Test

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1 Chapter 1

1.1 Equation Generated by Python

Consider the differential equation given below.

$$\frac{dy(t)}{dt} - 1.5y(t) = 1.5u(t), y(0) = 3.6$$
 (1)

1.2 Table

Consider the singal given below.

1.3 Inline Equation

Consider the differential equation given below.

$$\frac{dy(t)}{dt} - 1.5y(t) = 1.5u(t), y(0) = 3.6$$
 (2)

- Find an integral form solution for Eq.2.
- Find an analytic solution for Eq.2 when the input u(t) is given as, for $t \geq 0$. Is this input able to stabilize state y(t) when $t \to \infty$?
- Find the difference equation when sample time is $\triangle t = 0.3$ by exact discretization.
- Find the difference equation with time derivative approximated at $\Delta t = 0.3$ by finite difference method.
- Find a solution of difference equation and exact difference equation using MATLAB or any other software for k=20. Plot the sequence of numbers obtained by the exact difference equation and by finite difference method and applied piecewise constant input given as follows

$$u(0) = -2$$

$$u(1\triangle t) = -2e^{-2*1\triangle t}$$

$$u(2\triangle t) = -2e^{-2*2\triangle t}$$

$$\cdots = \cdots$$

$$u(k\triangle t) = -2e^{-2*k\triangle t}$$

with k=20

Solution:

•

$$y(t) = 5e^{2t} + 1.5e^{2t} \int_0^t (-2)e^{-2s}e^{-2s}ds = 5e^{2t} - 3e^{2t} \int_0^t e^{-4s}ds = 5e^{2t} - 3\int_0^t e^{-4s}\frac{d(-4s)}{-4}ds$$
$$y(t) = 5e^{2t} + \frac{3}{4}\left[e^{-4t} - 1\right]$$

• Exact discretization $\Delta t = 0.3$:

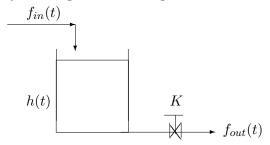
$$y_{k+1} = e^{a\Delta t}y_k + a^{-1}(e^{a\Delta t} - 1)bu_k$$
$$= 1.822y_k + 0.6166u_k$$

• Finite difference method $\Delta t = 0.3$:

$$\begin{array}{rcl} \frac{dy}{dt} \approx \frac{y_{k+1} - y_k}{\Delta t} & = & 2y_k + 1.5u_k \\ & & & \\ y_{k+1} & = & (1 + 2\Delta t)y_k + 1.5(\Delta t)u_k \\ & = & 1.6y_k + 0.45u_k \end{array}$$

1.4 ditaa & LaTEX Graph

For the physical process of tank dynamics given in the Figure below:



Solution:

- $\frac{dh}{dt} = -\frac{1}{K\overline{A}}h + \frac{1}{\overline{A}}f_{in}$
- Assume that the tank height is measured, y(t) = h(t)

$$\Sigma(A, B, C, D) = \Sigma\left(-\frac{1}{K\overline{A}}, \frac{1}{\overline{A}}, 1, 0\right)$$

• The state-space realization is given as:

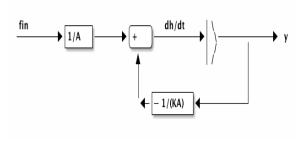


Figure 1: Block diagram elements.

$$\Phi = e^{-\frac{0.2}{K\overline{A}}}, \quad \Gamma = -K \left(e^{-\frac{0.2}{K\overline{A}}} - 1 \right), \quad \theta = 1$$

$$\Sigma(A_d, B_d, C_d, D_d) = \Sigma \left(e^{-\frac{0.2}{K\overline{A}}}, -K \left(e^{-\frac{0.2}{K\overline{A}}} - 1 \right), 1, 0 \right)$$

• Assume that h(0) = 0. Laplace transform:

$$\frac{Y(s)}{U(s)} = \frac{5}{s+1}$$

$$\tau = 1, \quad \tau_d = 0 \Rightarrow \Delta t = (0.1 \sim 0.2)1\tau = 0.1 \sim 0.2$$

2 Chapter 2

2.1 JavaScript

2.2 Answer Sheet via Email

+RESULTS: AnswerSheet

Student ID:

token:

token:

Question1:

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2.3 Answer Sheet via Post

Name:

Gender: male female

E-mail:

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