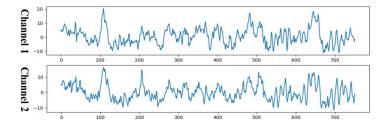
EEG classification

1. Introduction

在這個實驗中·需要實作EEG的分類模型·分別是EEGNet和 DeepConvNet·並嘗試三種不同的 activation function (ReLU, Leaky ReLU, ELU)。 (使用資料集:BCI Competition III - IIIIb) 目標是將腦波訊號分類成兩種類別(左手、右手)。

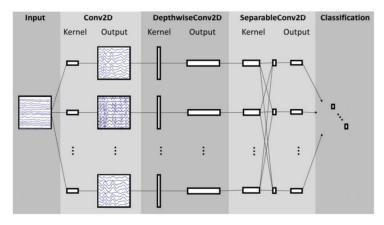
Reference: http://www.bbci.de/competition/iii/desc_IIIb.pdf



資料集中有兩個 channel·各有 750 個資料點·標記為左,右手兩種類別。

兩種模型的比較:

- ◆DeepConvNet:採用基本CNN架構
- ◆EEG:是為專門一般的腦電圖識別任務而設計的通用且緊湊的捲積神經網絡,設計思路則是借鑒了MobileNet。在訓練數據有限的情況下,EEGNet具有更強的泛化能力和更高的性能,用少量的訓練資料就可得到不錯的結果。



上圖是EEGnet的整體結構圖,只有三個卷積模塊,重點是depthwise conv (逐通道的捲積層操作)和separable conv這兩個卷積模塊。

其中separable conv由一個Depthwise Convolution(逐通道的捲積層操作)和一個Pointwise Convolution(逐點的捲積層操作)組成。

2. Experiment set up

A. The detail of your model

• EEGNet

```
EEGNet(
  (firstconv): Sequential(
    (0): Conv2d(1, 16, kernel_size=(1, 51), stride=(1, 1), padding=(0, 25), bias=False)
    (1): BatchNorm2d(16, eps=le-05, momentum=0.1, affine=True, track_running_stats=True)
} (depthwiseConv): Sequential(
    (0): Conv2d(16, 32, kernel_size=(2, 1), stride=(1, 1), groups=16, bias=False)
    (1): BatchNorm2d(32, eps=le-05, momentum=0.1, affine=True, track_running_stats=True)
    (2): ELU(alpha=1.0)
    (3): AvgPool2d(kernel_size=(1, 4), stride=(1, 4), padding=0)
    (4): Dropout(p=0.25)
} (separableConv): Sequential(
    (0): Conv2d(32, 32, kernel_size=(1, 15), stride=(1, 1), padding=(0, 7), bias=False)
    (1): BatchNorm2d(32, eps=le-05, momentum=6.1, affine=True, track_running_stats=True)
    (2): ELU(alpha=1.0)
    (3): AvgPool2d(kernel_size=(1, 8), stride=(1, 8), padding=0)
    (4): Dropout(p=0.25)
} (classify): Sequential(
    (0): Linear(in_features=736, out_features=2, bias=True)
}
```

程式碼:

```
class EEG(nn.Module):
    def init (self, act func):
        super(EEG, self). init ()
        self.activationDict = {
            'ReLU': nn.ReLU(),
            'LeakyReLU': nn.LeakyReLU(),
            'ELU': nn.ELU(),
        self.firstConv = nn.Sequential(
            nn.Conv2d(in_channels=1, out_channels=16, kernel_size=(1,51), stride=(1,1),padding=(0,25), bias=False), #input=1x2x750 output=16x2x750
            nn.BatchNorm2d(16, eps=1e-5, momentum=0.1, affine=True, track_running_stats=True),
        self.depthwiseConv = nn.Sequential(
            nn.Conv2d(in_channels=16, out_channels=32, kernel_size=(2,1), stride=(1,1), groups=16, bias=False), #input=16x2x750 output=32x1x750
            nn.BatchNorm2d(32, eps=1e-5, momentum=0.1, affine=True, track_running_stats=True),
            self.activationDict[act_func],
            nn. AvgPool2d(kernel\_size=(1,4), \ stride=(1,4), \ padding=0), \ \#input=32x1x750 \ output=32x1x187
            nn.Dropout(p=0.25),
        self.separableConv = nn.Sequential(
            nn. Conv2d (in \ channels=32, \ out \ channels=32, \ kernel \ size=(1,15), stride=(1,1), padding=(0,7), \ bias=False), \ \#input=32x1x187 \ output=32x1x187
```

```
nn.BatchNorm2d(32, eps=1e-5, momentum=0.1, affine=True, track_running_stats=True),
    self.activationDict[act_func],
    nn.AvgPool2d(kernel_size=(1,8), stride=(1,8), padding=0), #input=32x1x187 output=32x1x23
    nn.Dropout(p=0.25)
)
self.classifyConv = nn.Sequential(
    nn.Flatten(), #input=32x1x23 output=736
    nn.Linear(in_features=736,out_features=2,bias=True)
)
def forward(self, x):
    x = self.firstConv(x)
    x = self.depthwiseConv(x)
    x = self.separableConv(x)
    x = self.classifyConv(x)
    return x
```

*DeepConvNet

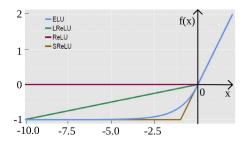
Layer	# filters	size	# params	Activation	Options
Input		(C, T)			
Reshape		(1, C, T)			
Conv2D	25	(1, 5)	150	Linear	$\bmod e = \mathrm{valid}, \max \mathrm{norm} = 2$
Conv2D	25	(C, 1)	25 * 25 * C + 25	Linear	mode = valid, max norm = 2
BatchNorm			2 * 25		${\rm epsilon} = 1\text{e-}05, \text{momentum} = 0.1$
Activation				ELU	
MaxPool2D		(1, 2)			
Dropout					p = 0.5
Conv2D	50	(1, 5)	25 * 50 * C + 50	Linear	mode = valid, max norm = 2
BatchNorm			2 * 50		epsilon = 1e-05, $momentum = 0.1$
Activation				ELU	
MaxPool2D		(1, 2)			
Dropout					p = 0.5
Conv2D	100	(1, 5)	50 * 100 * C + 100	Linear	mode = valid, max norm = 2
BatchNorm			2 * 100		${\rm epsilon} = 1\text{e-}05, \text{momentum} = 0.1$
Activation				ELU	
MaxPool2D		(1, 2)			
Dropout					p = 0.5
Conv2D	200	(1, 5)	100 * 200 * C + 200	Linear	mode = valid, max norm = 2
BatchNorm			2 * 200		${\rm epsilon} = 1\text{e-}05, \text{momentum} = 0.1$
Activation				ELU	
MaxPool2D		(1, 2)			
Dropout					p = 0.5
Flatten					
Dense	N			softmax	max norm = 0.5

程式碼:

```
class DeepConvNet(nn.Module):
   def __init__(self, act_func):
        \verb"super(DeepConvNet, self).\__init\__()
       self.activationDict = {
            'ReLU': nn.ReLU(),
            'LeakyReLU': nn.LeakyReLU(),
            'ELU': nn.ELU(),
        self.doubleConv = nn.Sequential(
           nn. Conv2d (in\_channels=1, \ out\_channels=25, \ kernel\_size=(1,5)), \ \#input=1x2x750 \ output=25x2x746
            nn. Conv2d (in\_channels=25, \ out\_channels=25, \ kernel\_size=(2,1)), \ \#input=25x2x746 \ output=25x1x746
           nn.BatchNorm2d(25, eps=1e-5, momentum=0.1),
           self.activationDict[act_func],
           nn.MaxPool2d(kernel_size=(1,2)), #input=25x1x746 output=25x1x373
           nn.Dropout(p=0.5)
        self.secondConv = nn.Sequential(
           nn.Conv2d(in_channels=25, out_channels=50, kernel_size=(1,5)), #input=25x1x378 output=50x1x369
            nn.BatchNorm2d(50, eps=1e-5, momentum=0.1),
            self.activationDict[act_func],
           nn.MaxPool2d(kernel_size=(1,2)), #input=50x1x369 output=50x1x184
           nn.Dropout(p=0.5)
       self.thirdConv = nn.Sequential(
           nn.Conv2d(in_channels=50, out_channels=100, kernel_size=(1,5)), #input=50x1x184 output=100x1x180
            nn.BatchNorm2d(100, eps=1e-5, momentum=0.1),
            self.activationDict[act_func],
            nn.MaxPool2d(kernel_size=(1,2)), #input=100x1x180 output=100x1x90
            nn.Dropout(p=0.5)
        self.fourthConv = nn.Sequential(
           nn.Conv2d(in_channels=100, out_channels=200, kernel_size=(1,5)), #input=100x1x90 output=200x1x86
           nn.BatchNorm2d(200, eps=1e-5, momentum=0.1),
           self.activationDict[act_func],
           nn.MaxPool2d(kernel_size=(1,2)), #input=200x1x86 output=200x1x43
           nn.Dropout(p=0.5)
        self.flatten = nn.Flatten()
        self.dense = nn.Sequential(
           nn.Linear(in_features=8600,out_features=2)
   def forward(self, x):
       x = self.doubleConv(x)
        x = self.secondConv(x)
        x = self.thirdConv(x)
        x = self.fourthConv(x)
```

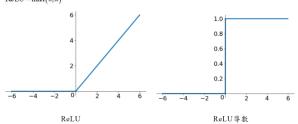
x = self.flatten(x)
x = self.dense(x)
return x

B. Explain the activation function (ReLU, Leaky ReLU, ELU)



*ReLU

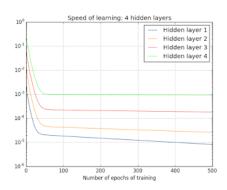
ReLU = max(0,x)



若輸入為正數·則輸出該值大小·若值為負數·則輸出為0。ReLU函數並不是全區間皆可微分·但是不可微分的部分可以使用Sub-gradient進行取代。其有以下特點:

(1)解決梯度消失問題

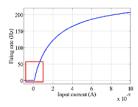
ReLU的分段線性性質能有效地克服梯度消失之問題。



(2)計算量大幅降低

無需使用任何指數運算,只需要判斷輸入值是否大於0,來進行輸出。

(3)生物事實(細胞激活現象)



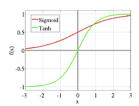


Figure 1: Left: Common neural activation function motivated by biological data. Right: Commonly used activation functions in neural networks literature: logistic sigmoid and hyperbolic tangent (tanh).

ReLU函數成功模擬了細胞對於刺激的反應現象:當對細胞的刺激未達到一定強度時,神經元不會進行訊息傳遞,但當超越啟動之強度時,會引起神經衝動,而進行訊息之傳遞。

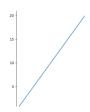
(4)類神經網路的稀疏性(奧卡姆剃刀原則)

ReLU激勵函數會使負數部分的神經元輸出為0.可以讓網路變得更加多樣性.如同Dropout的概念.可以緩解過擬合(Over fitting)之問題.但會衍生Dead ReLU的問題(當某個神經元輸出為0後.就難以再度輸出)。 容易導致dead ReLU發生的原因:

1. 初始化權重設定為不能被激活的數值。

2. 學習率設置過大,在剛開始進行誤差反向傳遞時,容易修正權重值過大,導致權重梯度為 $\mathbf{0}$,神經元即再也無法被激活。

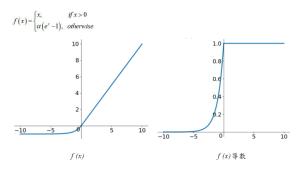
◆Leaky ReLU





ReLU是將所有的負值都設為零,而為了解決Dead ReLU Problem,Leaky ReLU結所有負值賦予一個非零斜率,如此一來,即能防止值為負號時永遠無法被激活之問題。理論上來說,Leaky ReLU擁有ReLU的所有優點,也成功避免 Dead ReLU Problem的問題產生,但是於實際使用上,還沒有辦法完全證明Leaky ReLU永遠優於ReLU。

+ELU



ELU函數也是為了解決Dead ReLU問題而被提出,但需要計算指數,計算量較大。其平均激活均值趨近爲 0,並負飽和區的存在使得 ELU 比 Leaky ReLU 更加健壯,抗噪聲能力更強。理論上來說,ELU 擁有ReLU的所有優點,也成功變免Dead ReLU Problem的問題產生,但是於實際使用上,還沒有辦法完全證明Leaky ReLU永遠優於ReLU,

3. Experimental results

A. The highest testing accuracy

*Screenshot with two models

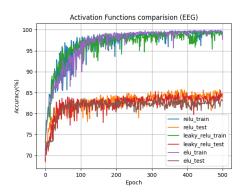
Learning rate = 1e-3 (train/test) (單位:%)

model \ activation	ReLU	LeakyReLU	ELU	
EEGNet	99.4/83.79	99.35/84.62	97.68/83.05	
DeepConvNet	96.01/76.85	96.66/77.07	99.90/77.59	

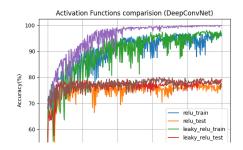
EEG ReLU train				DeepConvNet_ReLU_train							
epoch=	250	loss=	3.402955761110341e-05	correct=	0.9925925925925926	epoch=	250	loss=	0.00014599338173866273	correct=	0.9435185185185185
epoch=	500	loss=	1.7752998543006404e-05	correct=	0.994444444444445	epoch=	500	loss=	0.00014489585602724993	correct=	0.9601851851851851
EEG_ReL	U_tes	t				DeepConvNet_ReLU_test					
epoch=	250	loss=	0.000572562438470346	correct=	0.8416666666666667	epoch=	250	loss=	0.0007435650737197311	correct=	0.7462962962962963
epoch=	500	loss=	0.0007224686719753124	correct=	0.8379629629629629	epoch=	500	loss=	0.0008095357705045629	correct=	0.7685185185185185
EEG_Lea	kyReLI	J_train				DeepCon	vNet_	LeakyRe	LU_train		
epoch=	250	loss=	6.823038889302148e-05	correct=	0.969444444444444	epoch=	250	loss=	0.00016172417887934932	correct=	0.937962962962963
epoch=	500	loss=	1.899072796934181e-05	correct=	0.9935185185185185	epoch=	500	loss=	0.00011148922559287813	correct=	0.966666666666667
EEG_Lea	kyReLI	J_test				DeepConvNet_LeakyReLU_test					
epoch=	250	loss=	0.0005801748898294237	correct=	0.837037037037037	epoch=	250	loss=	0.0006718383895026313	correct=	0.75555555555555
epoch=	500	loss=	0.0007137201450489186	correct=	0.8462962962962963				0.000962156057357788	correct=	0.7907407407407407
EEG_ELU_train				DeepConvNet_ELU_train							
epoch=	250	loss=	3.399812030019583e-05	correct=	0.9925925925925926	epoch=	250	loss=	3.118925831384129e-05	correct=	0.9898148148148148
epoch=	500	loss=	5.2501130159254425e-05	correct=	0.9768518518518519				3.40719621076628e-06	correct=	0.9990740740740741
EEG_ELU	test					DeepCon	vNet_	ELU_tes			
epoch=	250	loss=	0.0005791956075915584	correct=	0.8175925925925925				0.000963965720600552		
epoch=	500	loss=	0.0007926864756478204	correct=	0.830555555555556	epoch=	500	loss=	0.0014684530319990935	correct=	0.7759259259259259

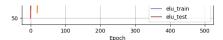
B. Comparison figures

• EEGNet



DeepConvNet





4. Discussion

(1)發現調低學習率能訓練得更好。

註:本實驗使用的學習率為:1-e3·其結果在報告中可查訊。以下附上學習率1e-2與1-e3在test的準確率差異及習率為:1-e2的結果報告。

◆學習率1e-2與1-e3在test的準確率差異(1-e3準確率-1-e2準確率)

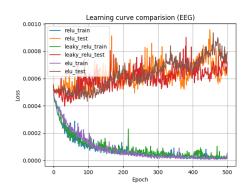
model \ activation	ReLU	LeakyReLU	ELU	
EEGNet	5	4.62	4.72	
DeepConvNet	1.02	0.59	-0.55	

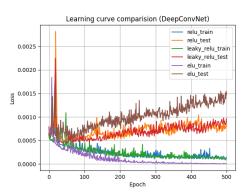
◆Learning rate = 1e-2 (train/test) (單位:%)

model \ activation	ReLU	LeakyReLU	ELU	
EEGNet	98.24/78.79	98.98/80	98.05/78.33	
DeepConvNet	95.37/75.83	95.55/76.48	99.62/78.14	

```
250 loss= 0.0001974168199080008 correct= 0.9314814814814815
500 loss= 0.00018889683264273184 correct= 0.9537037037037037
viket_ReLU_test
       250 loss= 0.0006119198821209095 correct= 0.7833333333333
500 loss= 0.0006306861837704976 correct= 0.75833333333333
/Net_LeakyReLU_train
       250 loss= 4.254696131856353e-05 correct= 0.9879629629629629
500 loss= 4.2715040897881544e-05 correct= 0.9898148148148148
                                                                                                     250
                                                                                                          loss= 0.00019607342503688953 correct= 0.9324074074074075
loss= 0.00018065833935031184 correct= 0.955555555555555
EG_LeakyReLU_test
                                                                                                     Net LeakyReLU test
       250
500
                                                                                                           EG ELU train
                                                                                             epConvNet ELU train
       250 loss= 4.1765164307974e-05 correct= 0.98888888888888
500 loss= 5.26627491193789e-05 correct= 0.980555555555555
                                                                                                          loss= 4.701902055078083e-05 correct= 0.9907407407407407
loss= 2.0252031929515027e-05 correct= 0.996296296296296296
EG ELU test
                                                                                              epConvNet ELU test
             loss= 0.001314703071558917 correct= 0.7898148148148149
loss= 0.002448132082268044 correct= 0.78333333333333
                                                                                                    250 loss= 0.0013801352845297919 correct= 0.7657407407407407
500 loss= 0.003982188966539171 correct= 0.7814814814814814
```

(2)發現不論在 EEGNet或是**DeepConvNet**·大概訓練 100 個 epoch 後·在 train data 正確率基本都可以達到九成·不過在 test data 上繼續訓練也沒有太多進步。 Loss 的學 習曲線中·推測為 overfit現象。





(3)weight decay的使用

weight decay(權值衰減)的使用其最終目的是防止過擬合。在損失函數中·weight decay是放在正則項(regularization)前面的一個係數·正則項一般指示模型的複雜度·所以weight decay的作用是調節模型複雜度對損失函數的影響·若weight decay很大·則複雜的模型損失函數的值也就大。

optimizer = optim.Adam(model.parameters(),Learning_Rate, weight_decay = 0.001)

在本次實驗中·加入weight decay·在DeepConvNet的表現上準確率皆提升2%-3%·但在EEG上就較沒有明顯的變化。