

Investigating the role of the cosmological constant in gravitational lensing using a numerical approach

Lingyi Hu

Introduction: motivation

Key question

- Does the cosmological constant directly affect gravitational lensing?

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Motivation

- Both the cosmological constant and gravitational lensing form important parts of our understanding of the universe
- Can become important for future precision cosmology measurements
- Most approaches in literature have been analytical rather than numerical

Introduction: overview of the literature

Key question

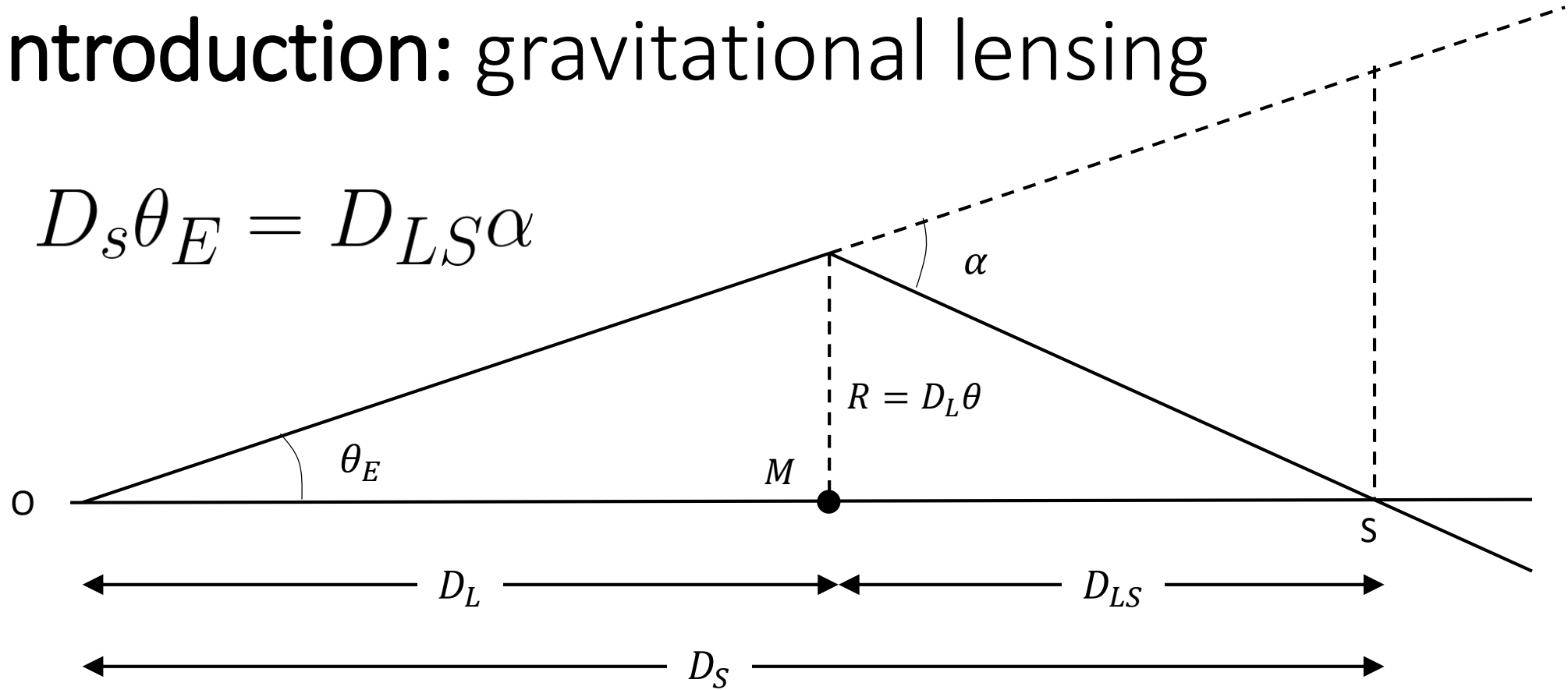
- Does the cosmological constant directly affect gravitational lensing?

Key papers

- Islam, 1983 (Conventional view)
- Rindler and Ishak, 2007 (Challenging the conventional view)

Introduction: gravitational lensing

$$D_s \theta_E = D_{LS} \alpha$$



Introduction: gravitational lensing

$$\alpha_{\text{FRW}} = 4\frac{M}{R} + \frac{15\pi}{4} \left(\frac{M}{R}\right)^2 + \frac{401}{12} \left(\frac{M}{R}\right)^3$$

Introduction: gravitational lensing

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$$\alpha_{\text{Ishak}} = 4\frac{M}{R} + \frac{15\pi}{4} \left(\frac{M}{R}\right)^2 + \frac{305}{12} \left(\frac{M}{R}\right)^3 - \frac{\Lambda R r_h}{3}$$

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$$\begin{aligned} \alpha_{\text{Kantowski}} = & \left(\frac{r_s}{2r_0}\right) \cos \tilde{\phi}_1 \left[-4 \cos^2 \tilde{\phi}_1 - 12 \cos \tilde{\phi}_1 \sin \tilde{\phi}_1 \sqrt{\frac{\Lambda r_0^2}{3} + \frac{r_s}{r_0} \sin^3 \tilde{\phi}_1} + \Lambda r_0^2 \left(\frac{8}{3} - \frac{20}{3} \sin^2 \tilde{\phi}_1 \right) \right] \\ & + \left(\frac{r_s}{2r_0}\right)^2 \left[\frac{15}{4} (2\tilde{\phi}_1 - \pi) + \cos \tilde{\phi}_1 \left(4 + \frac{33}{2} \sin \tilde{\phi}_1 - 4 \sin^2 \tilde{\phi}_1 + 19 \sin^3 \tilde{\phi}_1 - 64 \sin^5 \tilde{\phi}_1 \right) \right. \\ & \left. - 12 \log \left\{ \tan \frac{\tilde{\phi}_1}{2} \right\} \sin^3 \tilde{\phi}_1 \right] + \mathcal{O} \left(\frac{r_s}{r_0} + \Lambda r_0^2 \right)^{5/2} \end{aligned}$$

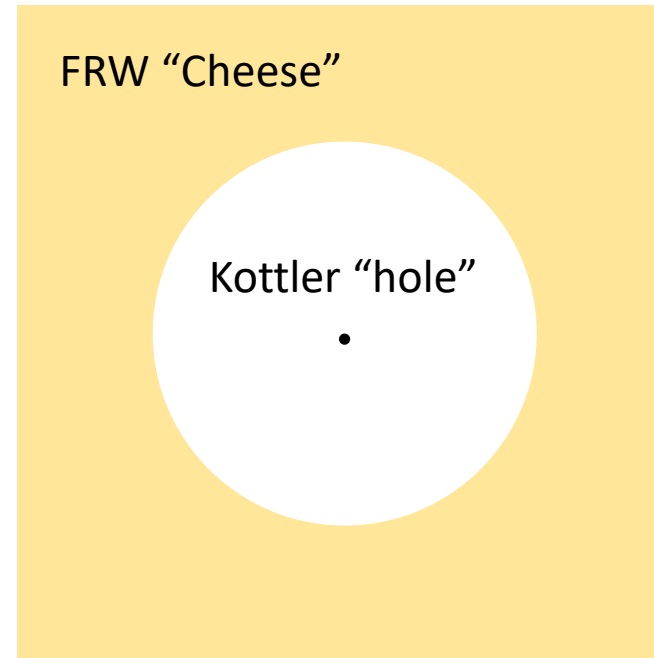
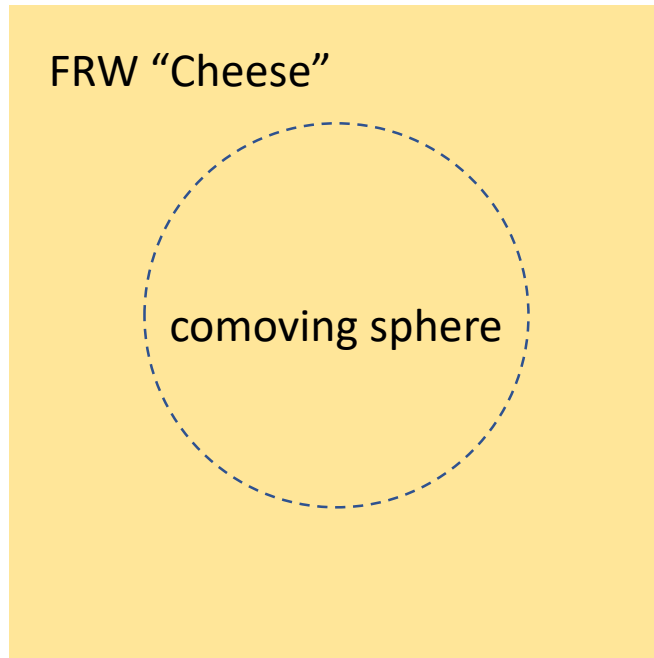
Method: our approach

Numerical approach in a Swiss-Cheese model

Previous similar research:

- Schücker (2009): partially numerical approach in a Swiss-Cheese model
- Kantowski et al (2010) analytical estimation of the effect in a Swiss Cheese universe
- Aghili et al (2017) investigated numerical approach in a McVittie metric

The Swiss Cheese Model



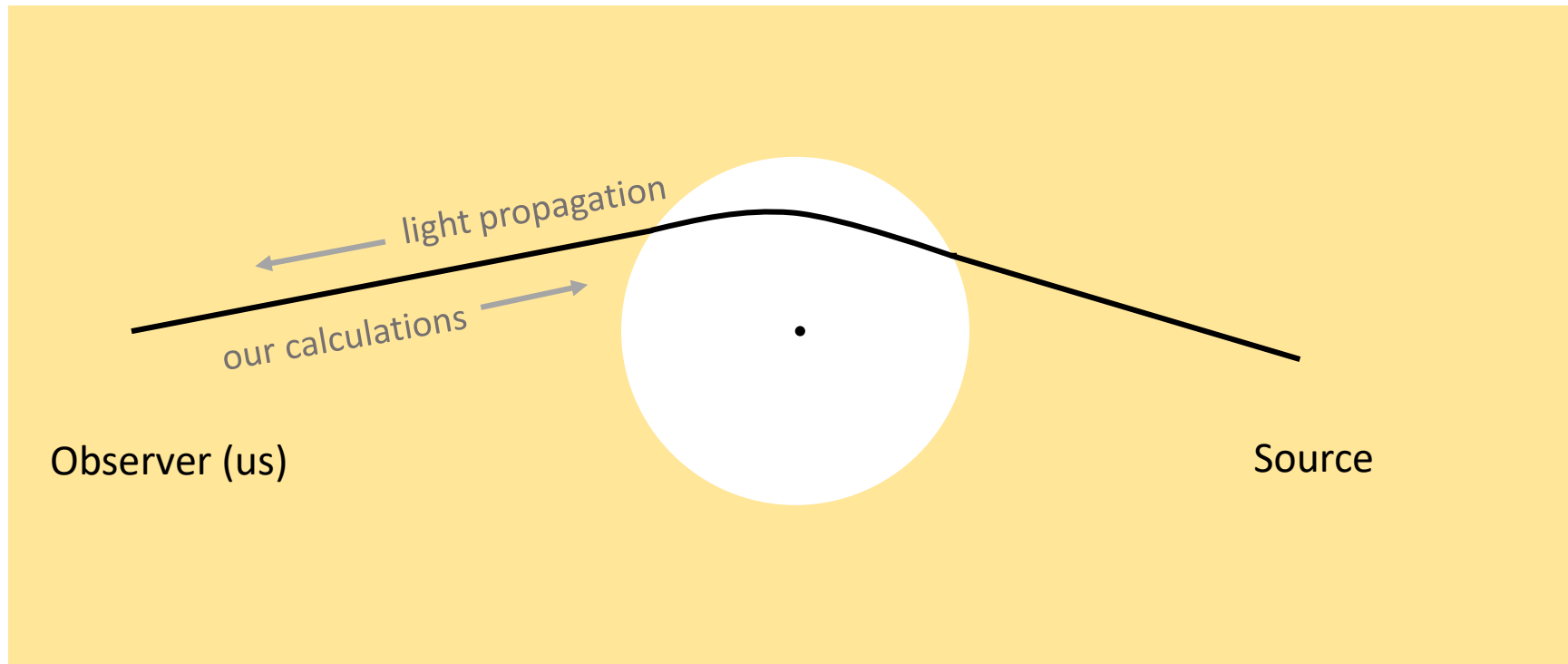
Cheese:

- Homogeneous and expanding
- Filled with pressureless matter (dust)

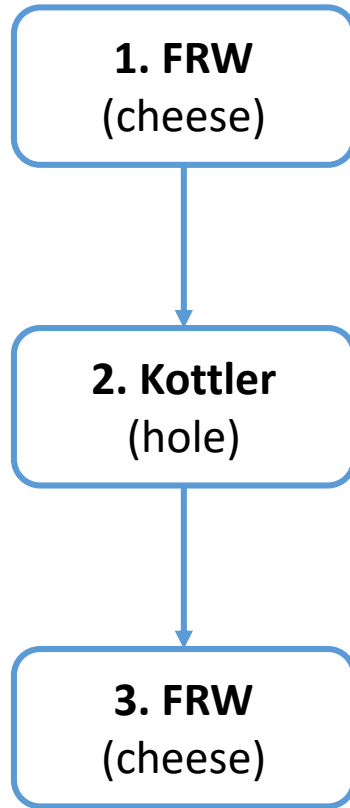
Hole:

- Point mass at the centre
- Vacuum everywhere else with a cosmological constant

Propagation of light



Propagation of light: an overview



General method

To find light path in each region,

1. Write down the metric
2. Calculate the Christoffel symbols and hence the equations of motion using

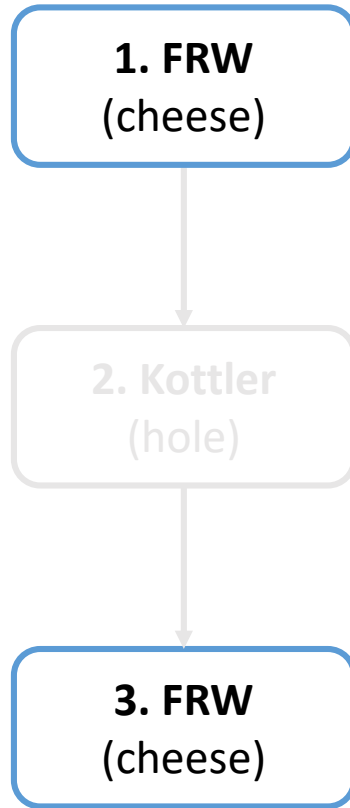
$$\ddot{x}^\mu + \Gamma_{\alpha\beta}^\mu \dot{x}^\alpha \dot{x}^\beta = 0$$

and the null condition

$$ds^2 = 0$$

3. Solve the resulting differential equations (numerically or analytically)

Propagation of light



Friedmann-Robertson-Walker metric

$$ds^2 = -dt^2 + a(t)^2 \left[\frac{dr^2}{1 - kr^2} + r^2(d\theta^2 + \sin^2 \theta d\phi^2) \right]$$

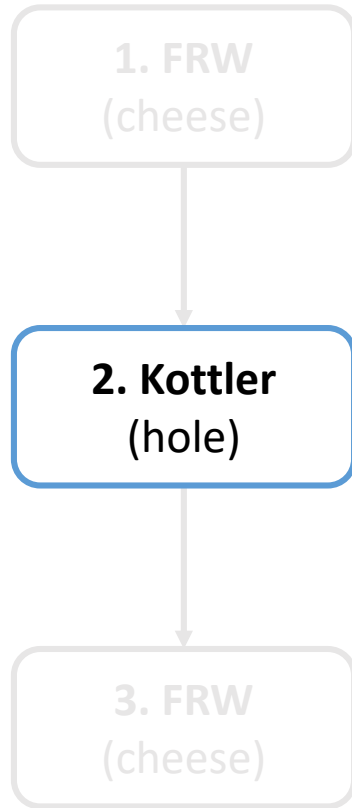
Null geodesics

$$\ddot{r} = (1 - kr^2)r\dot{\phi}^2 - \frac{k\dot{r}^2}{1 - kr^2} - \frac{2a_{,t}}{a}\dot{r}\dot{t}$$

$$\dot{\phi} = \frac{L}{a^2 r^2}$$

$$a_{,t} = aH_0 \sqrt{\Omega_M/a^3 + \Omega_k/a^2 + \Omega_\Lambda}$$

Propagation of light



Kottler metric

$$ds^2 = -f(R)dT^2 + \frac{dR^2}{f(R)} + R^2(d\theta^2 + \sin^2 \theta d\phi^2)$$

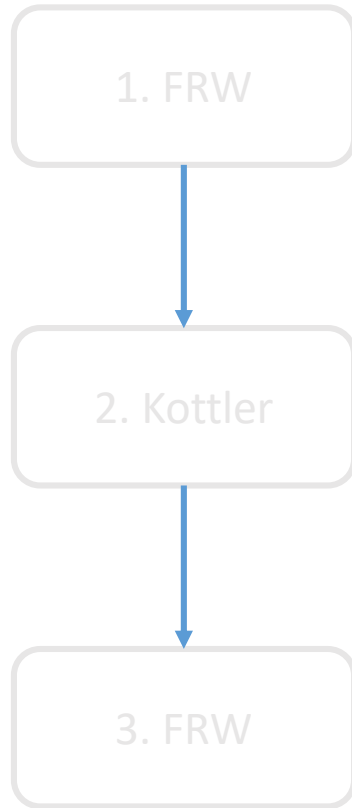
$$\text{where } f(R) = 1 - \frac{2M}{R} - \frac{\Lambda R^2}{3}$$

Null geodesics

$$\ddot{R} = \frac{L_k^2(R - 3M)}{R^4}$$

$$\dot{\phi} = \frac{L_k}{R^2}$$

Propagation of light



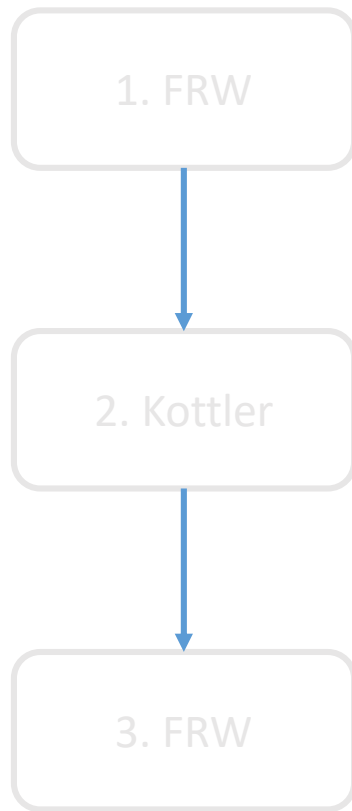
Gluing the two metrics together

A spacetime obtained by gluing two different geometries via a hypersurface Σ is well defined if it satisfies the Israel junction conditions (Israel, 1966):

Both geometries must induce, on Σ ,

1. the same 3-metric, and
2. the same extrinsic curvature

Propagation of light



Gluing the two metrics together

A spacetime obtained by gluing two different geometries via a hypersurface Σ is well defined if it satisfies the Israel junction conditions (Israel, 1966):

These junction conditions tell us:

1. The size of the hole is related to the mass by

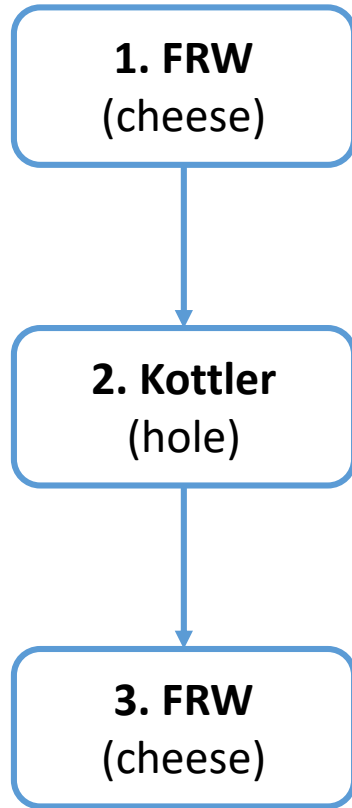
$$M = \frac{4\pi}{3} \rho a^3 r^3$$

2. The rate of expansion of the hole in Kottler coordinates:

$$R_{h,t} = \left(1 - \frac{2M}{R_h} - \frac{\Lambda R_h^2}{3} \right) \sqrt{\frac{2M}{R_h} + \frac{\Lambda R_h^2}{3}}$$

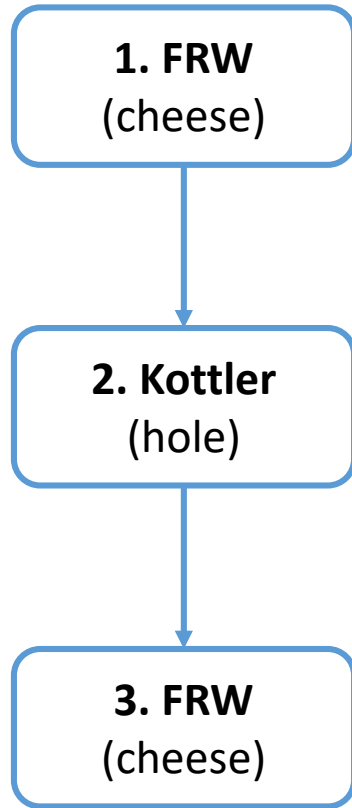
3. the Jacobian for transforming velocities from one coordinate to the other

Propagation of light: the full picture



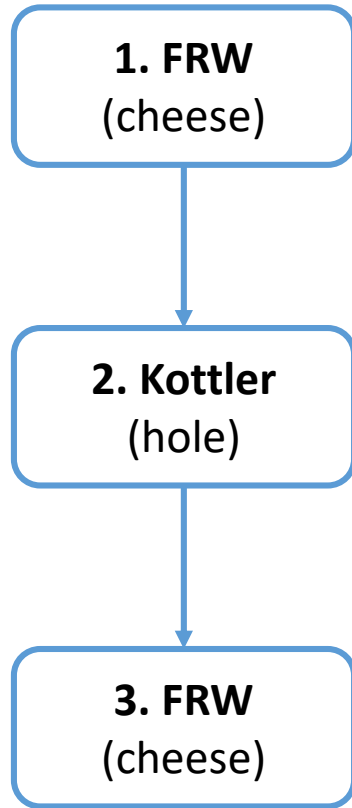
- Start off light ray with a fixed θ
 - Propagate light rays until it reaches the boundary of the hole
 - Convert from FRW coordinates to Kottler coordinates using the Jacobian obtained from matching conditions
-
- Propagate light rays in hole using null geodesic equations
 - At the same time, the boundary of the hole is also changing
 - Stop when it has reached the boundary of the hole
 - Convert from Kottler coordinates back to FRW coordinates
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- Continue propagating light rays until it crosses the axis
 - Record the coordinate at which it crosses the axis

Propagation of light: the full picture



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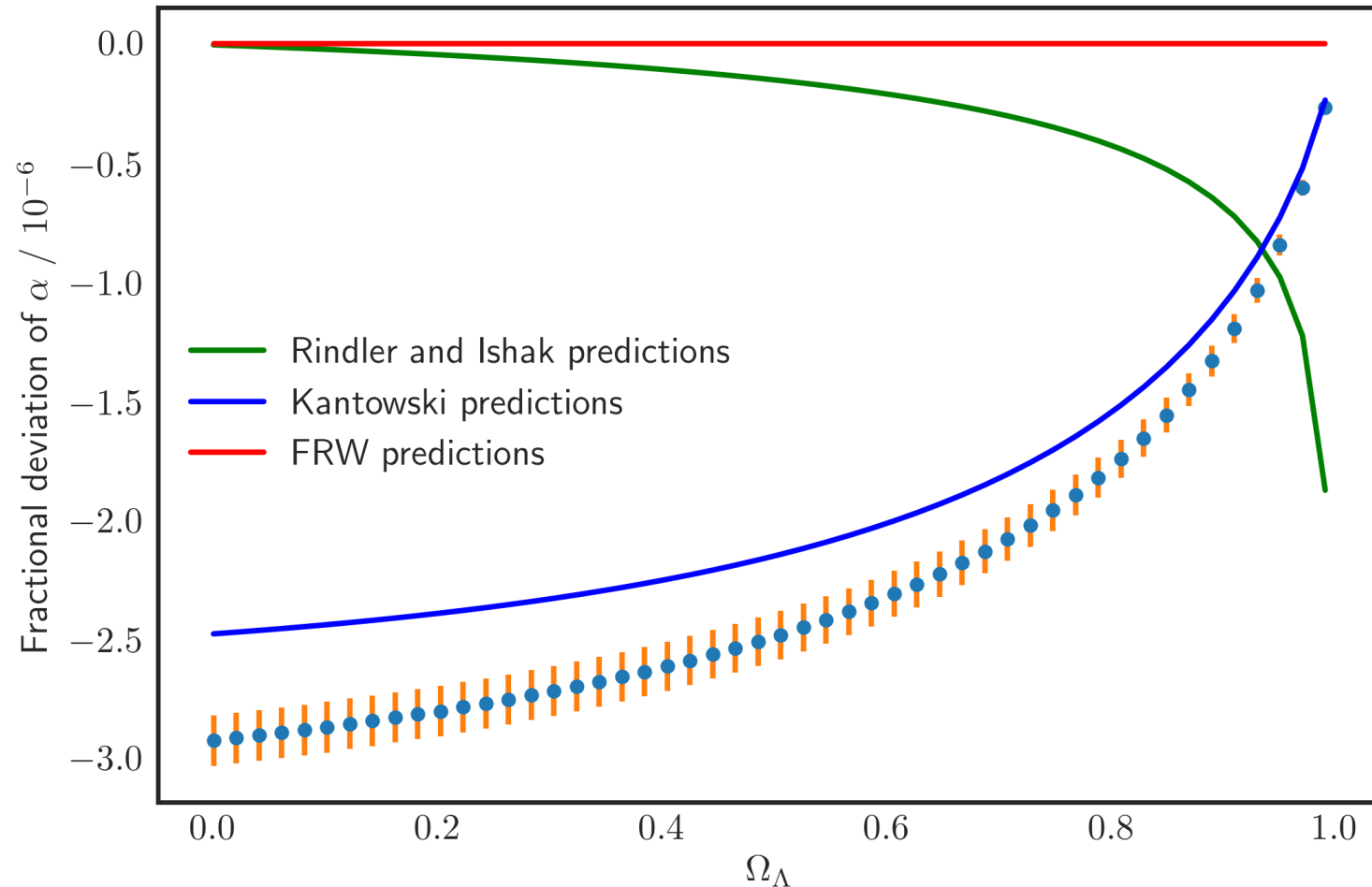
Propagation of light: the full picture



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Results

Results: Keeping the mass fixed

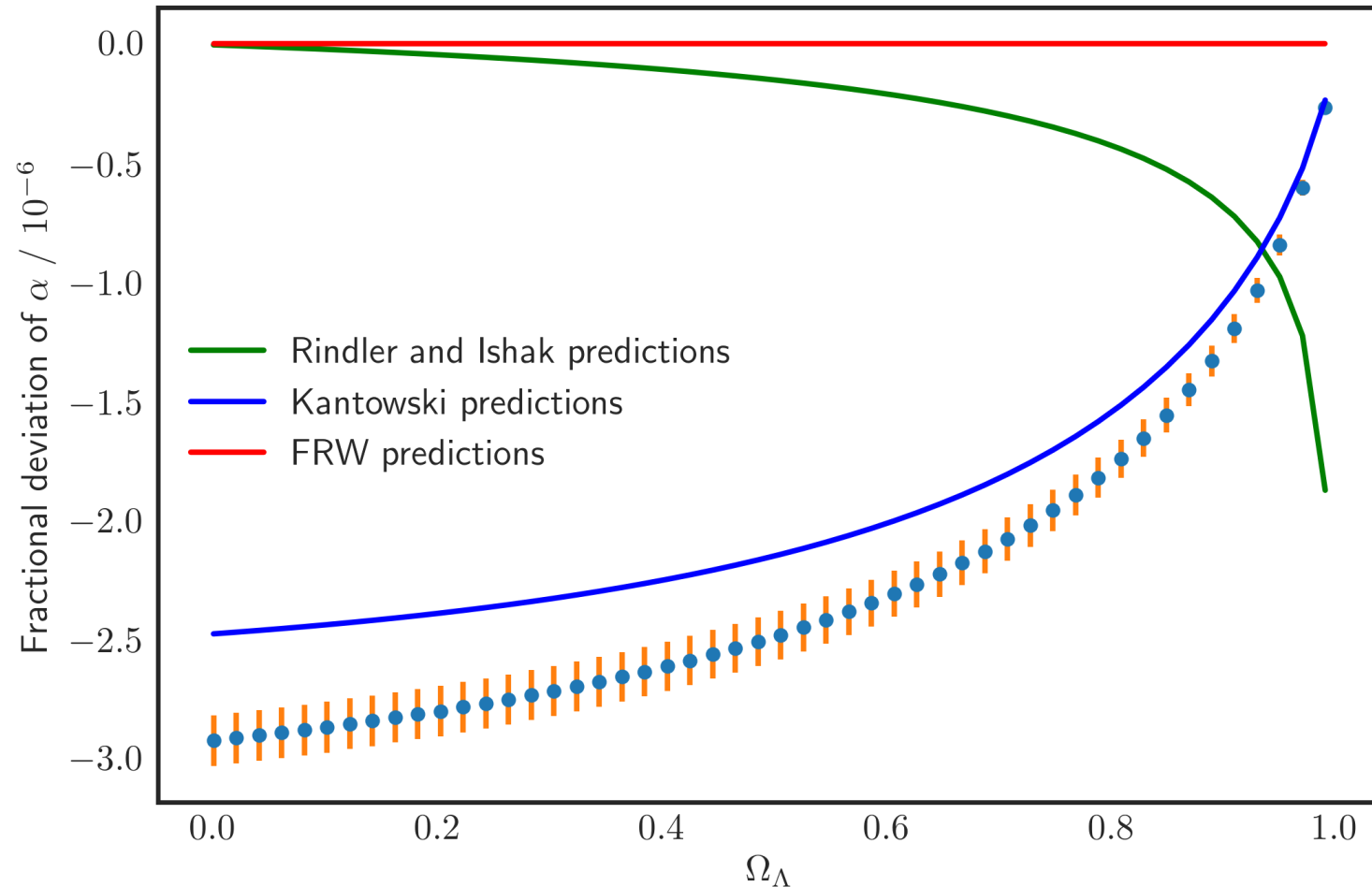


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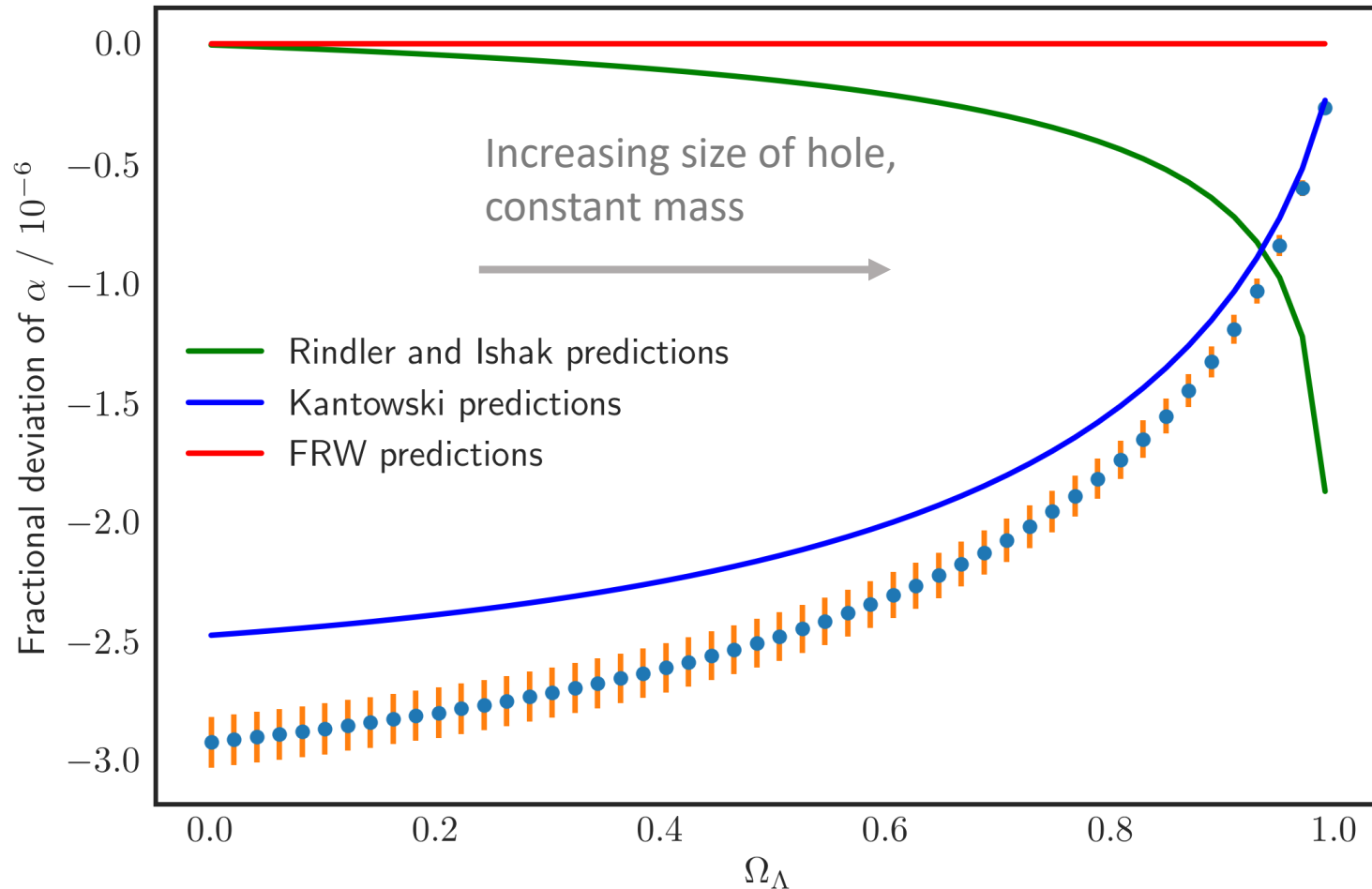
$$\alpha_{\text{Ishak}} = 4\frac{M}{R} + \frac{15\pi}{4} \left(\frac{M}{R}\right)^2 + \frac{305}{12} \left(\frac{M}{R}\right)^3 - \frac{\Lambda R r_h}{3}$$

$$\begin{aligned} \alpha_{\text{Kantowski}} = & \left(\frac{r_s}{2r_0}\right) \cos \tilde{\phi}_1 \left[-4 \cos^2 \tilde{\phi}_1 - 12 \cos \tilde{\phi}_1 \sin \tilde{\phi}_1 \sqrt{\frac{\Lambda r_0^2}{3} + \frac{r_s}{r_0} \sin^3 \tilde{\phi}_1} + \Lambda r_0^2 \left(\frac{8}{3} - \frac{20}{3} \sin^2 \tilde{\phi}_1 \right) \right] \\ & + \left(\frac{r_s}{2r_0}\right)^2 \left[\frac{15}{4} (2\tilde{\phi}_1 - \pi) + \cos \tilde{\phi}_1 \left(4 + \frac{33}{2} \sin \tilde{\phi}_1 - 4 \sin^2 \tilde{\phi}_1 + 19 \sin^3 \tilde{\phi}_1 - 64 \sin^5 \tilde{\phi}_1 \right) \right. \\ & \left. - 12 \log \left\{ \tan \frac{\tilde{\phi}_1}{2} \right\} \sin^3 \tilde{\phi}_1 \right] + \mathcal{O} \left(\frac{r_s}{r_0} + \Lambda r_0^2 \right)^{5/2} \end{aligned}$$

Results: Keeping the mass fixed



Results: Keeping the mass fixed

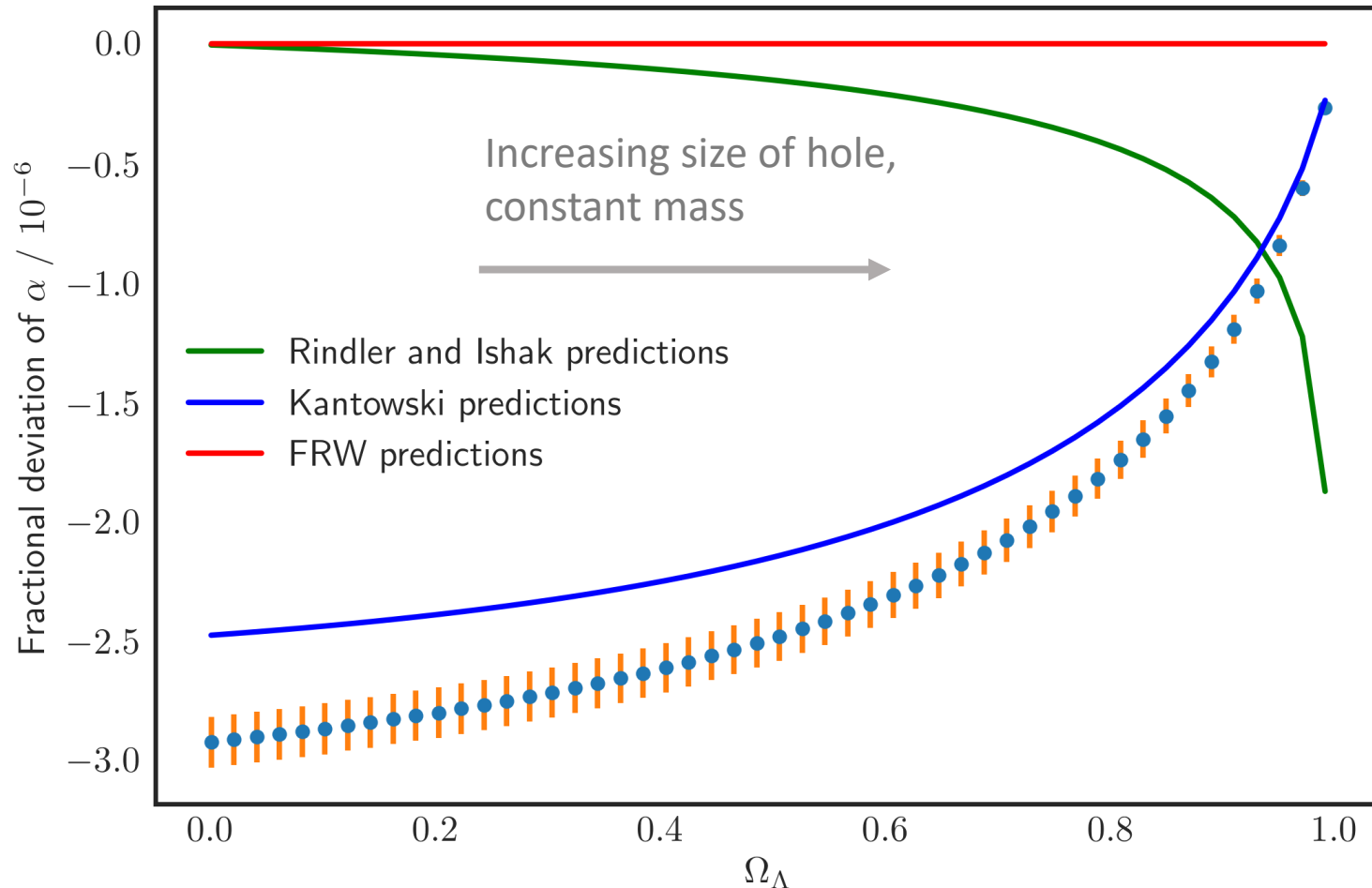


A few factors at play:

- Size of the hole is increased as Λ increases

$$M = \frac{4\pi}{3}\rho a^3 r^3$$

Results: Keeping the mass fixed



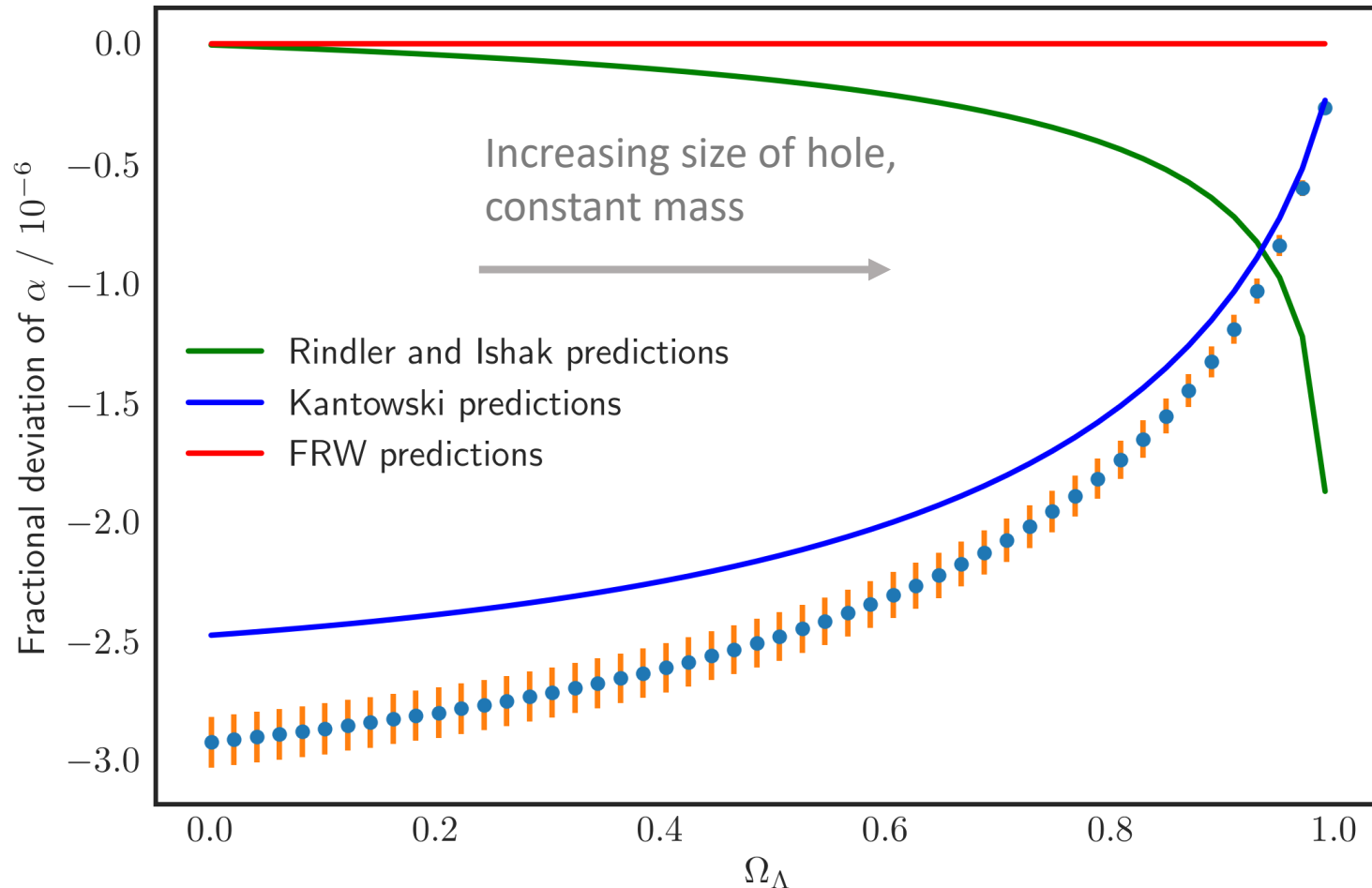
A few factors at play:

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$$M = \frac{4\pi}{3}\rho a^3 r^3$$
- Expansion rate of the hole boundary depends on Λ

$$R_{h,t} = \left(1 - \frac{2M}{R_h} - \frac{\Lambda R_h^2}{3}\right) \sqrt{\frac{2M}{R_h} + \frac{\Lambda R_h^2}{3}}$$

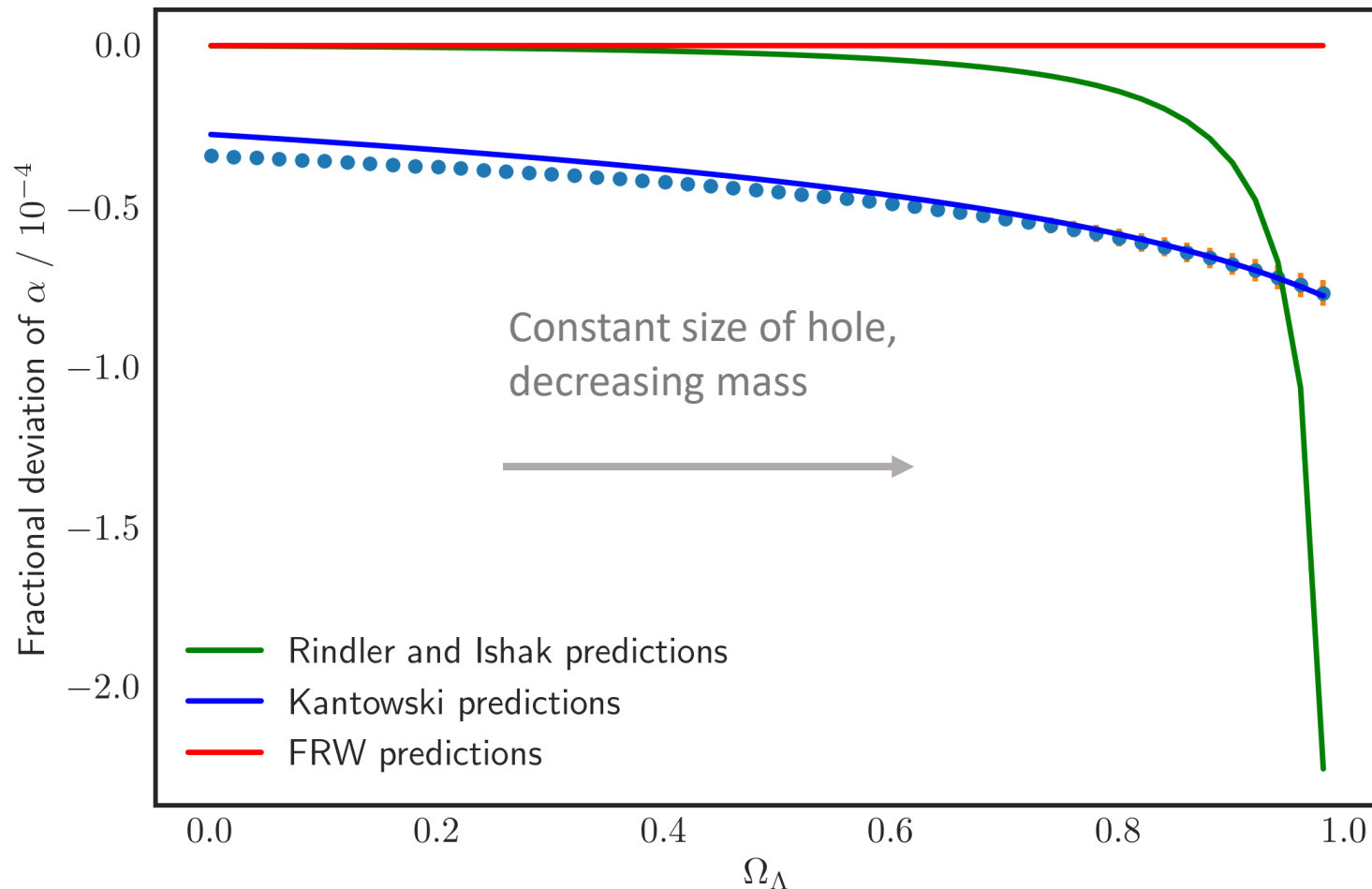
Results: Keeping the mass fixed



A few factors at play:

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- Jacobian at the boundary depends on Λ

Results: Keeping size of the hole fixed



A few factors at play:

- Size of the hole is increased as Λ increases

$$M = \frac{4\pi}{3}\rho a^3 r^3$$
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$$R_{h,t} = \left(1 - \frac{2M}{R_h} - \frac{\Lambda R_h^2}{3}\right) \sqrt{\frac{2M}{R_h} + \frac{\Lambda R_h^2}{3}}$$
- Jacobian at the boundary depends on Λ

Currently working on / future work

- Curved space
- Better estimation of numerical errors
- Extend the model to a general mass distribution instead of a point mass

References

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Thank you!