Linear Models for Supervised Learning

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Discriminative Model and Generative Model

Discriminative model

- modeling the dependence of unobserved variables on observed ones
- also called conditional models.
- Deterministic: $y = f_{\theta}(x)$
- Probabilistic: $p_{\theta}(y|x)$

Generative model

- modeling the joint probabilistic distribution of data
- given some hidden parameters or variables

$$p_{\theta}(x,y)$$

then do the conditional inference

$$p_{\theta}(y|x) = \frac{p_{\theta}(x,y)}{p_{\theta}(x)} = \frac{p_{\theta}(x,y)}{\sum_{y'} p_{\theta}(x,y')}$$

Discriminative Model and Generative Model

Discriminative model

- modeling the dependence of unobserved variables on observed ones
- also called conditional models.
- Deterministic: $y = f_{\theta}(x)$
- Probabilistic: $p_{\theta}(y|x)$
- Directly model the dependence for label prediction
- Easy to define dependence specific features and models
- Practically yielding higher prediction performance
- Linear regression, logistic regression, k nearest neighbor, SVMs, (multi-layer) perceptrons, decision trees, random forest etc.

Discriminative Model and Generative Model

Generative model

- modeling the joint probabilistic distribution of data
- given some hidden parameters or variables

$$p_{\theta}(x,y)$$

then do the conditional inference

$$p_{\theta}(y|x) = \frac{p_{\theta}(x,y)}{p_{\theta}(x)} = \frac{p_{\theta}(x,y)}{\sum_{y'} p_{\theta}(x,y')}$$

- Recover the data distribution [essence of data science]
- Benefit from hidden variables modeling
- Naive Bayes, Hidden Markov Model, Mixture Gaussian, Markov Random Fields, Latent Dirichlet Allocation etc.

Linear Regression

Linear Discriminative Models

- Discriminative model
 - modeling the dependence of unobserved variables on observed ones
 - also called conditional models.
 - Deterministic: $y = f_{\theta}(x)$
 - Probabilistic: $p_{\theta}(y|x)$
- Focus of this course
 - Linear regression model
 - Linear classification model

Linear Discriminative Models

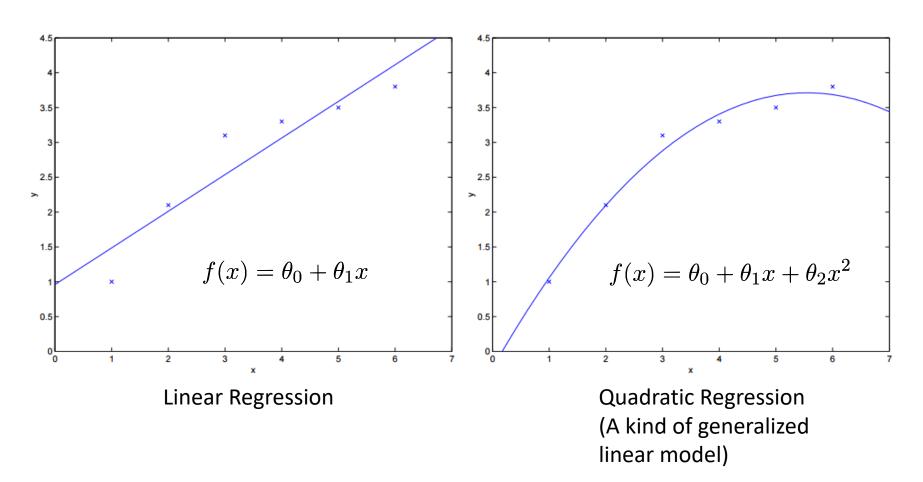
- Discriminative model
 - modeling the dependence of unobserved variables on observed ones
 - also called conditional models.
 - Deterministic: $y = f_{\theta}(x)$
 - Probabilistic: $p_{\theta}(y|x)$
- Linear regression model

$$y = f_{\theta}(x) = \theta_0 + \sum_{j=1}^{d} \theta_j x_j = \theta^{\top} x$$

 $x = (1, x_1, x_2, \dots, x_d)$

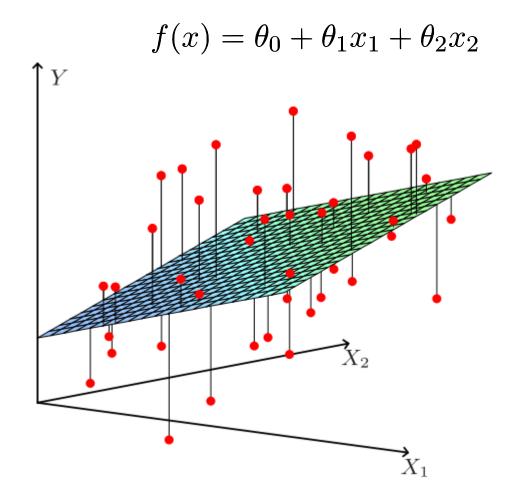
Linear Regression

One-dimensional linear & quadratic regression



Linear Regression

Two-dimensional linear regression



Learning Objective

• Make the prediction close to the corresponding label N

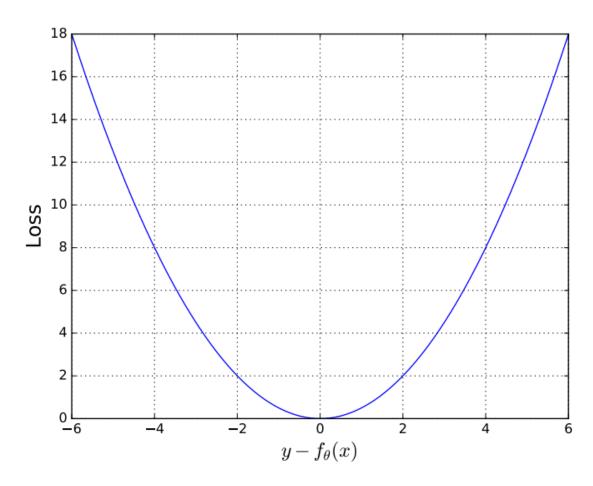
$$\min_{\theta} \frac{1}{N} \sum_{i=1}^{N} \mathcal{L}(y_i, f_{\theta}(x_i))$$

- Loss function $\mathcal{L}(y_i, f_{\theta}(x_i))$ measures the error between the label and prediction
- The definition of loss function depends on the data and task
- Most popular loss function: squared loss

$$\mathcal{L}(y_i, f_{\theta}(x_i)) = (y_i - f_{\theta}(x_i))^2$$

Squared Loss

$$\mathcal{L}(y_i, f_{\theta}(x_i)) = \frac{1}{2}(y_i - f_{\theta}(x_i))^2$$



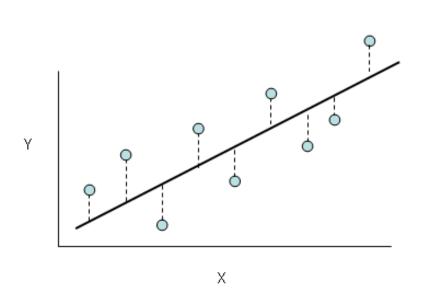
 Penalty much more on larger distances

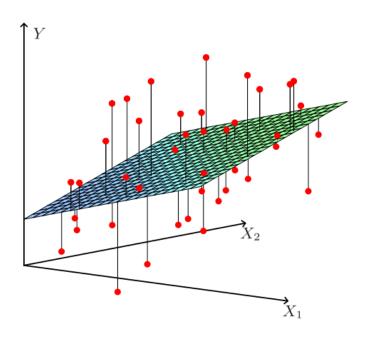
- Accept small distance (error)
 - Observation noise etc.
 - Generalization

Least Square Linear Regression

Objective function to minimize

$$J_{\theta} = \frac{1}{2N} \sum_{i=1}^{N} (y_i - f_{\theta}(x_i))^2 \qquad \min_{\theta} J_{\theta}$$

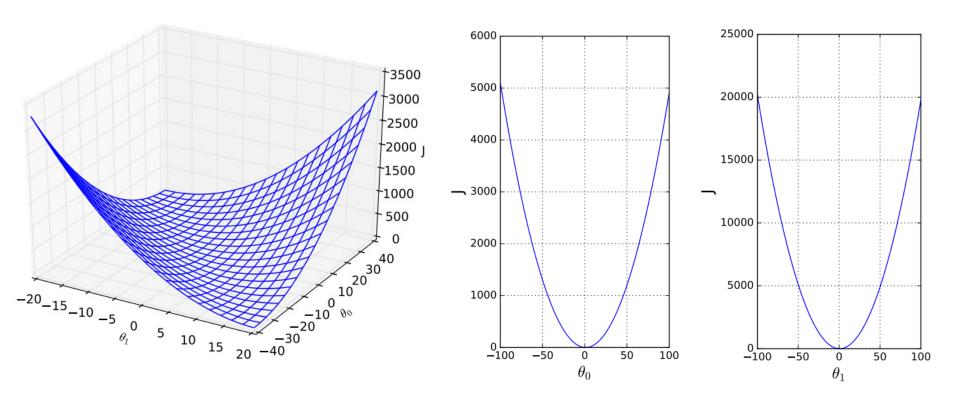




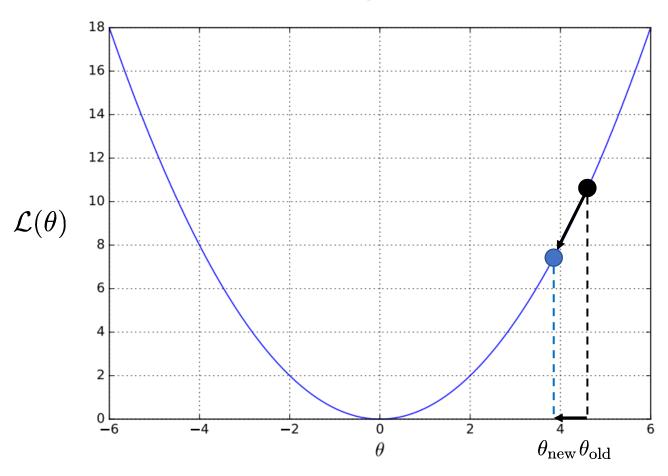
Minimize the Objective Function

• Let N=1 for a simple case, for (x,y)=(2,1)

$$J(\theta) = \frac{1}{2}(y - \theta_0 - \theta_1 x)^2 = \frac{1}{2}(1 - \theta_0 - 2\theta_1)^2$$



Gradient Learning Methods



$$\theta_{\text{new}} \leftarrow \theta_{\text{old}} - \eta \frac{\partial \mathcal{L}(\theta)}{\partial \theta}$$

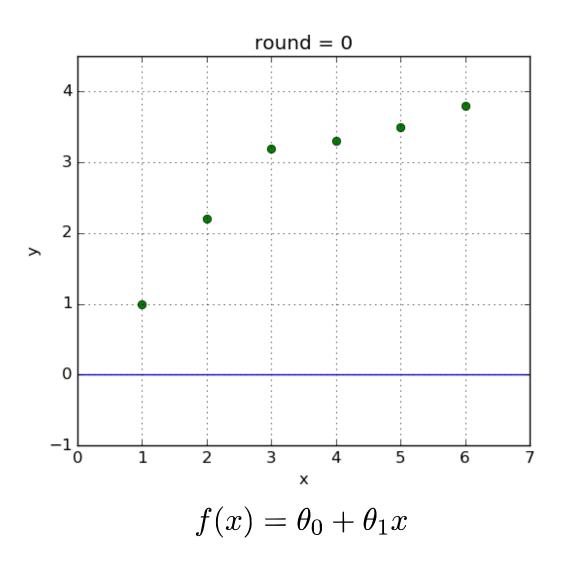
Batch Gradient Descent

$$J(\theta) = \frac{1}{2N} \sum_{i=1}^{N} (y_i - f_{\theta}(x_i))^2 \qquad \min_{\theta} J(\theta)$$

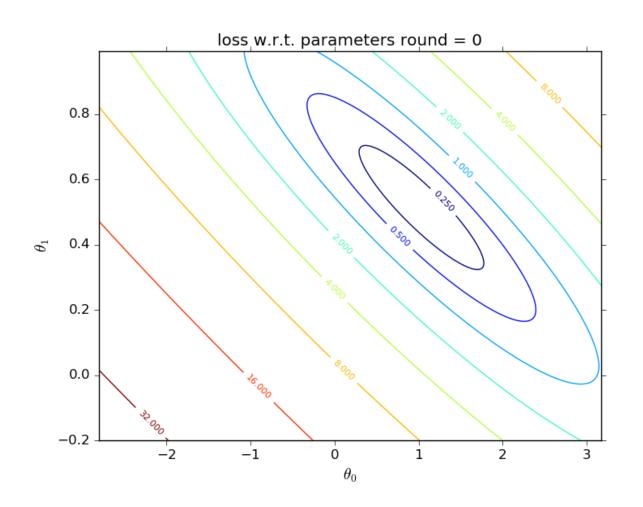
• Update $\theta_{\text{new}} \leftarrow \theta_{\text{old}} - \eta \frac{\partial J(\theta)}{\partial \theta}$ for the whole batch

$$\frac{\partial J(\theta)}{\partial \theta} = -\frac{1}{N} \sum_{i=1}^{N} (y_i - f_{\theta}(x_i)) \frac{\partial f_{\theta}(x_i)}{\partial \theta}$$
$$= -\frac{1}{N} \sum_{i=1}^{N} (y_i - f_{\theta}(x_i)) x_i$$
$$\theta_{\text{new}} = \theta_{\text{old}} + \eta \frac{1}{N} \sum_{i=1}^{N} (y_i - f_{\theta}(x_i)) x_i$$

Learning Linear Model - Curve



Learning Linear Model - Weights



Stochastic Gradient Descent

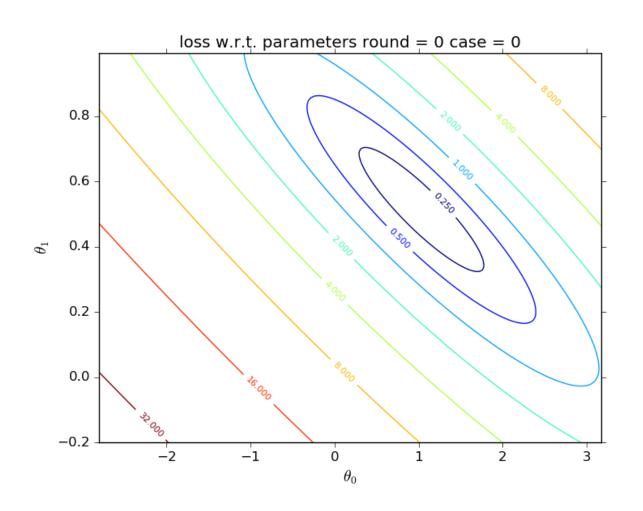
$$J^{(i)}(\theta) = \frac{1}{2} (y_i - f_{\theta}(x_i))^2 \qquad \min_{\theta} \frac{1}{N} \sum_{i} J^{(i)}(\theta)$$

• Update $\, heta_{
m new} = heta_{
m old} - \eta rac{\partial J^{(i)}(heta)}{\partial heta} \,$ for every single instance

$$\frac{\partial J^{(i)}(\theta)}{\partial \theta} = -(y_i - f_{\theta}(x_i)) \frac{\partial f_{\theta}(x_i)}{\partial \theta}$$
$$= -(y_i - f_{\theta}(x_i)) x_i$$
$$\theta_{\text{new}} = \theta_{\text{old}} + \eta (y_i - f_{\theta}(x_i)) x_i$$

- Compare with BGD
 - Faster learning
 - Uncertainty or fluctuation in learning

Linear Classification Model



Mini-Batch Gradient Descent

- A combination of batch GD and stochastic GD
- Split the whole dataset into K mini-batches

$$\{1, 2, 3, \dots, K\}$$

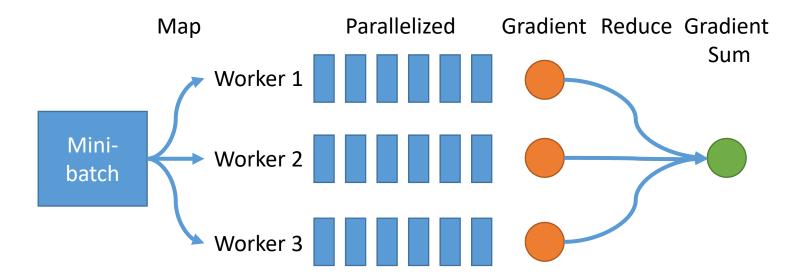
For each mini-batch k, perform one-step BGD toward minimizing

$$J^{(k)}(\theta) = \frac{1}{2N_k} \sum_{i=1}^{N_k} (y_i - f_{\theta}(x_i))^2$$

• Update $heta_{
m new} = heta_{
m old} - \eta rac{\partial J^{(k)}(heta)}{\partial heta}$ for each mini-batch

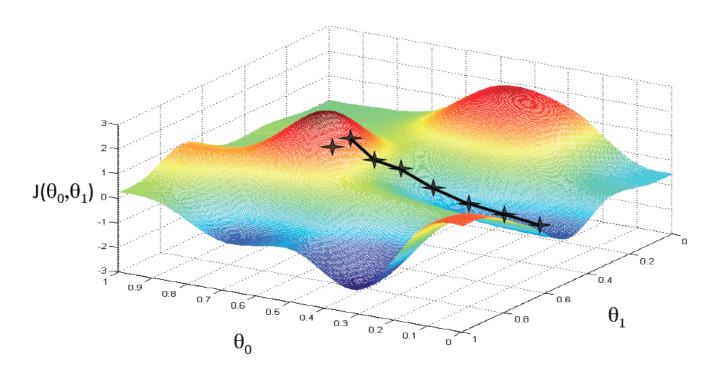
Mini-Batch Gradient Descent

- Good learning stability (BGD)
- Good convergence rate (SGD)
- Easy to be parallelized
 - Parallelization within a mini-batch



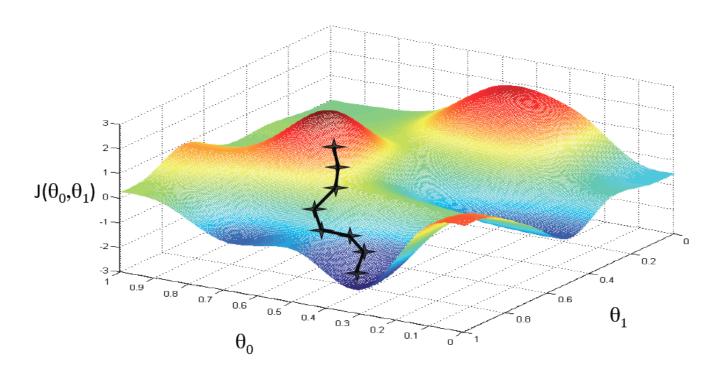
Basic Search Procedure

- Choose an initial value for θ
- ullet Update heta iteratively with the data
- Until we research a minimum

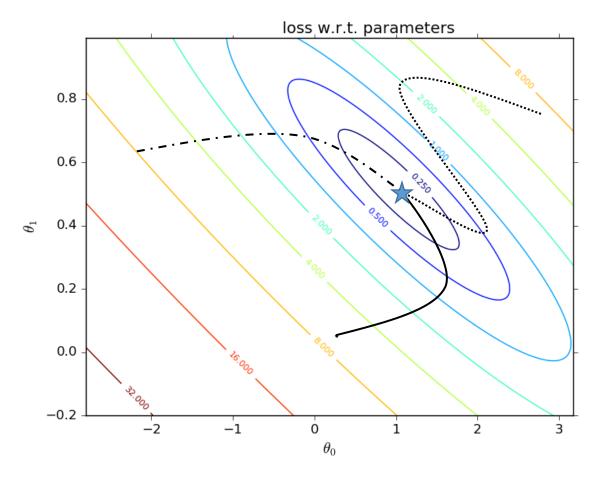


Basic Search Procedure

- Choose a new initial value for θ
- ullet Update heta iteratively with the data
- Until we research a minimum



Unique Minimum for Convex Objective

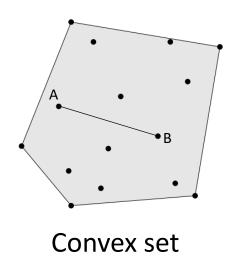


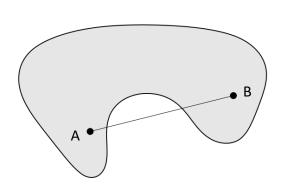
 Different initial parameters and different learning algorithm lead to the same optimum

Convex Set

 A convex set S is a set of points such that, given any two points A, B in that set, the line AB joining them lies entirely within S.

$$tx_1 + (1-t)x_2 \in S$$
 for all $x_1, x_2 \in S, 0 \le t \le 1$

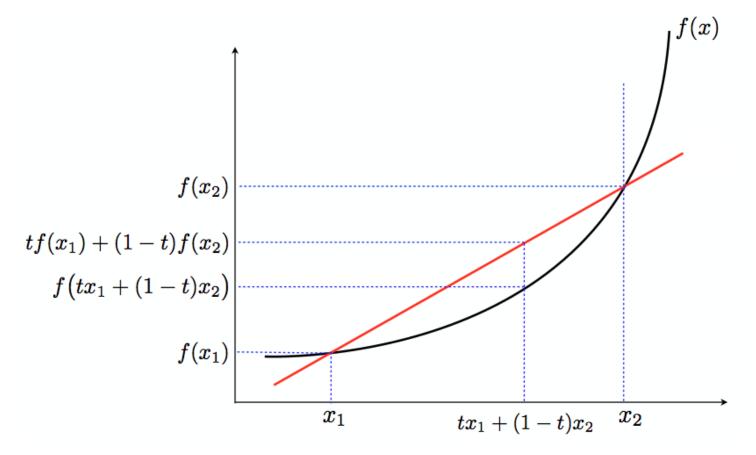




Non-convex set

[Boyd, Stephen, and Lieven Vandenberghe. Convex optimization. Cambridge university press, 2004.]

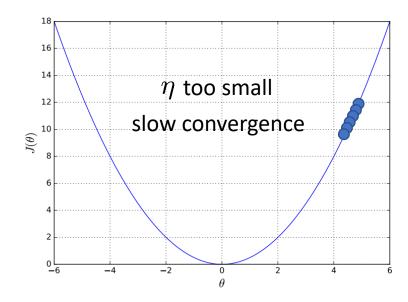
Convex Function

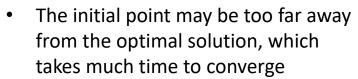


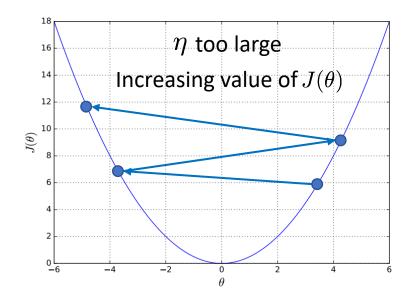
 $f:\mathbb{R}^n \to \mathbb{R}$ is convex if $\operatorname{\mathbf{dom}} f$ is a convex set and $f(tx_1+(1-t)x_2) \leq tf(x_1)+(1-t)f(x_2)$ for all $x_1,x_2 \in \operatorname{\mathbf{dom}} f, 0 \leq t \leq 1$

Choosing Learning Rate

$$\theta_{\text{new}} = \theta_{\text{old}} - \eta \frac{\partial J(\theta)}{\partial \theta}$$







- May overshoot the minimum
- May fail to converge
- May even diverge
- To see if gradient descent is working, print out $J(\theta)$ for each or every several iterations. If $J(\theta)$ does not drop properly, adjust η

Algebra Perspective

$$m{X} = egin{bmatrix} m{x}^{(1)} \ m{x}^{(2)} \ m{x}^{(2)} \end{bmatrix} = egin{bmatrix} x_1^{(1)} & x_2^{(1)} & x_3^{(1)} & \dots & x_d^{(1)} \ x_1^{(2)} & x_2^{(2)} & x_3^{(2)} & \dots & x_d^{(2)} \ m{\vdots} & m{\vdots} & m{\ddots} & m{\vdots} \ x_1^{(n)} & x_2^{(n)} & x_3^{(n)} & \dots & x_d^{(n)} \end{bmatrix} \quad m{ heta} = egin{bmatrix} heta_1 \ heta_2 \ m{\vdots} \ heta_d \end{bmatrix} \quad m{y} = egin{bmatrix} y_1 \ y_2 \ m{\vdots} \ y_n \end{bmatrix}$$

• Prediction
$$\hat{m{y}} = m{X}m{ heta} = egin{bmatrix} m{x}^{(1)}m{ heta} \\ m{x}^{(2)}m{ heta} \\ \vdots \\ m{x}^{(n)}m{ heta} \end{bmatrix}$$

• Objective
$$J(\boldsymbol{\theta}) = \frac{1}{2}(\boldsymbol{y} - \hat{\boldsymbol{y}})^{\top}(\boldsymbol{y} - \hat{\boldsymbol{y}}) = \frac{1}{2}(\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta})^{\top}(\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta})$$

Matrix Form

Objective

$$J(\boldsymbol{\theta}) = \frac{1}{2} (\boldsymbol{y} - \boldsymbol{X} \boldsymbol{\theta})^{\top} (\boldsymbol{y} - \boldsymbol{X} \boldsymbol{\theta}) \quad \min_{\boldsymbol{\theta}} J(\boldsymbol{\theta})$$

Gradient

$$\frac{\partial J(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = -\boldsymbol{X}^{\top}(\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta})$$

$$egin{aligned} ullet & \operatorname{Solution} & rac{\partial J(oldsymbol{ heta})}{\partial oldsymbol{ heta}} = oldsymbol{0} & \Rightarrow & oldsymbol{X}^ op (oldsymbol{y} - oldsymbol{X} oldsymbol{ heta}) = oldsymbol{0} \ & \Rightarrow & oldsymbol{X}^ op oldsymbol{y} = oldsymbol{X}^ op oldsymbol{X} oldsymbol{0} \ & \Rightarrow & \hat{oldsymbol{ heta}} = (oldsymbol{X}^ op oldsymbol{X})^{-1} oldsymbol{X}^ op oldsymbol{y} \ & \Rightarrow & \hat{oldsymbol{ heta}} = (oldsymbol{X}^ op oldsymbol{X})^{-1} oldsymbol{X}^ op oldsymbol{y} \ \end{pmatrix}$$

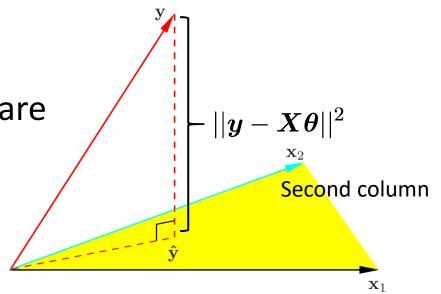
Matrix Form

Then the predicted values are

$$\hat{m{y}} = m{X} (m{X}^{ op} m{X})^{-1} m{X}^{ op} m{y}$$

$$= m{H} m{y}$$

H: hat matrix



First column

- Geometrical Explanation
 - The column vectors $[\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_d]$ form a subspace of \mathbb{R}^n
 - H is a least square projection

$$m{X} = egin{bmatrix} x_1^{(1)} & x_2^{(1)} & x_3^{(1)} & \dots & x_d^{(1)} \ x_1^{(2)} & x_2^{(2)} & x_3^{(2)} & \dots & x_d^{(2)} \ dots & dots & dots & dots & dots \ x_1^{(n)} & x_2^{(n)} & x_3^{(n)} & \dots & x_d^{(n)} \end{bmatrix} = [\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_d] \quad m{y} = egin{bmatrix} y_1 \ y_2 \ dots \ y_n \end{bmatrix}$$

More details refer to Sec 3.2. Hastie et al. The elements of statistical learning.

$oldsymbol{X}^{ op}oldsymbol{X}$ Might be Singular

- When some column vectors are not independent
 - For example, $\mathbf{x}_2 = 3\mathbf{x}_1$

then $\boldsymbol{X}^{\top}\boldsymbol{X}$ is singular, thus $\hat{\boldsymbol{\theta}} = (\boldsymbol{X}^{\top}\boldsymbol{X})^{-1}\boldsymbol{X}^{\top}\boldsymbol{y}$ cannot be directly calculated.

Solution: regularization

$$J(\boldsymbol{\theta}) = \frac{1}{2} (\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta})^{\top} (\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta}) + \frac{\lambda}{2} ||\boldsymbol{\theta}||_{2}^{2}$$

Matrix Form with Regularization

Objective

$$J(\boldsymbol{\theta}) = \frac{1}{2} (\boldsymbol{y} - \boldsymbol{X} \boldsymbol{\theta})^{\top} (\boldsymbol{y} - \boldsymbol{X} \boldsymbol{\theta}) + \frac{\lambda}{2} ||\boldsymbol{\theta}||_2^2 \quad \min_{\boldsymbol{\theta}} J(\boldsymbol{\theta})$$

Gradient

$$\frac{\partial J(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = -\boldsymbol{X}^{\top}(\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta}) + \lambda \boldsymbol{\theta}$$

Solution

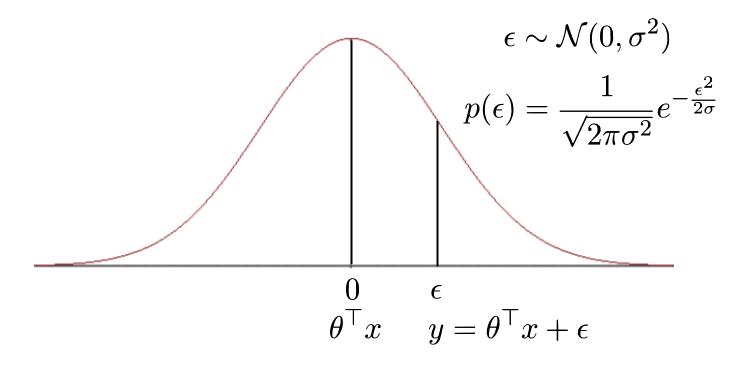
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Linear Discriminative Models

- Discriminative model
 - modeling the dependence of unobserved variables on observed ones
 - also called conditional models.
 - Deterministic: $y = f_{\theta}(x)$
 - Probabilistic: $p_{\theta}(y|x)$
- Linear regression with Gaussian noise model

$$y = f_{\theta}(x) + \epsilon = \theta_0 + \sum_{j=1}^{d} \theta_j x_j + \epsilon = \theta^{\top} x + \epsilon$$
$$\epsilon \sim \mathcal{N}(0, \sigma^2)$$
$$x = (1, x_1, x_2, \dots, x_d)$$

Objective: Likelihood



Data likelihood

$$p(y|x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y-\theta^\top x)^2}{2\sigma}}$$

Learning

Maximize the data likelihood

$$\max_{\theta} \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - \theta^\top x_i)^2}{2\sigma}}$$

Maximize the data log-likelihood

$$\log \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - \theta^{\top} x_i)^2}{2\sigma}} = \sum_{i=1}^{N} \log \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - \theta^{\top} x_i)^2}{2\sigma}}$$
$$= -\sum_{i=1}^{N} \frac{(y_i - \theta^{\top} x_i)^2}{2\sigma} + \text{const}$$

$$\min_{\theta} \sum_{i=1}^{N} (y_i - \theta^{\top} x_i)^2$$
 Equivalent to least square error learning

Linear Classification

Classification Problem

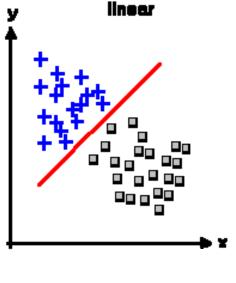
Given:

- A description of an instance, $x \in \mathbb{X}$, where \mathbb{X} is the instance space.
- A fixed set of categories: $C = \{c_1, c_2, \dots, c_m\}$

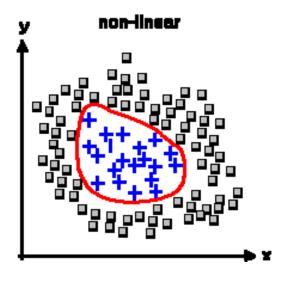
• Determine:

- The category of x : $f(x) \in C$, where f(x) is a categorization function whose domain is $\mathbb X$ and whose range is C
- If the category set binary, i.e. $C = \{0,1\}$ ({false, true}, {negative, positive}) then it is called binary classification.

Binary Classification



Linearly inseparable



Non-linearly inseparable

Linear Discriminative Models

- Discriminative model
 - modeling the dependence of unobserved variables on observed ones
 - also called conditional models.
 - Deterministic: $y = f_{\theta}(x)$
 - Non-differentiable
 - Probabilistic: $p_{\theta}(y|x)$
 - Differentiable
- For binary classification

$$p_{\theta}(y = 1|x)$$

 $p_{\theta}(y = 0|x) = 1 - p_{\theta}(y = 1|x)$

Loss Function

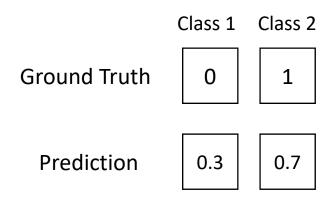
Cross entropy loss

Discrete case:
$$H(p,q) = -\sum_x p(x) \log q(x)$$
 Continuous case:
$$H(p,q) = -\int_x p(x) \log q(x) dx$$

For classification problem

Ground Truth
$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 \end{bmatrix}$$
 Prediction $\begin{bmatrix} 0.1 & 0.6 & 0.05 & 0.05 & 0.05 \end{bmatrix}$ $\begin{bmatrix} 0.05 & 0.05 & 0.05 & 0.2 \end{bmatrix}$ $\mathcal{L}(y,x,p_{\theta})=-\sum_k \delta(y=c_k)\log p_{\theta}(y=c_k|x)$ $\delta(z)=\begin{cases} 1, & z \text{ is true} \\ 0, & \text{otherwise} \end{cases}$

Cross Entropy for Binary Classification



Loss function

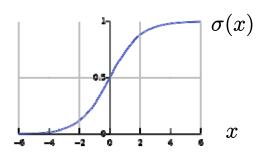
$$\mathcal{L}(y, x, p_{\theta}) = -\delta(y = 1) \log p_{\theta}(y = 1|x) - \delta(y = 0) \log p_{\theta}(y = 0|x)$$
$$= -y \log p_{\theta}(y = 1|x) - (1 - y) \log(1 - p_{\theta}(y = 1|x))$$

Logistic Regression

Logistic regression is a binary classification model

$$p_{\theta}(y = 1|x) = \sigma(\theta^{\top}x) = \frac{1}{1 + e^{-\theta^{\top}x}}$$

$$p_{\theta}(y = 0|x) = \frac{e^{-\theta^{\top}x}}{1 + e^{-\theta^{\top}x}}$$



Cross entropy loss function

$$\mathcal{L}(y, x, p_{\theta}) = -y \log \sigma(\theta^{\top} x) - (1 - y) \log(1 - \sigma(\theta^{\top} x))$$

Gradient

$$\frac{\partial \mathcal{L}(y, x, p_{\theta})}{\partial \theta} = -y \frac{1}{\sigma(\theta^{\top} x)} \sigma(z) (1 - \sigma(z)) x - (1 - y) \frac{-1}{1 - \sigma(\theta^{\top} x)} \sigma(z) (1 - \sigma(z)) x$$

$$= (\sigma(\theta^{\top} x) - y) x$$

$$\theta \leftarrow \theta + \eta(y - \sigma(\theta^{\top} x)) x$$

$$\frac{\partial \sigma(z)}{\partial z} = \sigma(z) (1 - \sigma(z))$$

Label Decision

Logistic regression provides the probability

$$p_{\theta}(y = 1|x) = \sigma(\theta^{\top}x) = \frac{1}{1 + e^{-\theta^{\top}x}}$$

$$p_{\theta}(y = 0|x) = \frac{e^{-\theta^{\top}x}}{1 + e^{-\theta^{\top}x}}$$

• The final label of an instance is decided by setting a threshold \boldsymbol{h}

$$\hat{y} = \begin{cases} 1, & p_{\theta}(y = 1|x) > h \\ 0, & \text{otherwise} \end{cases}$$

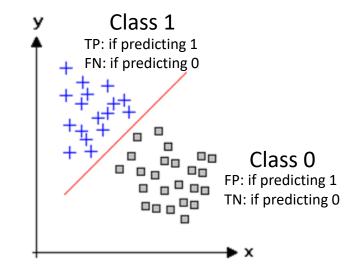
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PPP	iction
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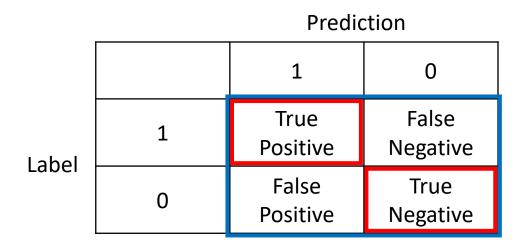
Label

	1	0
1	True Positive	False Negative
0	False Positive	True Negative

• True / False

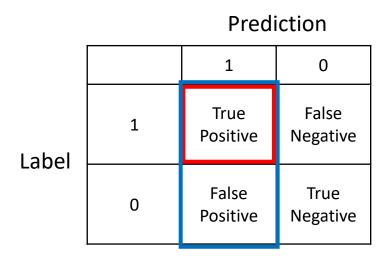
- True: prediction = label
- False: prediction ≠ label
- Positive / Negative
 - Positive: predict y = 1
 - Negative: predict y = 0





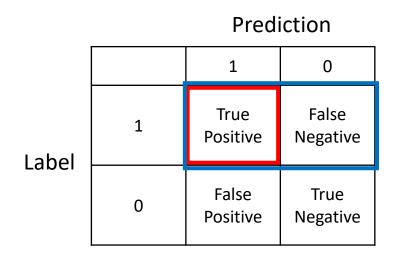
Accuracy: the ratio of cases when prediction = label

$$Acc = \frac{TP + TN}{TP + TN + FP + FN}$$



 Precision: the ratio of true class 1 cases in those with prediction 1

$$Prec = \frac{TP}{TP + FP}$$



• **Recall**: the ratio of cases with prediction 1 in all true class 1 cases

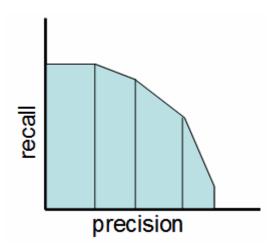
$$Rec = \frac{TP}{TP + FN}$$

Precision-recall tradeoff

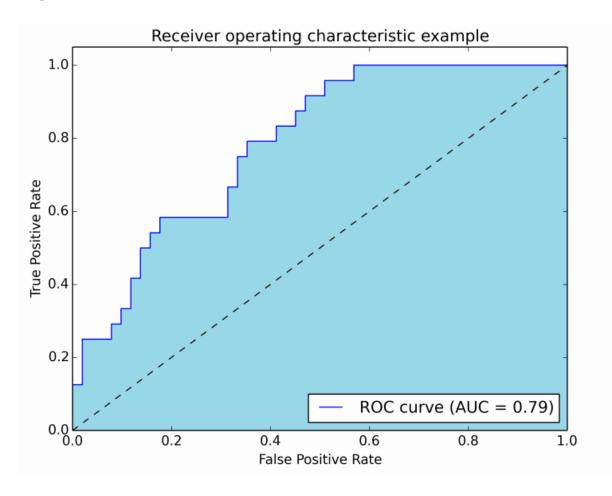
$$\hat{y} = \begin{cases} 1, & p_{\theta}(y=1|x) > h \\ 0, & \text{otherwise} \end{cases}$$

- Higher threshold, higher precision, lower recall
 - Extreme case: threshold = 0.99
- Lower threshold, lower precision, higher recall
 - Extreme case: threshold = 0
- F1 Measure

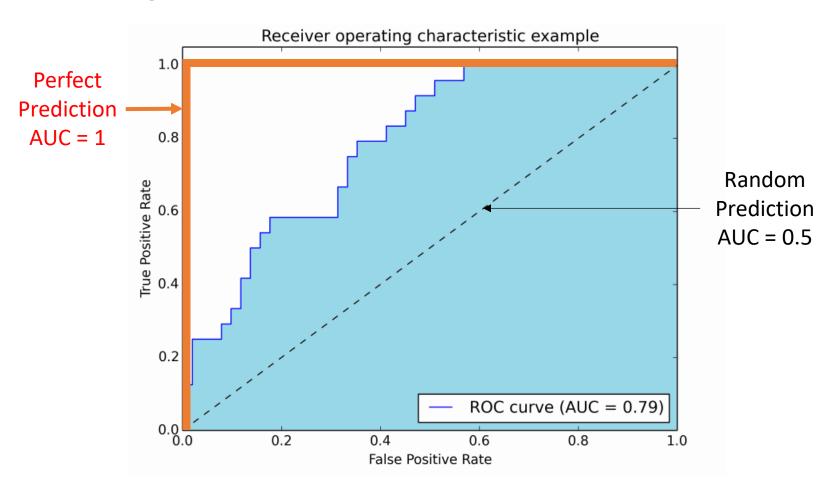
$$F1 = \frac{2 \times Prec \times Recall}{Prec + Rec}$$



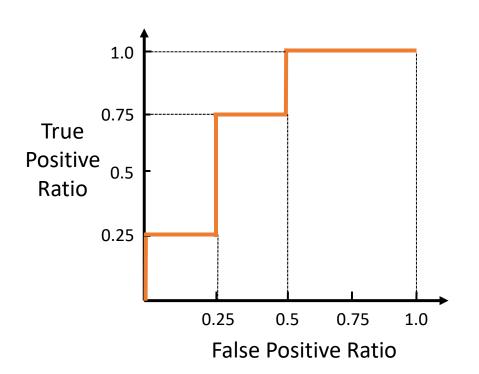
Ranking-based measure: Area Under ROC Curve (AUC)



Ranking-based measure: Area Under ROC Curve (AUC)



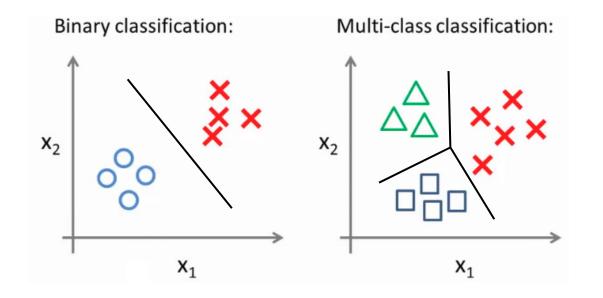
A simple example of Area Under ROC Curve (AUC)



Prediction	Label
0.91	1
0.85	0
0.77	1
0.72	1
0.61	0
0.48	1
0.42	0
0.33	0

AUC = 0.75

Multi-Class Classification



Still cross entropy loss

Ground Truth

0

1

0

Prediction

0.1

0.7

0.2

$$\mathcal{L}(y, x, p_{\theta}) = -\sum_{k} \delta(y = c_{k}) \log p_{\theta}(y = c_{k}|x) \qquad \delta(z) = \begin{cases} 1, & z \text{ is true} \\ 0, & \text{otherwise} \end{cases}$$

Multi-Class Logistic Regression

• Class set $C = \{c_1, c_2, \dots, c_m\}$

• Predicting the probability of $p_{\theta}(y=c_j|x)$

$$p_{\theta}(y = c_j | x) = \frac{e^{\theta_j^{\top} x}}{\sum_{k=1}^{m} e^{\theta_j^{\top} x}} \quad \text{for } j = 1, \dots, m$$

- Softmax
 - Parameters $\theta = \{\theta_1, \theta_2, \dots, \theta_m\}$
 - Can be normalized with m-1 groups of parameters

Multi-Class Logistic Regression

- Learning on one instance $(x, y = c_j)$
 - Maximize log-likelihood

$$\max_{\theta} \log p_{\theta}(y = c_j | x)$$

Gradient

$$\frac{\partial p_{\theta}(y = c_{j}|x)}{\partial \theta_{j}} = \frac{\partial}{\partial \theta_{j}} \log \frac{e^{\theta_{j}^{\top}x}}{\sum_{k=1}^{m} e^{\theta_{k}^{\top}x}}$$

$$= x - \frac{\partial}{\partial \theta_{j}} \log \sum_{k=1}^{m} e^{\theta_{k}^{\top}x}$$

$$= x - \frac{e^{\theta_{j}^{\top}x}x}{\sum_{k=1}^{m} e^{\theta_{k}^{\top}x}}$$

Application Case Study

Click-Through Rate (CTR) Estimation in Online Advertising

Ad Click-Through Rate Estimation

大陆



河南省公安厅彻查"封丘36人入警 35人身份不合规"

中封丘县公安局的38名受训人员,35人是公安局内部的文职或临时人员, 与"民警必须具备公务员身份"的国家规定不符,引发该局内部

- 上海至成都沿江高铁提上日程 串联长江沿线22城市
- 2016号歼-20原型机曝光 已滑行测试(图)
- 日媒:中国或派万吨海警船巡钓鱼岛 打消耗战
- 外媒: 中国开始研制隐身武装直升机 预计2020年交付
- 习近平关于中美关系的十个判断
- 住建部黑臭水沟整治工作指南:9成百姓满意才能达标
- 陕西: 职校"校长"让女学生陪酒 学校被撤除
- 揭秘"团团伙伙"的武钢漩涡和落马高管

国际



巴塞罗那200万人游行 呼吁加泰罗尼亚独立(图)

• 李炜光: 收税是不公平的恶?

• 许章润: 超级大国没有纯粹内政

刘昀献:国外政党联系群众的路 径研究

时局观



民革中央副主席:中 共从未否定国民党抗 战作用

- 施芝鸿:文革基础上搞改革致一个时期市场官场乱象
- 朱维群回应争议:尊重民族差异 而不强化。
- 伊协副会长:穆斯林不应因宗教 功修忽视社会责任

领袖圈



奥巴马54岁啦,当7年 总统人苍老了头发也

Click or not?



海绵城市 未来之城 水危机: 青岛告急 探访中国绿化博览会 帝都吸引华人首富 凤凰房产 诚邀加盟 谈华山论剑与中国精神 黑龙江创新驱动三步棋 《印记》之江城夜未眠 办公环境搜查令 屬层生活尽在凤凰会

精彩视频

凤凰联播台



菲媒曝菲律宾军演针对中 国 直指南海生命线

播放数: 2602282

User response estimation problem

Problem definition

One instance data

Date: 20160320

Hour: 14Weekday: 7

IP: 119.163.222.*Region: England

• City: London

Country: UK

Ad Exchange: GoogleDomain: yahoo.co.uk

• URL: http://www.yahoo.co.uk/abc/xyz.html

OS: Windows

Browser: ChromeAd size: 300*250

Ad ID: a1890

User occupation: Student User tags: Sports, Electronics

Corresponding label

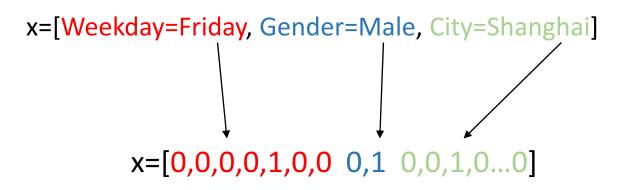


Click (1) or not (0)?

Predicted CTR (0.15)

One-Hot Binary Encoding

A standard feature engineering paradigm



Sparse representation: x=[5:1 9:1 12:1]

- High dimensional sparse binary feature vector
 - Usually higher than 1M dimensions, even 1B dimensions
 - Extremely sparse

Training/Validation/Test Data

Examples (in LibSVM format)

```
1 5:1 9:1 12:1 45:1 154:1 509:1 4089:1 45314:1 988576:1 0 2:1 7:1 18:1 34:1 176:1 510:1 3879:1 71310:1 818034:1
```

...

- Training/Validation/Test data split
 - Sort data by time
 - Train:validation:test = 8:1:1
 - Shuffle training data

Training Logistic Regression

Logistic regression is a binary classification model

$$p_{\theta}(y=1|x) = \sigma(\theta^{\top}x) = \frac{1}{1 + e^{-\theta^{\top}x}}$$

Cross entropy loss function with L2 regularization

$$\mathcal{L}(y, x, p_{\theta}) = -y \log \sigma(\theta^{\top} x) - (1 - y) \log(1 - \sigma(\theta^{\top} x)) + \frac{\lambda}{2} ||\theta||_2^2$$

Parameter learning

$$\theta \leftarrow (1 - \lambda \eta)\theta + \eta(y - \sigma(\theta^{\top}x))x$$

Only update non-zero entries

Experimental Results

Datasets

- Criteo Terabyte Dataset
 - 13 numerical fields, 26 categorical fields
 - 7 consecutive days out of 24 days in total (about 300 GB) during 2014
 - 79.4M impressions, 1.6M clicks after negative down sampling

iPinYou Dataset

- 65 categorical fields
- 10 consecutive days during 2013
- 19.5M impressions, 937.7K clicks without negative down sampling

Performance

Model	Linearity	AUC		Log Loss	
		Criteo	iPinYou	Criteo	iPinYou
Logistic Regression	Linear	71.48%	73.43%	0.1334	5.581e-3
Factorization Machine	Bi-linear	72.20%	75.52%	0.1324	5.504e-3
Deep Neural Networks	Non- linear	75.66%	76.19%	0.1283	5.443e-3

- Compared with non-linear models, linear models
 - Pros: standardized, easily understood and implemented, efficient and scalable
 - Cons: modeling limit (feature independent assumption), cannot explore feature interactions

Generalized Linear Models

Review: Linear Regression

$$m{X} = egin{bmatrix} m{x}^{(1)} \ m{x}^{(2)} \ m{x}^{(n)} \end{bmatrix} = egin{bmatrix} x_1^{(1)} & x_2^{(1)} & x_3^{(1)} & \dots & x_d^{(1)} \ x_1^{(2)} & x_2^{(2)} & x_3^{(2)} & \dots & x_d^{(2)} \ m{x}^{(1)} & m{x}^{(2)} & m{x}^{(2)} & m{x}^{(2)} \ m{x}^{(1)} & m{x}^{(2)} & m{x}^{(2)} \ m{x}^{(1)} & x_2^{(1)} & x_3^{(1)} & \dots & x_d^{(n)} \end{bmatrix} \quad m{ heta} = egin{bmatrix} m{ heta}_1 \\ m{ heta}_2 \\ m{ heta}_2 \\ m{ heta}_1 \end{bmatrix} \quad m{y} = egin{bmatrix} y_1 \\ y_2 \\ m{ heta}_2 \\ m{ heta}_1 \end{bmatrix}$$

• Prediction
$$\hat{m{y}} = m{X}m{ heta} = egin{bmatrix} m{x}^{(1)}m{ heta} \\ m{x}^{(2)}m{ heta} \\ \vdots \\ m{x}^{(n)}m{ heta} \end{bmatrix}$$

• Objective
$$J(\boldsymbol{\theta}) = \frac{1}{2}(\boldsymbol{y} - \hat{\boldsymbol{y}})^{\top}(\boldsymbol{y} - \hat{\boldsymbol{y}}) = \frac{1}{2}(\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta})^{\top}(\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta})$$

Review: Matrix Form of Linear Reg.

Objective

$$J(\boldsymbol{\theta}) = \frac{1}{2} (\boldsymbol{y} - \boldsymbol{X} \boldsymbol{\theta})^{\top} (\boldsymbol{y} - \boldsymbol{X} \boldsymbol{\theta}) \quad \min_{\boldsymbol{\theta}} J(\boldsymbol{\theta})$$

Gradient

$$\frac{\partial J(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = -\boldsymbol{X}^{\top}(\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta})$$

Solution

$$egin{aligned} rac{\partial J(oldsymbol{ heta})}{\partial oldsymbol{ heta}} &= oldsymbol{0} &
ightarrow oldsymbol{X}^ op (oldsymbol{y} - oldsymbol{X}oldsymbol{ heta}) = oldsymbol{0} \ &
ightarrow oldsymbol{X}^ op oldsymbol{y} &= oldsymbol{X}^ op oldsymbol{X}oldsymbol{0} &= oldsymbol{0} oldsymbol{X}^ op oldsymbol{X}oldsymbol{0} &= oldsymbol{0} & oldsymbol{0} &= oldsymbol{0} oldsymbol{0} & oldsymbol{0} &= oldsymbol{0} & oldsymbo$$

Generalized Linear Models

Dependence

$$y = f(\theta^{\top} \phi(x))$$

- Feature mapping function $\phi(x): \mathbb{R}^d \mapsto \mathbb{R}^h$
- Mapped feature matrix $\Phi_{n \times h}$

$$\Phi = \begin{bmatrix} \phi(x^{(1)}) \\ \phi(x^{(2)}) \\ \vdots \\ \phi(x^{(i)}) \\ \vdots \\ \phi(x^{(n)}) \end{bmatrix} = \begin{bmatrix} \phi_1(x^{(1)}) & \phi_2(x^{(1)}) & \cdots & \phi_h(x^{(1)}) \\ \phi_1(x^{(2)}) & \phi_2(x^{(2)}) & \cdots & \phi_h(x^{(2)}) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_1(x^{(i)}) & \phi_2(x^{(i)}) & \cdots & \phi_h(x^{(i)}) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_1(x^{(n)}) & \phi_2(x^{(n)}) & \cdots & \phi_h(x^{(n)}) \end{bmatrix}$$

Matrix Form of Kernel Linear Regression

Objective

$$J(\boldsymbol{\theta}) = \frac{1}{2} (\boldsymbol{y} - \boldsymbol{\Phi} \boldsymbol{\theta})^{\top} (\boldsymbol{y} - \boldsymbol{\Phi} \boldsymbol{\theta}) \quad \min_{\boldsymbol{\theta}} J(\boldsymbol{\theta})$$

Gradient

$$\frac{\partial J(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = -\boldsymbol{\Phi}^\top (\boldsymbol{y} - \boldsymbol{\Phi} \boldsymbol{\theta})$$

Solution

$$egin{aligned} rac{\partial J(oldsymbol{ heta})}{\partial oldsymbol{ heta}} &= oldsymbol{0} &
ightarrow oldsymbol{\Phi}^ op (oldsymbol{y} - oldsymbol{\Phi}oldsymbol{ heta}) = oldsymbol{0} \ &
ightarrow oldsymbol{\Phi}^ op oldsymbol{y} &= oldsymbol{\Phi}^ op oldsymbol{\Phi}oldsymbol{\Phi} \ &
ightarrow oldsymbol{ heta} &= (oldsymbol{\Phi}^ op oldsymbol{\Phi})^{-1} oldsymbol{\Phi}^ op oldsymbol{y} \end{aligned}$$

Matrix Form of Kernel Linear Regression

With the Algebra trick

$$(\mathbf{P}^{-1} + \mathbf{B}^{\top} \mathbf{R}^{-1} \mathbf{B})^{-1} \mathbf{B}^{\top} \mathbf{R}^{-1} = \mathbf{P} \mathbf{B}^{\top} (\mathbf{B} \mathbf{P} \mathbf{B}^{\top} + \mathbf{R})^{-1}$$

The optimal parameters with L2 regularization

$$\hat{oldsymbol{ heta}} = (oldsymbol{\Phi}^ op oldsymbol{\Phi} + \lambda oldsymbol{I}_h)^{-1} oldsymbol{\Phi}^ op oldsymbol{y}
onumber \ = oldsymbol{\Phi}^ op (oldsymbol{\Phi} oldsymbol{\Phi}^ op + \lambda oldsymbol{I}_n)^{-1} oldsymbol{y}
onumber$$

for prediction, we never actually need access Φ

$$egin{aligned} \hat{m{y}} &= m{\Phi} \hat{m{ heta}} = m{\Phi} m{\Phi}^ op (m{\Phi} m{\Phi}^ op + \lambda m{I}_n)^{-1} m{y} \ &= m{K} (m{K} + \lambda m{I}_n)^{-1} m{y} \end{aligned}$$

where the kernel matrix $\boldsymbol{K} = \{K(\boldsymbol{x}^{(i)}, \boldsymbol{x}^{(j)})\}$