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Convolutional Neural Network

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http://www.labri.fr/perso/vle

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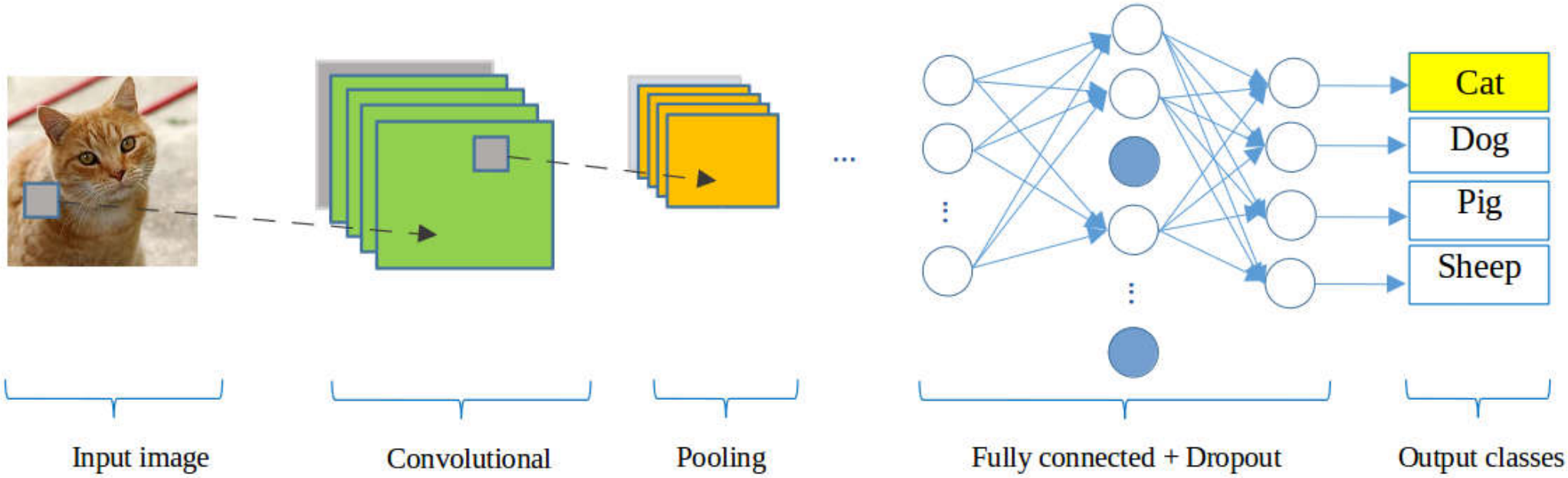
Architecture overview



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Architecture overview

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Similar with ordinary Neural Network:

- Make up of neurons that have learnable weights and bias
- Each neuron receives some inputs, perform a dot product and optionally follows it with a non-linearity function.
- Use different kinds of activation functions

However:

- The input are images
- Encode certain properties into the architecture
- Reduce the amount of parameters in the network
- Arrange in 3 dimensions: width, height, depth

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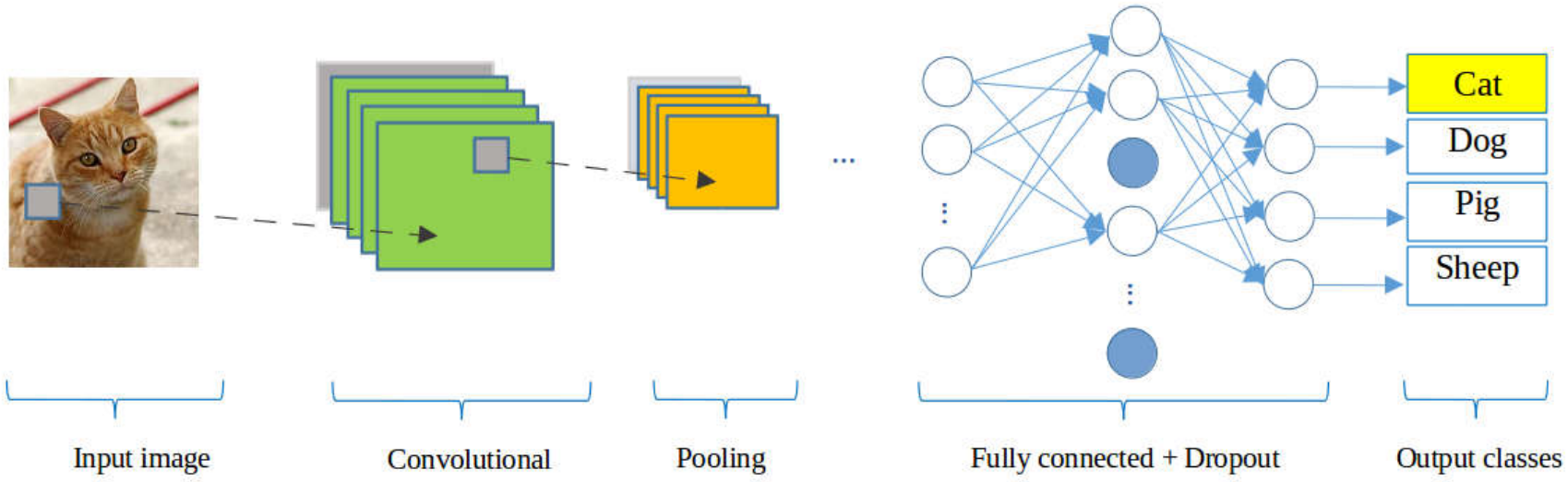
Convolutional Neural Network's Layers

Three main types of layers to build CNN architectures:

- Convolutional Layer
- Pooling layer
- Fully-Connected layer



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Convolutional Neural Network's Layers

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Convolutional Layer: is the core of CNN with the parameters consist of a set of learnable filters

- Accept a input of $(W_1 \times H_1 \times D_1)$
- Hyper-parameters: Number of filters K, filter size F, the stride S, amount of zero padding P
- Output with the size of $(W_2 \times H_2 \times D_2)$, where:

$$W_2 = (W_1 - F + 2P)/S + 1$$

$$H_2 = (H_1 - F + 2P)/S + 1$$

$$D_2 = K$$

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Convolutional Neural Network's Layers

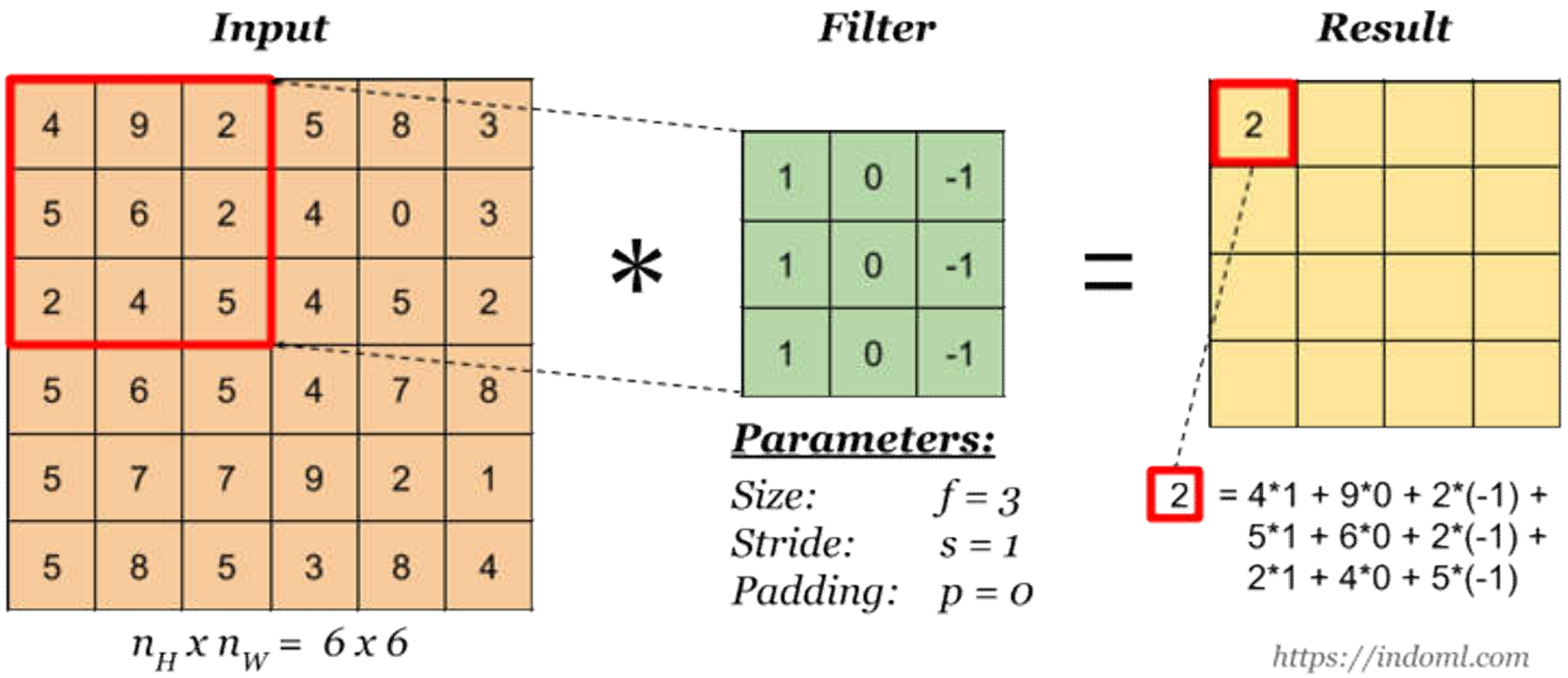

Image from indoml.com

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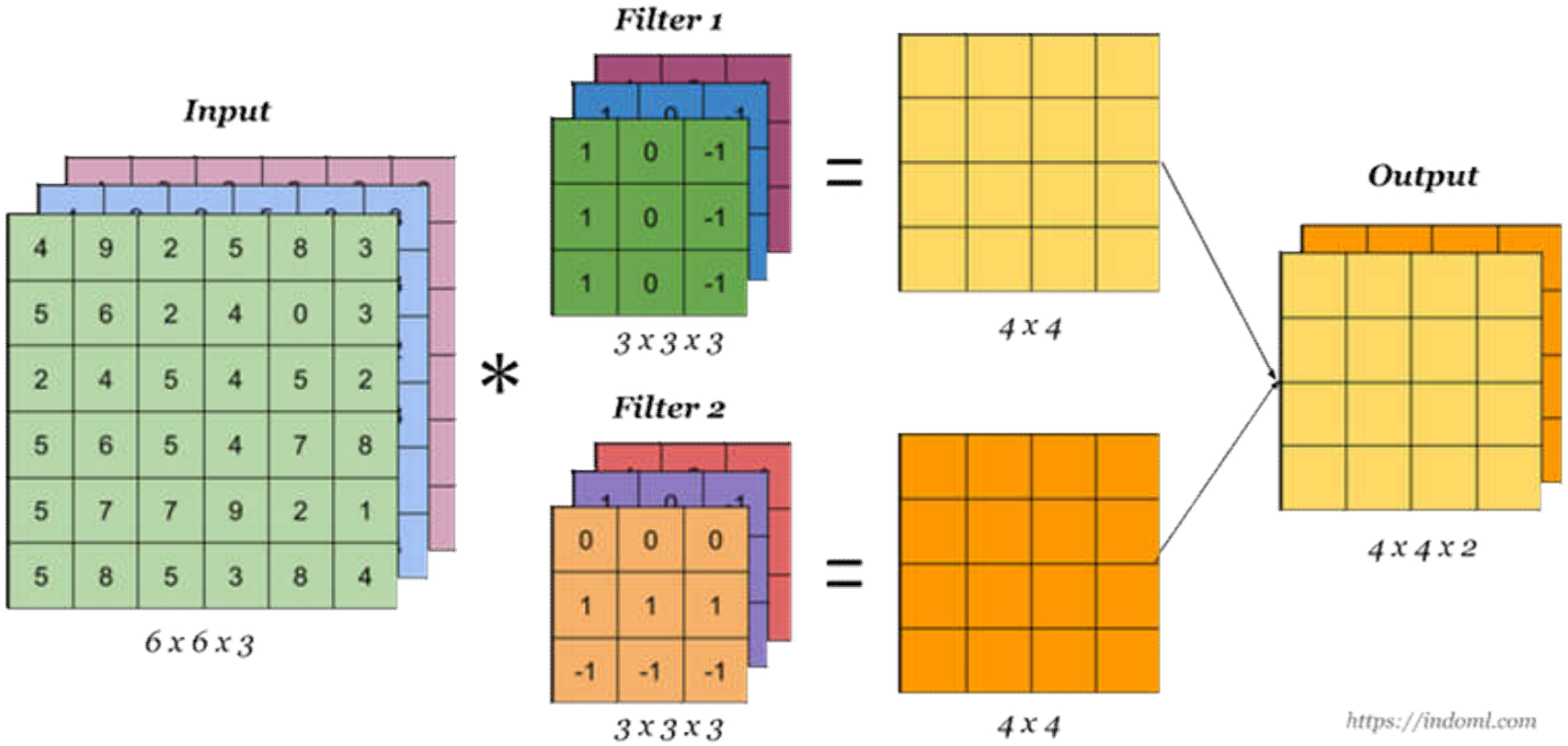
Convolutional Neural Network's Layers



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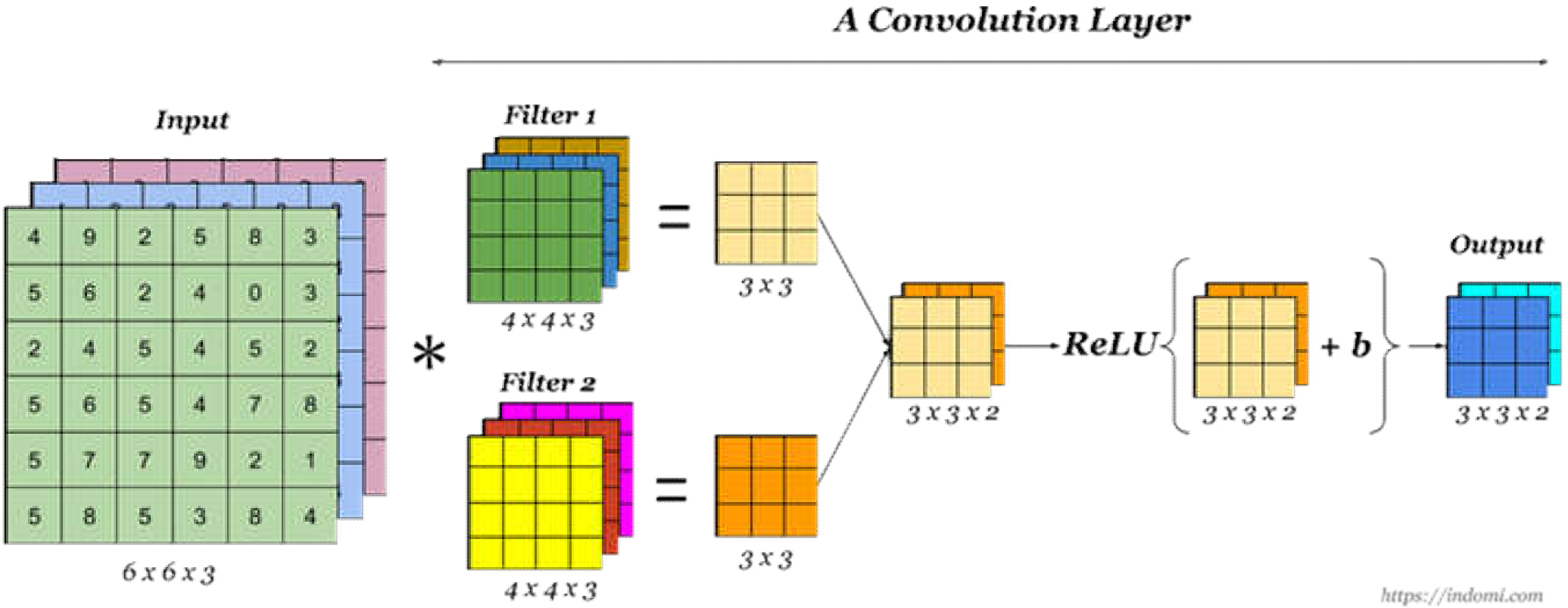
Convolutional Neural Network's Layers



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Convolutional Neural Network's Layers

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Pooling layer:

- Reduce the spatial size of the representation
- Reduce the amount of parameters and computation
- Control overfitting
- Two common types of pooling: MAX and AVERAGE

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Convolutional Neural Network's Layers

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Pooling layer:

- Accept a input of $(W_1 \times H_1 \times D_1)$
- Hyper-parameters: filter size F, the stride S,
- Output with the size of $(W_2 \times H_2 \times D_2)$, where:

$$W_2 = (W_1 - F)/S + 1$$

$$H_2 = (H_1 - F)/S + 1$$

$$D_2 = D_1$$

The pooling layer have **zero** parameters

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Convolutional Neural Network's Layers

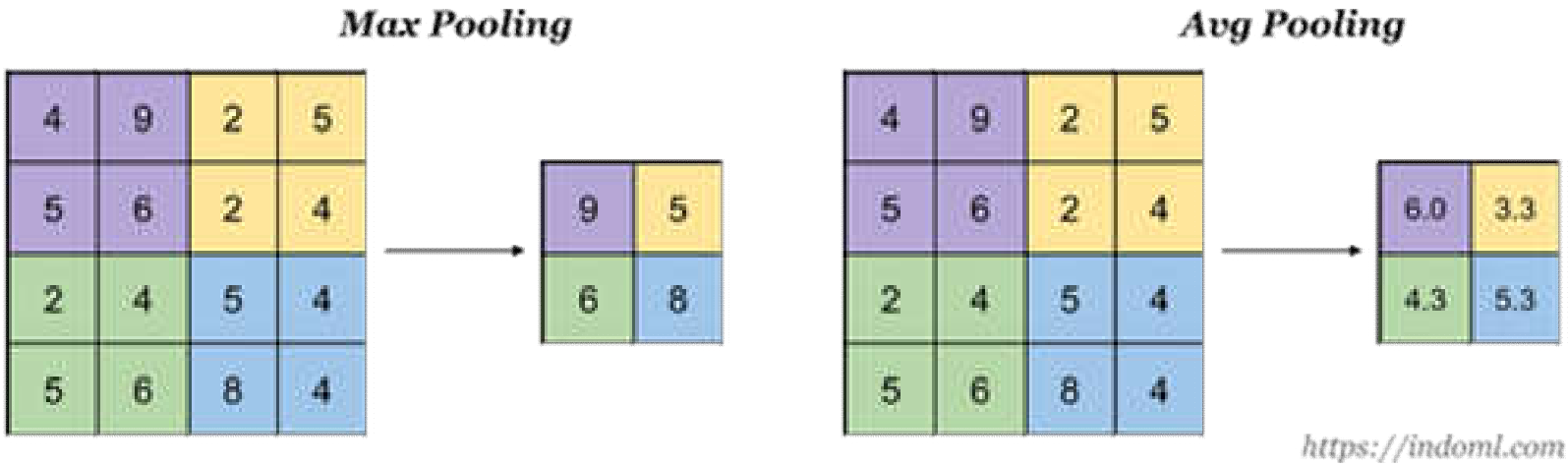

Image from indoml.com

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Convolutional Neural Network's Layers

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Fully-connected layer:

- Have full connections to all activations in previous layer
- Their computation is the same as in regular Neural Network

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Case studies

LeNet-5: ~ 60 thousands parameters

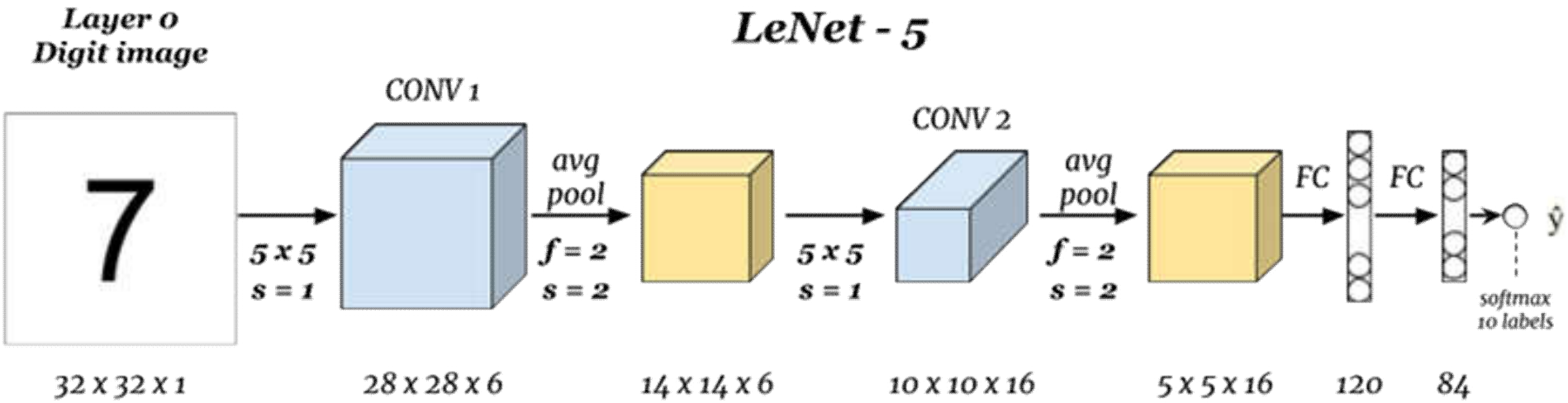

Image from indoml.com

Y. Lecun, L. Bottou, Y. Bengio and P. Haffner, *Gradient-Based Learning Applied to Document Recognition*, 1998

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Case studies

AlexNet: ~ 60 millions parameters

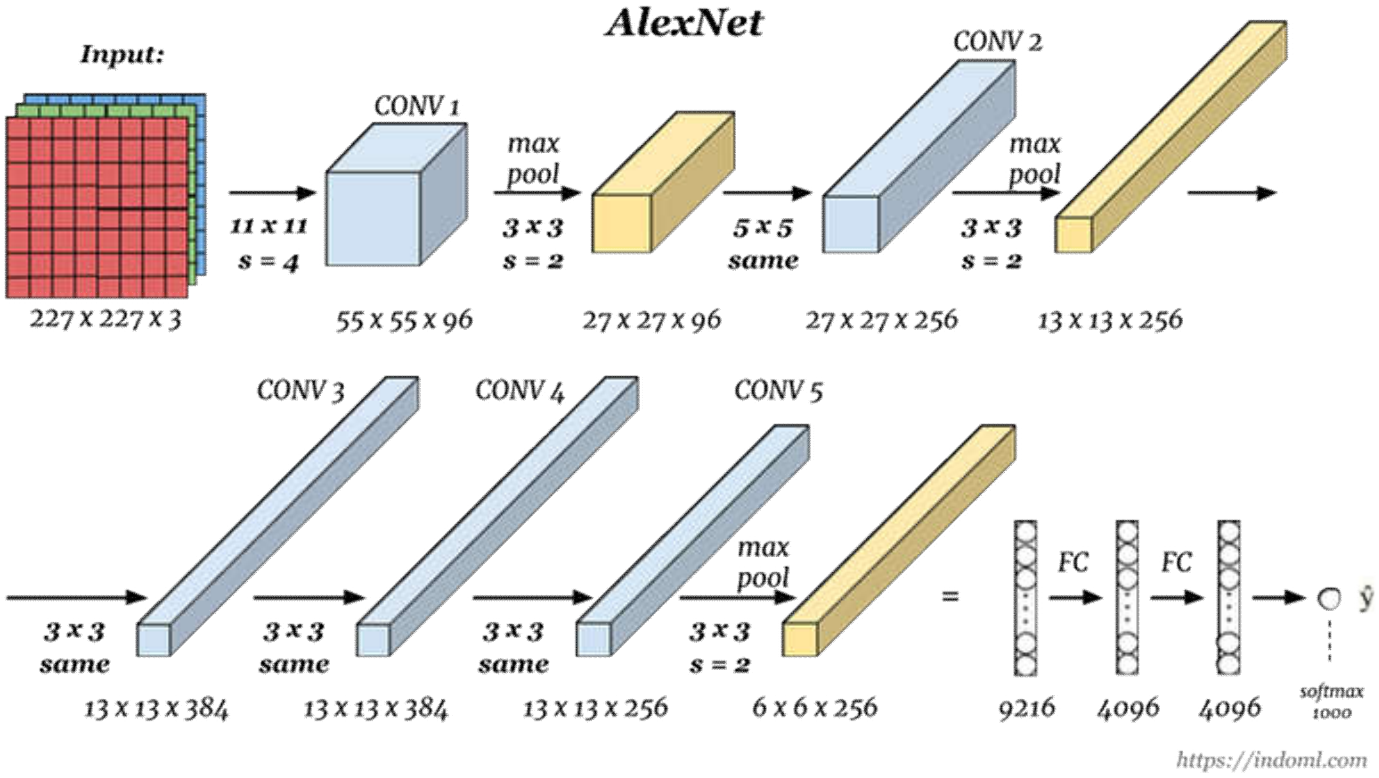

Image from indoml.com

Alex Krizhevsky, Geoffrey Hinton, and Ilya Sutskever, *Classification with Deep Convolutional Neural Networks*, 2012

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Case studies

VGG-16: ~ 38 millions parameters

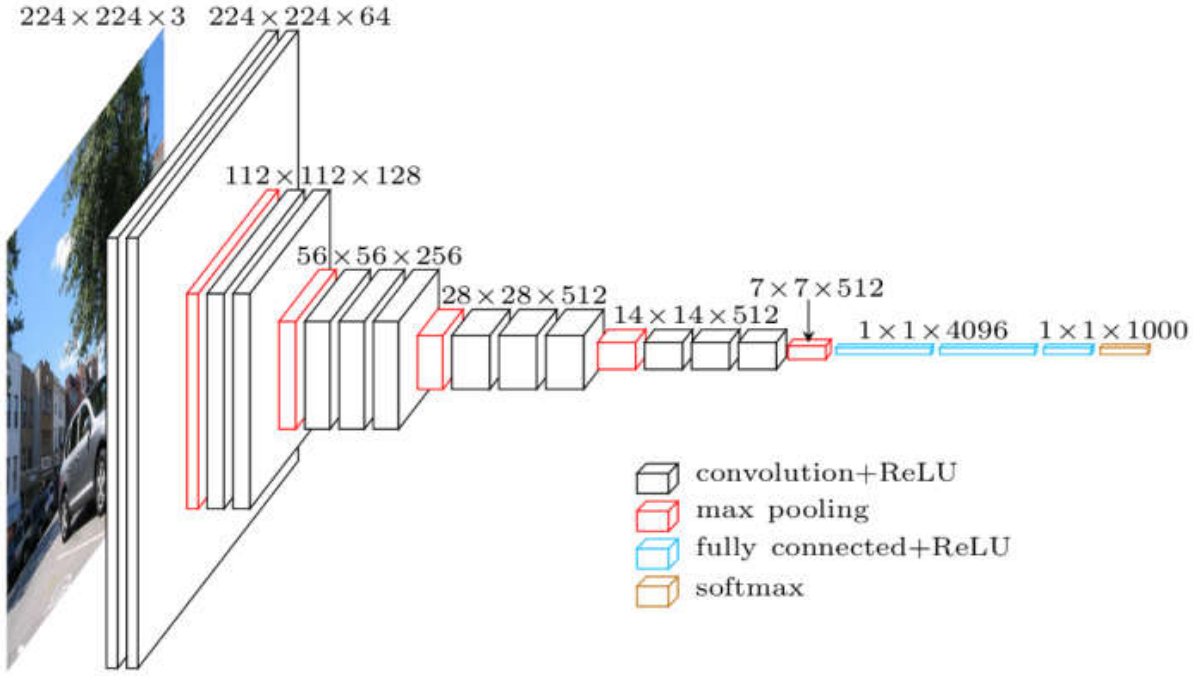

Image from blog.heuritech.com

Karen Simonyan and Andrew Zisserman, *Very Deep Convolutional Networks for Large-Scale Image Recognition*, 2014

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Case studies

ResNet: use skip connections

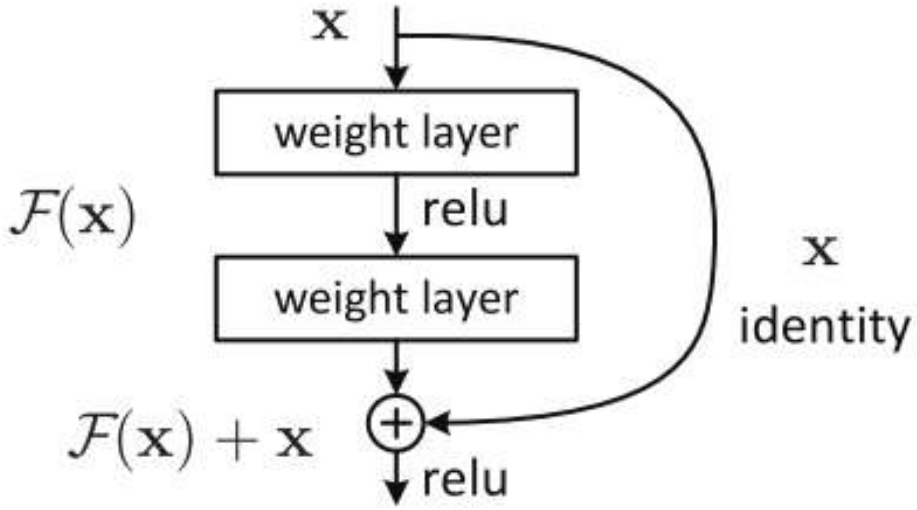
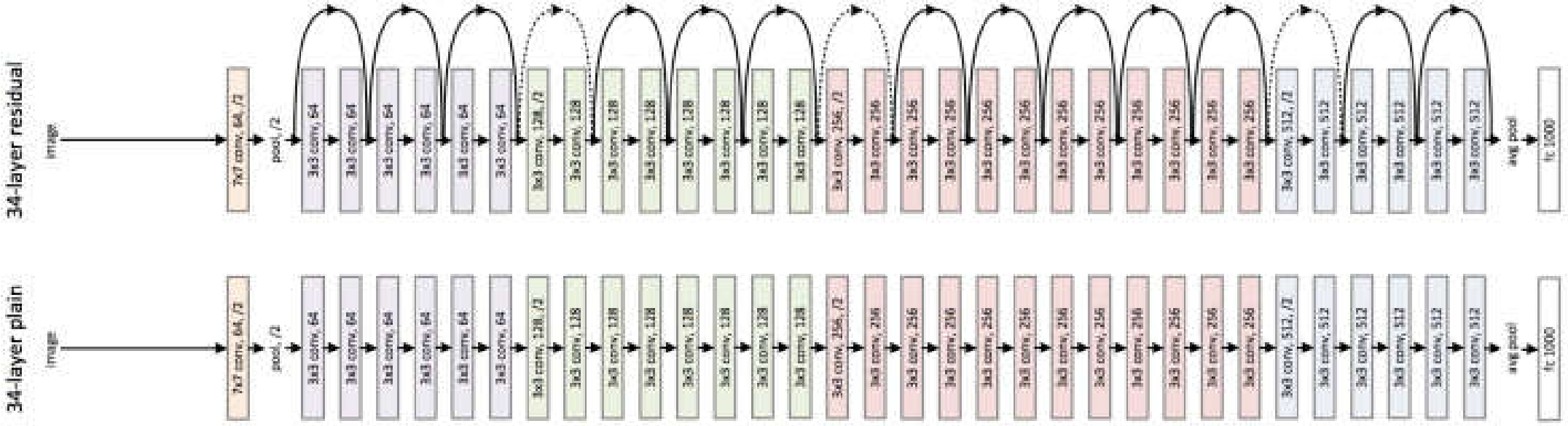


Image from medium.com

He at al, *Deep Residual Learning for Image Recognition paper* , 2015/ Image from medium.com

Case studies

ResNet: use skip connections



He at al, *Deep Residual Learning for Image Recognition paper* , 2015/ Image from euler.stat.yale.edu

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4. **Implement a CNN in PyTorch**

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Implement a CNN in PyTorch

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Preparer:

- Data: MNIST for example
- Model: How many CONV layers, POOL layers, FC layers
- Hyper-parameters: number of epochs, loss functions, ….

Process:

- Like the neural network
- Use different kinds of layers in PyTorch library

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