

Class: Machine Learning

Support Vector Machines – part 2

Instructor: Matteo Leonetti

Learning outcomes



- Define Soft-Margin SVMs
- Project a given dataset to a higher-dimensional space

The SVM Formulation



Margin as large as possible



minimise:
$$\frac{1}{2} ||\mathbf{w}||^2$$

Subject to the constraints: $t_i(\mathbf{w}^T \mathbf{x}_i + \mathbf{w}_0) \ge 1$

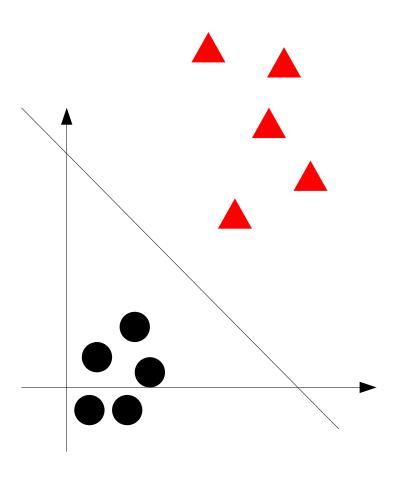


Every point is on the correct side, no point is on the hyperplane

Why SUPPORT VECTOR Machine?



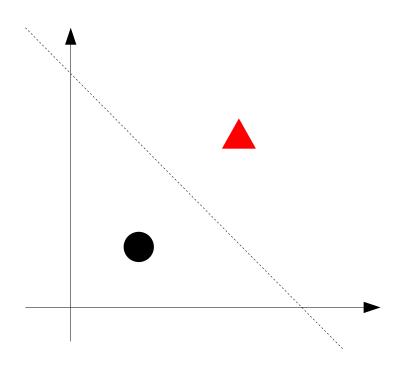
Consider this dataset:



Why SUPPORT VECTOR Machine?



Consider this dataset:

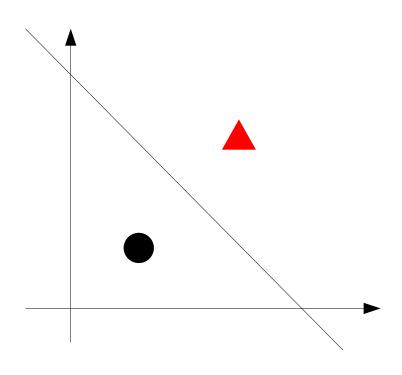


Does the optimal separating line change if I remove all but the closest points?

Why SUPPORT VECTOR Machine?

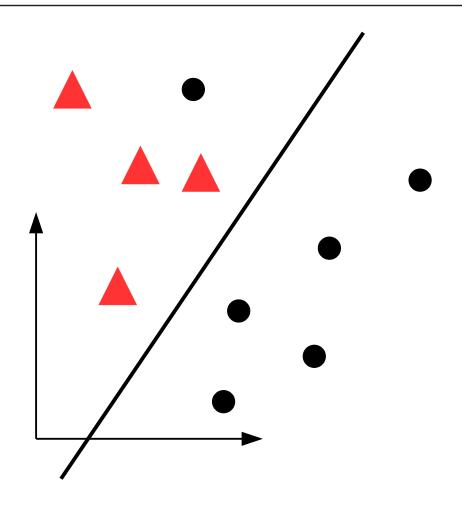


Consider this dataset:



Back to linear separability

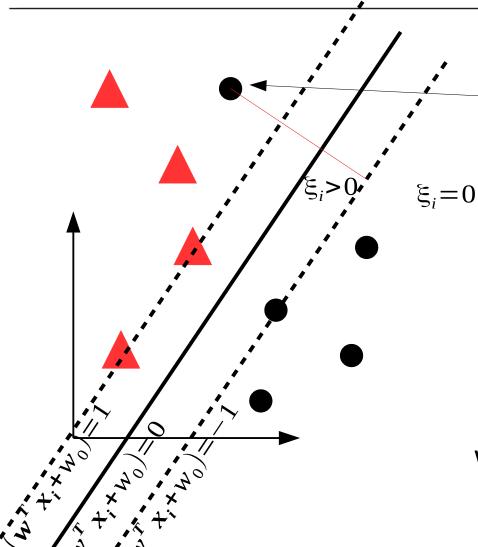




Is this classifier acceptable?

Slack Variables





For this point we want to allow the corresponding constraint to be *softened*:

$$t_i(\mathbf{w}^T \mathbf{x}_i + \mathbf{w}_0) \ge 1$$

One way to do this is to introduce an additional, positive, variable:

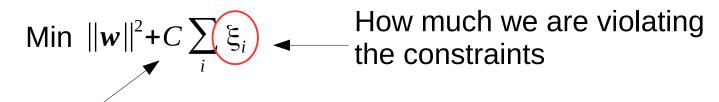
$$t_i(\mathbf{w}^T \mathbf{x}_i + \mathbf{w}_0) \ge 1 - \xi_i$$

With the additional constraints:

$$\xi_i \ge 0$$

Soft margin





Weight of violations

Subject to:

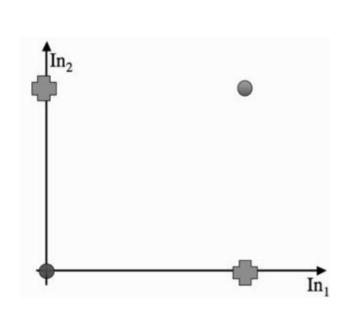
$$t_i(\mathbf{w}^T \mathbf{x}_i + \mathbf{w}_0) \ge 1 - \xi_i \qquad \qquad \xi_i \ge 0$$

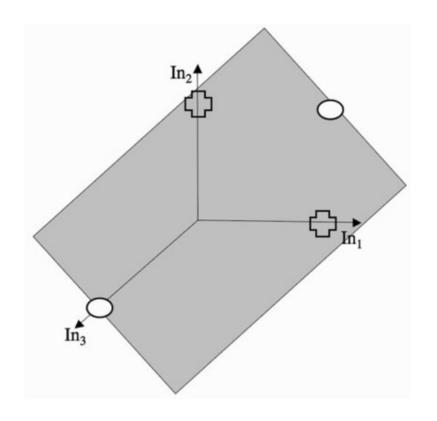
Sensible to outliers!

$$C = \infty$$
 Hard margin

Linear separability... revisited







Wait, what?!? More dimensions seem to help! Where do we get the extra dimensions from?

Example: Polynomial features



Let's take 2 points in 1 dimension:

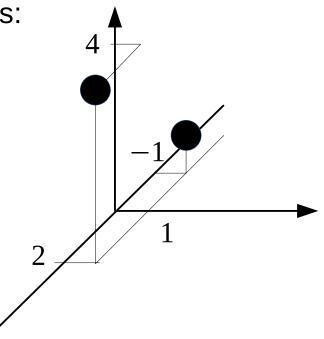
$$\langle -1
angle$$
 , $\langle 2
angle$



and project them in 3 dimensions:

In general: $\langle 1, x, x^2 \rangle$

Our points: $\langle 1,-1,1\rangle,\langle 1,2,4\rangle$



Example: Polynomial features



The original dataset has 1 variable:

$$\langle x_1, t_1 \rangle, \langle x_2, t_2 \rangle, \dots, \langle x_N, t_N \rangle$$

But we want a higher dimensional space...

Let's use polynomial features: $\Phi_i(x) = x^i$

Our points become:

$$\langle 1, x_1, x_1^2, x_1^3, ..., x_1^d, t_1 \rangle, \langle 1, x_2, x_2^2, x_2^3, ..., x_2^d, t_2 \rangle, ..., \langle 1, x_N, x_N^2, x_N^3, ..., x_N^d, t_N \rangle$$



How can we add extra dimensions?

Original point: x

Define a set of functions $\Phi_i(x)$

New point: $\Phi(x) = \langle \Phi_0(x), \Phi_1(x), \Phi_2(x), \Phi_3(x), ..., \Phi_n(x) \rangle$

Substitution



dataset:

$$\langle x_i, t_i \rangle = \langle -1, 1 \rangle, \langle 2, -1 \rangle$$

$$\langle \mathbf{x}_i, t_i \rangle = \langle 1, -1, 1, 1 \rangle, \langle 1, 2, 4, -1 \rangle$$



problem:

$$\min \quad \frac{1}{2} \|\langle w_1 \rangle\|^2 = \frac{1}{2} w_1^2$$

s.t.:
$$1 \cdot (-1 \cdot w_1 + w_0) \ge 1$$

 $-1 \cdot (2 \cdot w_1 + w_0) \ge 1$

$$\min \frac{1}{2} \| \langle w_1, w_2, w_3 \rangle \|^2$$
s.t.: $1 \cdot ([w_1 \ w_2 \ w_3] \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + w_0) \ge 1$

$$-1 \cdot (\begin{bmatrix} w_1 & w_2 & w_3 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} + w_0) \ge 1$$

Substitution



minimise:
$$\frac{1}{2} \| \mathbf{w} \|^2$$

Subject to the constraints: $t_i(\mathbf{w}^T \Phi(\mathbf{x}_i) + \mathbf{w}_0) \ge 1$

This way we would have a higher dimensional problem, which is also more difficult to solve.

Is there a better formulation?

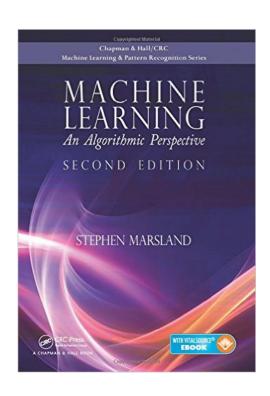


Conclusion

Learning outcomes



- Define Soft-Margin SVMs
- Project a given dataset to a higher-dimensional space



Chapter 8.2