

Otto DIY Quadruped robot



VIEW IN BROWSER

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Summary

A great mix of 2 great opensource robots Otto and Kame, giving the ability to move around in a more dynamic way.

<u>Hobby & Makers</u> > <u>RC & Robotics</u>

Tags: quad robot spider arduino quadruped ottodiy

Quad was inspired was inspired by #OttoDIY hat we all know;) and MiniKame is a little quadruped robot based on an ESP8266 WiFi module. It has 8 servos (two per leg) and a small LiPo battery.

Print instructions

Recommended to use a FDM 3D printer with PLA material.

No need supports or rafts.

Resolution: 0.3mm or 0.2mm for better resolution

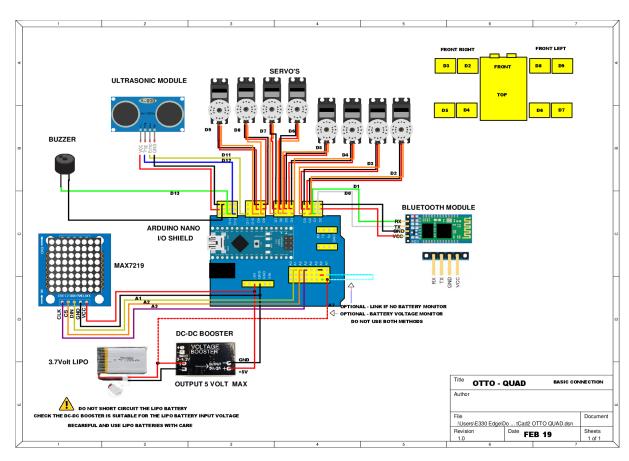
Fill density: 15%

Features

- Simple Programming with Otto Blockly or Arduino
- Instruction manual included
- Walks & dances
- Makes emotional sounds and melodies

List of Parts

- Otto Nano Microcontroller + I/O board
- Micro USB cable
- Rechargeable battery
- ② 8 x micro servo motors with set of screws.
- Buzzer
- 16 x DuPont cables
- Phillips screwdriver
- 3D Printed head (select from ultrasound or led matrix)
- 3D Printed body
- 3D Printed legs
- 3D Printed feet



We invested lots of time and resources to provide open source code, software and hardware, please support this project by just **giving us a ♥ Like and share** and you are **welcome to be a part of this friendly community** of robot builders, teachers and makers. **Join today our Otto Builder community**

This remix is based on



Otto DIY build your own robot

by Otto DIY

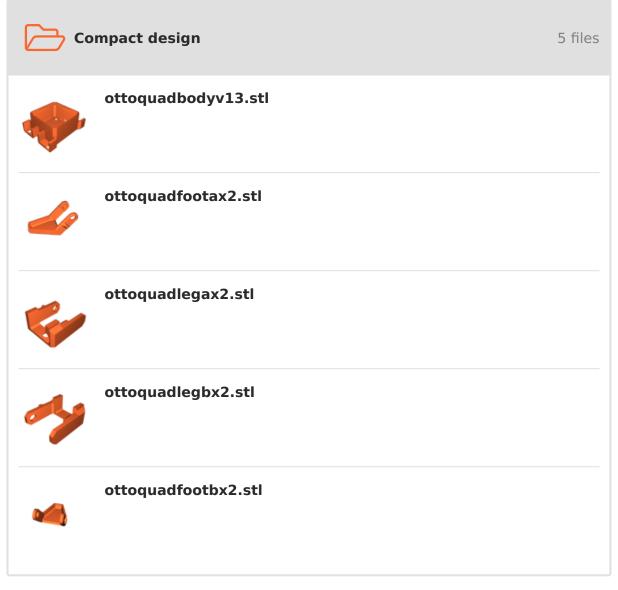


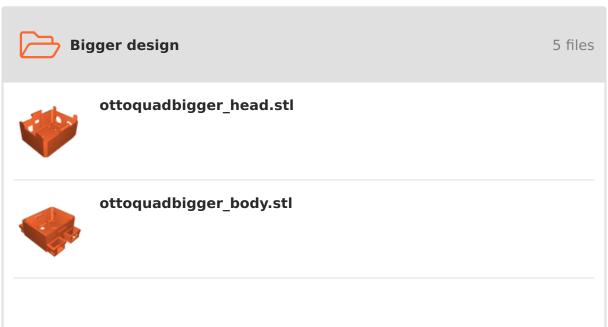
Poor Mini Kame - 8 DOF Quadruped Robot by Makergal3D

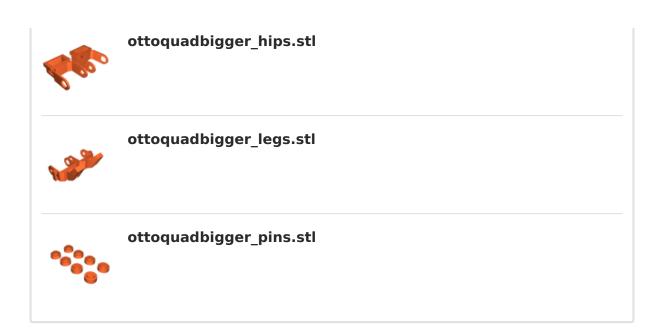


Otto DIY is a 3D printable open source robot

Model files







Other files

firmwarever_9.ino	
☐ Arduino code	
ottoquadlibs.zip	
ottoquaunbs.zip	
☐ Arduino Libraries	
ottoquadbigger_code.zip	
☐ Alternative code with Android App apk	

Find source .stl files on Thingiverse.com

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