

# Implementation and Evaluation of a Compact Table Propagator in Gecode

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# Outline

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## Background

- Constraint Programming
- Propagators
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- The Compact Table algorithm

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## Algorithms

- Sparse bit-set
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# Kakuro puzzle

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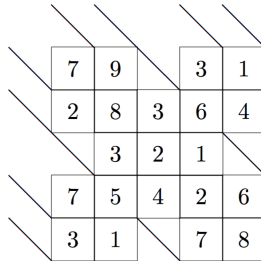
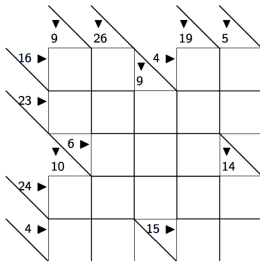
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- Rows and columns of cells (*entries*) with prefilled numbers (*clues*).
- Fill in digits from 1 to 9 inclusive into the empty cells so that for each entry, the sum of the digits is equal to the clue of that entry, and so that each digit appears at most once in each entry.



# Kakuro puzzle as a constraint problem (1)

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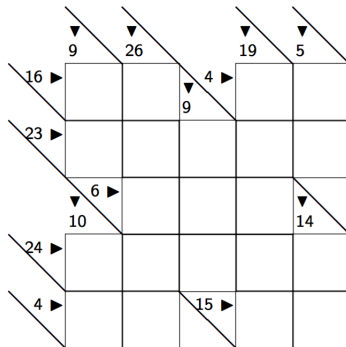
## Evaluation

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**Variables** One per empty cell.

**Domains**  $\{1 \dots 9\}$  for all variables.

**Constraints (1)** For each entry: variables are *distinct*, and the *sum* of them is equal to the clue.



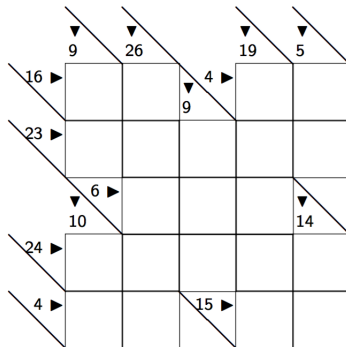


# Kakuro puzzle as a constraint problem (2)

**Variables** One per empty cell.

**Domains**  $\{1 \dots 9\}$  for all variables.

**Constraints (2)** For each entry: state the *possible combinations of values* that the variables can take.



For an entry of size 2 and clue 4:  $\langle 1, 3 \rangle$  and  $\langle 3, 1 \rangle$  are the only combinations.



# Constraints and TABLE constraints (definitions)

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### Definition (Constraint)

A **constraint** on a finite sequence of  $n$  variables  $X$  is a relation, denoted  $rel(c)$ , that contains the set of allowed  $n$ -tuples for  $X$ . Each variable  $x_i \in X$  has a corresponding *domain*  $D_i$  that is the set of possible values that  $x_i$  can take.

### Definition (TABLE constraints)

A TABLE constraint explicitly lists  $rel(c)$  as a sequence of  $n$ -tuples.

Example of a TABLE constraint.



# Constraint Problems (definition)

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### Definition (Constraint problem)

A **constraint satisfaction problem (CSP)** is a triple

$$\langle V, D, C \rangle$$

where:

- $V = v_1, \dots, v_n$  is a finite sequence of variables,
- $D = D_1, \dots, D_n$  is a finite sequence of domains for the respective variable,
- $C = \{c_1, \dots, c_m\}$  is a finite set of constraints, each on a subsequence of  $V$ .





# Constraint Stores (definition)

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### Definition (Constraint store)

A **constraint store**  $s$  is a function mapping a finite set of variables  $V = v_1, \dots, v_n$  to a finite set of domains  $D = D_1, \dots, D_n$ :

$$s : \text{variables} \mapsto \text{domains}$$

Furthermore, a store  $s$ ...

- ...is a *failed store* iff  $s(v_i) = \emptyset$  for some  $v_i \in V$ .
- ...is an *assignment store* iff  $|s(v_i)| = 1$  for all  $v_i \in V$ .
- ...is a *solution store* for a constraint  $c$  iff  $s$  is an assignment store that constructs a solution to  $c$ .



# Propagators (definition)

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### Definition (Propagators.)

A **propagator**  $p$  is a function mapping stores to stores:

$$p : \text{store} \mapsto \text{store}$$

Furthermore, a propagator  $p$ ...

- ...is a decreasing function (i.e. can only remove values and not add new values).
- ...is a monotonic function (not a strict obligation).
- ...must faithfully implement its constraint.
- ...signals a *status message*.



# Status messages

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**FAIL.**  $p(s)$  is a failed store.

**SUBSUMED.**  $p$  can never propagate any more values (all the following stores will be fixpoints).

**FIX.**  $p(s)$  is a fixpoint to  $p$ :  $p(s) = p(p(s))$

**NOFIX.**  $p(s)$  is (possibly) not a fixpoint.

Obligations regarding status messages:

- Must signal SUBSUMED on a solution store  $s$ .
- Must signal FAIL on an assignment store  $s$  that is not a solution store.
- Must not claim FIX or SUBSUMED if it could propagate more.

Always safe to signal NOFIX on stores that are not assignment stores.



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**Gecode** (Generic Constraint Development Environment)  
is...

- ...a constraint solver (a software that solves constraint problems).
- ...written in C++, modular, extensible, and has state-of-the-art performance.
- ...supports the programming of new propagators.
- ...developed at KTH, Sweden.

Two existing propagators for the TABLE constraint, and one for the related constraint REGULAR, that expresses  $rel(c)$  as a DFA.



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A new propagation algorithm for the TABLEconstraint.  
Published in a 2016 paper  
No attempt to implement it in  
Gecode (until now).



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```
PROCEDURE COMPACTTABLE( $s$  : store) :  $\langle StatusMsg, store \rangle$ 
1: if the propagator is being posted then
2:    $s \leftarrow \text{INITIALISECT}(s, T_0)$ 
3:   if  $s = \emptyset$  then
4:     return  $\langle \text{FAIL}, \emptyset \rangle$ 
5: else
6:   foreach variable  $x \in s$  whose domain has changed since
   last time do
7:     UPDATETABLE( $s, x$ )
8:     if validTuples.isEmpty() then
9:       return  $\langle \text{FAIL}, \emptyset \rangle$ 
10:   if validTuples has changed since last time then
11:      $s \leftarrow \text{FILTERDOMAINS}(s)$ 
12:   if there is at most one unassigned variable left then
13:     return  $\langle \text{SUBSUMED}, s \rangle$ 
14:   else
15:     return  $\langle \text{FIX}, s \rangle$ 
```

### Algorithm 1: Compact Table Propagator.



# Updating validTuples

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**PROCEDURE** UPDATETABLE( $s$ : store,  $x$ : variable)

```
1: validTuples.clearMask()
2: if  $\Delta_x$  is available  $\wedge |\Delta_x| < |s(x)|$  then
3:   foreach  $a \in \Delta_x$  do
4:     validTuples.addToMask(supports[ $x, a$ ])
5:   validTuples.reverseMask()
6: else
7:   foreach  $a \in s(x)$  do
8:     validTuples.addToMask(supports[ $x, a$ ])
9: validTuples.intersectWithMask()
```





# Filtering out values

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```
PROCEDURE FILTERDOMAINS(s) : store
1: foreach  $x \in s$  such that  $|s(x)| > 1$  do
2:   foreach  $a \in s(x)$  do
3:      $index \leftarrow residues[x, a]$ 
4:     if  $validTuples[index] \ \& \ supports[x, a][index] = 0$  then
5:        $index \leftarrow validTuples.intersectIndex(supports[x, a])$ 
6:       if  $index \neq -1$  then
7:          $residues[x, a] \leftarrow index$ 
8:       else
9:          $s \leftarrow s[x \mapsto s(x) \setminus \{a\}]$ 
10: return s
```



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