

Lingyu Zhang

<https://lingyu98.github.io/>
New York, NY 10025
+1 (929) 553 - 4609 lz2814@columbia.edu

EDUCATION

Columbia University, New York, NY

Master of Science, Electrical Engineering
GPA: 3.92/4.0

Sep 2021 — Dec 2022 (Expected)

Relevant Coursework: Representation Learning, Computer Vision II, Advanced Deep Learning, Unsupervised Learning, Natural Language Processing, Reinforcement Learning

Nanjing University, Nanjing, China

Bachelor of Engineering, Microelectronic Science and Engineering
GPA: 4.16/5.0

Sep 2017 — June 2021

Relevant Coursework: Computer Vision, Engineering Fundamental of AI, AI & project practice, Data Structure and Algorithms

University of California, Berkeley, Berkeley, CA

Berkeley International Study Program

Aug 2019 — Dec 2019

Relevant Coursework: Introduction to Machine Learning, Efficient Algorithms and Intractable Problems, Optimization Models in Engineering.

PAPER UNDER REVIEW

Lingyu Zhang*, Chengzhi Mao*, Junfeng Yang, Carl Vondrick. Adversarially Robust Video Perception by Seeing Motion. Submitted to CVPR 2023. [[arxiv](#), [project-page](#)]

Chengzhi Mao, **Lingyu Zhang**, Abhishek Vaibhav Joshi, Junfeng Yang, Hao Wang, Carl Vondrick. Robust Perception through Equivariance. Submitted to CVPR 2023. [[arxiv](#), [project-page](#)]

PUBLICATIONS

Bangpeng Xiao, Shenyuan Ye, Xicai Li, Min Li, **Lingyu Zhang**, Yuanqing Wang. A Stereo Matching Method for Three-Dimensional Eye Localization of Autostereoscopic Display. ICIG 2021.

Lingyu Zhang, and Gang Song. Improved antireflection based on biomimetic nanostructures at material interface. Journal of Optics 2018.

Lingyu Zhang, and Gang Song. Thermo-responsive plasmonic nanohybrids with tunable optical properties. Journal of Modern Optics 2017.

RESEARCH EXPERIENCE

Columbia University, Fu Foundation School of Engineering and Applied Science

Research Assistant: Robust Action Recognition with Motion

Advisor: Prof. Junfeng Yang & Prof. Carl Vondrick, June-Nov 2022

Designed a novel test-time adaptive adversarial defense for action recognition models using motion consistency. Based on the observation of adversarial examples collaterally disrupting intrinsic temporal structures of videos, proposed to repair inputs by restoring motion. Consistently improved robust accuracy against a variety of attacks. Paper under review.

Research Assistant: Robust Perception Through Equivariance

Advisor: Prof. Junfeng Yang, Feb-Sept 2022

Conducted experiments on the performance of a novel adversarial purification method based on dense equivariant properties of neural networks. Adapted the algorithm to different tasks and datasets. Paper under review.

Nanjing University, School of Electronic Science and Engineering

Undergraduate Thesis: Learned Multi-scale Image Compression

Advisor: Prof. Qiu Shen, Dec 2020 -June 2021

Implemented an end-to-end optimized image compression model based on an entropy-constrained variational autoencoder. Integrated a multi-scale encoder, achieving state of art compression performance. Investigated potential for latent space vision tasks without decoding.

Research Intern: Designing Materials with Improved Optical Properties

Advisor: Dr. Gang Song & Dr. Haodong Wu, 2017-2018

Designed nanomaterials with desirable optical properties based on the effective medium theory.

HONORS/AWARDS

Renmin Scholarship, 2018

Renmin Scholarship, 2019

FlyAI Excellent Algorithm Award (two tasks), 2021

LEADERSHIP/SERVICE

Graduate Electrical Engineering Council, Columbia

Career Chair, Jan 2022 - present

Engineering Graduate Student Council at Columbia Engineering

Lead Department Representative of EE, Jan 2022 - present

Nanjing University Summer Social Practice Project

Team Leader, June-Aug 2020

The Berkeley Project

Site Leader & Volunteer, Oct 2019

Nanjing University Hip-Hop Association

President, Aug 2018-June 2019

PROFESSIONAL TRAINING

Karlsruhe Institute of Technology, Virtual

Industry 4.0 Training for Young Talent, Sep-Oct 2020

Training covering Lean Production, Lean Line Design, Machine Learning, Data Analysis and Industry 4.0 of Production Planning and Control.

TECHNICAL SKILLS

Programming Language: Python, Matlab, C

Frameworks / Tools: PyTorch, PyTorch Lightning, OpenCV, Numpy, Matplotlib, Advertorch