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Vision Language Model

A General Classification of Vision Language Models (VLMs)

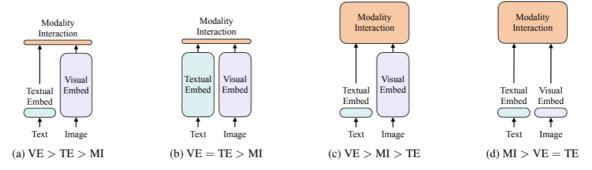


Figure 2. Four categories of vision-and-language models. The height of each rectangle denotes its relative computational size. VE, TE, and MI are short for visual embedder, textual embedder, and modality interaction, respectively.

- Class 1: Small text encoder + Large vision encoder + Simple interaction
 - VSE++, SCAN
- Class 2: Large text encoder + Large vision encoder + Simple interaction
 - CLIP
- Class 3: Small text encoder + Large vision encoder + Large interaction
- Class 4: Small text encoder + Small vision encoder + Large interaction
- Learning Transferable Visual Models From Natural Language Supervision [arXiv 2021] Alec Radford (arXiv) (pdf) (Citation: 7930)

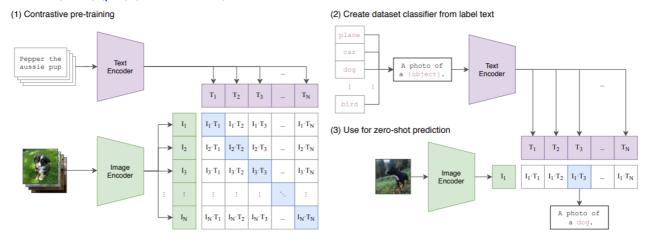


Figure 1. Summary of our approach. While standard image models jointly train an image feature extractor and a linear classifier to predict some label, CLIP jointly trains an image encoder and a text encoder to predict the correct pairings of a batch of (image, text) training examples. At test time the learned text encoder synthesizes a zero-shot linear classifier by embedding the names or descriptions of the target dataset's classes.

- Core: use natural language to supervise image training
 - Map visual semantic and language semantic
- Constrastive pre-training:
 - Training data Image & text pairs
 - Image encoder (ViT, ResNet) Extract image features
 - Text encoder (Transformer) Extract text features
 - Training goal Minimize the distance (cosine similarity) between text and image features if they are a pair (i.e., \$I_1T_I\$, \$I_2T_2\$ in the image).

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- Both image and text encoders are trained from scratch.
- Downstream task example: Object detection
 - Prompt template: A photo of {objects}, this {objects} are objects candidates, i.e., dog, cat, etc.
 - Calculate the consine similarity between the prompt features and image features and find the one with the highest similarity.
- ViLT Vision-and-Language Transformer Without Convolution or Region Supervision [ICML 2021]

Wonjae Kim, Bokyung Son, Ildoo Kim (arXiv) (pdf) (Citation: 808)

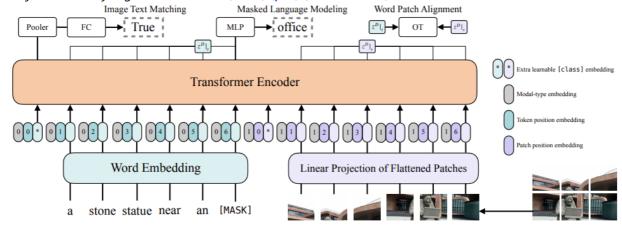


Figure 3. Model overview. Illustration inspired by Dosovitskiy et al. (2020).

- Remove feature extraction model in traditional Transformer-based vision detector
- The Performance of ViLT is similar to the feature extration method, but the running time is much shorter.