# Automatic identification of landmarks by shape recognition

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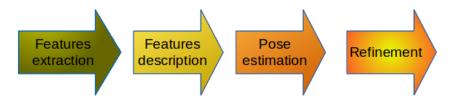


### Introduction

- Shape analysis by landmarks is increasingly used in biological and medical applications.
- Indicate the landmarks:
  - By hands
  - Automatically

### Introduction

The propose method<sup>[1]</sup> includes four steps:



# Segmentation

#### Purpose:

- Extract the features (edge) from images
- Get the approximate lines

#### Method:

- Indicate the threshold value by analysis histogram of image
- Canny
- Break edge algorithm

Result: The set of approximate lines

# Pairwise geometric histogram

Purpose: detecting the present of scene image in model image

Method<sup>[2]</sup>:

- Construct the local PGH
- Construct the shape PGH
- Matching shape's PGH by Bhattacharyya metric

# Pairwise geometric histogram Local PGH and shape PGH

Local PGH: PGH for each feature (line)
Shape PGH: contains many Local PGH

PGH: a matrix two dimensions: angle axis and distance axis

PGH information: angle between two lines and perpendicular distance from two endpoints of scene line to reference line.

## Probabilistic Hough Transform

- Purpose:
- Determine the presence and location of model image in scene image
  - Estimate the landmarks in the scene image
- Method:
- Construct the reference table
  - Find the pair scene lines have the best "vote"
  - Estimate the "reference point" in scene image
- Estimate the landmarks
- Result: Estimated model landmarks on scene image

# Probabilistic Hough Transform





# Template matching

Purpose: Refine the estimated landmarks on the scene image

### Method:

- On model image: For each landmark, create a bounding box with size "t1" and landmark is center point of box
- Rotate scene image to match with model
- On scene image: For each estimated landmark, create a bounding box with size "t2" and landmark is center point of box
- Sliding t1 on t2 and find the the best match (cross-correlation)

# Template matching





### Result

- Dataset: Mandibule droite and mandibule gauche
- Method can be estimated landmarks but the accuracy of the landmarks (compare with original landmarks) is not good.

#### References I



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Thacker, Neil A., P. A. Riocreux, and R. B. Yates.

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Image and Vision Computing, 13.5 (1995): 423-429.

# Thank you!