# Quan Nguyen

Curriculum Vitae

Horner Weg 201C Hamburg, 22111 ⊠ manhquan233@gmail.com '• https://github.com/ngmq/



#### Education

- 2015–2017 **University of Hamburg**, *Current GPA: 1.19*, Master candidate, *Intelligent Adaptive Systems*. Thesis: Object proposal generation applying distance dependent Dirichlet processes for superpixels clustering with learning features.
- 2009–2014 **FPT University**, *Degree type: Very Good*, Bachelors of Engineering, *Software Engineering*. Thesis: Indoor Robot Localization.

#### Honors and Awards

- 2017 **Second prize**, Instagram Machine Learning Competition.
- 2013 Bronze prize, Vietnam ACM ICPC National Algorithm Programming Competition.
- 2013 First prize, FPT University ACM ICPC Programming Competition.
- 2009 2014 Full scholarships for Undergraduate study in Software Engineering, FPT University.
  - 2009 Odon Vallet scholarship for exceptional Vietnamese high school students.
  - 2009 Third prize, Vietnam High School National Physics Contest.
  - 2009 **Second Prize**, Annual Contest of Mathematics and Youth magazine.

# Conference papers

- [1] Nikhil Churamani, Paul Anton, Marc Bruegger, Erik Fliesswasser, Thomas Hummel, Julius Mayer, Waleed Mustafa, Hwei Geok Ng, Thi Linh Chi Nguyen, **Quan Nguyen**, Marcus Soll, Sebastian Springenberg, Sascha Griffiths, Stefan Heinrich, Nicolas Navarro-Guerrero, Erik Strahl, Johannes Twiefel, Cornelius Weber, Stefan Wermter. (2017). *The Impact of Personalisation on Human-Robot Interaction in Learning Scenarios*. Proceedings of the Fifth International Conference on Human Agent Interaction, pages 171–180, doi:10.1145/3125739.3125756.
- [2] Hwei Geok Ng, Paul Anton, Marc Bruegger, Nikhil Churamani, Erik Fliesswasser, Thomas Hummel, Julius Mayer, Waleed Mustafa, Thi Linh Chi Nguyen, **Quan Nguyen**, Marcus Soll, Sebastian Springenberg, Sascha Griffiths, Stefan Heinrich, Nicolas Navarro-Guerrero, Erik Strahl, Johannes Twiefel, Cornelius Weber, Stefan Wermter. (2017). *Hey Robot, Why Don't You Talk To Me?*. Proceedings of the IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN), pages 728–731.

# Technical Reports

- [1] Quan Nguyen. (2016). Simplified spiking neural network model applied to handwritten digit recognition. Neural Networks Seminar, University of Hamburg.
- [2] Quan Nguyen. (2016). *Recurrent Neural Networks for Sequential Image Processing*. Bio-inspired Artificial Intelligence Seminar, University of Hamburg.
- [3] Quan Nguyen. (2015). Low variance sampling for Particle Filter. Intelligent Robotics Seminar, University of Hamburg.
- [4] Quan Nguyen (2015). *Information Retrieval and Ranking in InfoSearch*. Knowledge Processing Seminar, University of Hamburg.

#### Skills & Abilities

Al methods Machine Learning, Computer Vision, Natural Language Processing, Nonpara-

METRIC STATISTICS, BAYESIAN STATISTICS

Programming C/C++, Python, R, MATLAB

Languages

Frameworks OPENCV, NUMPY, CAFFE, TENSORFLOW, KERAS, ROS

## Machine Learning Projects

September Object proposal generation applying distance dependent Dirichlet processes for super-2017 – Now pixels clustering with learning features, MASTER THESIS.

Developing a probabilistic framework object proposals generation with focus on addressing two of the most frequent criticisms in object detection systems: 1) superpixels-based approaches are highly susceptible to even small pertubations in illumination or rotations (Hosang et. al, 2015) and 2) Object-Proposal Evaluation Protocol is 'Gameable' (Chavali et. al, 2016)

July 2017 – Excitation Back-propagation for saliency detection systems on PASCAL-S dataset, Cog-September NITIVE COMPUTER VISION LAB.

2017 Analyzed the suitability of the PASCAL-S dataset for saliency detection task. This work resulted in a technical report that contains a comprehensive list of images and their ground truths that are more suitable for object dection rather than saliency detection, effectively indicating a certain amount of flawness in this popular dataset.

April 2017 – Gender recognition using deep learning on Fei Dataset, Cognitive Computer Vision May 2017 Course.

Built and trained a convolutional neural network (CNN) capable of recognizing gender in Fei dataset. This model achieved a state of the art performance of 97% accuracy. The model and analyses were done in Python using Keras with Tensorflow backend. Code and analysis are available at https://github.com/ngmq/AI/tree/master/Fei%20FaceDatabase

March 2017 – Bottom-up Saliency detection with VOCUS2 system, Cognitive Computer Vision May 2017 Course.

Built a bottom-up saliency system that is able to construct saliency map from Intensity, Orientations, Lab color channels contrast features. Framework: OpenCV with C++. Code available at https://github.com/ngmq/SaliencyDetection

October 2016 Interactive Neural-Inspired Companion Robot, MASTER PROJECT.

- March 2017 Built and trained several deep learning models for Noun Phrase chunking, Named Entity Recognition and Speech recognition in Natural Language Understanding model for a robotic system. The model successfully learned end-to-end tasks with minimal preprocessing and was later used in a study on social impact of interactive robots. Framework: Natural language processing toolkit NLTK, Tensorflow. Video accepted to 26th IEEE International Symposium on Robot and Human Interactive Communication RO-MAN 2017. Paper accepted to 40th German Conference on Artificial Intelligence KI 2017.

October 2015 Low variance sampling for Particle Filter, INTELLIGENT ROBOTICS SEMINAR.

- January Researched and implemented the effect of difference sampling techniques on performance of Particle Filter.

2016 Technical report available at https://www.researchgate.net

December Indoor Robot Localization, Bachelor Thesis.

2013 – May Implemented an indoor localization mechanism for robots based on their received wireless signals. Tech-2014 niques and Framework: Kalman Filter and Particle Filter using Java

#### Work Experience

July 2017 - Research Assistant, Cognitive Computer Vision Group, University of Hamburg.

May 2015 – **Embedded Software Developer**, FPT SOFTWARE.

September Developed and maintained functionalities in franking machines for Neopost customers.

2014

## Languages

English Fluent

Vietnamese Native Speaker

### References

[1] **Prof. Simone Frintrop**, Department of Informatics, University of Hamburg. Email: frintrop@informatik.uni-hamburg.de

[2] Dr. Mikko Lauri, Department of Informatics, University of Hamburg. Email: lauri@informatik.uni-hamburg.de

[3] Dr. Sven Magg (Lecturer), Department of Informatics, University of Hamburg. Email: magg@informatik.uni-hamburg.de

[4] Prof. Victor Uc-Cetina, Computational Learning and Imaging Research, Universidad Autonoma de Yucatan.

Email: uccetina@uady.mx