# MI3.22 Advanced Programming for HPC Master ICT, USTH, 2<sup>nd</sup> year

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## Lecture 1 – Thrust and first Parallel Patterns

- Thrust: high-level library
- First example
- Iterators
- Introduction to PRAM
- Parallel Patterns

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# Thrust: an introduction

Thrust is a high level parallel library:

- Resembles the STL (so it is a C++ library, with templates)
- Handles memory allocation and release using vectors
- Implements many parallel patterns:
  - MAP (known as transform in thrust)
  - GATHER
  - SCATTER
  - REDUCE
  - SCAN
  - SEGMENTED SCAN
  - COMPACT (or compress)
  - ALLOCATE
  - ...

Full documentation at: http://thrust.github.io/doc/index.html

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# First thrust example: addition of two vectors I

```
#include <iostream>
#include <thrust/device_vector.h>
#include <thrust/sequence.h>
#include <thrust/fill.h>
/// display a vector
void display(thrust::device_vector<float>& U, const std::string& name)
    // copy the data from GPU memory to CPU memory
    thrust::host\_vector < float > V = U:
    // display each values
    for (int i=0; i<V. size (); ++i) {
        std::cout<< name << "[" << i << "] _=_" << V[i] << std::endl;
/// function that adds two elements and return a new one
class AdditionFunctor : public thrust::binary_function < float , float , float > {
  public:
    __host__ _device__ float operator()(const float &x, const float &y) {
        return x + y;
};
```

# First thrust example: addition of two vectors II

```
/// creates two vectors on GPU, and do their addition
void doAddition(unsigned workSize)
    thrust::device_vector < float > result (work Size);
    thrust :: device_vector < float > U( workSize );
    thrust :: device_vector < float > V( workSize );
    /// initialization of two given arrays
    // fill U with 1, 2, 3 .... U.size()
    thrust::sequence(U.begin(), U.end(), 1.f);
    // fill V with 4. 4. .... 4
    thrust :: fill (V. begin (), V. end (), 4. f);
    /// do a MAP (one-to-one operation)
    thrust::transform(U.begin(), U.end(),
                       V. begin (),
                       result.begin(),
                       AdditionFunctor()):
    /// display the result (if not too big)
    if(workSize < 128) display(result, "result");</pre>
/// main function
    main (void)
    doAddition(10); // add "big" vectors (of size 10)
    return 0:
```

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# Iterator: a key for Thrust programming

#### Same meaning than in STL or other library:

allows to traverse a given container

#### **Properties**

- Similar to Boost's iterators
- 5 kinds of iterators:

- Some specialized iterators
  - constant
  - counting
  - fancy
  - zip
  - ...

# Iterator: a key for thrust programming

Same program, excepting the addition function:

```
// creates two vectors on GPU, and do their addition
void doAdditionIterator(const unsigned workSize)
{
    thrust::device_vector<float> result(workSize);
    thrust::counting_iterator<float> U(1.f);
    thrust::constant_iterator<float> V(4.f);
    thrust::transform(U, U+workSize, V, result.begin(), AdditionFunctor());
    if(workSize < 128) display(result, "result");
}</pre>
```

We use far less memory, and so computations are done faster ;-)

Another example is the ZIP iterator: addition of three vectors:

#### where the functor is:

```
// function that adds three elements and returns a new one
typedef thrust::tuple<float, float, float> myFloat3;
class AdditionFunctor3 : public thrust::unary_function<myFloat3, float> {
    public:
        --device-- float operator()(const myFloat3& tuple) {
            return thrust::get<0>(tuple) + thrust::get<1>(tuple) + thrust::get<2>(tuple);
};
};
```

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#### Introduction

#### Why a theoretical model?

Sequential computation: TURING's machine

- Algorithm cost (Computability and Complexity)
- Polynomial problem or NP-complete

#### Parallelism:

- Communication cost? Simpler is to ignore it!
- Imperfect model, but useful to classify algorithms (their complexity)
- We will speak about maximal parallelism

#### PRAM model

Main memory is  $\infty$ , shared among all PE ( $\infty$  of them)

- CRCW: Concurrent Read Concurrent Write
  - Concurrent Writing: consistent, arbitrary or fusion modes
- CREW: Concurrent Read Exclusive Write
- EREW: Exclusive Read Exclusive Write

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#### Goals

Writing a parallel algorithm is very complicated!

- Race condition, deadlock, ...
- Generally we start with a sequential solution

We need some well known parallel patterns:

- Pattern: software engineering solution to common problem
- Tools to write parallel algorithms efficiently

You should already know:

- MAP (or transform)
- SCAN and PRESCAN
- GATHER and SCATTER

The following is a catalog using PRAM and Thrust ...

# A CUDA specific pattern: BLOCKING

#### Problems:

- DRAM accesses must be coalescent for efficiency!
- DRAM latency is high ... avoid it for reading and writing!

#### BLOCKING solution:

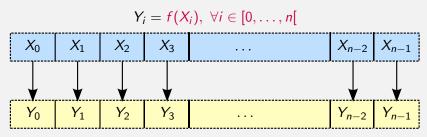
- Logically partition data in well-sized blocks
  - Small enough to be staged into limited shared memory
- Use a sufficient number of blocks
- In each block, threads load data into shared memory
- Do the computation, using shared memory only
- Threads write the final result to DRAM

In each block, a thread is responsible to load/write a piece of memory in a coalescent way!

## MAP

#### MAP is a one-to-one operation:

- For a given function f, an input array X of size n ...
- It computes the array *Y* of size *n* such that:



In Thrust, use the thrust::transform functions:

- Some for thrust::unary\_function
- And some for thrust::binary\_function

# Exercise: Add vectors

## Just try the previous examples, by doing it yourself ...

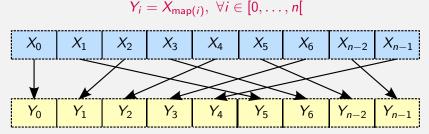
- lacktriangle For two vectors containing data on the host (with at least  $2^{16}$  values)
- For two vectors of the same size, but using counting and constant iterators
- For three vectors (on CPU) of the same size

For each question, check its computation time (launch the calculation two or three times in a loop before to measure the time, since GPU takes some time to wake-up).

#### **GATHER**

Read data from arbitrary location to write contiguous values:

- Let X be an entry of size n, map(i) being a function returning a new index
- The result is a set of contiguous values *Y* of size *n* such that:



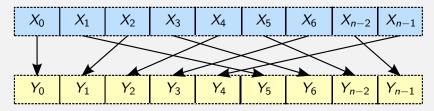
- In this figure: the map indicating from where output data come from is  $\{0, 2, 4, 6, 8, 1, 3, 5, 7\}$
- In Thrust, it is implemented by functions thrust::gather
- Important to retain: the results are consecutively filled ...

# **SCATTER**

#### Read consecutive data to write values in arbitrary locations:

- Let X be an entry of size n, map(i) being a function returning an index into  $[0, \ldots, n[$
- The result is a set of values Y of size n such that:

$$Y_{\mathsf{map}(i)} = X_i, \ \forall i \in [0, \dots, n[$$



- In this figure, the map is  $\{0, 5, 1, 6, 2, 7, 3, 8, 4\}$
- In Thrust, it is implemented by functions thrust::scatter
- Difference with GATHER? Consecutive Read, not Write ...

# MAP, GATHER & SCATTER using PRAM

#### MAP in PRAM

```
1 MAP(X, f)
        \{X \text{ is an array of size N, } f \text{ a unary function } \}
        FOR each PE i in parallel
              Y_i \leftarrow f(X_i)
        RETURN Y
```

#### GATHER in PRAM

```
GATHER(X, Map)
      \{ X \text{ and } Map \text{ are two arrays of size } N \}
     FOR each PE i in parallel
           Y_i \leftarrow X_{Map_i}
     RETURN Y
```

#### SCATTER in PRAM

```
SCATTER(X, Map)
     \{ X \text{ and } Map \text{ are two arrays of size N } \}
     FOR each PE i in parallel
           Y_{Map_i} \leftarrow X_i
     RETURN Y
```

# Exercise: Odd-Even

## Separate the numbers by odd and even index ...

Write two functions that takes as input a large vector of integers, and that separates and returns the same vector containing first the data at even indexes and then the ones at odd indexes. First function uses GATHER, second SCATTER.

e.g.: 
$$\{7,5,14,10,21,15,28\}$$
 becomes  $\{7,14,21,28,5,10,15\}$ .

Hint: transform\_iterator and counting\_iterator may help you.

② Do the same but for more heavy objects (records containing some useless data).

For each exercise, check its computation time (launch the calculation two or three times in a loop before to measure the time, since GPU takes some time to wake-up).