# Lecture 3: Single nonlinear equations

COMP5930M Scientific Computation

# Today

Notation

Basic approach

Convergence

Bisection method

Convergence

Next

## Standard notation

Given a scalar function F(x):  $\mathbb{R} \to \mathbb{R}$ , find a point  $x^* \in \mathbb{R}$  s.t.

$$F(x^*) = 0.$$

Although not all our problems are immediately viewed in this form we can always rewrite them in this way.

Commonly termed the zero-finding problem

# The basic approach

- Since we do not have a direct method of solution we use an iterative method
- $\triangleright$  A solution algorithm generates a sequence of values  $x_n$

$$x_0, x_1, x_2, \dots$$

from a given initial point  $x_0$ 

► Further details of the process are specific to each algorithm

## Convergence criteria

Possible conditions to satisfy:

$$|x_{n+1} - x^*| < |x_n - x^*|$$
 ie. we are getting closer to the root at each step

$$|F(x_{n+1})| < |F(x_n)|$$
  
ie. the function  $F(x)$  is reduced at each step

These criteria are distinct and one does not imply the other.

Different algorithms may satisfy one of these, rarely both, and often neither

## Convergence rate

Assume the sequence  $x_0, x_1, \dots, x_n$  converges to  $x^*$ . We say the sequence **converges linearly**, if there exists  $0 < \alpha < 1$  and

$$\lim_{n\to\infty}\frac{|x^*-x_{n+1}|}{|x^*-x_n|}=\alpha.$$

Here  $\alpha$  is the **rate of convergence**, i.e. the error is (eventually) reduced by a constant factor of  $\alpha$  after each iteration. If  $\alpha=1$  the sequence converges **sublinearly**.

## Convergence rate

Assume the sequence  $x_0, x_1, \dots, x_n$  converges to  $x^*$ . We say the sequence **converges linearly**, if there exists  $0 < \alpha < 1$  and

$$\lim_{n\to\infty}\frac{|x^*-x_{n+1}|}{|x^*-x_n|}=\alpha.$$

Here  $\alpha$  is the rate of convergence, i.e. the error is (eventually) reduced by a constant factor of  $\alpha$  after each iteration. If  $\alpha = 1$  the sequence converges sublinearly.

Sequence **converges superlinearly**, if for some q > 1 and  $\alpha > 0$ 

$$\lim_{n\to\infty}\frac{|x^*-x_{n+1}|}{|x^*-x_n|^q}=\alpha.$$

If q = 2, we say it **converges quadratically**.

## Convergence rate

Assume the sequence  $x_0, x_1, \dots, x_n$  converges to  $x^*$ . We say the sequence **converges linearly**, if there exists  $0 < \alpha < 1$  and

$$\lim_{n\to\infty}\frac{|x^*-x_{n+1}|}{|x^*-x_n|}=\alpha.$$

Here  $\alpha$  is the rate of convergence, i.e. the error is (eventually) reduced by a constant factor of  $\alpha$  after each iteration. If  $\alpha = 1$  the sequence converges sublinearly.

Sequence **converges superlinearly**, if for some q>1 and lpha>0

$$\lim_{n\to\infty}\frac{|x^*-x_{n+1}|}{|x^*-x_n|^q}=\alpha.$$

If q = 2, we say it **converges quadratically**.

## Examples of orders and rates of convergence

Define  $\varepsilon_n = |x^* - x_n|$  as the error of the *n*th iteration step.

**Ex.1:** If  $\varepsilon_n = 1/n$ , then

$$\frac{\varepsilon_{n+1}}{\varepsilon_n^q} = \frac{n^q}{n+1} \to \begin{cases} 0, & \text{if } q < 1\\ 1, & \text{if } q = 1\\ \infty, & \text{if } q > 1 \end{cases}$$

so that the convergence is **sublinear**  $(q = 1, \alpha = 1)$ 

## Examples of orders and rates of convergence

Define  $\varepsilon_n = |x^* - x_n|$  as the error of the *n*th iteration step.

**Ex.2:** If  $\varepsilon_n = 1/2^n$ , then

$$\frac{\varepsilon_{n+1}}{\varepsilon_n^q} = \frac{2^{nq}}{2^{n+1}} = \frac{(2^n)^{q-1}}{2} \to \begin{cases} 0, & \text{if } q < 1\\ 1/2, & \text{if } q = 1\\ \infty, & \text{if } q > 1 \end{cases}$$

so that the convergence is **linear**  $(q = 1, \alpha = 1/2)$ 

# Examples of orders and rates of convergers

Define  $\varepsilon_n = |x^* - x_n|$  as the error of the *n*th iteration step.

**Ex.3:** If 
$$\varepsilon_n = 1/2^{2^n}$$
, then

$$\frac{\varepsilon_{n+1}}{\varepsilon_n^q} = \frac{(2^{2^n})^q}{2^{2^{n+1}}} = \frac{(2^{2^n})^q}{(2^{2^n})^2} \to \begin{cases} 0, & \text{if } q < 2\\ 1, & \text{if } q = 2\\ \infty, & \text{if } q > 2 \end{cases}$$

so that the convergence is quadratic (q = 2)

### The Bisection Method

- Assume the function F(x) is continuous
- Assume we know two points  $x_L$  and  $x_R$ , such that

$$F(x_L) F(x_R) \leq 0$$

called the bracket condition for the bracket  $[x_L, x_R]$ 

This implies that there is a solution  $x^* \in [x_L, x_R]$ , since the function changes sign over that interval (due to the Intermediate Value Theorem).

# The algorithm of bisection method

#### At iteration *n*:

- ▶ Consider the point  $x_C^n = (x_L^n + x_R^n)/2$  and find  $F(x_C^n)$ .
  - If  $F(x_n^n) F(x_n^n) \le 0$  then  $x^* \in [x_n^n, x_n^n]$ .
  - ▶ If  $F(x_C^n) F(x_R^n) < 0$  then  $x^* \in [x_C^n, x_R^n]$ .
- Select the new interval (also termed the **bracket**)  $[x_L^{n+1}, x_R^{n+1}]$  as the subinterval containing  $x^*$ .
  - Note that in one step the bracket containing x\* has been halved.
- Repeat this process until x<sub>R</sub><sup>n</sup> − x<sub>L</sub><sup>n</sup> < TOL, where TOL is a user-supplied value,</p>
  i.e. repeat until the bracket is sufficiently sm
  - i.e. repeat until the bracket is sufficiently small.

The initial error is 
$$\varepsilon_0 := |x^* - x_C^0| \le (x_R^0 - x_L^0)/2$$
.

At each iteration, we half the interval so that the error is halved:

$$\varepsilon_n := |x^* - x_C^n| \le \frac{x_R^n - x_L^n}{2} = \dots = \frac{x_R^0 - x_L^0}{2^{n+1}}.$$

The initial error is  $\varepsilon_0 := |x^* - x_C^0| \le (x_R^0 - x_L^0)/2$ .

At each iteration, we half the interval so that the error is halved:

$$\varepsilon_n := |x^* - x_C^n| \le \frac{x_R^n - x_L^n}{2} = \ldots = \frac{x_R^0 - x_L^0}{2^{n+1}}.$$

The error of the method at step i can be bounded from above:

$$\varepsilon_n \leq \frac{1}{2^{n+1}} (x_R^0 - x_L^0).$$

Therefore the method converges linearly at rate  $\alpha = 1/2$ .

The initial error is  $\varepsilon_0 := |x^* - x_C^0| \le (x_R^0 - x_L^0)/2$ .

At each iteration, we half the interval so that the error is halved:

$$\varepsilon_n := |x^* - x_C^n| \le \frac{x_R^n - x_L^n}{2} = \dots = \frac{x_R^0 - x_L^0}{2^{n+1}}.$$

The error of the method at step i can be bounded from above:

$$\varepsilon_n \leq \frac{1}{2^{n+1}}(x_R^0 - x_L^0).$$

Therefore the method converges linearly at rate  $\alpha = 1/2$ .

The error of the method at step n can be bounded from above:

$$\varepsilon_n \leq \frac{1}{2^{n+1}}(x_R^0 - x_L^0).$$

Therefore the method converges linearly at rate  $\alpha = 1/2$ .

**Note:** The convergence is **not monotone** in general, i.e. it can happen that for some steps n we have  $|F(x_{n+1})| > |F(x_n)|$ .

The upper bound above guarantees that eventually  $\lim_{n\to\infty}x_C^n=x^*$  so that  $\lim_{n\to\infty}F(x_C^n)=0$ .

The error of the method at step n can be bounded from above:

$$\varepsilon_n \leq \frac{1}{2^{n+1}}(x_R^0 - x_L^0).$$

Therefore the method converges linearly at rate  $\alpha = 1/2$ .

**Note:** The convergence is **not monotone** in general, i.e. it can happen that for some steps n we have  $|F(x_{n+1})| > |F(x_n)|$ .

The upper bound above guarantees that eventually  $\lim_{n\to\infty} x_C^n = x^*$  so that  $\lim_{n\to\infty} F(x_C^n) = 0$ .

### Pros and cons of bisection method

#### Performance:

- ► Guaranteed to converge to x\*
- Slow (linear convergence rate)

#### Other issues:

- We require an initial bracket (2 values), not just an initial guess (1 value)
- ► In practice we <u>may have to search for a bracket</u> given one point
- ▶ The initial bracket  $[x_L, x_R]$  may contain more than one zero and it is not clear which it will compute

# Newton's Method (recalling)

**Assumption:** F(x) differentiable with derivative F'(x), initial guess  $x_0$  s.t.  $F'(x_0) \neq 0$ .

- ▶ Start from  $x_0$ , compute  $F(x_0)$  and  $F'(x_0)$
- Newton step n:

$$x_{n+1} = x_n - \frac{F(x_n)}{F'(x_n)}, \quad n = 0, 1, 2, ...$$

▶ Iterate until  $|F(x_n)|$  < TOL or maximum number of iterations reached.

Generates a sequence of iterates  $x_n$  that converges to  $x^*$ .

### Pros and cons of Newton's method

#### Performance

- Fast (quadratic convergence rate)
- Not robust

#### Other issues

- Requires the derivative function
- Requires a "good" initial guess

### Convergence criteria

- (1) The Bisection Method is usually stopped when  $|b-a| < TOL_x$  for a bracket [a,b].
- (2) Newton's Method is usually stopped when  $|F(x)| < TOL_{F}$

$$|F(x)| < TOL_F$$

 $TOL_x$  and  $TOL_F$  are appropriately chosen tolerances

## Problems?

- ▶ (1) does not necessarily imply (2);
- ▶ (2) does not necessarily imply (1).

# In practice

We usually accept a solution  $x_n$  if

- ▶  $|x_{n+1} x_n|$  <  $TOL_x$  (beware of stalled iteration!)
- ightharpoonup or,  $|F(x_{n+1})| < TOL_F$

or, accept we have failed

if the number of function evaluations/iterations exceeds a user-specified number N<sub>f</sub>

The last criteria handles failure gracefully

# Summary

Two contrasting, classical approaches to the problem

- Bisection method
  - Derivative not needed
  - Robust
  - Slow (linear convergence)
  - Newton's method
    - Derivative required
    - Not robust
    - Fast (quadratic convergence)

## Next time...

#### Lecture

Extending Newton's method