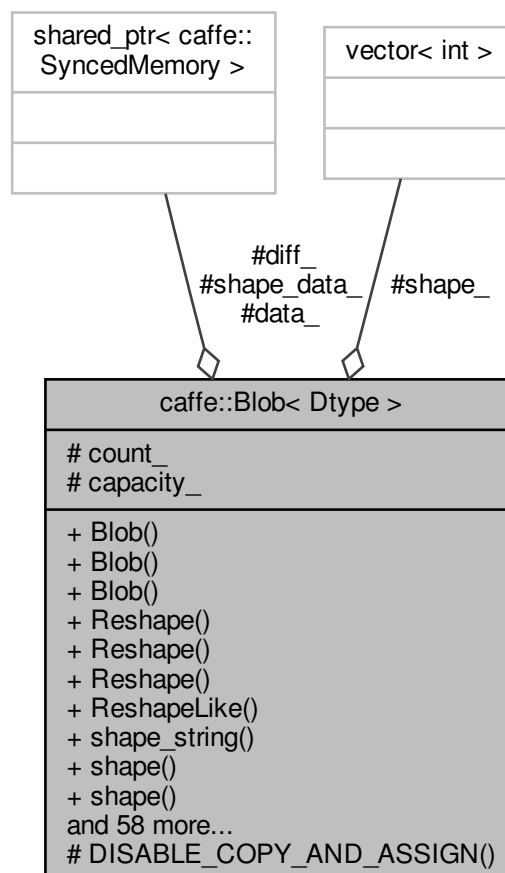
- `include/caffe/filler.hpp`

## 5.15 `caffe::Blob< Dtype >` Class Template Reference

A wrapper around [SyncedMemory](#) holders serving as the basic computational unit through which [Layers](#), [Nets](#), and [Solvers](#) interact.

```
#include <blob.hpp>
```

Collaboration diagram for `caffe::Blob< Dtype >`:



## Public Member Functions

- **Blob** (const int **num**, const int **channels**, const int **height**, const int **width**)  
*Deprecated; use `Blob(const vector<int>& shape)`.*
- **Blob** (const vector< int > &shape)
- void **Reshape** (const int **num**, const int **channels**, const int **height**, const int **width**)  
*Deprecated; use `Reshape(const vector<int>& shape)`.*
- void **Reshape** (const vector< int > &shape)  
*Change the dimensions of the blob, allocating new memory if necessary.*
- void **Reshape** (const BlobShape &shape)
- void **ReshapeLike** (const **Blob** &other)
- string **shape\_string** () const
- const vector< int > &**shape** () const
- int **shape** (int index) const  
*Returns the dimension of the index-th axis (or the negative index-th axis from the end, if index is negative).*
- int **num\_axes** () const
- int **count** () const
- int **count** (int start\_axis, int end\_axis) const  
*Compute the volume of a slice; i.e., the product of dimensions among a range of axes.*
- int **count** (int start\_axis) const  
*Compute the volume of a slice spanning from a particular first axis to the final axis.*
- int **CanonicalAxisIndex** (int axis\_index) const  
*Returns the 'canonical' version of a (usually) user-specified axis, allowing for negative indexing (e.g., -1 for the last axis).*
- int **num** () const  
*Deprecated legacy shape accessor num: use `shape(0)` instead.*
- int **channels** () const  
*Deprecated legacy shape accessor channels: use `shape(1)` instead.*
- int **height** () const  
*Deprecated legacy shape accessor height: use `shape(2)` instead.*
- int **width** () const  
*Deprecated legacy shape accessor width: use `shape(3)` instead.*
- int **LegacyShape** (int index) const
- int **offset** (const int n, const int c=0, const int h=0, const int w=0) const
- int **offset** (const vector< int > &indices) const
- void **CopyFrom** (const **Blob**< Dtype > &source, bool copy\_diff=false, bool reshape=false)  
*Copy from a source `Blob`.*
- Dtype **data\_at** (const int n, const int c, const int h, const int w) const
- Dtype **diff\_at** (const int n, const int c, const int h, const int w) const
- Dtype **data\_at** (const vector< int > &index) const
- Dtype **diff\_at** (const vector< int > &index) const
- const shared\_ptr< **SyncedMemory** > &**data** () const
- const shared\_ptr< **SyncedMemory** > &**diff** () const
- const Dtype \* **cpu\_data** () const
- void **set\_cpu\_data** (Dtype \*data)
- const int \* **gpu\_shape** () const
- const Dtype \* **gpu\_data** () const
- void **set\_gpu\_data** (Dtype \*data)
- const Dtype \* **cpu\_diff** () const
- const Dtype \* **gpu\_diff** () const
- Dtype \* **mutable\_cpu\_data** ()
- Dtype \* **mutable\_gpu\_data** ()
- Dtype \* **mutable\_cpu\_diff** ()

- `Dtype * mutable_gpu_diff ()`
- `void Update ()`
- `void FromProto (const BlobProto &proto, bool reshape=true)`
- `void ToProto (BlobProto *proto, bool write_diff=false) const`
- `Dtype asum_data () const`  
*Compute the sum of absolute values (L1 norm) of the data.*
- `Dtype asum_diff () const`  
*Compute the sum of absolute values (L1 norm) of the diff.*
- `Dtype sumsq_data () const`  
*Compute the sum of squares (L2 norm squared) of the data.*
- `Dtype sumsq_diff () const`  
*Compute the sum of squares (L2 norm squared) of the diff.*
- `void scale_data (Dtype scale_factor)`  
*Scale the blob data by a constant factor.*
- `void scale_diff (Dtype scale_factor)`  
*Scale the blob diff by a constant factor.*
- `void ShareData (const Blob &other)`  
*Set the data\_shared\_ptr to point to the SyncedMemory holding the data\_ of Blob other – useful in Layers which simply perform a copy in their Forward pass.*
- `void ShareDiff (const Blob &other)`  
*Set the diff\_shared\_ptr to point to the SyncedMemory holding the diff\_ of Blob other – useful in Layers which simply perform a copy in their Forward pass.*
- `bool ShapeEquals (const BlobProto &other)`
- `template<>`  
`void Update ()`
- `template<>`  
`void Update ()`
- `template<>`  
`unsigned int asum_data () const`
- `template<>`  
`int asum_data () const`
- `template<>`  
`unsigned int asum_diff () const`
- `template<>`  
`int asum_diff () const`
- `template<>`  
`unsigned int sumsq_data () const`
- `template<>`  
`int sumsq_data () const`
- `template<>`  
`unsigned int sumsq_diff () const`
- `template<>`  
`int sumsq_diff () const`
- `template<>`  
`void scale_data (unsigned int scale_factor)`
- `template<>`  
`void scale_data (int scale_factor)`
- `template<>`  
`void scale_diff (unsigned int scale_factor)`
- `template<>`  
`void scale_diff (int scale_factor)`
- `template<>`  
`void ToProto (BlobProto *proto, bool write_diff) const`
- `template<>`  
`void ToProto (BlobProto *proto, bool write_diff) const`



## Protected Member Functions

- **DISABLE\_COPY\_AND\_ASSIGN** ([Blob](#))

## Protected Attributes

- shared\_ptr< [SyncedMemory](#) > **data\_**
- shared\_ptr< [SyncedMemory](#) > **diff\_**
- shared\_ptr< [SyncedMemory](#) > **shape\_data\_**
- vector< int > **shape\_**
- int **count\_**
- int **capacity\_**

### 5.15.1 Detailed Description

```
template<typename Dtype>
class caffe::Blob< Dtype >
```

A wrapper around [SyncedMemory](#) holders serving as the basic computational unit through which [Layers](#), [Nets](#), and [Solvers](#) interact.

TODO(dox): more thorough description.

### 5.15.2 Member Function Documentation

#### 5.15.2.1 CanonicalAxisIndex()

```
template<typename Dtype>
int caffe::Blob< Dtype >::CanonicalAxisIndex (
    int axis_index ) const [inline]
```

Returns the 'canonical' version of a (usually) user-specified axis, allowing for negative indexing (e.g., -1 for the last axis).

#### Parameters

<i>axis_index</i>	the axis index. If $0 \leq \text{index} < \text{num\_axes}()$ , return index. If $-\text{num\_axes} \leq \text{index} \leq -1$ , return $(\text{num\_axes}() - (-\text{index}))$ , e.g., the last axis index $(\text{num\_axes}() - 1)$ if index == -1, the second to last if index == -2, etc. Dies on out of range index.
-------------------	---

#### 5.15.2.2 CopyFrom()

```
template<typename Dtype>
void caffe::Blob< Dtype >::CopyFrom (
```

```
const Blob< Dtype > & source,
bool copy_diff = false,
bool reshape = false )
```

Copy from a source [Blob](#).

#### Parameters

<i>source</i>	the <a href="#">Blob</a> to copy from
<i>copy_diff</i>	if false, copy the data; if true, copy the diff
<i>reshape</i>	if false, require this <a href="#">Blob</a> to be pre-shaped to the shape of other (and die otherwise); if true, Reshape this <a href="#">Blob</a> to other's shape if necessary

#### 5.15.2.3 count() [1/2]

```
template<typename Dtype>
int caffe::Blob< Dtype >::count (
    int start_axis,
    int end_axis ) const [inline]
```

Compute the volume of a slice; i.e., the product of dimensions among a range of axes.

#### Parameters

<i>start_axis</i>	The first axis to include in the slice.
<i>end_axis</i>	The first axis to exclude from the slice.

#### 5.15.2.4 count() [2/2]

```
template<typename Dtype>
int caffe::Blob< Dtype >::count (
    int start_axis ) const [inline]
```

Compute the volume of a slice spanning from a particular first axis to the final axis.

#### Parameters

<i>start_axis</i>	The first axis to include in the slice.
-------------------	---

#### 5.15.2.5 Reshape()

```
template<typename Dtype >
void caffe::Blob< Dtype >::Reshape (
    const vector< int > & shape )
```

Change the dimensions of the blob, allocating new memory if necessary.

This function can be called both to create an initial allocation of memory, and to adjust the dimensions of a top blob during `Layer::Reshape` or `Layer::Forward`. When changing the size of blob, memory will only be reallocated if sufficient memory does not already exist, and excess memory will never be freed.

Note that reshaping an input blob and immediately calling `Net::Backward` is an error; either `Net::Forward` or `Net::Reshape` need to be called to propagate the new input shape to higher layers.

#### 5.15.2.6 `shape()`

```
template<typename Dtype>
int caffe::Blob< Dtype >::shape (
    int index ) const [inline]
```

Returns the dimension of the index-th axis (or the negative index-th axis from the end, if index is negative).

##### Parameters

<i>index</i>	the axis index, which may be negative as it will be "canonicalized" using <code>CanonicalAxisIndex</code> . Dies on out of range index.
--------------	---

#### 5.15.2.7 `ShareData()`

```
template<typename Dtype >
void caffe::Blob< Dtype >::ShareData (
    const Blob< Dtype > & other )
```

Set the `data_` `shared_ptr` to point to the `SyncedMemory` holding the `data_` of `Blob` `other` – useful in `Layers` which simply perform a copy in their Forward pass.

This deallocates the `SyncedMemory` holding this `Blob`'s `data_`, as `shared_ptr` calls its destructor when reset with the "=" operator.

#### 5.15.2.8 `ShareDiff()`

```
template<typename Dtype >
void caffe::Blob< Dtype >::ShareDiff (
    const Blob< Dtype > & other )
```

Set the `diff_` `shared_ptr` to point to the `SyncedMemory` holding the `diff_` of `Blob` `other` – useful in `Layers` which simply perform a copy in their Forward pass.

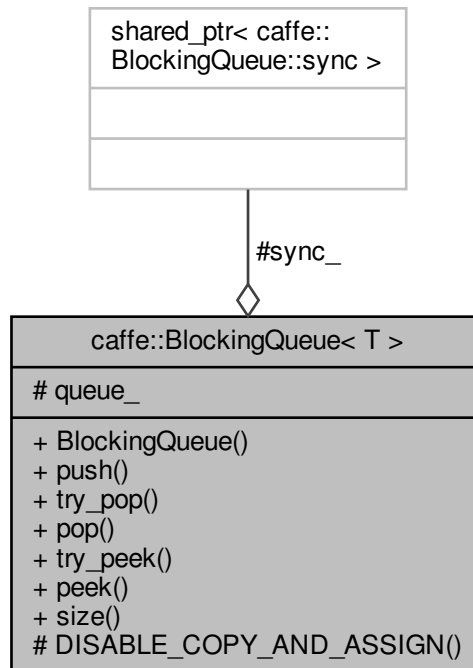
This deallocates the `SyncedMemory` holding this `Blob`'s `diff_`, as `shared_ptr` calls its destructor when reset with the "=" operator.

The documentation for this class was generated from the following files:

- `include/caffe/blob.hpp`
- `src/caffe/blob.cpp`

## 5.16 `caffe::BlockingQueue< T >` Class Template Reference

Collaboration diagram for `caffe::BlockingQueue< T >`:



### Classes

- class [sync](#)

### Public Member Functions

- void **push** (const T &t)
- bool **try\_pop** (T \*t)
- T **pop** (const string &log\_on\_wait="")
- bool **try\_peek** (T \*t)
- T **peek** ()
- size\_t **size** () const

### Protected Member Functions

- **DISABLE\_COPY\_AND\_ASSIGN** ([BlockingQueue](#))

### Protected Attributes

- `std::queue< T > queue_`
- `shared_ptr< sync > sync_`

The documentation for this class was generated from the following files:

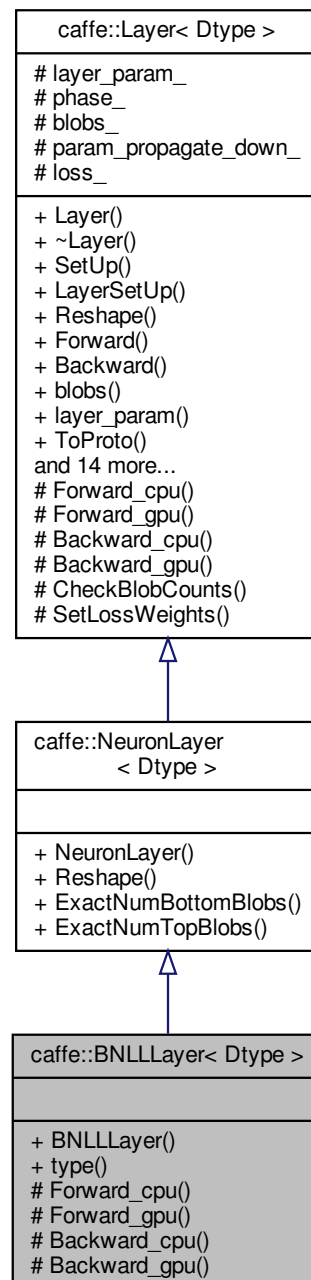
- `include/caffe/util/blocking_queue.hpp`
- `src/caffe/util/blocking_queue.cpp`

## 5.17 `caffe::BNLLayer< Dtype >` Class Template Reference

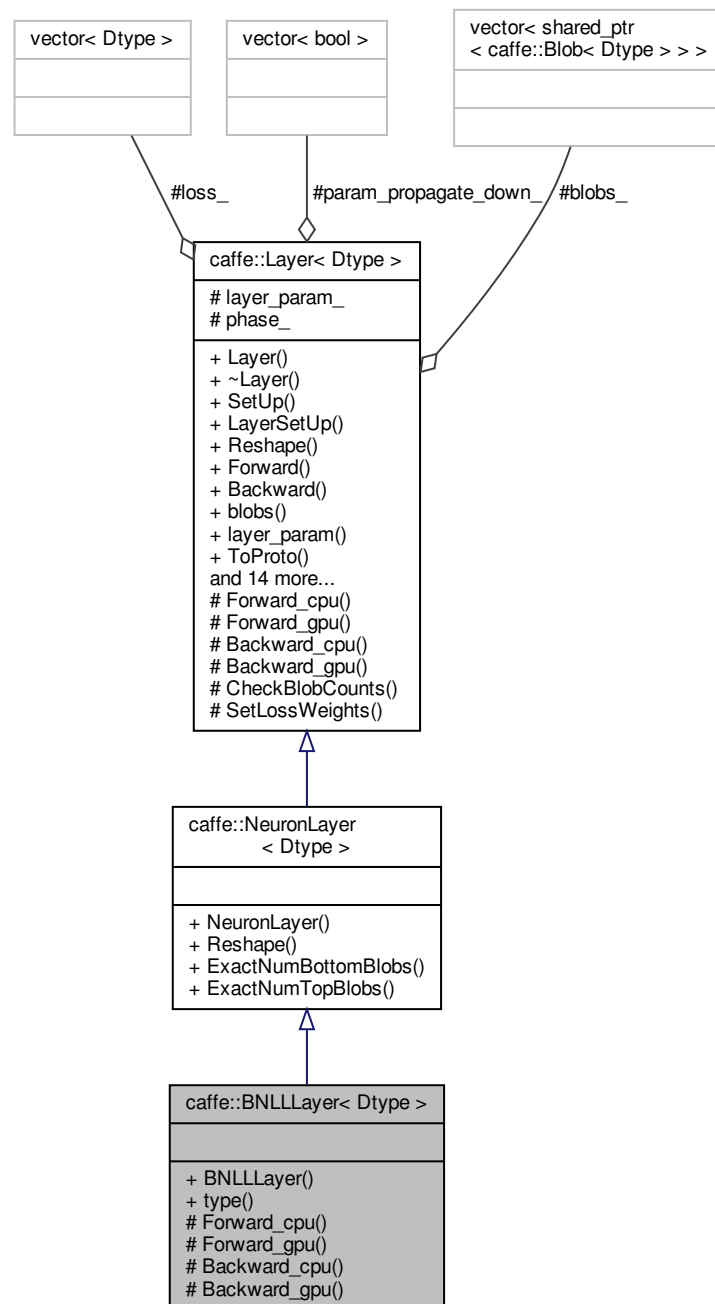
Computes  $y = x + \log(1 + \exp(-x))$  if  $x > 0$ ;  $y = \log(1 + \exp(x))$  otherwise.

```
#include <bnll_layer.hpp>
```

Inheritance diagram for `caffe::BNLLayer< Dtype >`:



Collaboration diagram for caffe::BNLLayer< Dtype >:



## Public Member Functions

- **BNLLayer** (const LayerParameter &param)
- virtual const char \* **type** () const

*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Computes  $y = x + \log(1 + \exp(-x))$  if  $x > 0$ ;  $y = \log(1 + \exp(x))$  otherwise.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Computes the error gradient w.r.t. the BNLL inputs.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Additional Inherited Members

### 5.17.1 Detailed Description

```
template<typename Dtype>
class caffe::BNLLayer< Dtype >
```

Computes  $y = x + \log(1 + \exp(-x))$  if  $x > 0$ ;  $y = \log(1 + \exp(x))$  otherwise.

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = \begin{cases} x + \log(1 + \exp(-x)) & \text{if } x > 0 \\ \log(1 + \exp(x)) & \text{otherwise} \end{cases}$

### 5.17.2 Member Function Documentation

#### 5.17.2.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::BNLLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the BNLL inputs.



## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times H \times W)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) 1. $(N \times C \times H \times W)$ the inputs $x$ ; Backward fills their diff with gradients $\frac{\partial E}{\partial x}$ if <code>propagate_down[0]</code>

Implements [caffe::Layer< Dtype >](#).

## 5.17.2.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::BNLLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

Computes  $y = x + \log(1 + \exp(-x))$  if  $x > 0$ ;  $y = \log(1 + \exp(x))$  otherwise.

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = \begin{cases} x + \log(1 + \exp(-x)) & \text{if } x > 0 \\ \log(1 + \exp(x)) & \text{otherwise} \end{cases}$

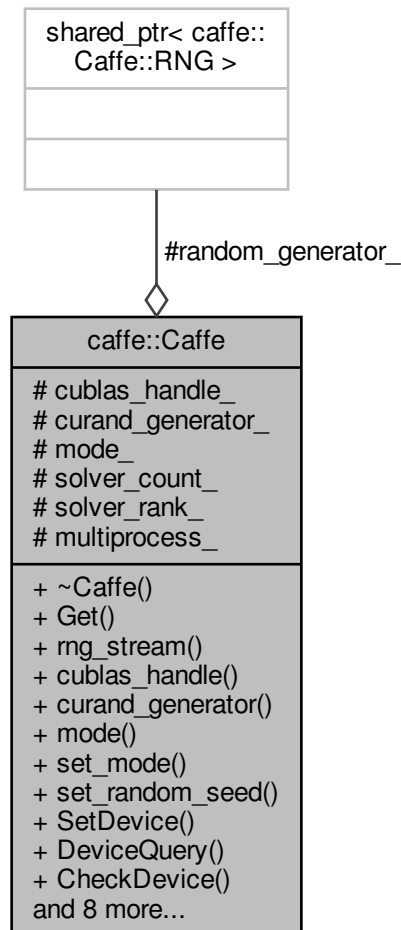
Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

- include/caffe/layers/bnll\_layer.hpp
- src/caffe/layers/bnll\_layer.cpp

## 5.18 caffe::Caffe Class Reference

Collaboration diagram for caffe::Caffe:



### Classes

- class [RNG](#)

### Public Types

- enum **Brew** { **CPU**, **GPU** }

### Static Public Member Functions

- static [Caffe](#) & **Get** ()
- static [RNG](#) & **rng\_stream** ()
- static cublasHandle\_t **cublas\_handle** ()
- static curandGenerator\_t **curand\_generator** ()
- static Brew **mode** ()
- static void **set\_mode** (Brew mode)
- static void **set\_random\_seed** (const unsigned int seed)
- static void **SetDevice** (const int device\_id)
- static void **DeviceQuery** ()
- static bool **CheckDevice** (const int device\_id)
- static int **FindDevice** (const int start\_id=0)
- static int **solver\_count** ()
- static void **set\_solver\_count** (int val)
- static int **solver\_rank** ()
- static void **set\_solver\_rank** (int val)
- static bool **multiprocess** ()
- static void **set\_multiprocess** (bool val)
- static bool **root\_solver** ()

### Protected Attributes

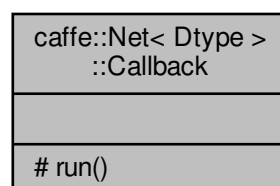
- cublasHandle\_t **cublas\_handle\_**
- curandGenerator\_t **curand\_generator\_**
- shared\_ptr< [RNG](#) > **random\_generator\_**
- Brew **mode\_**
- int **solver\_count\_**
- int **solver\_rank\_**
- bool **multiprocess\_**

The documentation for this class was generated from the following files:

- include/caffe/common.hpp
- src/caffe/common.cpp

## 5.19 caffe::Net< Dtype >::Callback Class Reference

Collaboration diagram for caffe::Net< Dtype >::Callback:



## Protected Member Functions

- virtual void **run** (int layer)=0

## Friends

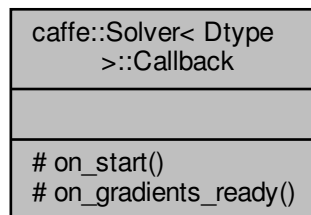
- template<typename T >  
class **Net**

The documentation for this class was generated from the following file:

- include/caffe/net.hpp

## 5.20 caffe::Solver< Dtype >::Callback Class Reference

Collaboration diagram for caffe::Solver< Dtype >::Callback:



## Protected Member Functions

- virtual void **on\_start** ()=0
- virtual void **on\_gradients\_ready** ()=0

## Friends

- template<typename T >  
class **Solver**

The documentation for this class was generated from the following file:

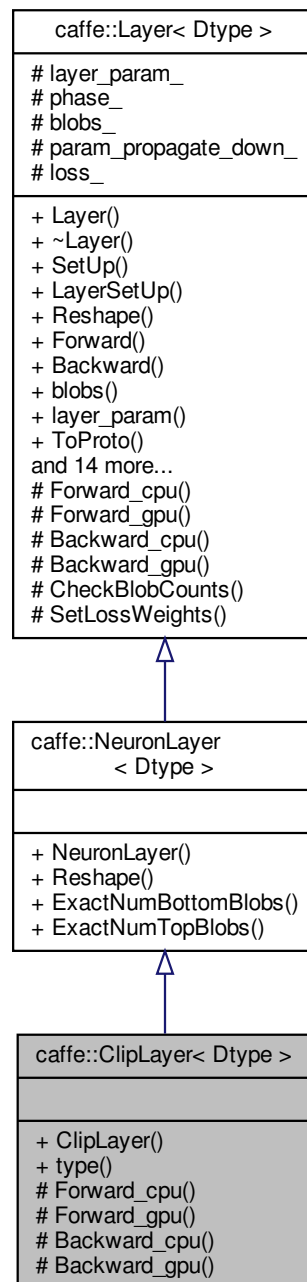
- include/caffe/solver.hpp

## 5.21 caffe::ClipLayer< Dtype > Class Template Reference

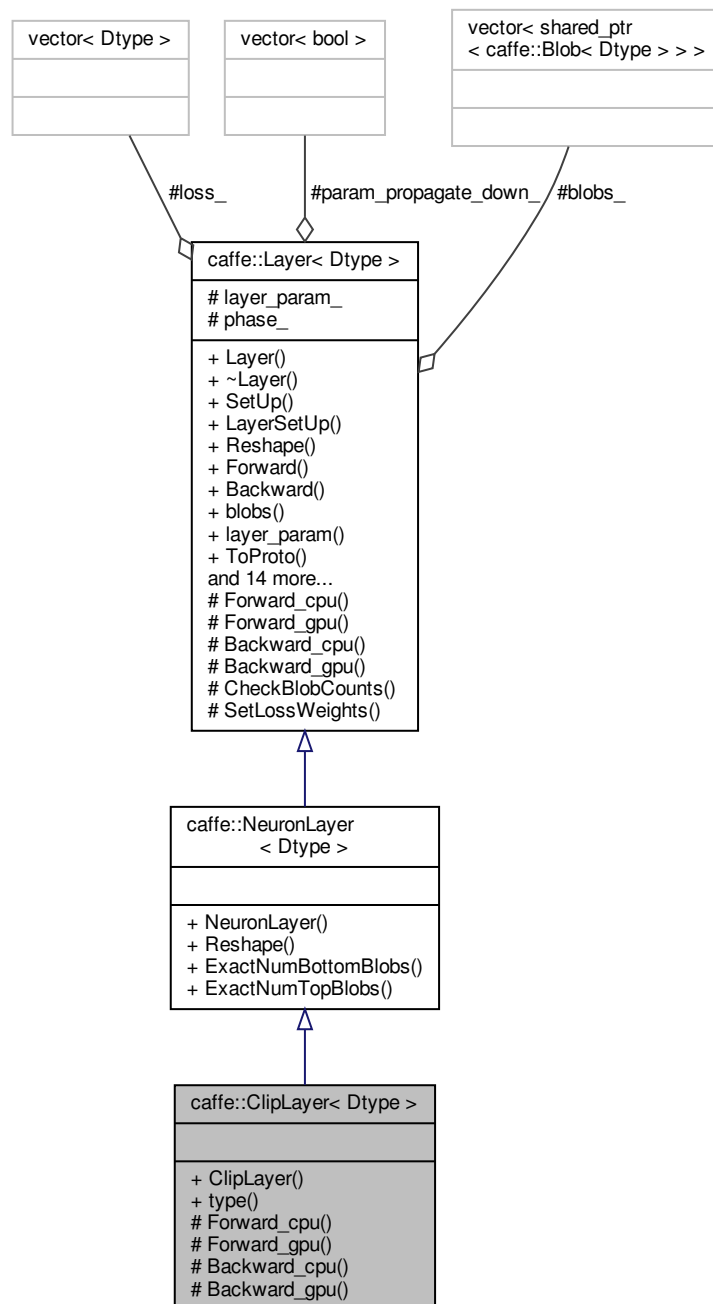
Clip:  $y = \max(\min, \min(\max, x))$ .

```
#include <clip_layer.hpp>
```

Inheritance diagram for caffe::ClipLayer< Dtype >:



Collaboration diagram for `caffe::ClipLayer< Dtype >`:



## Public Member Functions

- [ClipLayer](#) (const LayerParameter &param)
- virtual const char \* [type](#) () const

*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the error gradient w.r.t. the clipped inputs.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Additional Inherited Members

### 5.21.1 Detailed Description

```
template<typename Dtype>
class caffe::ClipLayer< Dtype >
```

Clip:  $y = \max(\min, \min(\max, x))$ .

### 5.21.2 Constructor & Destructor Documentation

#### 5.21.2.1 ClipLayer()

```
template<typename Dtype >
caffe::ClipLayer< Dtype >::ClipLayer (
    const LayerParameter & param ) [inline], [explicit]
```

#### Parameters

<i>param</i>	provides ClipParameter clip_param, with <a href="#">ClipLayer</a> options: <ul style="list-style-type: none"> <li>• min</li> <li>• max</li> </ul>
--------------	---

### 5.21.3 Member Function Documentation

## 5.21.3.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::ClipLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the clipped inputs.

## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times H \times W)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$ ; Backward fills their diff with gradients $\frac{\partial E}{\partial x} = \begin{cases} 0 & \text{if } x < \min \vee x > \max \\ \frac{\partial E}{\partial y} & \text{if } x \geq \min \wedge x \leq \max \end{cases}$

Implements [caffe::Layer< Dtype >](#).

## 5.21.3.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::ClipLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = \max(\min, \min(\max, x))$

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

- include/caffe/layers/clip\_layer.hpp
- src/caffe/layers/clip\_layer.cpp

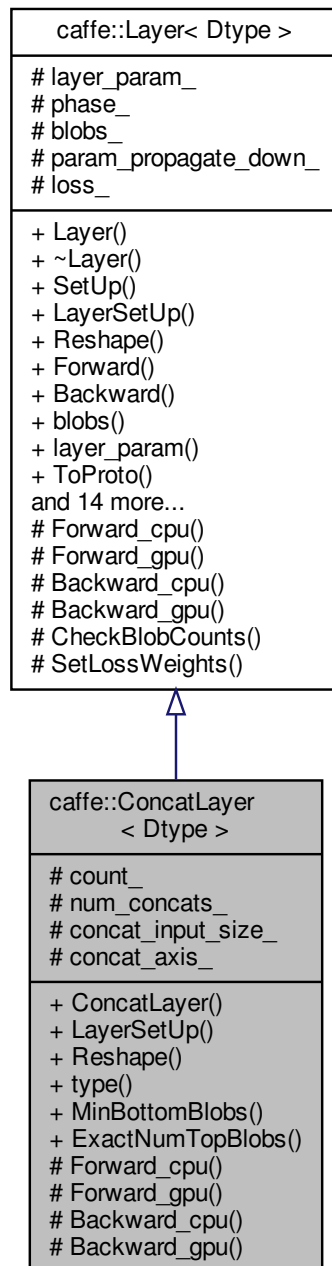


## 5.22 caffe::ConcatLayer< Dtype > Class Template Reference

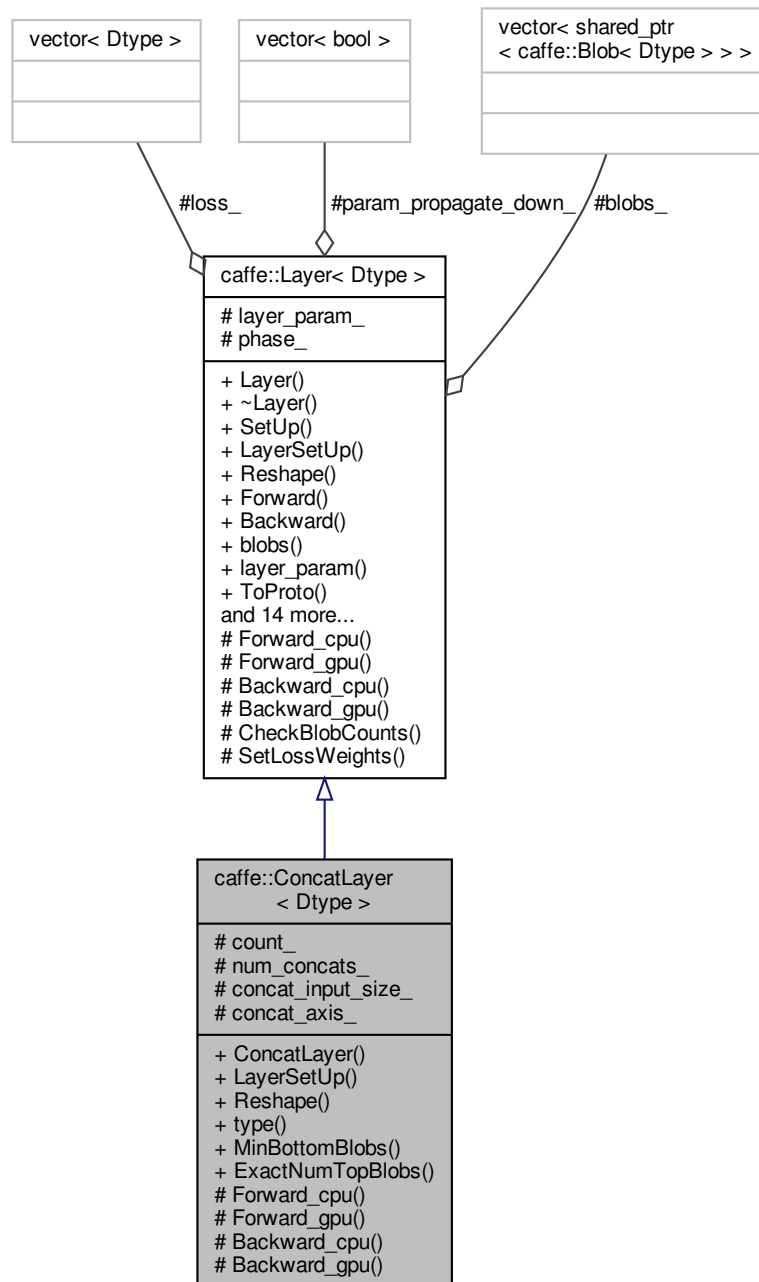
Takes at least two [Blobs](#) and concatenates them along either the num or channel dimension, outputting the result.

```
#include <concat_layer.hpp>
```

Inheritance diagram for caffe::ConcatLayer< Dtype >:



Collaboration diagram for `caffe::ConcatLayer< Dtype >`:



## Public Member Functions

- **ConcatLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as *Reshape*.
- virtual void **Reshape** (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

- virtual const char \* [type](#) () const  
*Returns the layer type.*
- virtual int [MinBottomBlobs](#) () const  
*Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.*
- virtual int [ExactNumTopBlobs](#) () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

### Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Computes the error gradient w.r.t. the concatenate inputs.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

### Protected Attributes

- int [count\\_](#)
- int [num\\_concats\\_](#)
- int [concat\\_input\\_size\\_](#)
- int [concat\\_axis\\_](#)

## 5.22.1 Detailed Description

```
template<typename Dtype>
class caffe::ConcatLayer< Dtype >
```

Takes at least two [Blobs](#) and concatenates them along either the num or channel dimension, outputting the result.

## 5.22.2 Member Function Documentation

### 5.22.2.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::ConcatLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the concatenate inputs.

## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(KN \times C \times H \times W)$ if axis == 0, or $(N \times KC \times H \times W)$ if axis == 1: containing error gradients $\frac{\partial E}{\partial y}$ with respect to concatenated outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length K), into which the top gradient $\frac{\partial E}{\partial y}$ is deconcatenated back to the inputs $\left[ \frac{\partial E}{\partial x_1} \quad \frac{\partial E}{\partial x_2} \quad \dots \quad \frac{\partial E}{\partial x_K} \right] = \frac{\partial E}{\partial y}$

Implements [caffe::Layer< Dtype >](#).

## 5.22.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::ConcatLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.22.2.3 Forward\_cpu()

```
template<typename Dtype >
void caffe::ConcatLayer< Dtype >::Forward\_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2+) 1. $(N \times C \times H \times W)$ the inputs $x_1$ 2. $(N \times C \times H \times W)$ the inputs $x_2$ 3. ... • K $(N \times C \times H \times W)$ the inputs $x_K$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(KN \times C \times H \times W)$ if axis == 0, or $(N \times KC \times H \times W)$ if axis == 1: the concatenated output $y = \begin{bmatrix} x_1 & x_2 & \dots & x_K \end{bmatrix}$

Implements [caffe::Layer< Dtype >](#).

#### 5.22.2.4 LayerSetUp()

```
template<typename Dtype >
void caffe::ConcatLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

##### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.22.2.5 MinBottomBlobs()

```
template<typename Dtype >
virtual int caffe::ConcatLayer< Dtype >::MinBottomBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.22.2.6 Reshape()

```
template<typename Dtype >
void caffe::ConcatLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

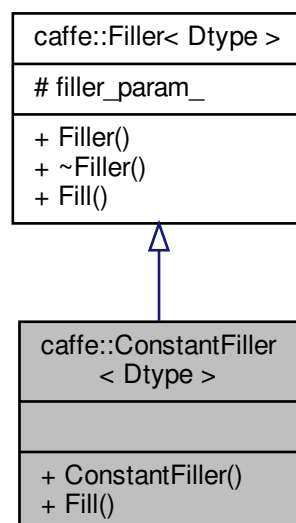
- include/caffe/layers/concat\_layer.hpp
- src/caffe/layers/concat\_layer.cpp

## 5.23 [caffe::ConstantFiller< Dtype >](#) Class Template Reference

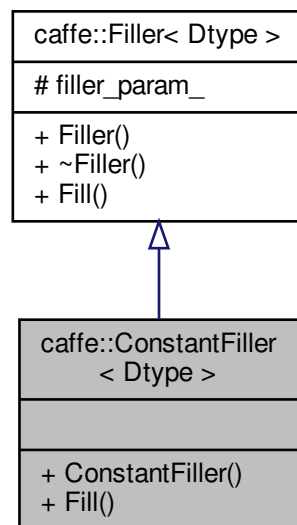
Fills a [Blob](#) with constant values  $x = 0$ .

```
#include <filler.hpp>
```

Inheritance diagram for [caffe::ConstantFiller< Dtype >](#):



Collaboration diagram for caffe::ConstantFiller< Dtype >:



## Public Member Functions

- **ConstantFiller** (const FillerParameter &param)
- virtual void **Fill** (Blob< Dtype > \*blob)

## Additional Inherited Members

### 5.23.1 Detailed Description

```
template<typename Dtype>
class caffe::ConstantFiller< Dtype >
```

Fills a [Blob](#) with constant values  $x = 0$ .

The documentation for this class was generated from the following file:

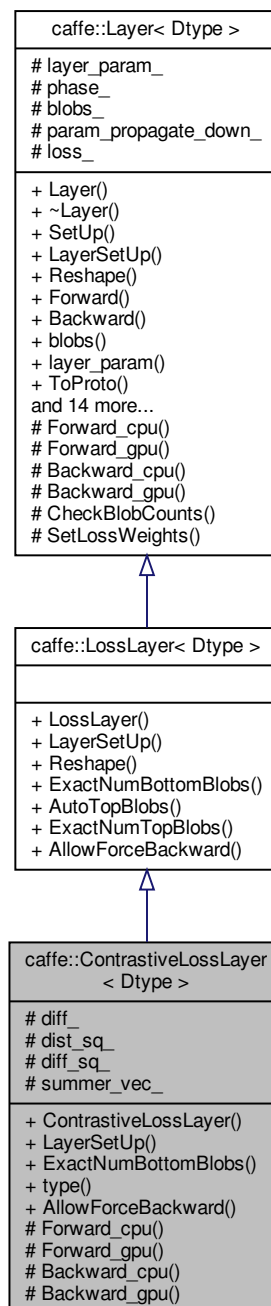
- include/caffe/filler.hpp

## 5.24 caffe::ContrastiveLossLayer< Dtype > Class Template Reference

Computes the contrastive loss  $E = \frac{1}{2N} \sum_{n=1}^N (y) d^2 + (1 - y) \max(\text{margin} - d, 0)^2$  where  $d = \|a_n - b_n\|_2$ . This can be used to train siamese networks.

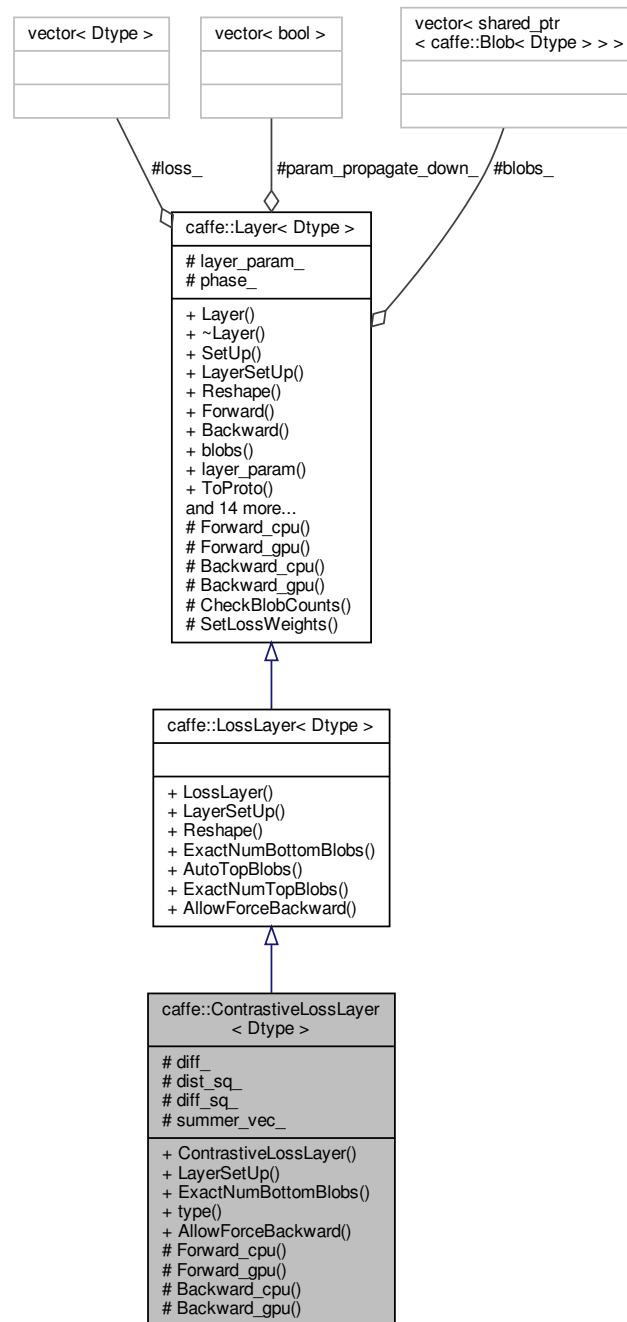
```
#include <contrastive_loss_layer.hpp>
```

Inheritance diagram for caffe::ContrastiveLossLayer< Dtype >:





Collaboration diagram for caffe::ContrastiveLossLayer< Dtype >:



## Public Member Functions

- **ContrastiveLossLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as *Reshape*.
- virtual int **ExactNumBottomBlobs** () const  
Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

- virtual const char \* [type](#) () const  
*Returns the layer type.*
- virtual bool [AllowForceBackward](#) (const int bottom\_index) const

### Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Computes the contrastive loss  $E = \frac{1}{2N} \sum_{n=1}^N (y) d^2 + (1 - y) \max(\text{margin} - d, 0)^2$  where  $d = \|a_n - b_n\|_2$ . This can be used to train siamese networks.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Computes the Contrastive error gradient w.r.t. the inputs.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

### Protected Attributes

- [Blob](#)< Dtype > [diff\\_](#)
- [Blob](#)< Dtype > [dist\\_sq\\_](#)
- [Blob](#)< Dtype > [diff\\_sq\\_](#)
- [Blob](#)< Dtype > [summer\\_vec\\_](#)

### 5.24.1 Detailed Description

```
template<typename Dtype>
class caffe::ContrastiveLossLayer< Dtype >
```

Computes the contrastive loss  $E = \frac{1}{2N} \sum_{n=1}^N (y) d^2 + (1 - y) \max(\text{margin} - d, 0)^2$  where  $d = \|a_n - b_n\|_2$ . This can be used to train siamese networks.

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 3) <ol style="list-style-type: none"> <li>1. <math>(N \times C \times 1 \times 1)</math> the features <math>a \in [-\infty, +\infty]</math></li> <li>2. <math>(N \times C \times 1 \times 1)</math> the features <math>b \in [-\infty, +\infty]</math></li> <li>3. <math>(N \times 1 \times 1 \times 1)</math> the binary similarity <math>s \in [0, 1]</math></li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li>1. <math>(1 \times 1 \times 1 \times 1)</math> the computed contrastive loss:  <math display="block">E = \frac{1}{2N} \sum_{n=1}^N (y) d^2 + (1 - y) \max(\text{margin} - d, 0)^2</math> where <math>d = \ a_n - b_n\ _2</math>. This can be used to train siamese networks.</li> </ol>

## 5.24.2 Member Function Documentation

### 5.24.2.1 AllowForceBackward()

```
template<typename Dtype >
virtual bool caffe::ContrastiveLossLayer< Dtype >::AllowForceBackward (
    const int bottom_index ) const [inline], [virtual]
```

Unlike most loss layers, in the [ContrastiveLossLayer](#) we can backpropagate to the first two inputs.

Reimplemented from [caffe::LossLayer< Dtype >](#).

### 5.24.2.2 Backward\_cpu()

```
template<typename Dtype >
void caffe::ContrastiveLossLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the Contrastive error gradient w.r.t. the inputs.

Computes the gradients with respect to the two input vectors (bottom[0] and bottom[1]), but not the similarity label (bottom[2]).

#### Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> This <a href="#">Blob</a>'s diff will simply contain the <code>loss_weight</code>* <math>\lambda</math>, as <math>\lambda</math> is the coefficient of this layer's output <math>\ell_i</math> in the overall <a href="#">Net</a> loss <math>E = \lambda_i \ell_i + \text{other loss terms}</math>; hence <math>\frac{\partial E}{\partial \ell_i} = \lambda_i</math>. (*Assuming that this top <a href="#">Blob</a> is not used as a bottom (input) by any other layer of the <a href="#">Net</a>.)</li> </ol>
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times 1 \times 1)</math> the features <i>a</i>; Backward fills their diff with gradients if <code>propagate_down[0]</code></li> <li><math>(N \times C \times 1 \times 1)</math> the features <i>b</i>; Backward fills their diff with gradients if <code>propagate_down[1]</code></li> </ol>

Implements [caffe::Layer< Dtype >](#).

### 5.24.2.3 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::ContrastiveLossLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline],
[virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::LossLayer< Dtype >](#).

### 5.24.2.4 Forward\_cpu()

```
template<typename Dtype >
void caffe::ContrastiveLossLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

Computes the contrastive loss  $E = \frac{1}{2N} \sum_{n=1}^N (y) d^2 + (1 - y) \max (margin - d, 0)^2$  where  $d = \|a_n - b_n\|_2$ . This can be used to train siamese networks.

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 3) <ol style="list-style-type: none"> <li><math>(N \times C \times 1 \times 1)</math> the features <math>a \in [-\infty, +\infty]</math></li> <li><math>(N \times C \times 1 \times 1)</math> the features <math>b \in [-\infty, +\infty]</math></li> <li><math>(N \times 1 \times 1 \times 1)</math> the binary similarity <math>s \in [0, 1]</math></li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> the computed contrastive loss:  <math display="block">E = \frac{1}{2N} \sum_{n=1}^N (y) d^2 + (1 - y) \max (margin - d, 0)^2</math> where <math>d = \ a_n - b_n\ _2</math>. This can be used to train siamese networks.</li> </ol>

Implements [caffe::Layer< Dtype >](#).

### 5.24.2.5 LayerSetUp()

```
template<typename Dtype >
void caffe::ContrastiveLossLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::LossLayer< Dtype >](#).

The documentation for this class was generated from the following files:

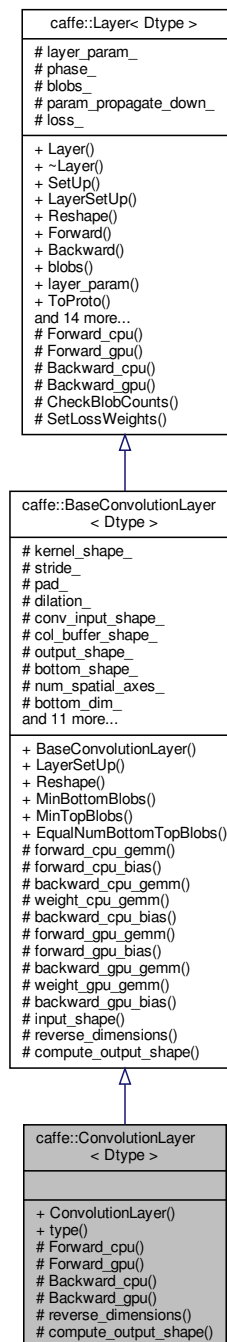
- `include/caffe/layers/contrastive_loss_layer.hpp`
- `src/caffe/layers/contrastive_loss_layer.cpp`

## 5.25 `caffe::ConvolutionLayer< Dtype >` Class Template Reference

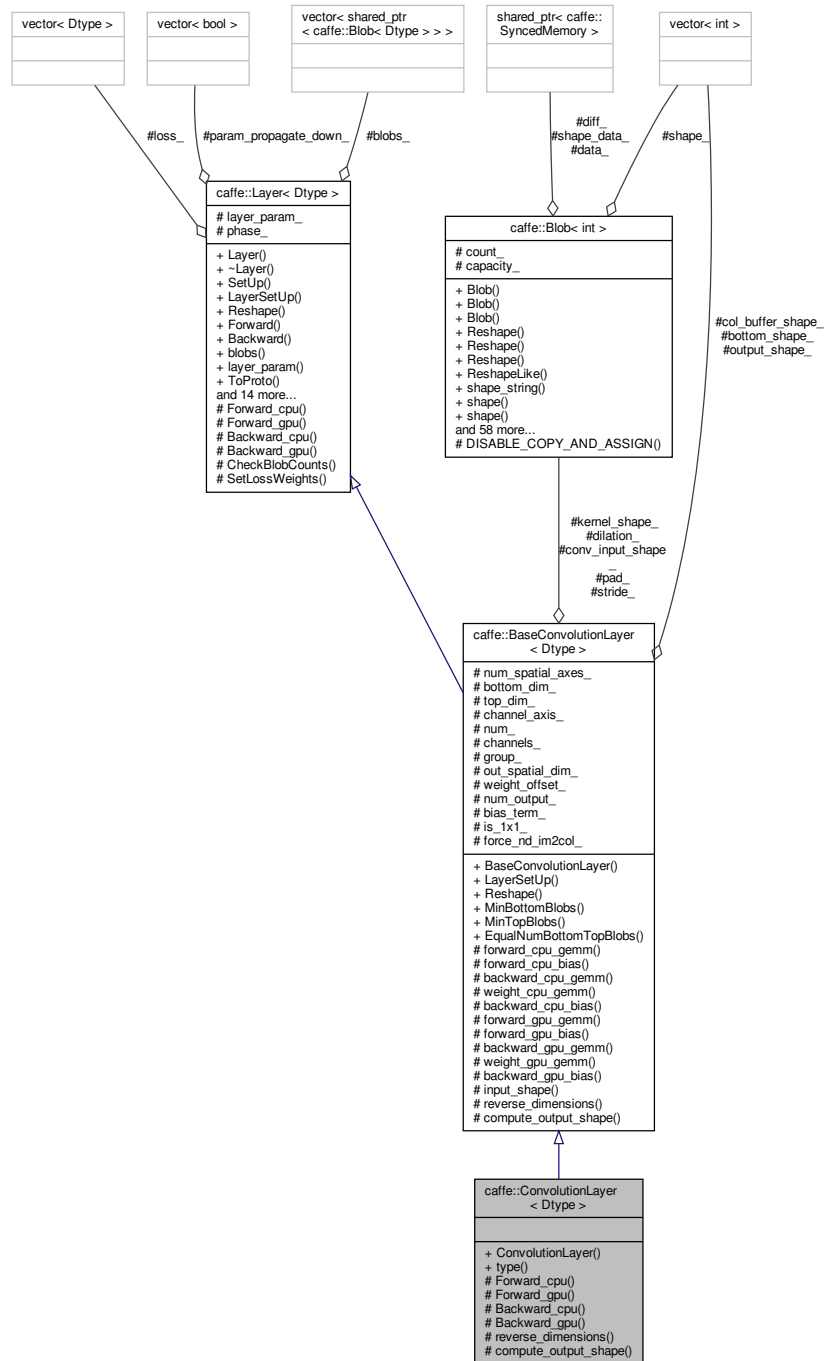
Convolves the input image with a bank of learned filters, and (optionally) adds biases.

```
#include <conv_layer.hpp>
```

Inheritance diagram for `caffe::ConvolutionLayer< Dtype >`:



Collaboration diagram for caffe::ConvolutionLayer< Dtype >:



## Public Member Functions

- [ConvolutionLayer](#) (const LayerParameter &param)
- virtual const char \* [type](#) () const  
*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*
- virtual bool **reverse\_dimensions** ()
- virtual void **compute\_output\_shape** ()

## Additional Inherited Members

### 5.25.1 Detailed Description

```
template<typename Dtype>
class caffe::ConvolutionLayer< Dtype >
```

Convolves the input image with a bank of learned filters, and (optionally) adds biases.

[Caffe](#) convolves by reduction to matrix multiplication. This achieves high-throughput and generality of input and filter dimensions but comes at the cost of memory for matrices. This makes use of efficiency in BLAS.

The input is "im2col" transformed to a channel K' x H x W data matrix for multiplication with the N x K' x H x W filter matrix to yield a N' x H x W output matrix that is then "col2im" restored. K' is the input channel \* kernel height \* kernel width dimension of the unrolled inputs so that the im2col matrix has a column for each input region to be filtered. col2im restores the output spatial structure by rolling up the output channel N' columns of the output matrix.

### 5.25.2 Constructor & Destructor Documentation

#### 5.25.2.1 ConvolutionLayer()

```
template<typename Dtype >
caffe::ConvolutionLayer< Dtype >::ConvolutionLayer (
    const LayerParameter & param ) [inline], [explicit]
```



## Parameters

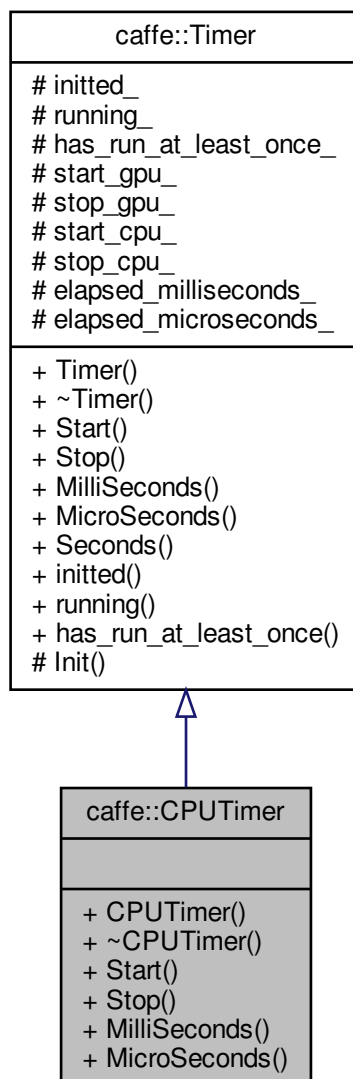
<i>param</i>	<p>provides ConvolutionParameter convolution_param, with <a href="#">ConvolutionLayer</a> options:</p> <ul style="list-style-type: none"> <li>• num_output. The number of filters.</li> <li>• kernel_size / kernel_h / kernel_w. The filter dimensions, given by kernel_size for square filters or kernel_h and kernel_w for rectangular filters.</li> <li>• stride / stride_h / stride_w (<b>optional</b>, default 1). The filter stride, given by stride_size for equal dimensions or stride_h and stride_w for different strides. By default the convolution is dense with stride 1.</li> <li>• pad / pad_h / pad_w (<b>optional</b>, default 0). The zero-padding for convolution, given by pad for equal dimensions or pad_h and pad_w for different padding. Input padding is computed implicitly instead of actually padding.</li> <li>• dilation (<b>optional</b>, default 1). The filter dilation, given by dilation_size for equal dimensions for different dilation. By default the convolution has dilation 1.</li> <li>• group (<b>optional</b>, default 1). The number of filter groups. Group convolution is a method for reducing parameterization by selectively connecting input and output channels. The input and output channel dimensions must be divisible by the number of groups. For <math>\text{group} \geq 1</math>, the convolutional filters' input and output channels are separated s.t. each group takes <math>1 / \text{group}</math> of the input channels and makes <math>1 / \text{group}</math> of the output channels. Concretely 4 input channels, 8 output channels, and 2 groups separate input channels 1-2 and output channels 1-4 into the first group and input channels 3-4 and output channels 5-8 into the second group.</li> <li>• bias_term (<b>optional</b>, default true). Whether to have a bias.</li> <li>• engine: convolution has CAFFE (matrix multiplication) and CUDNN (library kernels + stream parallelism) engines.</li> </ul>
--------------	---

The documentation for this class was generated from the following files:

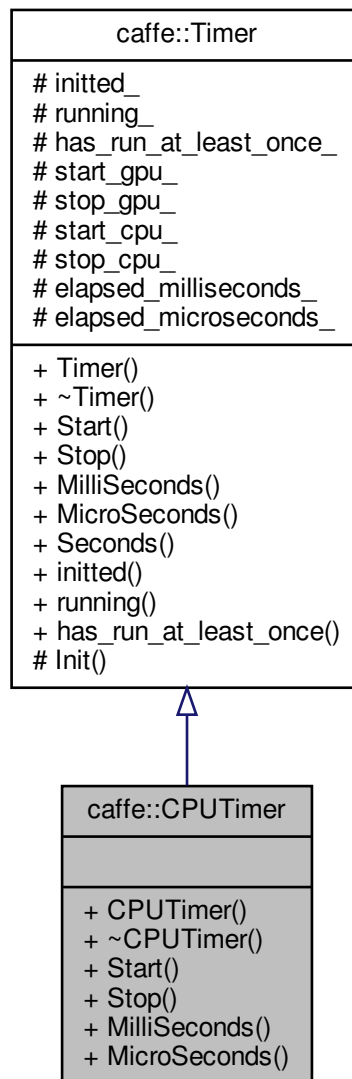
- include/caffe/layers/conv\_layer.hpp
- src/caffe/layers/conv\_layer.cpp

## 5.26 caffe::CPUTimer Class Reference

Inheritance diagram for caffe::CPUTimer:



Collaboration diagram for caffe::CPUTimer:



### Public Member Functions

- virtual void **Start** ()
- virtual void **Stop** ()
- virtual float **MilliSeconds** ()
- virtual float **MicroSeconds** ()

### Additional Inherited Members

The documentation for this class was generated from the following files:

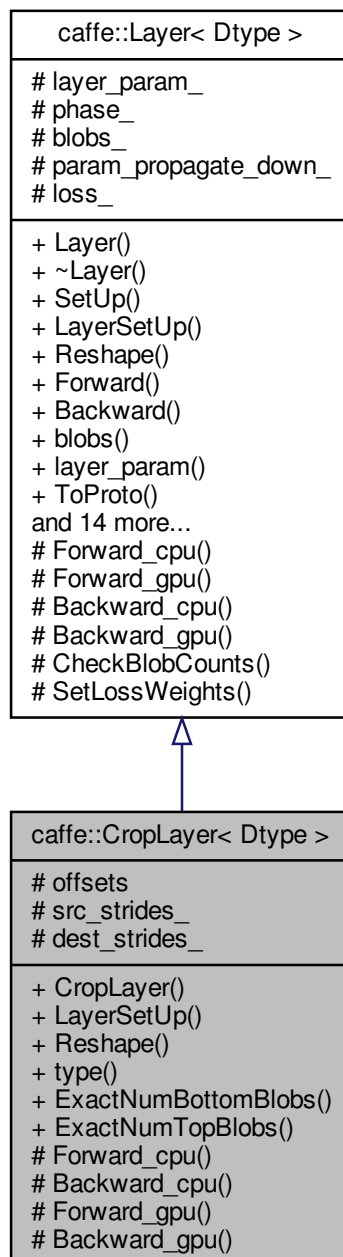
- include/caffe/util/benchmark.hpp
- src/caffe/util/benchmark.cpp

## 5.27 caffe::CropLayer< Dtype > Class Template Reference

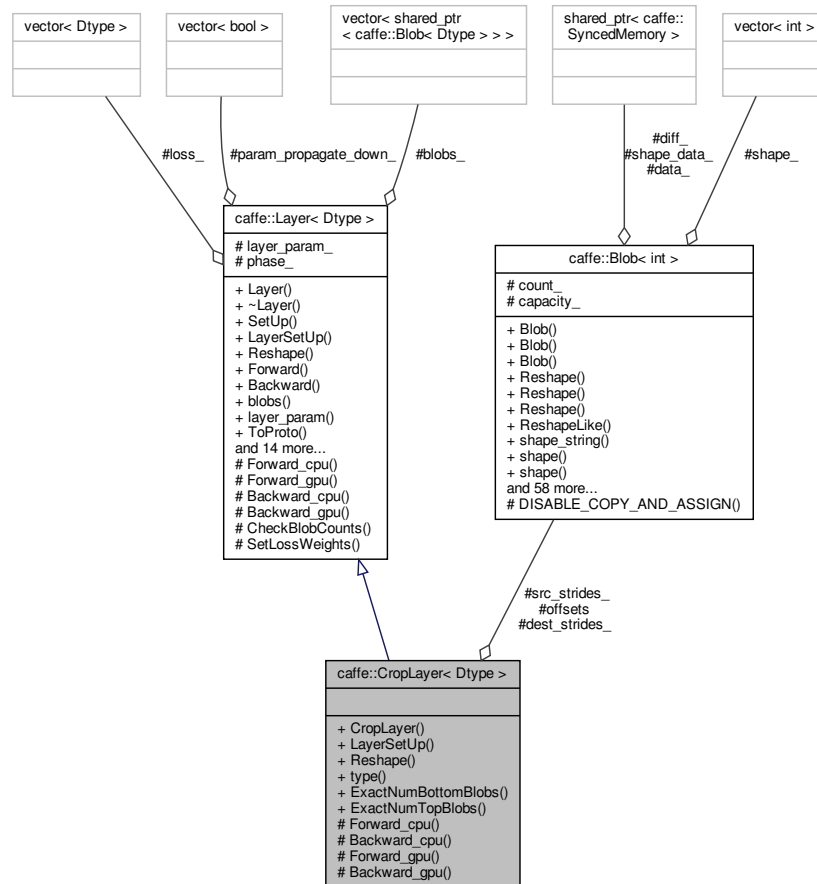
Takes a [Blob](#) and crop it, to the shape specified by the second input [Blob](#), across all dimensions after the specified axis.

```
#include <crop_layer.hpp>
```

Inheritance diagram for caffe::CropLayer< Dtype >:



Collaboration diagram for caffe::CropLayer< Dtype >:



## Public Member Functions

- **CropLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void **Forward\_cpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)

*Using the CPU device, compute the layer output.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- [Blob](#)< int > **offsets**
- [Blob](#)< int > **src\_strides\_**
- [Blob](#)< int > **dest\_strides\_**

## 5.27.1 Detailed Description

```
template<typename Dtype>
class caffe::CropLayer< Dtype >
```

Takes a [Blob](#) and crop it, to the shape specified by the second input [Blob](#), across all dimensions after the specified axis.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

## 5.27.2 Member Function Documentation

### 5.27.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::CropLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer](#)< Dtype >.

5.27.2.2 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::CropLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.27.2.3 `LayerSetUp()`

```
template<typename Dtype >
void caffe::CropLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from `caffe::Layer< Dtype >`.

5.27.2.4 `Reshape()`

```
template<typename Dtype >
void caffe::CropLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as

reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

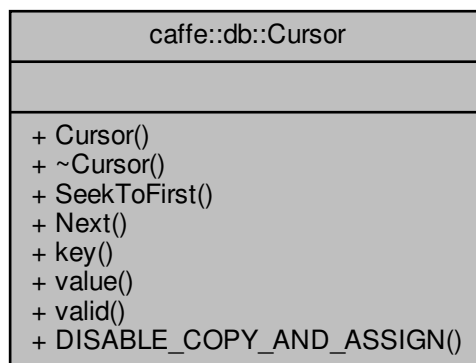
Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

- include/caffe/layers/crop\_layer.hpp
- src/caffe/layers/crop\_layer.cpp

## 5.28 caffe::db::Cursor Class Reference

Collaboration diagram for caffe::db::Cursor:



### Public Member Functions

- virtual void **SeekToFirst** ()=0
- virtual void **Next** ()=0
- virtual string **key** ()=0
- virtual string **value** ()=0
- virtual bool **valid** ()=0
- **DISABLE\_COPY\_AND\_ASSIGN** ([Cursor](#))

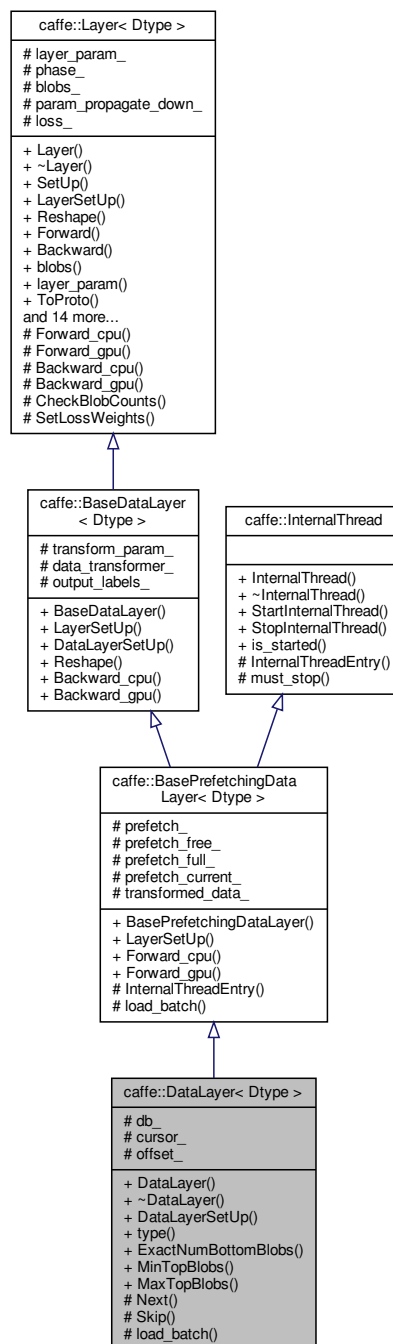
The documentation for this class was generated from the following file:

- include/caffe/util/db.hpp

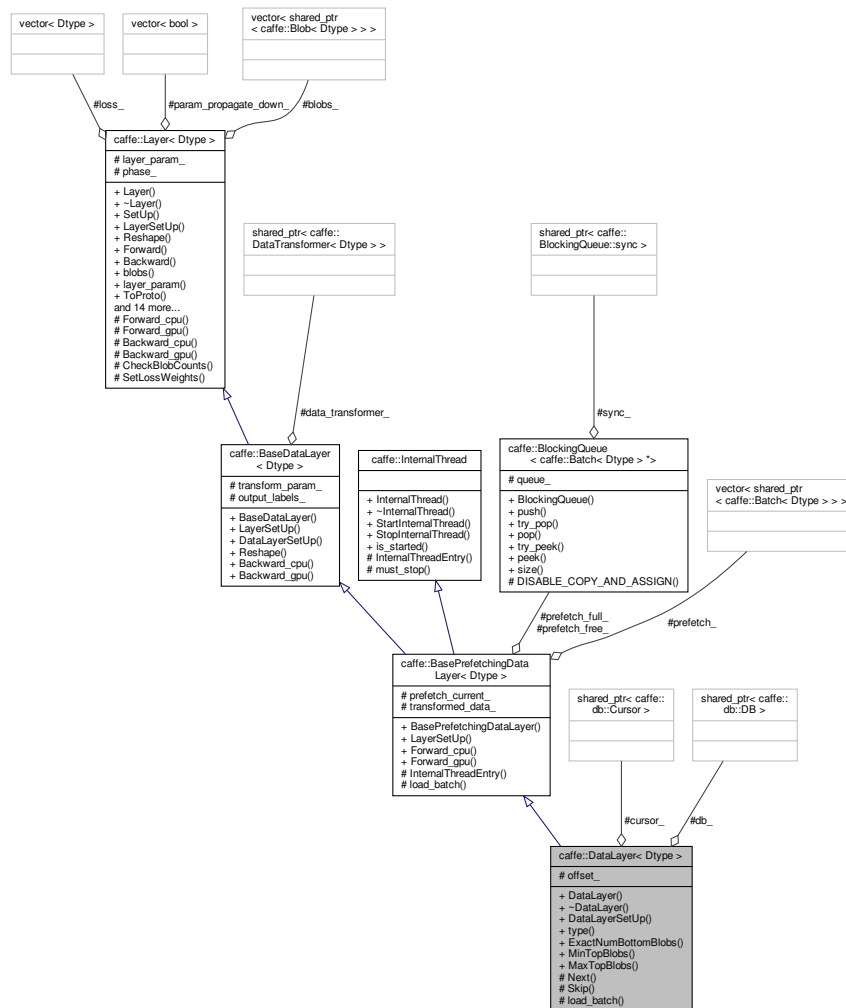


## 5.29 caffe::DataLayer&lt; Dtype &gt; Class Template Reference

Inheritance diagram for caffe::DataLayer< Dtype >:



Collaboration diagram for `caffe::DataLayer< Dtype >`:



## Public Member Functions

- **DataLayer** (const LayerParameter &param)
- virtual void **DataLayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **MinTopBlobs** () const  
*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*
- virtual int **MaxTopBlobs** () const  
*Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.*

## Protected Member Functions

- void **Next** ()
- bool **Skip** ()
- virtual void **load\_batch** (Batch< Dtype > \*batch)

## Protected Attributes

- `shared_ptr< db::DB > db_`
- `shared_ptr< db::Cursor > cursor_`
- `uint64_t offset_`

## 5.29.1 Member Function Documentation

### 5.29.1.1 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::DataLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.29.1.2 `MaxTopBlobs()`

```
template<typename Dtype >
virtual int caffe::DataLayer< Dtype >::MaxTopBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.29.1.3 `MinTopBlobs()`

```
template<typename Dtype >
virtual int caffe::DataLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

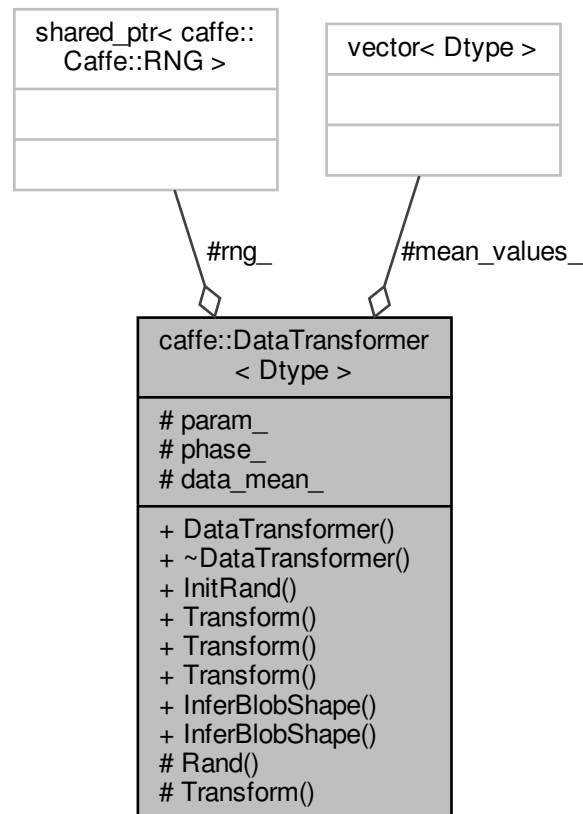
- `include/caffe/layers/data_layer.hpp`
- `src/caffe/layers/data_layer.cpp`

### 5.30 caffe::DataTransformer< Dtype > Class Template Reference

Applies common transformations to the input data, such as scaling, mirroring, subtracting the image mean...

```
#include <data_transformer.hpp>
```

Collaboration diagram for caffe::DataTransformer< Dtype >:



#### Public Member Functions

- **DataTransformer** (const TransformationParameter &param, Phase phase)
- void **InitRand** ()  
*Initialize the Random number generations if needed by the transformation.*
- void **Transform** (const Datum &datum, Blob< Dtype > \*transformed\_blob)  
*Applies the transformation defined in the data layer's transform\_param block to the data.*
- void **Transform** (const vector< Datum > &datum\_vector, Blob< Dtype > \*transformed\_blob)  
*Applies the transformation defined in the data layer's transform\_param block to a vector of Datum.*
- void **Transform** (Blob< Dtype > \*input\_blob, Blob< Dtype > \*transformed\_blob)  
*Applies the same transformation defined in the data layer's transform\_param block to all the num images in a input->\_blob.*
- vector< int > **InferBlobShape** (const Datum &datum)

*Infers the shape of transformed\_blob will have when the transformation is applied to the data.*

- vector< int > [InferBlobShape](#) (const vector< Datum > &datum\_vector)

*Infers the shape of transformed\_blob will have when the transformation is applied to the data. It uses the first element to infer the shape of the blob.*

## Protected Member Functions

- virtual int [Rand](#) (int n)

*Infers the shape of transformed\_blob will have when the transformation is applied to the data. It uses the first element to infer the shape of the blob.*

- void **Transform** (const Datum &datum, Dtype \*transformed\_data)

## Protected Attributes

- TransformationParameter **param\_**
- shared\_ptr< [Caffe::RNG](#) > **rng\_**
- Phase **phase\_**
- [Blob](#)< Dtype > **data\_mean\_**
- vector< Dtype > **mean\_values\_**

### 5.30.1 Detailed Description

```
template<typename Dtype>
class caffe::DataTransformer< Dtype >
```

Applies common transformations to the input data, such as scaling, mirroring, subtracting the image mean...

### 5.30.2 Member Function Documentation

#### 5.30.2.1 InferBlobShape() [1/2]

```
template<typename Dtype >
vector< int > caffe::DataTransformer< Dtype >::InferBlobShape (
    const Datum & datum )
```

Infers the shape of transformed\_blob will have when the transformation is applied to the data.

#### Parameters

<i>datum</i>	Datum containing the data to be transformed.
--------------	--

### 5.30.2.2 InferBlobShape() [2/2]

```
template<typename Dtype >
vector< int > caffe::DataTransformer< Dtype >::InferBlobShape (
    const vector< Datum > & datum_vector )
```

Infers the shape of transformed\_blob will have when the transformation is applied to the data. It uses the first element to infer the shape of the blob.

#### Parameters

<i>datum_vector</i>	A vector of Datum containing the data to be transformed.
---------------------	--

### 5.30.2.3 Rand()

```
template<typename Dtype >
int caffe::DataTransformer< Dtype >::Rand (
    int n ) [protected], [virtual]
```

Infers the shape of transformed\_blob will have when the transformation is applied to the data. It uses the first element to infer the shape of the blob.

#### Parameters

<i>mat_vector</i>	A vector of Mat containing the data to be transformed. Generates a random integer from Uniform({0, 1, ..., n-1}).
<i>n</i>	The upperbound (exclusive) value of the random number.

#### Returns

A uniformly random integer value from ({0, 1, ..., n-1}).

### 5.30.2.4 Transform() [1/3]

```
template<typename Dtype >
void caffe::DataTransformer< Dtype >::Transform (
    const Datum & datum,
    Blob< Dtype > * transformed_blob )
```

Applies the transformation defined in the data layer's transform\_param block to the data.

#### Parameters

<i>datum</i>	Datum containing the data to be transformed.
<i>transformed_blob</i>	This is destination blob. It can be part of top blob's data if set_cpu_data() is used. See data_layer.cpp for an example.

## 5.30.2.5 Transform() [2/3]

```
template<typename Dtype >
void caffe::DataTransformer< Dtype >::Transform (
    const vector< Datum > & datum_vector,
    Blob< Dtype > * transformed_blob )
```

Applies the transformation defined in the data layer's transform\_param block to a vector of Datum.

## Parameters

<i>datum_vector</i>	A vector of Datum containing the data to be transformed.
<i>transformed_blob</i>	This is destination blob. It can be part of top blob's data if set_cpu_data() is used. See memory_layer.cpp for an example.

## 5.30.2.6 Transform() [3/3]

```
template<typename Dtype >
void caffe::DataTransformer< Dtype >::Transform (
    Blob< Dtype > * input_blob,
    Blob< Dtype > * transformed_blob )
```

Applies the same transformation defined in the data layer's transform\_param block to all the num images in a input\_blob.

## Parameters

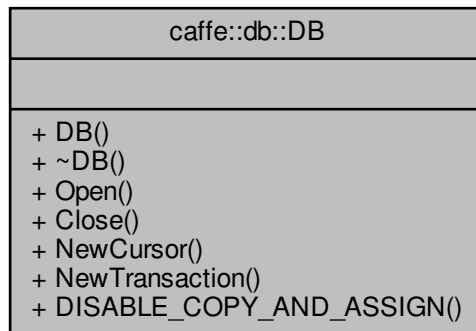
<i>input_blob</i>	A Blob containing the data to be transformed. It applies the same transformation to all the num images in the blob.
<i>transformed_blob</i>	This is destination blob, it will contain as many images as the input blob. It can be part of top blob's data.

The documentation for this class was generated from the following files:

- include/caffe/data\_transformer.hpp
- src/caffe/data\_transformer.cpp

## 5.31 `caffe::db::DB` Class Reference

Collaboration diagram for `caffe::db::DB`:



### Public Member Functions

- virtual void **Open** (const string &source, Mode mode)=0
- virtual void **Close** ()=0
- virtual [Cursor](#) \* **NewCursor** ()=0
- virtual [Transaction](#) \* **NewTransaction** ()=0
- **DISABLE\_COPY\_AND\_ASSIGN** ([DB](#))

The documentation for this class was generated from the following file:

- include/caffe/util/db.hpp

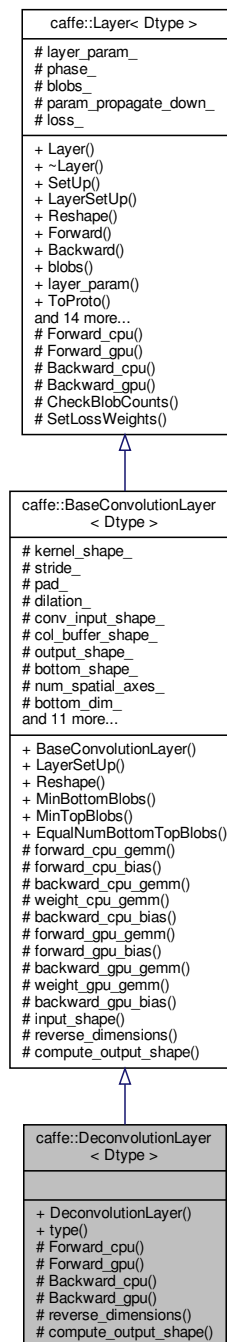
## 5.32 `caffe::DeconvolutionLayer< Dtype >` Class Template Reference

Convolve the input with a bank of learned filters, and (optionally) add biases, treating filters and convolution parameters in the opposite sense as [ConvolutionLayer](#).

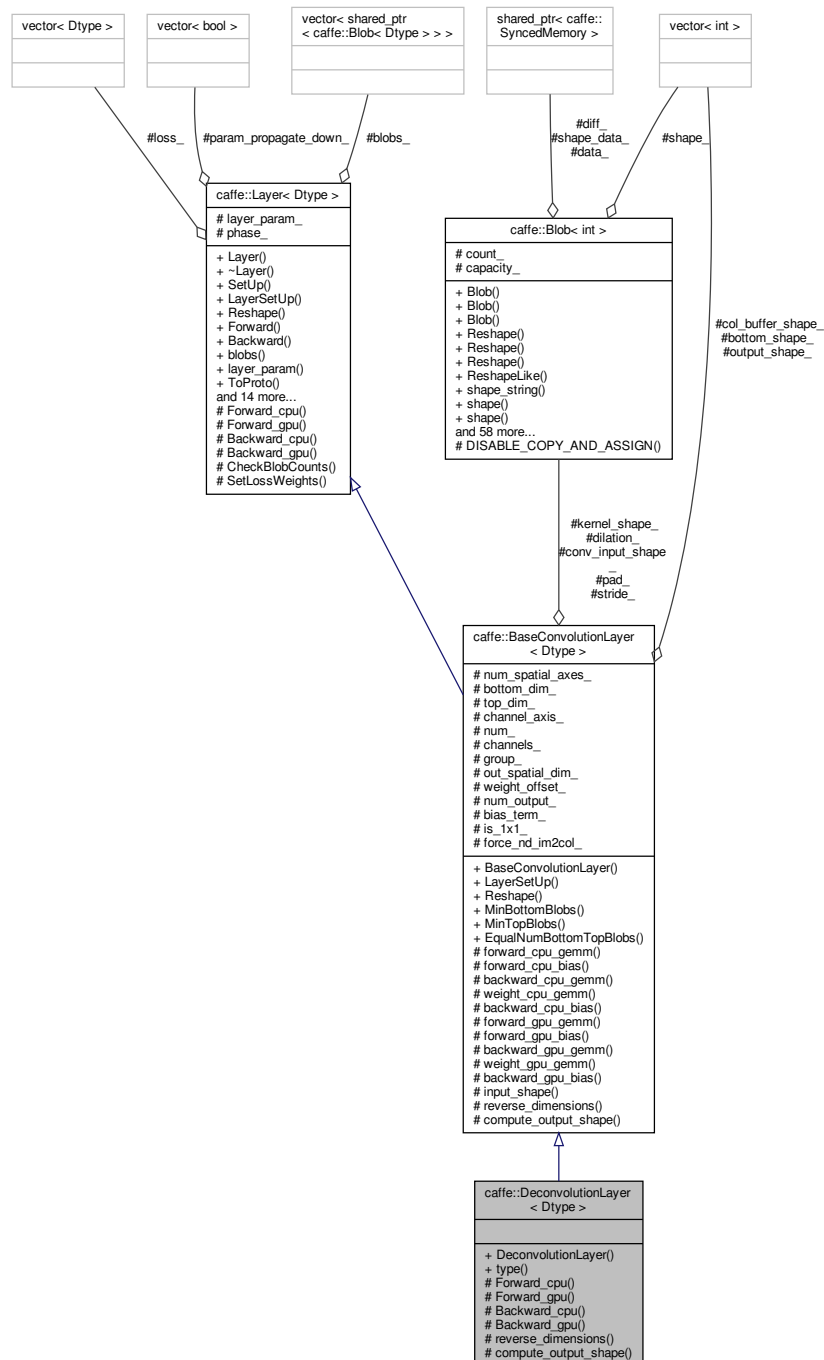
```
#include <deconv_layer.hpp>
```



Inheritance diagram for caffe::DeconvolutionLayer< Dtype >:



Collaboration diagram for `caffe::DeconvolutionLayer< Dtype >`:



## Public Member Functions

- **DeconvolutionLayer** (const LayerParameter &param)
- virtual const char \* **type** () const

*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*
- virtual bool [reverse\\_dimensions](#) ()
- virtual void [compute\\_output\\_shape](#) ()

## Additional Inherited Members

### 5.32.1 Detailed Description

```
template<typename Dtype>
class caffe::DeconvolutionLayer< Dtype >
```

Convolve the input with a bank of learned filters, and (optionally) add biases, treating filters and convolution parameters in the opposite sense as [ConvolutionLayer](#).

[ConvolutionLayer](#) computes each output value by dotting an input window with a filter; [DeconvolutionLayer](#) multiplies each input value by a filter elementwise, and sums over the resulting output windows. In other words, [DeconvolutionLayer](#) is [ConvolutionLayer](#) with the forward and backward passes reversed. [DeconvolutionLayer](#) reuses [ConvolutionParameter](#) for its parameters, but they take the opposite sense as in [ConvolutionLayer](#) (so padding is removed from the output rather than added to the input, and stride results in upsampling rather than downsampling).

The documentation for this class was generated from the following files:

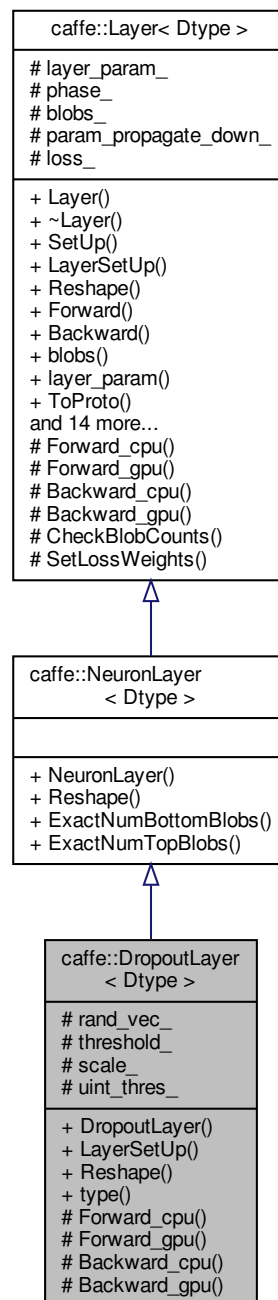
- include/caffe/layers/deconv\_layer.hpp
- src/caffe/layers/deconv\_layer.cpp

## 5.33 caffe::DropoutLayer< Dtype > Class Template Reference

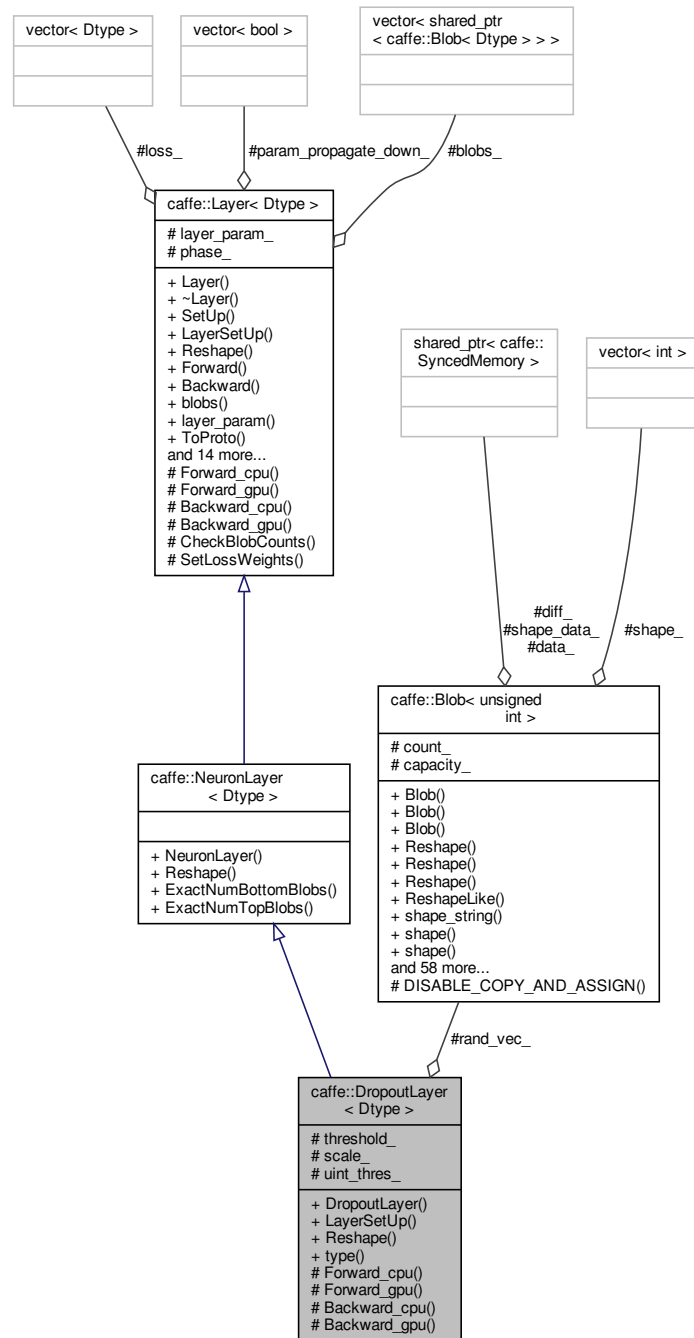
During training only, sets a random portion of  $x$  to 0, adjusting the rest of the vector magnitude accordingly.

```
#include <dropout_layer.hpp>
```

Inheritance diagram for `caffe::DropoutLayer< Dtype >`:



Collaboration diagram for caffe::DropoutLayer< Dtype >:



## Public Member Functions

- `DropoutLayer` (const LayerParameter &param)
- virtual void `LayerSetUp` (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as `Reshape`.
- virtual void `Reshape` (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

- virtual const char \* [type](#) () const  
*Returns the layer type.*

### Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

### Protected Attributes

- [Blob](#)< unsigned int > [rand\\_vec\\_](#)  
*when divided by `UINT_MAX`, the randomly generated values  $u \sim U(0, 1)$*
- Dtype [threshold\\_](#)  
*the probability  $p$  of dropping any input*
- Dtype [scale\\_](#)  
*the scale for undropped inputs at train time  $1/(1 - p)$*
- unsigned int [uint\\_thres\\_](#)

#### 5.33.1 Detailed Description

```
template<typename Dtype>
class caffe::DropoutLayer< Dtype >
```

During training only, sets a random portion of  $x$  to 0, adjusting the rest of the vector magnitude accordingly.

##### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y =  x $

#### 5.33.2 Constructor & Destructor Documentation

## 5.33.2.1 DropoutLayer()

```
template<typename Dtype >
caffe::DropoutLayer< Dtype >::DropoutLayer (
    const LayerParameter & param ) [inline], [explicit]
```

## Parameters

<i>param</i>	provides DropoutParameter dropout_param, with DropoutLayer options: <ul style="list-style-type: none"> <li>dropout_ratio (<b>optional</b>, default 0.5). Sets the probability <math>p</math> that any given unit is dropped.</li> </ul>
--------------	---

## 5.33.3 Member Function Documentation

## 5.33.3.1 Forward\_cpu()

```
template<typename Dtype >
void caffe::DropoutLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input Blob vector (length 1) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the inputs <math>x</math></li> </ol>
<i>top</i>	output Blob vector (length 1) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the computed outputs. At training time, we have <math>y_{\text{train}} = \begin{cases} \frac{x}{1-p} &amp; \text{if } u &gt; p \\ 0 &amp; \text{otherwise} \end{cases}</math>, where <math>u \sim U(0, 1)</math> is generated independently for each input at each iteration. At test time, we simply have <math>y_{\text{test}} = \mathbb{E}[y_{\text{train}}] = x</math>.</li> </ol>

Implements [caffe::Layer< Dtype >](#).

## 5.33.3.2 LayerSetUp()

```
template<typename Dtype >
void caffe::DropoutLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.33.3.3 Reshape()

```
template<typename Dtype >
void caffe::DropoutLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Reimplemented from [caffe::NeuronLayer< Dtype >](#).

The documentation for this class was generated from the following files:

- include/caffe/layers/dropout\_layer.hpp
- src/caffe/layers/dropout\_layer.cpp

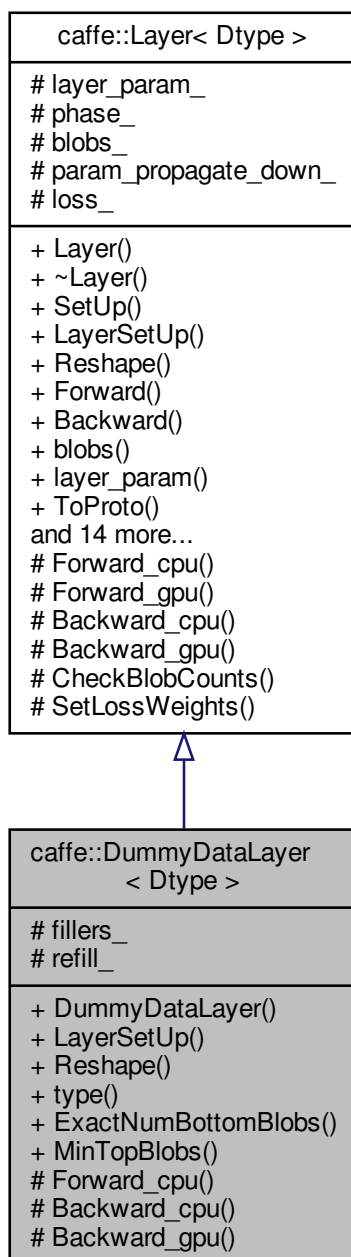
## 5.34 caffe::DummyDataLayer&lt; Dtype &gt; Class Template Reference

Provides data to the [Net](#) generated by a [Filler](#).

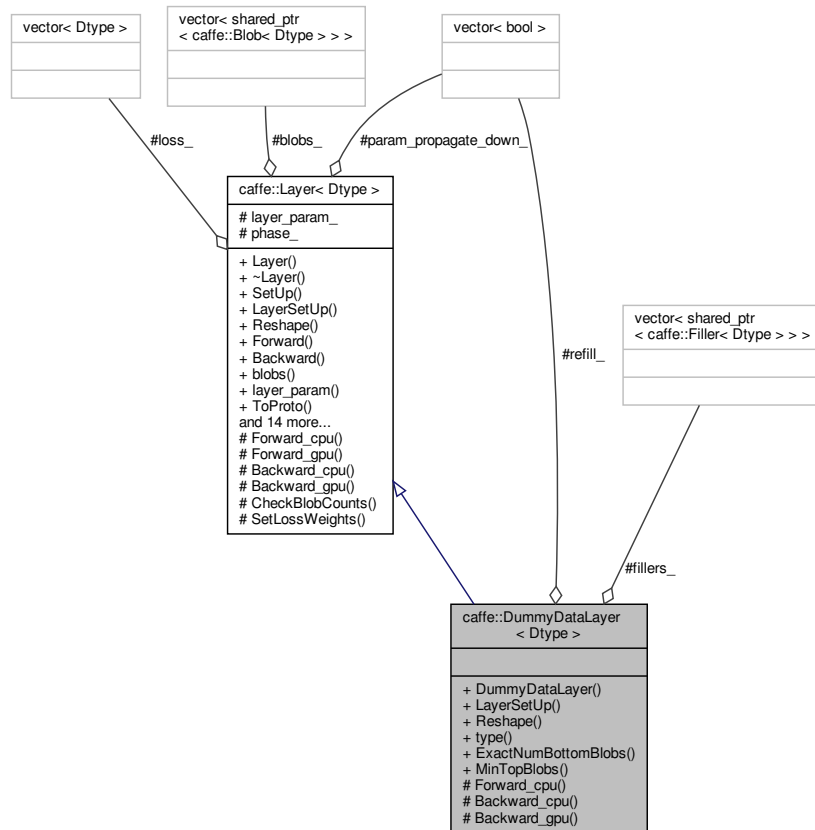
```
#include <dummy_data_layer.hpp>
```



Inheritance diagram for caffe::DummyDataLayer< Dtype >:



Collaboration diagram for `caffe::DummyDataLayer< Dtype >`:



## Public Member Functions

- **DummyDataLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **MinTopBlobs** () const  
*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*

## Protected Member Functions

- virtual void **Forward\_cpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Using the CPU device, compute the layer output.*

- virtual void `Backward_cpu` (const vector< `Blob`< `Dtype` > \*> &top, const vector< bool > &propagate\_down, const vector< `Blob`< `Dtype` > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void `Backward_gpu` (const vector< `Blob`< `Dtype` > \*> &top, const vector< bool > &propagate\_down, const vector< `Blob`< `Dtype` > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to `Backward_cpu()` if unavailable.*

### Protected Attributes

- vector< shared\_ptr< `Filler`< `Dtype` > > `fillers_`
- vector< bool > `refill_`

### 5.34.1 Detailed Description

```
template<typename Dtype>
class caffe::DummyDataLayer< Dtype >
```

Provides data to the `Net` generated by a `Filler`.

TODO(dox): thorough documentation for Forward and proto params.

### 5.34.2 Member Function Documentation

#### 5.34.2.1 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::DummyDataLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.34.2.2 `LayerSetUp()`

```
template<typename Dtype >
void caffe::DummyDataLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.34.2.3 MinTopBlobs()

```
template<typename Dtype >
virtual int caffe::DummyDataLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.34.2.4 Reshape()

```
template<typename Dtype >
virtual void caffe::DummyDataLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [inline], [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

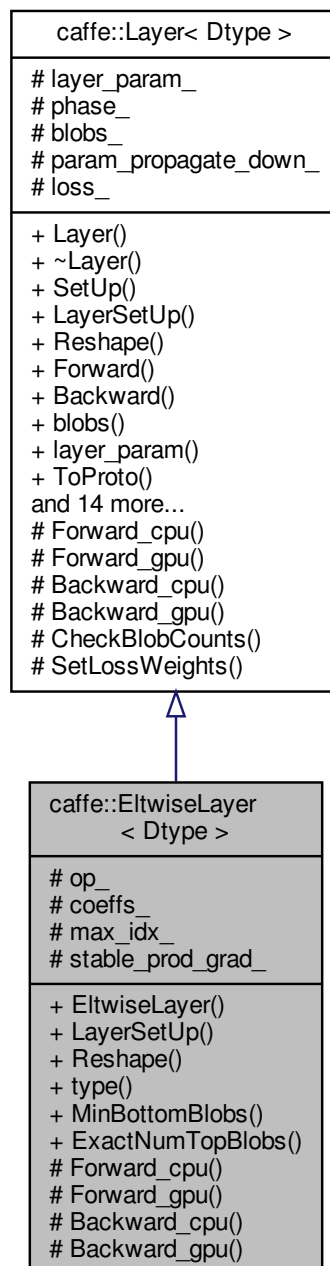
- include/caffe/layers/dummy\_data\_layer.hpp
- src/caffe/layers/dummy\_data\_layer.cpp

## 5.35 caffe::EltwiseLayer< Dtype > Class Template Reference

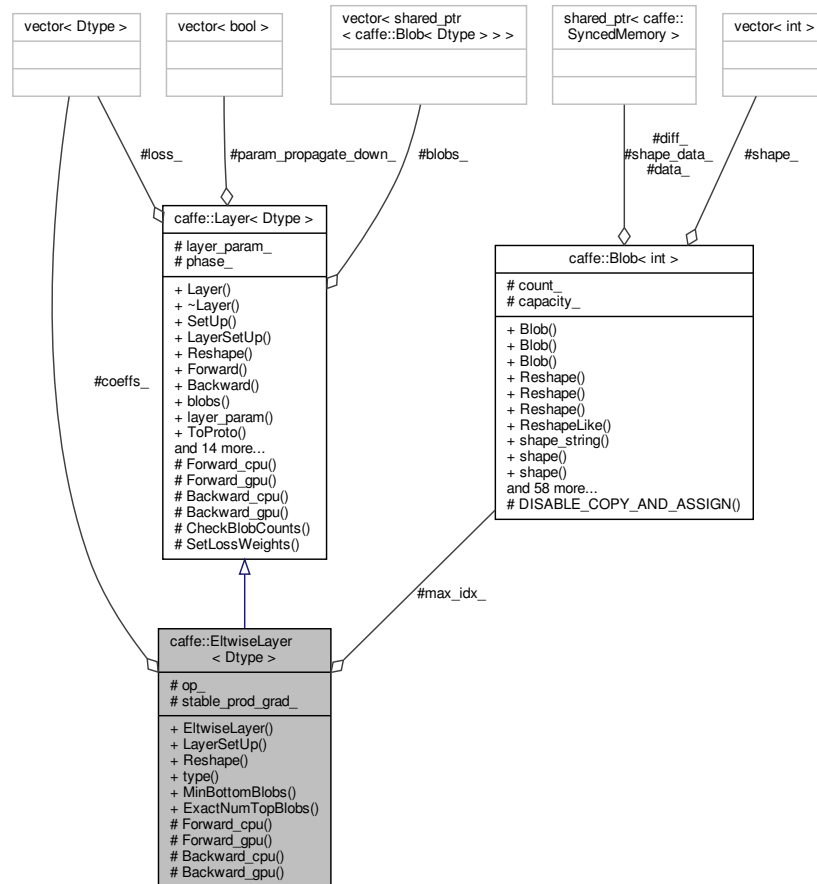
Compute elementwise operations, such as product and sum, along multiple input Blobs.

```
#include <eltwise_layer.hpp>
```

Inheritance diagram for caffe::EltwiseLayer< Dtype >:



Collaboration diagram for `caffe::EltwiseLayer< Dtype >`:



## Public Member Functions

- **EltwiseLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **MinBottomBlobs** () const  
*Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void **Forward\_cpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)

*Using the CPU device, compute the layer output.*

- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

*Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- EltwiseParameter\_EltwiseOp **op\_**
- vector< Dtype > **coeffs\_**
- [Blob](#)< int > **max\_idx\_**
- bool **stable\_prod\_grad\_**

### 5.35.1 Detailed Description

```
template<typename Dtype>
class caffe::EltwiseLayer< Dtype >
```

Compute elementwise operations, such as product and sum, along multiple input Blobs.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

### 5.35.2 Member Function Documentation

#### 5.35.2.1 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::EltwiseLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer](#)< Dtype >.

#### 5.35.2.2 LayerSetUp()

```
template<typename Dtype >
void caffe::EltwiseLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.35.2.3 MinBottomBlobs()

```
template<typename Dtype >
virtual int caffe::EltwiseLayer< Dtype >::MinBottomBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.35.2.4 Reshape()

```
template<typename Dtype >
void caffe::EltwiseLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

- include/caffe/layers/eltwise\_layer.hpp
- src/caffe/layers/eltwise\_layer.cpp

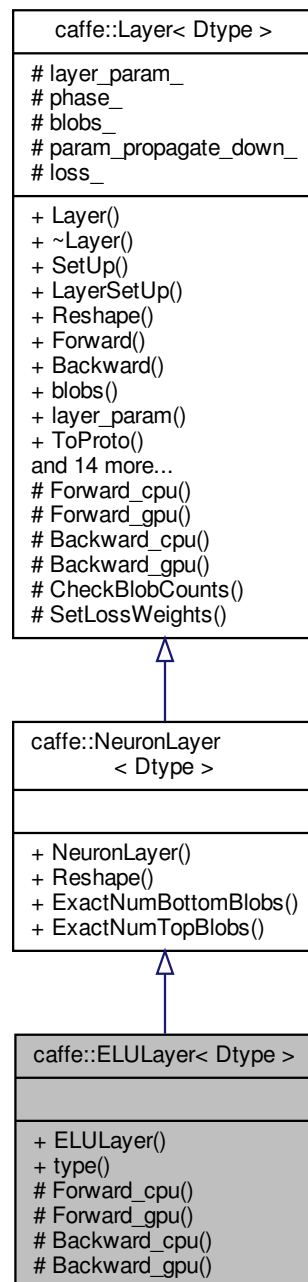


## 5.36 caffe::ELULayer< Dtype > Class Template Reference

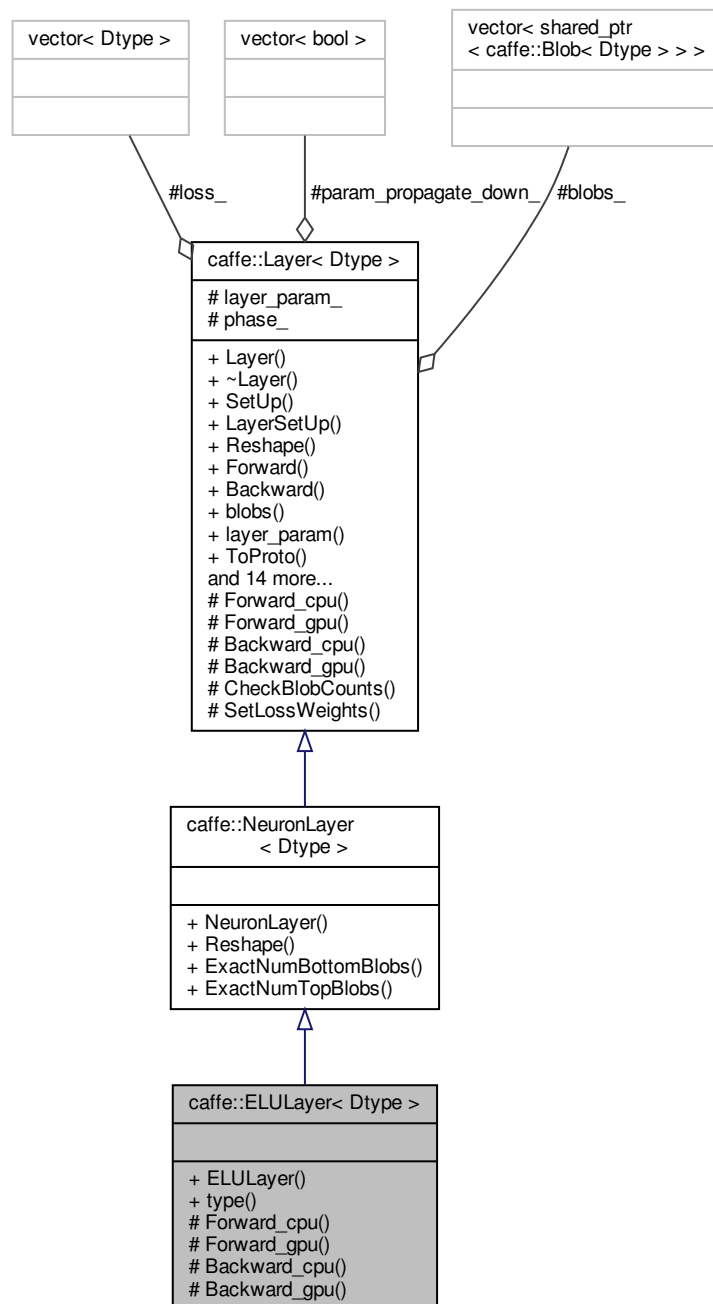
Exponential Linear Unit non-linearity  $y = \begin{cases} x & \text{if } x > 0 \\ \alpha(\exp(x) - 1) & \text{if } x \leq 0 \end{cases} .$

```
#include <elu_layer.hpp>
```

Inheritance diagram for caffe::ELULayer< Dtype >:



Collaboration diagram for `caffe::ELULayer< Dtype >`:



## Public Member Functions

- [ELULayer](#) (const LayerParameter &param)
- virtual const char \* [type](#) () const

*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the error gradient w.r.t. the ELU inputs.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Additional Inherited Members

### 5.36.1 Detailed Description

```
template<typename Dtype>
class caffe::ELULayer< Dtype >
```

Exponential Linear Unit non-linearity  $y = \begin{cases} x & \text{if } x > 0 \\ \alpha(\exp(x) - 1) & \text{if } x \leq 0 \end{cases}$ .

### 5.36.2 Constructor & Destructor Documentation

#### 5.36.2.1 ELULayer()

```
template<typename Dtype >
caffe::ELULayer< Dtype >::ELULayer (
    const LayerParameter & param ) [inline], [explicit]
```

#### Parameters

<i>param</i>	provides ELUParameter elu_param, with <a href="#">ELULayer</a> options: <ul style="list-style-type: none"> <li>• alpha (<b>optional</b>, default 1). the value <math>\alpha</math> by which controls saturation for negative inputs.</li> </ul>
--------------	---

### 5.36.3 Member Function Documentation

## 5.36.3.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::ELULayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the ELU inputs.

## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times H \times W)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$ ; Backward fills their diff with gradients $\frac{\partial E}{\partial x} = \begin{cases} 1 & \text{if } x > 0 \\ y + \alpha & \text{if } x \leq 0 \end{cases} \text{ if propagate\_down}[0].$

Implements [caffe::Layer< Dtype >](#).

## 5.36.3.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::ELULayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = \begin{cases} x & \text{if } x > 0 \\ \alpha(\exp(x) - 1) & \text{if } x \leq 0 \end{cases}$ .

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

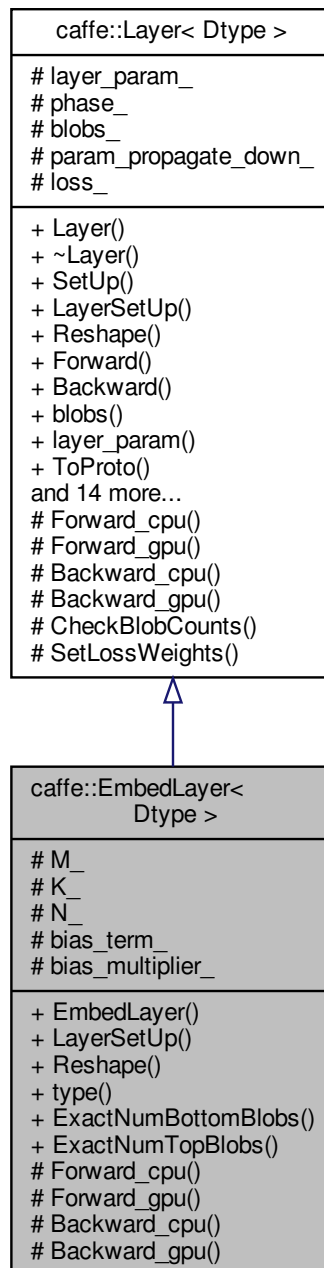
- include/caffe/layers/elu\_layer.hpp
- src/caffe/layers/elu\_layer.cpp

## 5.37 caffe::EmbedLayer< Dtype > Class Template Reference

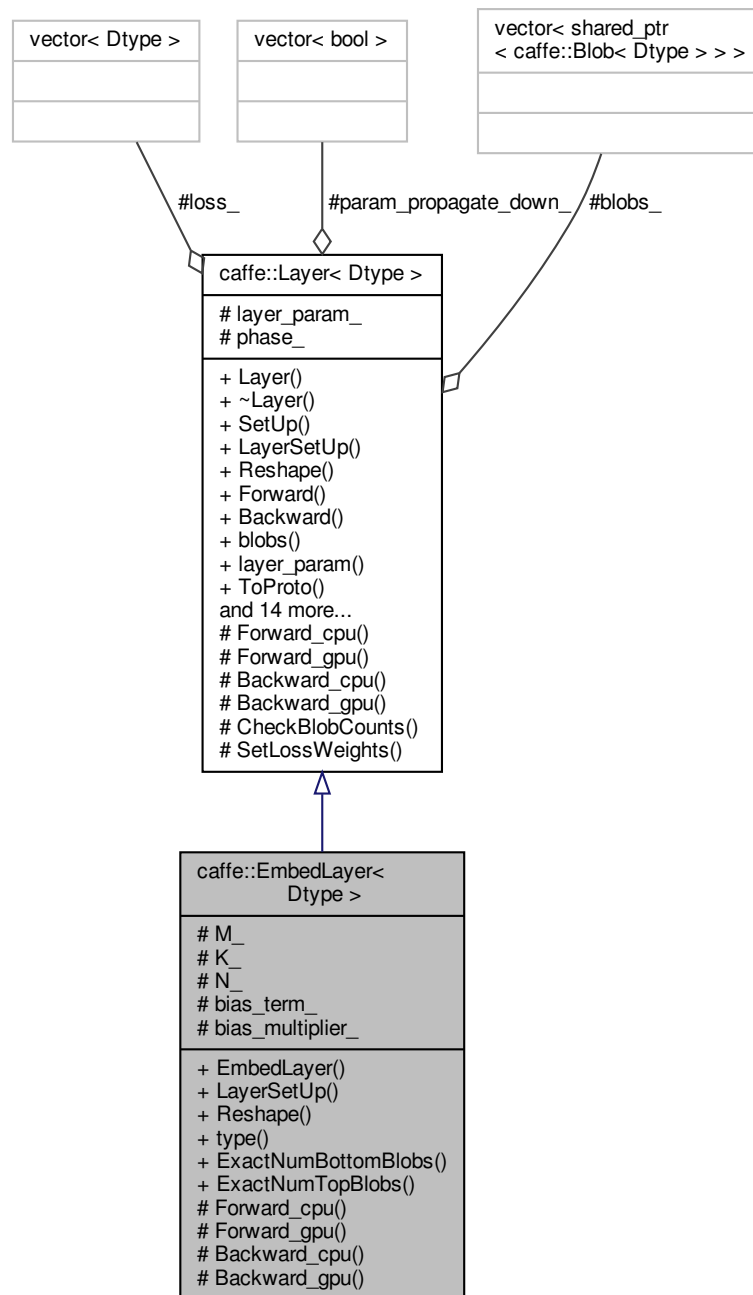
A layer for learning "embeddings" of one-hot vector input. Equivalent to an [InnerProductLayer](#) with one-hot vectors as input, but for efficiency the input is the "hot" index of each column itself.

```
#include <embed_layer.hpp>
```

Inheritance diagram for caffe::EmbedLayer< Dtype >:



Collaboration diagram for `caffe::EmbedLayer< Dtype >`:



## Public Member Functions

- **EmbedLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*

- virtual const char \* `type` () const  
*Returns the layer type.*
- virtual int `ExactNumBottomBlobs` () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int `ExactNumTopBlobs` () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

### Protected Member Functions

- virtual void `Forward_cpu` (const vector< `Blob< Dtype > *` &bottom, const vector< `Blob< Dtype > *` &top)  
*Using the CPU device, compute the layer output.*
- virtual void `Forward_gpu` (const vector< `Blob< Dtype > *` &bottom, const vector< `Blob< Dtype > *` &top)  
*Using the GPU device, compute the layer output. Fall back to `Forward_cpu()` if unavailable.*
- virtual void `Backward_cpu` (const vector< `Blob< Dtype > *` &top, const vector< bool > &propagate\_down, const vector< `Blob< Dtype > *` &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void `Backward_gpu` (const vector< `Blob< Dtype > *` &top, const vector< bool > &propagate\_down, const vector< `Blob< Dtype > *` &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to `Backward_cpu()` if unavailable.*

### Protected Attributes

- int `M_`
- int `K_`
- int `N_`
- bool `bias_term_`
- `Blob< Dtype >` `bias_multiplier_`

#### 5.37.1 Detailed Description

```
template<typename Dtype>
class caffe::EmbedLayer< Dtype >
```

A layer for learning "embeddings" of one-hot vector input. Equivalent to an `InnerProductLayer` with one-hot vectors as input, but for efficiency the input is the "hot" index of each column itself.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

#### 5.37.2 Member Function Documentation

### 5.37.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::EmbedLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.37.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::EmbedLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.37.2.3 LayerSetUp()

```
template<typename Dtype >
void caffe::EmbedLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

#### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).



## 5.37.2.4 Reshape()

```
template<typename Dtype >
void caffe::EmbedLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

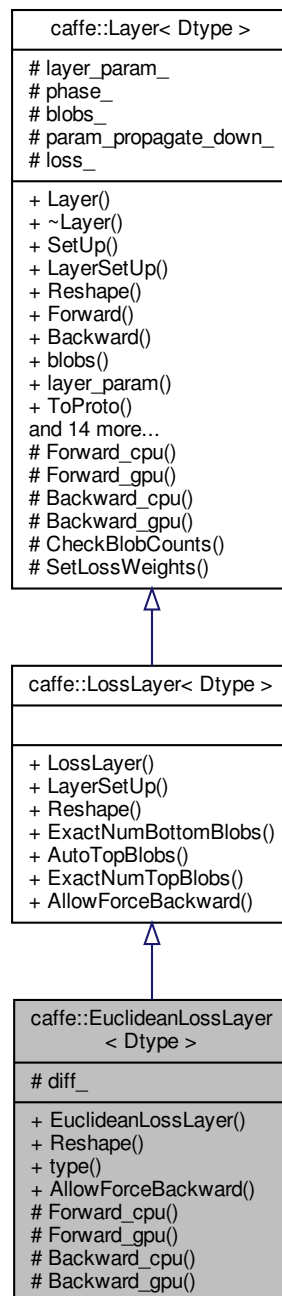
- include/caffe/layers/embed\_layer.hpp
- src/caffe/layers/embed\_layer.cpp

## 5.38 caffe::EuclideanLossLayer&lt; Dtype &gt; Class Template Reference

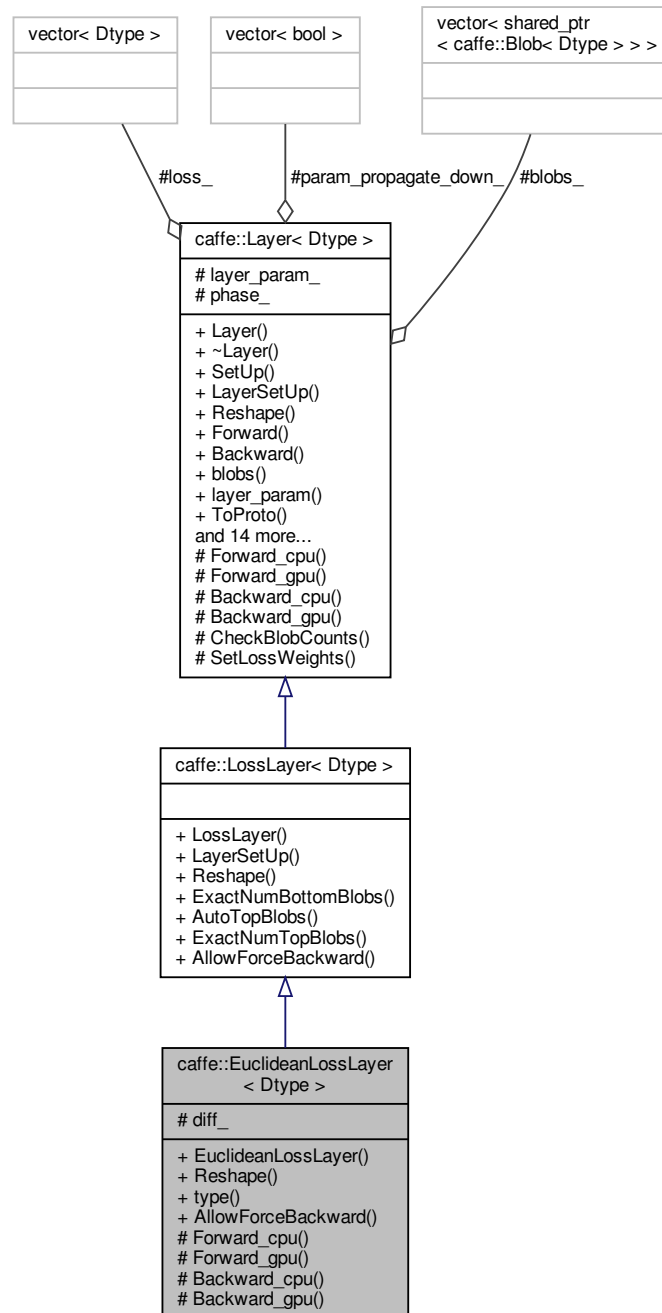
Computes the Euclidean (L2) loss  $E = \frac{1}{2N} \sum_{n=1}^N \|\hat{y}_n - y_n\|_2^2$  for real-valued regression tasks.

```
#include <euclidean_loss_layer.hpp>
```

Inheritance diagram for `caffe::EuclideanLossLayer< Dtype >`:



Collaboration diagram for caffe::EuclideanLossLayer< Dtype >:



## Public Member Functions

- **EuclideanLossLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual bool **AllowForceBackward** (const int bottom\_index) const

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Computes the Euclidean (L2) loss  $E = \frac{1}{2N} \sum_{n=1}^N \|\hat{y}_n - y_n\|_2^2$  for real-valued regression tasks.*

- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the Euclidean error gradient w.r.t. the inputs.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- [Blob](#)< Dtype > **diff\_**

### 5.38.1 Detailed Description

```
template<typename Dtype>
class caffe::EuclideanLossLayer< Dtype >
```

Computes the Euclidean (L2) loss  $E = \frac{1}{2N} \sum_{n=1}^N \|\hat{y}_n - y_n\|_2^2$  for real-valued regression tasks.

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the predictions <math>\hat{y} \in [-\infty, +\infty]</math></li> <li><math>(N \times C \times H \times W)</math> the targets <math>y \in [-\infty, +\infty]</math></li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> the computed Euclidean loss: <math>E = \frac{1}{2n} \sum_{n=1}^N \ \hat{y}_n - y_n\ _2^2</math></li> </ol>

This can be used for least-squares regression tasks. An [InnerProductLayer](#) input to a [EuclideanLossLayer](#) exactly formulates a linear least squares regression problem. With non-zero weight decay the problem becomes one of ridge regression – see `src/caffe/test/test_gradient_based_solver.cpp` for a concrete example wherein we check that the gradients computed for a [Net](#) with exactly this structure match hand-computed gradient formulas for ridge regression.

(Note: [Caffe](#), and SGD in general, is certainly **not** the best way to solve linear least squares problems! We use it only as an instructive example.)

## 5.38.2 Member Function Documentation

5.38.2.1 `AllowForceBackward()`

```
template<typename Dtype >
virtual bool caffe::EuclideanLossLayer< Dtype >::AllowForceBackward (
    const int bottom_index ) const [inline], [virtual]
```

Unlike most loss layers, in the `EuclideanLossLayer` we can backpropagate to both inputs – override to return true and always allow `force_backward`.

Reimplemented from `caffe::LossLayer< Dtype >`.

5.38.2.2 `Backward_cpu()`

```
template<typename Dtype >
void caffe::EuclideanLossLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > * > & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > * > & bottom ) [protected], [virtual]
```

Computes the Euclidean error gradient w.r.t. the inputs.

Unlike other children of `LossLayer`, `EuclideanLossLayer` **can** compute gradients with respect to the label inputs `bottom[1]` (but still only will if `propagate_down[1]` is set, due to being produced by learnable parameters or if `force_backward` is set). In fact, this layer is "commutative" – the result is the same regardless of the order of the two bottoms.

## Parameters

<i>top</i>	output <code>Blob</code> vector (length 1), providing the error gradient with respect to the outputs <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> This <code>Blob</code>'s diff will simply contain the <code>loss_weight * λ</code>, as <math>λ</math> is the coefficient of this layer's output <math>ℓ_i</math> in the overall <code>Net</code> loss <math>E = λ_i ℓ_i + \text{other loss terms}</math>; hence <math>\frac{\partial E}{\partial ℓ_i} = λ_i</math>. (*Assuming that this top <code>Blob</code> is not used as a bottom (input) by any other layer of the <code>Net</code>.)</li> </ol>
<i>propagate_down</i>	see <code>Layer::Backward</code> .
<i>bottom</i>	input <code>Blob</code> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the predictions <math>\hat{y}</math>; Backward fills their diff with gradients <math display="block">\frac{\partial E}{\partial \hat{y}} = \frac{1}{n} \sum_{n=1}^N (\hat{y}_n - y_n) \text{ if } \text{propagate\_down}[0]</math> </li> <li><math>(N \times C \times H \times W)</math> the targets <math>y</math>; Backward fills their diff with gradients <math display="block">\frac{\partial E}{\partial y} = \frac{1}{n} \sum_{n=1}^N (y_n - \hat{y}_n) \text{ if } \text{propagate\_down}[1]</math> </li> </ol>

Implements `caffe::Layer< Dtype >`.

### 5.38.2.3 Forward\_cpu()

```
template<typename Dtype >
void caffe::EuclideanLossLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

Computes the Euclidean (L2) loss  $E = \frac{1}{2N} \sum_{n=1}^N \|\hat{y}_n - y_n\|_2^2$  for real-valued regression tasks.

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the predictions <math>\hat{y} \in [-\infty, +\infty]</math></li> <li><math>(N \times C \times H \times W)</math> the targets <math>y \in [-\infty, +\infty]</math></li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> the computed Euclidean loss: <math>E = \frac{1}{2n} \sum_{n=1}^N \ \hat{y}_n - y_n\ _2^2</math></li> </ol>

This can be used for least-squares regression tasks. An [InnerProductLayer](#) input to a [EuclideanLossLayer](#) exactly formulates a linear least squares regression problem. With non-zero weight decay the problem becomes one of ridge regression – see `src/caffe/test/test_gradient_based_solver.cpp` for a concrete example wherein we check that the gradients computed for a [Net](#) with exactly this structure match hand-computed gradient formulas for ridge regression.

(Note: [Caffe](#), and SGD in general, is certainly **not** the best way to solve linear least squares problems! We use it only as an instructive example.)

Implements [caffe::Layer< Dtype >](#).

### 5.38.2.4 Reshape()

```
template<typename Dtype >
void caffe::EuclideanLossLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

#### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as

reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Reimplemented from [caffe::LossLayer< Dtype >](#).

The documentation for this class was generated from the following files:

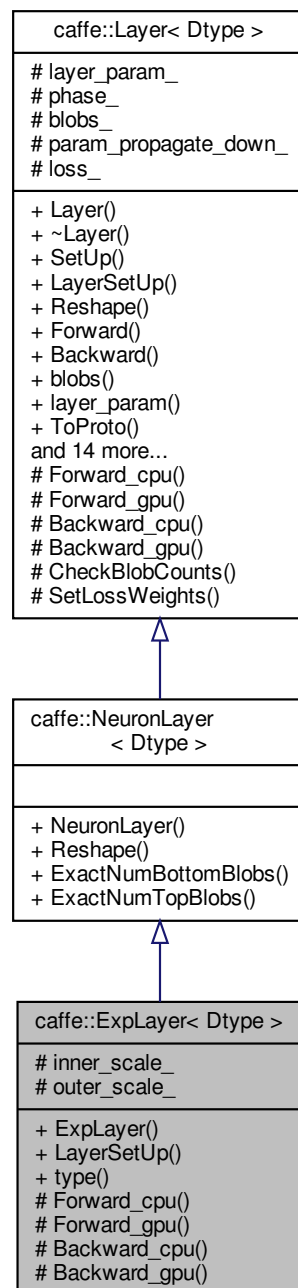
- `include/caffe/layers/euclidean_loss_layer.hpp`
- `src/caffe/layers/euclidean_loss_layer.cpp`

## 5.39 `caffe::ExpLayer< Dtype >` Class Template Reference

Computes  $y = \gamma^{\alpha x + \beta}$ , as specified by the scale  $\alpha$ , shift  $\beta$ , and base  $\gamma$ .

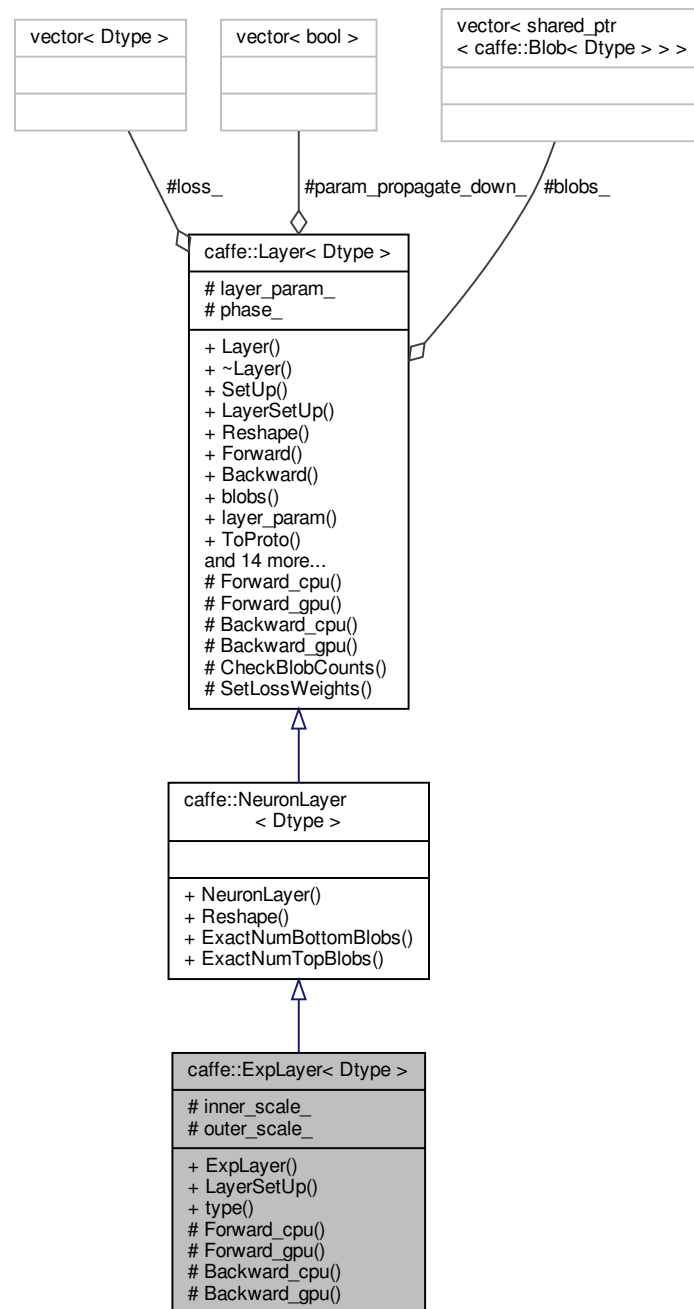
```
#include <exp_layer.hpp>
```

Inheritance diagram for `caffe::ExpLayer< Dtype >`:





Collaboration diagram for caffe::ExpLayer< Dtype >:



## Public Member Functions

- [ExpLayer](#) (const LayerParameter &param)
- virtual void [LayerSetUp](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as *Reshape*.
- virtual const char \* [type](#) () const  
Returns the layer type.

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the error gradient w.r.t. the exp inputs.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- Dtype **inner\_scale\_**
- Dtype **outer\_scale\_**

### 5.39.1 Detailed Description

```
template<typename Dtype>
class caffe::ExpLayer< Dtype >
```

Computes  $y = \gamma^{\alpha x + \beta}$ , as specified by the scale  $\alpha$ , shift  $\beta$ , and base  $\gamma$ .

### 5.39.2 Constructor & Destructor Documentation

#### 5.39.2.1 ExpLayer()

```
template<typename Dtype >
caffe::ExpLayer< Dtype >::ExpLayer (
    const LayerParameter & param ) [inline], [explicit]
```

#### Parameters

<i>param</i>	provides ExpParameter exp_param, with <a href="#">ExpLayer</a> options: <ul style="list-style-type: none"> <li>• scale (<b>optional</b>, default 1) the scale <math>\alpha</math></li> <li>• shift (<b>optional</b>, default 0) the shift <math>\beta</math></li> <li>• base (<b>optional</b>, default -1 for a value of <math>e \approx 2.718</math>) the base <math>\gamma</math></li> </ul>
--------------	--

### 5.39.3 Member Function Documentation

#### 5.39.3.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::ExpLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the exp inputs.

##### Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times H \times W)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$ ; Backward fills their diff with gradients $\frac{\partial E}{\partial x} = \frac{\partial E}{\partial y} y \alpha \log_e(\gamma)$ if <code>propagate_down[0]</code>

Implements [caffe::Layer< Dtype >](#).

#### 5.39.3.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::ExpLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

##### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = \gamma^{\alpha x + \beta}$

Implements [caffe::Layer< Dtype >](#).

### 5.39.3.3 LayerSetUp()

```
template<typename Dtype >
void caffe::ExpLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

#### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following files:

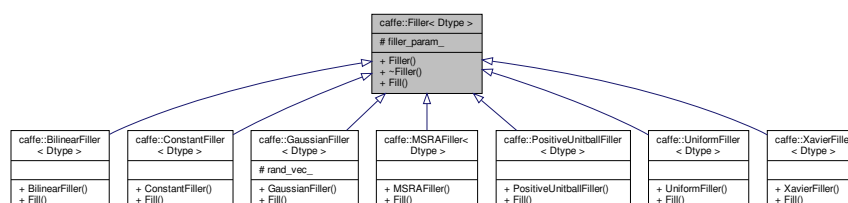
- include/caffe/layers/exp\_layer.hpp
- src/caffe/layers/exp\_layer.cpp

## 5.40 caffe::Filler< Dtype > Class Template Reference

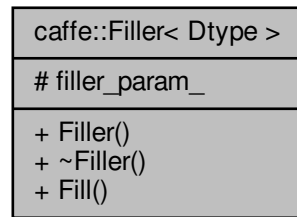
Fills a `Blob` with constant or randomly-generated data.

```
#include <filler.hpp>
```

Inheritance diagram for `caffe::Filler< Dtype >`:



Collaboration diagram for caffe::Filler< Dtype >:



### Public Member Functions

- **Filler** (const FillerParameter &param)
- virtual void **Fill** (Blob< Dtype > \*blob)=0

### Protected Attributes

- FillerParameter **filler\_param\_**

#### 5.40.1 Detailed Description

```
template<typename Dtype>
class caffe::Filler< Dtype >
```

Fills a [Blob](#) with constant or randomly-generated data.

The documentation for this class was generated from the following file:

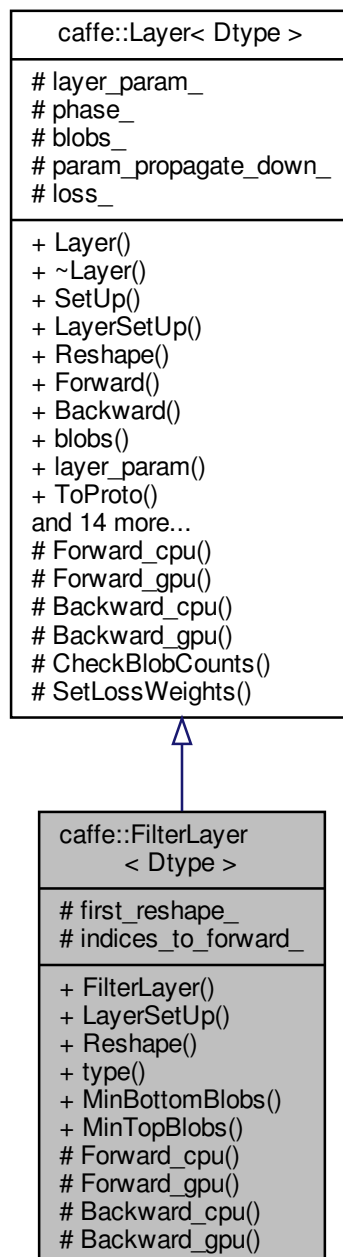
- include/caffe/filler.hpp

## 5.41 caffe::FilterLayer< Dtype > Class Template Reference

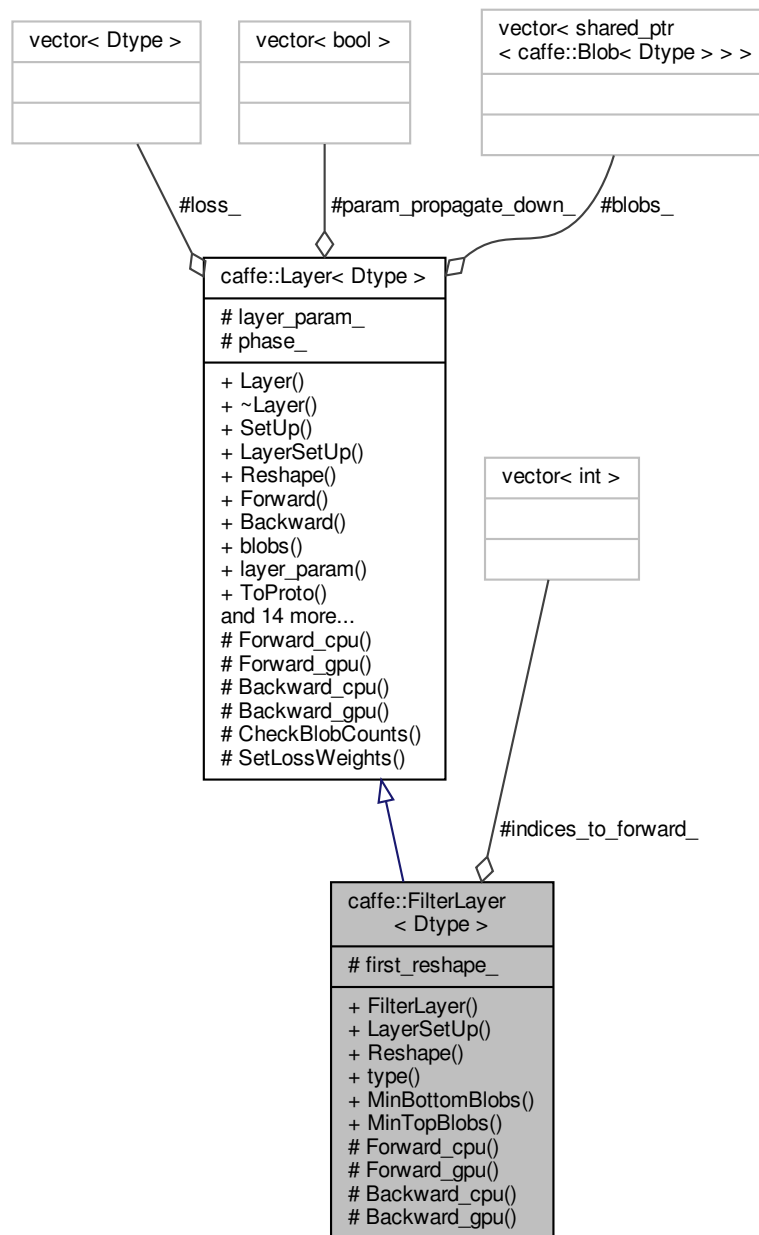
Takes two+ Blobs, interprets last [Blob](#) as a selector and filter remaining Blobs accordingly with selector data (0 means that the corresponding item has to be filtered, non-zero means that corresponding item needs to stay).

```
#include <filter_layer.hpp>
```

Inheritance diagram for `caffe::FilterLayer< Dtype >`:



Collaboration diagram for caffe::FilterLayer< Dtype >:



## Public Member Functions

- **FilterLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const

*Returns the layer type.*

- virtual int [MinBottomBlobs](#) () const

*Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.*

- virtual int [MinTopBlobs](#) () const

*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

*Computes the error gradient w.r.t. the forwarded inputs.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- bool **first\_reshape\_**
- vector< int > **indices\_to\_forward\_**

### 5.41.1 Detailed Description

```
template<typename Dtype>
class caffe::FilterLayer< Dtype >
```

Takes two+ Blobs, interprets last [Blob](#) as a selector and filter remaining Blobs accordingly with selector data (0 means that the corresponding item has to be filtered, non-zero means that corresponding item needs to stay).

### 5.41.2 Member Function Documentation

#### 5.41.2.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::FilterLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > * > & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > * > & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the forwarded inputs.



## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1+), providing the error gradient with respect to the outputs
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 2+), into which the top error gradient is copied

Implements [caffe::Layer< Dtype >](#).

## 5.41.2.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::FilterLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2+) <ol style="list-style-type: none"> <li>1. <math>(N \times C \times H \times W)</math> the inputs to be filtered <math>x_1</math></li> <li>2. ...</li> <li>3. <math>(N \times C \times H \times W)</math> the inputs to be filtered <math>x_K</math></li> <li>4. <math>(N \times 1 \times 1 \times 1)</math> the selector blob</li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1+) <ol style="list-style-type: none"> <li>1. <math>(S \times C \times H \times W)</math> () the filtered output <math>x_1</math> where S is the number of items that haven't been filtered <math>(S \times C \times H \times W)</math> the filtered output <math>x_K</math> where S is the number of items that haven't been filtered</li> </ol>

Implements [caffe::Layer< Dtype >](#).

## 5.41.2.3 LayerSetUp()

```
template<typename Dtype >
void caffe::FilterLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.41.2.4 MinBottomBlobs()

```
template<typename Dtype >
virtual int caffe::FilterLayer< Dtype >::MinBottomBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.41.2.5 MinTopBlobs()

```
template<typename Dtype >
virtual int caffe::FilterLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.41.2.6 Reshape()

```
template<typename Dtype >
void caffe::FilterLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

##### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as

reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following files:

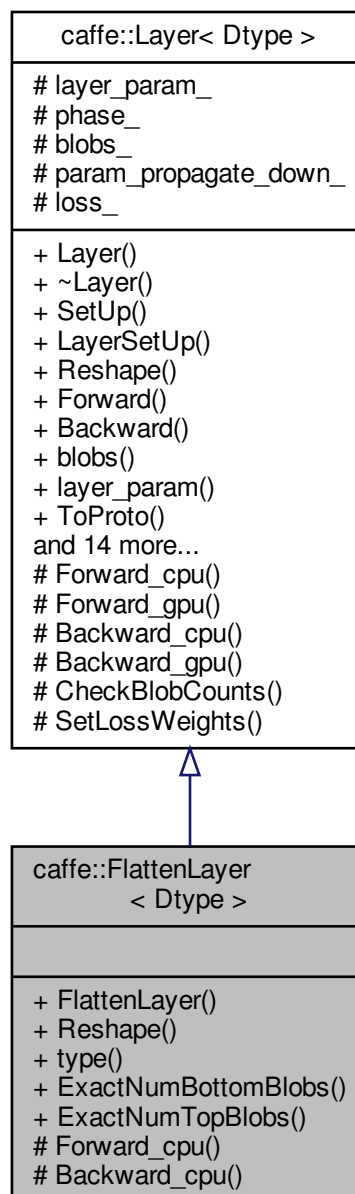
- `include/caffe/layers/filter_layer.hpp`
- `src/caffe/layers/filter_layer.cpp`

## 5.42 `caffe::FlattenLayer< Dtype >` Class Template Reference

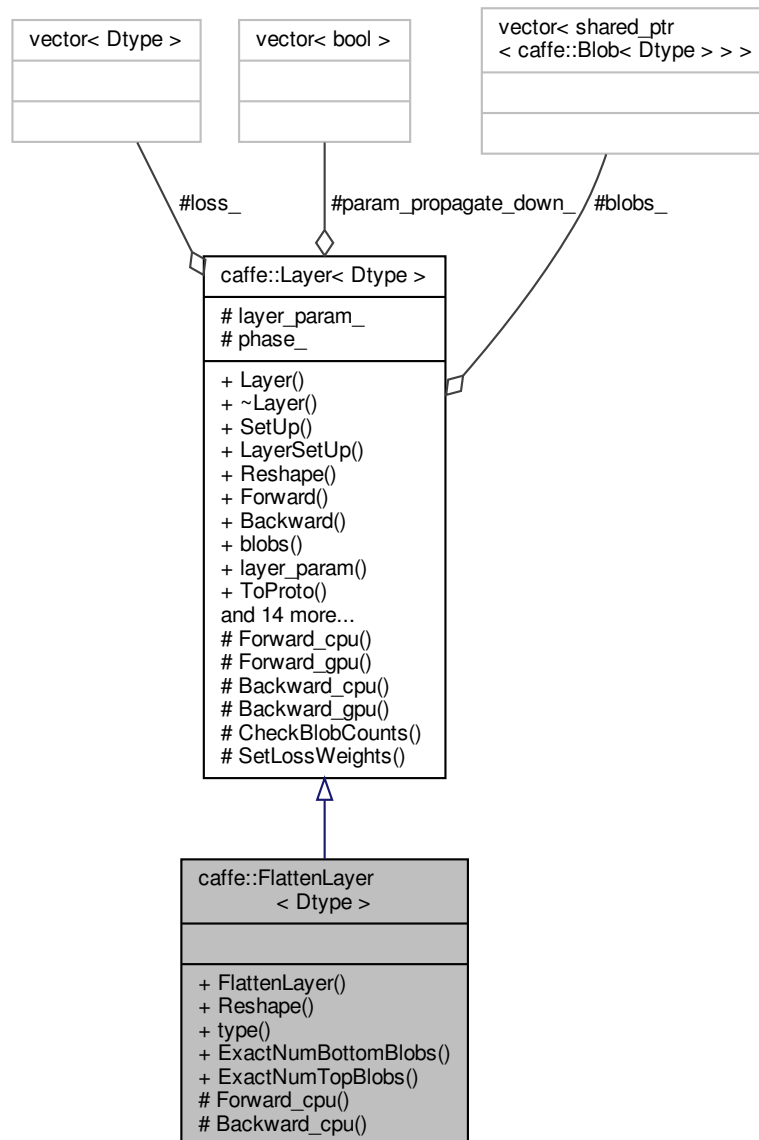
Reshapes the input `Blob` into flat vectors.

```
#include <flatten_layer.hpp>
```

Inheritance diagram for `caffe::FlattenLayer< Dtype >`:



Collaboration diagram for caffe::FlattenLayer< Dtype >:



## Public Member Functions

- **FlattenLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the error gradient w.r.t. the concatenate inputs.*

## Additional Inherited Members

### 5.42.1 Detailed Description

```
template<typename Dtype>
class caffe::FlattenLayer< Dtype >
```

Reshapes the input [Blob](#) into flat vectors.

Note: because this layer does not change the input values – merely the dimensions – it can simply copy the input. The copy happens "virtually" (thus taking effectively 0 real time) by setting, in Forward, the data pointer of the top [Blob](#) to that of the bottom [Blob](#) (see [Blob::ShareData](#)), and in Backward, the diff pointer of the bottom [Blob](#) to that of the top [Blob](#) (see [Blob::ShareDiff](#)).

### 5.42.2 Member Function Documentation

#### 5.42.2.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::FlattenLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom )    [protected], [virtual]
```

Computes the error gradient w.r.t. the concatenate inputs.

#### Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length K), into which the top error gradient is (virtually) copied

Implements [caffe::Layer< Dtype >](#).

5.42.2.2 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::FlattenLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.42.2.3 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::FlattenLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.42.2.4 `Forward_cpu()`

```
template<typename Dtype >
void caffe::FlattenLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <code>Blob</code> vector (length 2+) 1. $(N \times C \times H \times W)$ the inputs
<i>top</i>	output <code>Blob</code> vector (length 1) 1. $(N \times CHW \times 1 \times 1)$ the outputs – i.e., the (virtually) copied, flattened inputs

Implements `caffe::Layer< Dtype >`.

5.42.2.5 `Reshape()`

```
template<typename Dtype >
void caffe::FlattenLayer< Dtype >::Reshape (
```

```
const vector< Blob< Dtype > * > & bottom,
const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

#### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

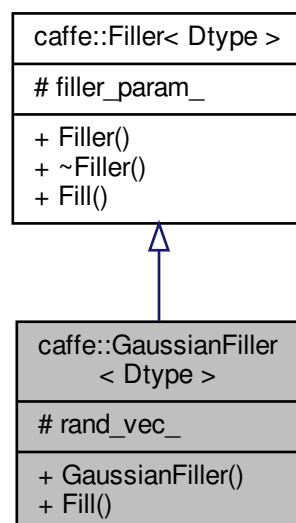
- include/caffe/layers/flatten\_layer.hpp
- src/caffe/layers/flatten\_layer.cpp

## 5.43 [caffe::GaussianFiller< Dtype >](#) Class Template Reference

Fills a [Blob](#) with Gaussian-distributed values  $x = a$ .

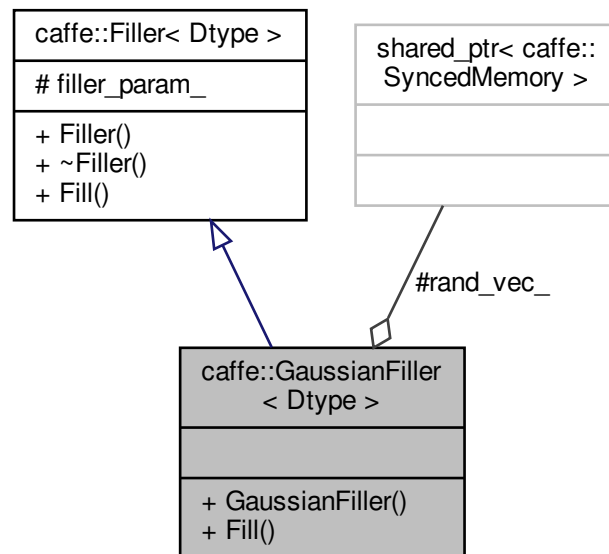
```
#include <filler.hpp>
```

Inheritance diagram for [caffe::GaussianFiller< Dtype >](#):





Collaboration diagram for caffe::GaussianFiller< Dtype >:



## Public Member Functions

- **GaussianFiller** (const FillerParameter &param)
- virtual void **Fill** ([Blob](#)< Dtype > \*blob)

## Protected Attributes

- shared\_ptr< [SyncedMemory](#) > **rand\_vec\_**

### 5.43.1 Detailed Description

```
template<typename Dtype>
class caffe::GaussianFiller< Dtype >
```

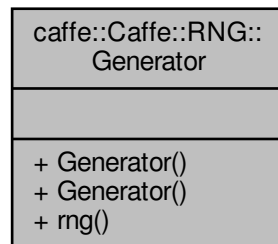
Fills a [Blob](#) with Gaussian-distributed values  $x = a$ .

The documentation for this class was generated from the following file:

- include/caffe/filler.hpp

## 5.44 `caffe::Caffe::RNG::Generator` Class Reference

Collaboration diagram for `caffe::Caffe::RNG::Generator`:



### Public Member Functions

- **Generator** (unsigned int seed)
- `caffe::rng_t * rng ()`

The documentation for this class was generated from the following file:

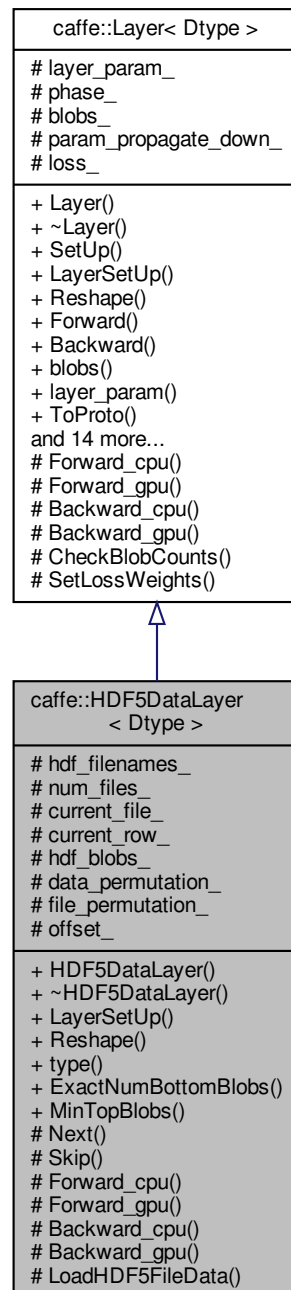
- `src/caffe/common.cpp`

## 5.45 `caffe::HDF5DataLayer< Dtype >` Class Template Reference

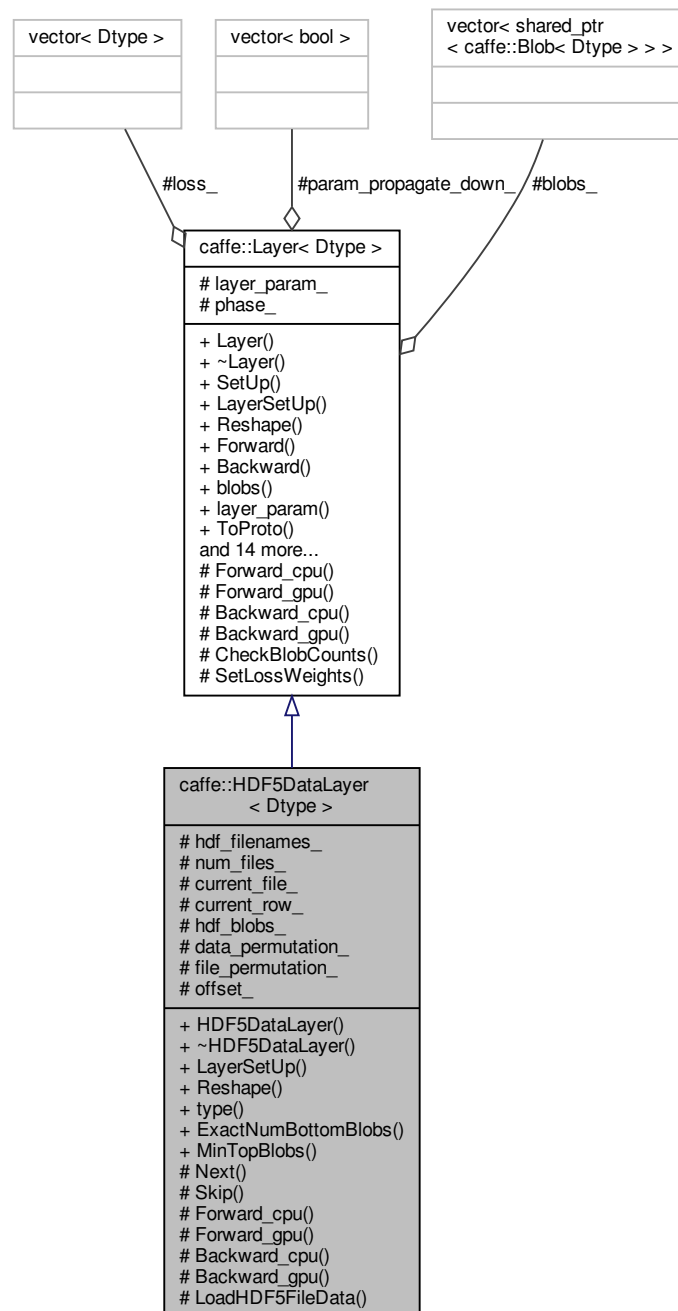
Provides data to the [Net](#) from HDF5 files.

```
#include <hdf5_data_layer.hpp>
```

Inheritance diagram for caffe::HDF5DataLayer< Dtype >:



Collaboration diagram for `caffe::HDF5DataLayer< Dtype >`:



## Public Member Functions

- **HDF5DataLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*

- virtual const char \* [type](#) () const  
*Returns the layer type.*
- virtual int [ExactNumBottomBlobs](#) () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int [MinTopBlobs](#) () const  
*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*

### Protected Member Functions

- void **Next** ()
- bool **Skip** ()
- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*
- virtual void **LoadHDF5FileData** (const char \*filename)

### Protected Attributes

- std::vector< std::string > **hdf\_filenames\_**
- unsigned int **num\_files\_**
- unsigned int **current\_file\_**
- hsize\_t **current\_row\_**
- std::vector< shared\_ptr< [Blob](#)< Dtype > > > **hdf\_blobs\_**
- std::vector< unsigned int > **data\_permutation\_**
- std::vector< unsigned int > **file\_permutation\_**
- uint64\_t **offset\_**

#### 5.45.1 Detailed Description

```
template<typename Dtype>
class caffe::HDF5DataLayer< Dtype >
```

Provides data to the [Net](#) from HDF5 files.

TODO(dox): thorough documentation for Forward and proto params.

#### 5.45.2 Member Function Documentation

#### 5.45.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::HDF5DataLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.45.2.2 LayerSetUp()

```
template<typename Dtype >
virtual void caffe::HDF5DataLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

##### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.45.2.3 MinTopBlobs()

```
template<typename Dtype >
virtual int caffe::HDF5DataLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.45.2.4 Reshape()

```
template<typename Dtype >
virtual void caffe::HDF5DataLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [inline], [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

**Parameters**

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following file:

- `include/caffe/layers/hdf5_data_layer.hpp`

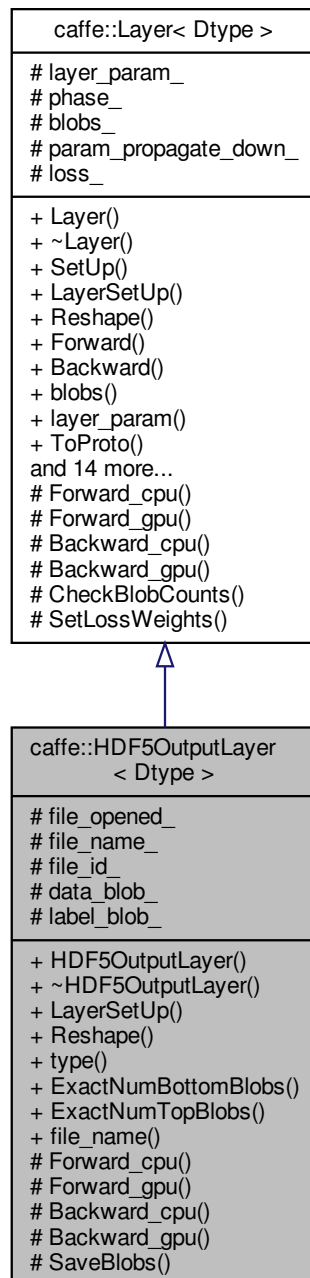
## 5.46 `caffe::HDF5OutputLayer< Dtype >` Class Template Reference

Write blobs to disk as HDF5 files.

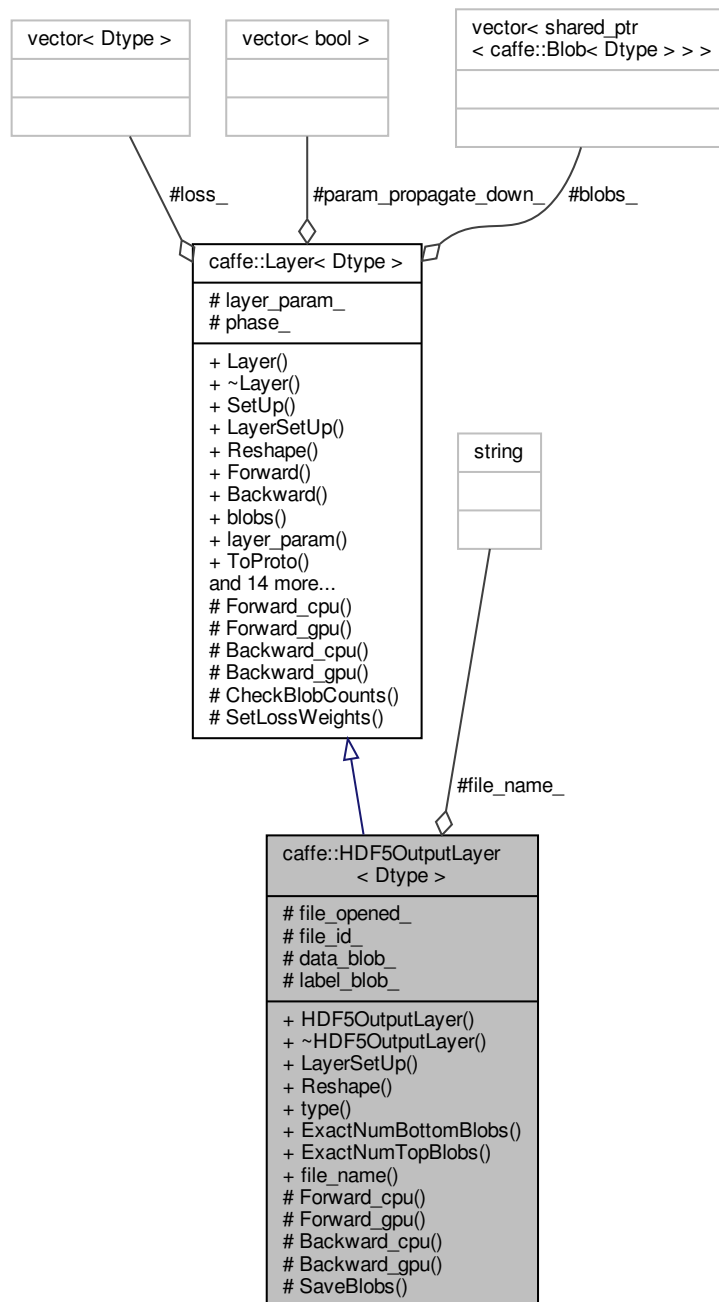
```
#include <hdf5_output_layer.hpp>
```



Inheritance diagram for caffe::HDF5OutputLayer< Dtype >:



Collaboration diagram for `caffe::HDF5OutputLayer< Dtype >`:



## Public Member Functions

- **HDF5OutputLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*

- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*
- std::string **file\_name** () const

### Protected Member Functions

- virtual void **Forward\_cpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Using the CPU device, compute the layer output.*
- virtual void **Forward\_gpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to **Forward\_cpu()** if unavailable.*
- virtual void **Backward\_cpu** (const vector< **Blob**< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< **Blob**< Dtype > \* > &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void **Backward\_gpu** (const vector< **Blob**< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< **Blob**< Dtype > \* > &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to **Backward\_cpu()** if unavailable.*
- virtual void **SaveBlobs** ()

### Protected Attributes

- bool **file\_opened\_**
- std::string **file\_name\_**
- hid\_t **file\_id\_**
- **Blob**< Dtype > **data\_blob\_**
- **Blob**< Dtype > **label\_blob\_**

#### 5.46.1 Detailed Description

```
template<typename Dtype>
class caffe::HDF5OutputLayer< Dtype >
```

Write blobs to disk as HDF5 files.

TODO(dox): thorough documentation for Forward and proto params.

#### 5.46.2 Member Function Documentation

#### 5.46.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::HDF5OutputLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.46.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::HDF5OutputLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.46.2.3 LayerSetUp()

```
template<typename Dtype >
virtual void caffe::HDF5OutputLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

##### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

5.46.2.4 `Reshape()`

```
template<typename Dtype >
virtual void caffe::HDF5OutputLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * & bottom,
    const vector< Blob< Dtype > * & top ) [inline], [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following file:

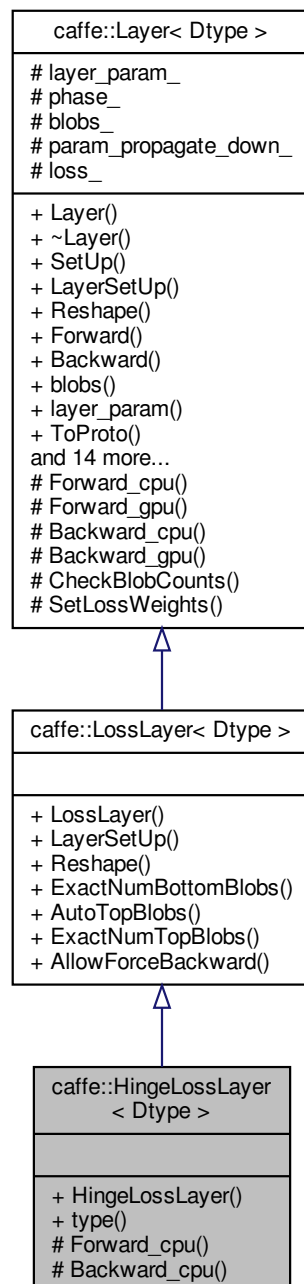
- `include/caffe/layers/hdf5_output_layer.hpp`

5.47 `caffe::HingeLossLayer< Dtype >` Class Template Reference

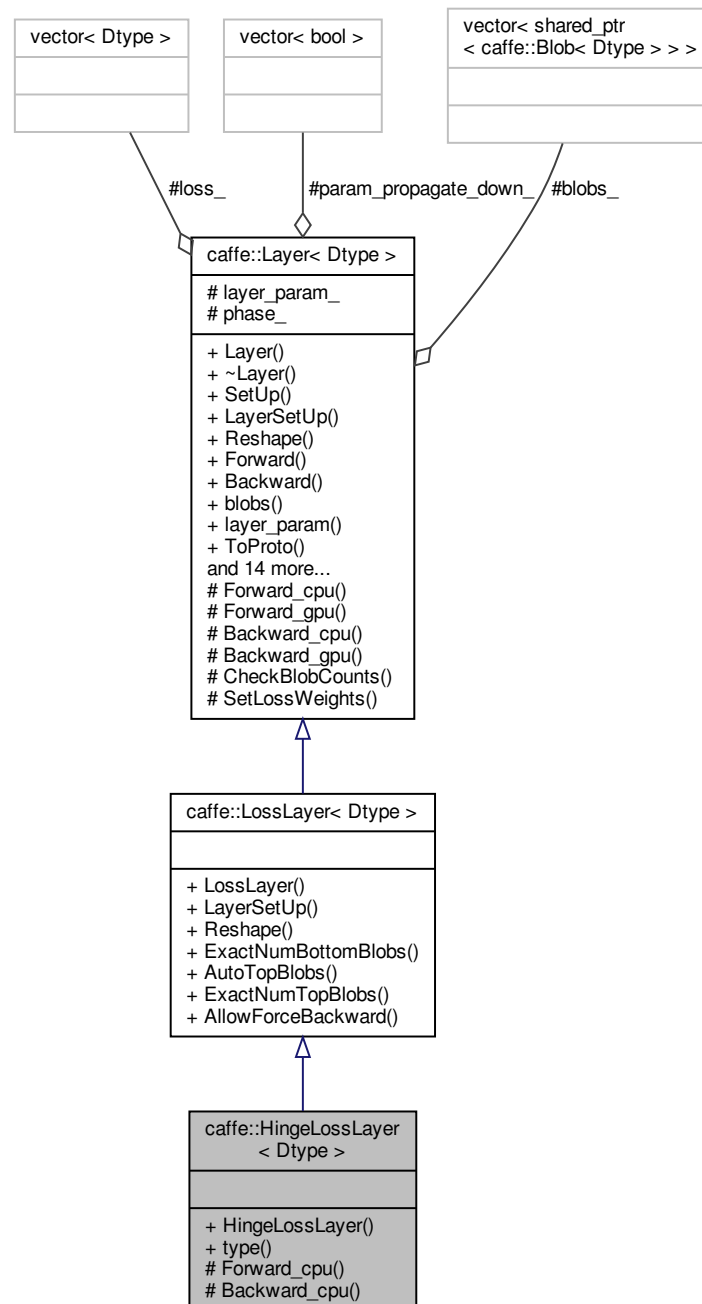
Computes the hinge loss for a one-of-many classification task.

```
#include <hinge_loss_layer.hpp>
```

Inheritance diagram for `caffe::HingeLossLayer< Dtype >`:



Collaboration diagram for caffe::HingeLossLayer< Dtype >:



## Public Member Functions

- **HingeLossLayer** (const LayerParameter &param)
- virtual const char \* **type** () const

*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Computes the hinge loss for a one-of-many classification task.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the hinge loss error gradient w.r.t. the predictions.*

## Additional Inherited Members

### 5.47.1 Detailed Description

```
template<typename Dtype>
class caffe::HingeLossLayer< Dtype >
```

Computes the hinge loss for a one-of-many classification task.

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the predictions <math>t</math>, a <a href="#">Blob</a> with values in <math>[-\infty, +\infty]</math> indicating the predicted score for each of the <math>K = CHW</math> classes. In an SVM, <math>t</math> is the result of taking the inner product <math>X^T W</math> of the <math>D</math>-dimensional features <math>X \in \mathcal{R}^{D \times N}</math> and the learned hyperplane parameters <math>W \in \mathcal{R}^{D \times K}</math>, so a <a href="#">Net</a> with just an <a href="#">InnerProductLayer</a> (with num_output = <math>D</math>) providing predictions to a <a href="#">HingeLossLayer</a> and no other learnable parameters or losses is equivalent to an SVM.</li> <li><math>(N \times 1 \times 1 \times 1)</math> the labels <math>l</math>, an integer-valued <a href="#">Blob</a> with values <math>l_n \in [0, 1, 2, \dots, K - 1]</math> indicating the correct class label among the <math>K</math> classes</li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> the computed hinge loss: <math>E = \frac{1}{N} \sum_{n=1}^N \sum_{k=1}^K [\max(0, 1 - \delta\{l_n = k\} t_{nk})]^p</math>, for the <math>L^p</math> norm (defaults to <math>p = 1</math>, the L1 norm; L2 norm, as in L2-SVM, is also available), and <math>\delta\{\text{condition}\} = \begin{cases} 1 &amp; \text{if condition} \\ -1 &amp; \text{otherwise} \end{cases}</math></li> </ol>

In an SVM,  $t \in \mathcal{R}^{N \times K}$  is the result of taking the inner product  $X^T W$  of the features  $X \in \mathcal{R}^{D \times N}$  and the learned hyperplane parameters  $W \in \mathcal{R}^{D \times K}$ . So, a [Net](#) with just an [InnerProductLayer](#) (with num\_output =  $K$ ) providing predictions to a [HingeLossLayer](#) is equivalent to an SVM (assuming it has no other learned outside the [InnerProductLayer](#) and no other losses outside the [HingeLossLayer](#)).

### 5.47.2 Member Function Documentation



## 5.47.2.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::HingeLossLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the hinge loss error gradient w.r.t. the predictions.

Gradients cannot be computed with respect to the label inputs (bottom[1]), so this method ignores bottom[1] and requires !propagate\_down[1], crashing if propagate\_down[1] is set.

## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> This <a href="#">Blob</a>'s diff will simply contain the loss_weight* <math>\lambda</math>, as <math>\lambda</math> is the coefficient of this layer's output <math>\ell_i</math> in the overall <a href="#">Net</a> loss <math>E = \lambda_i \ell_i + \text{other loss terms}</math>; hence <math>\frac{\partial E}{\partial \ell_i} = \lambda_i</math>. (*Assuming that this top <a href="#">Blob</a> is not used as a bottom (input) by any other layer of the <a href="#">Net</a>.)</li> </ol>
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> . propagate_down[1] must be false as we can't compute gradients with respect to the labels.
<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the predictions <math>t</math>; Backward computes diff <math>\frac{\partial E}{\partial t}</math></li> <li><math>(N \times 1 \times 1 \times 1)</math> the labels – ignored as we can't compute their error gradients</li> </ol>

Implements [caffe::Layer< Dtype >](#).

## 5.47.2.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::HingeLossLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

Computes the hinge loss for a one-of-many classification task.

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li>1. <math>(N \times C \times H \times W)</math> the predictions <math>t</math>, a <a href="#">Blob</a> with values in <math>[-\infty, +\infty]</math> indicating the predicted score for each of the <math>K = CHW</math> classes. In an SVM, <math>t</math> is the result of taking the inner product <math>X^T W</math> of the <math>D</math>-dimensional features <math>X \in \mathcal{R}^{D \times N}</math> and the learned hyperplane parameters <math>W \in \mathcal{R}^{D \times K}</math>, so a <a href="#">Net</a> with just an <a href="#">InnerProductLayer</a> (with num_output = D) providing predictions to a <a href="#">HingeLossLayer</a> and no other learnable parameters or losses is equivalent to an SVM.</li> <li>2. <math>(N \times 1 \times 1 \times 1)</math> the labels <math>l</math>, an integer-valued <a href="#">Blob</a> with values <math>l_n \in [0, 1, 2, \dots, K - 1]</math> indicating the correct class label among the <math>K</math> classes</li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li>1. <math>(1 \times 1 \times 1 \times 1)</math> the computed hinge loss: <math>E = \frac{1}{N} \sum_{n=1}^N \sum_{k=1}^K [\max(0, 1 - \delta\{l_n = k\} t_{nk})]^p</math>, for the <math>L^p</math> norm (defaults to <math>p = 1</math>, the L1 norm; L2 norm, as in L2-SVM, is also available), and <math>\delta\{\text{condition}\} = \begin{cases} 1 &amp; \text{if condition} \\ -1 &amp; \text{otherwise} \end{cases}</math></li> </ol>

In an SVM,  $t \in \mathcal{R}^{N \times K}$  is the result of taking the inner product  $X^T W$  of the features  $X \in \mathcal{R}^{D \times N}$  and the learned hyperplane parameters  $W \in \mathcal{R}^{D \times K}$ . So, a [Net](#) with just an [InnerProductLayer](#) (with num\_output =  $k$ ) providing predictions to a [HingeLossLayer](#) is equivalent to an SVM (assuming it has no other learned outside the [InnerProductLayer](#) and no other losses outside the [HingeLossLayer](#)).

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

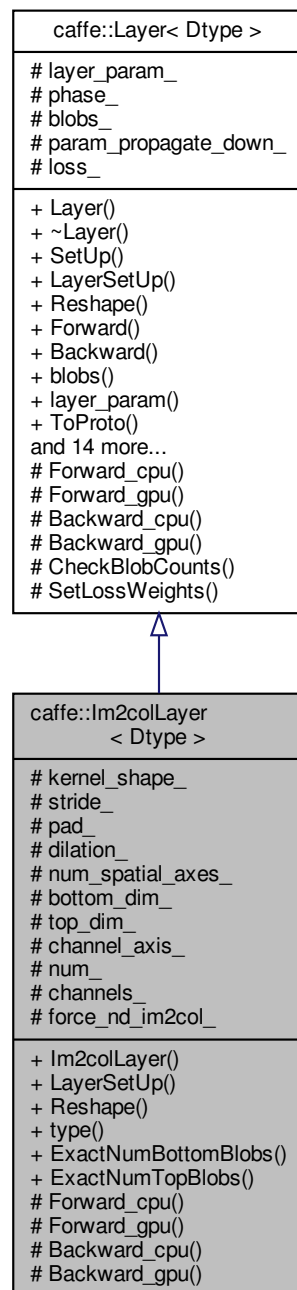
- include/caffe/layers/hinge\_loss\_layer.hpp
- src/caffe/layers/hinge\_loss\_layer.cpp

## 5.48 [caffe::Im2colLayer< Dtype >](#) Class Template Reference

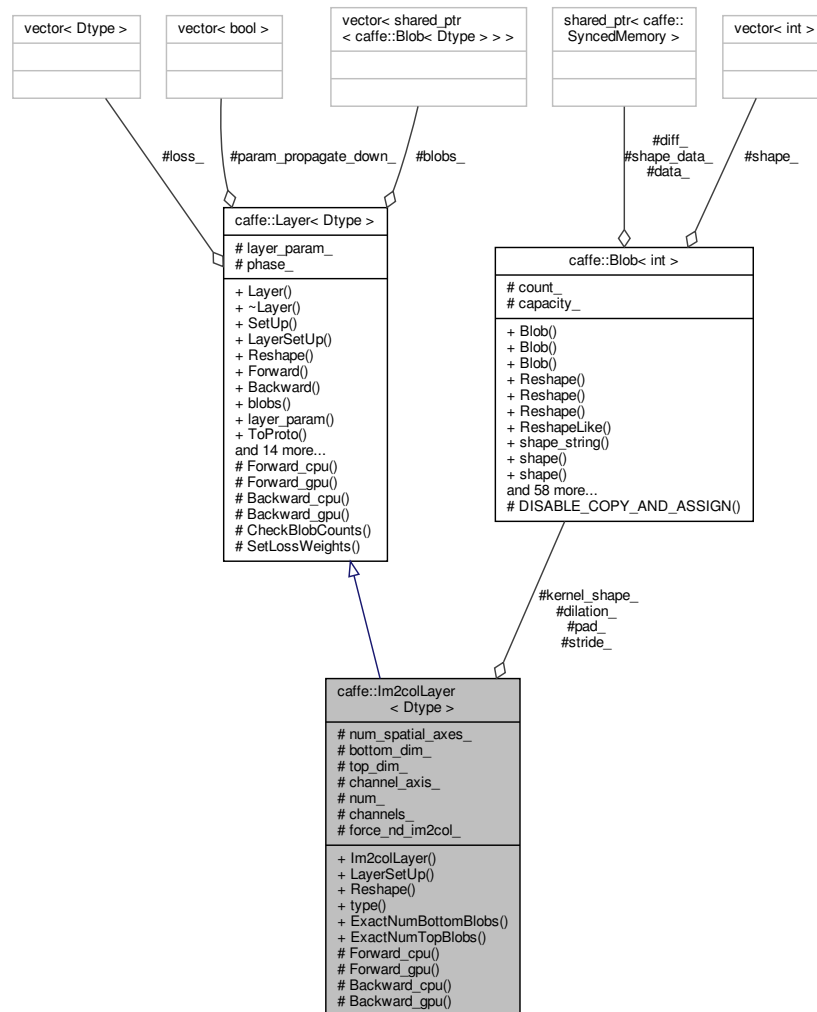
A helper for image operations that rearranges image regions into column vectors. Used by [ConvolutionLayer](#) to perform convolution by matrix multiplication.

```
#include <im2col_layer.hpp>
```

Inheritance diagram for caffe::Im2colLayer< Dtype >:



Collaboration diagram for `caffe::Im2colLayer< Dtype >`:



## Public Member Functions

- **Im2colLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- [Blob](#)< int > [kernel\\_shape\\_](#)  
*The spatial dimensions of a filter kernel.*
- [Blob](#)< int > [stride\\_](#)  
*The spatial dimensions of the stride.*
- [Blob](#)< int > [pad\\_](#)  
*The spatial dimensions of the padding.*
- [Blob](#)< int > [dilation\\_](#)  
*The spatial dimensions of the dilation.*
- int [num\\_spatial\\_axes\\_](#)
- int [bottom\\_dim\\_](#)
- int [top\\_dim\\_](#)
- int [channel\\_axis\\_](#)
- int [num\\_](#)
- int [channels\\_](#)
- bool [force\\_nd\\_im2col\\_](#)

### 5.48.1 Detailed Description

```
template<typename Dtype>
class caffe::Im2colLayer< Dtype >
```

A helper for image operations that rearranges image regions into column vectors. Used by [ConvolutionLayer](#) to perform convolution by matrix multiplication.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

### 5.48.2 Member Function Documentation

#### 5.48.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::Im2colLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.48.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::Im2colLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.48.2.3 LayerSetUp()

```
template<typename Dtype >
void caffe::Im2colLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

##### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

5.48.2.4 `Reshape()`

```
template<typename Dtype >
void caffe::Im2colLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following files:

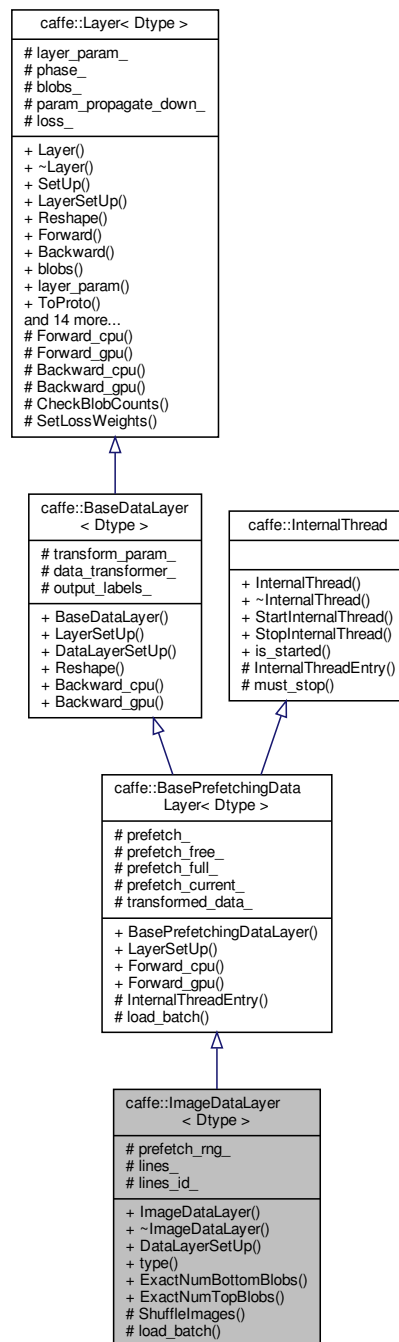
- `include/caffe/layers/im2col_layer.hpp`
- `src/caffe/layers/im2col_layer.cpp`

5.49 `caffe::ImageDataLayer< Dtype >` Class Template Reference

Provides data to the `Net` from image files.

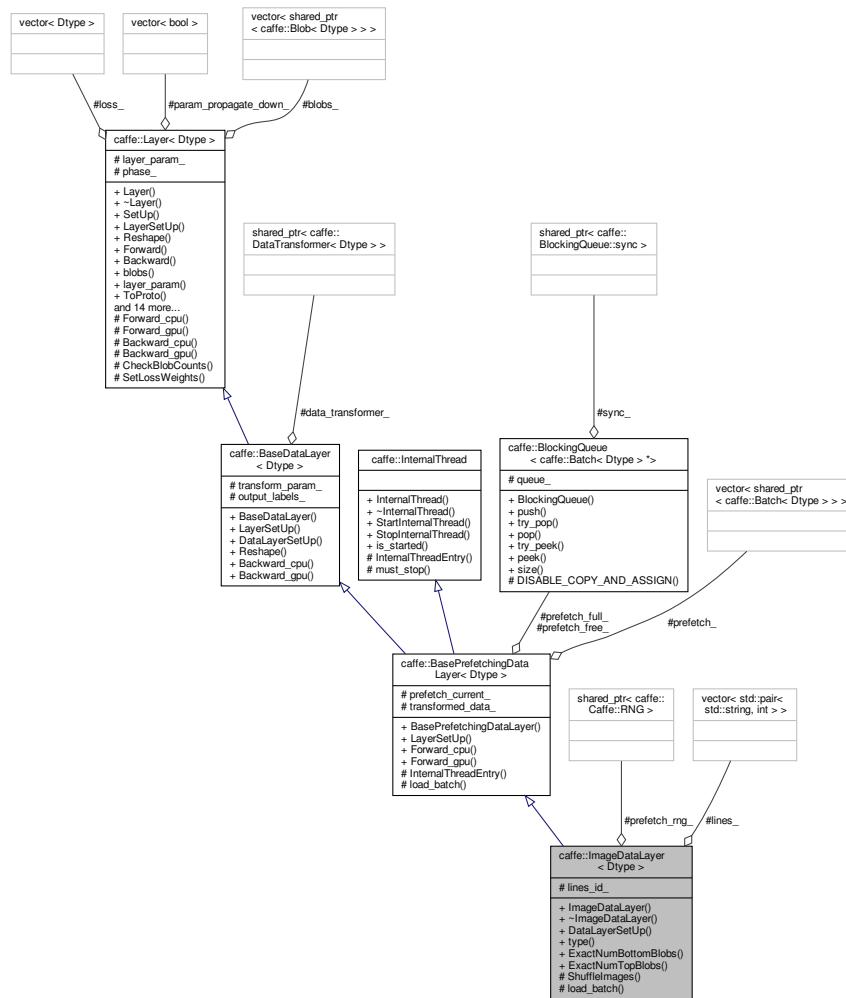
```
#include <image_data_layer.hpp>
```

Inheritance diagram for `caffe::ImageDataLayer< Dtype >`:





Collaboration diagram for caffe::ImageDataLayer< Dtype >:



## Public Member Functions

- **ImageDataLayer** (const LayerParameter &param)
- virtual void **DataLayerSetup** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void **ShuffleImages** ()
- virtual void **load\_batch** (Batch< Dtype > \*batch)

## Protected Attributes

- `shared_ptr< Caffe::RNG > prefetch_rng_`
- `vector< std::pair< std::string, int > > lines_`
- `int lines_id_`

### 5.49.1 Detailed Description

```
template<typename Dtype>
class caffe::ImageDataLayer< Dtype >
```

Provides data to the [Net](#) from image files.

TODO(dox): thorough documentation for Forward and proto params.

### 5.49.2 Member Function Documentation

#### 5.49.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::ImageDataLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.49.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::ImageDataLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following file:

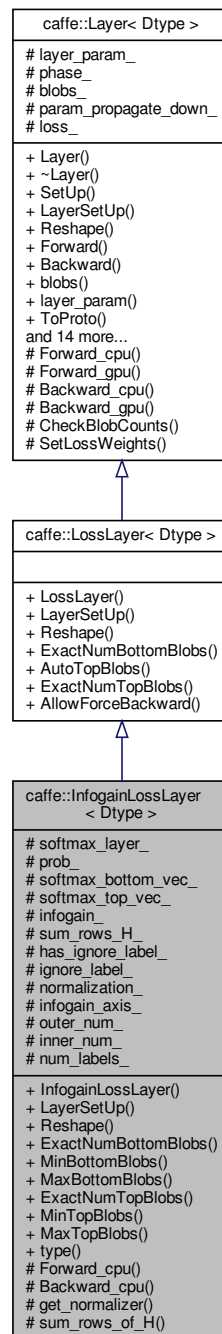
- `include/caffe/layers/image_data_layer.hpp`

## 5.50 caffe::InfogainLossLayer< Dtype > Class Template Reference

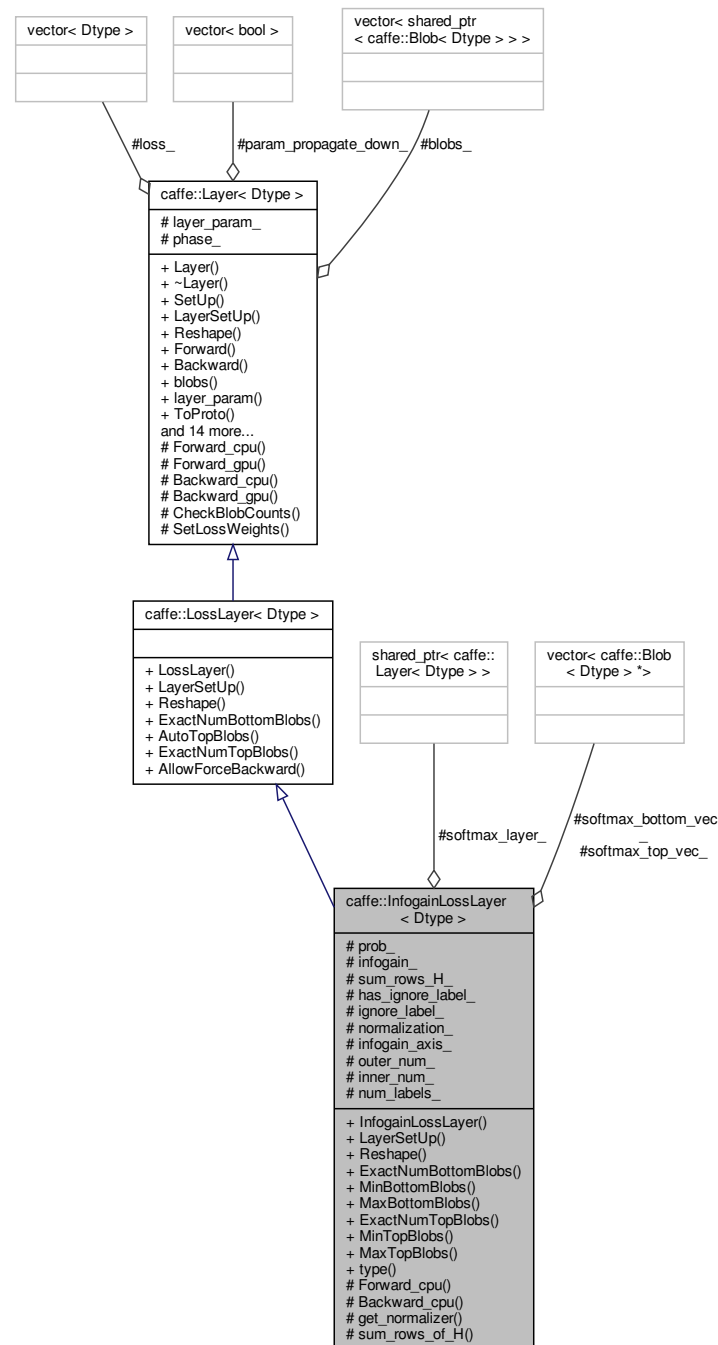
A generalization of [SoftmaxWithLossLayer](#) that takes an "information gain" (infogain) matrix specifying the "value" of all label pairs.

```
#include <infogain_loss_layer.hpp>
```

Inheritance diagram for caffe::InfogainLossLayer< Dtype >:



Collaboration diagram for `caffe::InfogainLossLayer< Dtype >`:



## Public Member Functions

- **InfogainLossLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as *Reshape*.
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

- virtual int [ExactNumBottomBlobs](#) () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int [MinBottomBlobs](#) () const  
*Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.*
- virtual int [MaxBottomBlobs](#) () const  
*Returns the maximum number of bottom blobs required by the layer, or -1 if no maximum number is required.*
- virtual int [ExactNumTopBlobs](#) () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*
- virtual int [MinTopBlobs](#) () const  
*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*
- virtual int [MaxTopBlobs](#) () const  
*Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.*
- virtual const char \* [type](#) () const  
*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*A generalization of [SoftmaxWithLossLayer](#) that takes an "information gain" (infogain) matrix specifying the "value" of all label pairs.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Computes the infogain loss error gradient w.r.t. the predictions.*
- virtual Dtype [get\\_normalizer](#) (LossParameter\_NormalizationMode normalization\_mode, int valid\_count)
- virtual void [sum\\_rows\\_of\\_H](#) (const [Blob](#)< Dtype > \*H)  
*fill sum\_rows\_H\_ according to matrix H*

## Protected Attributes

- shared\_ptr< [Layer](#)< Dtype > > [softmax\\_layer\\_](#)  
*The internal [SoftmaxLayer](#) used to map predictions to a distribution.*
- [Blob](#)< Dtype > [prob\\_](#)  
*prob stores the output probability predictions from the [SoftmaxLayer](#).*
- vector< [Blob](#)< Dtype > \* > [softmax\\_bottom\\_vec\\_](#)  
*bottom vector holder used in call to the underlying [SoftmaxLayer::Forward](#)*
- vector< [Blob](#)< Dtype > \* > [softmax\\_top\\_vec\\_](#)  
*top vector holder used in call to the underlying [SoftmaxLayer::Forward](#)*
- [Blob](#)< Dtype > [infogain\\_](#)
- [Blob](#)< Dtype > [sum\\_rows\\_H\\_](#)
- bool [has\\_ignore\\_label\\_](#)  
*Whether to ignore instances with a certain label.*
- int [ignore\\_label\\_](#)  
*The label indicating that an instance should be ignored.*
- LossParameter\_NormalizationMode [normalization\\_](#)  
*How to normalize the output loss.*
- int [infogain\\_axis\\_](#)
- int [outer\\_num\\_](#)
- int [inner\\_num\\_](#)
- int [num\\_labels\\_](#)

### 5.50.1 Detailed Description

```
template<typename Dtype>
class caffe::InfogainLossLayer< Dtype >
```

A generalization of [SoftmaxWithLossLayer](#) that takes an "information gain" (infogain) matrix specifying the "value" of all label pairs.

Equivalent to the [SoftmaxWithLossLayer](#) if the infogain matrix is the identity.

#### Parameters

<i>bottom</i>	<p>input <a href="#">Blob</a> vector (length 2-3)</p> <ol style="list-style-type: none"> <li>1. <math>(N \times C \times H \times W)</math> the predictions <math>x</math>, a <a href="#">Blob</a> with values in <math>[-\infty, +\infty]</math> indicating the predicted score for each of the <math>K = CHW</math> classes. This layer maps these scores to a probability distribution over classes using the softmax function <math>\hat{p}_{nk} = \exp(x_{nk}) / [\sum_{k'} \exp(x_{nk'})]</math> (see <a href="#">SoftmaxLayer</a>).</li> <li>2. <math>(N \times 1 \times 1 \times 1)</math> the labels <math>l</math>, an integer-valued <a href="#">Blob</a> with values <math>l_n \in [0, 1, 2, \dots, K - 1]</math> indicating the correct class label among the <math>K</math> classes</li> <li>3. <math>(1 \times 1 \times K \times K)</math> (<b>optional</b>) the infogain matrix <math>H</math>. This must be provided as the third bottom blob input if not provided as the infogain_mat in the InfogainLossParameter. If <math>H = I</math>, this layer is equivalent to the <a href="#">SoftmaxWithLossLayer</a>.</li> </ol>
<i>top</i>	<p>output <a href="#">Blob</a> vector (length 1)</p> <ol style="list-style-type: none"> <li>1. <math>(1 \times 1 \times 1 \times 1)</math> the computed infogain multinomial logistic loss:  <math display="block">E = \frac{1}{N} \sum_{n=1}^N H_{l_n} \log(\hat{p}_n) = \frac{1}{N} \sum_{n=1}^N \sum_{k=1}^K H_{l_n, k} \log(\hat{p}_{n, k}),</math> where <math>H_{l_n}</math> denotes row <math>l_n</math> of <math>H</math>.</li> </ol>

### 5.50.2 Member Function Documentation

#### 5.50.2.1 Backward\_cpu()

```
template<typename Dtype>
void caffe::InfogainLossLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the infogain loss error gradient w.r.t. the predictions.

Gradients cannot be computed with respect to the label inputs (bottom[1]), so this method ignores bottom[1] and requires !propagate\_down[1], crashing if propagate\_down[1] is set. (The same applies to the infogain matrix, if provided as bottom[2] rather than in the layer\_param.)

## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> This <a href="#">Blob</a>'s diff will simply contain the <code>loss_weight * <math>\lambda</math></code>, as <math>\lambda</math> is the coefficient of this layer's output <math>\ell_i</math> in the overall <a href="#">Net</a> loss <math>E = \lambda_i \ell_i + \text{other loss terms}</math>; hence <math>\frac{\partial E}{\partial \ell_i} = \lambda_i</math>. (*Assuming that this top <a href="#">Blob</a> is not used as a bottom (input) by any other layer of the <a href="#">Net</a>.)</li> </ol>
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> . <code>propagate_down[1]</code> must be false as we can't compute gradients with respect to the labels (similarly for <code>propagate_down[2]</code> and the infogain matrix, if provided as <code>bottom[2]</code> )
<i>bottom</i>	input <a href="#">Blob</a> vector (length 2-3) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the predictions <math>x</math>; Backward computes diff <math>\frac{\partial E}{\partial x}</math></li> <li><math>(N \times 1 \times 1 \times 1)</math> the labels – ignored as we can't compute their error gradients</li> <li><math>(1 \times 1 \times K \times K)</math> (<b>optional</b>) the information gain matrix – ignored as its error gradient computation is not implemented.</li> </ol>

Implements [caffe::Layer< Dtype >](#).

5.50.2.2 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::InfogainLossLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::LossLayer< Dtype >](#).

5.50.2.3 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::InfogainLossLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::LossLayer< Dtype >](#).

#### 5.50.2.4 Forward\_cpu()

```
template<typename Dtype >
void caffe::InfogainLossLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

A generalization of [SoftmaxWithLossLayer](#) that takes an "information gain" (infogain) matrix specifying the "value" of all label pairs.

Equivalent to the [SoftmaxWithLossLayer](#) if the infogain matrix is the identity.



## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2-3) <ol style="list-style-type: none"> <li>1. <math>(N \times C \times H \times W)</math> the predictions <math>x</math>, a <a href="#">Blob</a> with values in <math>[-\infty, +\infty]</math> indicating the predicted score for each of the <math>K = CHW</math> classes. This layer maps these scores to a probability distribution over classes using the softmax function <math>\hat{p}_{nk} = \exp(x_{nk}) / [\sum_{k'} \exp(x_{nk'})]</math> (see <a href="#">SoftmaxLayer</a>).</li> <li>2. <math>(N \times 1 \times 1 \times 1)</math> the labels <math>l</math>, an integer-valued <a href="#">Blob</a> with values <math>l_n \in [0, 1, 2, \dots, K - 1]</math> indicating the correct class label among the <math>K</math> classes</li> <li>3. <math>(1 \times 1 \times K \times K)</math> (<b>optional</b>) the infogain matrix <math>H</math>. This must be provided as the third bottom blob input if not provided as the <code>infogain_mat</code> in the <code>InfogainLossParameter</code>. If <math>H = I</math>, this layer is equivalent to the <a href="#">SoftmaxWithLossLayer</a>.</li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li>1. <math>(1 \times 1 \times 1 \times 1)</math> the computed infogain multinomial logistic loss:  <math display="block">E = \frac{-1}{N} \sum_{n=1}^N H_{l_n} \log(\hat{p}_n) = \frac{-1}{N} \sum_{n=1}^N \sum_{k=1}^K H_{l_n, k} \log(\hat{p}_{n, k}),</math>           where <math>H_{l_n}</math> denotes row <math>l_n</math> of <math>H</math>.</li> </ol>

Implements [caffe::Layer< Dtype >](#).

5.50.2.5 `get_normalizer()`

```
template<typename Dtype >
Dtype caffe::InfogainLossLayer< Dtype >::get_normalizer (
    LossParameter_NormalizationMode normalization_mode,
    int valid_count ) [protected], [virtual]
```

Read the normalization mode parameter and compute the normalizer based on the blob size. If `normalization_mode` is `VALID`, the count of valid outputs will be read from `valid_count`, unless it is -1 in which case all outputs are assumed to be valid.

5.50.2.6 `LayerSetUp()`

```
template<typename Dtype >
void caffe::InfogainLossLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`,

which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::LossLayer< Dtype >](#).

#### 5.50.2.7 MaxBottomBlobs()

```
template<typename Dtype >
virtual int caffe::InfogainLossLayer< Dtype >::MaxBottomBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of bottom blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.50.2.8 MaxTopBlobs()

```
template<typename Dtype >
virtual int caffe::InfogainLossLayer< Dtype >::MaxTopBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.50.2.9 MinBottomBlobs()

```
template<typename Dtype >
virtual int caffe::InfogainLossLayer< Dtype >::MinBottomBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

5.50.2.10 `MinTopBlobs()`

```
template<typename Dtype >
virtual int caffe::InfogainLossLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.50.2.11 `Reshape()`

```
template<typename Dtype >
void caffe::InfogainLossLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Reimplemented from `caffe::LossLayer< Dtype >`.

The documentation for this class was generated from the following files:

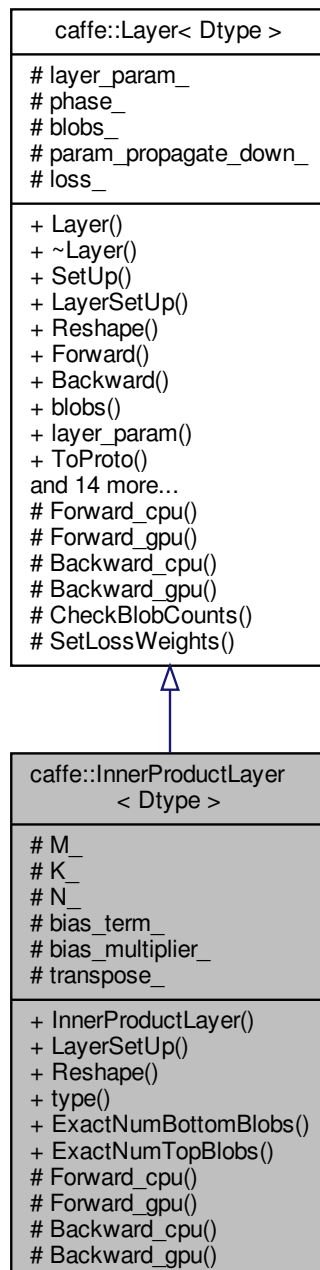
- `include/caffe/layers/infogain_loss_layer.hpp`
- `src/caffe/layers/infogain_loss_layer.cpp`

5.51 `caffe::InnerProductLayer< Dtype >` Class Template Reference

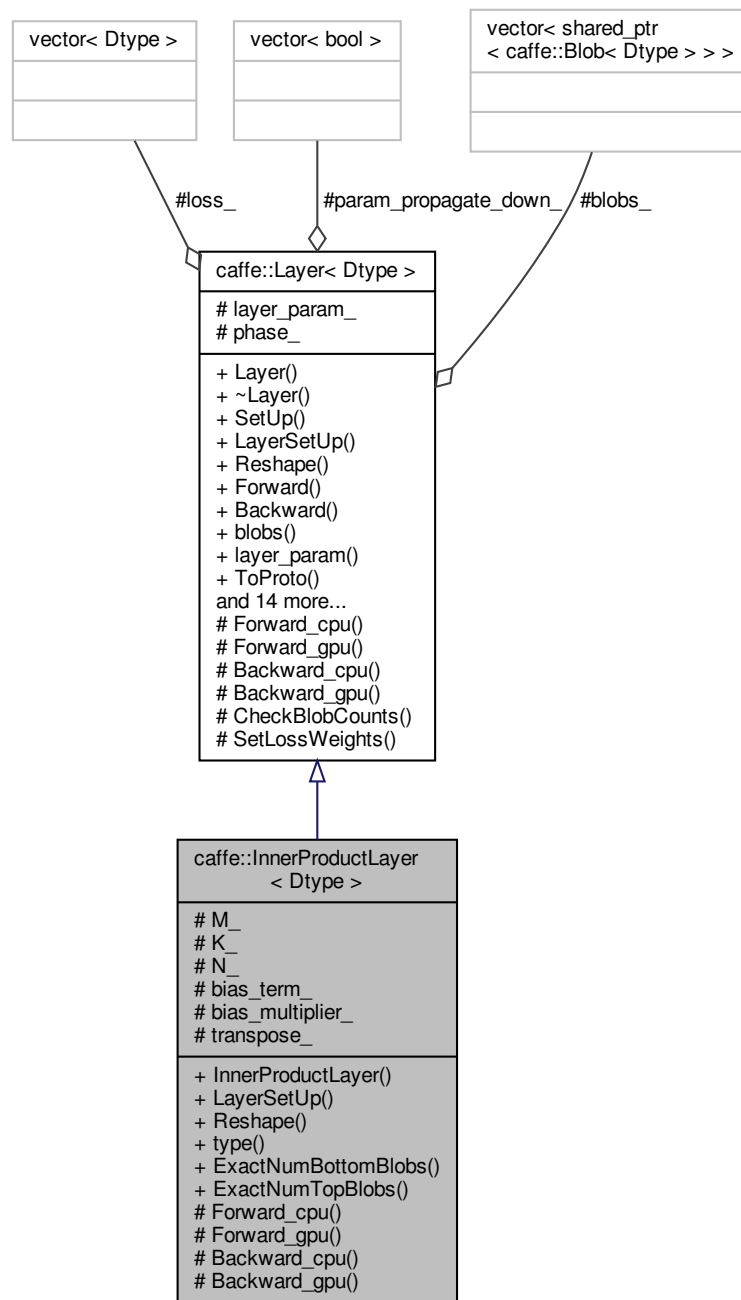
Also known as a "fully-connected" layer, computes an inner product with a set of learned weights, and (optionally) adds biases.

```
#include <inner_product_layer.hpp>
```

Inheritance diagram for `caffe::InnerProductLayer< Dtype >`:



Collaboration diagram for caffe::InnerProductLayer< Dtype >:



## Public Member Functions

- **InnerProductLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*

- virtual const char \* [type](#) () const  
*Returns the layer type.*
- virtual int [ExactNumBottomBlobs](#) () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int [ExactNumTopBlobs](#) () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- int **M\_**
- int **K\_**
- int **N\_**
- bool **bias\_term\_**
- [Blob](#)< Dtype > **bias\_multiplier\_**
- bool [transpose\\_](#)  
*if true, assume transposed weights*

### 5.51.1 Detailed Description

```
template<typename Dtype>
class caffe::InnerProductLayer< Dtype >
```

Also known as a "fully-connected" layer, computes an inner product with a set of learned weights, and (optionally) adds biases.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

### 5.51.2 Member Function Documentation

5.51.2.1 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::InnerProductLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.51.2.2 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::InnerProductLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.51.2.3 `LayerSetUp()`

```
template<typename Dtype >
void caffe::InnerProductLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.51.2.4 Reshape()

```
template<typename Dtype >
void caffe::InnerProductLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

##### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

- include/caffe/layers/inner\_product\_layer.hpp
- src/caffe/layers/inner\_product\_layer.cpp

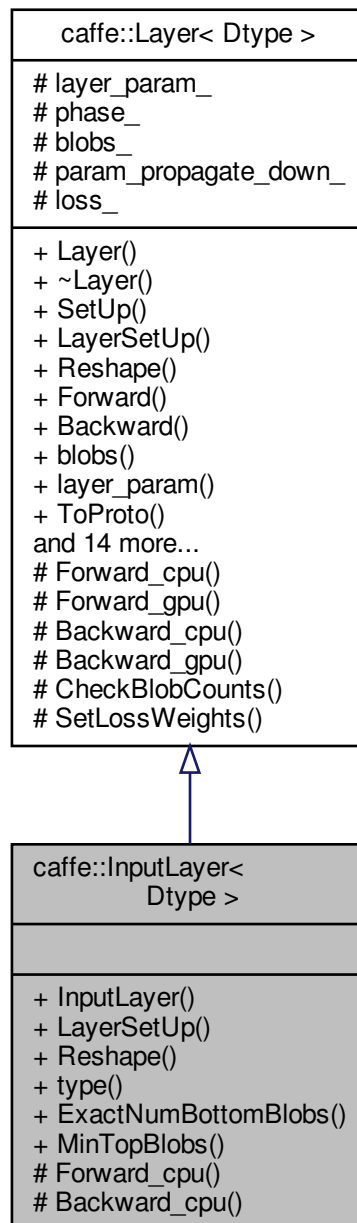
## 5.52 caffe::InputLayer< Dtype > Class Template Reference

Provides data to the [Net](#) by assigning tops directly.

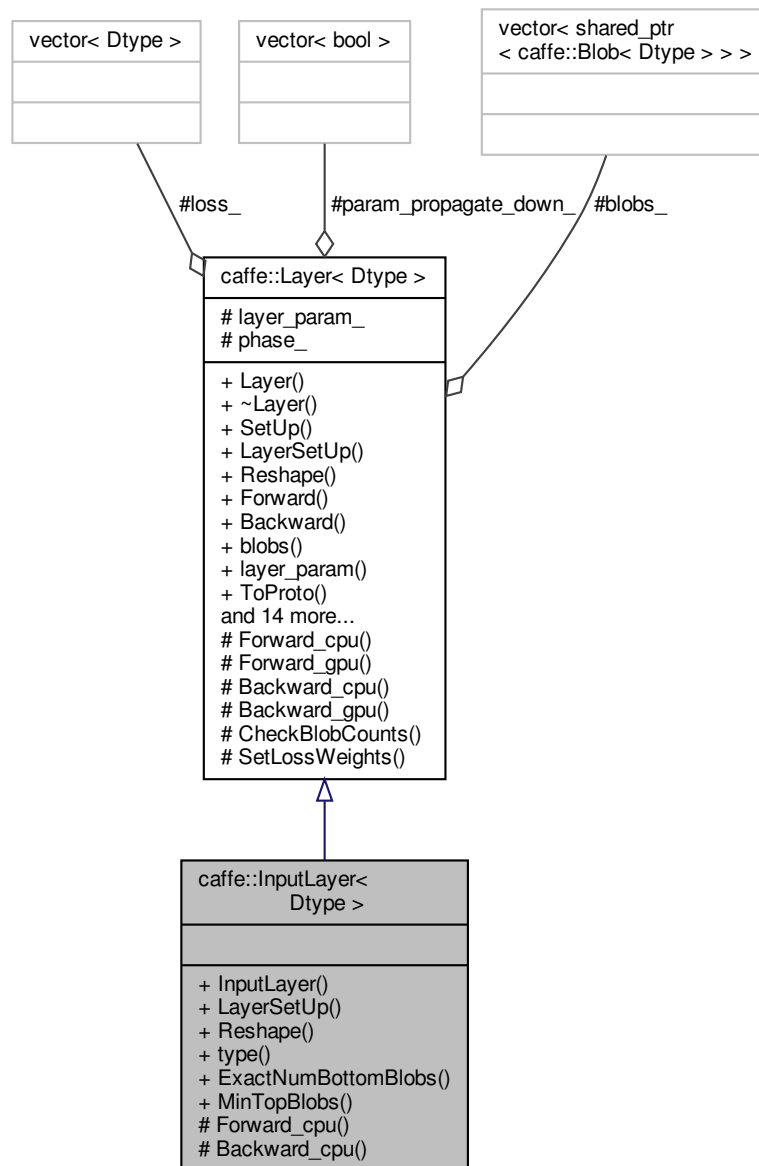
```
#include <input_layer.hpp>
```



Inheritance diagram for caffe::InputLayer< Dtype >:



Collaboration diagram for `caffe::InputLayer< Dtype >`:



## Public Member Functions

- **InputLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const

*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*

- virtual int [MinTopBlobs](#) () const

*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the CPU device, compute the layer output.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

## Additional Inherited Members

### 5.52.1 Detailed Description

```
template<typename Dtype>
class caffe::InputLayer< Dtype >
```

Provides data to the [Net](#) by assigning tops directly.

This data layer is a container that merely holds the data assigned to it; forward, backward, and reshape are all no-ops.

### 5.52.2 Member Function Documentation

#### 5.52.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::InputLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer](#)< Dtype >.

#### 5.52.2.2 LayerSetUp()

```
template<typename Dtype >
void caffe::InputLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.52.2.3 MinTopBlobs()

```
template<typename Dtype >
virtual int caffe::InputLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.52.2.4 Reshape()

```
template<typename Dtype >
virtual void caffe::InputLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [inline], [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

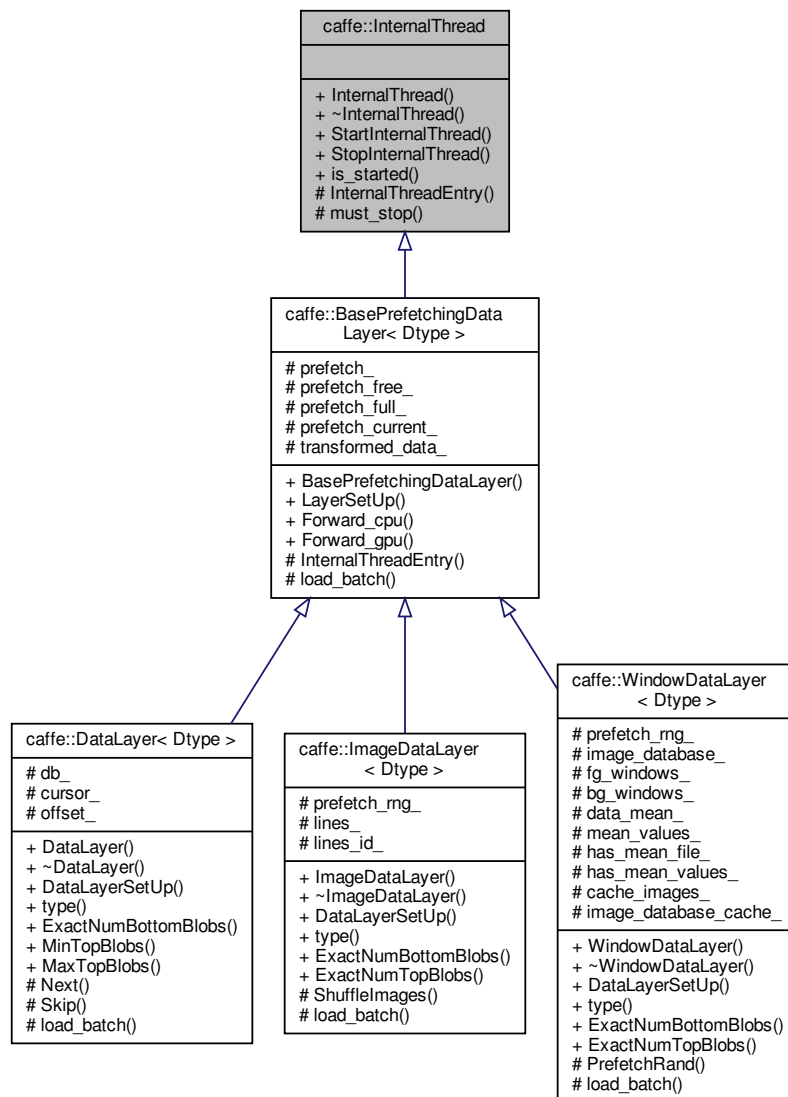
The documentation for this class was generated from the following files:

- include/caffe/layers/input\_layer.hpp
- src/caffe/layers/input\_layer.cpp

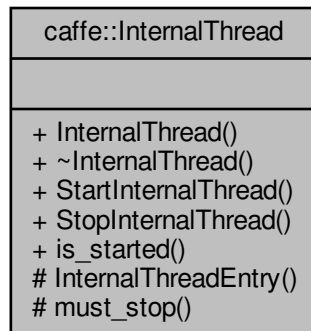
## 5.53 caffe::InternalThread Class Reference

```
#include <internal_thread.hpp>
```

Inheritance diagram for caffe::InternalThread:



Collaboration diagram for `caffe::InternalThread`:



### Public Member Functions

- void [StartInternalThread](#) ()
- void [StopInternalThread](#) ()
- bool **is\_started** () const

### Protected Member Functions

- virtual void **InternalThreadEntry** ()
- bool **must\_stop** ()

#### 5.53.1 Detailed Description

Virtual class encapsulate `boost::thread` for use in base class The child class will acquire the ability to run a single thread, by reimplementing the virtual function `InternalThreadEntry`.

#### 5.53.2 Member Function Documentation

##### 5.53.2.1 StartInternalThread()

```
void caffe::InternalThread::StartInternalThread ( )
```

[Caffe](#)'s thread local state will be initialized using the current thread values, e.g. device id, solver index etc. The random seed is initialized using `caffe_rng_rand`.

## 5.53.2.2 StopInternalThread()

```
void caffe::InternalThread::StopInternalThread ( )
```

Will not return until the internal thread has exited.

The documentation for this class was generated from the following files:

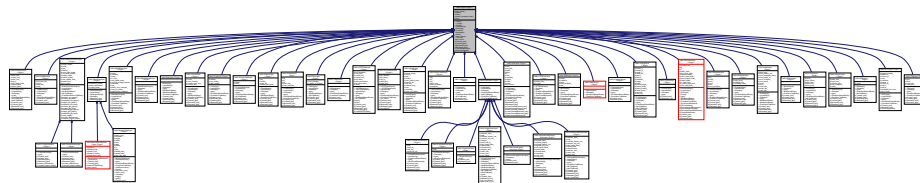
- include/caffe/internal\_thread.hpp
- src/caffe/internal\_thread.cpp

## 5.54 caffe::Layer&lt; Dtype &gt; Class Template Reference

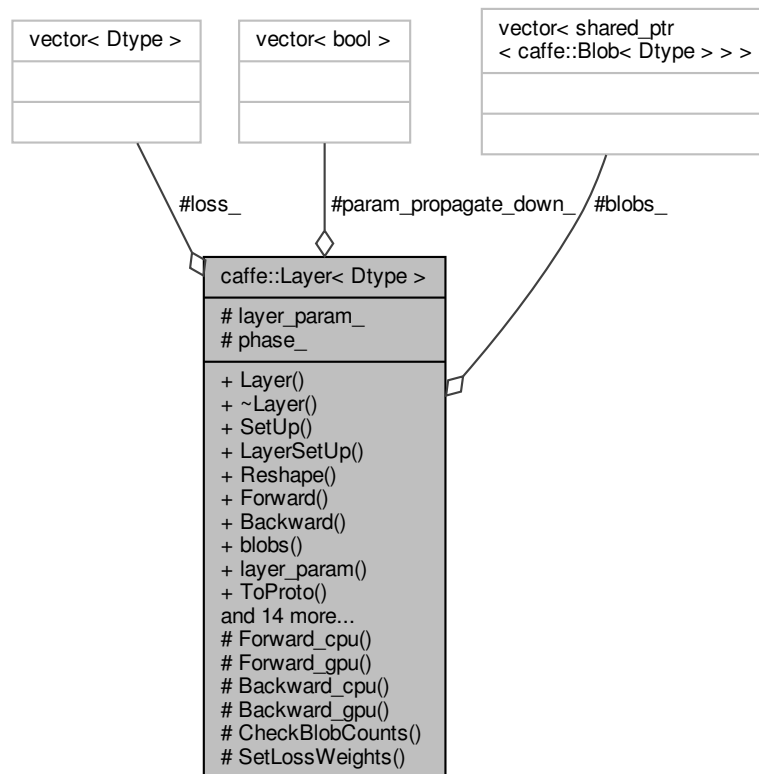
An interface for the units of computation which can be composed into a [Net](#).

```
#include <layer.hpp>
```

Inheritance diagram for caffe::Layer< Dtype >:



Collaboration diagram for caffe::Layer< Dtype >:



## Public Member Functions

- [Layer](#) (const LayerParameter &param)
- void [SetUp](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Implements common layer setup functionality.*
- virtual void [LayerSetUp](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void [Reshape](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)=0  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- Dtype [Forward](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Given the bottom blobs, compute the top blobs and the loss.*
- void [Backward](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Given the top blob error gradients, compute the bottom blob error gradients.*
- vector< shared\_ptr< [Blob](#)< Dtype > > > & [blobs](#) ()  
*Returns the vector of learnable parameter blobs.*
- const LayerParameter & [layer\\_param](#) () const  
*Returns the layer parameter.*
- virtual void [ToProto](#) (LayerParameter \*param, bool write\_diff=false)  
*Writes the layer parameter to a protocol buffer.*
- Dtype [loss](#) (const int top\_index) const  
*Returns the scalar loss associated with a top blob at a given index.*
- void [set\\_loss](#) (const int top\_index, const Dtype value)  
*Sets the loss associated with a top blob at a given index.*
- virtual const char \* [type](#) () const  
*Returns the layer type.*
- virtual int [ExactNumBottomBlobs](#) () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int [MinBottomBlobs](#) () const  
*Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.*
- virtual int [MaxBottomBlobs](#) () const  
*Returns the maximum number of bottom blobs required by the layer, or -1 if no maximum number is required.*
- virtual int [ExactNumTopBlobs](#) () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*
- virtual int [MinTopBlobs](#) () const  
*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*
- virtual int [MaxTopBlobs](#) () const  
*Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.*
- virtual bool [EqualNumBottomTopBlobs](#) () const  
*Returns true if the layer requires an equal number of bottom and top blobs.*
- virtual bool [AutoTopBlobs](#) () const  
*Return whether "anonymous" top blobs are created automatically by the layer.*
- virtual bool [AllowForceBackward](#) (const int bottom\_index) const  
*Return whether to allow force\_backward for a given bottom blob index.*
- bool [param\\_propagate\\_down](#) (const int param\_id)  
*Specifies whether the layer should compute gradients w.r.t. a parameter at a particular index given by param\_id.*
- void [set\\_param\\_propagate\\_down](#) (const int param\_id, const bool value)  
*Sets whether the layer should compute gradients w.r.t. a parameter at a particular index given by param\_id.*



## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)=0  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)=0  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*
- virtual void [CheckBlobCounts](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- void [SetLossWeights](#) (const vector< [Blob](#)< Dtype > \*> &top)

## Protected Attributes

- LayerParameter [layer\\_param\\_](#)
- Phase [phase\\_](#)
- vector< shared\_ptr< [Blob](#)< Dtype > > > [blobs\\_](#)
- vector< bool > [param\\_propagate\\_down\\_](#)
- vector< Dtype > [loss\\_](#)

### 5.54.1 Detailed Description

```
template<typename Dtype>
class caffe::Layer< Dtype >
```

An interface for the units of computation which can be composed into a [Net](#).

[Layers](#) must implement a Forward function, in which they take their input (bottom) [Blobs](#) (if any) and compute their output [Blobs](#) (if any). They may also implement a Backward function, in which they compute the error gradients with respect to their input [Blobs](#), given the error gradients with their output [Blobs](#).

### 5.54.2 Constructor & Destructor Documentation

#### 5.54.2.1 Layer()

```
template<typename Dtype >
caffe::Layer< Dtype >::Layer (
    const LayerParameter & param ) [inline], [explicit]
```

You should not implement your own constructor. Any set up code should go to [SetUp\(\)](#), where the dimensions of the bottom blobs are provided to the layer.

### 5.54.3 Member Function Documentation

#### 5.54.3.1 AllowForceBackward()

```
template<typename Dtype >
virtual bool caffe::Layer< Dtype >::AllowForceBackward (
    const int bottom_index ) const [inline], [virtual]
```

Return whether to allow `force_backward` for a given bottom blob index.

If `AllowForceBackward(i) == false`, we will ignore the `force_backward` setting and backpropagate to blob `i` only if it needs gradient information (as is done when `force_backward == false`).

Reimplemented in [caffe::LSTMUnitLayer< Dtype >](#), [caffe::RecurrentLayer< Dtype >](#), [caffe::EuclideanLossLayer< Dtype >](#), [caffe::ContrastiveLossLayer< Dtype >](#), and [caffe::LossLayer< Dtype >](#).

#### 5.54.3.2 AutoTopBlobs()

```
template<typename Dtype >
virtual bool caffe::Layer< Dtype >::AutoTopBlobs ( ) const [inline], [virtual]
```

Return whether "anonymous" top blobs are created automatically by the layer.

If this method returns true, [Net::Init](#) will create enough "anonymous" top blobs to fulfill the requirement specified by [ExactNumTopBlobs\(\)](#) or [MinTopBlobs\(\)](#).

Reimplemented in [caffe::LossLayer< Dtype >](#).

#### 5.54.3.3 Backward()

```
template<typename Dtype >
void caffe::Layer< Dtype >::Backward (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [inline]
```

Given the top blob error gradients, compute the bottom blob error gradients.

##### Parameters

<i>top</i>	the output blobs, whose <code>diff</code> fields store the gradient of the error with respect to themselves
<i>propagate_down</i>	a vector with equal length to <i>bottom</i> , with each index indicating whether to propagate the error gradients down to the bottom blob at the corresponding index
<i>bottom</i>	the input blobs, whose <code>diff</code> fields will store the gradient of the error with respect to themselves after <code>Backward</code> is run

The Backward wrapper calls the relevant device wrapper function (`Backward_cpu` or `Backward_gpu`) to compute the bottom blob diffs given the top blob diffs.

Your layer should implement `Backward_cpu` and (optionally) `Backward_gpu`.

#### 5.54.3.4 `CheckBlobCounts()`

```
template<typename Dtype >
virtual void caffe::Layer< Dtype >::CheckBlobCounts (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [inline], [protected], [virtual]
```

Called by the parent `Layer`'s `SetUp` to check that the number of bottom and top Blobs provided as input match the expected numbers specified by the `{ExactNum,Min,Max}{Bottom,Top}Blobs()` functions.

#### 5.54.3.5 `EqualNumBottomTopBlobs()`

```
template<typename Dtype >
virtual bool caffe::Layer< Dtype >::EqualNumBottomTopBlobs ( ) const [inline], [virtual]
```

Returns true if the layer requires an equal number of bottom and top blobs.

This method should be overridden to return true if your layer expects an equal number of bottom and top blobs.

Reimplemented in `caffe::BaseConvolutionLayer< Dtype >`.

#### 5.54.3.6 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::Layer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented in `caffe::LSTMUnitLayer< Dtype >`, `caffe::InfogainLossLayer< Dtype >`, `caffe::BatchNormLayer< Dtype >`, `caffe::ArgMaxLayer< Dtype >`, `caffe::ContrastiveLossLayer< Dtype >`, `caffe::AccuracyLayer< Dtype >`, `caffe::HDF5OutputLayer< Dtype >`, `caffe::HDF5DataLayer< Dtype >`, `caffe::WindowDataLayer< Dtype >`, `caffe::AbsValLayer< Dtype >`, `caffe::LRNLayer< Dtype >`, `caffe::ImageDataLayer< Dtype >`, `caffe::LossLayer< Dtype >`, `caffe::CropLayer< Dtype >`, `caffe::FlattenLayer< Dtype >`, `caffe::DummyDataLayer< Dtype >`, `caffe::EmbedLayer< Dtype >`, `caffe::Im2colLayer< Dtype >`, `caffe::InputLayer< Dtype >`, `caffe::ReductionLayer< Dtype >`, `caffe::BatchReindexLayer< Dtype >`, `caffe::InnerProductLayer< Dtype >`, `caffe::ParameterLayer< Dtype >`, `caffe::ReshapeLayer< Dtype >`, `caffe::SliceLayer< Dtype >`, `caffe::SPPLayer< Dtype >`, `caffe::MemoryDataLayer< Dtype >`, `caffe::PoolingLayer< Dtype >`, `caffe::SplitLayer< Dtype >`, `caffe::MVNLayer< Dtype >`, `caffe::NeuronLayer< Dtype >`, `caffe::SoftmaxLayer< Dtype >`, `caffe::DataLayer< Dtype >`, and `caffe::TileLayer< Dtype >`.

#### 5.54.3.7 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::Layer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented in [caffe::LSTMUnitLayer< Dtype >](#), [caffe::InfogainLossLayer< Dtype >](#), [caffe::SoftmaxWithLossLayer< Dtype >](#), [caffe::BatchNormLayer< Dtype >](#), [caffe::ArgMaxLayer< Dtype >](#), [caffe::RecurrentLayer< Dtype >](#), [caffe::LossLayer< Dtype >](#), [caffe::ScaleLayer< Dtype >](#), [caffe::HDF5OutputLayer< Dtype >](#), [caffe::WindowDataLayer< Dtype >](#), [caffe::AbsValLayer< Dtype >](#), [caffe::BiasLayer< Dtype >](#), [caffe::LRNLayer< Dtype >](#), [caffe::ImageDataLayer< Dtype >](#), [caffe::CropLayer< Dtype >](#), [caffe::FlattenLayer< Dtype >](#), [caffe::EmbedLayer< Dtype >](#), [caffe::Im2colLayer< Dtype >](#), [caffe::ReductionLayer< Dtype >](#), [caffe::BatchReindexLayer< Dtype >](#), [caffe::EltwiseLayer< Dtype >](#), [caffe::InnerProductLayer< Dtype >](#), [caffe::ParameterLayer< Dtype >](#), [caffe::ReshapeLayer< Dtype >](#), [caffe::SPPLayer< Dtype >](#), [caffe::MemoryDataLayer< Dtype >](#), [caffe::ConcatLayer< Dtype >](#), [caffe::MVNLayer< Dtype >](#), [caffe::NeuronLayer< Dtype >](#), [caffe::SoftmaxLayer< Dtype >](#), [caffe::SilenceLayer< Dtype >](#), and [caffe::TileLayer< Dtype >](#).

#### 5.54.3.8 Forward()

```
template<typename Dtype >
Dtype caffe::Layer< Dtype >::Forward (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [inline]
```

Given the bottom blobs, compute the top blobs and the loss.

##### Parameters

<i>bottom</i>	the input blobs, whose data fields store the input data for this layer
<i>top</i>	the preshaped output blobs, whose data fields will store this layers' outputs

##### Returns

The total loss from the layer.

The Forward wrapper calls the relevant device wrapper function (Forward\_cpu or Forward\_gpu) to compute the top blob values given the bottom blobs. If the layer has any non-zero loss\_weights, the wrapper then computes and returns the loss.

Your layer should implement Forward\_cpu and (optionally) Forward\_gpu.

#### 5.54.3.9 LayerSetUp()

```
template<typename Dtype >
virtual void caffe::Layer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [inline], [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented in [caffe::BasePrefetchingDataLayer< Dtype >](#), [caffe::SoftmaxWithLossLayer< Dtype >](#), [caffe::InfogainLossLayer< Dtype >](#), [caffe::SigmoidCrossEntropyLossLayer< Dtype >](#), [caffe::BatchNormLayer< Dtype >](#), [caffe::ContrastiveLossLayer< Dtype >](#), [caffe::ArgMaxLayer< Dtype >](#), [caffe::DropoutLayer< Dtype >](#), [caffe::PReLULayer< Dtype >](#), [caffe::SwishLayer< Dtype >](#), [caffe::ExpLayer< Dtype >](#), [caffe::LogLayer< Dtype >](#), [caffe::AccuracyLayer< Dtype >](#), [caffe::PowerLayer< Dtype >](#), [caffe::RecurrentLayer< Dtype >](#), [caffe::ScaleLayer< Dtype >](#), [caffe::AbsValLayer< Dtype >](#), [caffe::HDF5OutputLayer< Dtype >](#), [caffe::ThresholdLayer< Dtype >](#), [caffe::HDF5DataLayer< Dtype >](#), [caffe::BaseDataLayer< Dtype >](#), [caffe::LossLayer< Dtype >](#), [caffe::LRNLayer< Dtype >](#), [caffe::BiasLayer< Dtype >](#), [caffe::CropLayer< Dtype >](#), [caffe::EmbedLayer< Dtype >](#), [caffe::Im2colLayer< Dtype >](#), [caffe::ReductionLayer< Dtype >](#), [caffe::DummyDataLayer< Dtype >](#), [caffe::ElementwiseLayer< Dtype >](#), [caffe::FilterLayer< Dtype >](#), [caffe::InnerProductLayer< Dtype >](#), [caffe::InputLayer< Dtype >](#), [caffe::ReshapeLayer< Dtype >](#), [caffe::SliceLayer< Dtype >](#), [caffe::SPPLayer< Dtype >](#), [caffe::BaseConvolutionLayer< Dtype >](#), [caffe::PoolingLayer< Dtype >](#), [caffe::ConcatLayer< Dtype >](#), [caffe::PythonLayer< Dtype >](#), and [caffe::ParameterLayer< Dtype >](#).

## 5.54.3.10 MaxBottomBlobs()

```
template<typename Dtype >
virtual int caffe::Layer< Dtype >::MaxBottomBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of bottom blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of bottom blobs.

Reimplemented in [caffe::InfogainLossLayer< Dtype >](#), [caffe::RecurrentLayer< Dtype >](#), [caffe::ScaleLayer< Dtype >](#), and [caffe::BiasLayer< Dtype >](#).

## 5.54.3.11 MaxTopBlobs()

```
template<typename Dtype >
virtual int caffe::Layer< Dtype >::MaxTopBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of top blobs.

Reimplemented in [caffe::InfogainLossLayer< Dtype >](#), [caffe::SoftmaxWithLossLayer< Dtype >](#), [caffe::AccuracyLayer< Dtype >](#), [caffe::PoolingLayer< Dtype >](#), and [caffe::DataLayer< Dtype >](#).

#### 5.54.3.12 MinBottomBlobs()

```
template<typename Dtype >
virtual int caffe::Layer< Dtype >::MinBottomBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of bottom blobs.

Reimplemented in [caffe::InfogainLossLayer< Dtype >](#), [caffe::RecurrentLayer< Dtype >](#), [caffe::ScaleLayer< Dtype >](#), [caffe::BiasLayer< Dtype >](#), [caffe::EltwiseLayer< Dtype >](#), [caffe::FilterLayer< Dtype >](#), [caffe::BaseConvolutionLayer< Dtype >](#), [caffe::ConcatLayer< Dtype >](#), and [caffe::SilenceLayer< Dtype >](#).

#### 5.54.3.13 MinTopBlobs()

```
template<typename Dtype >
virtual int caffe::Layer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented in [caffe::InfogainLossLayer< Dtype >](#), [caffe::SoftmaxWithLossLayer< Dtype >](#), [caffe::AccuracyLayer< Dtype >](#), [caffe::HDF5DataLayer< Dtype >](#), [caffe::DummyDataLayer< Dtype >](#), [caffe::InputLayer< Dtype >](#), [caffe::FilterLayer< Dtype >](#), [caffe::SliceLayer< Dtype >](#), [caffe::PoolingLayer< Dtype >](#), [caffe::BaseConvolutionLayer< Dtype >](#), [caffe::SplitLayer< Dtype >](#), and [caffe::DataLayer< Dtype >](#).

#### 5.54.3.14 param\_propagate\_down()

```
template<typename Dtype >
bool caffe::Layer< Dtype >::param_propagate_down (
    const int param_id ) [inline]
```

Specifies whether the layer should compute gradients w.r.t. a parameter at a particular index given by param\_id.

You can safely ignore false values and always compute gradients for all parameters, but possibly with wasteful computation.

#### 5.54.3.15 Reshape()

```
template<typename Dtype >
virtual void caffe::Layer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [pure virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implemented in `caffe::LSTMUnitLayer< Dtype >`, `caffe::SoftmaxWithLossLayer< Dtype >`, `caffe::InfogainLossLayer< Dtype >`, `caffe::SigmoidCrossEntropyLossLayer< Dtype >`, `caffe::MultinomialLogisticLossLayer< Dtype >`, `caffe::BatchNormLayer< Dtype >`, `caffe::EuclideanLossLayer< Dtype >`, `caffe::ArgMaxLayer< Dtype >`, `caffe::PReLULayer< Dtype >`, `caffe::DropoutLayer< Dtype >`, `caffe::SwishLayer< Dtype >`, `caffe::AccuracyLayer< Dtype >`, `caffe::BaseDataLayer< Dtype >`, `caffe::HDF5OutputLayer< Dtype >`, `caffe::PythonLayer< Dtype >`, `caffe::RecurrentLayer< Dtype >`, `caffe::ScaleLayer< Dtype >`, `caffe::HDF5DataLayer< Dtype >`, `caffe::LossLayer< Dtype >`, `caffe::LRNLayer< Dtype >`, `caffe::BiasLayer< Dtype >`, `caffe::CropLayer< Dtype >`, `caffe::FlattenLayer< Dtype >`, `caffe::DummyDataLayer< Dtype >`, `caffe::EmbedLayer< Dtype >`, `caffe::Im2colLayer< Dtype >`, `caffe::InputLayer< Dtype >`, `caffe::ParameterLayer< Dtype >`, `caffe::ReductionLayer< Dtype >`, `caffe::BatchReindexLayer< Dtype >`, `caffe::EltwiseLayer< Dtype >`, `caffe::FilterLayer< Dtype >`, `caffe::InnerProductLayer< Dtype >`, `caffe::ReshapeLayer< Dtype >`, `caffe::SliceLayer< Dtype >`, `caffe::SPPLayer< Dtype >`, `caffe::BaseConvolutionLayer< Dtype >`, `caffe::PoolingLayer< Dtype >`, `caffe::ConcatLayer< Dtype >`, `caffe::NeuronLayer< Dtype >`, `caffe::SplitLayer< Dtype >`, `caffe::MVNLayer< Dtype >`, `caffe::SoftmaxLayer< Dtype >`, `caffe::SilenceLayer< Dtype >`, and `caffe::TileLayer< Dtype >`.

5.54.3.16 `SetLossWeights()`

```
template<typename Dtype >
void caffe::Layer< Dtype >::SetLossWeights (
    const vector< Blob< Dtype > *> & top ) [inline], [protected]
```

Called by `SetUp` to initialize the weights associated with any top blobs in the loss function. Store non-zero loss weights in the diff blob.

5.54.3.17 `SetUp()`

```
template<typename Dtype >
void caffe::Layer< Dtype >::SetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [inline]
```

Implements common layer setup functionality.

## Parameters

<i>bottom</i>	the preshaped input blobs
<i>top</i>	the allocated but unshaped output blobs, to be shaped by <code>Reshape</code>

Checks that the number of bottom and top blobs is correct. Calls `LayerSetUp` to do special layer setup for individual layer types, followed by `Reshape` to set up sizes of top blobs and internal buffers. Sets up the loss weight multiplier blobs for any non-zero loss weights. This method may not be overridden.

## 5.54.4 Member Data Documentation

### 5.54.4.1 blobs\_

```
template<typename Dtype >
vector<shared_ptr<Blob<Dtype> > > caffe::Layer< Dtype >::blobs_ [protected]
```

The vector that stores the learnable parameters as a set of blobs.

### 5.54.4.2 layer\_param\_

```
template<typename Dtype >
LayerParameter caffe::Layer< Dtype >::layer_param_ [protected]
```

The protobuf that stores the layer parameters

### 5.54.4.3 loss\_

```
template<typename Dtype >
vector<Dtype> caffe::Layer< Dtype >::loss_ [protected]
```

The vector that indicates whether each top blob has a non-zero weight in the objective function.

### 5.54.4.4 param\_propagate\_down\_

```
template<typename Dtype >
vector<bool> caffe::Layer< Dtype >::param_propagate_down_ [protected]
```

Vector indicating whether to compute the diff of each param blob.

### 5.54.4.5 phase\_

```
template<typename Dtype >
Phase caffe::Layer< Dtype >::phase_ [protected]
```

The phase: TRAIN or TEST

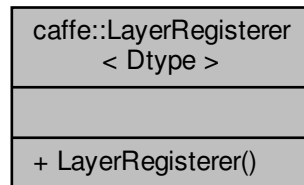
The documentation for this class was generated from the following file:

- include/caffe/layer.hpp



## 5.55 caffe::LayerRegisterer< Dtype > Class Template Reference

Collaboration diagram for caffe::LayerRegisterer< Dtype >:



### Public Member Functions

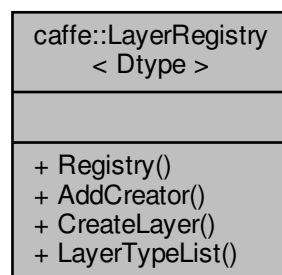
- **LayerRegisterer** (const string &type, shared\_ptr< [Layer](#)< Dtype > >(\*creator)(const LayerParameter &))

The documentation for this class was generated from the following file:

- include/caffe/layer\_factory.hpp

## 5.56 caffe::LayerRegistry< Dtype > Class Template Reference

Collaboration diagram for caffe::LayerRegistry< Dtype >:



### Public Types

- typedef shared\_ptr< [Layer](#)< Dtype > >(\* **Creator**) (const LayerParameter &)
- typedef std::map< string, Creator > **CreatorRegistry**

## Static Public Member Functions

- static CreatorRegistry & **Registry** ()
- static void **AddCreator** (const string &type, Creator creator)
- static shared\_ptr< [Layer](#)< Dtype > > **CreateLayer** (const LayerParameter &param)
- static vector< string > **LayerTypeList** ()

The documentation for this class was generated from the following file:

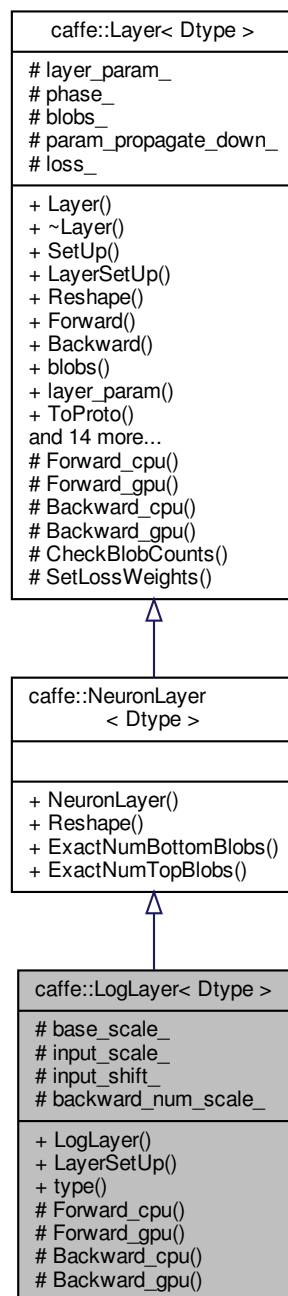
- include/caffe/layer\_factory.hpp

## 5.57 `caffe::LogLayer< Dtype >` Class Template Reference

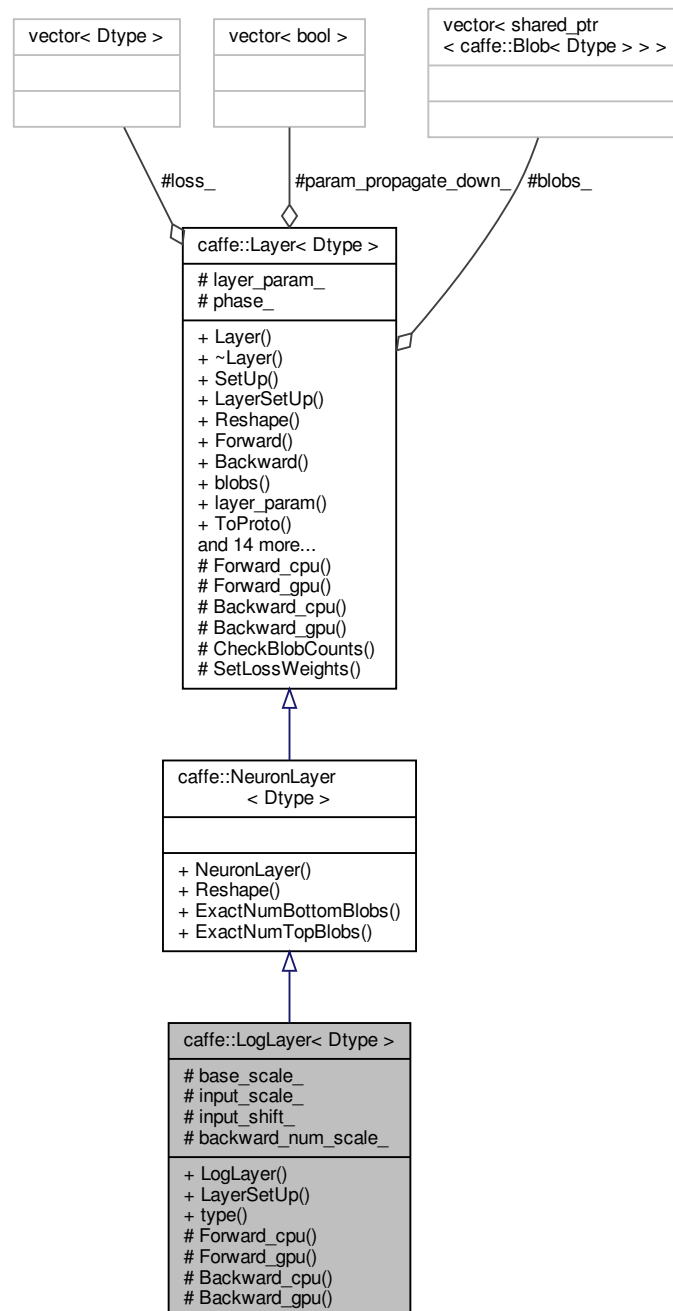
Computes  $y = \log_{\gamma}(\alpha x + \beta)$ , as specified by the scale  $\alpha$ , shift  $\beta$ , and base  $\gamma$ .

```
#include <log_layer.hpp>
```

Inheritance diagram for caffe::LogLayer< Dtype >:



Collaboration diagram for `caffe::LogLayer< Dtype >`:



## Public Member Functions

- `LogLayer` (const LayerParameter &param)
- virtual void `LayerSetUp` (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual const char \* `type` () const  
*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the error gradient w.r.t. the exp inputs.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- Dtype **base\_scale\_**
- Dtype **input\_scale\_**
- Dtype **input\_shift\_**
- Dtype **backward\_num\_scale\_**

### 5.57.1 Detailed Description

```
template<typename Dtype>
class caffe::LogLayer< Dtype >
```

Computes  $y = \log_{\gamma}(\alpha x + \beta)$ , as specified by the scale  $\alpha$ , shift  $\beta$ , and base  $\gamma$ .

### 5.57.2 Constructor & Destructor Documentation

#### 5.57.2.1 LogLayer()

```
template<typename Dtype >
caffe::LogLayer< Dtype >::LogLayer (
    const LayerParameter & param ) [inline], [explicit]
```

#### Parameters

<i>param</i>	provides LogParameter log_param, with <a href="#">LogLayer</a> options: <ul style="list-style-type: none"> <li>• scale (<b>optional</b>, default 1) the scale <math>\alpha</math></li> <li>• shift (<b>optional</b>, default 0) the shift <math>\beta</math></li> <li>• base (<b>optional</b>, default -1 for a value of <math>e \approx 2.718</math>) the base <math>\gamma</math></li> </ul>
--------------	--

## 5.57.3 Member Function Documentation

### 5.57.3.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::LogLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the exp inputs.

#### Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times H \times W)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$ ; Backward fills their diff with gradients $\frac{\partial E}{\partial x} = \frac{\partial E}{\partial y} y \alpha \log_e(\gamma)$ if <code>propagate_down[0]</code>

Implements [caffe::Layer< Dtype >](#).

### 5.57.3.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::LogLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = \log_{\gamma}(\alpha x + \beta)$

Implements [caffe::Layer< Dtype >](#).

## 5.57.3.3 LayerSetUp()

```
template<typename Dtype>
void caffe::LogLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following files:

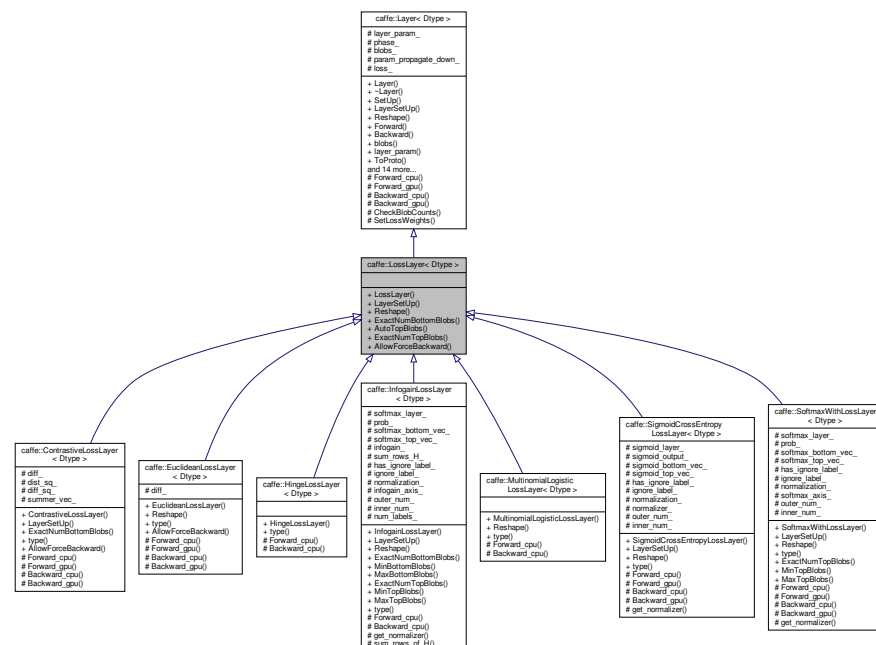
- include/caffe/layers/log\_layer.hpp
- src/caffe/layers/log\_layer.cpp

## 5.58 caffe::LossLayer&lt; Dtype &gt; Class Template Reference

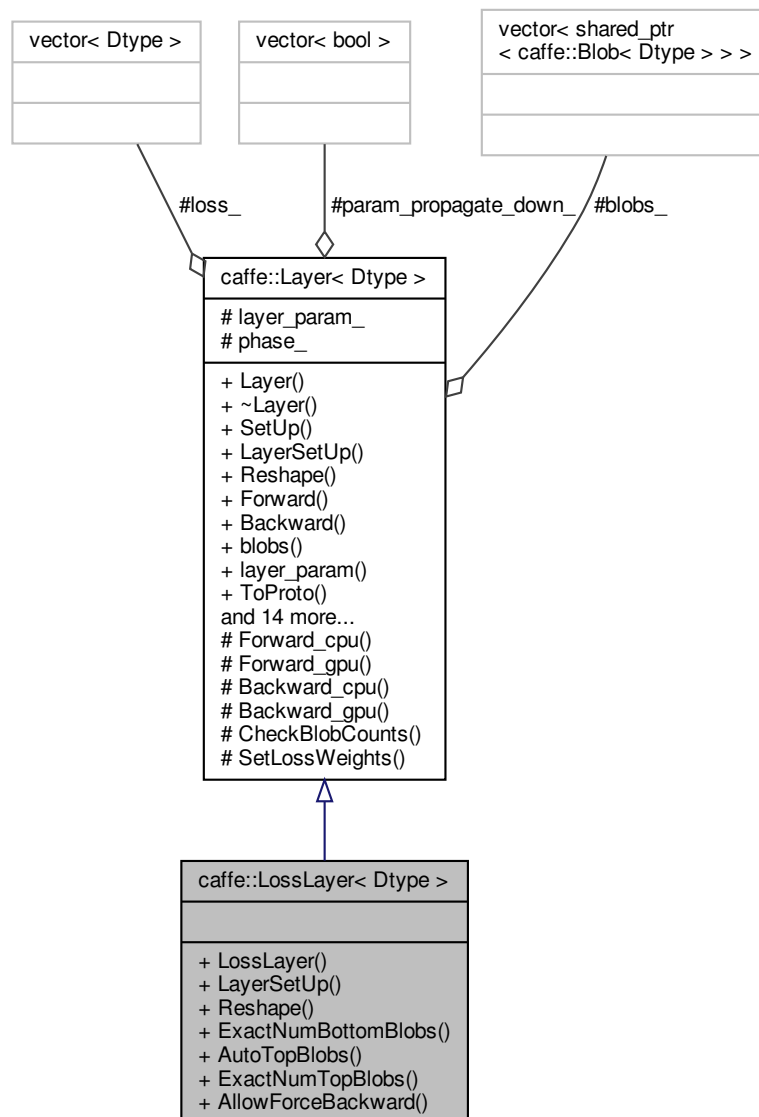
An interface for `Layers` that take two `Blobs` as input – usually (1) predictions and (2) ground-truth labels – and output a singleton `Blob` representing the loss.

```
#include <loss_layer.hpp>
```

Inheritance diagram for `caffe::LossLayer< Dtype >`:



Collaboration diagram for `caffe::LossLayer< Dtype >`:



## Public Member Functions

- **LossLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as *Reshape*.
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.
- virtual int **ExactNumBottomBlobs** () const  
Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.
- virtual bool **AutoTopBlobs** () const  
For convenience and backwards compatibility, instruct the *Net* to automatically allocate a single top *Blob* for Loss↔ Layers, into which they output their singleton loss, (even if the user didn't specify one in the prototxt, etc.).



- virtual int `ExactNumTopBlobs` () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*
- virtual bool `AllowForceBackward` (const int bottom\_index) const

## Additional Inherited Members

### 5.58.1 Detailed Description

```
template<typename Dtype>
class caffe::LossLayer< Dtype >
```

An interface for `Layers` that take two `Blobs` as input – usually (1) predictions and (2) ground-truth labels – and output a singleton `Blob` representing the loss.

LossLayers are typically only capable of backpropagating to their first input – the predictions.

### 5.58.2 Member Function Documentation

#### 5.58.2.1 `AllowForceBackward()`

```
template<typename Dtype >
virtual bool caffe::LossLayer< Dtype >::AllowForceBackward (
    const int bottom_index ) const [inline], [virtual]
```

We usually cannot backpropagate to the labels; ignore `force_backward` for these inputs.

Reimplemented from `caffe::Layer< Dtype >`.

Reimplemented in `caffe::EuclideanLossLayer< Dtype >`, and `caffe::ContrastiveLossLayer< Dtype >`.

#### 5.58.2.2 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::LossLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

Reimplemented in `caffe::InfogainLossLayer< Dtype >`, and `caffe::ContrastiveLossLayer< Dtype >`.

### 5.58.2.3 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::LossLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

Reimplemented in [caffe::InfogainLossLayer< Dtype >](#), and [caffe::SoftmaxWithLossLayer< Dtype >](#).

### 5.58.2.4 LayerSetUp()

```
template<typename Dtype >
void caffe::LossLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

#### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

Reimplemented in [caffe::SoftmaxWithLossLayer< Dtype >](#), [caffe::InfogainLossLayer< Dtype >](#), [caffe::SigmoidCrossEntropyLossLayer< Dtype >](#), and [caffe::ContrastiveLossLayer< Dtype >](#).

### 5.58.2.5 Reshape()

```
template<typename Dtype >
void caffe::LossLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

Reimplemented in [caffe::SoftmaxWithLossLayer< Dtype >](#), [caffe::InfogainLossLayer< Dtype >](#), [caffe::SigmoidCrossEntropyLossLayer< Dtype >](#), [caffe::MultinomialLogisticLossLayer< Dtype >](#), and [caffe::EuclideanLossLayer< Dtype >](#).

The documentation for this class was generated from the following files:

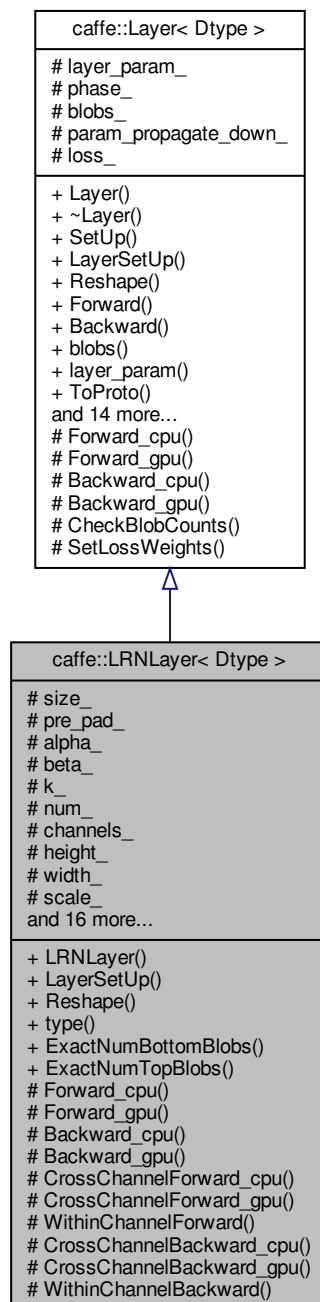
- `include/caffe/layers/loss_layer.hpp`
- `src/caffe/layers/loss_layer.cpp`

## 5.59 `caffe::LRNLayer< Dtype >` Class Template Reference

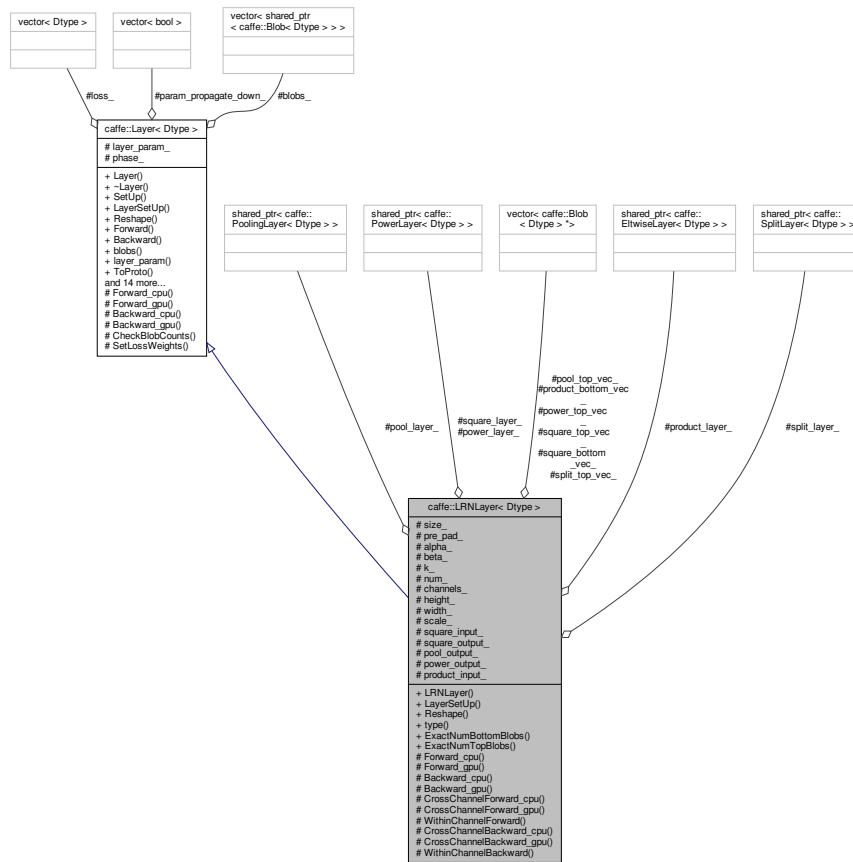
Normalize the input in a local region across or within feature maps.

```
#include <lrn_layer.hpp>
```

Inheritance diagram for caffe::LRNLayer< Dtype >:



Collaboration diagram for caffe::LRNLayer< Dtype >:



## Public Member Functions

- **LRNLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void **Forward\_cpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Using the CPU device, compute the layer output.*
- virtual void **Forward\_gpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

- virtual void **CrossChannelForward\_cpu** (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)
- virtual void **CrossChannelForward\_gpu** (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)
- virtual void **WithinChannelForward** (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)
- virtual void **CrossChannelBackward\_cpu** (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)
- virtual void **CrossChannelBackward\_gpu** (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)
- virtual void **WithinChannelBackward** (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

## Protected Attributes

- int **size\_**
- int **pre\_pad\_**
- Dtype **alpha\_**
- Dtype **beta\_**
- Dtype **k\_**
- int **num\_**
- int **channels\_**
- int **height\_**
- int **width\_**
- [Blob](#)< Dtype > **scale\_**
- shared\_ptr< [SplitLayer](#)< Dtype > > **split\_layer\_**
- vector< [Blob](#)< Dtype > \* > **split\_top\_vec\_**
- shared\_ptr< [PowerLayer](#)< Dtype > > **square\_layer\_**
- [Blob](#)< Dtype > **square\_input\_**
- [Blob](#)< Dtype > **square\_output\_**
- vector< [Blob](#)< Dtype > \* > **square\_bottom\_vec\_**
- vector< [Blob](#)< Dtype > \* > **square\_top\_vec\_**
- shared\_ptr< [PoolingLayer](#)< Dtype > > **pool\_layer\_**
- [Blob](#)< Dtype > **pool\_output\_**
- vector< [Blob](#)< Dtype > \* > **pool\_top\_vec\_**
- shared\_ptr< [PowerLayer](#)< Dtype > > **power\_layer\_**
- [Blob](#)< Dtype > **power\_output\_**
- vector< [Blob](#)< Dtype > \* > **power\_top\_vec\_**
- shared\_ptr< [EltwiseLayer](#)< Dtype > > **product\_layer\_**
- [Blob](#)< Dtype > **product\_input\_**
- vector< [Blob](#)< Dtype > \* > **product\_bottom\_vec\_**

### 5.59.1 Detailed Description

```
template<typename Dtype>
class caffe::LRNLayer< Dtype >
```

Normalize the input in a local region across or within feature maps.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

### 5.59.2 Member Function Documentation

#### 5.59.2.1 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::LRNLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.59.2.2 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::LRNLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.59.2.3 `LayerSetUp()`

```
template<typename Dtype >
void caffe::LRNLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from `caffe::Layer< Dtype >`.

## 5.59.2.4 Reshape()

```
template<typename Dtype >
void caffe::LRNLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following files:

- `include/caffe/layers/lrn_layer.hpp`
- `src/caffe/layers/lrn_layer.cpp`

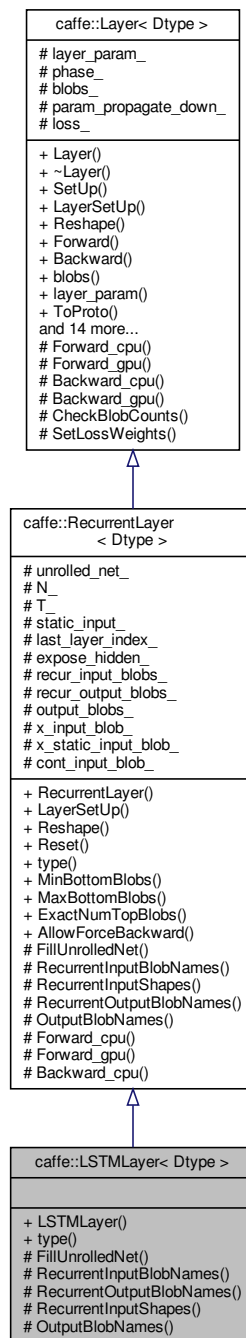
5.60 `caffe::LSTMLayer< Dtype >` Class Template Reference

Processes sequential inputs using a "Long Short-Term Memory" (LSTM) [1] style recurrent neural network (RNN). Implemented by unrolling the LSTM computation through time.

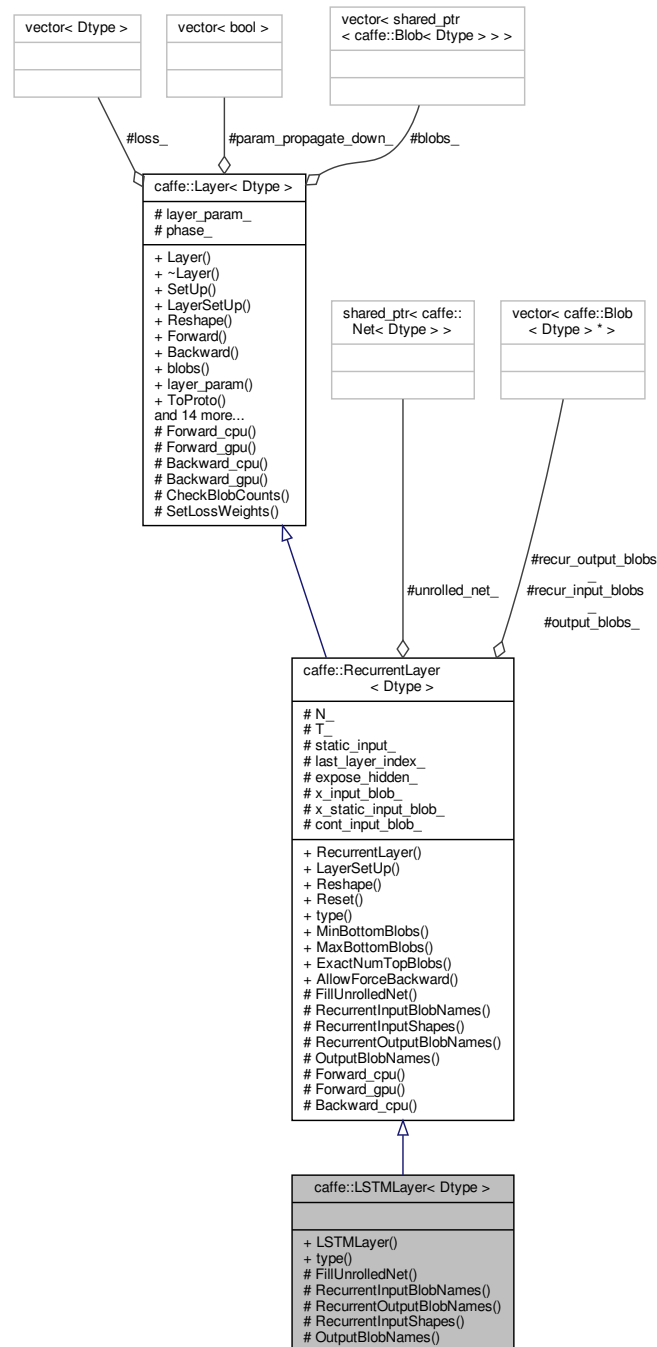
```
#include <lstmlayer.hpp>
```



Inheritance diagram for caffe::LSTMLayer< Dtype >:



Collaboration diagram for `caffe::LSTMLayer< Dtype >`:



## Public Member Functions

- **LSTMLayer** (const LayerParameter &param)
- virtual const char \* **type** () const

Returns the layer type.

## Protected Member Functions

- virtual void [FillUnrolledNet](#) (NetParameter \*net\_param) const  
*Fills net\_param with the recurrent network architecture. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void [RecurrentInputBlobNames](#) (vector< string > \*names) const  
*Fills names with the names of the 0th timestep recurrent input [Blob](#)&s. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void [RecurrentOutputBlobNames](#) (vector< string > \*names) const  
*Fills names with the names of the Tth timestep recurrent output [Blob](#)&s. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void [RecurrentInputShapes](#) (vector< BlobShape > \*shapes) const  
*Fills shapes with the shapes of the recurrent input [Blob](#)&s. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void [OutputBlobNames](#) (vector< string > \*names) const  
*Fills names with the names of the output blobs, concatenated across all timesteps. Should return a name for each top [Blob](#). Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*

## Additional Inherited Members

## 5.60.1 Detailed Description

```
template<typename Dtype>
class caffe::LSTMLayer< Dtype >
```

Processes sequential inputs using a "Long Short-Term Memory" (LSTM) [1] style recurrent neural network (RNN). Implemented by unrolling the LSTM computation through time.

The specific architecture used in this implementation is as described in "Learning to Execute" [2], reproduced below:  $i_t := [W_{\{hi\}} * h_{\{t-1\}} + W_{\{xi\}} * x_t + b_i]$   $f_t := [W_{\{hf\}} * h_{\{t-1\}} + W_{\{xf\}} * x_t + b_f]$   $o_t := [W_{\{ho\}} * h_{\{t-1\}} + W_{\{xo\}} * x_t + b_o]$   $g_t := [W_{\{hg\}} * h_{\{t-1\}} + W_{\{xg\}} * x_t + b_g]$   $c_t := (f_t .* c_{\{t-1\}}) + (i_t .* g_t)$   $h_t := o_t .* [c_t]$  In the implementation, the i, f, o, and g computations are performed as a single inner product.

Notably, this implementation lacks the "diagonal" gates, as used in the LSTM architectures described by Alex Graves [3] and others.

[1] Hochreiter, Sepp, and Schmidhuber, Jürgen. "Long short-term memory." Neural Computation 9, no. 8 (1997): 1735-1780.

[2] Zaremba, Wojciech, and Sutskever, Ilya. "Learning to execute." arXiv preprint arXiv:1410.4615 (2014).

[3] Graves, Alex. "Generating sequences with recurrent neural networks." arXiv preprint arXiv:1308.0850 (2013).

The documentation for this class was generated from the following files:

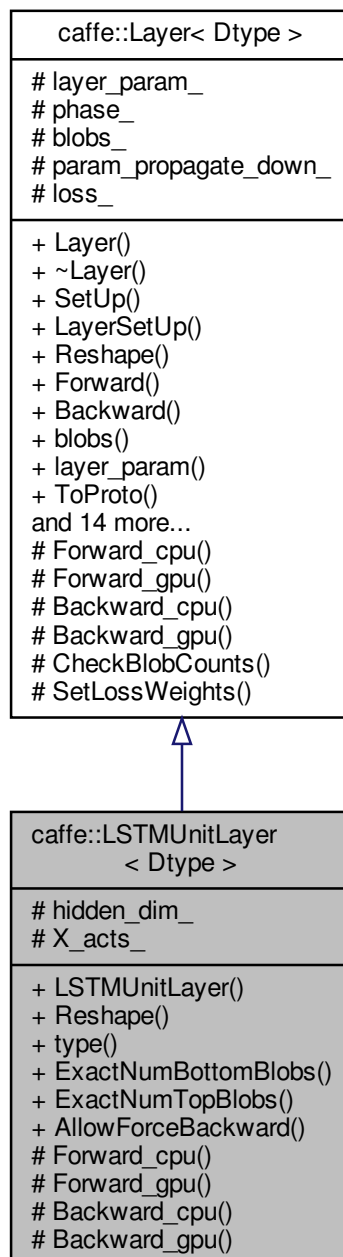
- include/caffe/layers/lstm\_layer.hpp
- src/caffe/layers/lstm\_layer.cpp

## 5.61 caffe::LSTMUnitLayer< Dtype > Class Template Reference

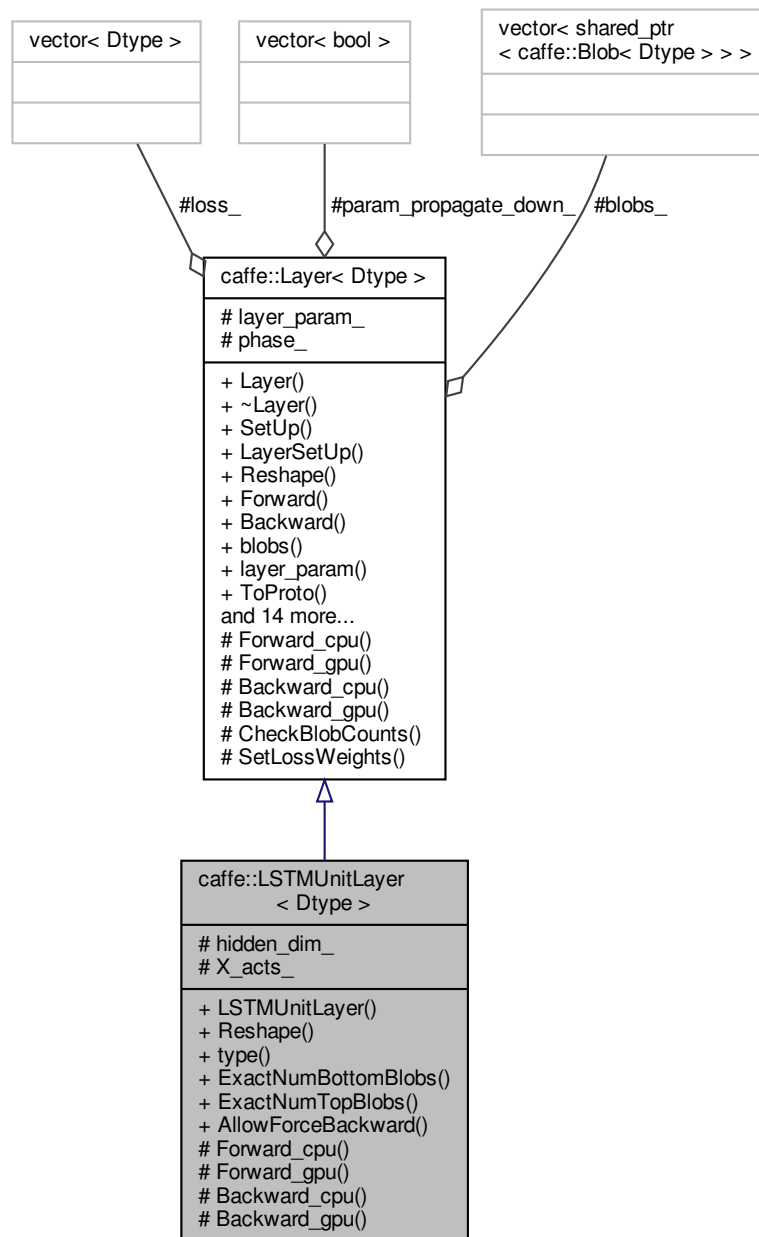
A helper for [LSTMLayer](#): computes a single timestep of the non-linearity of the LSTM, producing the updated cell and hidden states.

```
#include <lstm_layer.hpp>
```

Inheritance diagram for caffe::LSTMUnitLayer< Dtype >:



Collaboration diagram for caffe::LSTMUnitLayer< Dtype >:



## Public Member Functions

- **LSTMUnitLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.
- virtual const char \* **type** () const  
Returns the layer type.
- virtual int **ExactNumBottomBlobs** () const

*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*

- virtual int [ExactNumTopBlobs](#) () const

*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

- virtual bool [AllowForceBackward](#) (const int bottom\_index) const

*Return whether to allow force\_backward for a given bottom blob index.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

*Computes the error gradient w.r.t. the LSTMUnit inputs.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- int [hidden\\_dim\\_](#)

*The hidden and output dimension.*

- [Blob](#)< Dtype > [X\\_acts\\_](#)

## 5.61.1 Detailed Description

```
template<typename Dtype>
class caffe::LSTMUnitLayer< Dtype >
```

A helper for [LSTMLayer](#): computes a single timestep of the non-linearity of the LSTM, producing the updated cell and hidden states.

## 5.61.2 Member Function Documentation

### 5.61.2.1 AllowForceBackward()

```
template<typename Dtype >
virtual bool caffe::LSTMUnitLayer< Dtype >::AllowForceBackward (
    const int bottom_index ) const [inline], [virtual]
```

Return whether to allow force\_backward for a given bottom blob index.

If AllowForceBackward(i) == false, we will ignore the force\_backward setting and backpropagate to blob i only if it needs gradient information (as is done when force\_backward == false).

Reimplemented from [caffe::Layer](#)< Dtype >.

5.61.2.2 `Backward_cpu()`

```
template<typename Dtype >
void caffe::LSTMUnitLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the LSTMUnit inputs.

## Parameters

<i>top</i>	output <b>Blob</b> vector (length 2), providing the error gradient with respect to the outputs <ol style="list-style-type: none"> <li><math>(1 \times N \times D)</math>: containing error gradients <math>\frac{\partial E}{\partial c_t}</math> with respect to the updated cell state <math>c_t</math></li> <li><math>(1 \times N \times D)</math>: containing error gradients <math>\frac{\partial E}{\partial h_t}</math> with respect to the updated cell state <math>h_t</math></li> </ol>
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <b>Blob</b> vector (length 3), into which the error gradients with respect to the LSTMUnit inputs $c_{t-1}$ and the gate inputs are computed. Computation of the error gradients w.r.t. the sequence indicators is not implemented. <ol style="list-style-type: none"> <li><math>(1 \times N \times D)</math> the error gradient w.r.t. the previous timestep cell state <math>c_{t-1}</math></li> <li><math>(1 \times N \times 4D)</math> the error gradient w.r.t. the "gate inputs" <math>[\frac{\partial E}{\partial i_t} \frac{\partial E}{\partial f_t} \frac{\partial E}{\partial o_t} \frac{\partial E}{\partial g_t}]</math></li> <li><math>(1 \times 1 \times N)</math> the gradient w.r.t. the sequence continuation indicators <math>\delta_t</math> is currently not computed.</li> </ol>

Implements [caffe::Layer< Dtype >](#).

5.61.2.3 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::LSTMUnitLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

5.61.2.4 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::LSTMUnitLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.61.2.5 Forward\_cpu()

```
template<typename Dtype >
void caffe::LSTMUnitLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 3) <ol style="list-style-type: none"> <li>1. <math>(1 \times N \times D)</math> the previous timestep cell state <math>c_{t-1}</math></li> <li>2. <math>(1 \times N \times 4D)</math> the "gate inputs" <math>[i'_t, f'_t, o'_t, g'_t]</math></li> <li>3. <math>(1 \times N)</math> the sequence continuation indicators <math>\delta_t</math></li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li>1. <math>(1 \times N \times D)</math> the updated cell state <math>c_t</math>, computed as: <math>i\_t := [i\_t']</math> <math>f\_t := [f\_t']</math> <math>o\_t := [o\_t']</math> <math>g\_t := [g\_t']</math> <math>c\_t := \text{cont\_t} * (f\_t .* c_{t-1}) + (i\_t .* g\_t)</math></li> <li>2. <math>(1 \times N \times D)</math> the updated hidden state <math>h_t</math>, computed as: <math>h\_t := o\_t .* [c\_t]</math></li> </ol>

Implements [caffe::Layer< Dtype >](#).

## 5.61.2.6 Reshape()

```
template<typename Dtype >
void caffe::LSTMUnitLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

- include/caffe/layers/lstm\_layer.hpp
- src/caffe/layers/lstm\_unit\_layer.cpp

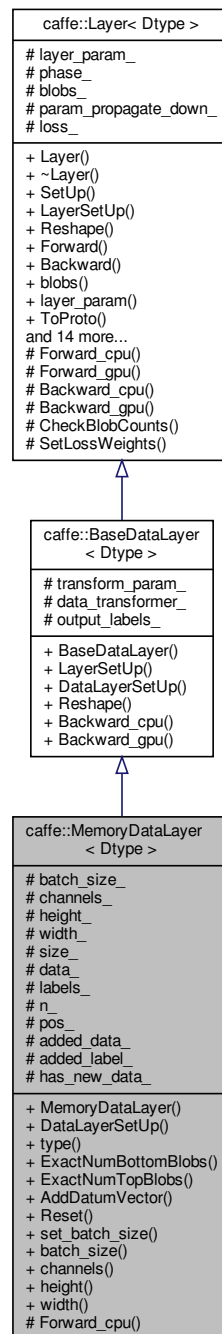


## 5.62 caffe::MemoryDataLayer< Dtype > Class Template Reference

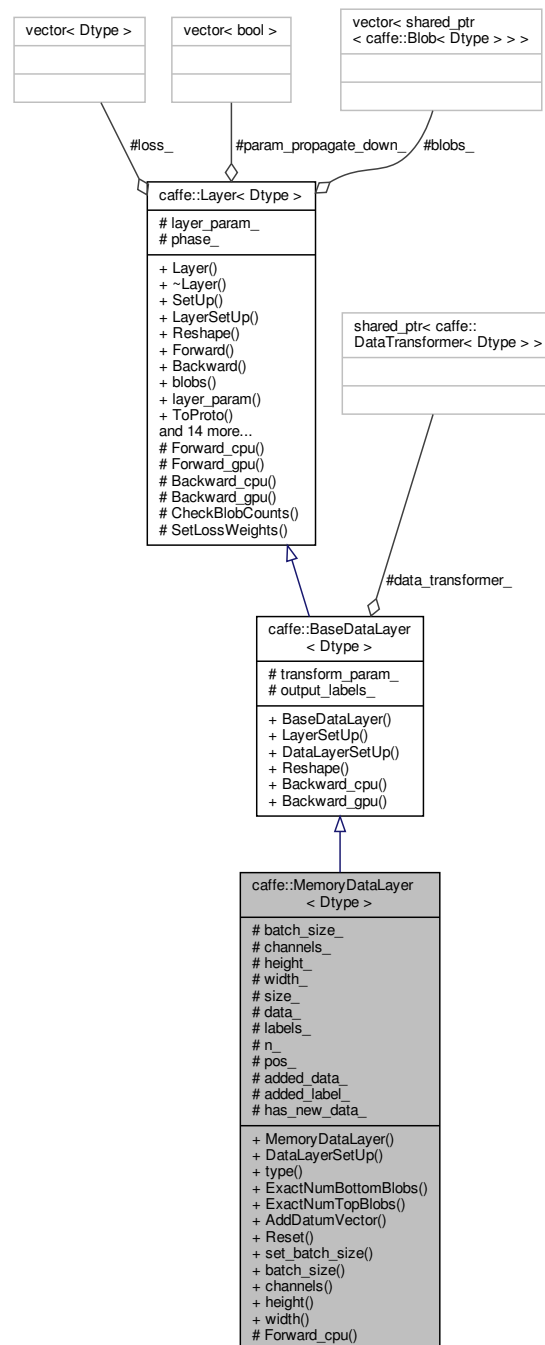
Provides data to the [Net](#) from memory.

```
#include <memory_data_layer.hpp>
```

Inheritance diagram for caffe::MemoryDataLayer< Dtype >:



Collaboration diagram for `caffe::MemoryDataLayer< Dtype >`:



## Public Member Functions

- **MemoryDataLayer** (const LayerParameter &param)
- virtual void **DataLayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)
- virtual const char \* **type** () const  
*Returns the layer type.*

- virtual int [ExactNumBottomBlobs](#) () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int [ExactNumTopBlobs](#) () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*
- virtual void **AddDatumVector** (const vector< Datum > &datum\_vector)
- void **Reset** (Dtype \*data, Dtype \*label, int n)
- void **set\_batch\_size** (int new\_size)
- int **batch\_size** ()
- int **channels** ()
- int **height** ()
- int **width** ()

### Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the CPU device, compute the layer output.*

### Protected Attributes

- int **batch\_size\_**
- int **channels\_**
- int **height\_**
- int **width\_**
- int **size\_**
- Dtype \* **data\_**
- Dtype \* **labels\_**
- int **n\_**
- size\_t **pos\_**
- [Blob](#)< Dtype > **added\_data\_**
- [Blob](#)< Dtype > **added\_label\_**
- bool **has\_new\_data\_**

#### 5.62.1 Detailed Description

```
template<typename Dtype>
class caffe::MemoryDataLayer< Dtype >
```

Provides data to the [Net](#) from memory.

TODO(dox): thorough documentation for Forward and proto params.

#### 5.62.2 Member Function Documentation

#### 5.62.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::MemoryDataLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.62.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::MemoryDataLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

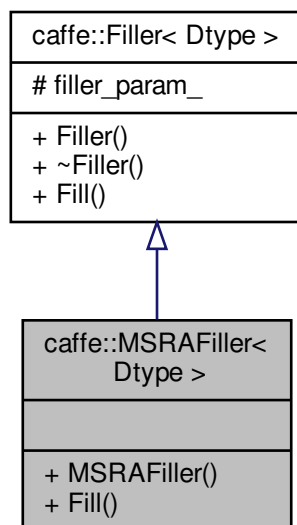
- include/caffe/layers/memory\_data\_layer.hpp
- src/caffe/layers/memory\_data\_layer.cpp

## 5.63 [caffe::MSRAFiller< Dtype >](#) Class Template Reference

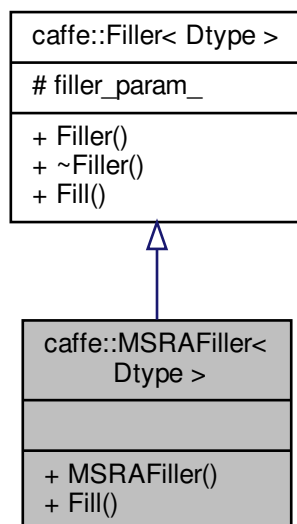
Fills a [Blob](#) with values  $x \sim N(0, \sigma^2)$  where  $\sigma^2$  is set inversely proportional to number of incoming nodes, outgoing nodes, or their average.

```
#include <filler.hpp>
```

Inheritance diagram for caffe::MSRAFiller< Dtype >:



Collaboration diagram for caffe::MSRAFiller< Dtype >:



### Public Member Functions

- **MSRAFiller** (const FillerParameter &param)
- virtual void **Fill** (Blob< Dtype > \*blob)

## Additional Inherited Members

### 5.63.1 Detailed Description

```
template<typename Dtype>
class caffe::MSRAFiller< Dtype >
```

Fills a [Blob](#) with values  $x \sim N(0, \sigma^2)$  where  $\sigma^2$  is set inversely proportional to number of incoming nodes, outgoing nodes, or their average.

A [Filler](#) based on the paper [He, Zhang, Ren and Sun 2015]: Specifically accounts for ReLU nonlinearities.

Aside: for another perspective on the scaling factor, see the derivation of [Saxe, McClelland, and Ganguli 2013 (v3)].

It fills the incoming matrix by randomly sampling Gaussian data with  $\text{std} = \sqrt{2 / n}$  where  $n$  is the `fan_in`, `fan_out`, or their average, depending on the `variance_norm` option. You should make sure the input blob has shape  $(\text{num}, a, b, c)$  where  $a * b * c = \text{fan\_in}$  and  $\text{num} * b * c = \text{fan\_out}$ . Note that this is currently not the case for inner product layers.

The documentation for this class was generated from the following file:

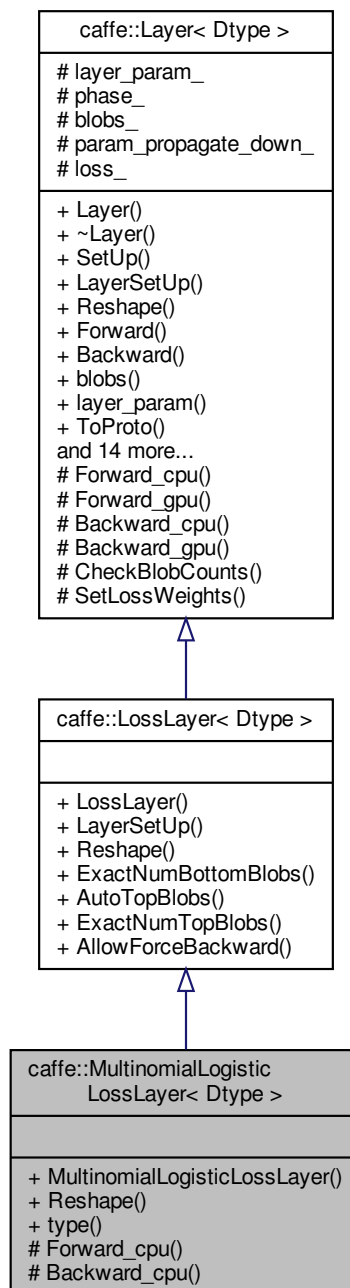
- `include/caffe/filler.hpp`

## 5.64 `caffe::MultinomialLogisticLossLayer< Dtype >` Class Template Reference

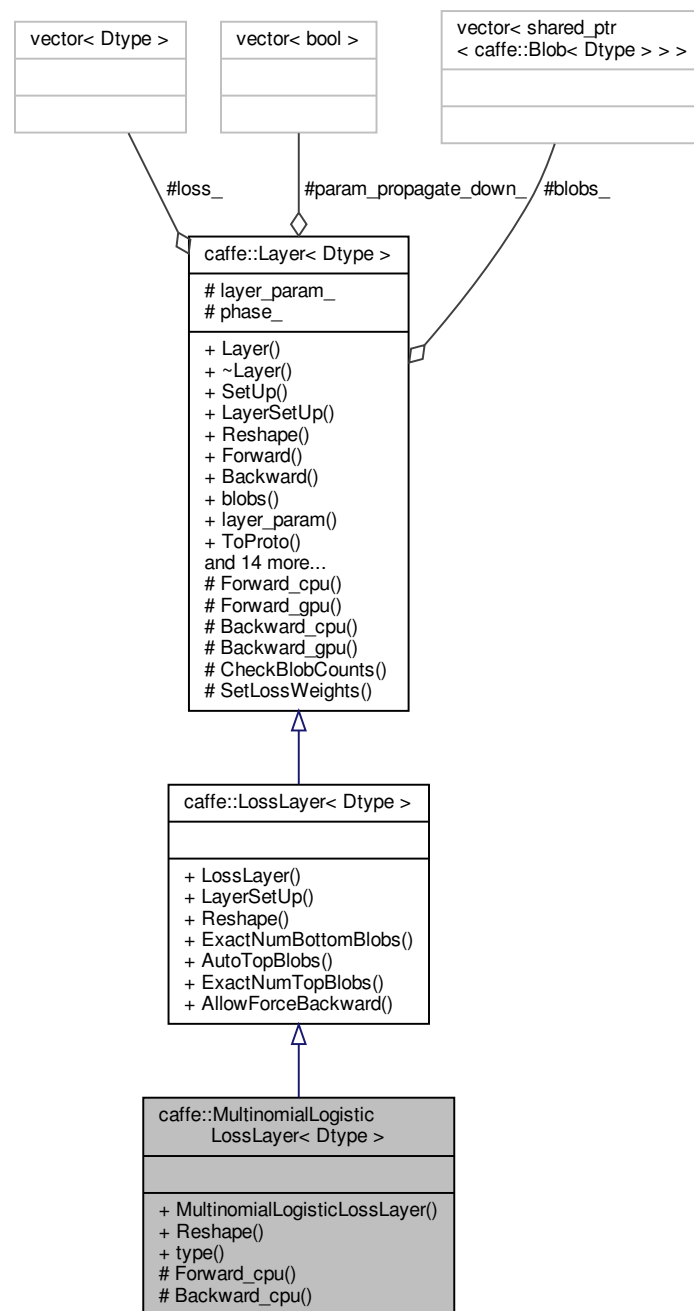
Computes the multinomial logistic loss for a one-of-many classification task, directly taking a predicted probability distribution as input.

```
#include <multinomial_logistic_loss_layer.hpp>
```

Inheritance diagram for caffe::MultinomialLogisticLossLayer< Dtype >:



Collaboration diagram for `caffe::MultinomialLogisticLossLayer< Dtype >`:



## Public Member Functions

- **MultinomialLogisticLossLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.
- virtual const char \* **type** () const  
Returns the layer type.



## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Computes the multinomial logistic loss for a one-of-many classification task, directly taking a predicted probability distribution as input.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Computes the multinomial logistic loss error gradient w.r.t. the predictions.*

## Additional Inherited Members

### 5.64.1 Detailed Description

```
template<typename Dtype>
class caffe::MultinomialLogisticLossLayer< Dtype >
```

Computes the multinomial logistic loss for a one-of-many classification task, directly taking a predicted probability distribution as input.

When predictions are not already a probability distribution, you should instead use the [SoftmaxWithLossLayer](#), which maps predictions to a distribution using the [SoftmaxLayer](#), before computing the multinomial logistic loss. The [SoftmaxWithLossLayer](#) should be preferred over separate [SoftmaxLayer](#) + [MultinomialLogisticLossLayer](#) as its gradient computation is more numerically stable.

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li>1. <math>(N \times C \times H \times W)</math> the predictions <math>\hat{p}</math>, a <a href="#">Blob</a> with values in <math>[0, 1]</math> indicating the predicted probability of each of the <math>K = CHW</math> classes. Each prediction vector <math>\hat{p}_n</math> should sum to 1 as in a probability distribution: <math>\forall n \sum_{k=1}^K \hat{p}_{nk} = 1</math>.</li> <li>2. <math>(N \times 1 \times 1 \times 1)</math> the labels <math>l</math>, an integer-valued <a href="#">Blob</a> with values <math>l_n \in [0, 1, 2, \dots, K - 1]</math> indicating the correct class label among the <math>K</math> classes</li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li>1. <math>(1 \times 1 \times 1 \times 1)</math> the computed multinomial logistic loss: <math>E = \frac{-1}{N} \sum_{n=1}^N \log(\hat{p}_{n,l_n})</math></li> </ol>

### 5.64.2 Member Function Documentation

#### 5.64.2.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::MultinomialLogisticLossLayer< Dtype >::Backward_cpu (
```

```
const vector< Blob< Dtype > *> & top,
const vector< bool > & propagate_down,
const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the multinomial logistic loss error gradient w.r.t. the predictions.

Gradients cannot be computed with respect to the label inputs (bottom[1]), so this method ignores bottom[1] and requires !propagate\_down[1], crashing if propagate\_down[1] is set.

#### Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> This <a href="#">Blob</a>'s diff will simply contain the loss_weight* <math>\lambda</math>, as <math>\lambda</math> is the coefficient of this layer's output <math>\ell_i</math> in the overall <a href="#">Net</a> loss <math>E = \lambda_i \ell_i + \text{other loss terms}</math>; hence <math>\frac{\partial E}{\partial \ell_i} = \lambda_i</math>. (*Assuming that this top <a href="#">Blob</a> is not used as a bottom (input) by any other layer of the <a href="#">Net</a>.)</li> </ol>
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> . propagate_down[1] must be false as we can't compute gradients with respect to the labels.
<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the predictions <math>\hat{p}</math>; Backward computes diff <math>\frac{\partial E}{\partial \hat{p}}</math></li> <li><math>(N \times 1 \times 1 \times 1)</math> the labels – ignored as we can't compute their error gradients</li> </ol>

Implements [caffe::Layer< Dtype >](#).

#### 5.64.2.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::MultinomialLogisticLossLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

Computes the multinomial logistic loss for a one-of-many classification task, directly taking a predicted probability distribution as input.

When predictions are not already a probability distribution, you should instead use the [SoftmaxWithLossLayer](#), which maps predictions to a distribution using the [SoftmaxLayer](#), before computing the multinomial logistic loss. The [SoftmaxWithLossLayer](#) should be preferred over separate [SoftmaxLayer](#) + [MultinomialLogisticLossLayer](#) as its gradient computation is more numerically stable.

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the predictions <math>\hat{p}</math>, a <a href="#">Blob</a> with values in <math>[0, 1]</math> indicating the predicted probability of each of the <math>K = CHW</math> classes. Each prediction vector <math>\hat{p}_n</math> should sum to 1 as in a probability distribution: <math>\forall n \sum_{k=1}^K \hat{p}_{nk} = 1</math>.</li> <li><math>(N \times 1 \times 1 \times 1)</math> the labels <math>l</math>, an integer-valued <a href="#">Blob</a> with values <math>l_n \in [0, 1, 2, \dots, K - 1]</math> indicating the correct class label among the <math>K</math> classes</li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <div style="text-align: right;">Generated by Doxygen</div> <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> the computed multinomial logistic loss: <math>E = \frac{-1}{N} \sum_{n=1}^N \log(\hat{p}_{n, l_n})</math></li> </ol>

Implements [caffe::Layer< Dtype >](#).

### 5.64.2.3 Reshape()

```
template<typename Dtype >
void caffe::MultinomialLogisticLossLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

#### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Reimplemented from [caffe::LossLayer< Dtype >](#).

The documentation for this class was generated from the following files:

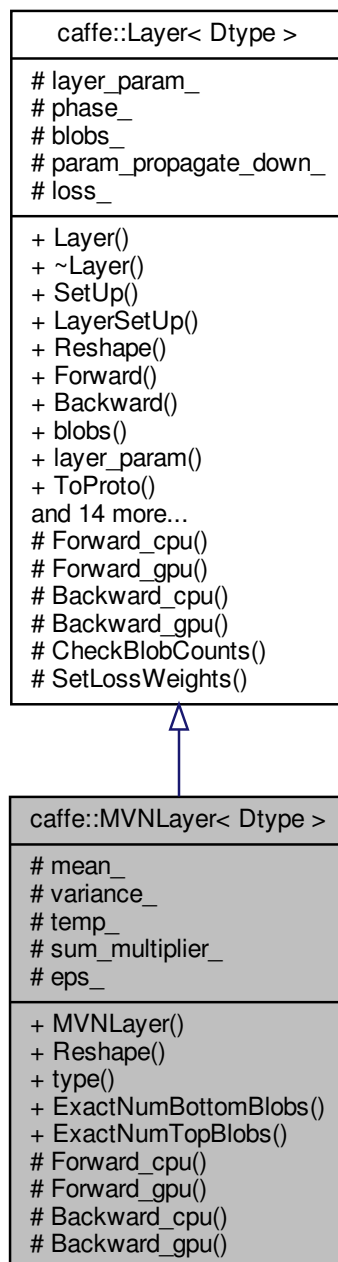
- `include/caffe/layers/multinomial_logistic_loss_layer.hpp`
- `src/caffe/layers/multinomial_logistic_loss_layer.cpp`

## 5.65 `caffe::MVNLayer< Dtype >` Class Template Reference

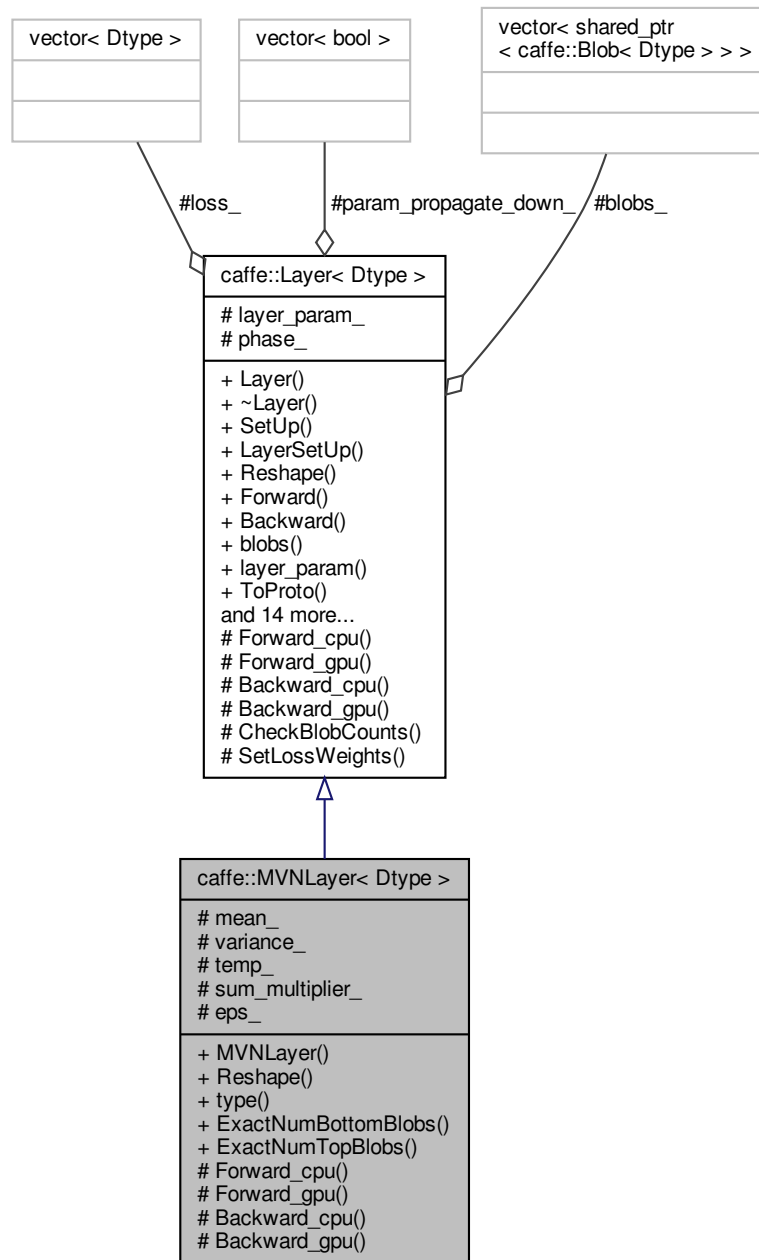
Normalizes the input to have 0-mean and/or unit (1) variance.

```
#include <mvn_layer.hpp>
```

Inheritance diagram for caffe::MVNLayer< Dtype >:



Collaboration diagram for caffe::MVNLayer< Dtype >:



## Public Member Functions

- **MVNLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.
- virtual const char \* **type** () const  
Returns the layer type.
- virtual int **ExactNumBottomBlobs** () const

*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*

- virtual int [ExactNumTopBlobs](#) () const

*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the CPU device, compute the layer output.*

- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- [Blob](#)< Dtype > **mean\_**
- [Blob](#)< Dtype > **variance\_**
- [Blob](#)< Dtype > **temp\_**
- [Blob](#)< Dtype > **sum\_multiplier\_**

*sum\_multiplier is used to carry out sum using BLAS*

- Dtype **eps\_**

### 5.65.1 Detailed Description

```
template<typename Dtype>
class caffe::MVNLayer< Dtype >
```

Normalizes the input to have 0-mean and/or unit (1) variance.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

### 5.65.2 Member Function Documentation

5.65.2.1 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::MVNLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.65.2.2 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::MVNLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.65.2.3 `Reshape()`

```
template<typename Dtype >
void caffe::MVNLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

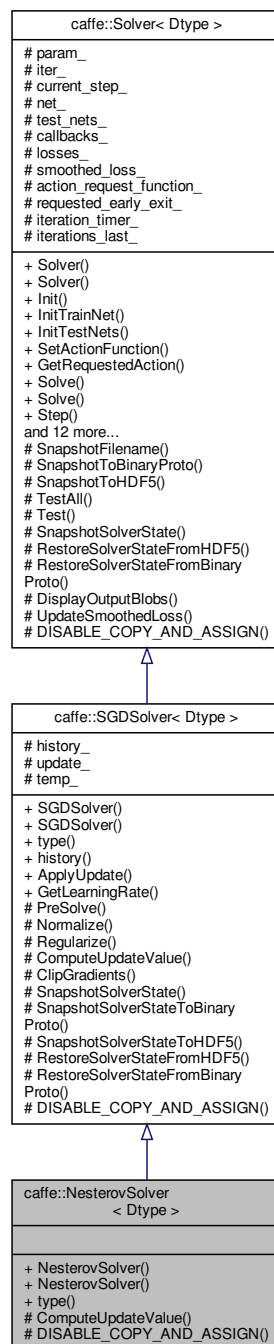
Implements `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following files:

- `include/caffe/layers/mvn_layer.hpp`
- `src/caffe/layers/mvn_layer.cpp`

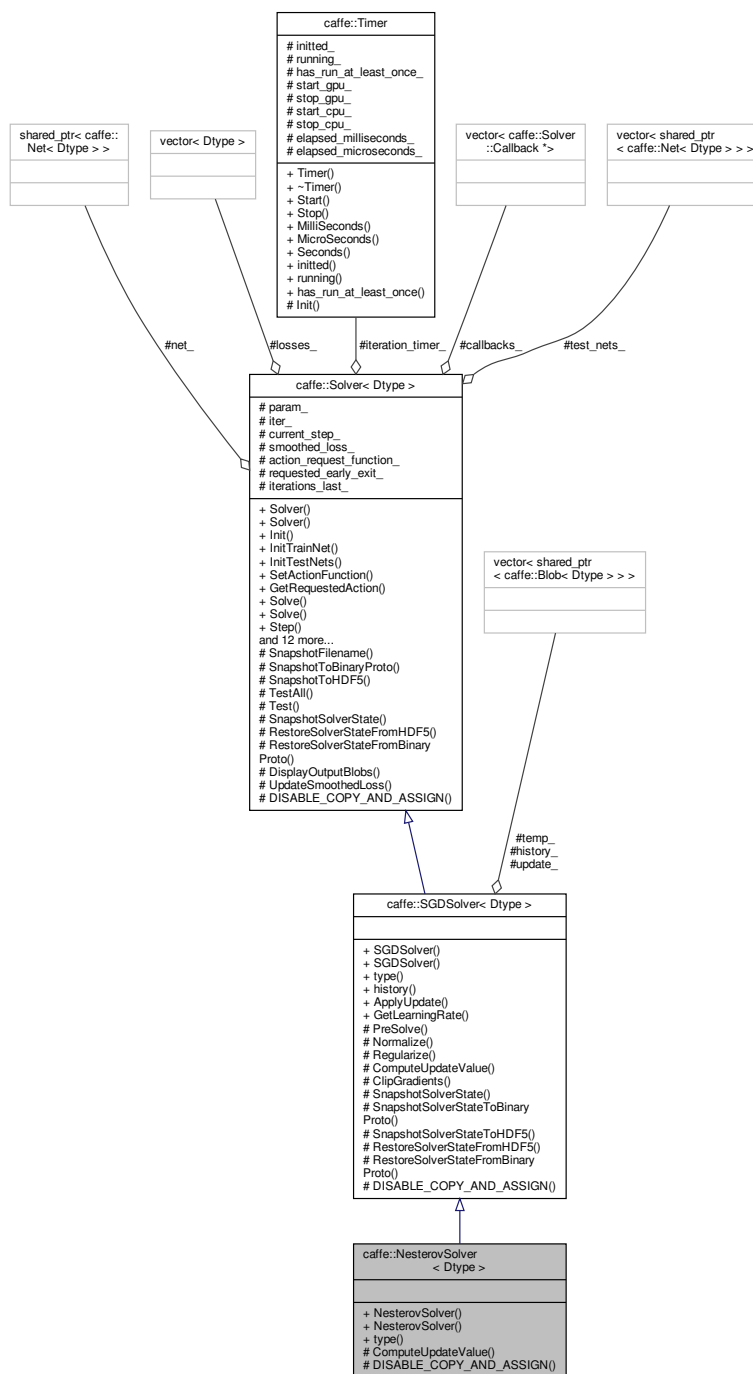
## 5.66 caffe::NesterovSolver< Dtype > Class Template Reference

Inheritance diagram for caffe::NesterovSolver< Dtype >:





Collaboration diagram for caffe::NesterovSolver< Dtype >:



## Public Member Functions

- **NesterovSolver** (const SolverParameter &param)
- **NesterovSolver** (const string &param\_file)
- virtual const char \* **type** () const

Returns the solver type.



- DEPRECATED; set input blobs then use [Forward\(\)](#) instead.*

  - void [ClearParamDiffs](#) ()
 

*Zeroes out the diffs of all net parameters. Should be run before Backward.*
  - void [Backward](#) ()
  - void [BackwardFromTo](#) (int start, int end)
  - void [BackwardFrom](#) (int start)
  - void [BackwardTo](#) (int end)
  - void [Reshape](#) ()
 

*Reshape all layers from bottom to top.*
  - Dtype [ForwardBackward](#) ()
  - void [Update](#) ()
 

*Updates the network weights based on the diff values computed.*
  - void [ShareWeights](#) ()
 

*Shares weight data of owner blobs with shared blobs.*
  - void [ShareTrainedLayersWith](#) (const [Net](#) \*other)
 

*For an already initialized net, implicitly copies (i.e., using no additional memory) the pre-trained layers from another [Net](#).*
  - void [CopyTrainedLayersFrom](#) (const NetParameter &param)
 

*For an already initialized net, copies the pre-trained layers from another [Net](#).*
  - void [CopyTrainedLayersFrom](#) (const string &trained\_filename)
  - void [CopyTrainedLayersFromBinaryProto](#) (const string &trained\_filename)
  - void [CopyTrainedLayersFromHDF5](#) (const string &trained\_filename)
  - void [ToProto](#) (NetParameter \*param, bool write\_diff=false) const
 

*Writes the net to a proto.*
  - void [ToHDF5](#) (const string &filename, bool write\_diff=false) const
 

*Writes the net to an HDF5 file.*
  - const string & [name](#) () const
 

*returns the network name.*
  - const vector< string > & [layer\\_names](#) () const
 

*returns the layer names*
  - const vector< string > & [blob\\_names](#) () const
 

*returns the blob names*
  - const vector< shared\_ptr< [Blob](#)< Dtype > > > & [blobs](#) () const
 

*returns the blobs*
  - const vector< shared\_ptr< [Layer](#)< Dtype > > > & [layers](#) () const
 

*returns the layers*
  - Phase [phase](#) () const
 

*returns the phase: TRAIN or TEST*
  - const vector< vector< [Blob](#)< Dtype > \* > > & [bottom\\_vecs](#) () const
 

*returns the bottom vecs for each layer – usually you won't need this unless you do per-layer checks such as gradients.*
  - const vector< vector< [Blob](#)< Dtype > \* > > & [top\\_vecs](#) () const
 

*returns the top vecs for each layer – usually you won't need this unless you do per-layer checks such as gradients.*
  - const vector< int > & [top\\_ids](#) (int i) const
 

*returns the ids of the top blobs of layer i*
  - const vector< int > & [bottom\\_ids](#) (int i) const
 

*returns the ids of the bottom blobs of layer i*
  - const vector< vector< bool > > & [bottom\\_need\\_backward](#) () const
  - const vector< Dtype > & [blob\\_loss\\_weights](#) () const
  - const vector< bool > & [layer\\_need\\_backward](#) () const
  - const vector< shared\_ptr< [Blob](#)< Dtype > > > & [params](#) () const
 

*returns the parameters*
  - const vector< [Blob](#)< Dtype > \* > & [learnable\\_params](#) () const

- const vector< float > & **params\_lr** () const  
*returns the learnable parameter learning rate multipliers*
- const vector< bool > & **has\_params\_lr** () const
- const vector< float > & **params\_weight\_decay** () const  
*returns the learnable parameter decay multipliers*
- const vector< bool > & **has\_params\_decay** () const
- const map< string, int > & **param\_names\_index** () const
- const vector< int > & **param\_owners** () const
- const vector< string > & **param\_display\_names** () const
- int **num\_inputs** () const  
*Input and output blob numbers.*
- int **num\_outputs** () const
- const vector< Blob< Dtype > \* > & **input\_blobs** () const
- const vector< Blob< Dtype > \* > & **output\_blobs** () const
- const vector< int > & **input\_blob\_indices** () const
- const vector< int > & **output\_blob\_indices** () const
- bool **has\_blob** (const string &blob\_name) const
- const shared\_ptr< Blob< Dtype > > & **blob\_by\_name** (const string &blob\_name) const
- bool **has\_layer** (const string &layer\_name) const
- const shared\_ptr< Layer< Dtype > > & **layer\_by\_name** (const string &layer\_name) const
- void **set\_debug\_info** (const bool value)
- const vector< Callback \* > & **before\_forward** () const
- void **add\_before\_forward** (Callback \*value)
- const vector< Callback \* > & **after\_forward** () const
- void **add\_after\_forward** (Callback \*value)
- const vector< Callback \* > & **before\_backward** () const
- void **add\_before\_backward** (Callback \*value)
- const vector< Callback \* > & **after\_backward** () const
- void **add\_after\_backward** (Callback \*value)

### Static Public Member Functions

- static void **FilterNet** (const NetParameter &param, NetParameter \*param\_filtered)  
*Remove layers that the user specified should be excluded given the current phase, level, and stage.*
- static bool **StateMeetsRule** (const NetState &state, const NetStateRule &rule, const string &layer\_name)  
*return whether NetState state meets NetStateRule rule*

### Protected Member Functions

- void **AppendTop** (const NetParameter &param, const int layer\_id, const int top\_id, set< string > \*available\_blobs, map< string, int > \*blob\_name\_to\_idx)  
*Append a new top blob to the net.*
- int **AppendBottom** (const NetParameter &param, const int layer\_id, const int bottom\_id, set< string > \*available\_blobs, map< string, int > \*blob\_name\_to\_idx)  
*Append a new bottom blob to the net.*
- void **AppendParam** (const NetParameter &param, const int layer\_id, const int param\_id)  
*Append a new parameter blob to the net.*
- void **ForwardDebugInfo** (const int layer\_id)  
*Helper for displaying debug info in Forward.*
- void **BackwardDebugInfo** (const int layer\_id)  
*Helper for displaying debug info in Backward.*
- void **UpdateDebugInfo** (const int param\_id)  
*Helper for displaying debug info in Update.*
- **DISABLE\_COPY\_AND\_ASSIGN** (Net)

## Protected Attributes

- string [name\\_](#)  
*The network name.*
- Phase [phase\\_](#)  
*The phase: TRAIN or TEST.*
- vector< shared\_ptr< [Layer](#)< Dtype > > > [layers\\_](#)  
*Individual layers in the net.*
- vector< string > [layer\\_names\\_](#)
- map< string, int > [layer\\_names\\_index\\_](#)
- vector< bool > [layer\\_need\\_backward\\_](#)
- vector< shared\_ptr< [Blob](#)< Dtype > > > [blobs\\_](#)  
*the blobs storing intermediate results between the layer.*
- vector< string > [blob\\_names\\_](#)
- map< string, int > [blob\\_names\\_index\\_](#)
- vector< bool > [blob\\_need\\_backward\\_](#)
- vector< vector< [Blob](#)< Dtype > \* > > [bottom\\_vecs\\_](#)
- vector< vector< int > > [bottom\\_id\\_vecs\\_](#)
- vector< vector< bool > > [bottom\\_need\\_backward\\_](#)
- vector< vector< [Blob](#)< Dtype > \* > > [top\\_vecs\\_](#)  
*top\_vecs stores the vectors containing the output for each layer*
- vector< vector< int > > [top\\_id\\_vecs\\_](#)
- vector< Dtype > [blob\\_loss\\_weights\\_](#)
- vector< vector< int > > [param\\_id\\_vecs\\_](#)
- vector< int > [param\\_owners\\_](#)
- vector< string > [param\\_display\\_names\\_](#)
- vector< pair< int, int > > [param\\_layer\\_indices\\_](#)
- map< string, int > [param\\_names\\_index\\_](#)
- vector< int > [net\\_input\\_blob\\_indices\\_](#)  
*blob indices for the input and the output of the net*
- vector< int > [net\\_output\\_blob\\_indices\\_](#)
- vector< [Blob](#)< Dtype > \* > [net\\_input\\_blobs\\_](#)
- vector< [Blob](#)< Dtype > \* > [net\\_output\\_blobs\\_](#)
- vector< shared\_ptr< [Blob](#)< Dtype > > > [params\\_](#)  
*The parameters in the network.*
- vector< [Blob](#)< Dtype > \* > [learnable\\_params\\_](#)
- vector< int > [learnable\\_param\\_ids\\_](#)
- vector< float > [params\\_lr\\_](#)  
*the learning rate multipliers for learnable\_params\_*
- vector< bool > [has\\_params\\_lr\\_](#)
- vector< float > [params\\_weight\\_decay\\_](#)  
*the weight decay multipliers for learnable\_params\_*
- vector< bool > [has\\_params\\_decay\\_](#)
- size\_t [memory\\_used\\_](#)  
*The bytes of memory used by this net.*
- bool [debug\\_info\\_](#)  
*Whether to compute and display debug info for the net.*
- vector< [Callback](#) \* > [before\\_forward\\_](#)
- vector< [Callback](#) \* > [after\\_forward\\_](#)
- vector< [Callback](#) \* > [before\\_backward\\_](#)
- vector< [Callback](#) \* > [after\\_backward\\_](#)

### 5.67.1 Detailed Description

```
template<typename Dtype>
class caffe::Net< Dtype >
```

Connects [Layers](#) together into a directed acyclic graph (DAG) specified by a NetParameter.

TODO(dox): more thorough description.

### 5.67.2 Member Function Documentation

#### 5.67.2.1 Backward()

```
template<typename Dtype >
void caffe::Net< Dtype >::Backward ( )
```

The network backward should take no input and output, since it solely computes the gradient w.r.t the parameters, and the data has already been provided during the forward pass.

#### 5.67.2.2 ForwardFromTo()

```
template<typename Dtype >
Dtype caffe::Net< Dtype >::ForwardFromTo (
    int start,
    int end )
```

The From and To variants of Forward and Backward operate on the (topological) ordering by which the net is specified. For general DAG networks, note that (1) computing from one layer to another might entail extra computation on unrelated branches, and (2) computation starting in the middle may be incorrect if all of the layers of a fan-in are not included.

#### 5.67.2.3 Reshape()

```
template<typename Dtype >
void caffe::Net< Dtype >::Reshape ( )
```

Reshape all layers from bottom to top.

This is useful to propagate changes to layer sizes without running a forward pass, e.g. to compute output feature size.

#### 5.67.2.4 ShareWeights()

```
template<typename Dtype >
void caffe::Net< Dtype >::ShareWeights ( )
```

Shares weight data of owner blobs with shared blobs.

Note: this is called by [Net::Init](#), and thus should normally not be called manually.

### 5.67.3 Member Data Documentation

#### 5.67.3.1 blob\_loss\_weights\_

```
template<typename Dtype >
vector<Dtype> caffe::Net< Dtype >::blob_loss_weights_ [protected]
```

Vector of weight in the loss (or objective) function of each net blob, indexed by blob\_id.

#### 5.67.3.2 bottom\_vecs\_

```
template<typename Dtype >
vector<vector<Blob<Dtype>*> > caffe::Net< Dtype >::bottom_vecs_ [protected]
```

bottom\_vecs stores the vectors containing the input for each layer. They don't actually host the blobs (blobs\_ does), so we simply store pointers.

#### 5.67.3.3 learnable\_param\_ids\_

```
template<typename Dtype >
vector<int> caffe::Net< Dtype >::learnable_param_ids_ [protected]
```

The mapping from params\_ -> learnable\_params\_: we have learnable\_param\_ids\_.size() == params\_.size(), and learnable\_params\_[learnable\_param\_ids\_[i]] == params\_[i].get() if and only if params\_[i] is an "owner"; otherwise, params\_[i] is a sharer and learnable\_params\_[learnable\_param\_ids\_[i]] gives its owner.

The documentation for this class was generated from the following files:

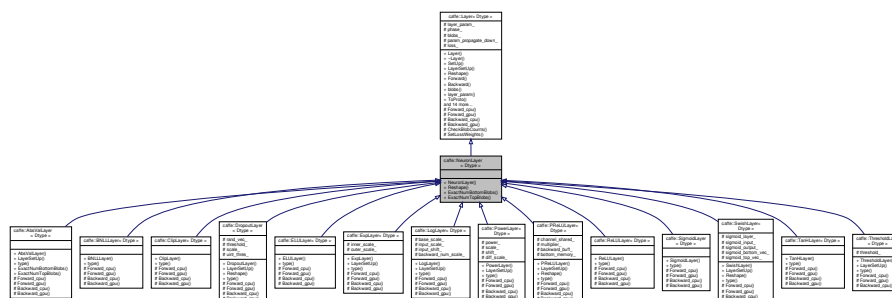
- include/caffe/net.hpp
- src/caffe/net.cpp

## 5.68 caffe::NeuronLayer< Dtype > Class Template Reference

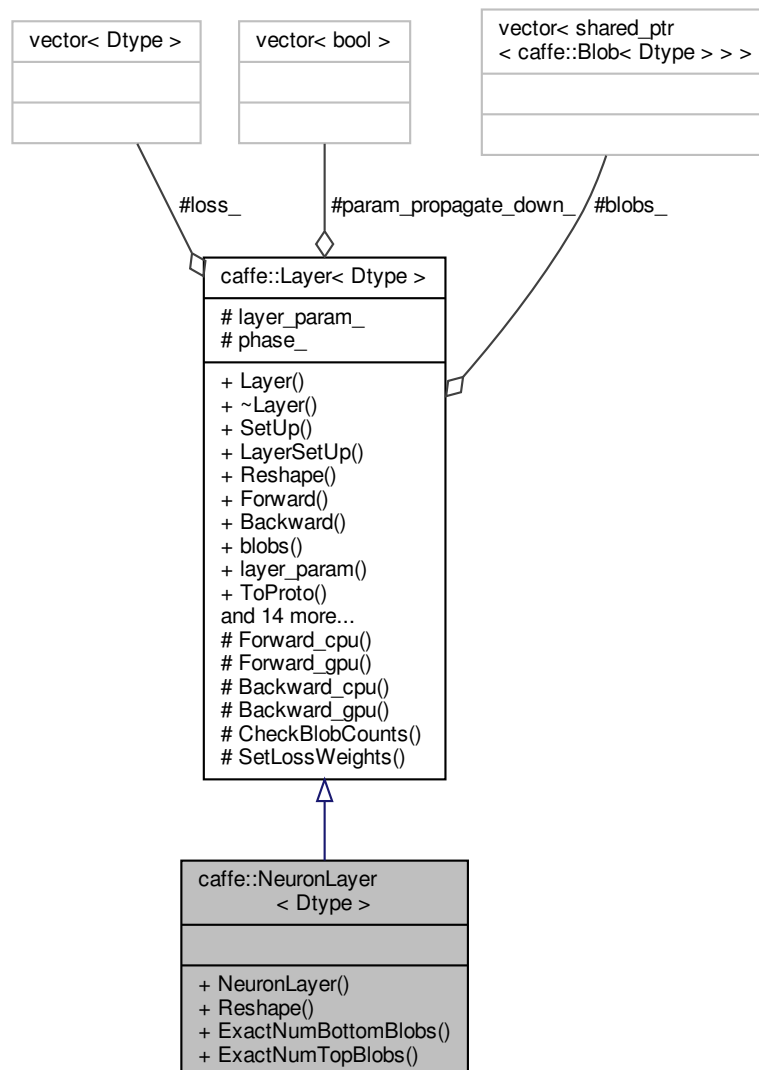
An interface for layers that take one blob as input (  $x$  ) and produce one equally-sized blob as output (  $y$  ), where each element of the output depends only on the corresponding input element.

```
#include <neuron_layer.hpp>
```

Inheritance diagram for caffe::NeuronLayer< Dtype >:



Collaboration diagram for `caffe::NeuronLayer< Dtype >`:



## Public Member Functions

- **NeuronLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*



## Additional Inherited Members

### 5.68.1 Detailed Description

```
template<typename Dtype>
class caffe::NeuronLayer< Dtype >
```

An interface for layers that take one blob as input (  $x$  ) and produce one equally-sized blob as output (  $y$  ), where each element of the output depends only on the corresponding input element.

### 5.68.2 Member Function Documentation

#### 5.68.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::NeuronLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

Reimplemented in [caffe::AbsValLayer< Dtype >](#).

#### 5.68.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::NeuronLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

Reimplemented in [caffe::AbsValLayer< Dtype >](#).

#### 5.68.2.3 Reshape()

```
template<typename Dtype >
void caffe::NeuronLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

**Parameters**

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

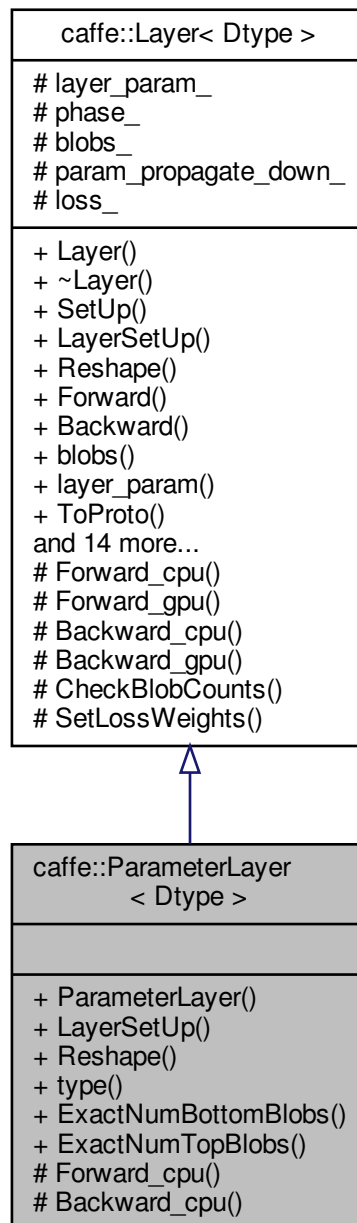
Reimplemented in [caffe::PReLULayer< Dtype >](#), [caffe::DropoutLayer< Dtype >](#), and [caffe::SwishLayer< Dtype >](#).

The documentation for this class was generated from the following files:

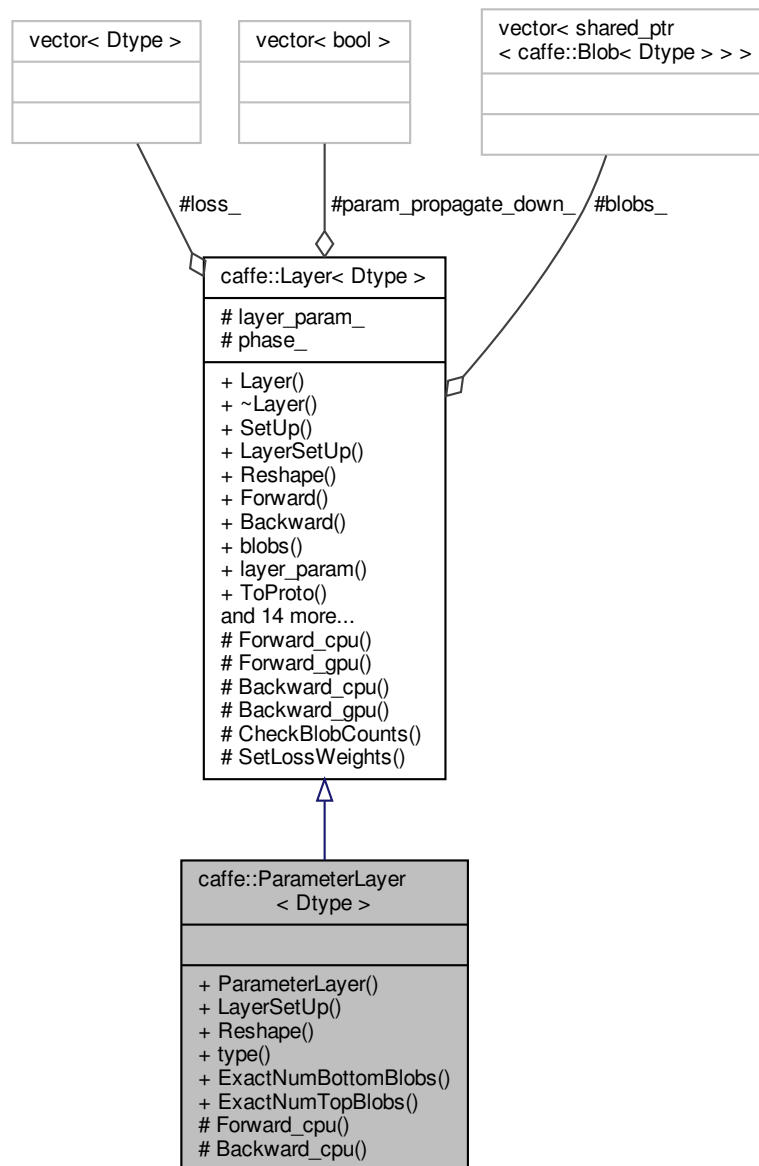
- include/caffe/layers/neuron\_layer.hpp
- src/caffe/layers/neuron\_layer.cpp

## 5.69 caffe::ParameterLayer&lt; Dtype &gt; Class Template Reference

Inheritance diagram for caffe::ParameterLayer< Dtype >:



Collaboration diagram for `caffe::ParameterLayer< Dtype >`:



## Public Member Functions

- **ParameterLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const

*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*

- virtual int `ExactNumTopBlobs` () const

*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void `Forward_cpu` (const vector< `Blob< Dtype > *` &bottom, const vector< `Blob< Dtype > *` &top)

*Using the CPU device, compute the layer output.*

- virtual void `Backward_cpu` (const vector< `Blob< Dtype > *` &top, const vector< bool > &propagate\_down, const vector< `Blob< Dtype > *` &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

## Additional Inherited Members

### 5.69.1 Member Function Documentation

#### 5.69.1.1 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::ParameterLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.69.1.2 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::ParameterLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

#### 5.69.1.3 `LayerSetUp()`

```
template<typename Dtype >
virtual void caffe::ParameterLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * & bottom,
    const vector< Blob< Dtype > * & top ) [inline], [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.69.1.4 Reshape()

```
template<typename Dtype >
virtual void caffe::ParameterLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [inline], [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following file:

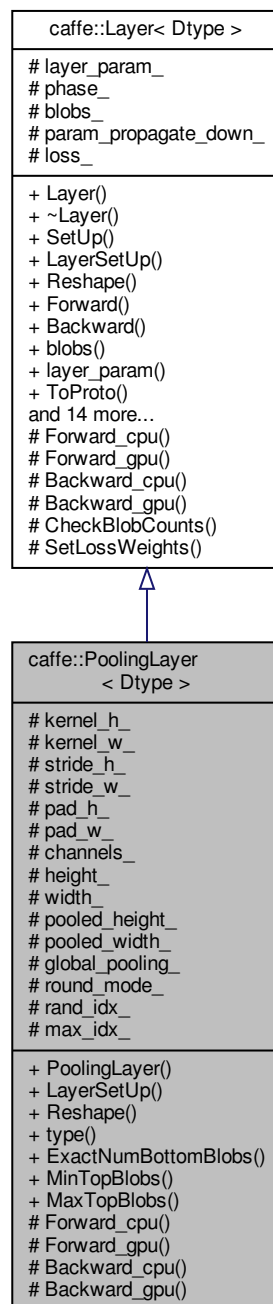
- `include/caffe/layers/parameter_layer.hpp`

## 5.70 caffe::PoolingLayer&lt; Dtype &gt; Class Template Reference

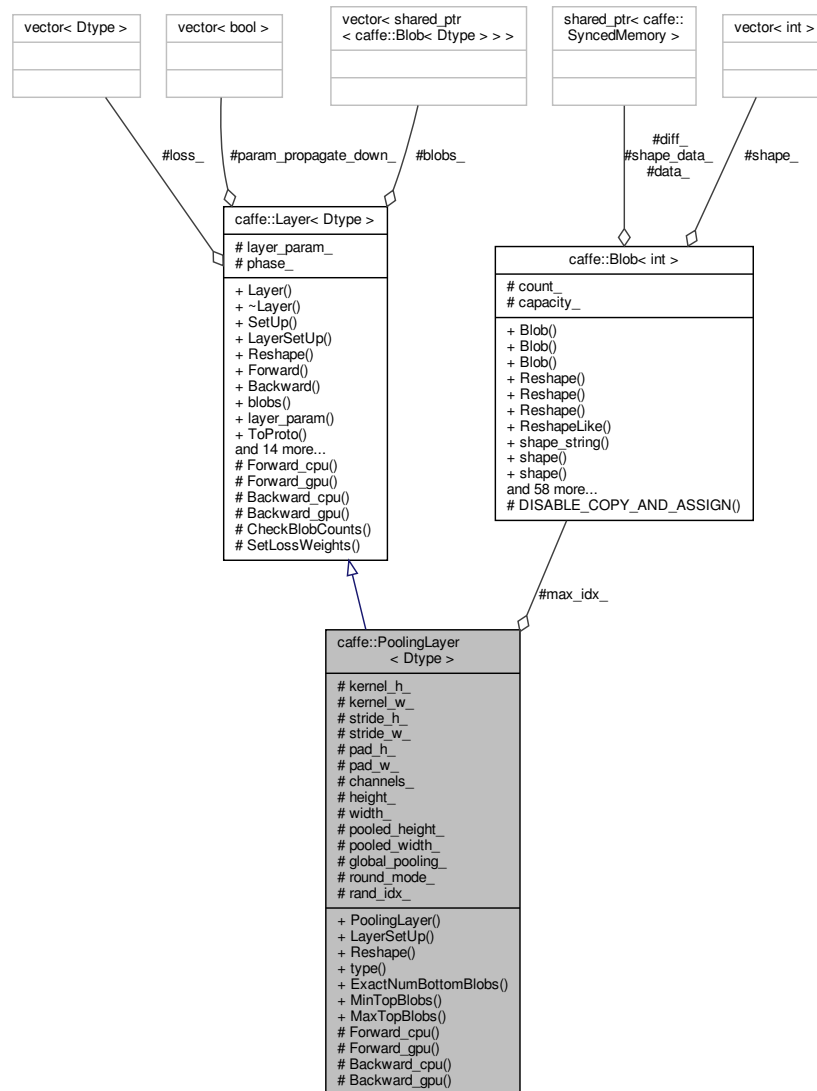
Pools the input image by taking the max, average, etc. within regions.

```
#include <pooling_layer.hpp>
```

Inheritance diagram for caffe::PoolingLayer< Dtype >:



Collaboration diagram for `caffe::PoolingLayer< Dtype >`:



## Public Member Functions

- **PoolingLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **MinTopBlobs** () const  
*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*
- virtual int **MaxTopBlobs** () const  
*Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.*



## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- int **kernel\_h\_**
- int **kernel\_w\_**
- int **stride\_h\_**
- int **stride\_w\_**
- int **pad\_h\_**
- int **pad\_w\_**
- int **channels\_**
- int **height\_**
- int **width\_**
- int **pooled\_height\_**
- int **pooled\_width\_**
- bool **global\_pooling\_**
- PoolingParameter\_RoundMode **round\_mode\_**
- [Blob](#)< Dtype > **rand\_idx\_**
- [Blob](#)< int > **max\_idx\_**

### 5.70.1 Detailed Description

```
template<typename Dtype>
class caffe::PoolingLayer< Dtype >
```

Pools the input image by taking the max, average, etc. within regions.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

### 5.70.2 Member Function Documentation

### 5.70.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::PoolingLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.70.2.2 LayerSetUp()

```
template<typename Dtype >
void caffe::PoolingLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

#### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.70.2.3 MaxTopBlobs()

```
template<typename Dtype >
virtual int caffe::PoolingLayer< Dtype >::MaxTopBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

5.70.2.4 `MinTopBlobs()`

```
template<typename Dtype >
virtual int caffe::PoolingLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.70.2.5 `Reshape()`

```
template<typename Dtype >
void caffe::PoolingLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following files:

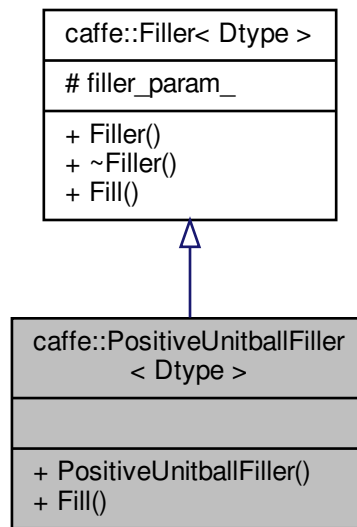
- `include/caffe/layers/pooling_layer.hpp`
- `src/caffe/layers/pooling_layer.cpp`

5.71 `caffe::PositiveUnitballFiller< Dtype >` Class Template Reference

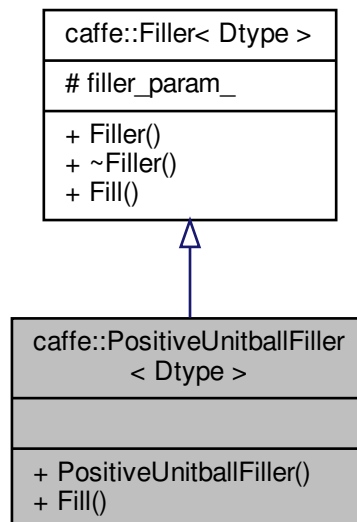
Fills a `Blob` with values  $x \in [0, 1]$  such that  $\forall i \sum_j x_{ij} = 1$ .

```
#include <filler.hpp>
```

Inheritance diagram for `caffe::PositiveUnitballFiller< Dtype >`:



Collaboration diagram for `caffe::PositiveUnitballFiller< Dtype >`:



## Public Member Functions

- **PositiveUnitballFiller** (const FillerParameter &param)
- virtual void **Fill** ([Blob](#)< Dtype > \*blob)

## Additional Inherited Members

### 5.71.1 Detailed Description

```
template<typename Dtype>
class caffe::PositiveUnitballFiller< Dtype >
```

Fills a [Blob](#) with values  $x \in [0, 1]$  such that  $\forall i \sum_j x_{ij} = 1$ .

The documentation for this class was generated from the following file:

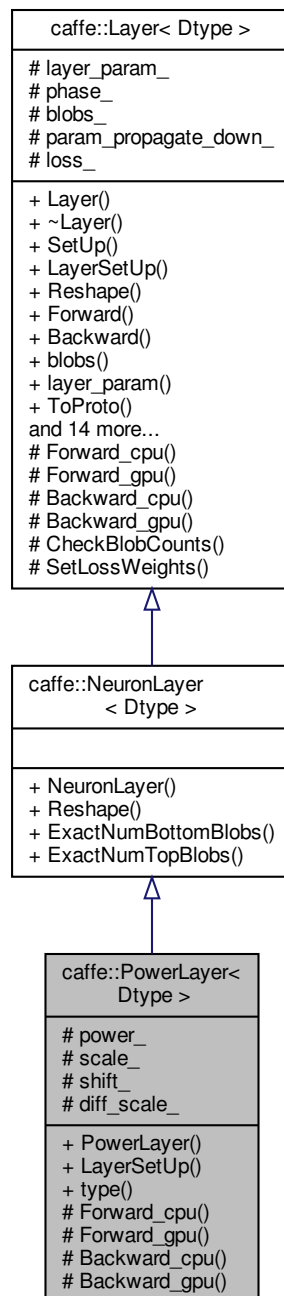
- include/caffe/filler.hpp

## 5.72 caffe::PowerLayer< Dtype > Class Template Reference

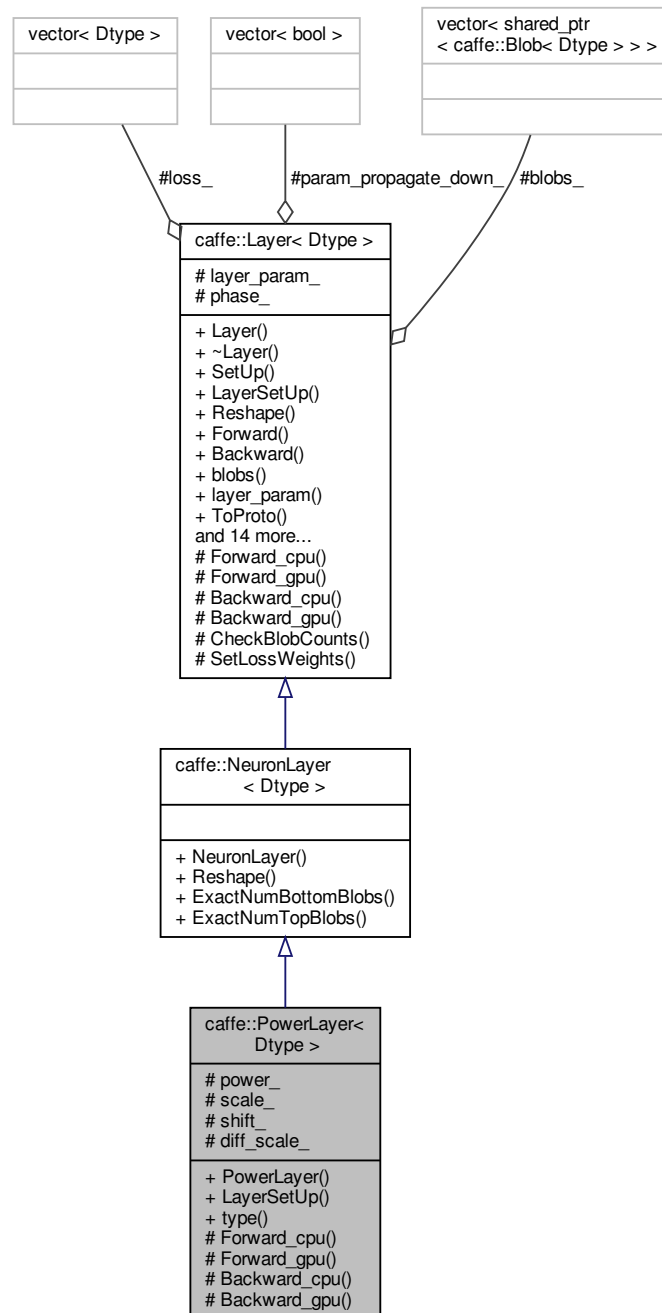
Computes  $y = (\alpha x + \beta)^\gamma$ , as specified by the scale  $\alpha$ , shift  $\beta$ , and power  $\gamma$ .

```
#include <power_layer.hpp>
```

Inheritance diagram for `caffe::PowerLayer< Dtype >`:



Collaboration diagram for caffe::PowerLayer< Dtype >:



## Public Member Functions

- `PowerLayer` (const LayerParameter &param)
- virtual void `LayerSetUp` (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual const char \* `type` () const  
*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Computes the error gradient w.r.t. the power inputs.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- Dtype [power\\_](#)  
 $\gamma$  from `layer_param_.power_param()`
- Dtype [scale\\_](#)  
 $\alpha$  from `layer_param_.power_param()`
- Dtype [shift\\_](#)  
 $\beta$  from `layer_param_.power_param()`
- Dtype [diff\\_scale\\_](#)  
*Result of  $\alpha\gamma$ .*

### 5.72.1 Detailed Description

```
template<typename Dtype>
class caffe::PowerLayer< Dtype >
```

Computes  $y = (\alpha x + \beta)^\gamma$ , as specified by the scale  $\alpha$ , shift  $\beta$ , and power  $\gamma$ .

### 5.72.2 Constructor & Destructor Documentation

#### 5.72.2.1 PowerLayer()

```
template<typename Dtype >
caffe::PowerLayer< Dtype >::PowerLayer (
    const LayerParameter & param ) [inline], [explicit]
```



## Parameters

<i>param</i>	provides PowerParameter power_param, with <a href="#">PowerLayer</a> options: <ul style="list-style-type: none"> <li>• scale (<b>optional</b>, default 1) the scale <math>\alpha</math></li> <li>• shift (<b>optional</b>, default 0) the shift <math>\beta</math></li> <li>• power (<b>optional</b>, default 1) the power <math>\gamma</math></li> </ul>
--------------	---

## 5.72.3 Member Function Documentation

## 5.72.3.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::PowerLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > * > & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > * > & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the power inputs.

## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs <ol style="list-style-type: none"> <li>1. <math>(N \times C \times H \times W)</math> containing error gradients <math>\frac{\partial E}{\partial y}</math> with respect to computed outputs <math>y</math></li> </ol>
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li>1. <math>(N \times C \times H \times W)</math> the inputs <math>x</math>; Backward fills their diff with gradients <math>\frac{\partial E}{\partial x} = \frac{\partial E}{\partial y} \alpha \gamma (\alpha x + \beta)^{\gamma-1} = \frac{\partial E}{\partial y} \frac{\alpha \gamma y}{\alpha x + \beta}</math> if propagate_down[0]</li> </ol>

Implements [caffe::Layer< Dtype >](#).

## 5.72.3.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::PowerLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = (\alpha x + \beta)^\gamma$

Implements [caffe::Layer< Dtype >](#).

## 5.72.3.3 LayerSetUp()

```
template<typename Dtype >
void caffe::PowerLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > \*> & bottom,
    const vector< Blob< Dtype > \*> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

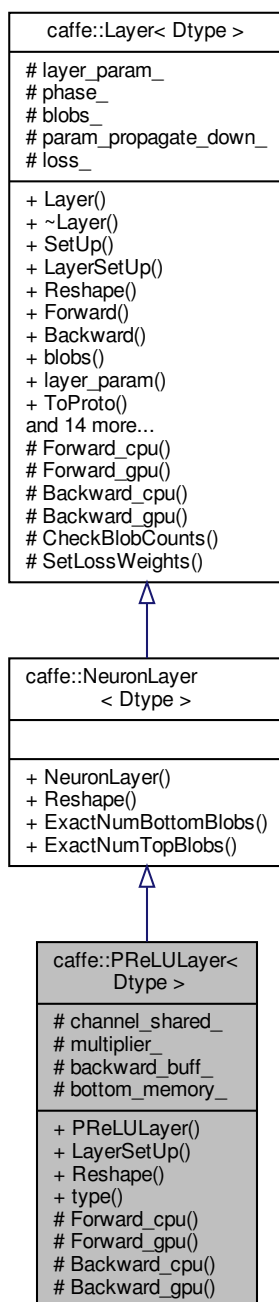
- include/caffe/layers/power\_layer.hpp
- src/caffe/layers/power\_layer.cpp

5.73 [caffe::PReLULayer< Dtype >](#) Class Template Reference

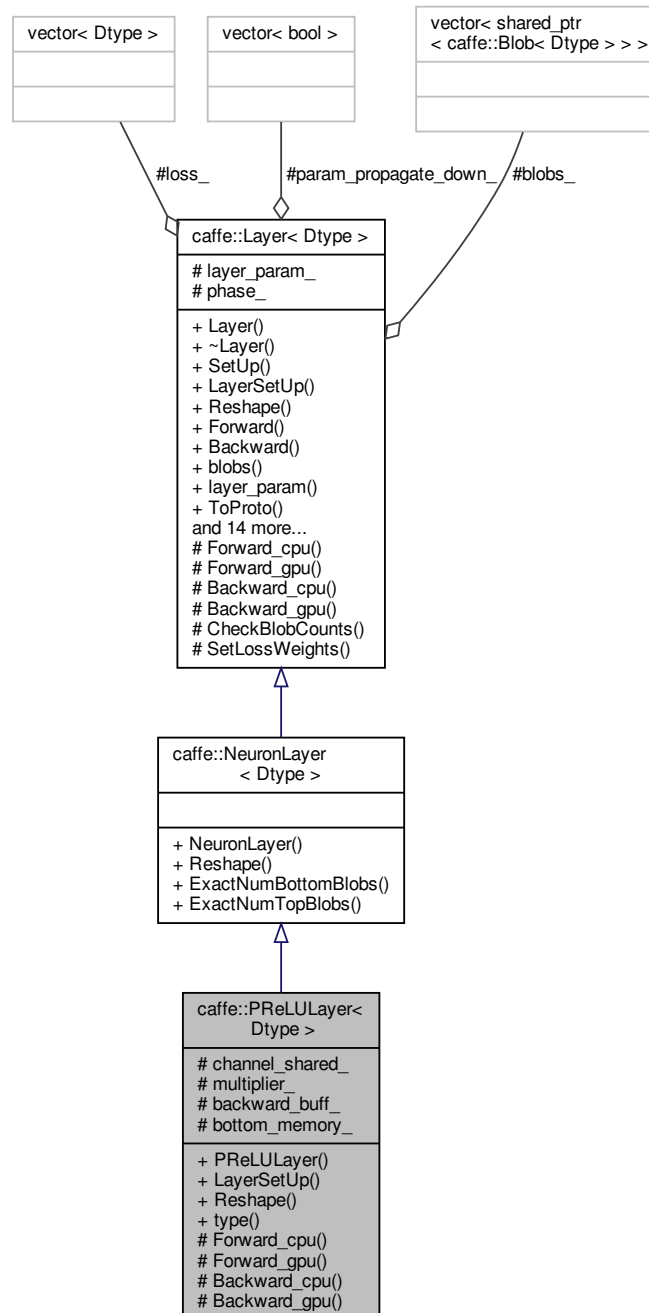
Parameterized Rectified Linear Unit non-linearity  $y_i = \max(0, x_i) + a_i \min(0, x_i)$ . The differences from [ReLULayer](#) are 1) negative slopes are learnable though backprop and 2) negative slopes can vary across channels. The number of axes of input blob should be greater than or equal to 2. The 1st axis (0-based) is seen as channels.

```
#include <prelu_layer.hpp>
```

Inheritance diagram for caffe::PReLULayer< Dtype >:



Collaboration diagram for `caffe::PReLULayer< Dtype >`:



## Public Member Functions

- `PReLULayer` (const LayerParameter &param)
- virtual void `LayerSetUp` (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as `Reshape`.
- virtual void `Reshape` (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

- virtual const char \* [type](#) () const  
*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Computes the error gradient w.r.t. the PReLU inputs.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- bool **channel\_shared\_**
- [Blob](#)< Dtype > **multiplier\_**
- [Blob](#)< Dtype > **backward\_buff\_**
- [Blob](#)< Dtype > **bottom\_memory\_**

### 5.73.1 Detailed Description

```
template<typename Dtype>
class caffe::PReLULayer< Dtype >
```

Parameterized Rectified Linear Unit non-linearity  $y_i = \max(0, x_i) + a_i \min(0, x_i)$ . The differences from [ReLU↵Layer](#) are 1) negative slopes are learnable though backprop and 2) negative slopes can vary across channels. The number of axes of input blob should be greater than or equal to 2. The 1st axis (0-based) is seen as channels.

### 5.73.2 Constructor & Destructor Documentation

#### 5.73.2.1 PReLULayer()

```
template<typename Dtype >
caffe::PReLULayer< Dtype >::PReLULayer (
    const LayerParameter & param ) [inline], [explicit]
```

## Parameters

<i>param</i>	provides PReLUParameter prelu_param, with <a href="#">PReLU</a> options: <ul style="list-style-type: none"> <li>• filler (<b>optional</b>, FillerParameter, default {'type': constant 'value':0.25}).</li> <li>• channel_shared (<b>optional</b>, default false). negative slopes are shared across channels.</li> </ul>
--------------	--

## 5.73.3 Member Function Documentation

## 5.73.3.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::PReLULayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the PReLU inputs.

## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times \dots)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times \dots)$ the inputs $x$ ; For each channel $i$ , backward fills their diff with gradients $\frac{\partial E}{\partial x_i} = \begin{cases} a_i \frac{\partial E}{\partial y_i} & \text{if } x_i \leq 0 \\ \frac{\partial E}{\partial y_i} & \text{if } x_i > 0 \end{cases} \quad \text{. If param\_propagate\_down[0] is true, it fills the diff}$ with gradients $\frac{\partial E}{\partial a_i} = \begin{cases} \sum_{x_i} x_i \frac{\partial E}{\partial y_i} & \text{if } x_i \leq 0 \\ 0 & \text{if } x_i > 0 \end{cases}$ .

Implements [caffe::Layer< Dtype >](#).

## 5.73.3.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::PReLULayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times \dots)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times \dots)$ the computed outputs for each channel $i$ $y_i = \max(0, x_i) + a_i \min(0, x_i)$ .

Implements [caffe::Layer< Dtype >](#).

## 5.73.3.3 LayerSetUp()

```
template<typename Dtype >
void caffe::PReLULayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.73.3.4 Reshape()

```
template<typename Dtype >
void caffe::PReLULayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Reimplemented from [caffe::NeuronLayer< Dtype >](#).

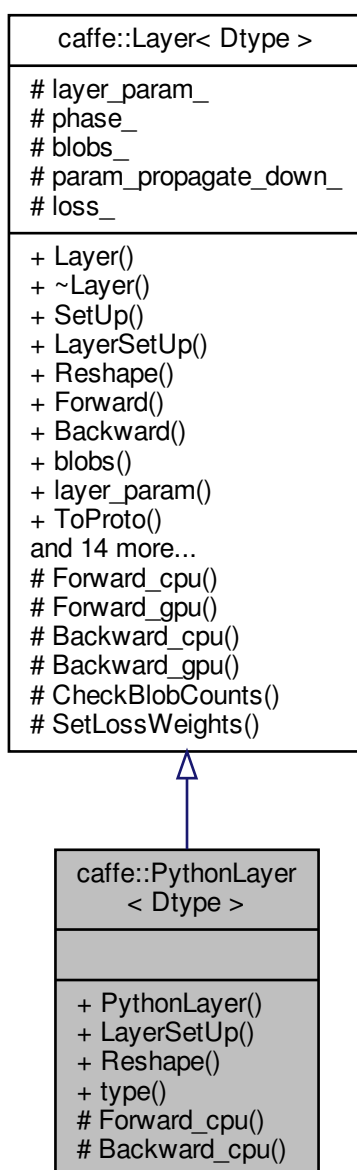
The documentation for this class was generated from the following files:

- `include/caffe/layers/prelu_layer.hpp`
- `src/caffe/layers/prelu_layer.cpp`

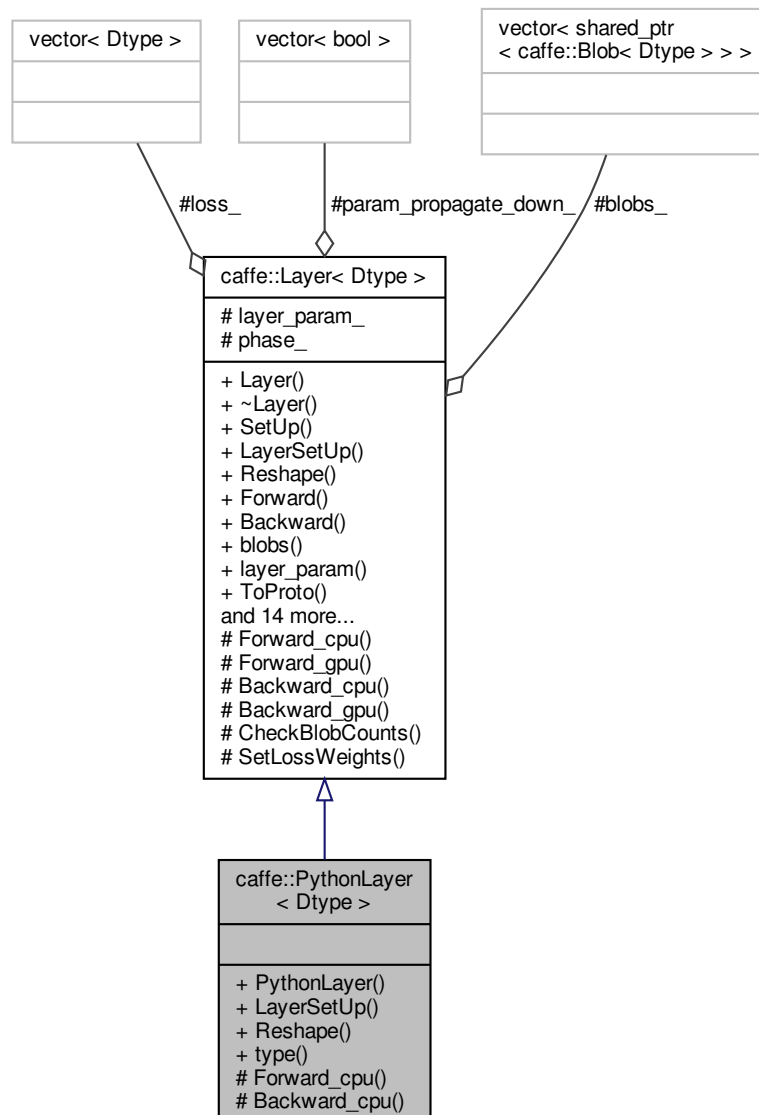


## 5.74 caffe::PythonLayer< Dtype > Class Template Reference

Inheritance diagram for caffe::PythonLayer< Dtype >:



Collaboration diagram for `caffe::PythonLayer< Dtype >`:



## Public Member Functions

- **PythonLayer** (`PyObject *self, const LayerParameter &param`)
- virtual void **LayerSetUp** (`const vector< Blob< Dtype > * > &bottom, const vector< Blob< Dtype > * > &top`)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (`const vector< Blob< Dtype > * > &bottom, const vector< Blob< Dtype > * > &top`)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the CPU device, compute the layer output.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

## Additional Inherited Members

### 5.74.1 Member Function Documentation

#### 5.74.1.1 LayerSetUp()

```
template<typename Dtype >
virtual void caffe::PythonLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [inline], [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

##### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.74.1.2 Reshape()

```
template<typename Dtype >
virtual void caffe::PythonLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [inline], [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

##### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following file:

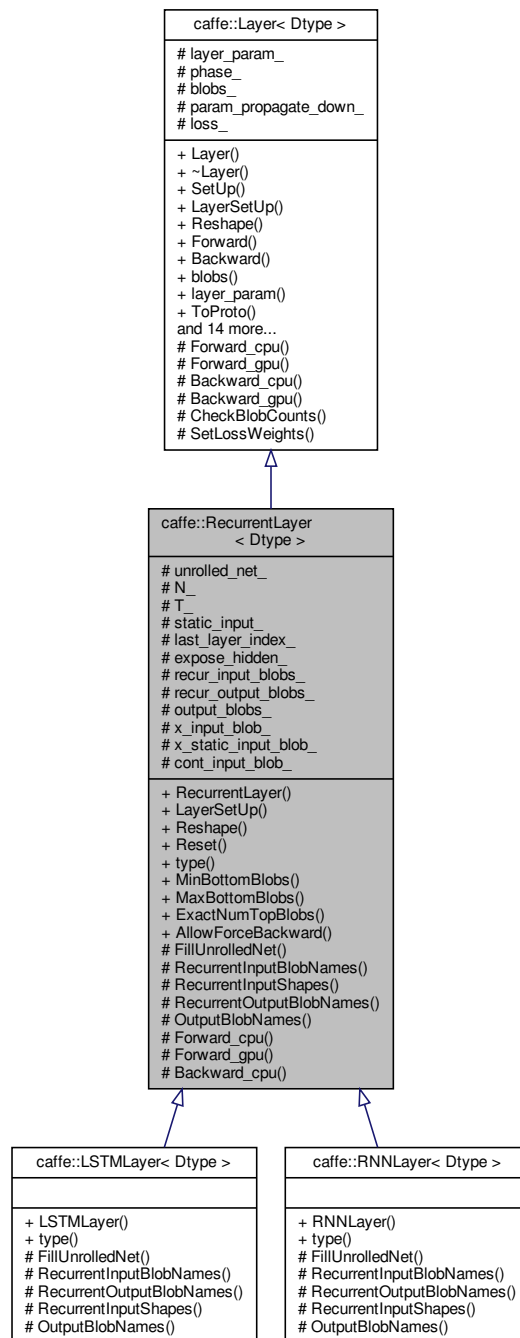
- `include/caffe/layers/python_layer.hpp`

## 5.75 `caffe::RecurrentLayer< Dtype >` Class Template Reference

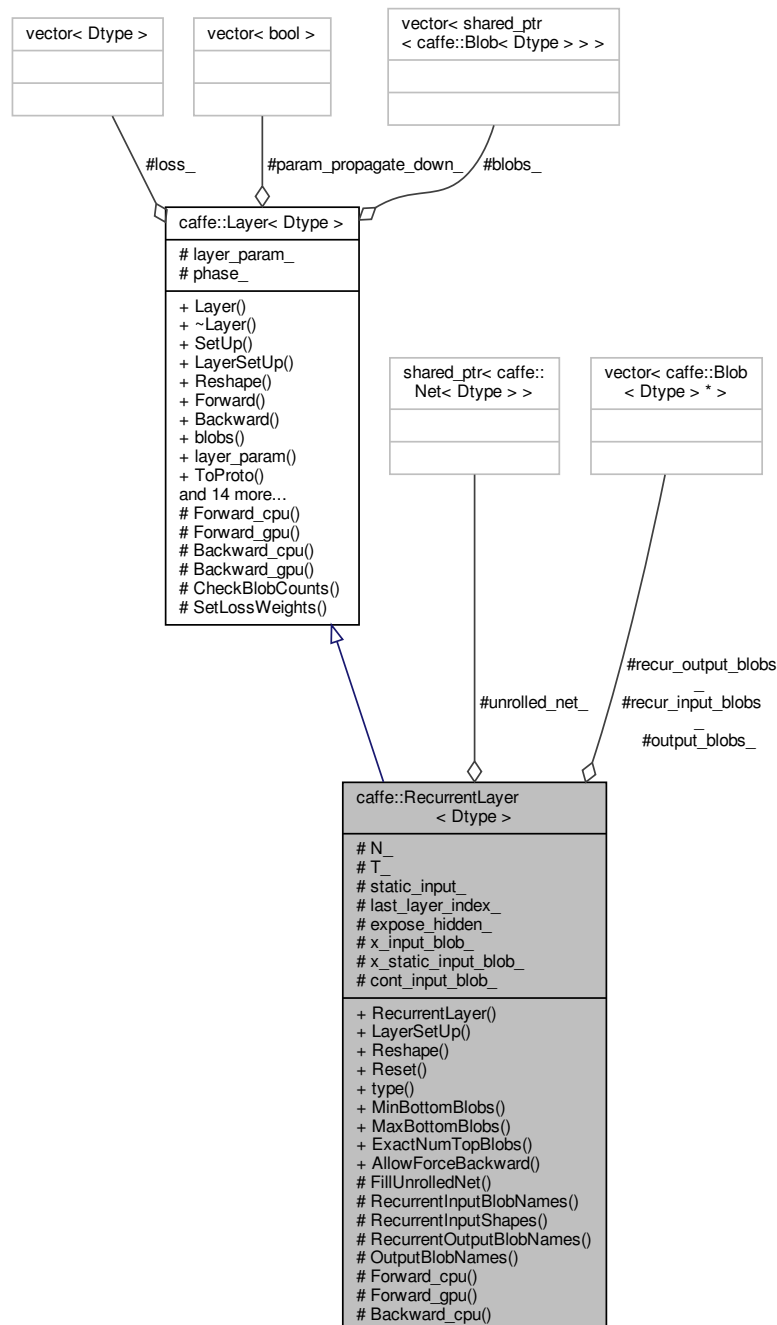
An abstract class for implementing recurrent behavior inside of an unrolled network. This [Layer](#) type cannot be instantiated – instead, you should use one of its implementations which defines the recurrent architecture, such as [RNNLayer](#) or [LSTMLayer](#).

```
#include <recurrent_layer.hpp>
```

Inheritance diagram for caffe::RecurrentLayer< Dtype >:



Collaboration diagram for `caffe::RecurrentLayer< Dtype >`:



## Public Member Functions

- **RecurrentLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as `Reshape`.
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

- virtual void **Reset** ()
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **MinBottomBlobs** () const  
*Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.*
- virtual int **MaxBottomBlobs** () const  
*Returns the maximum number of bottom blobs required by the layer, or -1 if no maximum number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*
- virtual bool **AllowForceBackward** (const int bottom\_index) const  
*Return whether to allow force\_backward for a given bottom blob index.*

## Protected Member Functions

- virtual void **FillUnrolledNet** (NetParameter \*net\_param) const =0  
*Fills net\_param with the recurrent network architecture. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void **RecurrentInputBlobNames** (vector< string > \*names) const =0  
*Fills names with the names of the 0th timestep recurrent input Blob&s. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void **RecurrentInputShapes** (vector< BlobShape > \*shapes) const =0  
*Fills shapes with the shapes of the recurrent input Blob&s. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void **RecurrentOutputBlobNames** (vector< string > \*names) const =0  
*Fills names with the names of the Tth timestep recurrent output Blob&s. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void **OutputBlobNames** (vector< string > \*names) const =0  
*Fills names with the names of the output blobs, concatenated across all timesteps. Should return a name for each top Blob. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void **Forward\_cpu** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)
- virtual void **Forward\_gpu** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void **Backward\_cpu** (const vector< Blob< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< Blob< Dtype > \* > &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

## Protected Attributes

- shared\_ptr< Net< Dtype > > **unrolled\_net\_**  
*A [Net](#) to implement the Recurrent functionality.*
- int **N\_**  
*The number of independent streams to process simultaneously.*
- int **T\_**  
*The number of timesteps in the layer's input, and the number of timesteps over which to backpropagate through time.*
- bool **static\_input\_**  
*Whether the layer has a "static" input copied across all timesteps.*
- int **last\_layer\_index\_**  
*The last layer to run in the network. (Any later layers are losses added to force the recurrent net to do backprop.)*
- bool **expose\_hidden\_**

*Whether the layer's hidden state at the first and last timesteps are layer inputs and outputs, respectively.*

- `vector< Blob< Dtype > *> recur_input_blobs_`
- `vector< Blob< Dtype > *> recur_output_blobs_`
- `vector< Blob< Dtype > *> output_blobs_`
- `Blob< Dtype > * x_input_blob_`
- `Blob< Dtype > * x_static_input_blob_`
- `Blob< Dtype > * cont_input_blob_`

### 5.75.1 Detailed Description

```
template<typename Dtype>
class caffe::RecurrentLayer< Dtype >
```

An abstract class for implementing recurrent behavior inside of an unrolled network. This [Layer](#) type cannot be instantiated – instead, you should use one of its implementations which defines the recurrent architecture, such as [RNNLayer](#) or [LSTMLayer](#).

### 5.75.2 Member Function Documentation

#### 5.75.2.1 AllowForceBackward()

```
template<typename Dtype >
virtual bool caffe::RecurrentLayer< Dtype >::AllowForceBackward (
    const int bottom_index ) const [inline], [virtual]
```

Return whether to allow `force_backward` for a given bottom blob index.

If `AllowForceBackward(i) == false`, we will ignore the `force_backward` setting and backpropagate to blob `i` only if it needs gradient information (as is done when `force_backward == false`).

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.75.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::RecurrentLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.75.2.3 Forward\_cpu()

```
template<typename Dtype >
void caffe::RecurrentLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```



## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2-3)
---------------	--

1.  $(T \times N \times \dots)$  the time-varying input  $x$ . After the first two axes, whose dimensions must correspond to the number of timesteps  $T$  and the number of independent streams  $N$ , respectively, its dimensions may be arbitrary. Note that the ordering of dimensions –  $(T \times N \times \dots)$ , rather than  $(N \times T \times \dots)$  – means that the  $N$  independent input streams must be "interleaved".
2.  $(T \times N)$  the sequence continuation indicators  $\delta$ . These inputs should be binary (0 or 1) indicators, where  $\delta_{t,n} = 0$  means that timestep  $t$  of stream  $n$  is the beginning of a new sequence, and hence the previous hidden state  $h_{t-1}$  is multiplied by  $\delta_t = 0$  and has no effect on the cell's output at timestep  $t$ , and a value of  $\delta_{t,n} = 1$  means that timestep  $t$  of stream  $n$  is a continuation from the previous timestep  $t - 1$ , and the previous hidden state  $h_{t-1}$  affects the updated hidden state and output.
3.  $(N \times \dots)$  (optional) the static (non-time-varying) input  $x_{static}$ . After the first axis, whose dimension must be the number of independent streams, its dimensions may be arbitrary. This is mathematically equivalent to using a time-varying input of  $x'_t = [x_t; x_{static}]$  – i.e., tiling the static input across the  $T$  timesteps and concatenating with the time-varying input. Note that if this input is used, all timesteps in a single batch within a particular one of the  $N$  streams must share the same static input, even if the sequence continuation indicators suggest that difference sequences are ending and beginning within a single batch. This may require padding and/or truncation for uniform length.

## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1)  <ol style="list-style-type: none"> <li>1. <math>(T \times N \times D)</math> the time-varying output <math>y</math>, where <math>D</math> is <code>recurrent_param.num_output()</code>. Refer to documentation for particular <a href="#">RecurrentLayer</a> implementations (such as <a href="#">RNNLayer</a> and <a href="#">LSTMLayer</a>) for the definition of <math>y</math>.</li> </ol>
------------	---

Implements [caffe::Layer< Dtype >](#).

## 5.75.2.4 LayerSetUp()

```
template<typename Dtype >
void caffe::RecurrentLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`,

which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.75.2.5 MaxBottomBlobs()

```
template<typename Dtype >
virtual int caffe::RecurrentLayer< Dtype >::MaxBottomBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of bottom blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.75.2.6 MinBottomBlobs()

```
template<typename Dtype >
virtual int caffe::RecurrentLayer< Dtype >::MinBottomBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.75.2.7 Reshape()

```
template<typename Dtype >
void caffe::RecurrentLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > \*> & bottom,
    const vector< Blob< Dtype > \*> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

##### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following files:

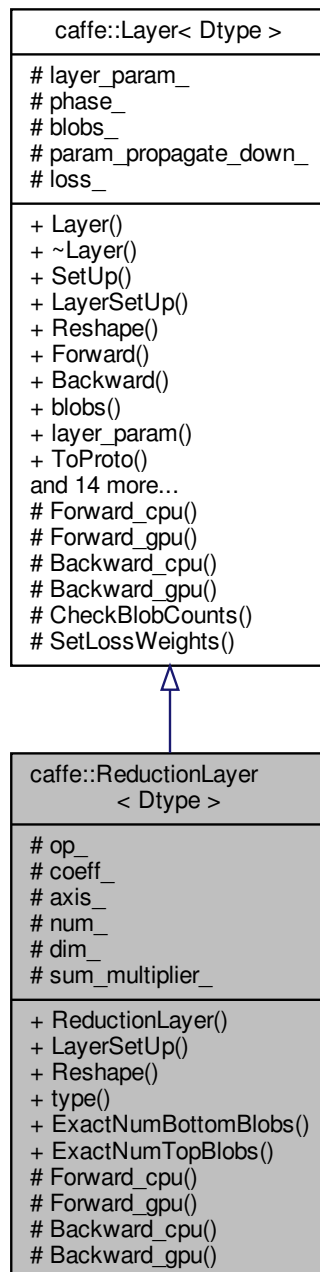
- `include/caffe/layers/lstm_layer.hpp`
- `include/caffe/layers/recurrent_layer.hpp`
- `src/caffe/layers/recurrent_layer.cpp`

## 5.76 `caffe::ReductionLayer< Dtype >` Class Template Reference

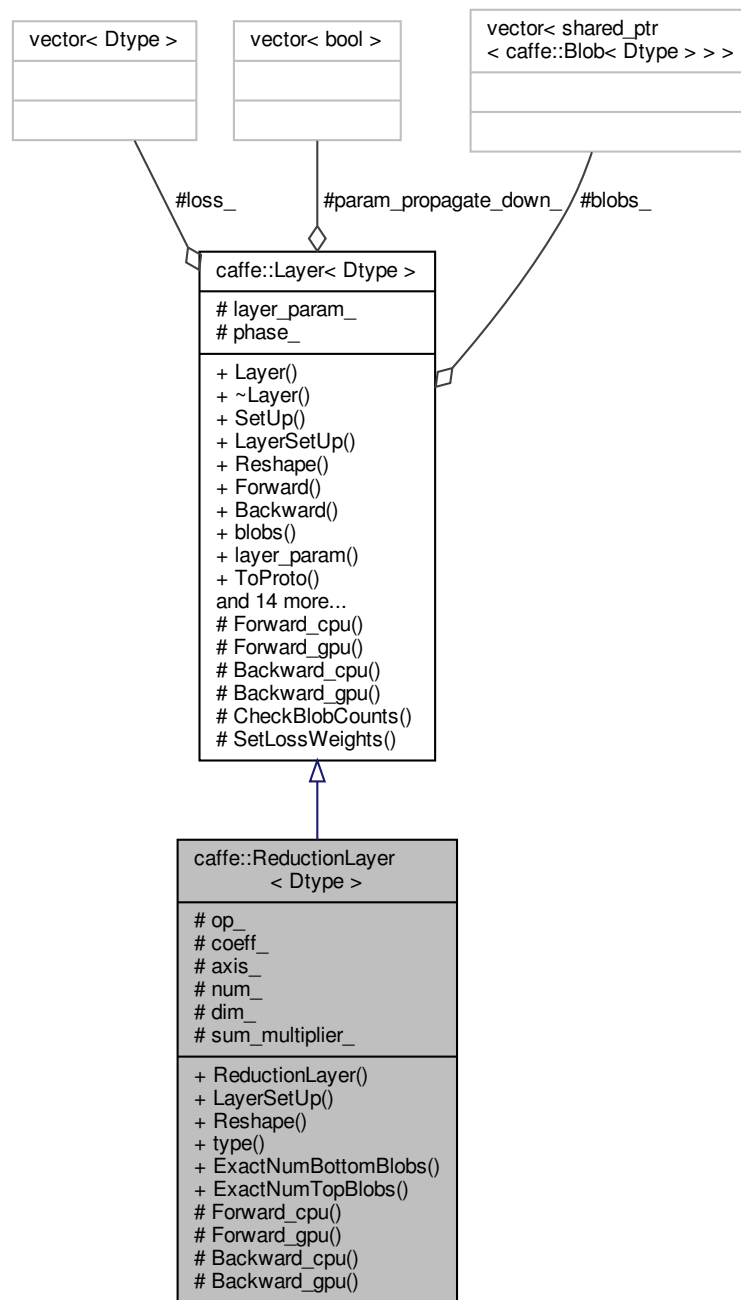
Compute "reductions" – operations that return a scalar output `Blob` for an input `Blob` of arbitrary size, such as the sum, absolute sum, and sum of squares.

```
#include <reduction_layer.hpp>
```

Inheritance diagram for `caffe::ReductionLayer< Dtype >`:



Collaboration diagram for caffe::ReductionLayer< Dtype >:



## Public Member Functions

- **ReductionLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*

- virtual const char \* [type](#) () const  
*Returns the layer type.*
- virtual int [ExactNumBottomBlobs](#) () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int [ExactNumTopBlobs](#) () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- ReductionParameter\_ReductionOp [op\\_](#)  
*the reduction operation performed by the layer*
- Dtype [coeff\\_](#)  
*a scalar coefficient applied to all outputs*
- int [axis\\_](#)  
*the index of the first input axis to reduce*
- int [num\\_](#)  
*the number of reductions performed*
- int [dim\\_](#)  
*the input size of each reduction*
- [Blob](#)< Dtype > [sum\\_multiplier\\_](#)  
*a helper [Blob](#) used for summation (op\_ == SUM)*

### 5.76.1 Detailed Description

```
template<typename Dtype>
class caffe::ReductionLayer< Dtype >
```

Compute "reductions" – operations that return a scalar output [Blob](#) for an input [Blob](#) of arbitrary size, such as the sum, absolute sum, and sum of squares.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

## 5.76.2 Member Function Documentation

### 5.76.2.1 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::ReductionLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

### 5.76.2.2 `ExactNumTopBlobs()`

```
template<typename Dtype >
virtual int caffe::ReductionLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from `caffe::Layer< Dtype >`.

### 5.76.2.3 `LayerSetUp()`

```
template<typename Dtype >
void caffe::ReductionLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

#### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.76.2.4 Reshape()

```
template<typename Dtype >
void caffe::ReductionLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

##### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

- include/caffe/layers/reduction\_layer.hpp
- src/caffe/layers/reduction\_layer.cpp

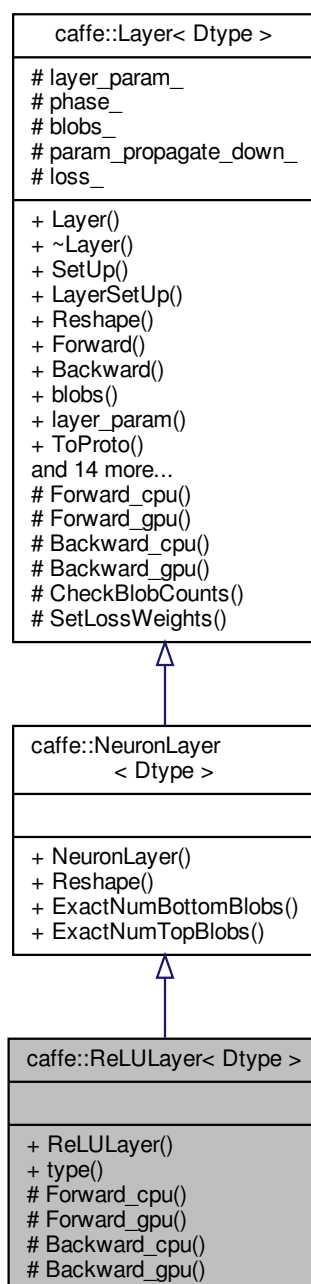
## 5.77 caffe::ReLULayer< Dtype > Class Template Reference

Rectified Linear Unit non-linearity  $y = \max(0, x)$ . The simple max is fast to compute, and the function does not saturate.

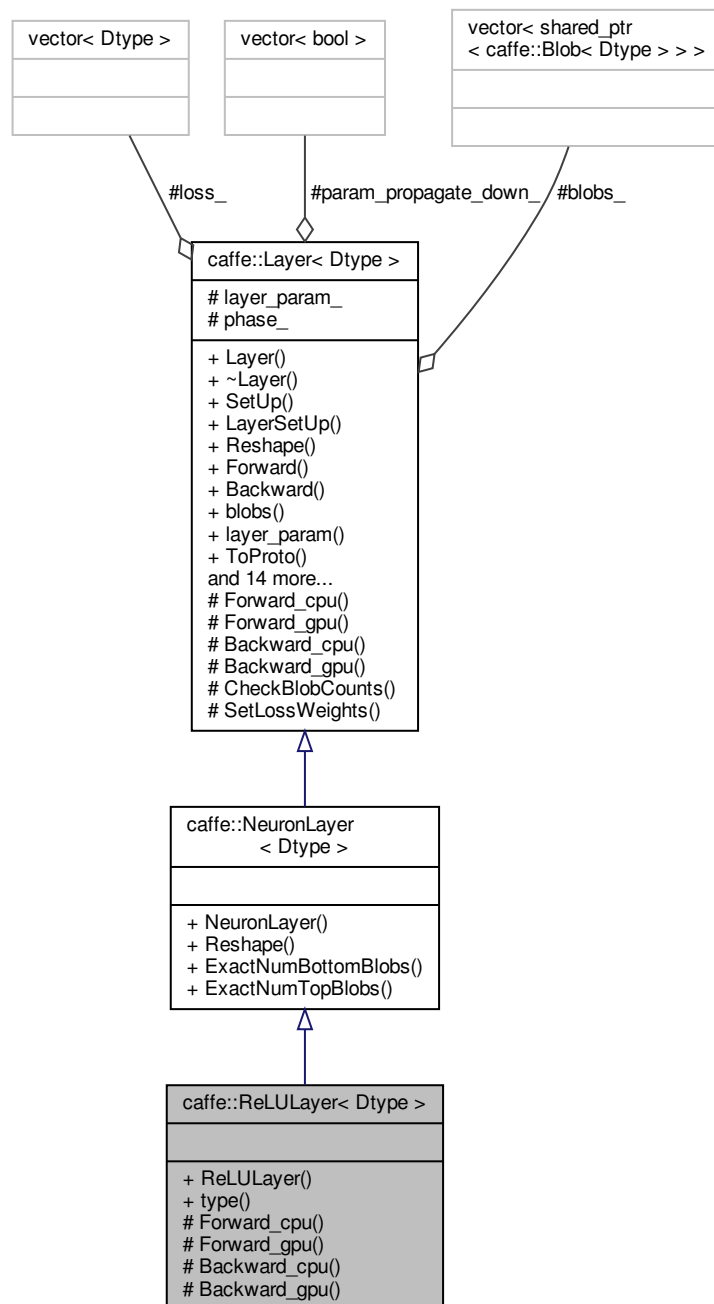
```
#include <relu_layer.hpp>
```



Inheritance diagram for caffe::ReLULayer< Dtype >:



Collaboration diagram for `caffe::ReLULayer< Dtype >`:



## Public Member Functions

- [ReLULayer](#) (const LayerParameter &param)
- virtual const char \* [type](#) () const

*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the error gradient w.r.t. the ReLU inputs.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Additional Inherited Members

### 5.77.1 Detailed Description

```
template<typename Dtype>
class caffe::ReLULayer< Dtype >
```

Rectified Linear Unit non-linearity  $y = \max(0, x)$ . The simple max is fast to compute, and the function does not saturate.

### 5.77.2 Constructor & Destructor Documentation

#### 5.77.2.1 ReLULayer()

```
template<typename Dtype >
caffe::ReLULayer< Dtype >::ReLULayer (
    const LayerParameter & param ) [inline], [explicit]
```

#### Parameters

<i>param</i>	provides ReLUParameter relu_param, with <a href="#">ReLULayer</a> options: <ul style="list-style-type: none"> <li>• <b>negative_slope</b> (<b>optional</b>, default 0). the value <math>\nu</math> by which negative values are multiplied.</li> </ul>
--------------	--

### 5.77.3 Member Function Documentation

## 5.77.3.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::ReLULayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the ReLU inputs.

## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times H \times W)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$ ; Backward fills their diff with gradients $\frac{\partial E}{\partial x} = \begin{cases} 0 & \text{if } x \leq 0 \\ \frac{\partial E}{\partial y} & \text{if } x > 0 \end{cases}$ if propagate_down[0], by default. If a non-zero negative_slope $\nu$ is provided, the computed gradients are $\frac{\partial E}{\partial x} = \begin{cases} \nu \frac{\partial E}{\partial y} & \text{if } x \leq 0 \\ \frac{\partial E}{\partial y} & \text{if } x > 0 \end{cases}.$

Implements [caffe::Layer< Dtype >](#).

## 5.77.3.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::ReLULayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = \max(0, x)$ by default. If a non-zero negative_slope $\nu$ is provided, the computed outputs are $y = \max(0, x) + \nu \min(0, x)$ .

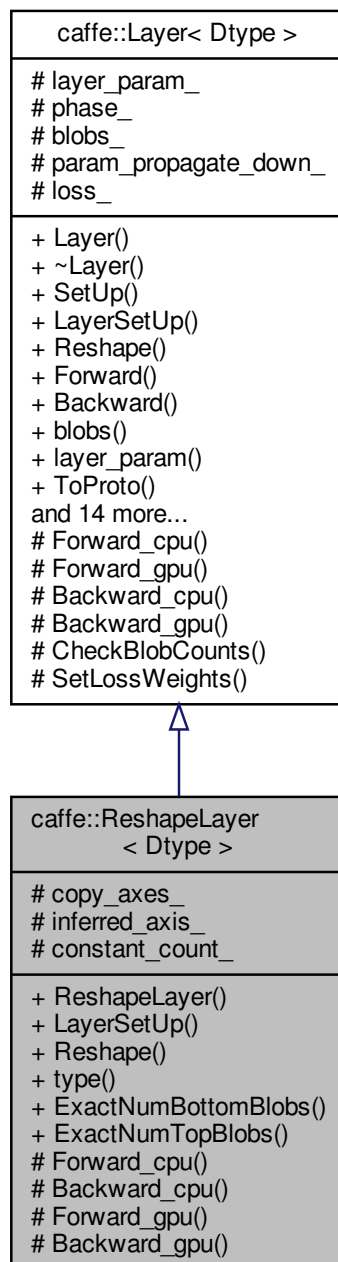
Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

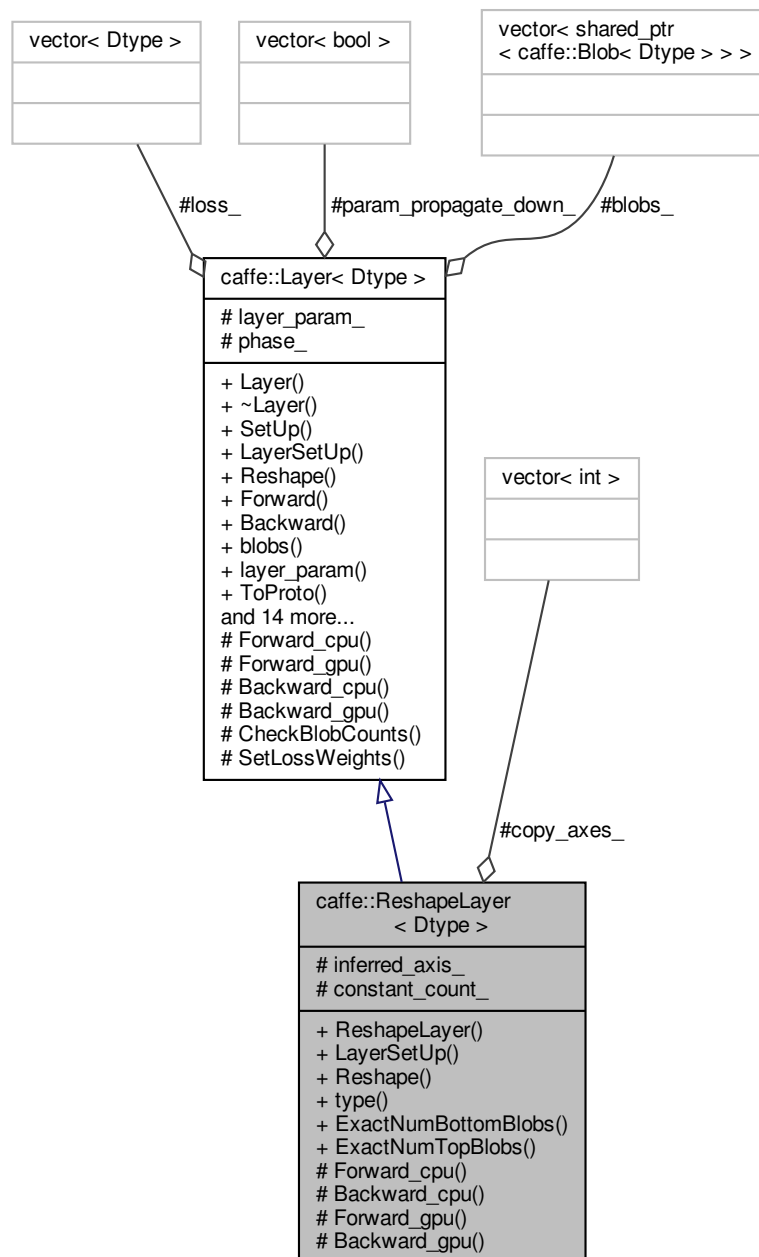
- include/caffe/layers/relu\_layer.hpp
- src/caffe/layers/relu\_layer.cpp

## 5.78 caffe::ReshapeLayer&lt; Dtype &gt; Class Template Reference

Inheritance diagram for caffe::ReshapeLayer< Dtype >:



Collaboration diagram for `caffe::ReshapeLayer< Dtype >`:



## Public Member Functions

- **ReshapeLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const

*Returns the layer type.*

- virtual int `ExactNumBottomBlobs` () const

*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*

- virtual int `ExactNumTopBlobs` () const

*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void `Forward_cpu` (const vector< `Blob< Dtype > *` &bottom, const vector< `Blob< Dtype > *` &top)

*Using the CPU device, compute the layer output.*

- virtual void `Backward_cpu` (const vector< `Blob< Dtype > *` &top, const vector< bool > &propagate\_down, const vector< `Blob< Dtype > *` &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

- virtual void `Forward_gpu` (const vector< `Blob< Dtype > *` &bottom, const vector< `Blob< Dtype > *` &top)

*Using the GPU device, compute the layer output. Fall back to `Forward_cpu()` if unavailable.*

- virtual void `Backward_gpu` (const vector< `Blob< Dtype > *` &top, const vector< bool > &propagate\_down, const vector< `Blob< Dtype > *` &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to `Backward_cpu()` if unavailable.*

## Protected Attributes

- vector< int > `copy_axes_`  
*vector of axes indices whose dimensions we'll copy from the bottom*
- int `inferred_axis_`  
*the index of the axis whose dimension we infer, or -1 if none*
- int `constant_count_`  
*the product of the "constant" output dimensions*

## 5.78.1 Member Function Documentation

### 5.78.1.1 `ExactNumBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::ReshapeLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

### 5.78.1.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::ReshapeLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.78.1.3 LayerSetUp()

```
template<typename Dtype >
void caffe::ReshapeLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

#### Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

### 5.78.1.4 Reshape()

```
template<typename Dtype >
void caffe::ReshapeLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

#### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as



reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

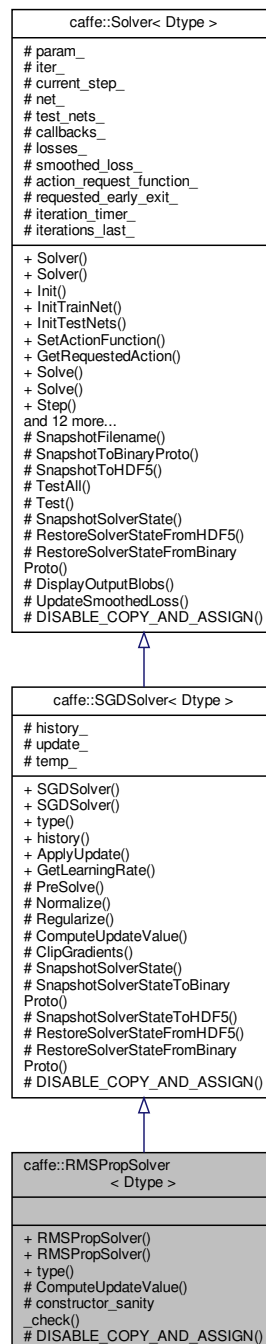
Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

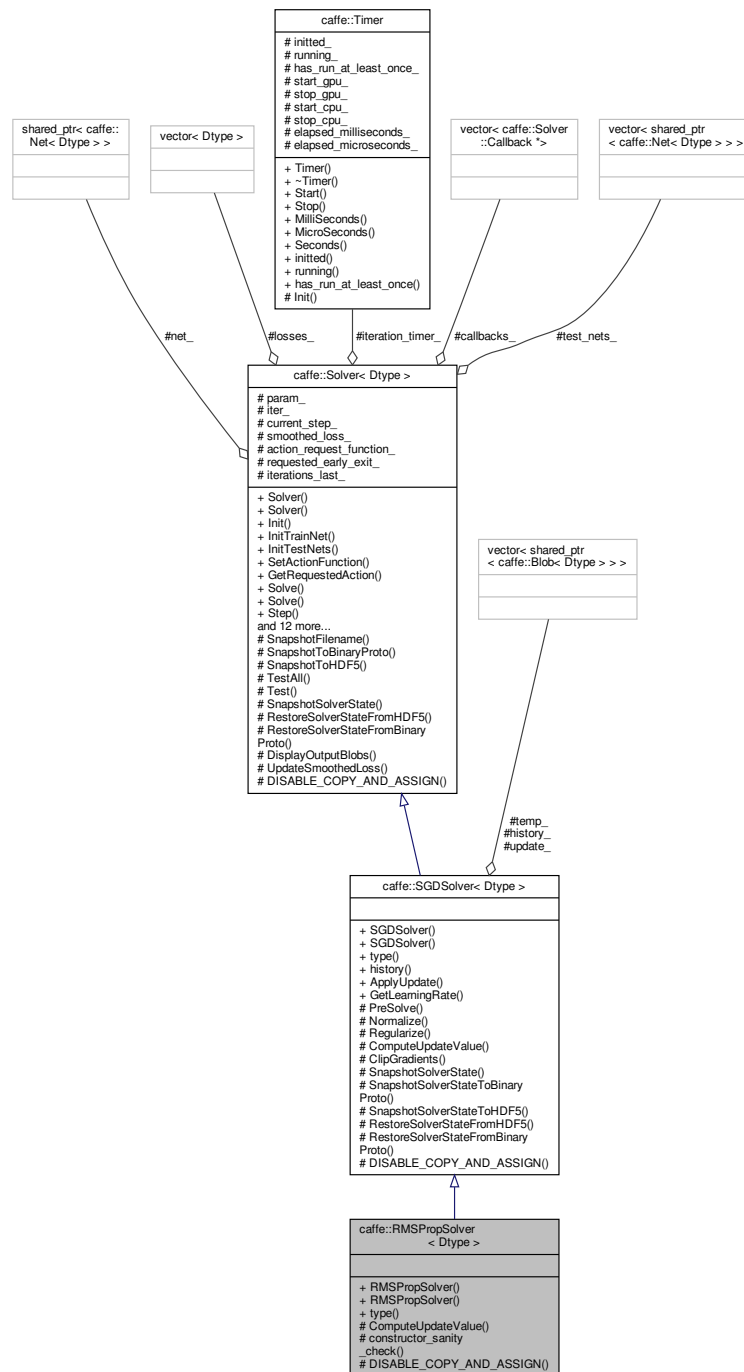
- `include/caffe/layers/reshape_layer.hpp`
- `src/caffe/layers/reshape_layer.cpp`

## 5.79 caffe::RMSPropSolver< Dtype > Class Template Reference

Inheritance diagram for caffe::RMSPropSolver< Dtype >:



Collaboration diagram for caffe::RMSPropSolver< Dtype >:



## Public Member Functions

- **RMSPropSolver** (const SolverParameter &param)
- **RMSPropSolver** (const string &param\_file)
- virtual const char \* **type** () const

Returns the solver type.

### Protected Member Functions

- virtual void **ComputeUpdateValue** (int param\_id, Dtype rate)
- void **constructor\_sanity\_check** ()
- **DISABLE\_COPY\_AND\_ASSIGN** ([RMSPropSolver](#))

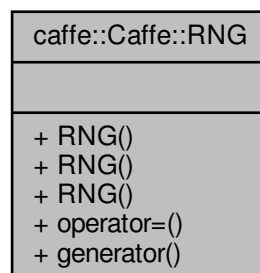
### Additional Inherited Members

The documentation for this class was generated from the following files:

- include/caffe/sgd\_solvers.hpp
- src/caffe/solvers/rmsprop\_solver.cpp

## 5.80 `caffe::Caffe::RNG` Class Reference

Collaboration diagram for `caffe::Caffe::RNG`:



### Classes

- class [Generator](#)

### Public Member Functions

- **RNG** (unsigned int seed)
- **RNG** (const [RNG](#) &)
- [RNG](#) & **operator=** (const [RNG](#) &)
- void \* **generator** ()

The documentation for this class was generated from the following files:

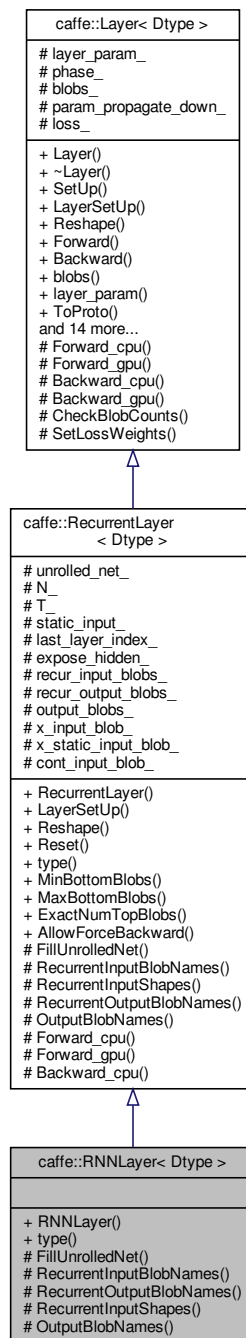
- include/caffe/common.hpp
- src/caffe/common.cpp

## 5.81 caffe::RNNLayer< Dtype > Class Template Reference

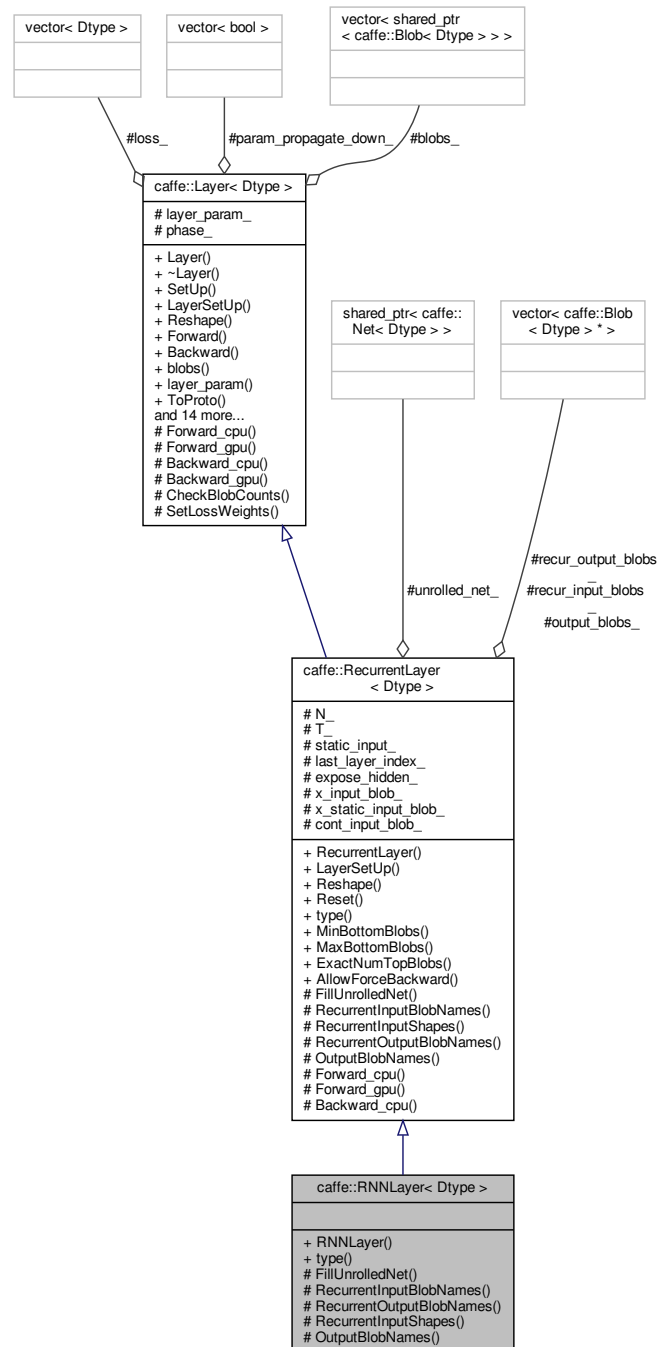
Processes time-varying inputs using a simple recurrent neural network (RNN). Implemented as a network unrolling the RNN computation in time.

```
#include <rnn_layer.hpp>
```

Inheritance diagram for caffe::RNNLayer< Dtype >:



Collaboration diagram for `caffe::RNNLayer< Dtype >`:



## Public Member Functions

- **RNNLayer** (const LayerParameter &param)
- virtual const char \* **type** () const

*Returns the layer type.*

## Protected Member Functions

- virtual void `FillUnrolledNet` (`NetParameter *net_param`) const  
*Fills `net_param` with the recurrent network architecture. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void `RecurrentInputBlobNames` (`vector< string > *names`) const  
*Fills `names` with the names of the 0th timestep recurrent input [Blob](#)s. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void `RecurrentOutputBlobNames` (`vector< string > *names`) const  
*Fills `names` with the names of the Tth timestep recurrent output [Blob](#)s. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void `RecurrentInputShapes` (`vector< BlobShape > *shapes`) const  
*Fills `shapes` with the shapes of the recurrent input [Blob](#)s. Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*
- virtual void `OutputBlobNames` (`vector< string > *names`) const  
*Fills `names` with the names of the output blobs, concatenated across all timesteps. Should return a name for each top [Blob](#). Subclasses should define this – see [RNNLayer](#) and [LSTMLayer](#) for examples.*

## Additional Inherited Members

## 5.81.1 Detailed Description

```
template<typename Dtype>
class caffe::RNNLayer< Dtype >
```

Processes time-varying inputs using a simple recurrent neural network (RNN). Implemented as a network unrolling the RNN computation in time.

Given time-varying inputs  $x_t$ , computes hidden state  $h_t := \tanh[W_{hh}h_{t-1} + W_{xh}x_t + b_h]$ , and outputs  $o_t := \tanh[W_{ho}h_t + b_o]$ .

The documentation for this class was generated from the following files:

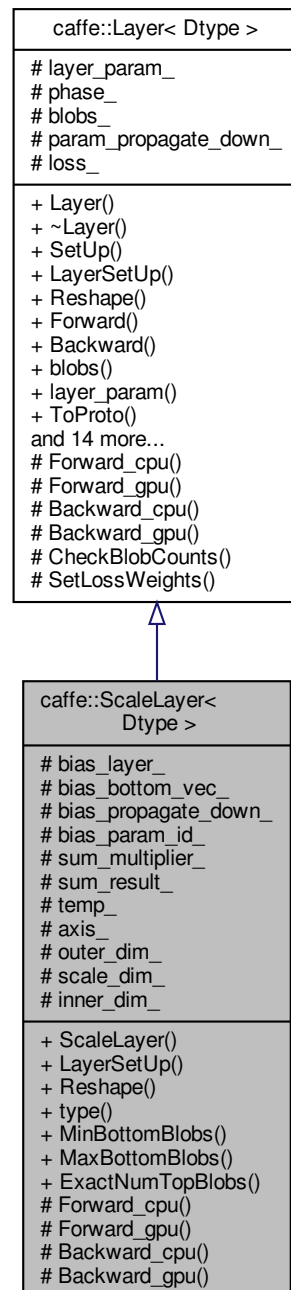
- `include/caffe/layers/rnn_layer.hpp`
- `src/caffe/layers/rnn_layer.cpp`

5.82 `caffe::ScaleLayer< Dtype >` Class Template Reference

Computes the elementwise product of two input Blobs, with the shape of the latter [Blob](#) "broadcast" to match the shape of the former. Equivalent to tiling the latter [Blob](#), then computing the elementwise product. Note: for efficiency and convenience, this layer can additionally perform a "broadcast" sum too when `bias_term: true` is set.

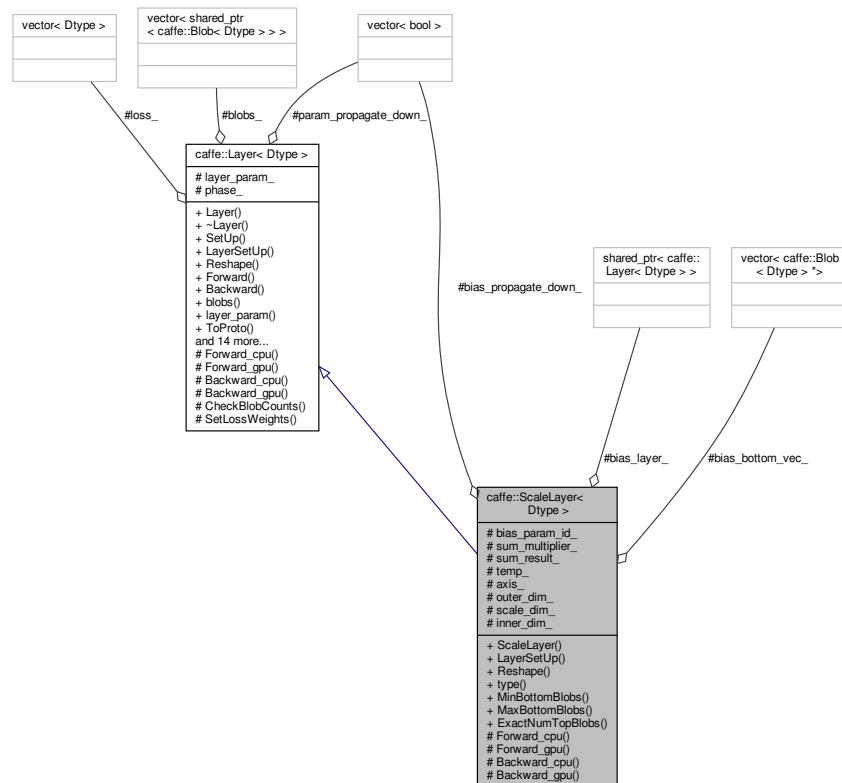
```
#include <scale_layer.hpp>
```

Inheritance diagram for `caffe::ScaleLayer< Dtype >`:





Collaboration diagram for caffe::ScaleLayer< Dtype >:



## Public Member Functions

- **ScaleLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **MinBottomBlobs** () const  
*Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.*
- virtual int **MaxBottomBlobs** () const  
*Returns the maximum number of bottom blobs required by the layer, or -1 if no maximum number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void **Forward\_cpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)
- virtual void **Forward\_gpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- shared\_ptr< [Layer](#)< Dtype > > **bias\_layer\_**
- vector< [Blob](#)< Dtype > \* > **bias\_bottom\_vec\_**
- vector< bool > **bias\_propagate\_down\_**
- int **bias\_param\_id\_**
- [Blob](#)< Dtype > **sum\_multiplier\_**
- [Blob](#)< Dtype > **sum\_result\_**
- [Blob](#)< Dtype > **temp\_**
- int **axis\_**
- int **outer\_dim\_**
- int **scale\_dim\_**
- int **inner\_dim\_**

## 5.82.1 Detailed Description

```
template<typename Dtype>
class caffe::ScaleLayer< Dtype >
```

Computes the elementwise product of two input Blobs, with the shape of the latter [Blob](#) "broadcast" to match the shape of the former. Equivalent to tiling the latter [Blob](#), then computing the elementwise product. Note: for efficiency and convenience, this layer can additionally perform a "broadcast" sum too when `bias_term: true` is set.

The latter, scale input may be omitted, in which case it's learned as parameter of the layer (as is the bias, if it is included).

## 5.82.2 Member Function Documentation

### 5.82.2.1 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::ScaleLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer](#)< Dtype >.

## 5.82.2.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::ScaleLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

In the below shape specifications,  $i$  denotes the value of the `axis` field given by `this->layer_param_↵ scale_param().axis()`, after canonicalization (i.e., conversion from negative to positive index, if applicable).

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(d_0 \times \dots \times d_i \times \dots \times d_j \times \dots \times d_n)</math> the first factor <math>x</math></li> <li><math>(d_i \times \dots \times d_j)</math> the second factor <math>y</math></li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li><math>(d_0 \times \dots \times d_i \times \dots \times d_j \times \dots \times d_n)</math> the product <math>z = xy</math> computed after "broadcasting" <math>y</math>. Equivalent to tiling <math>y</math> to have the same shape as <math>x</math>, then computing the elementwise product.</li> </ol>

Implements [caffe::Layer< Dtype >](#).

## 5.82.2.3 LayerSetUp()

```
template<typename Dtype >
void caffe::ScaleLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.82.2.4 MaxBottomBlobs()

```
template<typename Dtype >
virtual int caffe::ScaleLayer< Dtype >::MaxBottomBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of bottom blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.82.2.5 MinBottomBlobs()

```
template<typename Dtype >
virtual int caffe::ScaleLayer< Dtype >::MinBottomBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.82.2.6 Reshape()

```
template<typename Dtype >
void caffe::ScaleLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > \*> & bottom,
    const vector< Blob< Dtype > \*> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

##### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

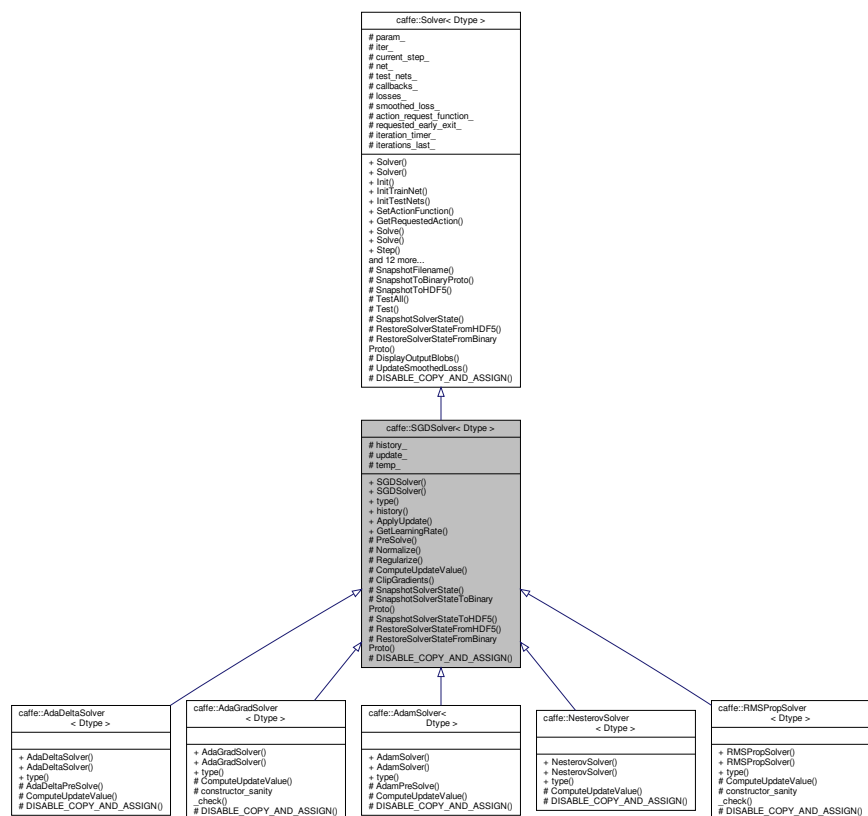
- include/caffe/layers/scale\_layer.hpp
- src/caffe/layers/scale\_layer.cpp

## 5.83 caffe::SGDSolver< Dtype > Class Template Reference

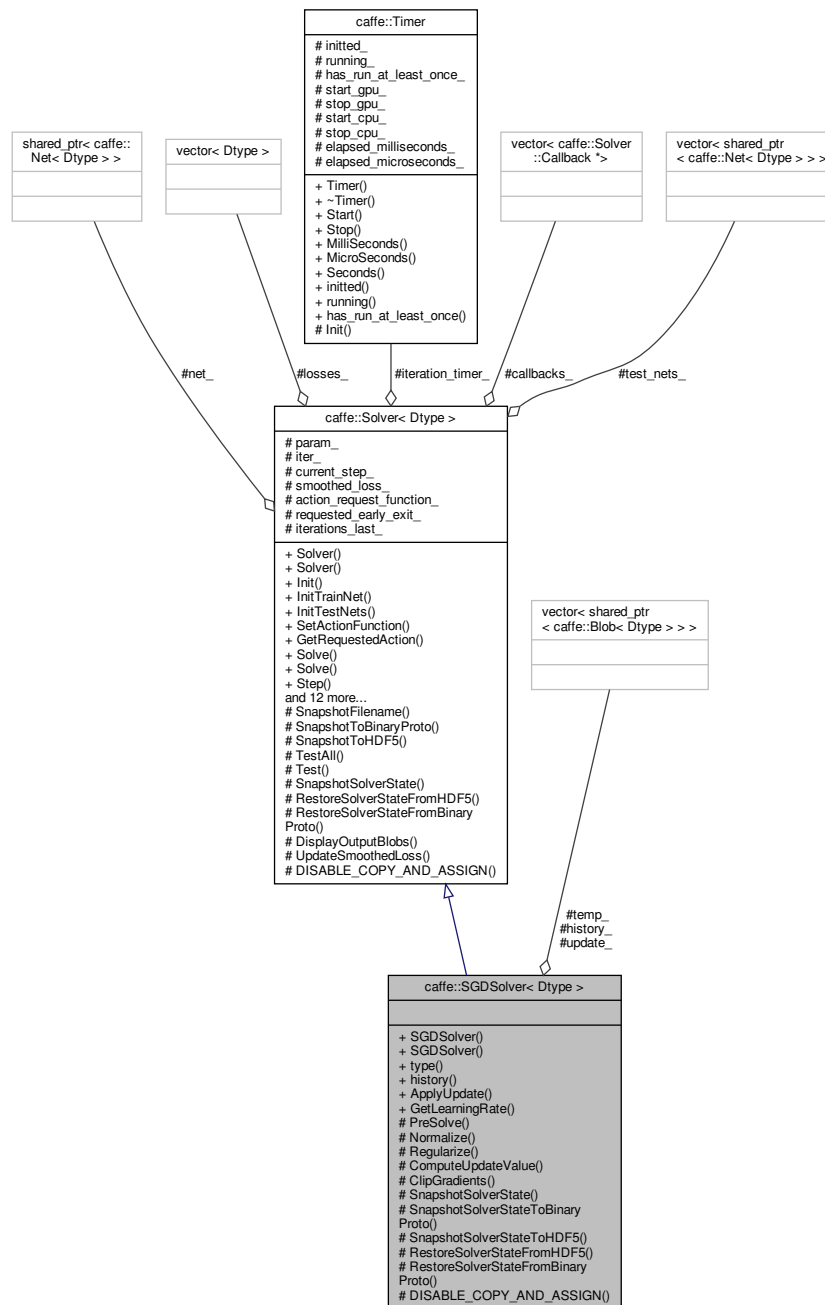
Optimizes the parameters of a [Net](#) using stochastic gradient descent (SGD) with momentum.

```
#include <sgd_solvers.hpp>
```

Inheritance diagram for caffe::SGDSolver< Dtype >:



Collaboration diagram for `caffe::SGDSolver< Dtype >`:



## Public Member Functions

- **SGDSolver** (const SolverParameter &param)
- **SGDSolver** (const string &param\_file)
- virtual const char \* **type** () const  
*Returns the solver type.*
- const vector< shared\_ptr< **Blob**< Dtype > > & **history** ()
- virtual void **ApplyUpdate** ()
- Dtype **GetLearningRate** ()

## Protected Member Functions

- void **PreSolve** ()
- virtual void **Normalize** (int param\_id)
- virtual void **Regularize** (int param\_id)
- virtual void **ComputeUpdateValue** (int param\_id, Dtype rate)
- virtual void **ClipGradients** ()
- virtual void **SnapshotSolverState** (const string &model\_filename)
- virtual void **SnapshotSolverStateToBinaryProto** (const string &model\_filename)
- virtual void **SnapshotSolverStateToHDF5** (const string &model\_filename)
- virtual void **RestoreSolverStateFromHDF5** (const string &state\_file)
- virtual void **RestoreSolverStateFromBinaryProto** (const string &state\_file)
- **DISABLE\_COPY\_AND\_ASSIGN** ([SGDSolver](#))

## Protected Attributes

- vector< shared\_ptr< [Blob](#)< Dtype > > > **history\_**
- vector< shared\_ptr< [Blob](#)< Dtype > > > **update\_**
- vector< shared\_ptr< [Blob](#)< Dtype > > > **temp\_**

## 5.83.1 Detailed Description

```
template<typename Dtype>
class caffe::SGDSolver< Dtype >
```

Optimizes the parameters of a [Net](#) using stochastic gradient descent (SGD) with momentum.

The documentation for this class was generated from the following files:

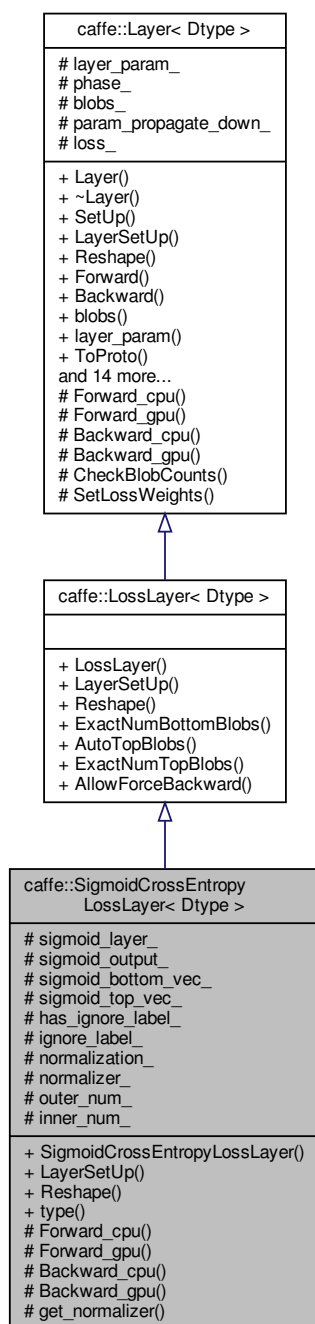
- include/caffe/sgd\_solvers.hpp
- src/caffe/solvers/sgd\_solver.cpp

## 5.84 caffe::SigmoidCrossEntropyLossLayer&lt; Dtype &gt; Class Template Reference

Computes the cross-entropy (logistic) loss  $E = \frac{-1}{n} \sum_{n=1}^N [p_n \log \hat{p}_n + (1 - p_n) \log(1 - \hat{p}_n)]$ , often used for predicting targets interpreted as probabilities.

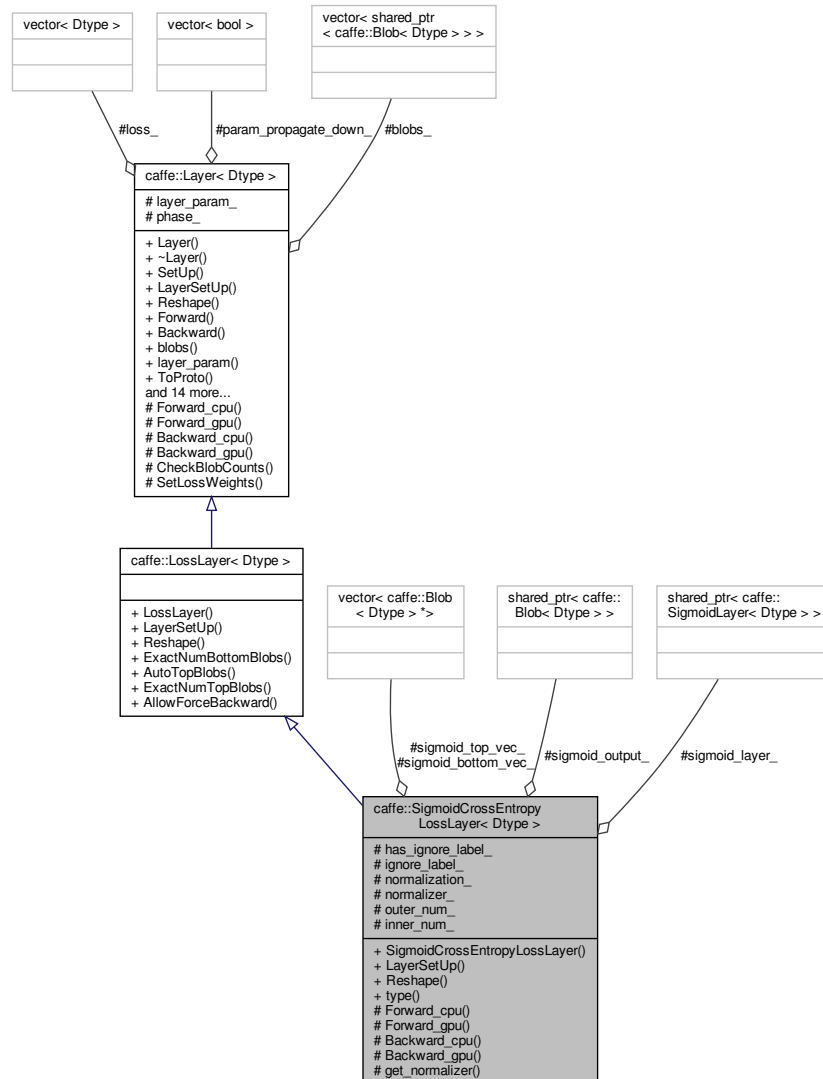
```
#include <sigmoid_cross_entropy_loss_layer.hpp>
```

Inheritance diagram for `caffe::SigmoidCrossEntropyLossLayer< Dtype >`:





Collaboration diagram for caffe::SigmoidCrossEntropyLossLayer< Dtype >:



## Public Member Functions

- **SigmoidCrossEntropyLossLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*

## Protected Member Functions

- virtual void **Forward\_cpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)

Computes the cross-entropy (logistic) loss  $E = \frac{-1}{n} \sum_{n=1}^N [p_n \log \hat{p}_n + (1 - p_n) \log(1 - \hat{p}_n)]$ , often used for predicting targets interpreted as probabilities.

- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)

Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

Computes the sigmoid cross-entropy loss error gradient w.r.t. the predictions.

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)

Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.

- virtual Dtype [get\\_normalizer](#) (LossParameter\_NormalizationMode normalization\_mode, int valid\_count)

## Protected Attributes

- shared\_ptr< [SigmoidLayer](#)< Dtype > > [sigmoid\\_layer\\_](#)  
The internal [SigmoidLayer](#) used to map predictions to probabilities.
- shared\_ptr< [Blob](#)< Dtype > > [sigmoid\\_output\\_](#)  
[sigmoid\\_output](#) stores the output of the [SigmoidLayer](#).
- vector< [Blob](#)< Dtype > \* > [sigmoid\\_bottom\\_vec\\_](#)  
bottom vector holder to call the underlying [SigmoidLayer::Forward](#)
- vector< [Blob](#)< Dtype > \* > [sigmoid\\_top\\_vec\\_](#)  
top vector holder to call the underlying [SigmoidLayer::Forward](#)
- bool [has\\_ignore\\_label\\_](#)  
Whether to ignore instances with a certain label.
- int [ignore\\_label\\_](#)  
The label indicating that an instance should be ignored.
- LossParameter\_NormalizationMode [normalization\\_](#)  
How to normalize the loss.
- Dtype [normalizer\\_](#)
- int [outer\\_num\\_](#)
- int [inner\\_num\\_](#)

### 5.84.1 Detailed Description

```
template<typename Dtype>
class caffe::SigmoidCrossEntropyLossLayer< Dtype >
```

Computes the cross-entropy (logistic) loss  $E = \frac{-1}{n} \sum_{n=1}^N [p_n \log \hat{p}_n + (1 - p_n) \log(1 - \hat{p}_n)]$ , often used for predicting targets interpreted as probabilities.

This layer is implemented rather than separate [SigmoidLayer](#) + [CrossEntropyLayer](#) as its gradient computation is more numerically stable. At test time, this layer can be replaced simply by a [SigmoidLayer](#).

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li>1. <math>(N \times C \times H \times W)</math> the scores <math>x \in [-\infty, +\infty]</math>, which this layer maps to probability predictions <math>\hat{p}_n = \sigma(x_n) \in [0, 1]</math> using the sigmoid function <math>\sigma(\cdot)</math> (see <a href="#">SigmoidLayer</a>).</li> <li>2. <math>(N \times C \times H \times W)</math> the targets <math>y \in [0, 1]</math></li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li>1. <math>(1 \times 1 \times 1 \times 1)</math> the computed cross-entropy loss:  <math display="block">E = \frac{-1}{n} \sum_{n=1}^N [p_n \log \hat{p}_n + (1 - p_n) \log(1 - \hat{p}_n)]</math> </li> </ol>

## 5.84.2 Member Function Documentation

## 5.84.2.1 Backward\_cpu()

```
template<typename Dtype>
void caffe::SigmoidCrossEntropyLossLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype >*> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype >*> & bottom )    [protected], [virtual]
```

Computes the sigmoid cross-entropy loss error gradient w.r.t. the predictions.

Gradients cannot be computed with respect to the target inputs (bottom[1]), so this method ignores bottom[1] and requires !propagate\_down[1], crashing if propagate\_down[1] is set.

## Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs <ol style="list-style-type: none"> <li>1. <math>(1 \times 1 \times 1 \times 1)</math> This <a href="#">Blob</a>'s diff will simply contain the loss_weight* <math>\lambda</math>, as <math>\lambda</math> is the coefficient of this layer's output <math>\ell_i</math> in the overall <a href="#">Net</a> loss <math>E = \lambda_i \ell_i + \text{other loss terms}</math>; hence <math>\frac{\partial E}{\partial \ell_i} = \lambda_i</math>. (*Assuming that this top <a href="#">Blob</a> is not used as a bottom (input) by any other layer of the <a href="#">Net</a>.)</li> </ol>
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> . propagate_down[1] must be false as gradient computation with respect to the targets is not implemented.
<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li>1. <math>(N \times C \times H \times W)</math> the predictions <math>x</math>; Backward computes diff <math>\frac{\partial E}{\partial x} = \frac{1}{n} \sum_{n=1}^N (\hat{p}_n - p_n)</math></li> <li>2. <math>(N \times 1 \times 1 \times 1)</math> the labels – ignored as we can't compute their error gradients</li> </ol>

Implements [caffe::Layer< Dtype >](#).

## 5.84.2.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::SigmoidCrossEntropyLossLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

Computes the cross-entropy (logistic) loss  $E = \frac{-1}{n} \sum_{n=1}^N [p_n \log \hat{p}_n + (1 - p_n) \log(1 - \hat{p}_n)]$ , often used for predicting targets interpreted as probabilities.

This layer is implemented rather than separate [SigmoidLayer](#) + [CrossEntropyLayer](#) as its gradient computation is more numerically stable. At test time, this layer can be replaced simply by a [SigmoidLayer](#).

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the scores <math>x \in [-\infty, +\infty]</math>, which this layer maps to probability predictions <math>\hat{p}_n = \sigma(x_n) \in [0, 1]</math> using the sigmoid function <math>\sigma(\cdot)</math> (see <a href="#">SigmoidLayer</a>).</li> <li><math>(N \times C \times H \times W)</math> the targets <math>y \in [0, 1]</math></li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> the computed cross-entropy loss:  <math display="block">E = \frac{-1}{n} \sum_{n=1}^N [p_n \log \hat{p}_n + (1 - p_n) \log(1 - \hat{p}_n)]</math> </li> </ol>

Implements [caffe::Layer< Dtype >](#).

## 5.84.2.3 get\_normalizer()

```
template<typename Dtype >
Dtype caffe::SigmoidCrossEntropyLossLayer< Dtype >::get_normalizer (
    LossParameter_NormalizationMode normalization_mode,
    int valid_count ) [protected], [virtual]
```

Read the normalization mode parameter and compute the normalizer based on the blob size. If `normalization_mode` is `VALID`, the count of valid outputs will be read from `valid_count`, unless it is -1 in which case all outputs are assumed to be valid.

## 5.84.2.4 LayerSetUp()

```
template<typename Dtype >
void caffe::SigmoidCrossEntropyLossLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::LossLayer< Dtype >](#).

5.84.2.5 `Reshape()`

```
template<typename Dtype >
void caffe::SigmoidCrossEntropyLossLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Reimplemented from [caffe::LossLayer< Dtype >](#).

The documentation for this class was generated from the following files:

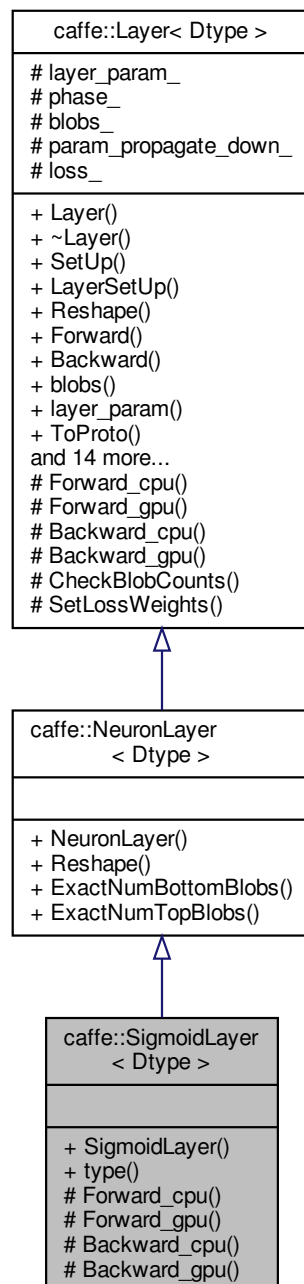
- `include/caffe/layers/sigmoid_cross_entropy_loss_layer.hpp`
- `src/caffe/layers/sigmoid_cross_entropy_loss_layer.cpp`

5.85 `caffe::SigmoidLayer< Dtype >` Class Template Reference

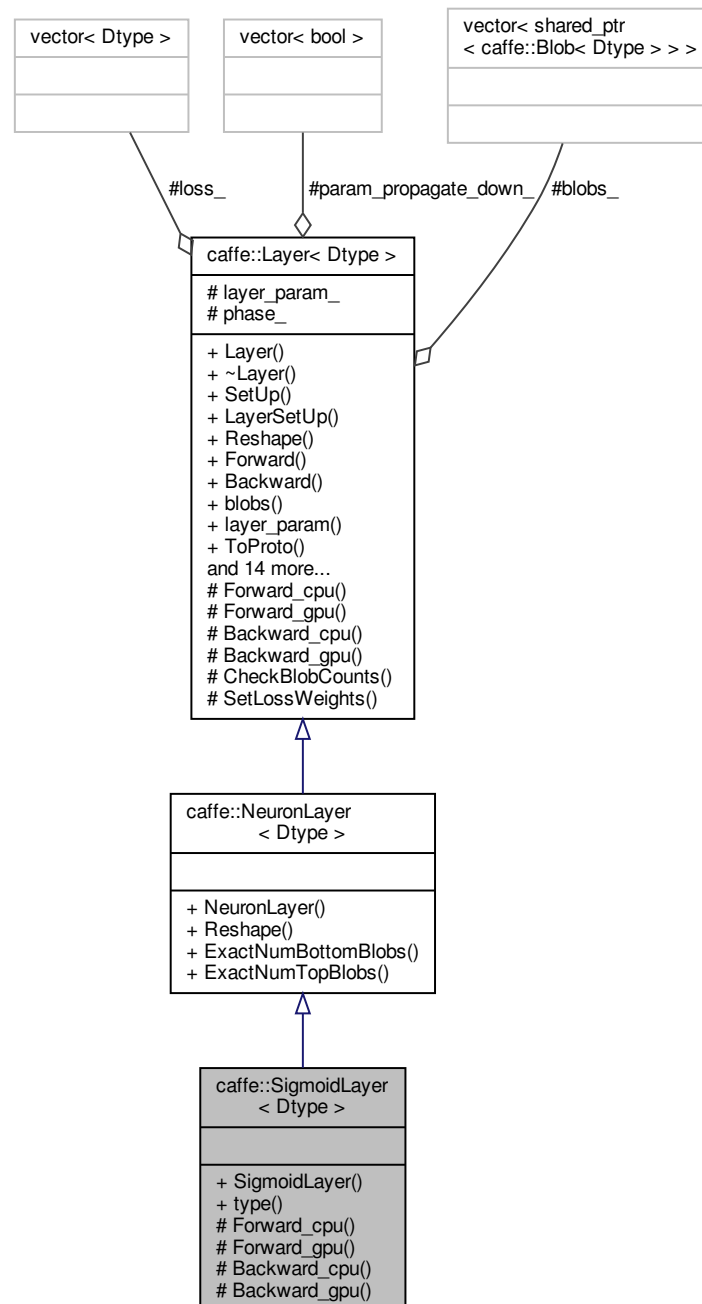
Sigmoid function non-linearity  $y = (1 + \exp(-x))^{-1}$ , a classic choice in neural networks.

```
#include <sigmoid_layer.hpp>
```

Inheritance diagram for `caffe::SigmoidLayer< Dtype >`:



Collaboration diagram for caffe::SigmoidLayer< Dtype >:



## Public Member Functions

- **SigmoidLayer** (const LayerParameter &param)
- virtual const char \* **type** () const

*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the error gradient w.r.t. the sigmoid inputs.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Additional Inherited Members

### 5.85.1 Detailed Description

```
template<typename Dtype>
class caffe::SigmoidLayer< Dtype >
```

Sigmoid function non-linearity  $y = (1 + \exp(-x))^{-1}$ , a classic choice in neural networks.

Note that the gradient vanishes as the values move away from 0. The [ReLULayer](#) is often a better choice for this reason.

### 5.85.2 Member Function Documentation

#### 5.85.2.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::SigmoidLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the sigmoid inputs.

#### Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times H \times W)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$ ; Backward fills their diff with gradients $\frac{\partial E}{\partial x} = \frac{\partial E}{\partial y} y(1 - y)$ if <code>propagate_down[0]</code>
	Generated by Doxygen



Implements [caffe::Layer< Dtype >](#).

#### 5.85.2.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::SigmoidLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

##### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = (1 + \exp(-x))^{-1}$

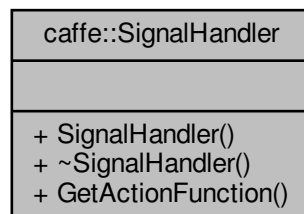
Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

- include/caffe/layers/sigmoid\_layer.hpp
- src/caffe/layers/sigmoid\_layer.cpp

## 5.86 caffe::SignalHandler Class Reference

Collaboration diagram for caffe::SignalHandler:



### Public Member Functions

- **SignalHandler** (SolverAction::Enum SIGINT\_action, SolverAction::Enum SIGHUP\_action)
- [ActionCallback](#) **GetActionFunction** ()

The documentation for this class was generated from the following files:

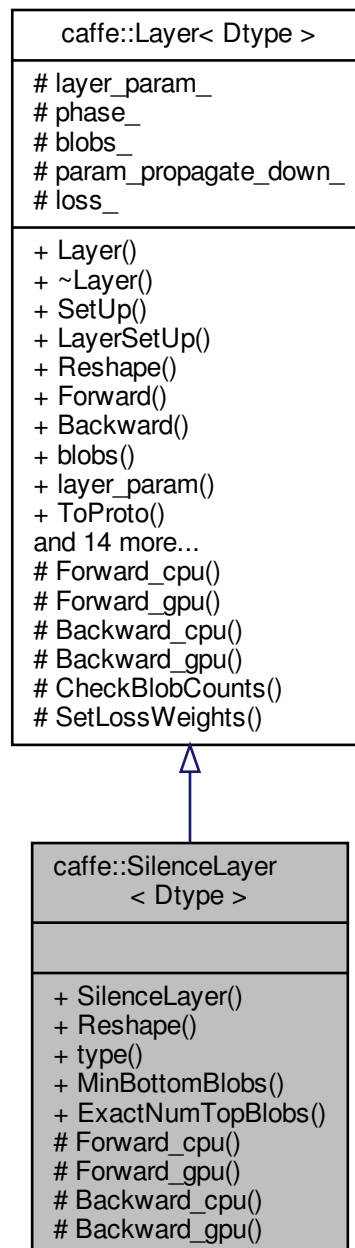
- include/caffe/util/signal\_handler.h
- src/caffe/util/signal\_handler.cpp

## 5.87 caffe::SilenceLayer< Dtype > Class Template Reference

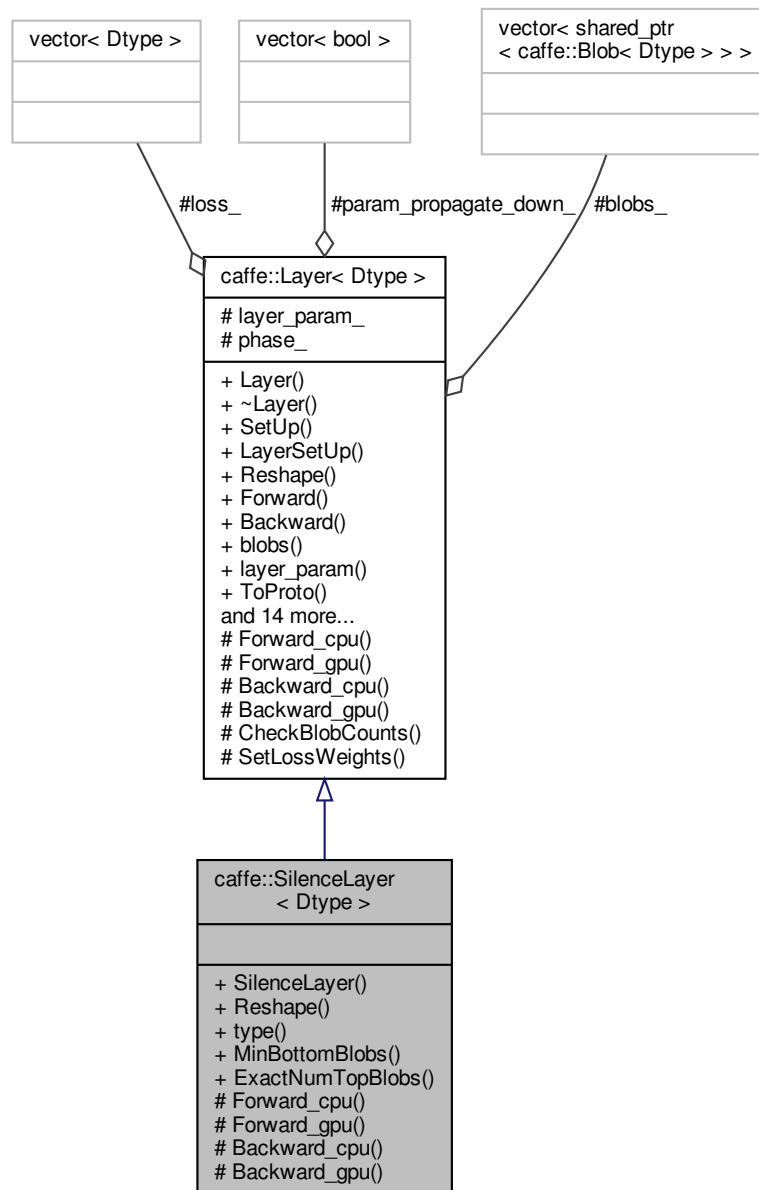
Ignores bottom blobs while producing no top blobs. (This is useful to suppress outputs during testing.)

```
#include <silence_layer.hpp>
```

Inheritance diagram for caffe::SilenceLayer< Dtype >:



Collaboration diagram for caffe::SilenceLayer< Dtype >:



## Public Member Functions

- **SilenceLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **MinBottomBlobs** () const  
*Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Additional Inherited Members

### 5.87.1 Detailed Description

```
template<typename Dtype>
class caffe::SilenceLayer< Dtype >
```

Ignores bottom blobs while producing no top blobs. (This is useful to suppress outputs during testing.)

### 5.87.2 Member Function Documentation

#### 5.87.2.1 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::SilenceLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

5.87.2.2 `MinBottomBlobs()`

```
template<typename Dtype >
virtual int caffe::SilenceLayer< Dtype >::MinBottomBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of bottom blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of bottom blobs.

Reimplemented from `caffe::Layer< Dtype >`.

5.87.2.3 `Reshape()`

```
template<typename Dtype >
virtual void caffe::SilenceLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [inline], [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements `caffe::Layer< Dtype >`.

The documentation for this class was generated from the following files:

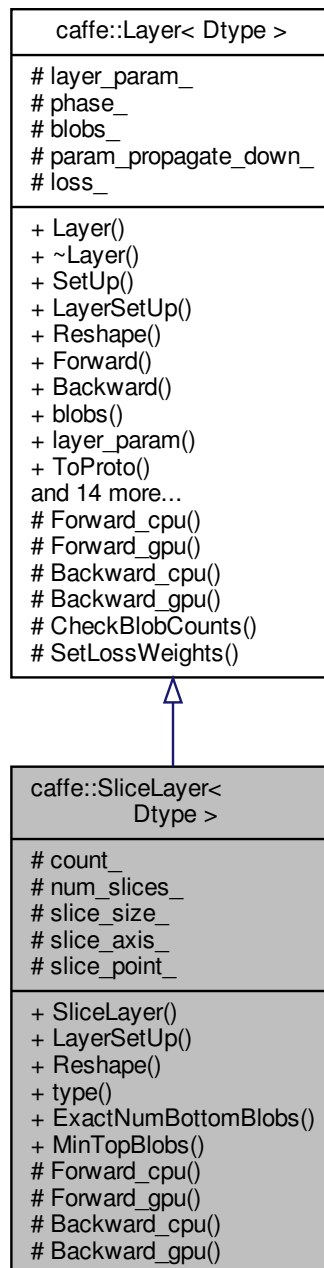
- `include/caffe/layers/silence_layer.hpp`
- `src/caffe/layers/silence_layer.cpp`

5.88 `caffe::SliceLayer< Dtype >` Class Template Reference

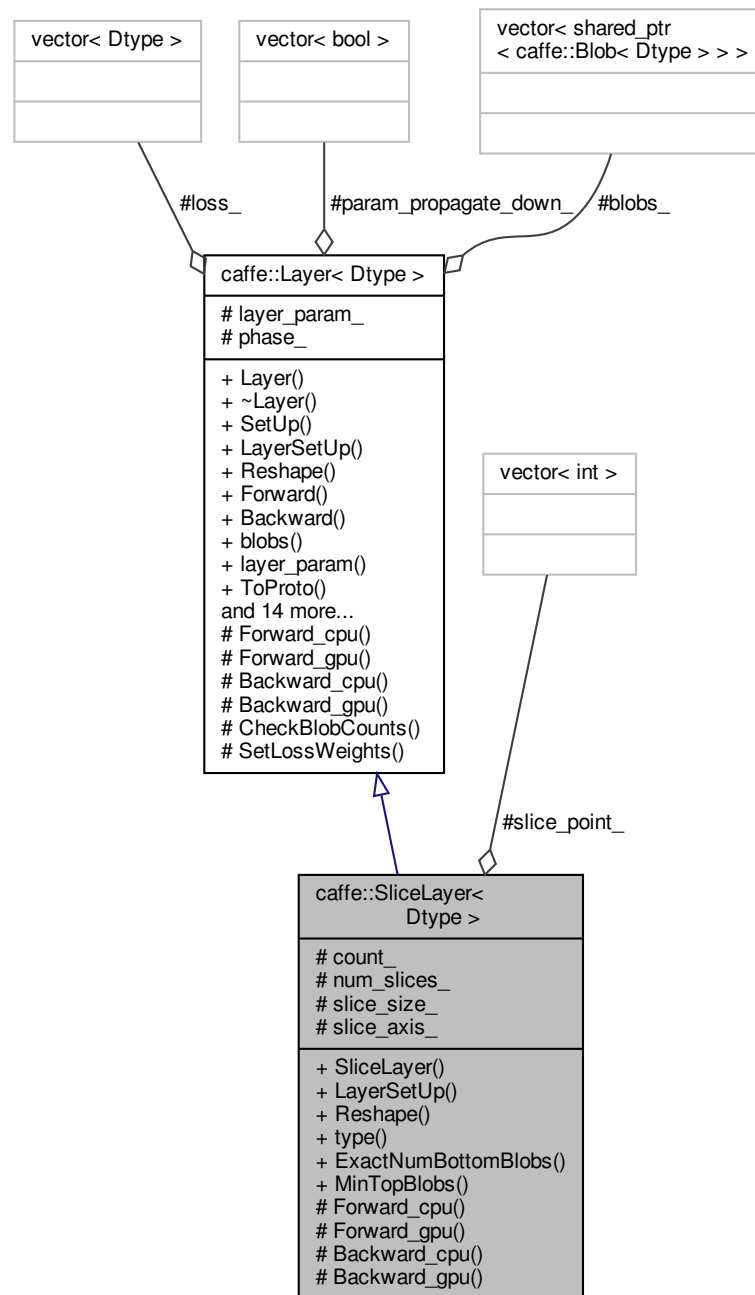
Takes a `Blob` and slices it along either the num or channel dimension, outputting multiple sliced `Blob` results.

```
#include <slice_layer.hpp>
```

Inheritance diagram for `caffe::SliceLayer< Dtype >`:



Collaboration diagram for caffe::SliceLayer< Dtype >:



## Public Member Functions

- **SliceLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*

- virtual const char \* [type](#) () const  
*Returns the layer type.*
- virtual int [ExactNumBottomBlobs](#) () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int [MinTopBlobs](#) () const  
*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- int **count\_**
- int **num\_slices\_**
- int **slice\_size\_**
- int **slice\_axis\_**
- vector< int > **slice\_point\_**

### 5.88.1 Detailed Description

```
template<typename Dtype>
class caffe::SliceLayer< Dtype >
```

Takes a [Blob](#) and slices it along either the num or channel dimension, outputting multiple sliced [Blob](#) results.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

### 5.88.2 Member Function Documentation



## 5.88.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::SliceLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.88.2.2 LayerSetUp()

```
template<typename Dtype >
void caffe::SliceLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.88.2.3 MinTopBlobs()

```
template<typename Dtype >
virtual int caffe::SliceLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.88.2.4 Reshape()

```
template<typename Dtype >
void caffe::SliceLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

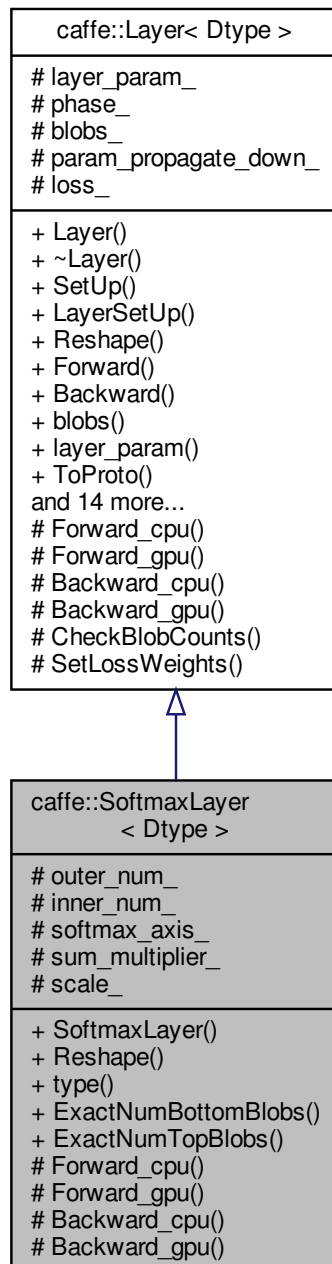
- `include/caffe/layers/slice_layer.hpp`
- `src/caffe/layers/slice_layer.cpp`

## 5.89 `caffe::SoftmaxLayer< Dtype >` Class Template Reference

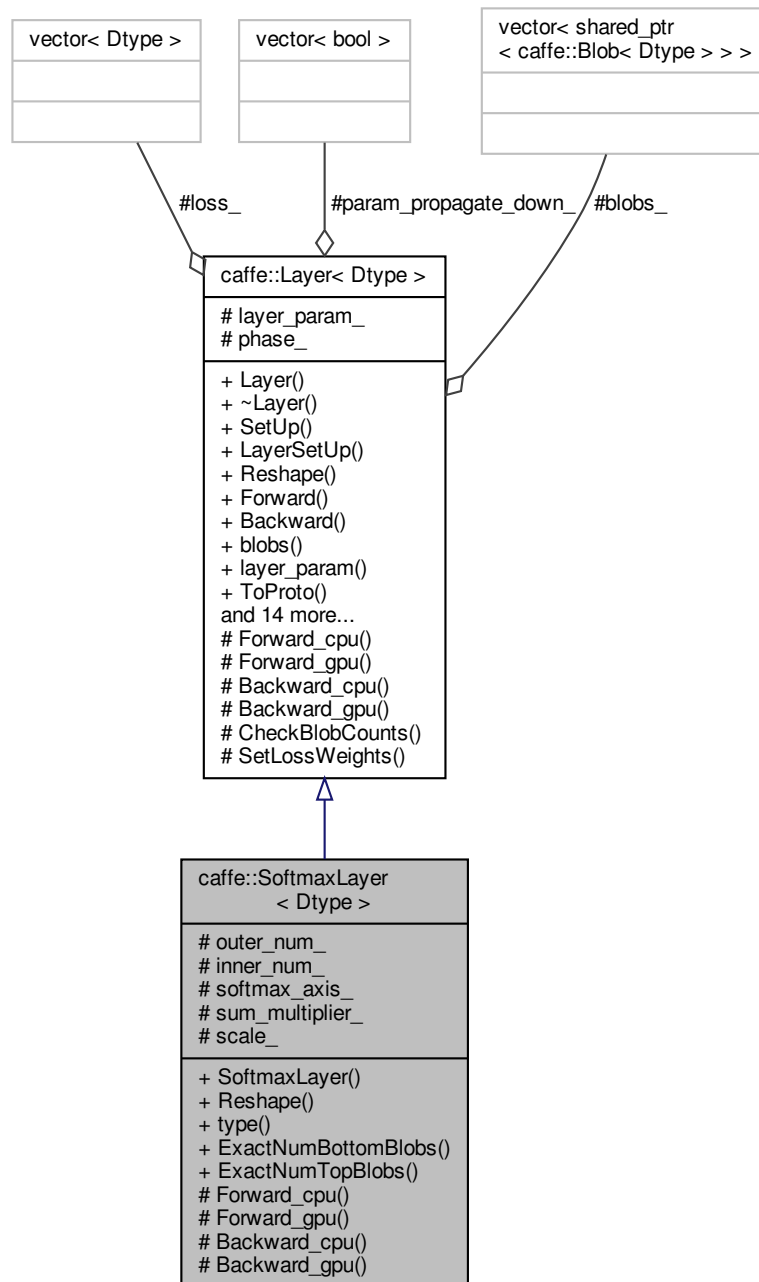
Computes the softmax function.

```
#include <softmax_layer.hpp>
```

Inheritance diagram for `caffe::SoftmaxLayer< Dtype >`:



Collaboration diagram for caffe::SoftmaxLayer< Dtype >:



## Public Member Functions

- **SoftmaxLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.
- virtual const char \* **type** () const  
Returns the layer type.

- virtual int [ExactNumBottomBlobs](#) () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int [ExactNumTopBlobs](#) () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- int **outer\_num\_**
- int **inner\_num\_**
- int **softmax\_axis\_**
- [Blob](#)< Dtype > [sum\\_multiplier\\_](#)  
*sum\_multiplier is used to carry out sum using BLAS*
- [Blob](#)< Dtype > [scale\\_](#)  
*scale is an intermediate [Blob](#) to hold temporary results.*

### 5.89.1 Detailed Description

```
template<typename Dtype>
class caffe::SoftmaxLayer< Dtype >
```

Computes the softmax function.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

### 5.89.2 Member Function Documentation

## 5.89.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::SoftmaxLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.89.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::SoftmaxLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.89.2.3 Reshape()

```
template<typename Dtype >
void caffe::SoftmaxLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

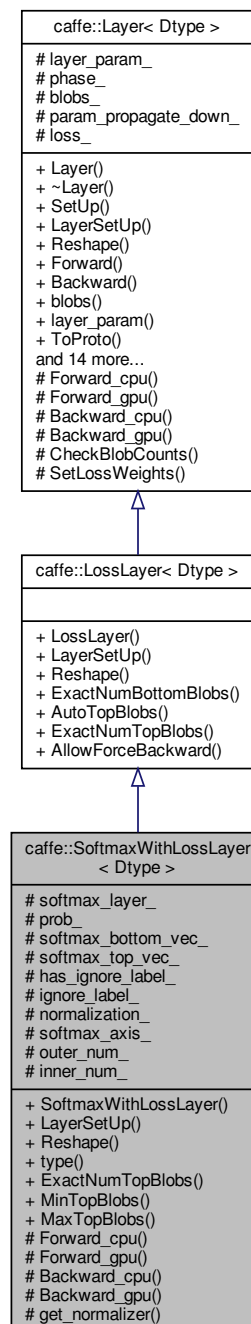
- include/caffe/layers/softmax\_layer.hpp
- src/caffe/layers/softmax\_layer.cpp

## 5.90 caffe::SoftmaxWithLossLayer< Dtype > Class Template Reference

Computes the multinomial logistic loss for a one-of-many classification task, passing real-valued predictions through a softmax to get a probability distribution over classes.

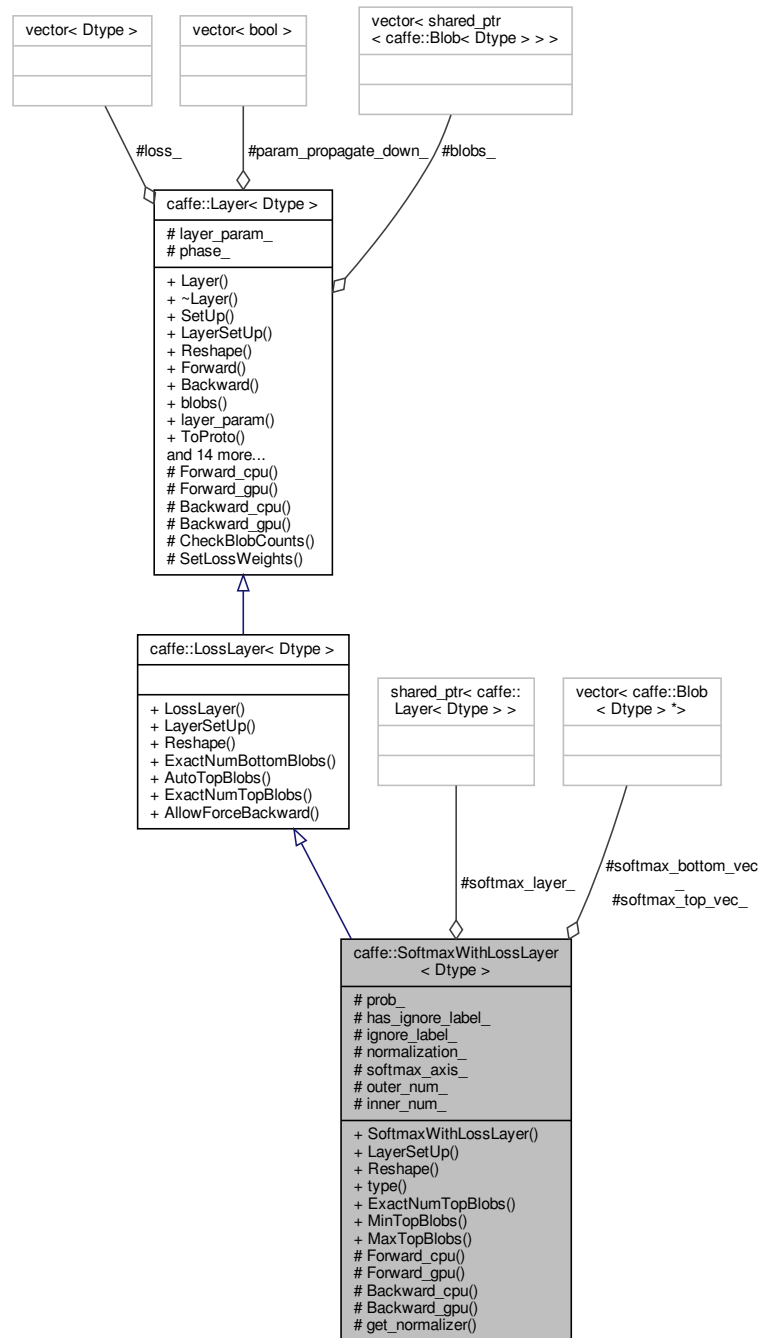
```
#include <softmax_loss_layer.hpp>
```

Inheritance diagram for caffe::SoftmaxWithLossLayer< Dtype >:





Collaboration diagram for caffe::SoftmaxWithLossLayer< Dtype >:



## Public Member Functions

- [SoftmaxWithLossLayer](#) (const LayerParameter &param)
- virtual void [LayerSetUp](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void [Reshape](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*

- virtual const char \* [type](#) () const  
*Returns the layer type.*
- virtual int [ExactNumTopBlobs](#) () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*
- virtual int [MinTopBlobs](#) () const  
*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*
- virtual int [MaxTopBlobs](#) () const  
*Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Computes the softmax loss error gradient w.r.t. the predictions.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*
- virtual Dtype [get\\_normalizer](#) (LossParameter\_NormalizationMode normalization\_mode, int valid\_count)

## Protected Attributes

- shared\_ptr< [Layer](#)< Dtype > > [softmax\\_layer\\_](#)  
*The internal [SoftmaxLayer](#) used to map predictions to a distribution.*
- [Blob](#)< Dtype > [prob\\_](#)  
*prob stores the output probability predictions from the [SoftmaxLayer](#).*
- vector< [Blob](#)< Dtype > \* > [softmax\\_bottom\\_vec\\_](#)  
*bottom vector holder used in call to the underlying [SoftmaxLayer::Forward](#)*
- vector< [Blob](#)< Dtype > \* > [softmax\\_top\\_vec\\_](#)  
*top vector holder used in call to the underlying [SoftmaxLayer::Forward](#)*
- bool [has\\_ignore\\_label\\_](#)  
*Whether to ignore instances with a certain label.*
- int [ignore\\_label\\_](#)  
*The label indicating that an instance should be ignored.*
- LossParameter\_NormalizationMode [normalization\\_](#)  
*How to normalize the output loss.*
- int [softmax\\_axis\\_](#)
- int [outer\\_num\\_](#)
- int [inner\\_num\\_](#)

### 5.90.1 Detailed Description

```
template<typename Dtype>  
class caffe::SoftmaxWithLossLayer< Dtype >
```

Computes the multinomial logistic loss for a one-of-many classification task, passing real-valued predictions through a softmax to get a probability distribution over classes.

This layer should be preferred over separate [SoftmaxLayer](#) + [MultinomialLogisticLossLayer](#) as its gradient computation is more numerically stable. At test time, this layer can be replaced simply by a [SoftmaxLayer](#).

## Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li>1. <math>(N \times C \times H \times W)</math> the predictions <math>x</math>, a <a href="#">Blob</a> with values in <math>[-\infty, +\infty]</math> indicating the predicted score for each of the <math>K = CHW</math> classes. This layer maps these scores to a probability distribution over classes using the softmax function <math>\hat{p}_{nk} = \exp(x_{nk}) / [\sum_{k'} \exp(x_{nk'})]</math> (see <a href="#">SoftmaxLayer</a>).</li> <li>2. <math>(N \times 1 \times 1 \times 1)</math> the labels <math>l</math>, an integer-valued <a href="#">Blob</a> with values <math>l_n \in [0, 1, 2, \dots, K - 1]</math> indicating the correct class label among the <math>K</math> classes</li> </ol>
<i>top</i>	output <a href="#">Blob</a> vector (length 1) <ol style="list-style-type: none"> <li>1. <math>(1 \times 1 \times 1 \times 1)</math> the computed cross-entropy classification loss: <math>E = \frac{-1}{N} \sum_{n=1}^N \log(\hat{p}_{n, l_n})</math>, for softmax output class probabilities <math>\hat{p}</math></li> </ol>

## 5.90.2 Constructor &amp; Destructor Documentation

## 5.90.2.1 SoftmaxWithLossLayer()

```
template<typename Dtype >
caffe::SoftmaxWithLossLayer< Dtype >::SoftmaxWithLossLayer (
    const LayerParameter & param ) [inline], [explicit]
```

## Parameters

<i>param</i>	provides LossParameter loss_param, with options: <ul style="list-style-type: none"> <li>• ignore_label (optional) Specify a label value that should be ignored when computing the loss.</li> <li>• normalize (optional, default true) If true, the loss is normalized by the number of (nonignored) labels present; otherwise the loss is simply summed over spatial locations.</li> </ul>
--------------	--

## 5.90.3 Member Function Documentation

## 5.90.3.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::SoftmaxWithLossLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the softmax loss error gradient w.r.t. the predictions.

Gradients cannot be computed with respect to the label inputs (`bottom[1]`), so this method ignores `bottom[1]` and requires `!propagate_down[1]`, crashing if `propagate_down[1]` is set.

#### Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs <ol style="list-style-type: none"> <li><math>(1 \times 1 \times 1 \times 1)</math> This <a href="#">Blob</a>'s diff will simply contain the <code>loss_weight * λ</code>, as <math>\lambda</math> is the coefficient of this layer's output <math>\ell_i</math> in the overall <a href="#">Net</a> loss <math>E = \lambda_i \ell_i + \text{other loss terms}</math>; hence <math>\frac{\partial E}{\partial \ell_i} = \lambda_i</math>. (*Assuming that this top <a href="#">Blob</a> is not used as a bottom (input) by any other layer of the <a href="#">Net</a>.)</li> </ol>
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> . <code>propagate_down[1]</code> must be false as we can't compute gradients with respect to the labels.
<i>bottom</i>	input <a href="#">Blob</a> vector (length 2) <ol style="list-style-type: none"> <li><math>(N \times C \times H \times W)</math> the predictions <math>x</math>; Backward computes diff <math>\frac{\partial E}{\partial x}</math></li> <li><math>(N \times 1 \times 1 \times 1)</math> the labels – ignored as we can't compute their error gradients</li> </ol>

Implements [caffe::Layer< Dtype >](#).

#### 5.90.3.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::SoftmaxWithLossLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::LossLayer< Dtype >](#).

#### 5.90.3.3 get\_normalizer()

```
template<typename Dtype >
Dtype caffe::SoftmaxWithLossLayer< Dtype >::get\_normalizer (
    LossParameter_NormalizationMode normalization_mode,
    int valid_count ) [protected], [virtual]
```

Read the normalization mode parameter and compute the normalizer based on the blob size. If `normalization_mode` is `VALID`, the count of valid outputs will be read from `valid_count`, unless it is -1 in which case all outputs are assumed to be valid.

#### 5.90.3.4 LayerSetUp()

```
template<typename Dtype >
void caffe::SoftmaxWithLossLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > \*> & bottom,
    const vector< Blob< Dtype > \*> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as `Reshape`.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::LossLayer< Dtype >](#).

## 5.90.3.5 MaxTopBlobs()

```
template<typename Dtype >
virtual int caffe::SoftmaxWithLossLayer< Dtype >::MaxTopBlobs ( ) const [inline], [virtual]
```

Returns the maximum number of top blobs required by the layer, or -1 if no maximum number is required.

This method should be overridden to return a non-negative value if your layer expects some maximum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.90.3.6 MinTopBlobs()

```
template<typename Dtype >
virtual int caffe::SoftmaxWithLossLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.90.3.7 Reshape()

```
template<typename Dtype >
void caffe::SoftmaxWithLossLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Reimplemented from [caffe::LossLayer< Dtype >](#).

The documentation for this class was generated from the following files:

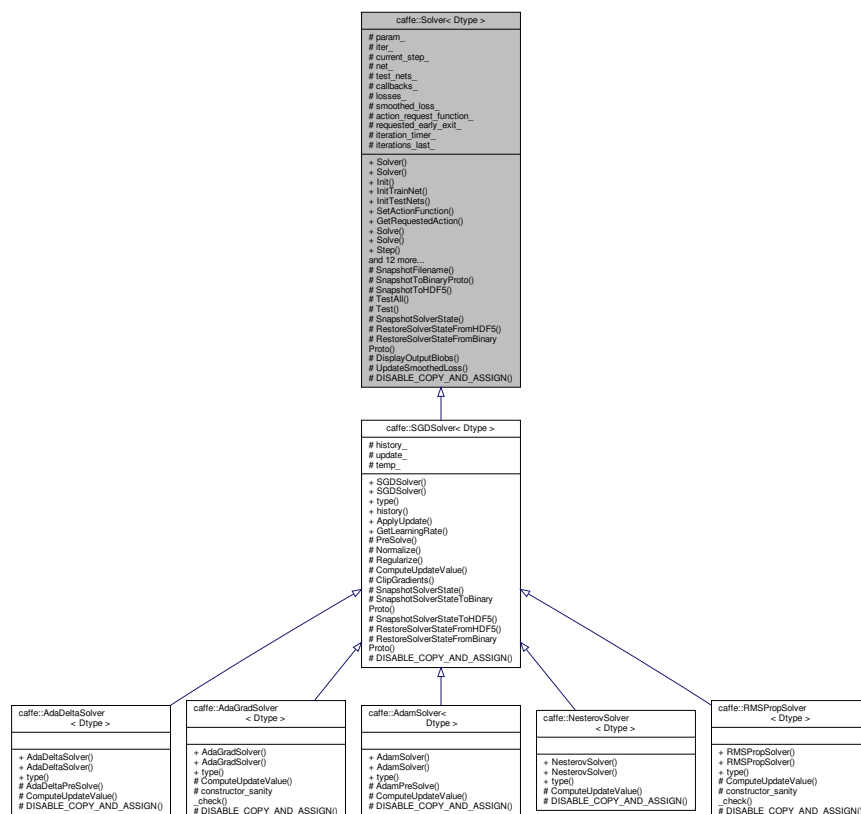
- include/caffe/layers/softmax\_loss\_layer.hpp
- src/caffe/layers/softmax\_loss\_layer.cpp

## 5.91 caffe::Solver< Dtype > Class Template Reference

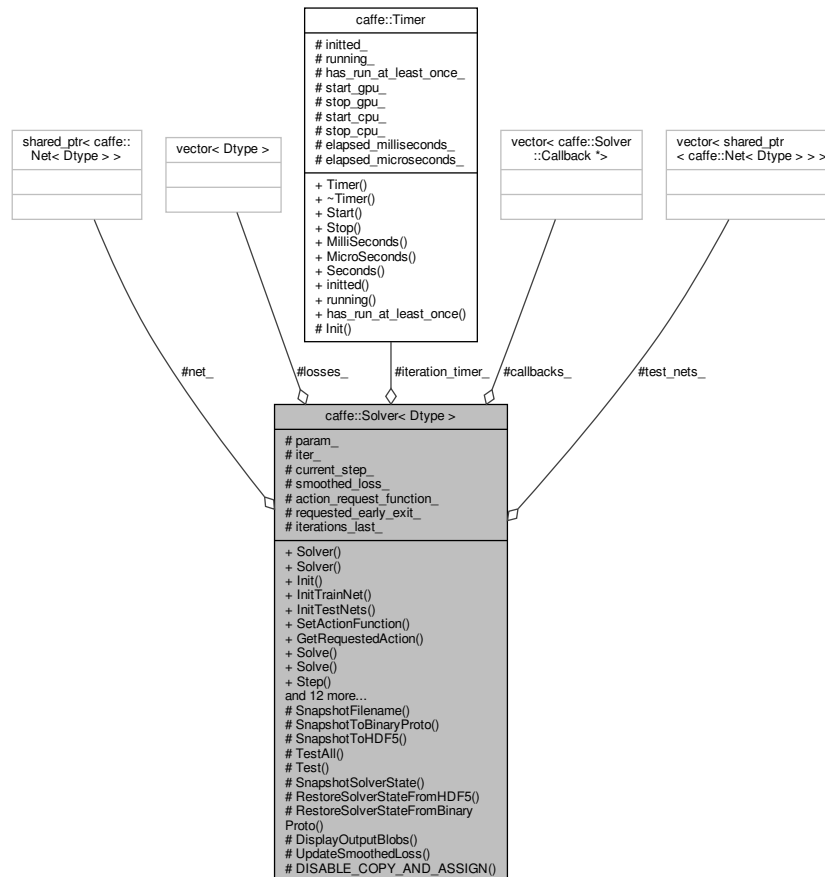
An interface for classes that perform optimization on [Nets](#).

```
#include <solver.hpp>
```

Inheritance diagram for caffe::Solver< Dtype >:



Collaboration diagram for `caffe::Solver< Dtype >`:



## Classes

- class [Callback](#)

## Public Member Functions

- **Solver** (const SolverParameter &param)
- **Solver** (const string &param\_file)
- void **Init** (const SolverParameter &param)
- void **InitTrainNet** ()
- void **InitTestNets** ()
- void **SetActionFunction** ([ActionCallback](#) func)
- SolverAction::Enum **GetRequestedAction** ()
- virtual void **Solve** (const char \*resume\_file=NULL)
- void **Solve** (const string &resume\_file)
- void **Step** (int iters)
- void **Restore** (const char \*resume\_file)
- void **Snapshot** ()
- const SolverParameter & **param** () const
- shared\_ptr< [Net](#)< Dtype > > **net** ()



- const vector< shared\_ptr< [Net](#)< Dtype > > > & **test\_nets** ()
- int **iter** () const
- const vector< [Callback](#) \* > & **callbacks** () const
- void **add\_callback** ([Callback](#) \*value)
- void **CheckSnapshotWritePermissions** ()
- virtual const char \* **type** () const  
*Returns the solver type.*
- virtual void **ApplyUpdate** ()=0

### Protected Member Functions

- string **SnapshotFilename** (const string &extension)
- string **SnapshotToBinaryProto** ()
- string **SnapshotToHDF5** ()
- void **TestAll** ()
- void **Test** (const int test\_net\_id=0)
- virtual void **SnapshotSolverState** (const string &model\_filename)=0
- virtual void **RestoreSolverStateFromHDF5** (const string &state\_file)=0
- virtual void **RestoreSolverStateFromBinaryProto** (const string &state\_file)=0
- void **DisplayOutputBlobs** (const int net\_id)
- void **UpdateSmoothedLoss** (Dtype loss, int start\_iter, int average\_loss)
- **DISABLE\_COPY\_AND\_ASSIGN** ([Solver](#))

### Protected Attributes

- SolverParameter **param\_**
- int **iter\_**
- int **current\_step\_**
- shared\_ptr< [Net](#)< Dtype > > **net\_**
- vector< shared\_ptr< [Net](#)< Dtype > > > **test\_nets\_**
- vector< [Callback](#) \* > **callbacks\_**
- vector< Dtype > **losses\_**
- Dtype **smoothed\_loss\_**
- [ActionCallback](#) **action\_request\_function\_**
- bool **requested\_early\_exit\_**
- [Timer](#) **iteration\_timer\_**
- float **iterations\_last\_**

#### 5.91.1 Detailed Description

```
template<typename Dtype>
class caffe::Solver< Dtype >
```

An interface for classes that perform optimization on [Nets](#).

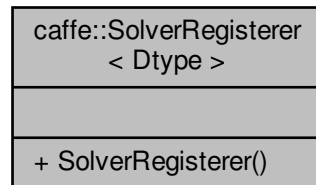
Requires implementation of ApplyUpdate to compute a parameter update given the current state of the [Net](#) parameters.

The documentation for this class was generated from the following files:

- include/caffe/solver.hpp
- src/caffe/solver.cpp

## 5.92 `caffe::SolverRegisterer< Dtype >` Class Template Reference

Collaboration diagram for `caffe::SolverRegisterer< Dtype >`:



### Public Member Functions

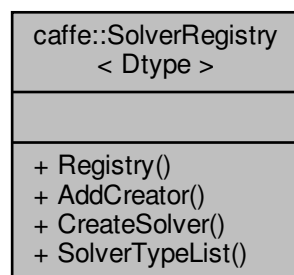
- **SolverRegisterer** (const string &type, [Solver](#)< Dtype > \*(\*creator)(const SolverParameter &))

The documentation for this class was generated from the following file:

- `include/caffe/solver_factory.hpp`

## 5.93 `caffe::SolverRegistry< Dtype >` Class Template Reference

Collaboration diagram for `caffe::SolverRegistry< Dtype >`:



### Public Types

- typedef [Solver](#)< Dtype > \*(\* **Creator**) (const SolverParameter &)
- typedef std::map< string, Creator > **CreatorRegistry**

### Static Public Member Functions

- static `CreatorRegistry & Registry ()`
- static void **AddCreator** (const string &type, Creator creator)
- static `Solver< Dtype > * CreateSolver` (const SolverParameter &param)
- static `vector< string > SolverTypeList ()`

The documentation for this class was generated from the following file:

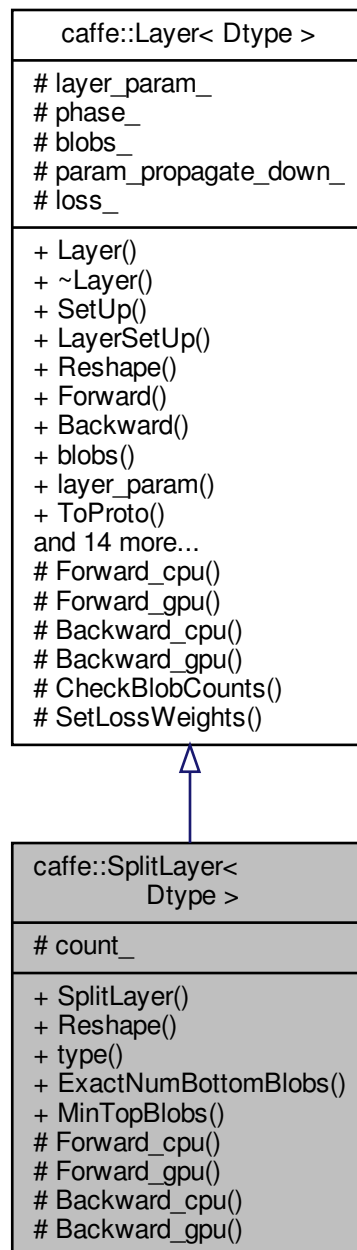
- `include/caffe/solver_factory.hpp`

## 5.94 `caffe::SplitLayer< Dtype >` Class Template Reference

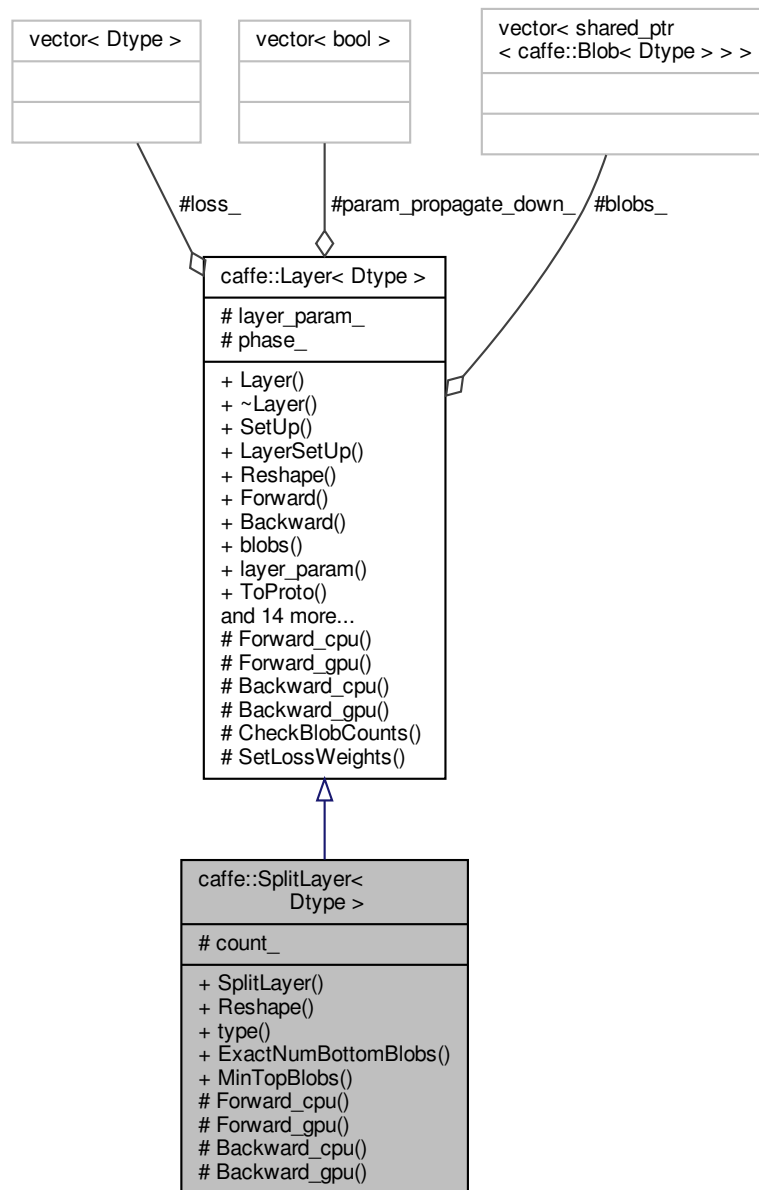
Creates a "split" path in the network by copying the bottom `Blob` into multiple top `Blobs` to be used by multiple consuming layers.

```
#include <split_layer.hpp>
```

Inheritance diagram for `caffe::SplitLayer< Dtype >`:



Collaboration diagram for caffe::SplitLayer< Dtype >:



## Public Member Functions

- **SplitLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **MinTopBlobs** () const  
*Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the CPU device, compute the layer output.*
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- int **count\_**

### 5.94.1 Detailed Description

```
template<typename Dtype>
class caffe::SplitLayer< Dtype >
```

Creates a "split" path in the network by copying the bottom [Blob](#) into multiple top [Blobs](#) to be used by multiple consuming layers.

TODO(dox): thorough documentation for Forward, Backward, and proto params.

### 5.94.2 Member Function Documentation

#### 5.94.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::SplitLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer](#)< Dtype >.

## 5.94.2.2 MinTopBlobs()

```
template<typename Dtype >
virtual int caffe::SplitLayer< Dtype >::MinTopBlobs ( ) const [inline], [virtual]
```

Returns the minimum number of top blobs required by the layer, or -1 if no minimum number is required.

This method should be overridden to return a non-negative value if your layer expects some minimum number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.94.2.3 Reshape()

```
template<typename Dtype >
void caffe::SplitLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

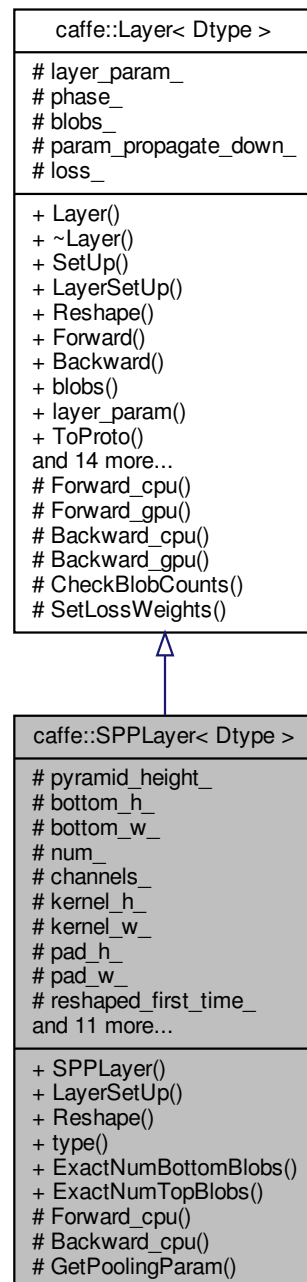
- include/caffe/layers/split\_layer.hpp
- src/caffe/layers/split\_layer.cpp

## 5.95 caffe::SPPLayer&lt; Dtype &gt; Class Template Reference

Does spatial pyramid pooling on the input image by taking the max, average, etc. within regions so that the result vector of different sized images are of the same size.

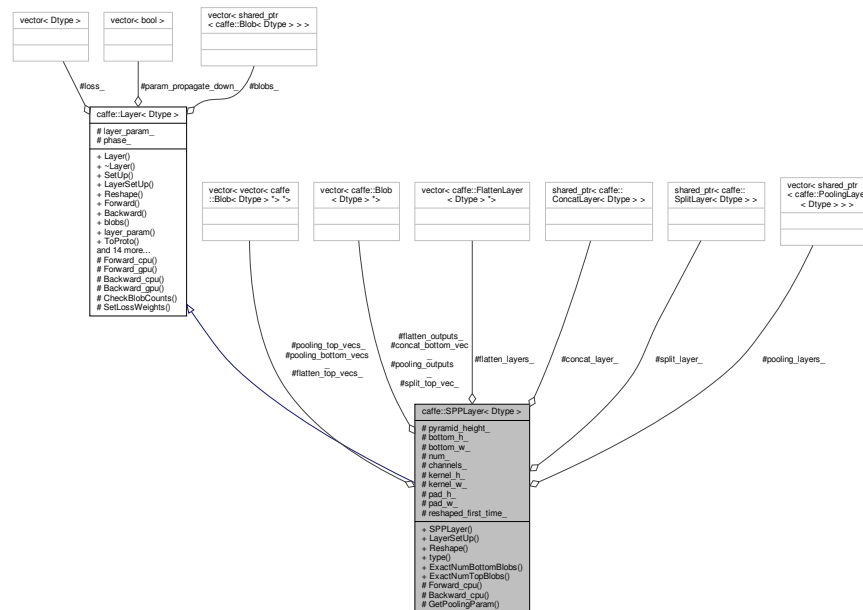
```
#include <spp_layer.hpp>
```

Inheritance diagram for `caffe::SPPLayer< Dtype >`:





Collaboration diagram for caffe::SPPLayer< Dtype > :



## Public Member Functions

- **SPPLayer** (const LayerParameter &param)
- virtual void **LayerSetUp** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void **Forward\_cpu** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Using the CPU device, compute the layer output.*
- virtual void **Backward\_cpu** (const vector< **Blob**< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< **Blob**< Dtype > \* > &bottom)  
*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*
- virtual LayerParameter **GetPoolingParam** (const int pyramid\_level, const int bottom\_h, const int bottom\_w, const SPPParameter spp\_param)

## Protected Attributes

- int **pyramid\_height\_**
- int **bottom\_h\_**
- int **bottom\_w\_**
- int **num\_**
- int **channels\_**
- int **kernel\_h\_**
- int **kernel\_w\_**
- int **pad\_h\_**
- int **pad\_w\_**
- bool **reshaped\_first\_time\_**
- shared\_ptr< [SplitLayer](#)< Dtype > > **split\_layer\_**  
*the internal Split layer that feeds the pooling layers*
- vector< [Blob](#)< Dtype > \* > **split\_top\_vec\_**  
*top vector holder used in call to the underlying [SplitLayer::Forward](#)*
- vector< vector< [Blob](#)< Dtype > \* > \* > **pooling\_bottom\_vecs\_**  
*bottom vector holder used in call to the underlying [PoolingLayer::Forward](#)*
- vector< shared\_ptr< [PoolingLayer](#)< Dtype > > > **pooling\_layers\_**  
*the internal Pooling layers of different kernel sizes*
- vector< vector< [Blob](#)< Dtype > \* > \* > **pooling\_top\_vecs\_**  
*top vector holders used in call to the underlying [PoolingLayer::Forward](#)*
- vector< [Blob](#)< Dtype > \* > **pooling\_outputs\_**  
*pooling\_outputs stores the outputs of the PoolingLayers*
- vector< [FlattenLayer](#)< Dtype > \* > **flatten\_layers\_**  
*the internal Flatten layers that the Pooling layers feed into*
- vector< vector< [Blob](#)< Dtype > \* > \* > **flatten\_top\_vecs\_**  
*top vector holders used in call to the underlying [FlattenLayer::Forward](#)*
- vector< [Blob](#)< Dtype > \* > **flatten\_outputs\_**  
*flatten\_outputs stores the outputs of the FlattenLayers*
- vector< [Blob](#)< Dtype > \* > **concat\_bottom\_vec\_**  
*bottom vector holder used in call to the underlying [ConcatLayer::Forward](#)*
- shared\_ptr< [ConcatLayer](#)< Dtype > > **concat\_layer\_**  
*the internal Concat layers that the Flatten layers feed into*

### 5.95.1 Detailed Description

```
template<typename Dtype>
class caffe::SPPLayer< Dtype >
```

Does spatial pyramid pooling on the input image by taking the max, average, etc. within regions so that the result vector of different sized images are of the same size.

### 5.95.2 Member Function Documentation

## 5.95.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::SPPLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.95.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::SPPLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.95.2.3 LayerSetUp()

```
template<typename Dtype >
void caffe::SPPLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

#### 5.95.2.4 Reshape()

```
template<typename Dtype >
void caffe::SPPLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

##### Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

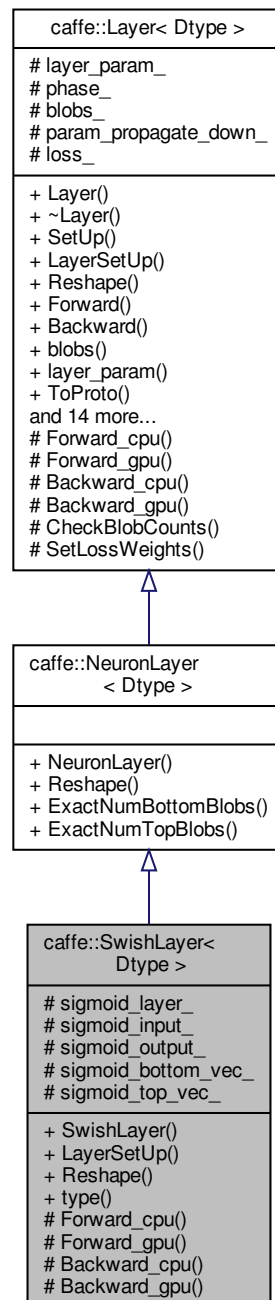
- include/caffe/layers/spp\_layer.hpp
- src/caffe/layers/spp\_layer.cpp

## 5.96 caffe::SwishLayer< Dtype > Class Template Reference

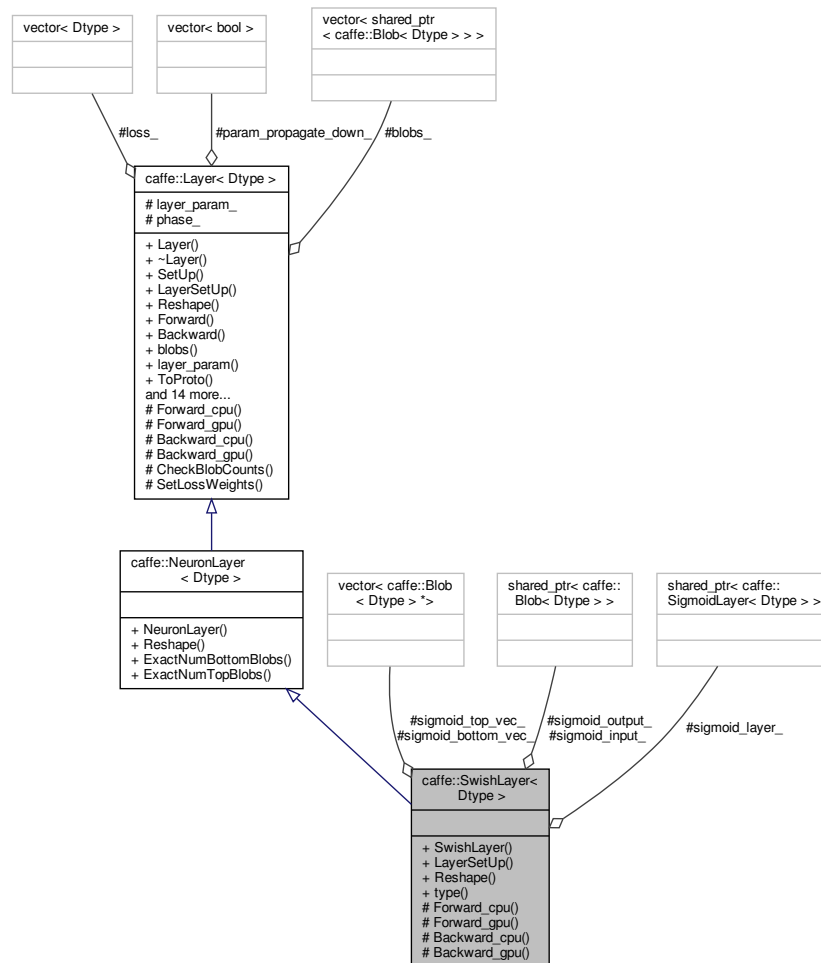
Swish non-linearity  $y = x\sigma(\beta x)$ . A novel activation function that tends to work better than ReLU [1].

```
#include <swish_layer.hpp>
```

Inheritance diagram for caffe::SwishLayer< Dtype >:



Collaboration diagram for `caffe::SwishLayer< Dtype >`:



## Public Member Functions

- [SwishLayer](#) (const LayerParameter &param)
- virtual void [LayerSetUp](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Does layer-specific setup: your layer should implement this function as well as Reshape.*
- virtual void [Reshape](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* [type](#) () const  
*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Computes the error gradient w.r.t. the sigmoid inputs.*
- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \* > &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \* > &bottom)  
*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- shared\_ptr< [SigmoidLayer](#)< Dtype > > [sigmoid\\_layer\\_](#)  
*The internal [SigmoidLayer](#).*
- shared\_ptr< [Blob](#)< Dtype > > [sigmoid\\_input\\_](#)  
*[sigmoid\\_input\\_](#) stores the input of the [SigmoidLayer](#).*
- shared\_ptr< [Blob](#)< Dtype > > [sigmoid\\_output\\_](#)  
*[sigmoid\\_output\\_](#) stores the output of the [SigmoidLayer](#).*
- vector< [Blob](#)< Dtype > \* > [sigmoid\\_bottom\\_vec\\_](#)  
*bottom vector holder to call the underlying [SigmoidLayer::Forward](#)*
- vector< [Blob](#)< Dtype > \* > [sigmoid\\_top\\_vec\\_](#)  
*top vector holder to call the underlying [SigmoidLayer::Forward](#)*

## 5.96.1 Detailed Description

```
template<typename Dtype>
class caffe::SwishLayer< Dtype >
```

Swish non-linearity  $y = x\sigma(\beta x)$ . A novel activation function that tends to work better than ReLU [1].

[1] Prajit Ramachandran, Barret Zoph, Quoc V. Le. "Searching for Activation Functions". arXiv preprint arXiv:1710.05941v2 (2017).

## 5.96.2 Constructor & Destructor Documentation

### 5.96.2.1 SwishLayer()

```
template<typename Dtype >
caffe::SwishLayer< Dtype >::SwishLayer (
    const LayerParameter & param ) [inline], [explicit]
```

#### Parameters

<i>param</i>	provides SwishParameter swish_param, with <a href="#">SwishLayer</a> options: <ul style="list-style-type: none"> <li>• beta (<b>optional</b>, default 1). the value <math>\beta</math> in the <math>y = x\sigma(\beta x)</math>.</li> </ul>
--------------	---

## 5.96.3 Member Function Documentation

### 5.96.3.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::SwishLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the sigmoid inputs.

#### Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times H \times W)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$ ; Backward fills their diff with gradients $\frac{\partial E}{\partial x} = \frac{\partial E}{\partial y}(\beta y + \sigma(\beta x)(1 - \beta y))$ if <code>propagate_down[0]</code>

Implements [caffe::Layer< Dtype >](#).

### 5.96.3.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::SwishLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = x\sigma(\beta x)$ .

Implements [caffe::Layer< Dtype >](#).



## 5.96.3.3 LayerSetUp()

```
template<typename Dtype >
void caffe::SwishLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

## Parameters

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.96.3.4 Reshape()

```
template<typename Dtype >
void caffe::SwishLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

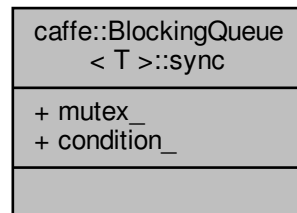
Reimplemented from [caffe::NeuronLayer< Dtype >](#).

The documentation for this class was generated from the following files:

- `include/caffe/layers/swish_layer.hpp`
- `src/caffe/layers/swish_layer.cpp`

## 5.97 caffe::BlockingQueue< T >::sync Class Reference

Collaboration diagram for caffe::BlockingQueue< T >::sync:



### Public Attributes

- boost::mutex **mutex\_**
- boost::condition\_variable **condition\_**

The documentation for this class was generated from the following file:

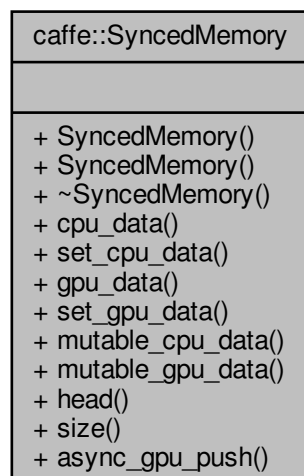
- src/caffe/util/blocking\_queue.cpp

## 5.98 caffe::SyncedMemory Class Reference

Manages memory allocation and synchronization between the host (CPU) and device (GPU).

```
#include <syncedmem.hpp>
```

Collaboration diagram for caffe::SyncedMemory:



## Public Types

- enum **SyncedHead** { UNINITIALIZED, HEAD\_AT\_CPU, HEAD\_AT\_GPU, SYNCED }

## Public Member Functions

- **SyncedMemory** (size\_t size)
- const void \* **cpu\_data** ()
- void **set\_cpu\_data** (void \*data)
- const void \* **gpu\_data** ()
- void **set\_gpu\_data** (void \*data)
- void \* **mutable\_cpu\_data** ()
- void \* **mutable\_gpu\_data** ()
- SyncedHead **head** () const
- size\_t **size** () const
- void **async\_gpu\_push** (const cudaStream\_t &stream)

### 5.98.1 Detailed Description

Manages memory allocation and synchronization between the host (CPU) and device (GPU).

TODO(dox): more thorough description.

The documentation for this class was generated from the following files:

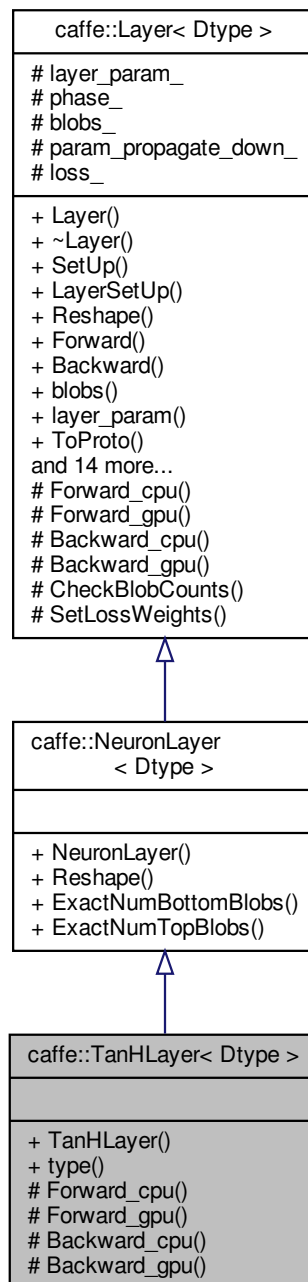
- include/caffe/syncedmem.hpp
- src/caffe/syncedmem.cpp

## 5.99 caffe::TanHLayer< Dtype > Class Template Reference

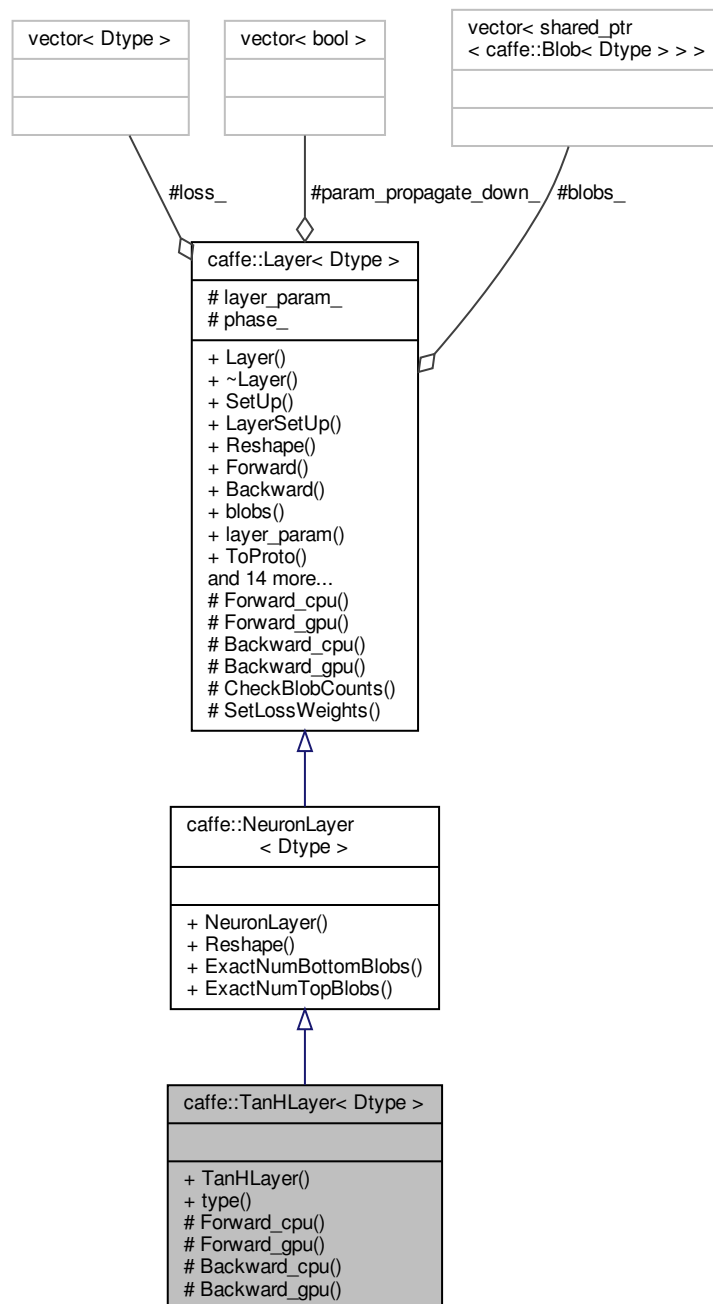
TanH hyperbolic tangent non-linearity  $y = \frac{\exp(2x)-1}{\exp(2x)+1}$ , popular in auto-encoders.

```
#include <tan_h_layer.hpp>
```

Inheritance diagram for `caffe::TanHLayer< Dtype >`:



Collaboration diagram for caffe::TanHLayer< Dtype >:



## Public Member Functions

- **TanHLayer** (const LayerParameter &param)
- virtual const char \* **type** () const

*Returns the layer type.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Computes the error gradient w.r.t. the sigmoid inputs.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Additional Inherited Members

### 5.99.1 Detailed Description

```
template<typename Dtype>
class caffe::TanHLayer< Dtype >
```

TanH hyperbolic tangent non-linearity  $y = \frac{\exp(2x)-1}{\exp(2x)+1}$ , popular in auto-encoders.

Note that the gradient vanishes as the values move away from 0. The [ReLULayer](#) is often a better choice for this reason.

### 5.99.2 Member Function Documentation

#### 5.99.2.1 Backward\_cpu()

```
template<typename Dtype >
void caffe::TanHLayer< Dtype >::Backward_cpu (
    const vector< Blob< Dtype > *> & top,
    const vector< bool > & propagate_down,
    const vector< Blob< Dtype > *> & bottom ) [protected], [virtual]
```

Computes the error gradient w.r.t. the sigmoid inputs.

#### Parameters

<i>top</i>	output <a href="#">Blob</a> vector (length 1), providing the error gradient with respect to the outputs 1. $(N \times C \times H \times W)$ containing error gradients $\frac{\partial E}{\partial y}$ with respect to computed outputs $y$
<i>propagate_down</i>	see <a href="#">Layer::Backward</a> .
<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$ ; Backward fills their diff with gradients
	$\frac{\partial E}{\partial x} = \frac{\partial E}{\partial y} \left( 1 - \left[ \frac{\exp(2x)-1}{\exp(2x)+1} \right]^2 \right) = \frac{\partial E}{\partial y} (1 - y^2)$ if propagate_down[0]

Implements [caffe::Layer< Dtype >](#).

### 5.99.2.2 Forward\_cpu()

```
template<typename Dtype >
void caffe::TanHLayer< Dtype >::Forward_cpu (
    const vector< Blob< Dtype > * > & bottom,
    const vector< Blob< Dtype > * > & top ) [protected], [virtual]
```

#### Parameters

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = \frac{\exp(2x)-1}{\exp(2x)+1}$

Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

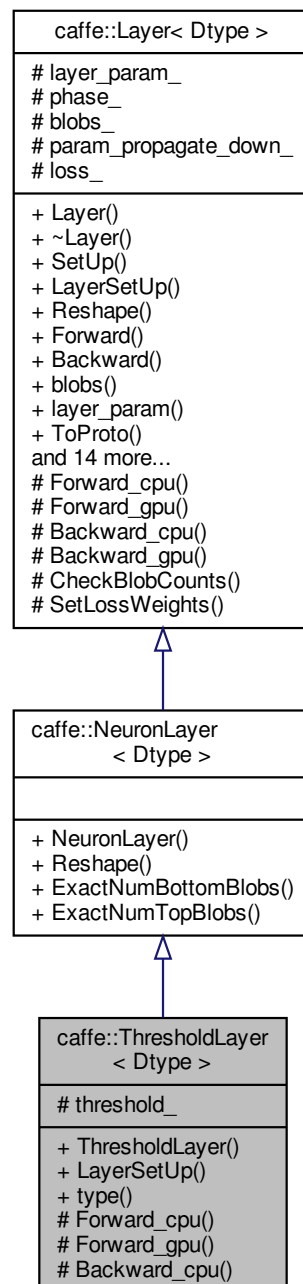
- include/caffe/layers/tanh\_layer.hpp
- src/caffe/layers/tanh\_layer.cpp

## 5.100 caffe::ThresholdLayer< Dtype > Class Template Reference

Tests whether the input exceeds a threshold: outputs 1 for inputs above threshold; 0 otherwise.

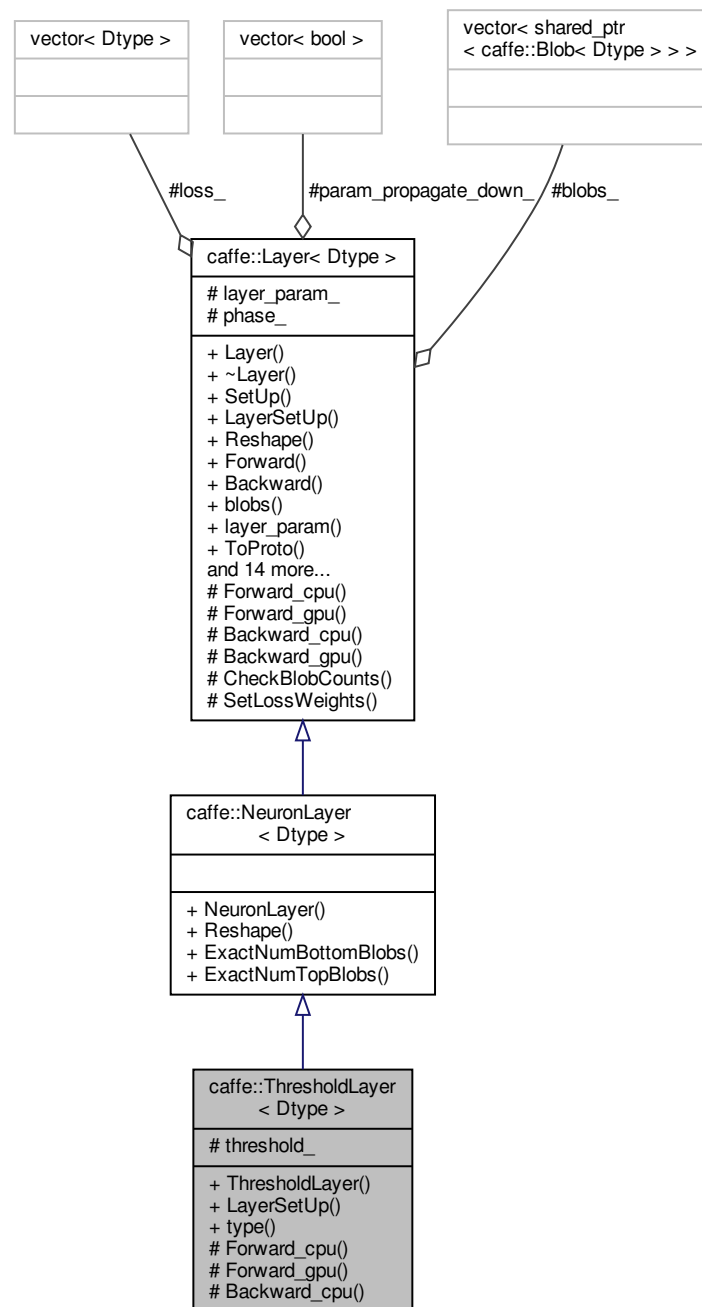
```
#include <threshold_layer.hpp>
```

Inheritance diagram for `caffe::ThresholdLayer< Dtype >`:





Collaboration diagram for caffe::ThresholdLayer< Dtype >:



## Public Member Functions

- [ThresholdLayer](#) (const LayerParameter &param)
- virtual void [LayerSetUp](#) (const vector< [Blob](#)< Dtype > \* > &bottom, const vector< [Blob](#)< Dtype > \* > &top)  
Does layer-specific setup: your layer should implement this function as well as *Reshape*.
- virtual const char \* [type](#) () const  
Returns the layer type.

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)
- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)  
*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*
- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)  
*Not implemented (non-differentiable function)*

## Protected Attributes

- Dtype [threshold\\_](#)

### 5.100.1 Detailed Description

```
template<typename Dtype>
class caffe::ThresholdLayer< Dtype >
```

Tests whether the input exceeds a threshold: outputs 1 for inputs above threshold; 0 otherwise.

### 5.100.2 Constructor & Destructor Documentation

#### 5.100.2.1 ThresholdLayer()

```
template<typename Dtype >
caffe::ThresholdLayer< Dtype >::ThresholdLayer (
    const LayerParameter & param ) [inline], [explicit]
```

#### Parameters

<i>param</i>	provides ThresholdParameter <a href="#">threshold_param</a> , with <a href="#">ThresholdLayer</a> options: <ul style="list-style-type: none"> <li>• <b>threshold</b> (<b>optional</b>, default 0). the threshold value <i>t</i> to which the input values are compared.</li> </ul>
--------------	--

### 5.100.3 Member Function Documentation

#### 5.100.3.1 Forward\_cpu()

```
template<typename Dtype >
void caffe::ThresholdLayer< Dtype >::Forward_cpu (
```

```
const vector< Blob< Dtype > *> & bottom,
const vector< Blob< Dtype > *> & top ) [protected], [virtual]
```

**Parameters**

<i>bottom</i>	input <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the inputs $x$
<i>top</i>	output <a href="#">Blob</a> vector (length 1) 1. $(N \times C \times H \times W)$ the computed outputs $y = \begin{cases} 0 & \text{if } x \leq t \\ 1 & \text{if } x > t \end{cases}$

Implements [caffe::Layer< Dtype >](#).

**5.100.3.2 LayerSetUp()**

```
template<typename Dtype >
void caffe::ThresholdLayer< Dtype >::LayerSetUp (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Does layer-specific setup: your layer should implement this function as well as Reshape.

**Parameters**

<i>bottom</i>	the preshaped input blobs, whose data fields store the input data for this layer
<i>top</i>	the allocated but unshaped output blobs

This method should do one-time layer specific setup. This includes reading and processing relevant parameters from the `layer_param_`. Setting up the shapes of top blobs and internal buffers should be done in `Reshape`, which will be called before the forward pass to adjust the top blob sizes.

Reimplemented from [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

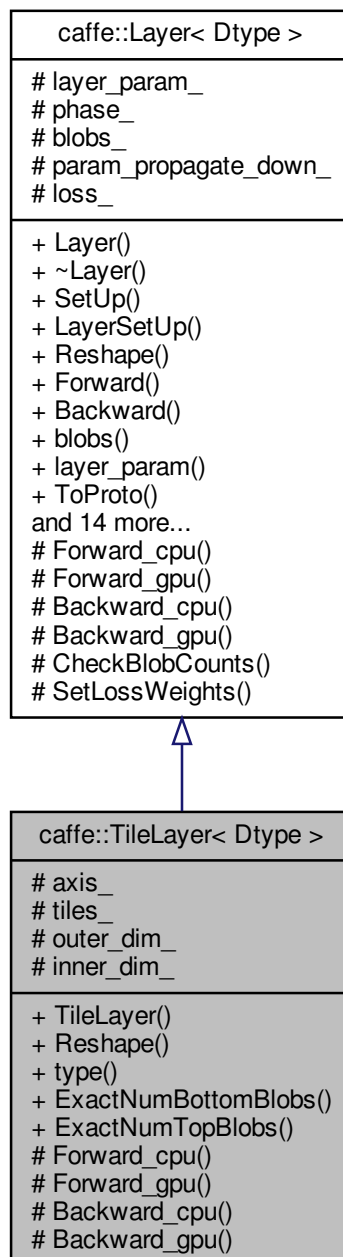
- include/caffe/layers/threshold\_layer.hpp
- src/caffe/layers/threshold\_layer.cpp

**5.101 caffe::TileLayer< Dtype > Class Template Reference**

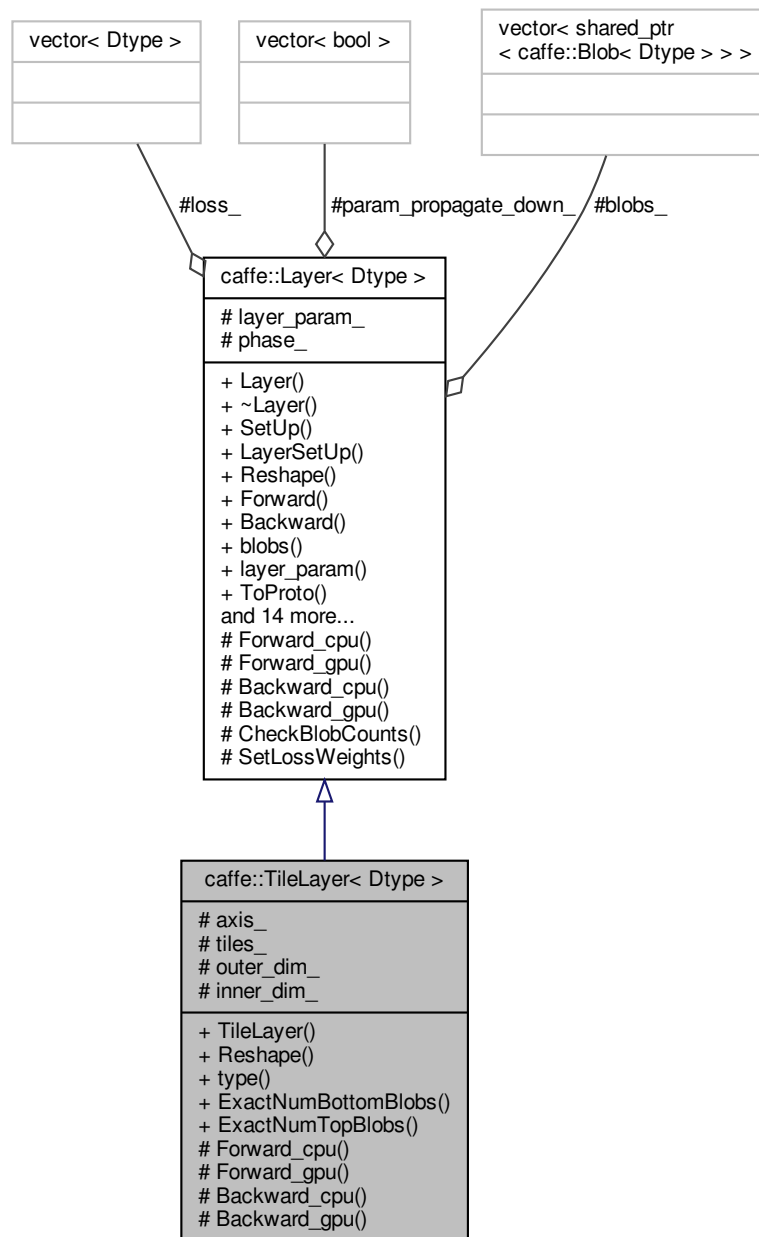
Copy a [Blob](#) along specified dimensions.

```
#include <tile_layer.hpp>
```

Inheritance diagram for `caffe::TileLayer< Dtype >`:



Collaboration diagram for caffe::TileLayer< Dtype >:



## Public Member Functions

- **TileLayer** (const LayerParameter &param)
- virtual void **Reshape** (const vector< **Blob**< Dtype > \* > &bottom, const vector< **Blob**< Dtype > \* > &top)  
*Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.*
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const

*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*

- virtual int [ExactNumTopBlobs](#) () const

*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Member Functions

- virtual void [Forward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the CPU device, compute the layer output.*

- virtual void [Forward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &bottom, const vector< [Blob](#)< Dtype > \*> &top)

*Using the GPU device, compute the layer output. Fall back to [Forward\\_cpu\(\)](#) if unavailable.*

- virtual void [Backward\\_cpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the CPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true.*

- virtual void [Backward\\_gpu](#) (const vector< [Blob](#)< Dtype > \*> &top, const vector< bool > &propagate\_down, const vector< [Blob](#)< Dtype > \*> &bottom)

*Using the GPU device, compute the gradients for any parameters and for the bottom blobs if propagate\_down is true. Fall back to [Backward\\_cpu\(\)](#) if unavailable.*

## Protected Attributes

- unsigned int **axis\_**
- unsigned int **tiles\_**
- unsigned int **outer\_dim\_**
- unsigned int **inner\_dim\_**

### 5.101.1 Detailed Description

```
template<typename Dtype>
class caffe::TileLayer< Dtype >
```

Copy a [Blob](#) along specified dimensions.

### 5.101.2 Member Function Documentation

#### 5.101.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::TileLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.101.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::TileLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

## 5.101.2.3 Reshape()

```
template<typename Dtype >
void caffe::TileLayer< Dtype >::Reshape (
    const vector< Blob< Dtype > *> & bottom,
    const vector< Blob< Dtype > *> & top ) [virtual]
```

Adjust the shapes of top blobs and internal buffers to accommodate the shapes of the bottom blobs.

## Parameters

<i>bottom</i>	the input blobs, with the requested input shapes
<i>top</i>	the top blobs, which should be reshaped as needed

This method should reshape top blobs as needed according to the shapes of the bottom (input) blobs, as well as reshaping any internal buffers and making any other necessary adjustments so that the layer can accommodate the bottom blobs.

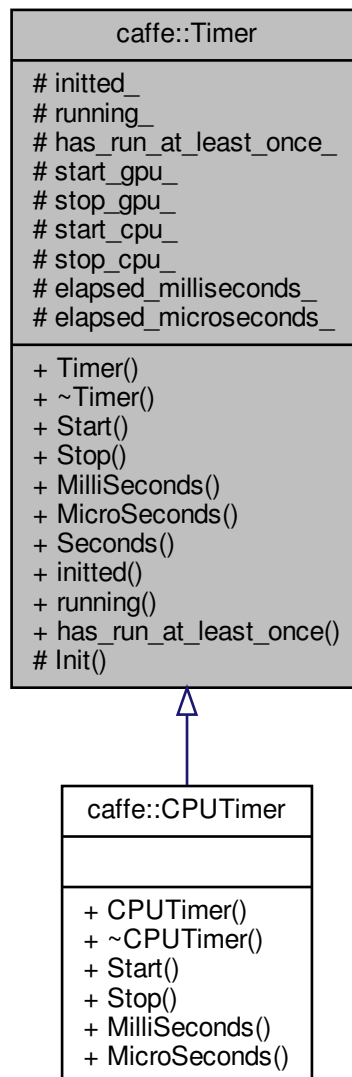
Implements [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following files:

- include/caffe/layers/tile\_layer.hpp
- src/caffe/layers/tile\_layer.cpp

## 5.102 caffe::Timer Class Reference

Inheritance diagram for caffe::Timer:





Collaboration diagram for caffe::Timer:

caffe::Timer
# initted_ # running_ # has_run_at_least_once_ # start_gpu_ # stop_gpu_ # start_cpu_ # stop_cpu_ # elapsed_milliseconds_ # elapsed_microseconds_
+ Timer() + ~Timer() + Start() + Stop() + MilliSeconds() + MicroSeconds() + Seconds() + initted() + running() + has_run_at_least_once() # Init()

### Public Member Functions

- virtual void **Start** ()
- virtual void **Stop** ()
- virtual float **MilliSeconds** ()
- virtual float **MicroSeconds** ()
- virtual float **Seconds** ()
- bool **initted** ()
- bool **running** ()
- bool **has\_run\_at\_least\_once** ()

### Protected Member Functions

- void **Init** ()

### Protected Attributes

- bool **initted\_**
- bool **running\_**
- bool **has\_run\_at\_least\_once\_**
- cudaEvent\_t **start\_gpu\_**

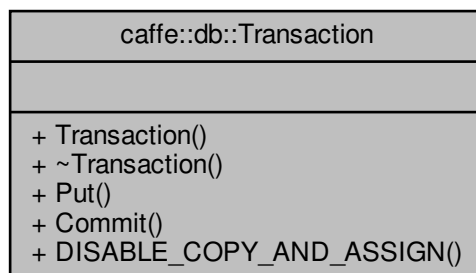
- cudaEvent\_t **stop\_gpu\_**
- boost::posix\_time::ptime **start\_cpu\_**
- boost::posix\_time::ptime **stop\_cpu\_**
- float **elapsed\_milliseconds\_**
- float **elapsed\_microseconds\_**

The documentation for this class was generated from the following files:

- include/caffe/util/benchmark.hpp
- src/caffe/util/benchmark.cpp

### 5.103 `caffe::db::Transaction` Class Reference

Collaboration diagram for `caffe::db::Transaction`:



#### Public Member Functions

- virtual void **Put** (const string &key, const string &value)=0
- virtual void **Commit** ()=0
- **DISABLE\_COPY\_AND\_ASSIGN** ([Transaction](#))

The documentation for this class was generated from the following file:

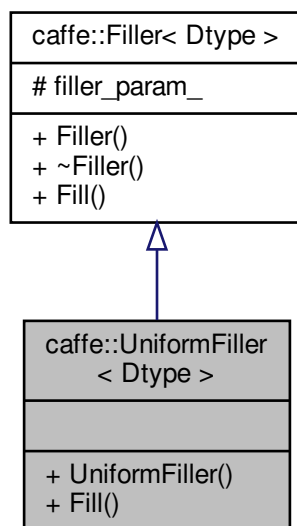
- include/caffe/util/db.hpp

## 5.104 caffe::UniformFiller< Dtype > Class Template Reference

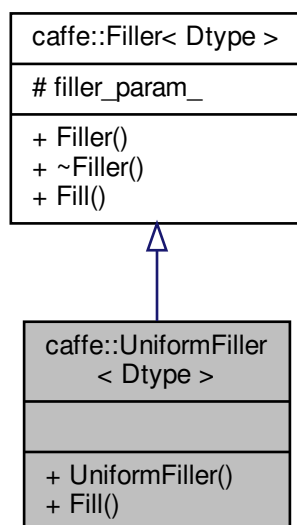
Fills a [Blob](#) with uniformly distributed values  $x \sim U(a, b)$ .

```
#include <filler.hpp>
```

Inheritance diagram for caffe::UniformFiller< Dtype >:



Collaboration diagram for caffe::UniformFiller< Dtype >:



## Public Member Functions

- **UniformFiller** (const FillerParameter &param)
- virtual void **Fill** ([Blob](#)< Dtype > \*blob)

## Additional Inherited Members

### 5.104.1 Detailed Description

```
template<typename Dtype>
class caffe::UniformFiller< Dtype >
```

Fills a [Blob](#) with uniformly distributed values  $x \sim U(a, b)$ .

The documentation for this class was generated from the following file:

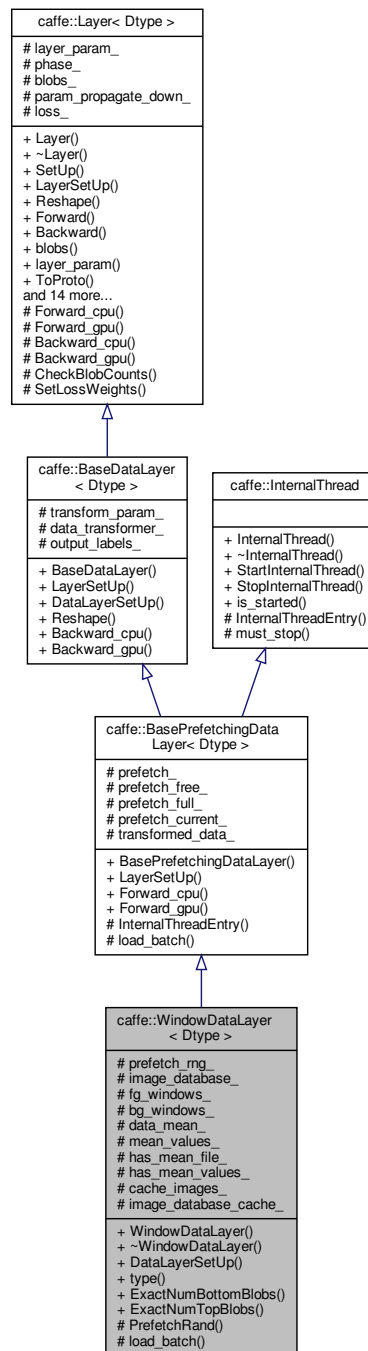
- include/caffe/filler.hpp

## 5.105 caffe::WindowDataLayer< Dtype > Class Template Reference

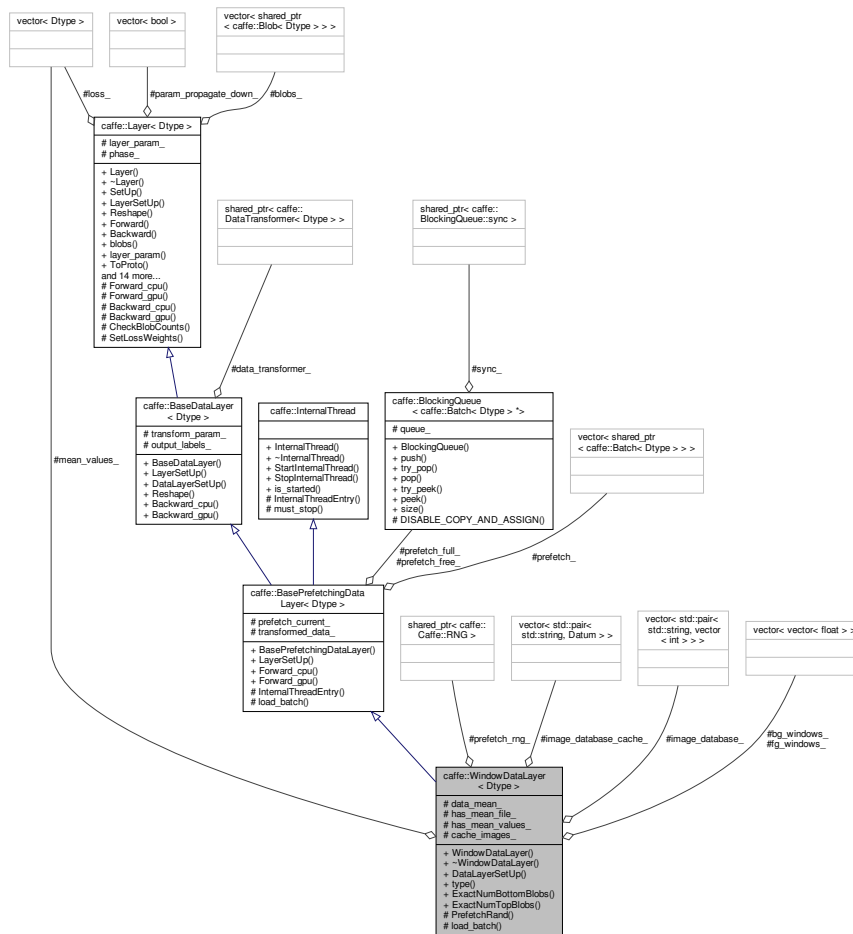
Provides data to the [Net](#) from windows of images files, specified by a window data file. This layer is *DEPRECATED* and only kept for archival purposes for use by the original R-CNN.

```
#include <window_data_layer.hpp>
```

Inheritance diagram for caffe::WindowDataLayer< Dtype >:



Collaboration diagram for `caffe::WindowDataLayer< Dtype >`:



## Public Member Functions

- **WindowDataLayer** (const LayerParameter &param)
- virtual void **DataLayerSetUp** (const vector< Blob< Dtype > \* > &bottom, const vector< Blob< Dtype > \* > &top)
- virtual const char \* **type** () const  
*Returns the layer type.*
- virtual int **ExactNumBottomBlobs** () const  
*Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.*
- virtual int **ExactNumTopBlobs** () const  
*Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.*

## Protected Types

- enum **WindowField** {  
  **IMAGE\_INDEX**, **LABEL**, **OVERLAP**, **X1**,  
  **Y1**, **X2**, **Y2**, **NUM** }

## Protected Member Functions

- virtual unsigned int **PrefetchRand** ()
- virtual void **load\_batch** ([Batch](#)< Dtype > \*batch)

## Protected Attributes

- shared\_ptr< [Caffe::RNG](#) > **prefetch\_rng\_**
- vector< std::pair< std::string, vector< int > > > **image\_database\_**
- vector< vector< float > > **fg\_windows\_**
- vector< vector< float > > **bg\_windows\_**
- [Blob](#)< Dtype > **data\_mean\_**
- vector< Dtype > **mean\_values\_**
- bool **has\_mean\_file\_**
- bool **has\_mean\_values\_**
- bool **cache\_images\_**
- vector< std::pair< std::string, Datum > > **image\_database\_cache\_**

### 5.105.1 Detailed Description

```
template<typename Dtype>
class caffe::WindowDataLayer< Dtype >
```

Provides data to the [Net](#) from windows of images files, specified by a window data file. This layer is *DEPRECATED* and only kept for archival purposes for use by the original R-CNN.

TODO(dox): thorough documentation for Forward and proto params.

### 5.105.2 Member Function Documentation

#### 5.105.2.1 ExactNumBottomBlobs()

```
template<typename Dtype >
virtual int caffe::WindowDataLayer< Dtype >::ExactNumBottomBlobs ( ) const [inline], [virtual]
```

Returns the exact number of bottom blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of bottom blobs.

Reimplemented from [caffe::Layer](#)< Dtype >.

### 5.105.2.2 ExactNumTopBlobs()

```
template<typename Dtype >
virtual int caffe::WindowDataLayer< Dtype >::ExactNumTopBlobs ( ) const [inline], [virtual]
```

Returns the exact number of top blobs required by the layer, or -1 if no exact number is required.

This method should be overridden to return a non-negative value if your layer expects some exact number of top blobs.

Reimplemented from [caffe::Layer< Dtype >](#).

The documentation for this class was generated from the following file:

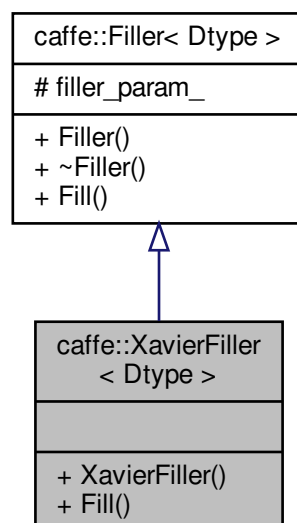
- include/caffe/layers/window\_data\_layer.hpp

## 5.106 caffe::XavierFiller< Dtype > Class Template Reference

Fills a [Blob](#) with values  $x \sim U(-a, +a)$  where  $a$  is set inversely proportional to number of incoming nodes, outgoing nodes, or their average.

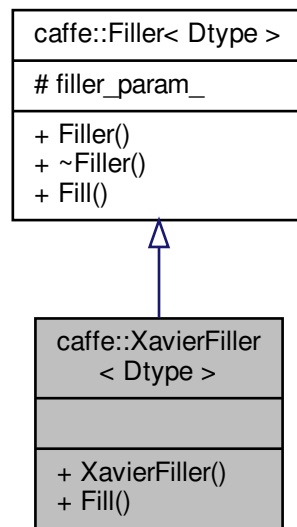
```
#include <filler.hpp>
```

Inheritance diagram for `caffe::XavierFiller< Dtype >`:





Collaboration diagram for caffe::XavierFiller< Dtype >:



## Public Member Functions

- **XavierFiller** (const FillerParameter &param)
- virtual void **Fill** ([Blob](#)< Dtype > \*blob)

## Additional Inherited Members

### 5.106.1 Detailed Description

```
template<typename Dtype>
class caffe::XavierFiller< Dtype >
```

Fills a [Blob](#) with values  $x \sim U(-a, +a)$  where  $a$  is set inversely proportional to number of incoming nodes, outgoing nodes, or their average.

A [Filler](#) based on the paper [Bengio and Glorot 2010]: Understanding the difficulty of training deep feedforward neuralnetworks.

It fills the incoming matrix by randomly sampling uniform data from  $[-scale, scale]$  where  $scale = \sqrt{3 / n}$  where  $n$  is the fan\_in, fan\_out, or their average, depending on the variance\_norm option. You should make sure the input blob has shape (num, a, b, c) where  $a * b * c = fan\_in$  and  $num * b * c = fan\_out$ . Note that this is currently not the case for inner product layers.

TODO(dox): make notation in above comment consistent with rest & use LaTeX.

The documentation for this class was generated from the following file:

- include/caffe/filler.hpp



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