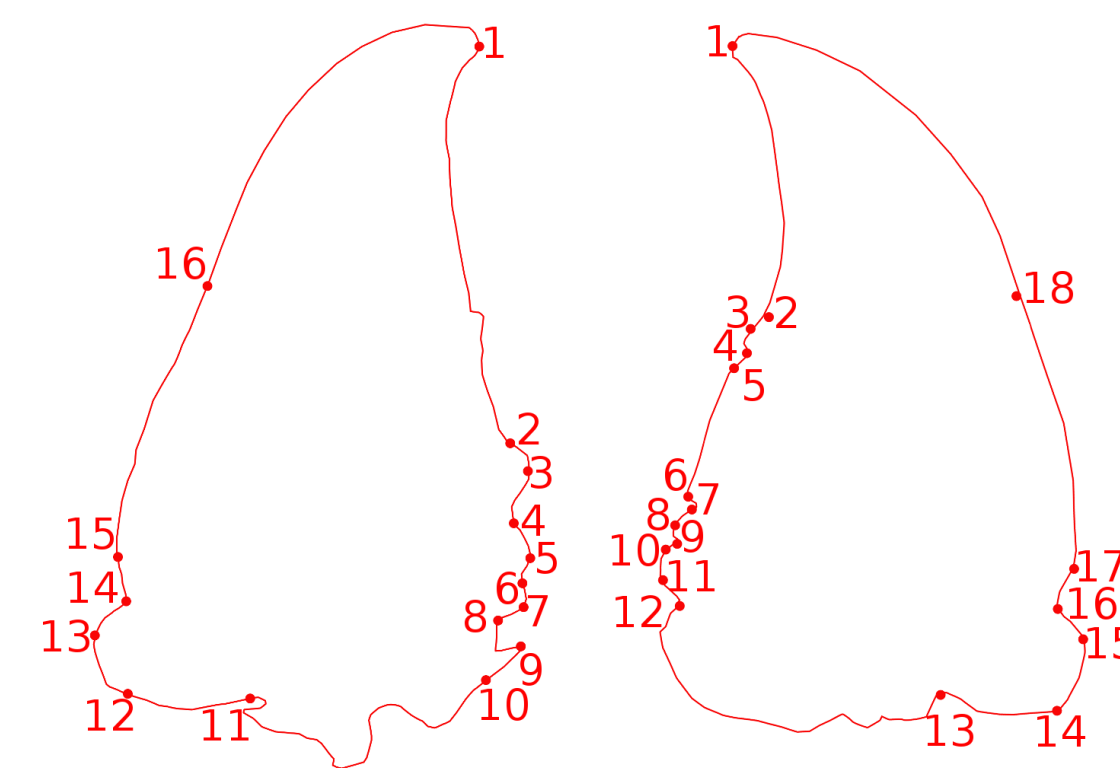


## Context

Morphometry analysis is a way to distinguish the characteristics of organisms, i.e. *shape, size, form,...*. It is used to appreciate the covariances between the ecological factors and the organisms. Landmark-based morphometry is known as one of the approaches to analyze the characteristics of organisms. Finding enough landmarks can give to biologists a comprehensive description of the organism. This work focuses on the automatic identification of landmarks on 2D biological images.

## Landmarks

- Morphometric landmarks are points of interest in the biological object. They usually stay along the outline of the image.
- Landmarks characterize specificities through the shape most often linked to biological information,
- They are usually **defined manually** by biologists,
- Images at the right side show manual landmarks in **beetle mandibles** belonging to our sample:  
 16 and 18 manual landmarks have been defined for each left mandible and right mandible, respectively.



## How to locate the landmarks automatically?

## Mandibles and manual landmarks

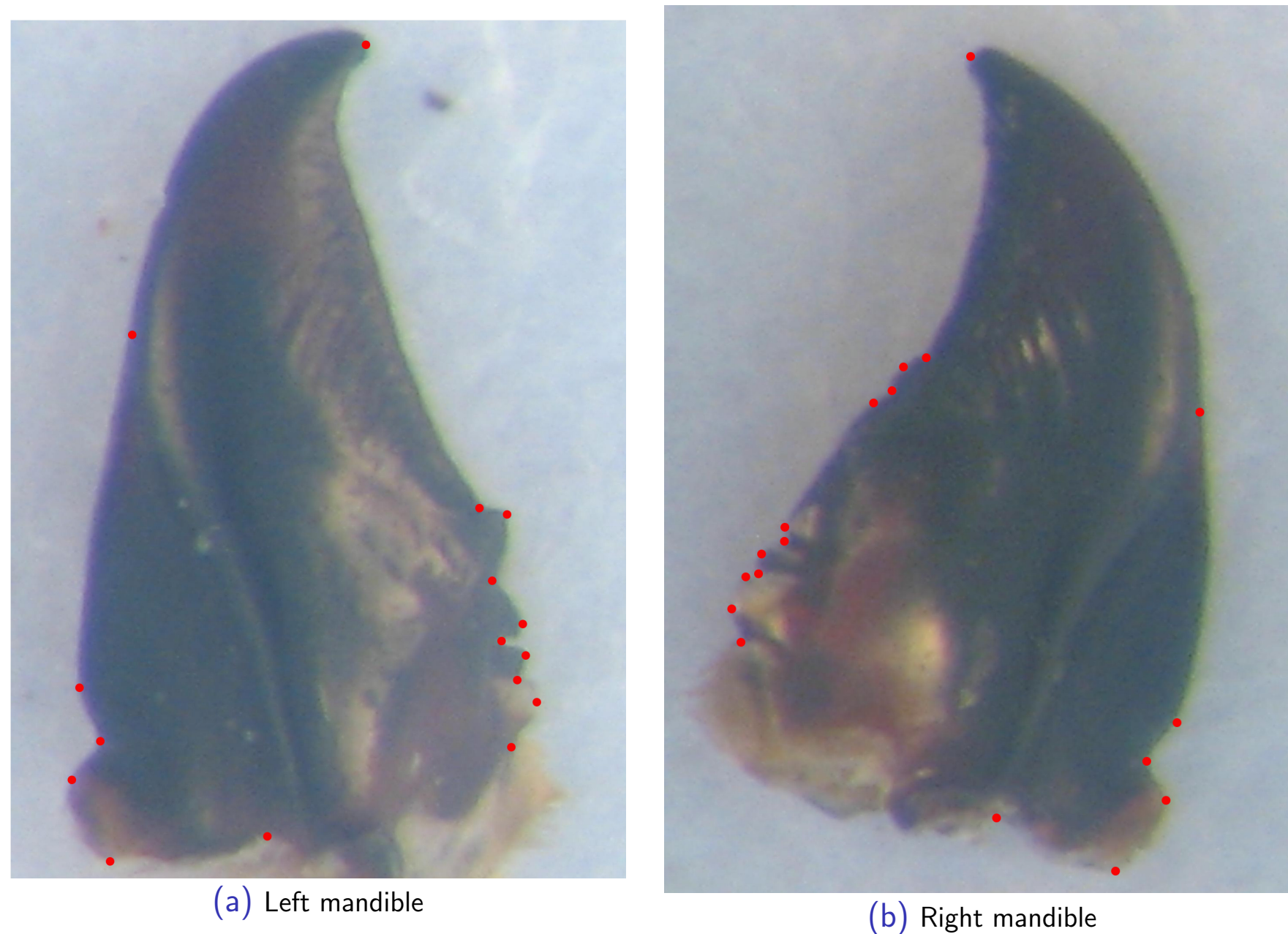
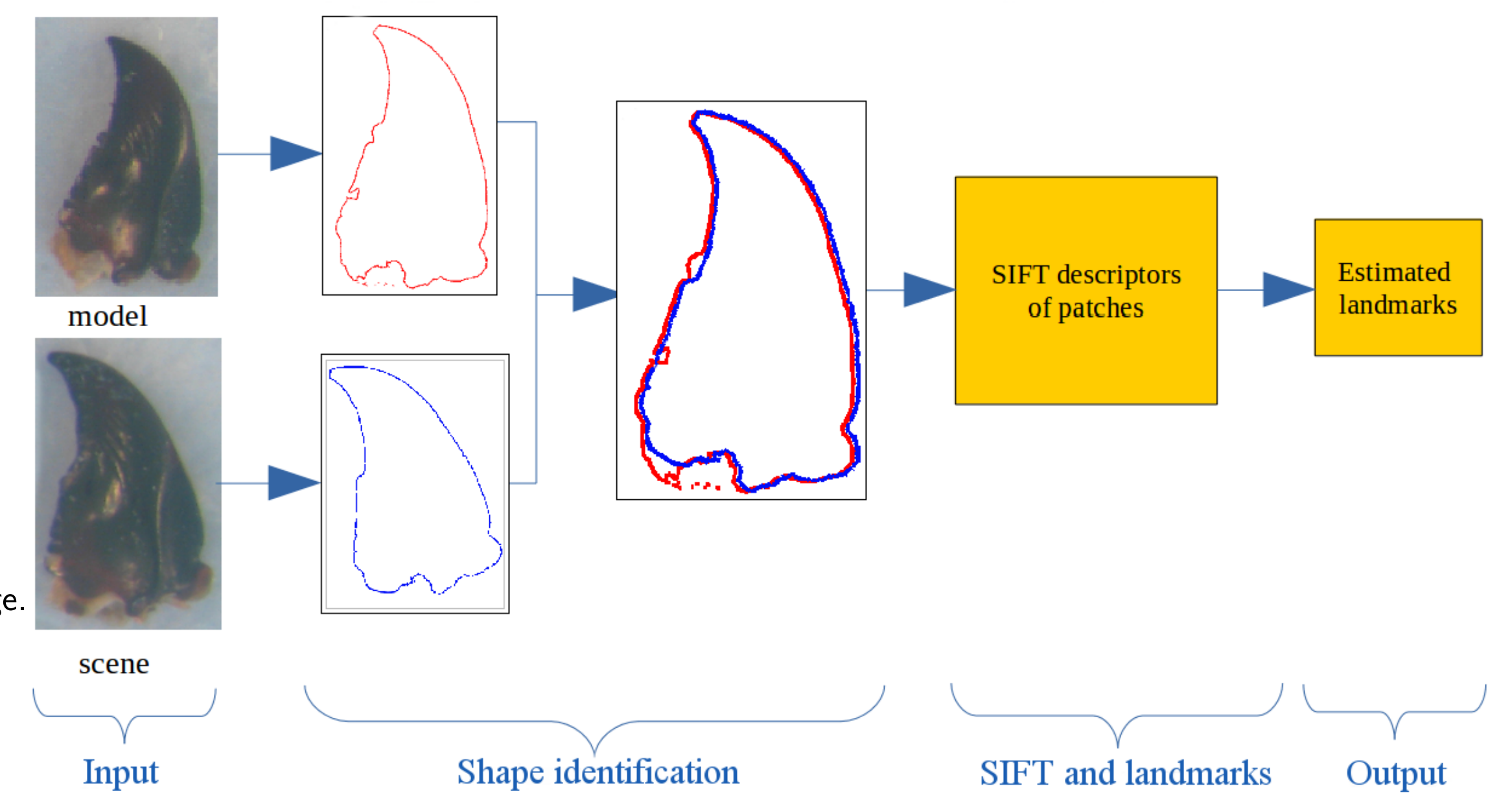


Figure: Example of beetle mandibles from the studied data set with manual landmarks.

## Proposed method

- **Input:**
  - A model image
  - The manual landmarks of model image
  - A scene image
- **Output:**
  - Landmarks of scene image
- **Steps:**
  - Shape identification: segmentation and registration
  - SIFT and landmarks: Extract the patches, calculate the SIFT descriptors and estimate the coordinates of landmarks on the scene image.



## Segmentation

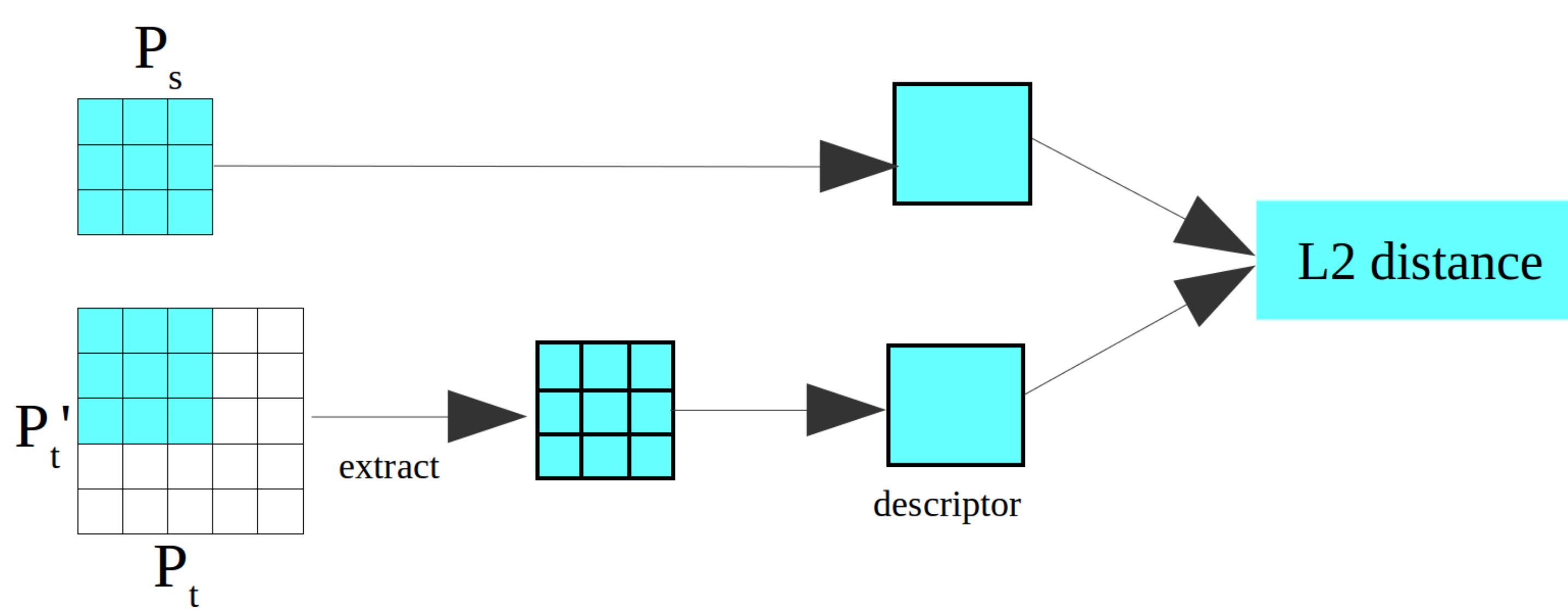
1. Converting the image to binary one by applying a threshold determined by histogram analysis [1],
2. Contours points are extracted by Canny algorithm [2]. The thresholds ratio in Canny:  $T_{lower} = (1/3) \times T_{upper}$ , in which  $T_{lower}$  equals to the threshold value in step 1.

## Registration

Model and scene images are segmented to extract the contours points. The contours points are registered by applying **Principal Component Analysis [3] Iteration (PCAI)**.

1. Compute the centroid point and principal axis of each list of contour points,
2. Compute the **translation** and **rotation** values between two lists of contour points,
3. **Register** the two lists of contour points,
4. Sort the contour points of scene image followed y-direction,
5. Select a subset of contour points of scene image and repeat step 1,
6. PCAI stop automatically when the **angle difference** between two lists of contour points is less than 1.5 **degree**.

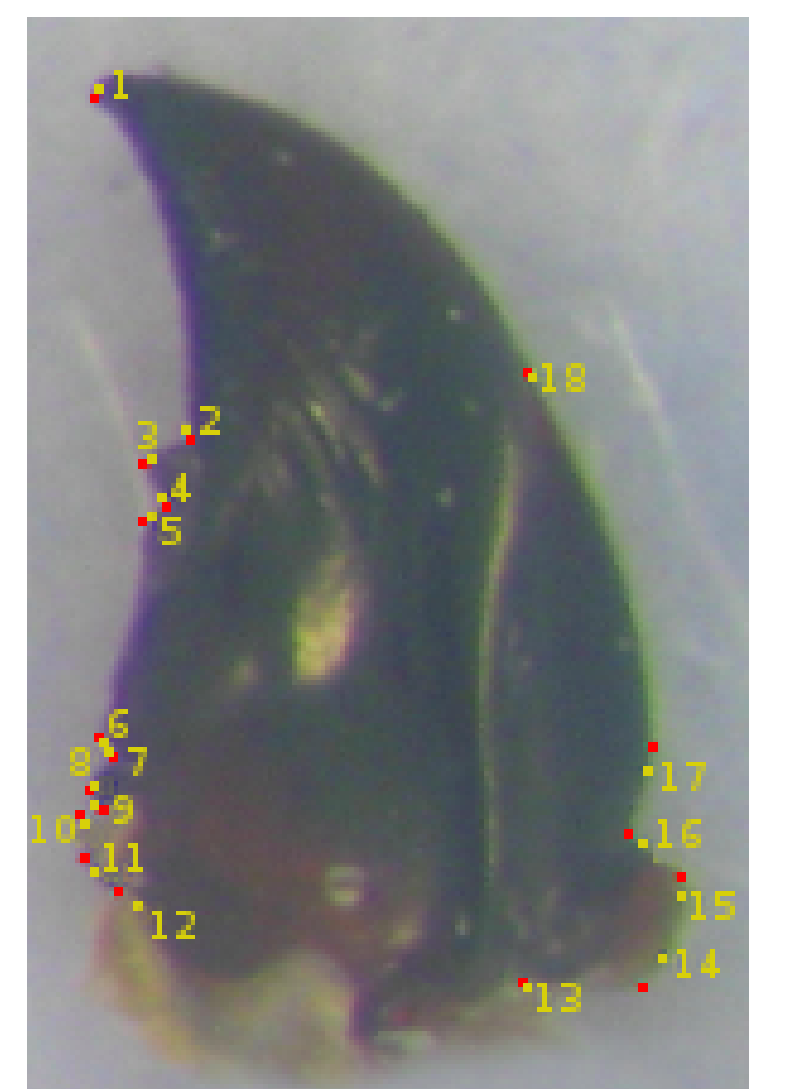
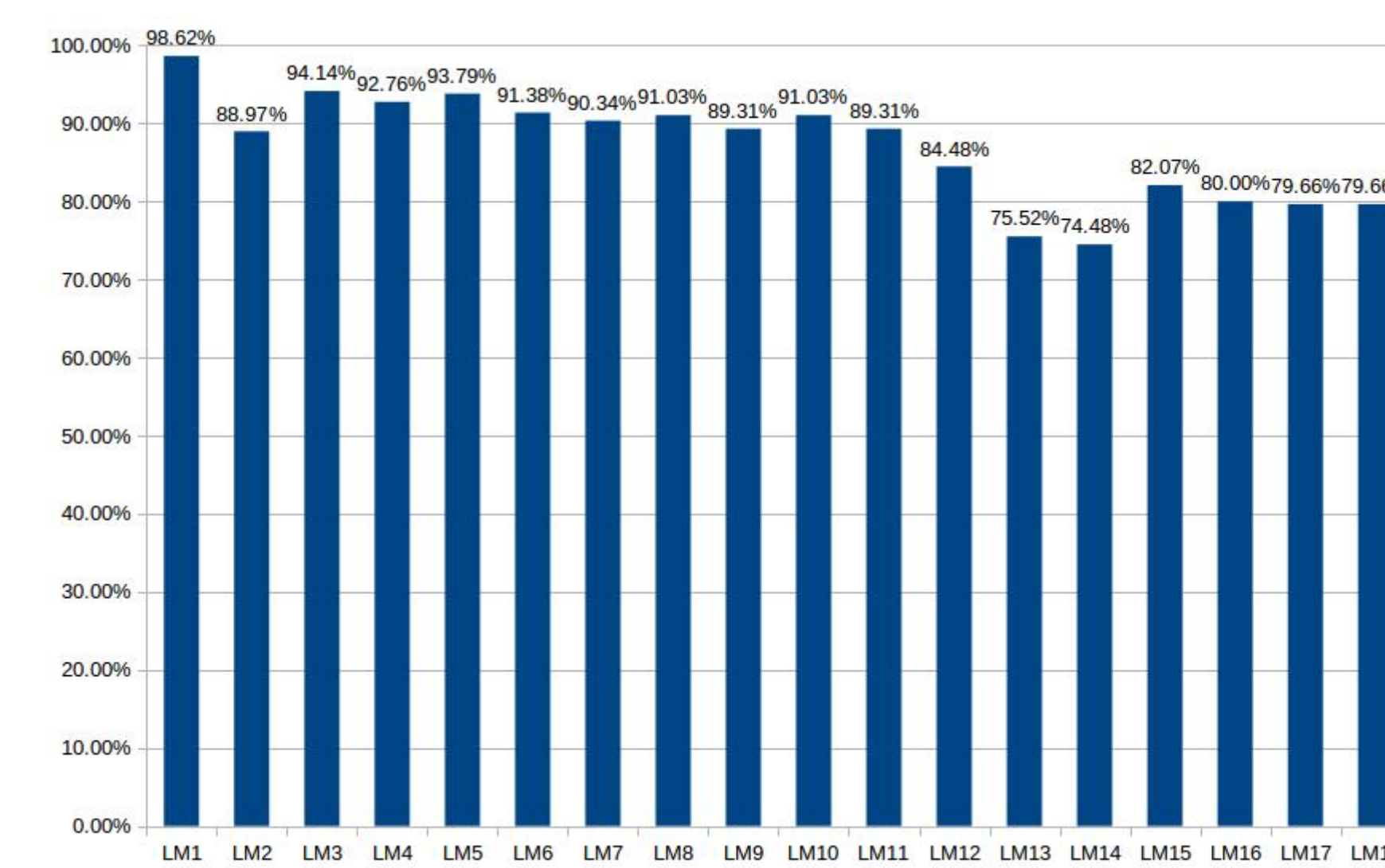
## SIFT and landmarks



1. A **patch**  $P_s$  is initialized at each manual landmark of model image (size of  $9 \times 9$ ),
2. Calculating the SIFT[4] descriptor for  $P_s$ ,
3. At the same position in the scene image, a patch  $P_t$  is created (size of  $36 \times 36$ ),
4. For each pixel in  $P_t$ , a patch  $P'_t$  is extracted with the same size than  $P_s$ ,
5. Calculating the SIFT descriptor for all  $P'_t$ ,
6. Computing the distance between the descriptor of  $P_s$  and each  $P'_t$ ,
7. At the end, the pixel that has the **minimum distance** with  $P_s$  is kept.

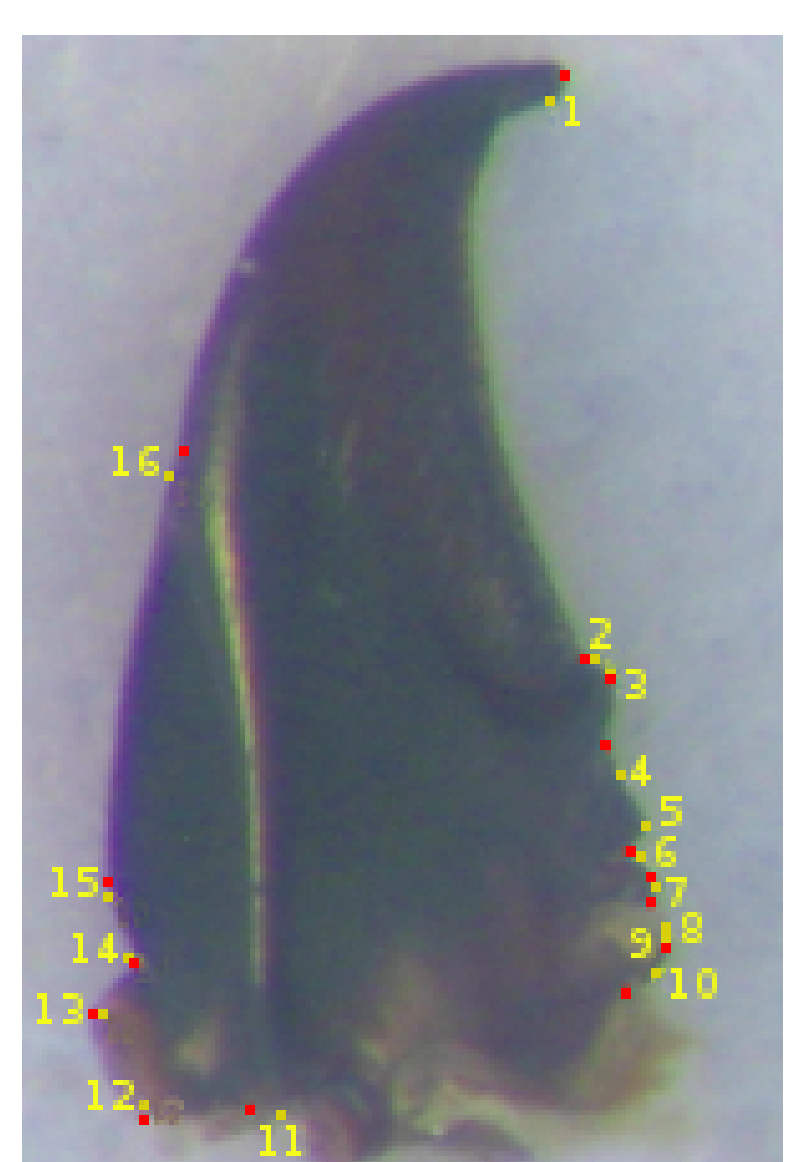
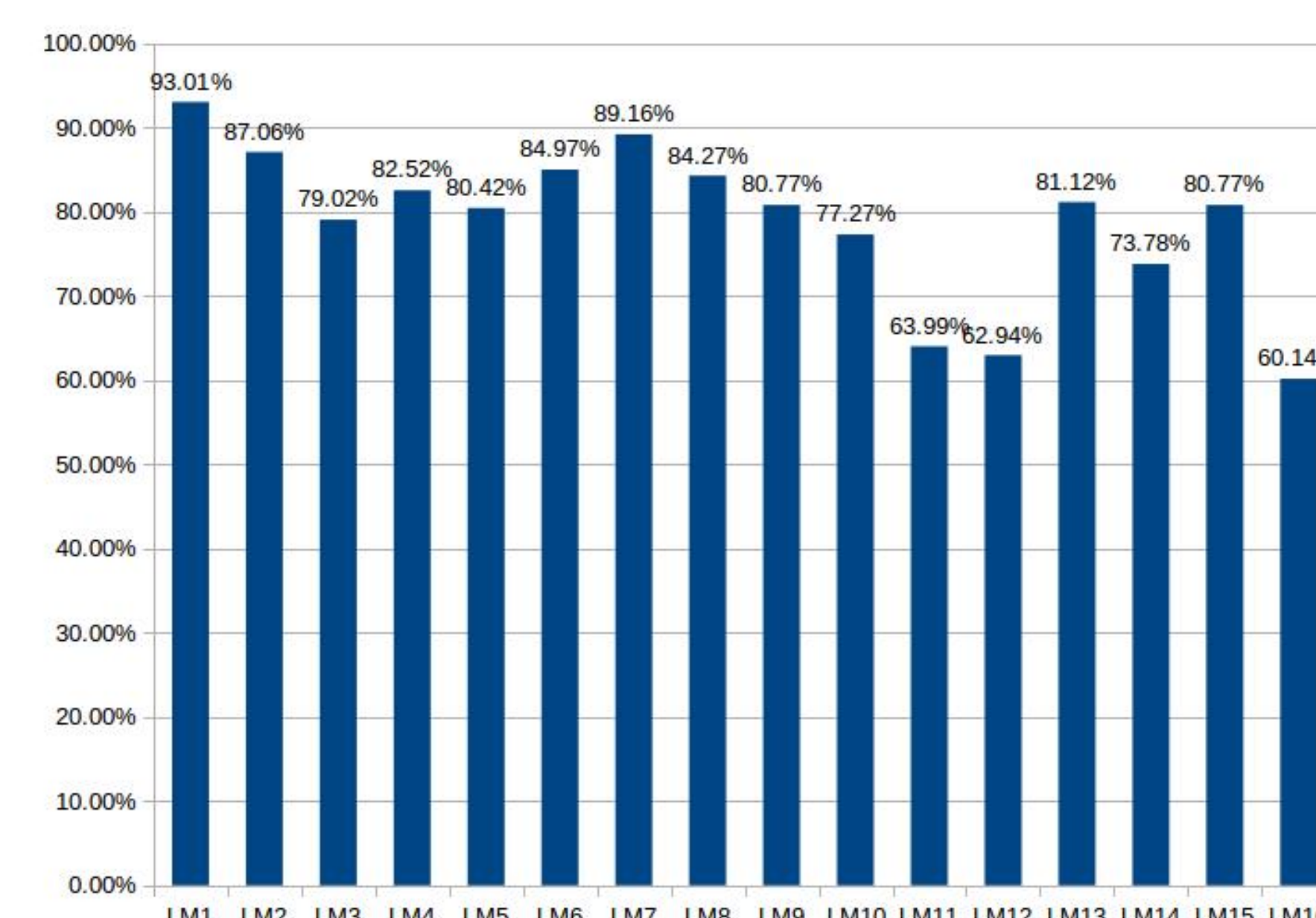
## Results on right mandibles

- Highest accuracy: 1<sup>st</sup> landmark with 98.62%
- Lowest accuracy: 13<sup>th</sup>, 14<sup>th</sup> landmark with app. 75%



## Results on left mandibles

- Highest accuracy: 1<sup>st</sup> landmark with 93.01%
- Lowest accuracy: 11<sup>th</sup>, 12<sup>th</sup> and 16<sup>th</sup> landmark from 60% to app. 63%



## Conclusion

- A solution based on SIFT descriptor for landmark estimation is presented,
- The results show that method **succeed in locating** all landmarks in request images,
- The accuracy of method is sufficient to be **proposed to biologists** as a **replacement of manual positioning**, and to characterize the shape.

## References

- [1] Marie Beurton-Aimar, Adrien Krähenbühl, Nicolas Parisey, et al. Maelab: a framework to automatize landmark estimation. In *WSCG 2017*, 2017.
- [2] John Canny. A computational approach to edge detection. *Pattern Analysis and Machine Intelligence, IEEE Transactions on*, (6):679–698, 1986.
- [3] Ian Jolliffe. *Principal component analysis*. Wiley Online Library, 2002.
- [4] David G Lowe. Object recognition from local scale-invariant features. In *Computer vision, 1999. The proceedings of the seventh IEEE international conference on*, volume 2, pages 1150–1157. Ieee, 1999.