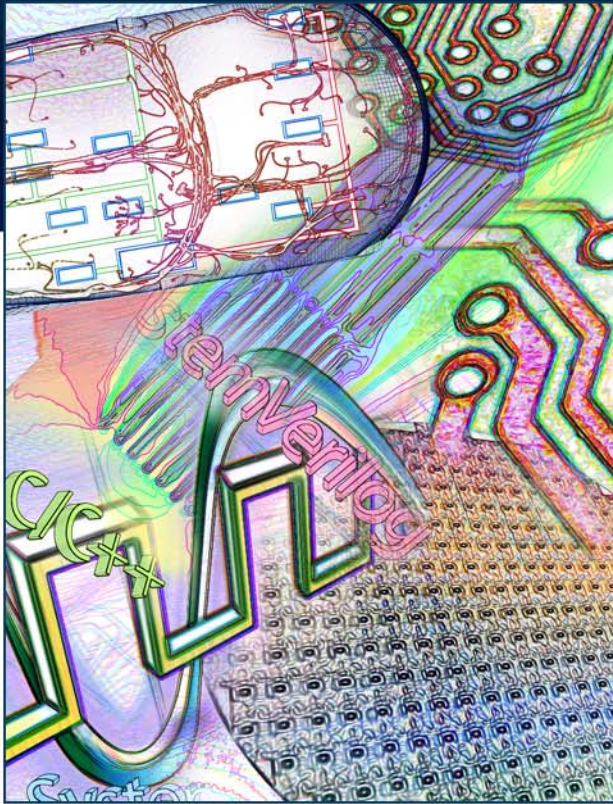


# AUTOSAR and Mentor Graphics' Solution VSx

# Outline

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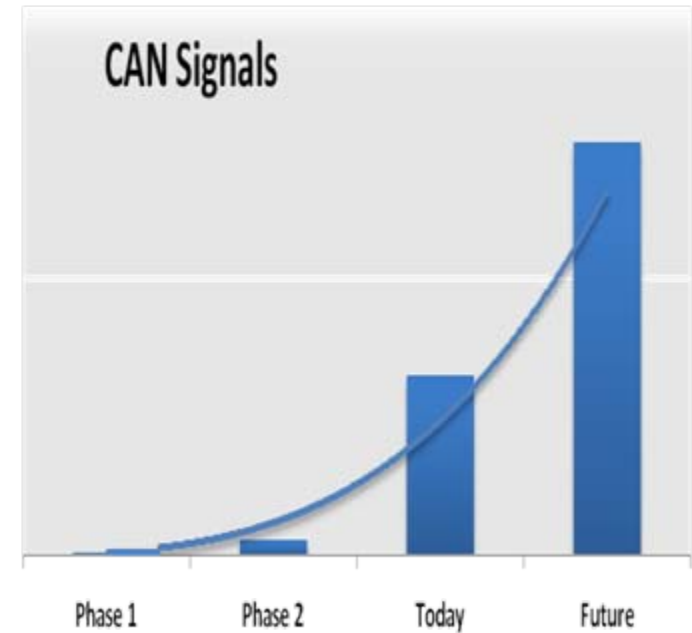
- Vehicle Development Trends
- AUTOSAR development methodology
- Mentor Graphics' AUTOSAR & Architecture Tool chain
- Summary



# Vehicle Development Trends

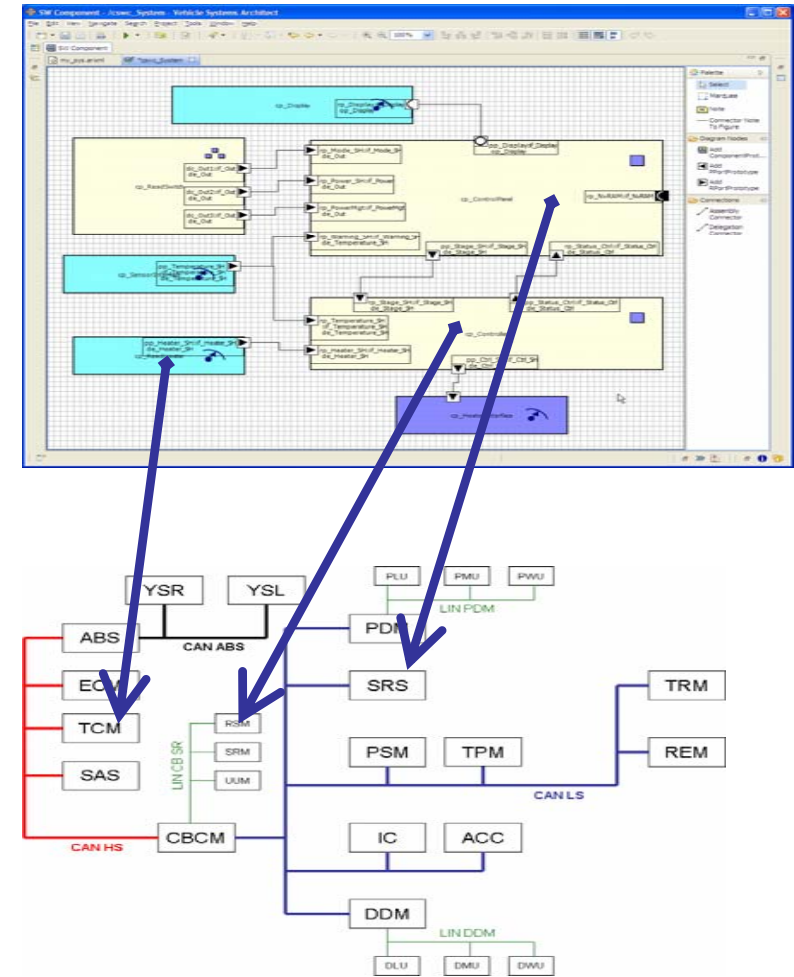
# Automotive Software and Electronics Development

- Increase of functionality
- Increase of E/E Complexity
  - Real time requirements
  - Software complexity
- Increasing Communication
  - More networks, More signals
- ECU number not increasing much anymore
  - More functionality in each ECU
  - Functions distributed over several ECUs
  - Integration of standard functionality like ABS into other ECUs
  - Today's maximum is about 95 ECUs in High Class Vehicles



# Automotive Software and Electronics Development

- New methods and standards
- Functionality described separately from implementation
- Enable reuse in multiple scenarios
- Separation between HW and SW in ECUs at System Design Level
- Enable to move SW components between ECUs
- Capture timing requirements

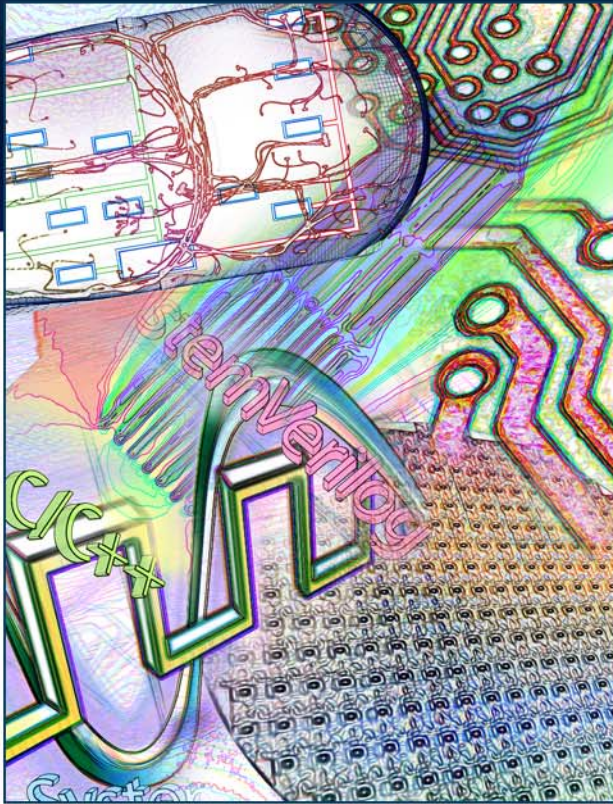




# General E/E Architecture Trends

Trend	Description	Objective
<b>Frontloading</b>	<ul style="list-style-type: none"> <li>▪ Increase effort in early design stages</li> </ul>	<ul style="list-style-type: none"> <li>▪ Reduce late changes</li> <li>▪ Reduce warranty and recall costs</li> </ul>
<b>Standardization</b>	<ul style="list-style-type: none"> <li>▪ AUTOSAR</li> <li>▪ EAST ADL</li> </ul>	<ul style="list-style-type: none"> <li>▪ Improve flexibility</li> <li>▪ Enable professional tooling</li> </ul>
<b>Integrate architecture design and implementation</b>	<ul style="list-style-type: none"> <li>▪ Bi-directional flow of information</li> </ul>	<ul style="list-style-type: none"> <li>▪ Use architecture design results in implement</li> <li>▪ Use feedback from implementation projects during architecture design</li> </ul>
<b>Attention to timing requirements</b>	<ul style="list-style-type: none"> <li>▪ Standardized timing models now part of AUTOSAR</li> </ul>	<ul style="list-style-type: none"> <li>▪ Reduce number of timing problems</li> <li>▪ Improve network design</li> </ul>

# AUTOSAR Development Methodology



# General Overview



## AUTomotive Open System Architecture

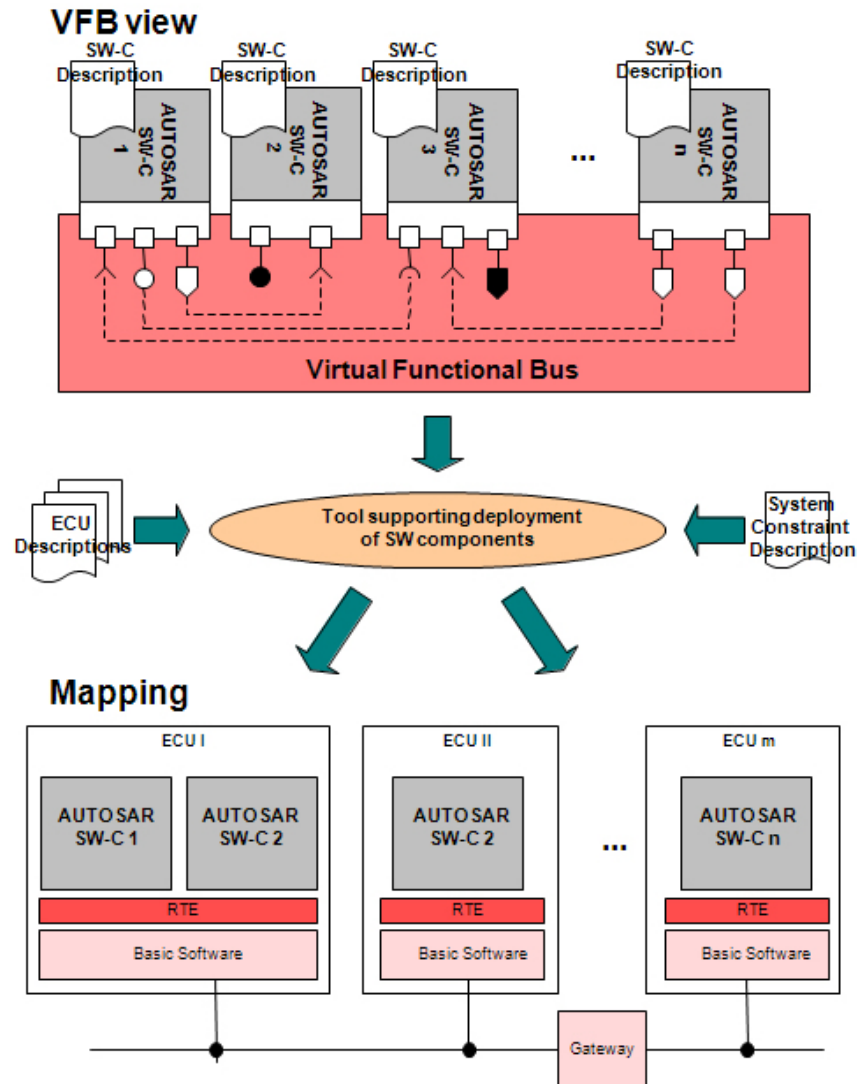
- AUTOSAR as a standard is providing specifications on 3 main areas
  - software architecture
  - application interfaces
  - methodology.
  
- AUTOSAR as a development project is following a stepwise approach to meet
  - quality
  - time schedule requirements.



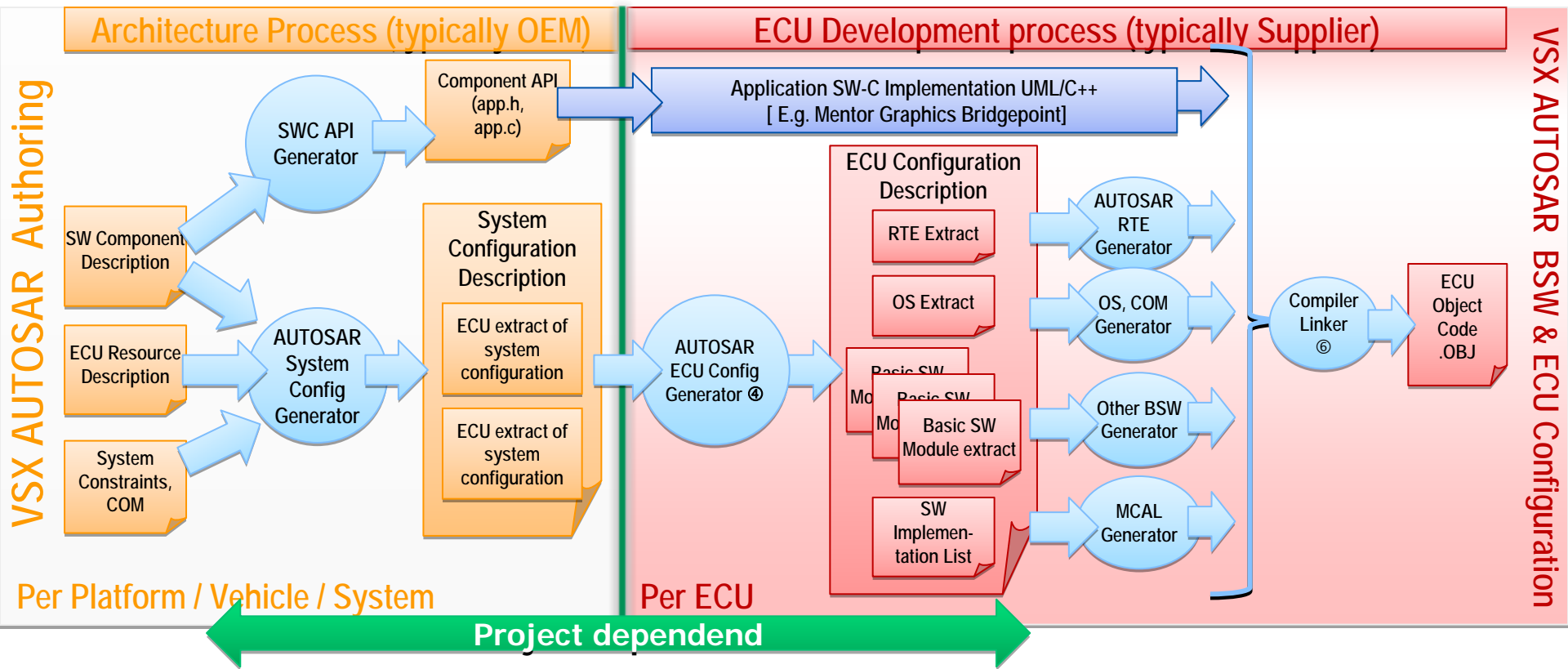
<http://www.autosar.org>



# AUTOSAR Basic Approach



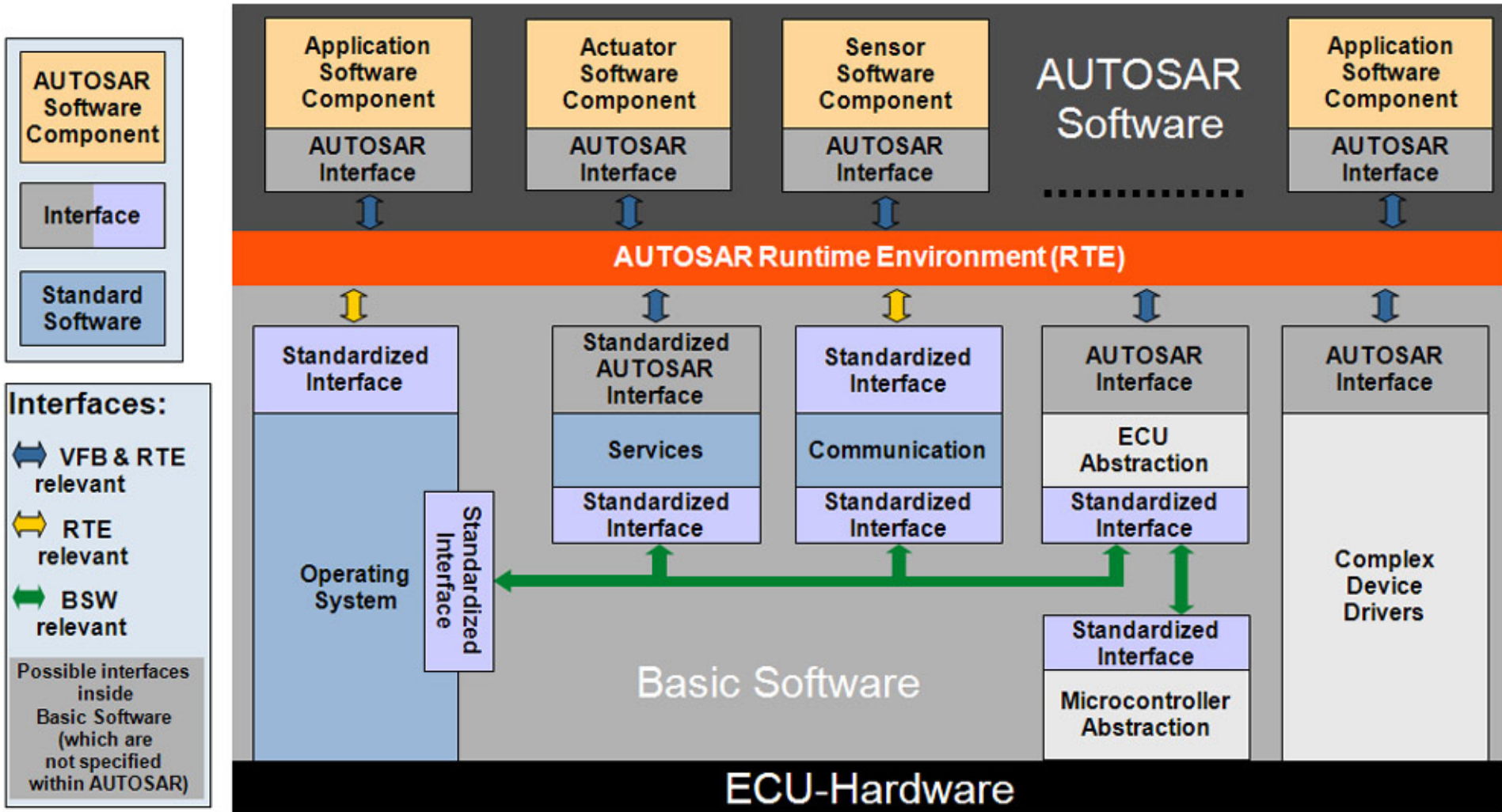
# AUTOSAR Methodology



- Information, Data, Files
- Process step, tool feature

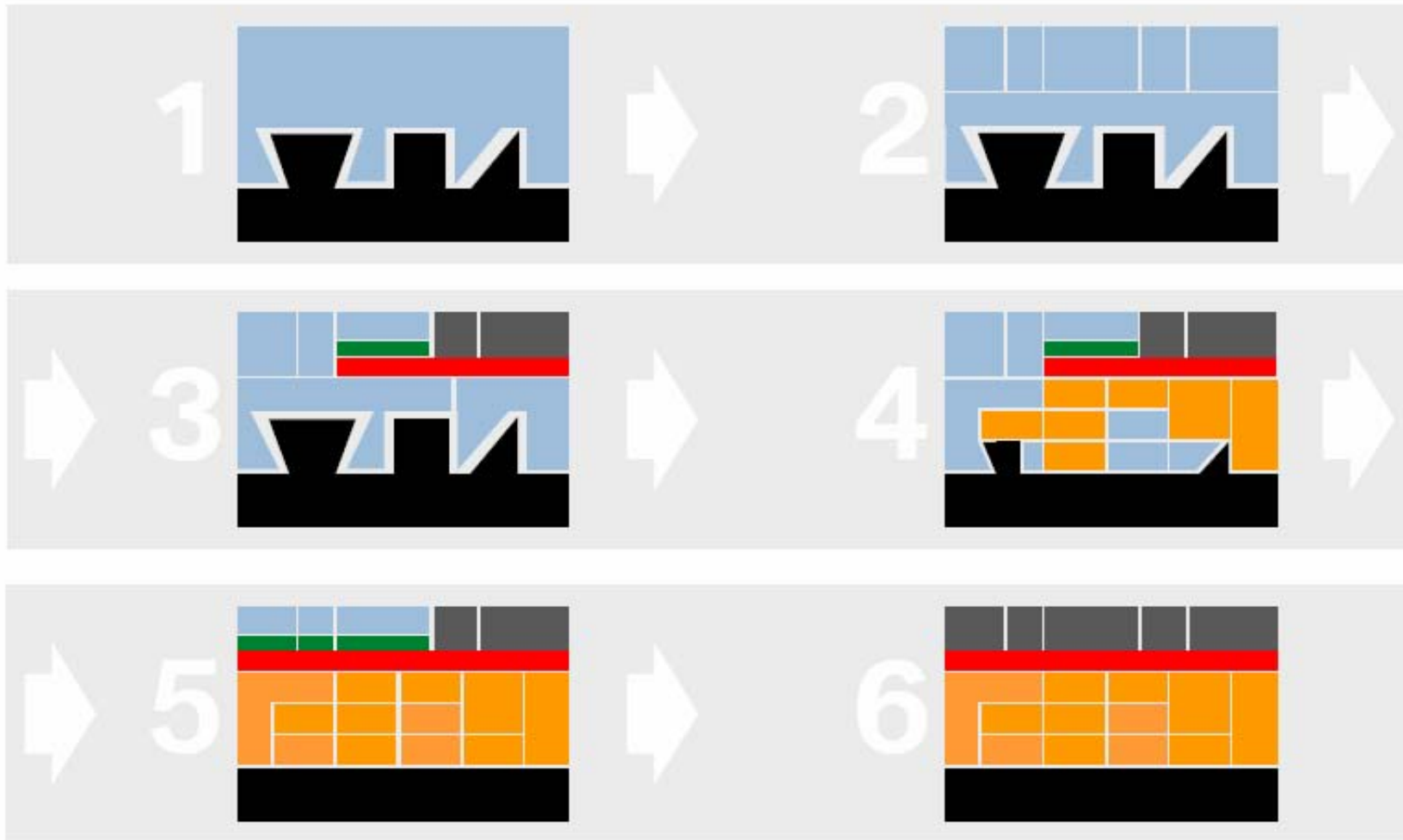
# AUTOSAR

## Applications and Interfaces



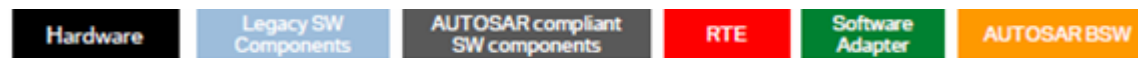
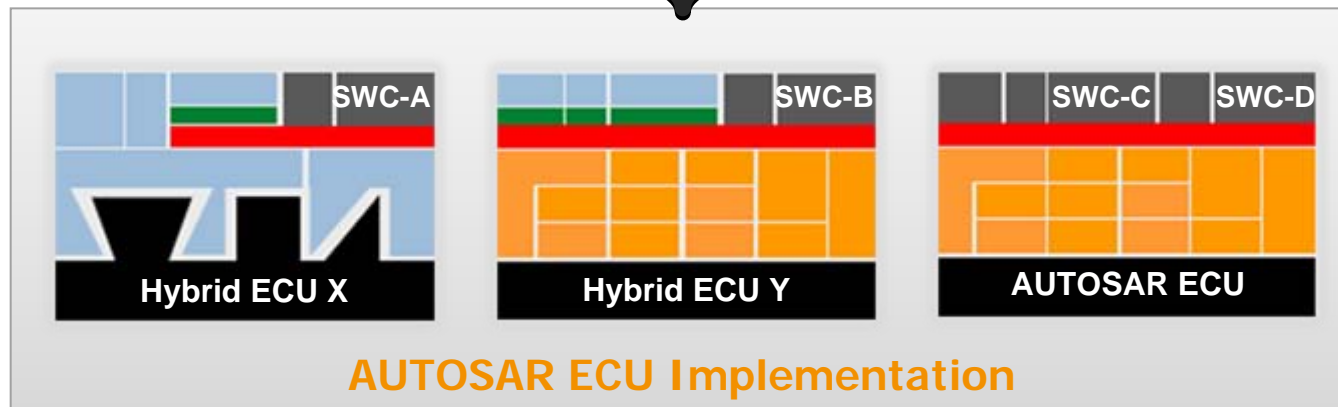
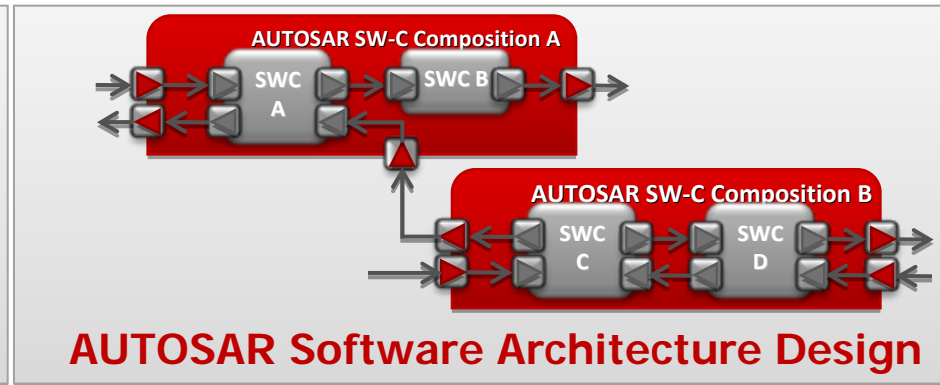
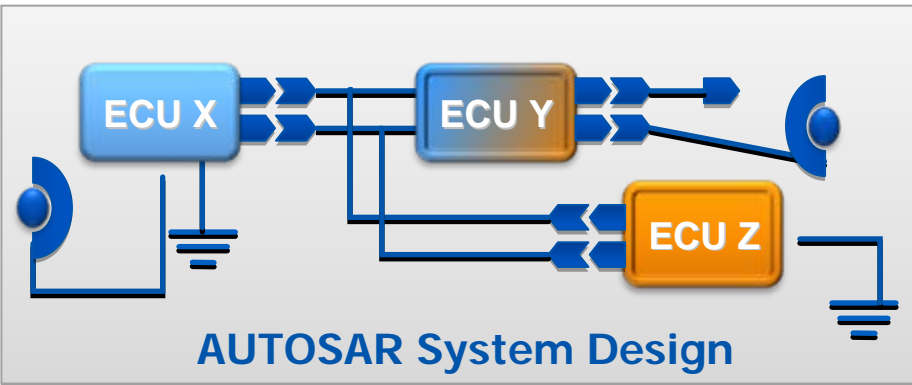
# AUTOSAR in Series Production.

## Possible Migration Path – BSW



# AUTOSAR in Series Production.

## Possible Migration Path - System

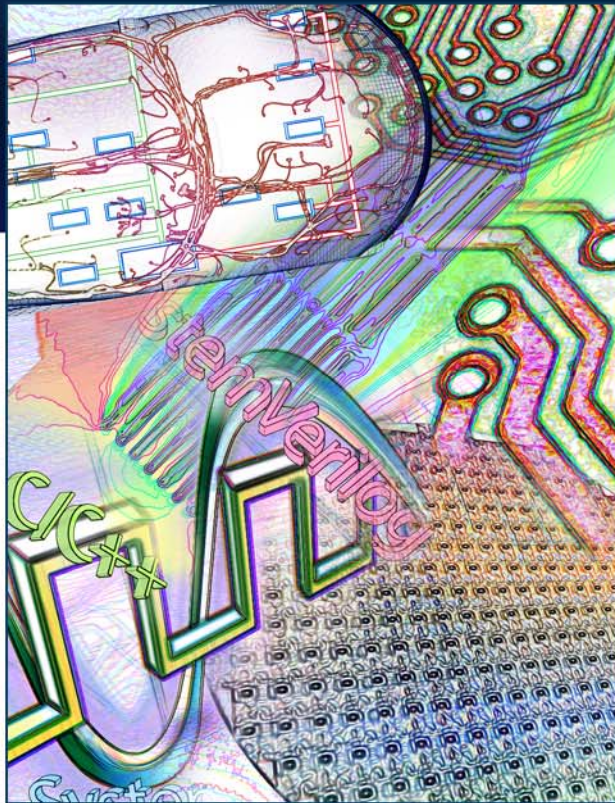




# Benefits of AUTOSAR

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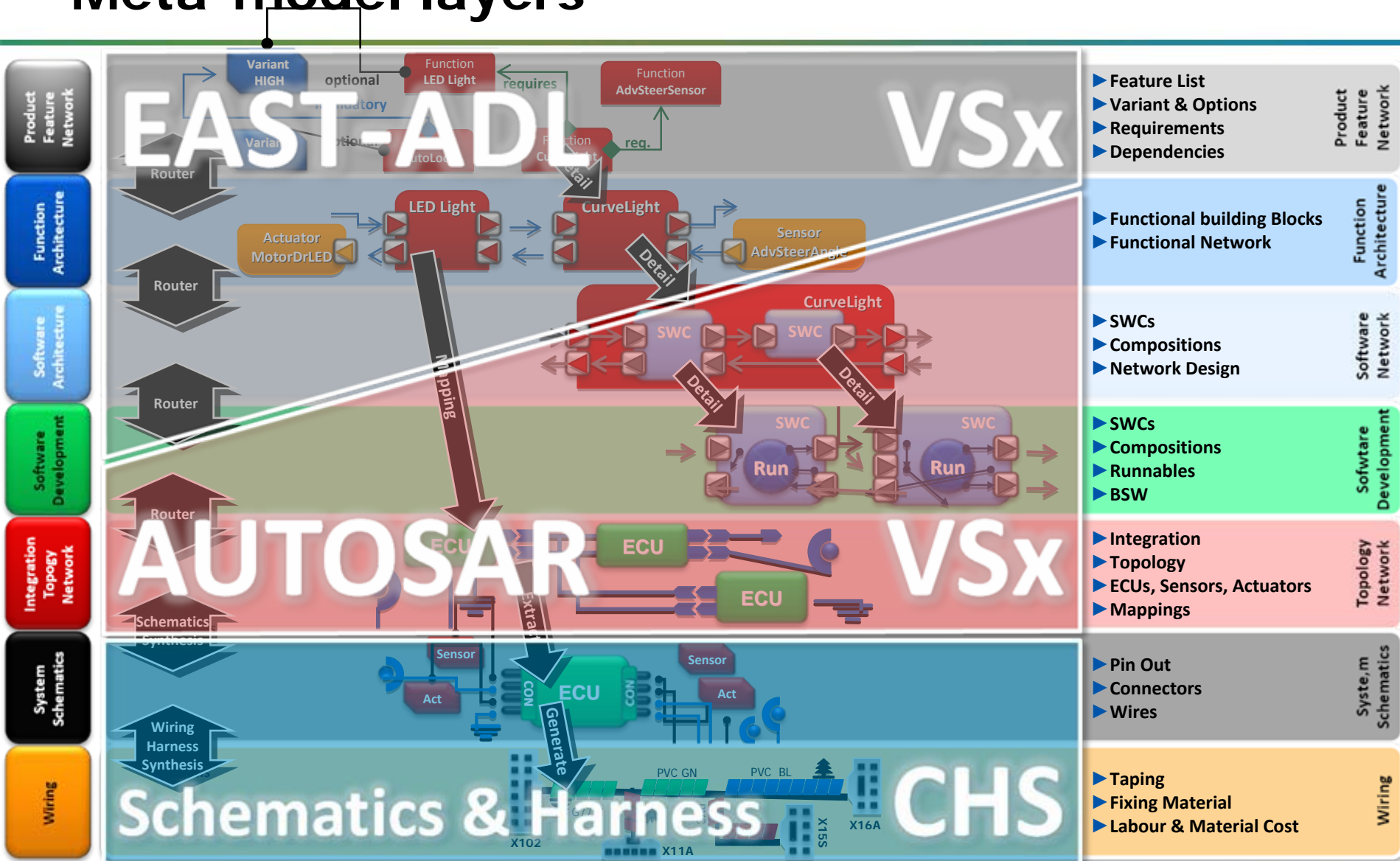
- Project and supplier independent, reusable application SW
- Standardized method to describe full E/E platform from requirements to implementation for HW and SW
- Standardized basic software enables common reusable HW platforms
- Enable independent choice of the best supplier for the job regarding (tool/SW vendor, T1 supplier, T2 supplier)



# Mentor Graphics AUTOSAR Solution VSx

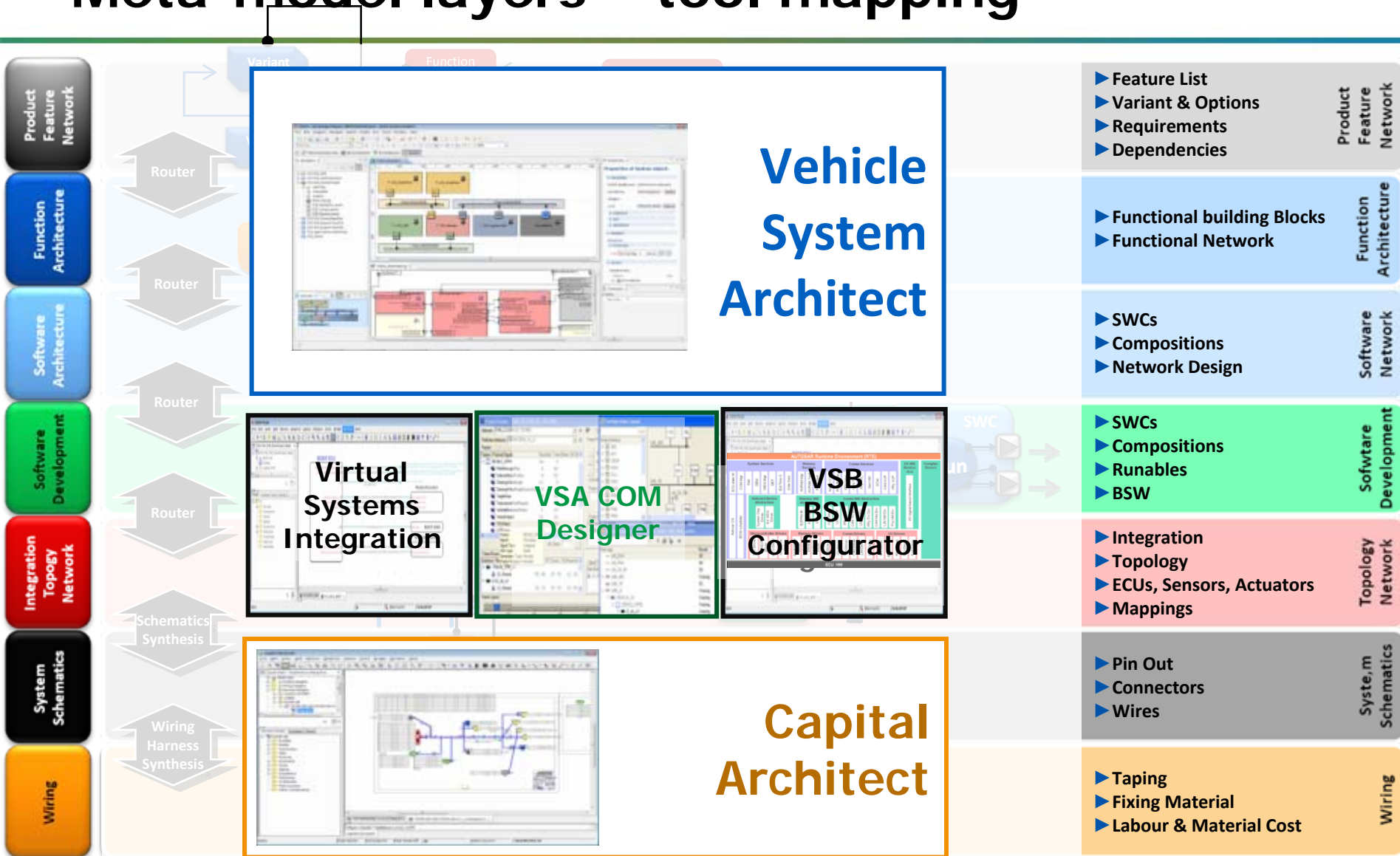
# E/E Architecture Design

## Meta-model layers



# E/E Architecture Design

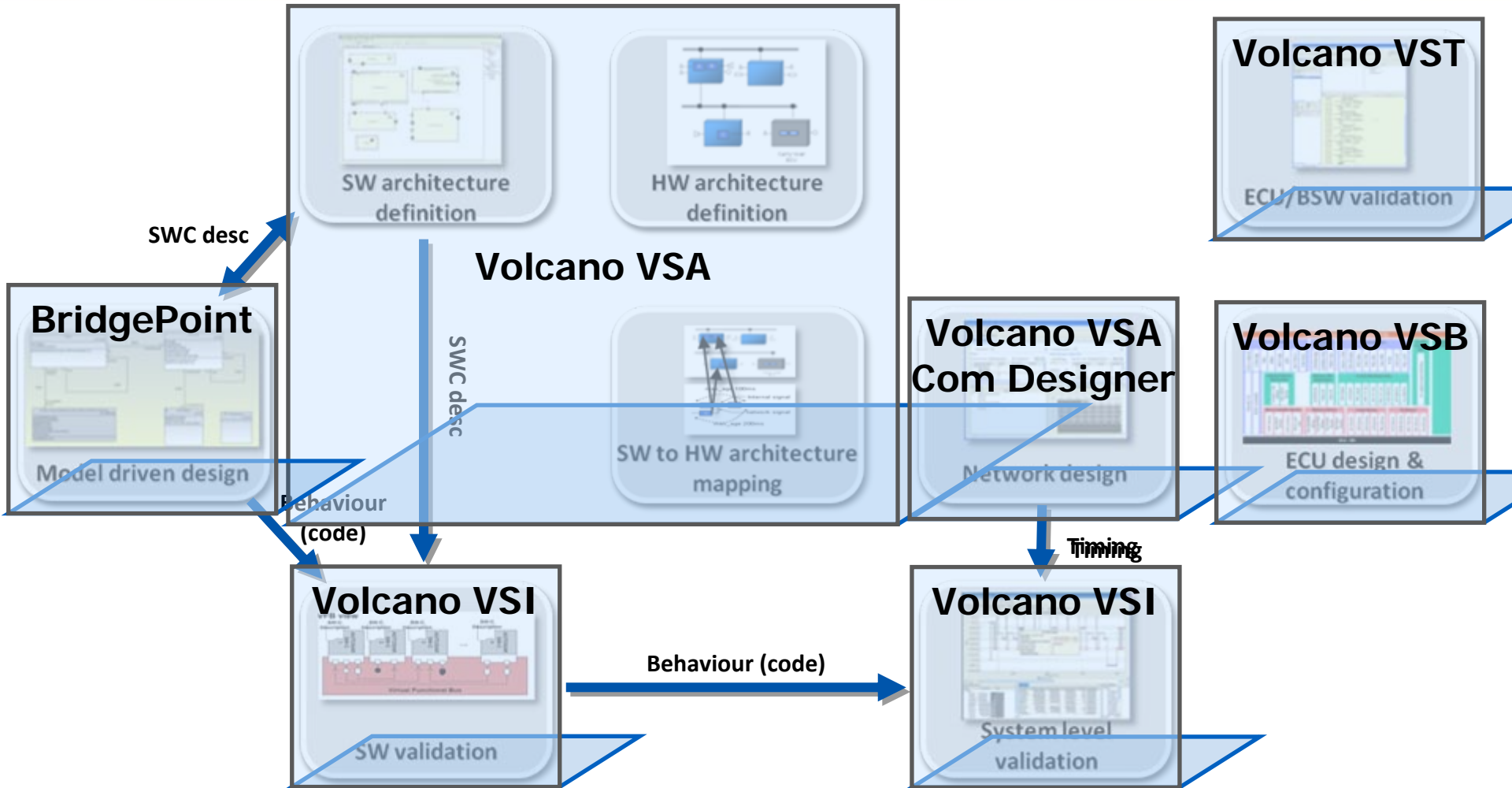
## Meta-model layers – tool mapping





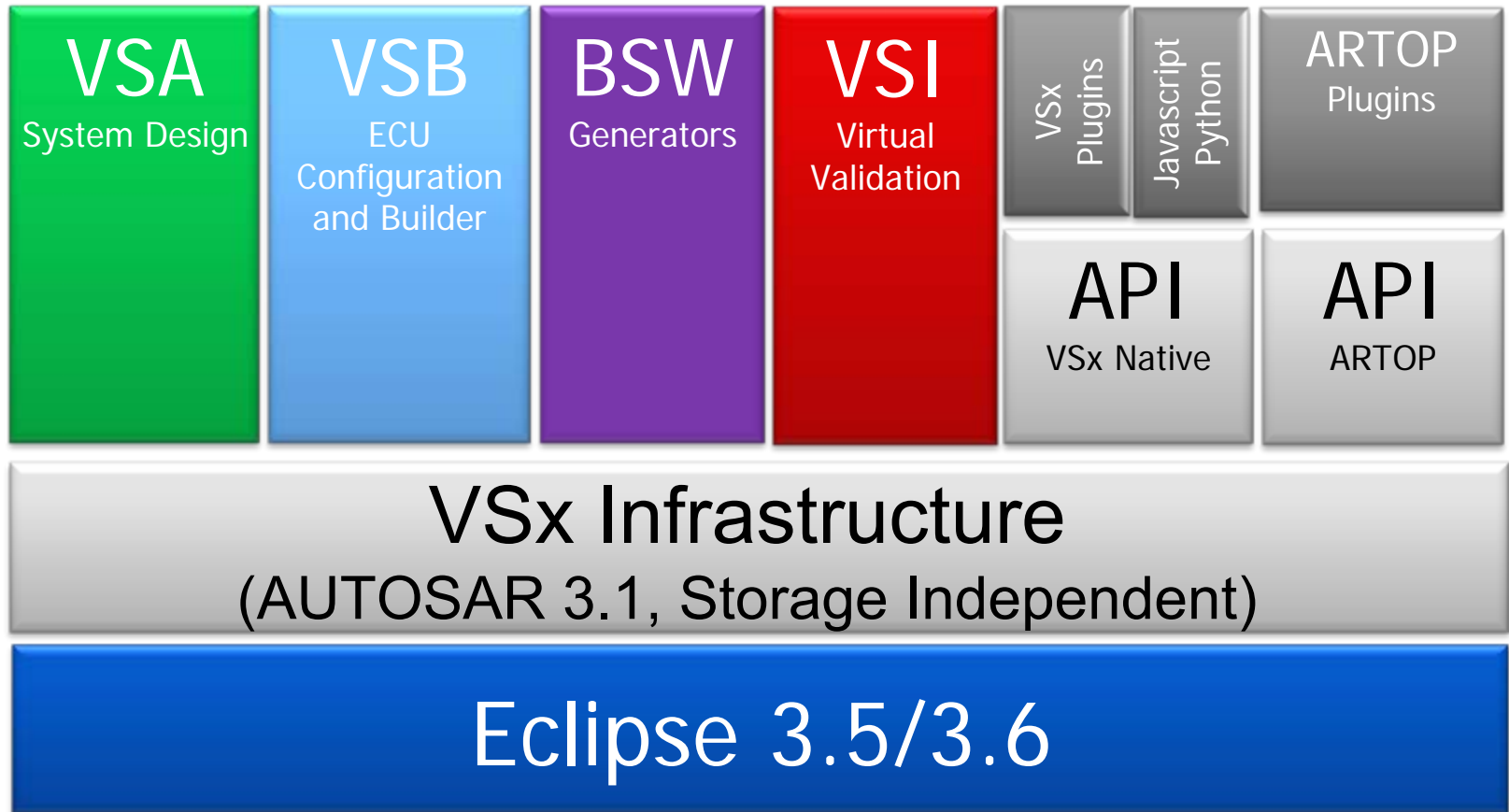
# VSx Architecture Development

## SW development process & tools



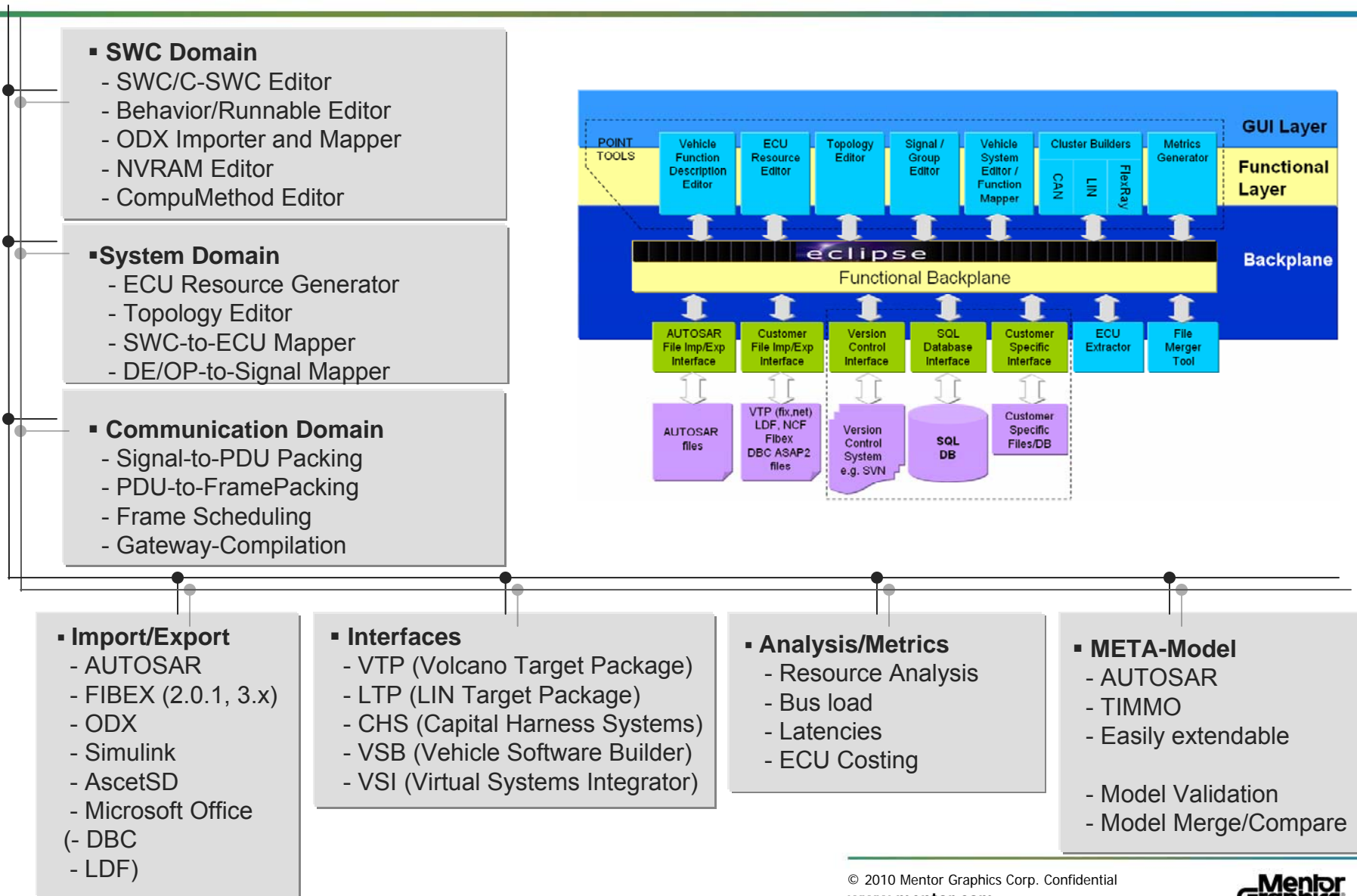


# VSx Tool Platform



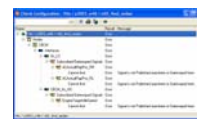
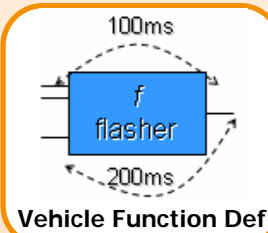
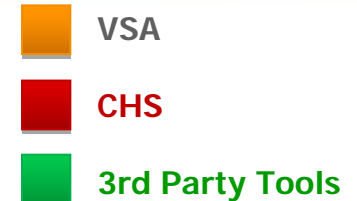
# VSA

## Architecture & Features



# VSA Activities

## Requirements mgmt



**Constraints and consistency  
(OEM design IP)**

```

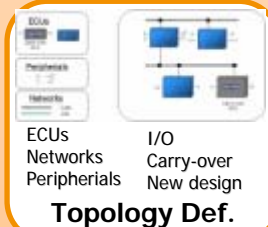
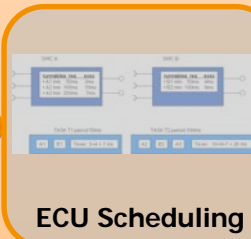
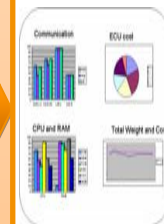
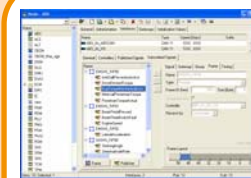
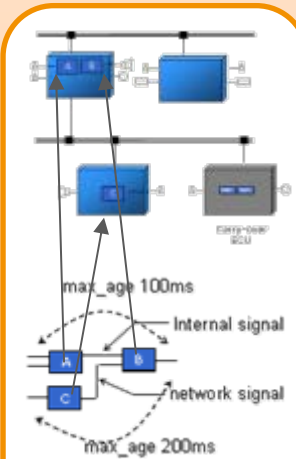
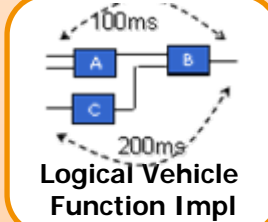
Constraint : function : con safety
if f.classification == "Safety" {
  for i in all inputs
    assert (i.type != LIN);
}

Constraint : SWC map : unique ECU
assert (e1.ECU != e2.ECU)
    
```

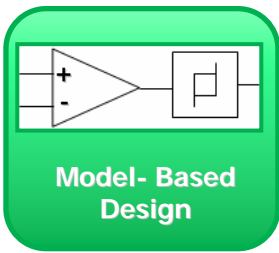
**Runnables** R1 25  
 R2 50  
**Memory** RAM 458  
 ROM 3489  
 Stack < 120



**SWC desc def**

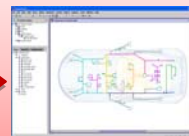
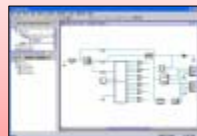


**ECU Extract of System  
Description**  
 (Other legacy files, DBC, LDF,  
FIBEX)



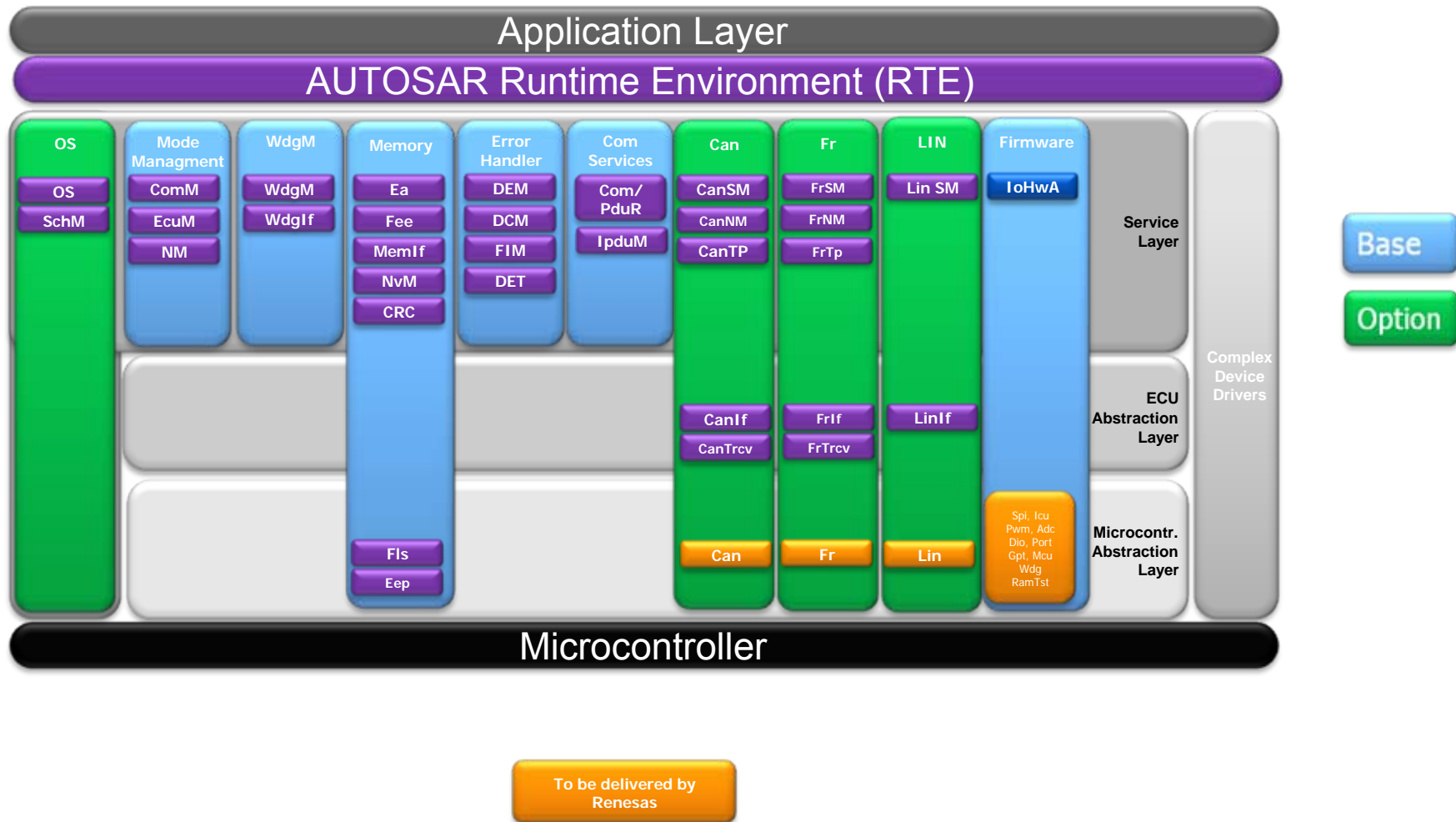
**CHS**

**E/E System**

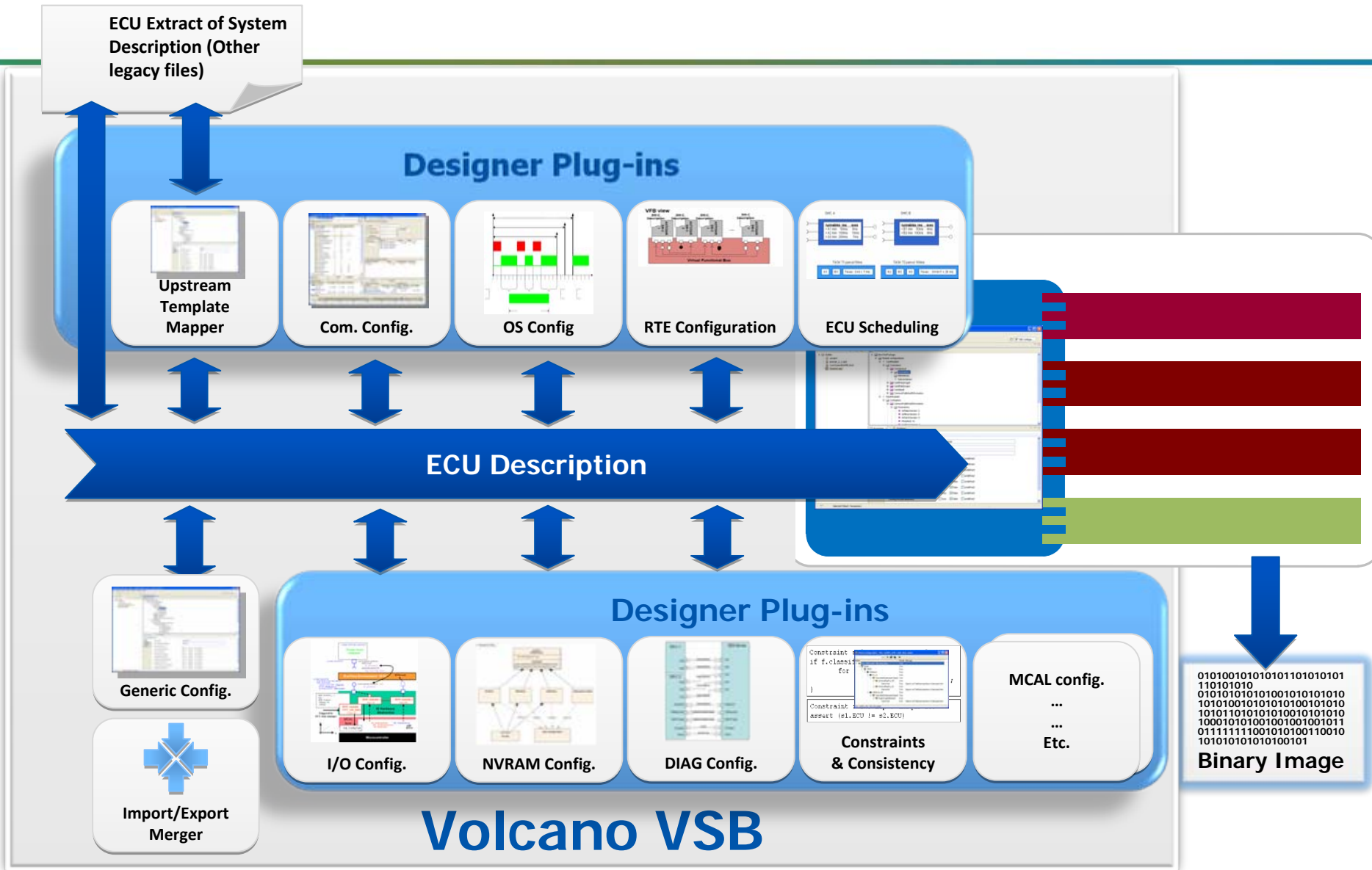


**Metrics  
Architecture  
evaluation**

# Standard BSW Stack (3.x)



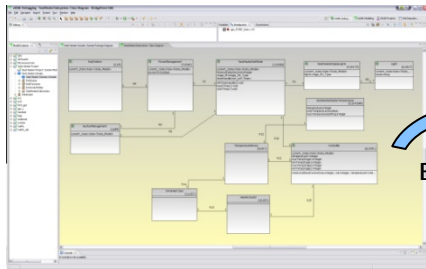
# VSB – Volcano system Builder





# VSI - Volcano System Integrator

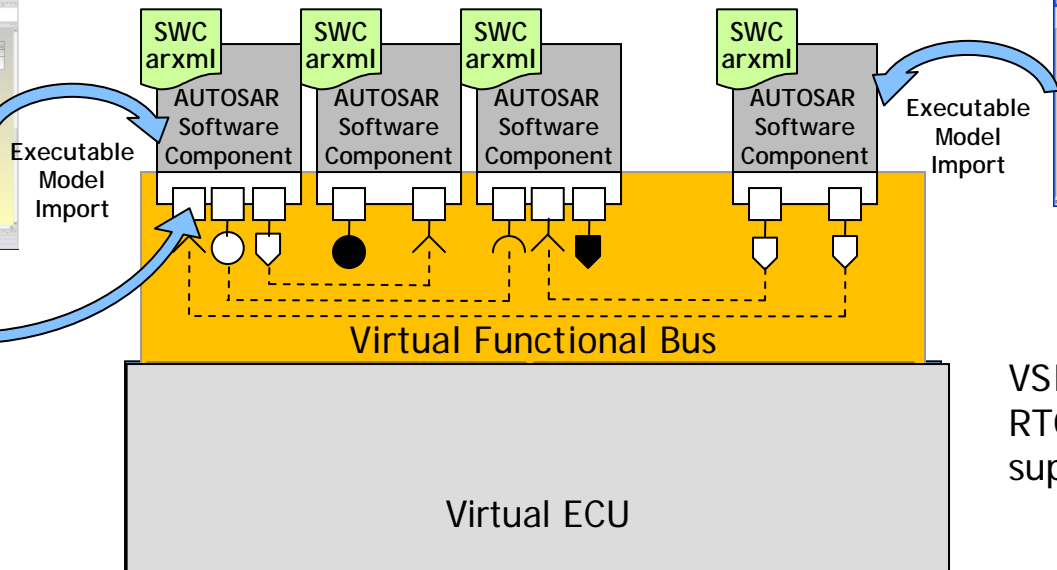
## Software Modeling



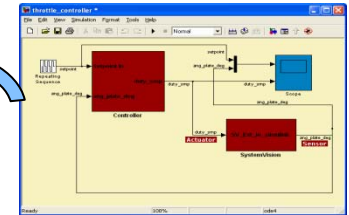
Executable  
Model  
Import

My\_mod.c  
My\_mod.c  
initial  
begin  
clk = 0;  
#10 clk = 1;  
forever #50 clk =  
!clk;  
end

Hand coded



## Algorithmic Modeling

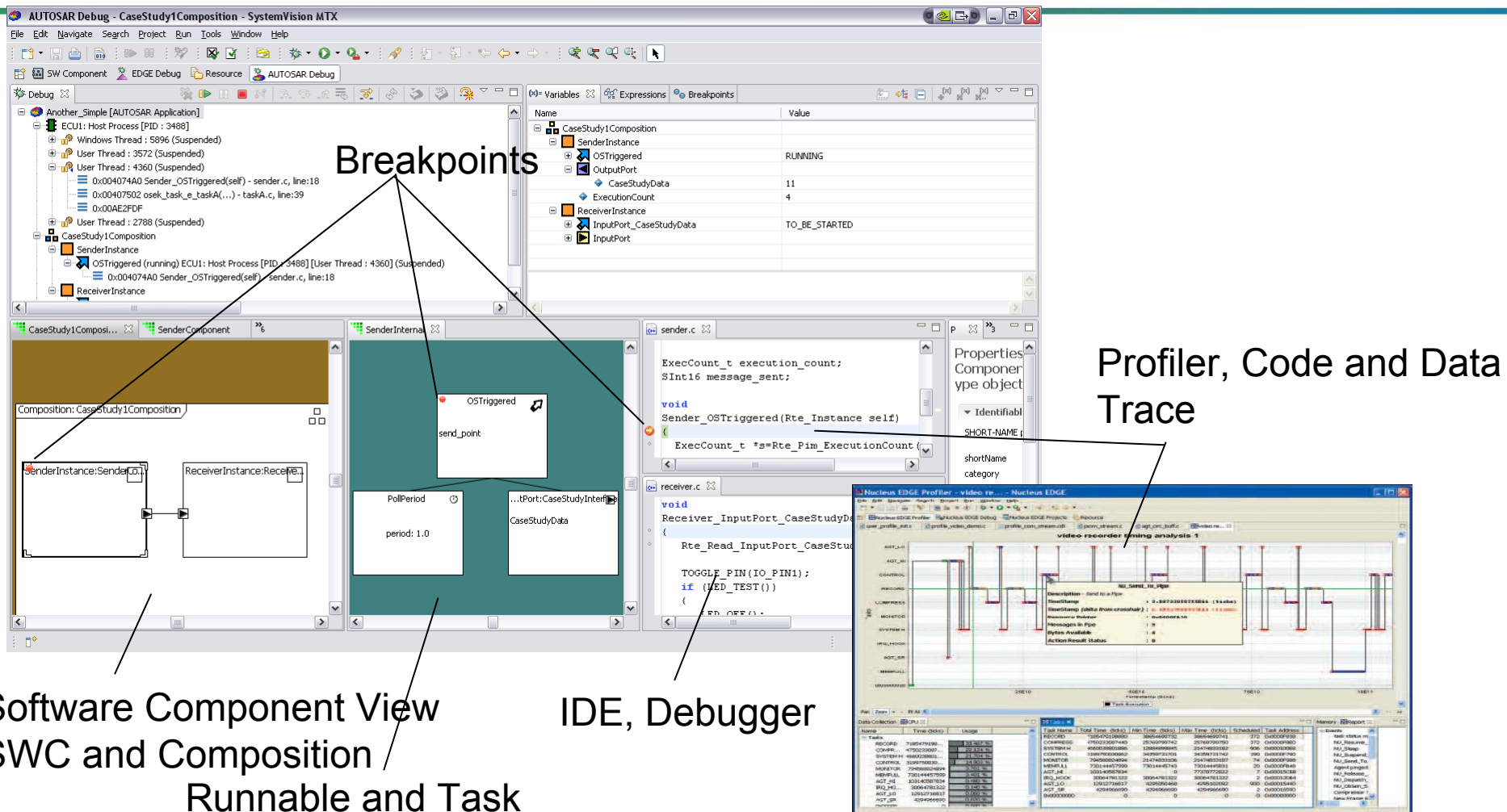


Executable  
Model  
Import

VSI incorporates  
RTOS and system  
support

- Execution environment for AUTOSAR Systems
- Early validation of SW functionality on virtual ECU and BSW
- Full debug and interactive validation at all relevant levels of software system, OS task or executing code

# VSI Tool Suite

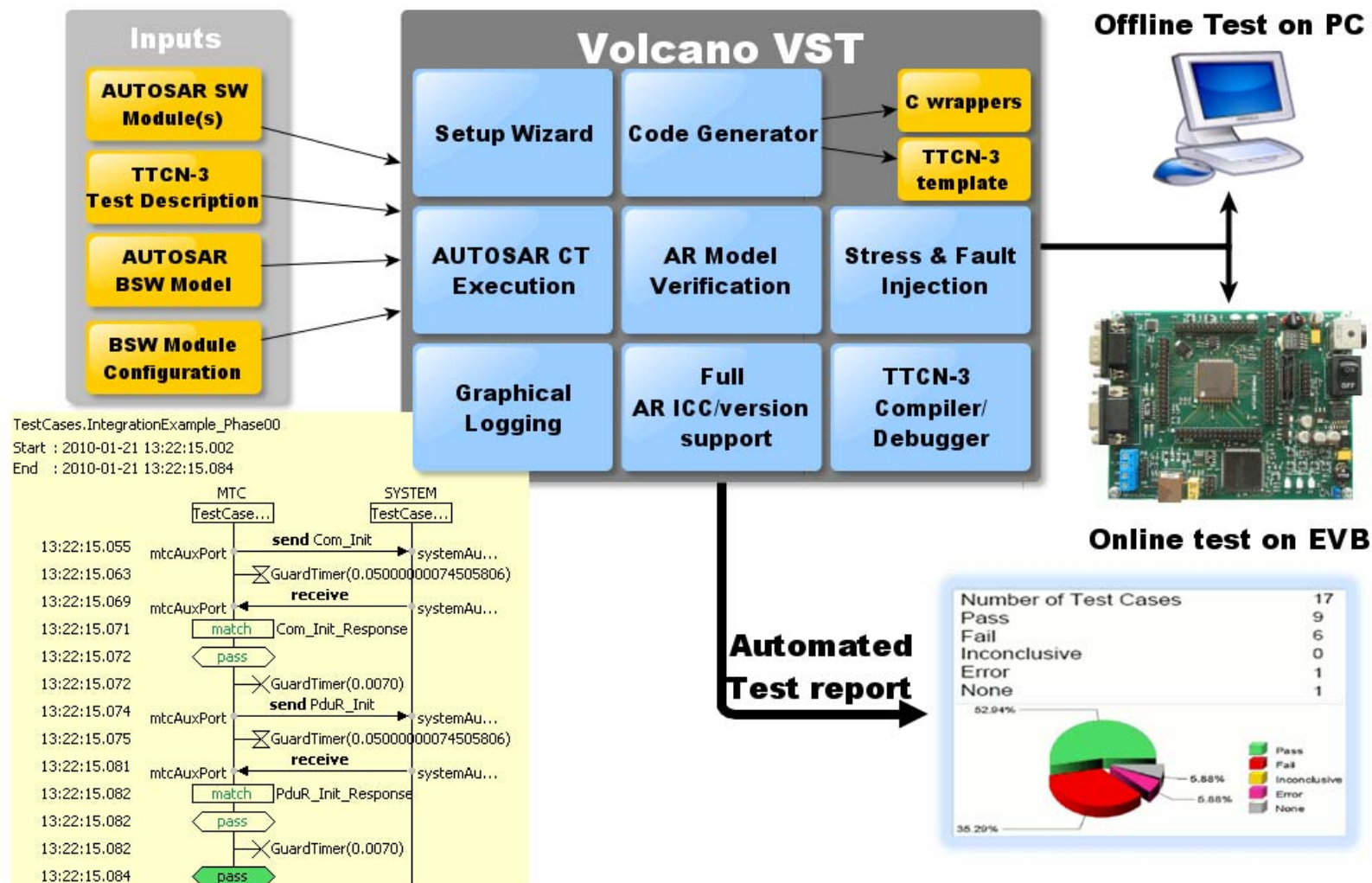


# VST – Volcano Systems Tester

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- One single environment for Test Development, Execution and Reporting.
- A generic test tool, not limited to AUTOSAR SW testing
- Test Execution either on Target or on PC
- Based on well known and open Standard Language (TTCN-3)
- Automatic report generation

# VST – Volcano Systems Tester



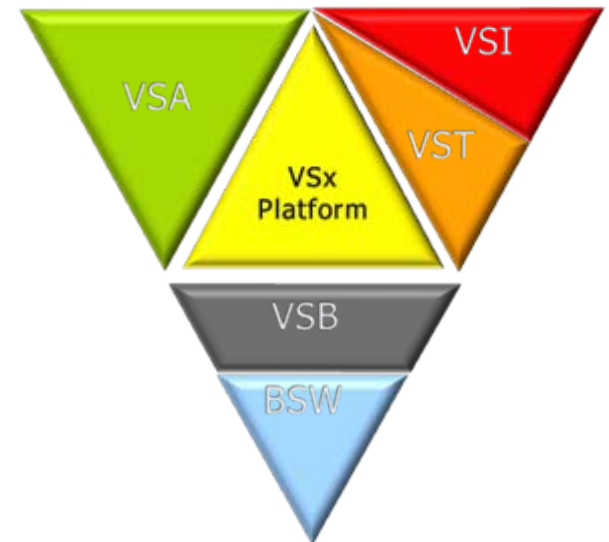
# Summary

## ■ VSx Covers

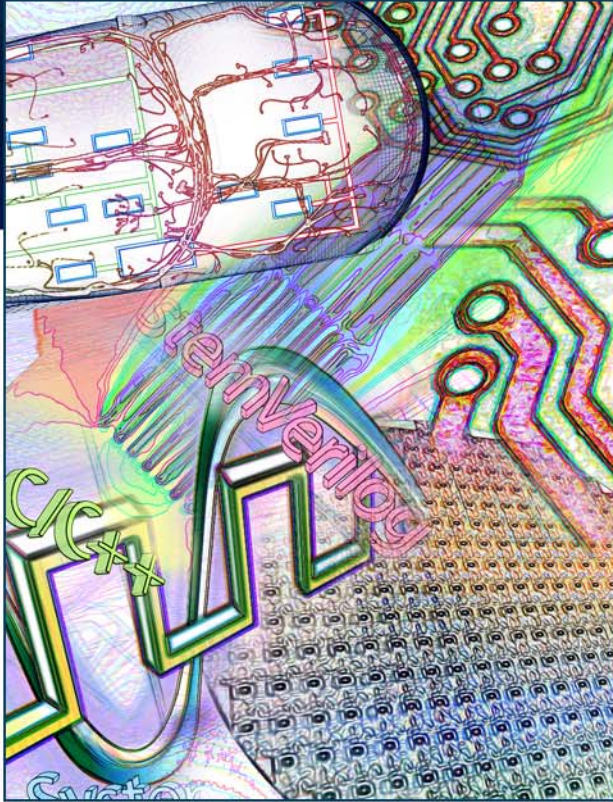
- Architecture design
- Network Design
- ECU configuration, design and test
- VFB level simulation
- Implementation in ECUs

## ■ VSx Goals

- Optimisation of the E/E architecture
- Early verification of the system
- "Correctness by design"
- Consistence guarantee from requirements to realisation







Thank You!