# **COMP5930M - Scientific Computation**

Coursework 2

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#### COMP5930M - Scientific Computation

- 1. A one-dimensional PDE: Nonlinear parabolic equation
  - (a), Formulation of the discrete problem
  - (b), Simulation and timings for different
  - (c), Timings and analysis of complexity, general case
  - (d), Jacobian structure
  - (e), Timings and analysis of complexity, tridiagonal case
- 2. A three-dimensional PDE: Nonlinear diffusion
  - (a). Simulations with dense version of the solver
  - (b), Comparison of dense and sparse solver outputs
  - (c), Analysis of the sparsity of the Jacobian matrix
  - (d), Analysis of the LU factors of the Jacobian
  - (e), Simulations with sparse version of the solver

## 1. A one-dimensional PDE: Nonlinear parabolic equation

#### (a), Formulation of the discrete problem

• The nonlinear parabolic equation is : find u(x, t) such that:

$$\frac{\partial u}{\partial t} = \epsilon \, \frac{\partial^2 u}{\partial x^2} + \alpha (\frac{\partial u}{\partial x})^2$$

• The central difference formulas in space:

$$u(x_i) \approx u_i$$

$$\frac{\partial u}{\partial x}\left(x_{i}\right) \approx \frac{u_{i+1} - u_{i-1}}{2h}$$

$$\frac{\partial^2 u}{\partial x^2} (x_i) \approx \frac{u_{i+1} - 2u_i + u_{i-1}}{h^2}$$

• The continuous problem is reduced to a semi-discrete system of ODEs for

$$\frac{\partial u}{\partial t} \equiv \dot{u}(t) = f(u)$$

• Implicit Euler

$$\frac{u^{k+1}-u^k}{\Delta t}=f(u^{k+1})$$

• Use implicit Euler. at node i of the gird:

$$\frac{u_i^{k+1} - u_i^k}{\Delta t} = \epsilon \frac{u_{i+1}^{k+1} - 2u_i^{k+1} + u_{i-1}^{k+1}}{h^2} + \alpha (\frac{u_{i+1}^{k+1} - u_{i-1}^{k+1}}{2h})^2$$

$$F_i(u_{i-1}^{k+1},u_i^{k+1},u_{i+1}^{k+1}) = F_i(U) = \frac{u_i^{k+1}-u_i^k}{\Delta t} - \epsilon \, \frac{u_{i+1}^{k+1}-2u_i^{k+1}+u_{i-1}^{k+1}}{h^2} + \alpha (\frac{u_{i+1}^{k+1}-u_{i-1}^{k+1}}{2h})^2 = 0$$

- So, the Full discrete nonlinear system F(U)=0 for the unknown  $u_i^{k+1}$ , i=2,...,n-1, equations are formed at each internal node i=2,...,n-1. Depends on previous  $u^k$ , time step  $\Delta t$  and gird size h. Each equation  $F_i$  depends on three neighboring nodes  $U_{i-1}, U_i, U_{i+1}$  through the FDM approximation.
- Initial conditions are specified at t = 0 as u(x, 0) = x.

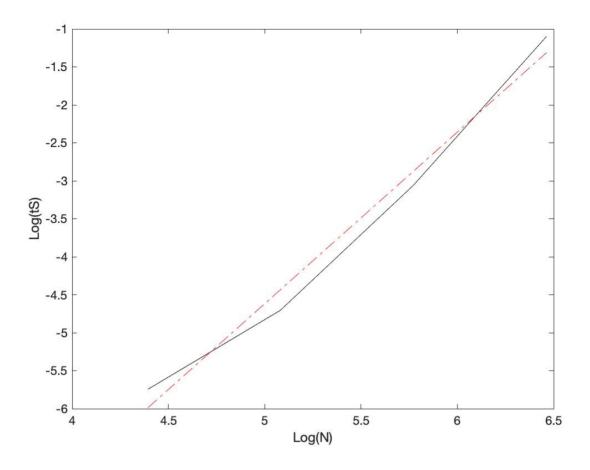
### (b), Simulation and timings for different $N_T$

Different $N_T$	T (seconds)	Total Iterations (S)	Average time $t_S = T/S$ (seconds)
20	0.189367	59	0.003209
40	0.417477	104	0.004014
80	0.743755	196	0.003794
160	1.293817	369	0.003506

#### (c), Timings and analysis of complexity, general case

Different N	T (seconds)	Total Iterations (S)	Average time $t_S = T/S$ (seconds)
81	0.333213	104	0.003204
161	0.978038	108	0.009056
321	5.768211	123	0.046896
641	43.318342	130	0.333218

- $t_S = CN^P$  and  $log(t_S) = logC + Plog(N)$
- By fitting the N values and  $t_S$ , can get  $log(t_S) = -17.45 + 2.6log(N)$  approximately.
- So get the cost of one New iteration with the N, have the equation:  $t_S = e^{-17.45} N^{2.6}$ , and the cost of the algorithms is match computation cost of Jacobian's  $O(n^3)$ .



### (d), Jacobian structure

• Finite differences + Implicit Euler. At node i of the gird:

$$F_i = \frac{U_i - u_i^k}{\Delta t} - \epsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} + \alpha (\frac{U_{i+1} - U_{i-1}}{2h})^2 = 0$$

For this problem we can analytically the Jacobian matrix:

$$\frac{\partial F_i}{\partial U_{i-1}} = -\frac{\epsilon}{h^2} + \frac{\alpha(U_{i-1} - U_{i+1})}{2h^2}$$
$$\frac{\partial F_i}{\partial U_i} = \frac{1}{\Delta t} + \frac{2\epsilon}{h^2}$$
$$\frac{\partial F_i}{\partial U_{i+1}} = -\frac{\epsilon}{h^2} + \frac{\alpha(U_{i+1} - U_{i-1})}{2h^2}$$

• These are the only nonzero elements of the i'th row.

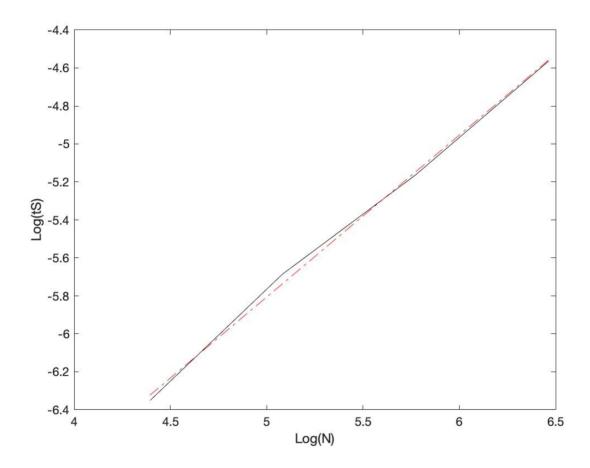
#### (e), Timings and analysis of complexity, tridiagonal case

 Using the Thomas algorithm and the tridiagonal implementation of numerical Jacobian computation.

Different N	T (seconds)	Total Iterations (S)	Average time $t_S = T/S$ (seconds)
81	0.181544	104	0.001745

161	0.386499	108	0.003393
321	0.703420	123	0.005718
641	1.354466	130	0.010418

- $t_S = CN^P$  and  $log(t_S) = logC + Plog(N)$
- By fitting the N values and  $t_S$ , can get  $log(t_S) = -10.75 + log(N)$  approximately.
- So get the cost of one New iteration with the N, have the equation:  $t_S = e^{-10.75} N^1$ , and the cost of the algorithms is match the theoretical cost O(n).



## 2. A three-dimensional PDE: Nonlinear diffusion

### (a), Simulations with dense version of the solver

• PDE for u(x, y, z), and  $[x, y, z] \in [-10, 10]^3$  with u(x, y, z) = 0 on the boundary of the domain, and some known function g(x, y, z) that does not depend on u.

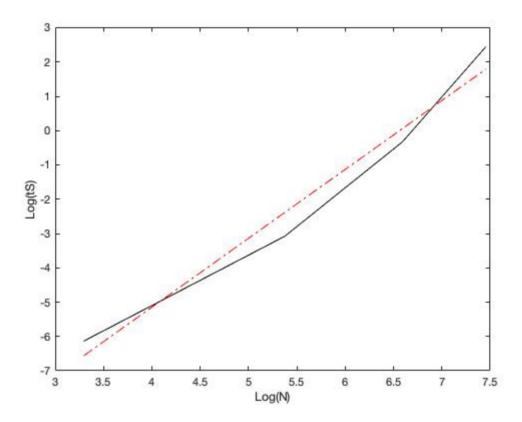
$$\frac{\partial}{\partial x}\left((1+u^2)\frac{\partial u}{\partial x}\right) + \frac{\partial}{\partial y}\left((1+u^2)\frac{\partial u}{\partial y}\right) + \frac{\partial}{\partial z}\left((1+u^2)\frac{\partial u}{\partial z}\right) = g(x,y,z)$$

• With gird dimension m = 5, 8 and 11 for  $tol = 10^{-8}$ 

Different Time Taken N (seconds)	Total Iterations (S)	Average time $t_S = T/S$ (seconds)	
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27	0.008670	4	0.002167
216	0.322518	7	0.046074
729	5.044202	7	0.720600

- $t_S = CN^P$  and  $log(t_S) = logC + Plog(N)$
- By fitting the N values and  $t_S$ , can get  $log(t_S) = -13.2 + 2log(N)$  approximately.
- Get the cost of one New iteration with the N, have the equation:  $t_S = e^{-13.2}N^2$ , since using the spare storage schemas in 2d systems, and just using 2 x nnz vectors, So the problem is how to find out the sparsity pattern of the Jacobian. the cost turn into to  $O(n^2)$ , and the cost of the algorithms is match the theoretical cost  $O(n^2)$ .

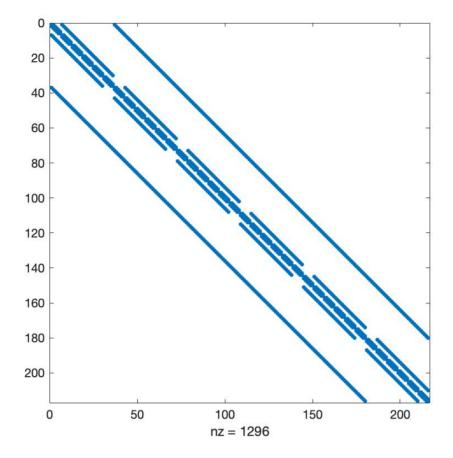


## (b), Comparison of dense and sparse solver outputs

- When m = 5, using the dense linear algebra and sparse linear algebra.
- This two methods have the same numerical solutions, but the cost time of using dense linear algebra is longer than the cost time of using spares linear algebra.

#### (c), Analysis of the sparsity of the Jacobian matrix

(i), The graph of the sparsity pattern A blow:

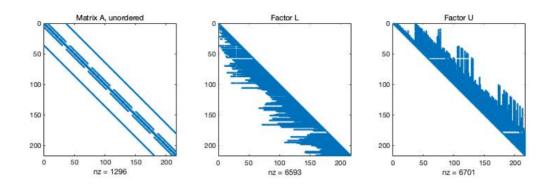


(ii),, base on the bandwidth of a matrix **A** is defined as the smallest number k s.t.  $a_{i,j}=0$  for all |i-j|>k.

• the smallest number k = 37, the bandwidth = 37.

## (d), Analysis of the LU factors of the Jacobian

- The number of non-zero elements L is 6593.
- The number of noe-zero elements U is 7601.
- The graph of the sparsity pattern of the L-U factors below:
- Using LU(p) method can cause the fill-in problem.



## (e), Simulations with sparse version of the solver

Different N	Time Taken (seconds)	Total Iterations (S)	Average time $t_S = T/S$ (seconds)
2197	0.144467	4	0.036117
4913	0.219073	4	0.054768
9261	1.683312	14	0.120236

- $t_S = CN^P$  and  $log(t_S) = logC + Plog(N)$
- By fitting the N values and  $t_S$ , can get  $log(t_S) = -10.06 + 0.86 log(N)$  approximately.
- Get the cost of one New iteration with the N, have the equation:  $t_S = e^{-10.06} N^{0.86}$ .
- Compare with the 2(a), which find the cost time of this new sparsity-based implementation using the timings of the numerical is less than the 2(a).