

# Principles and Applications of Microcontrollers

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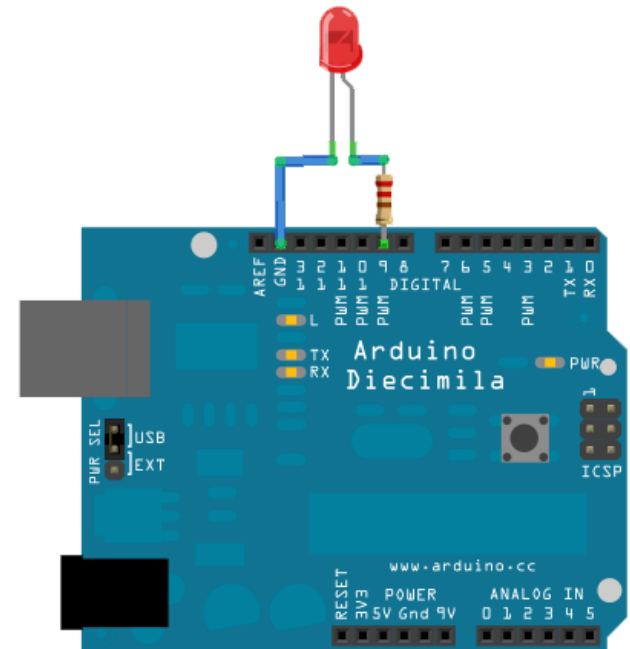
Today:

- Advanced Arduino programming
- Arduino PWM



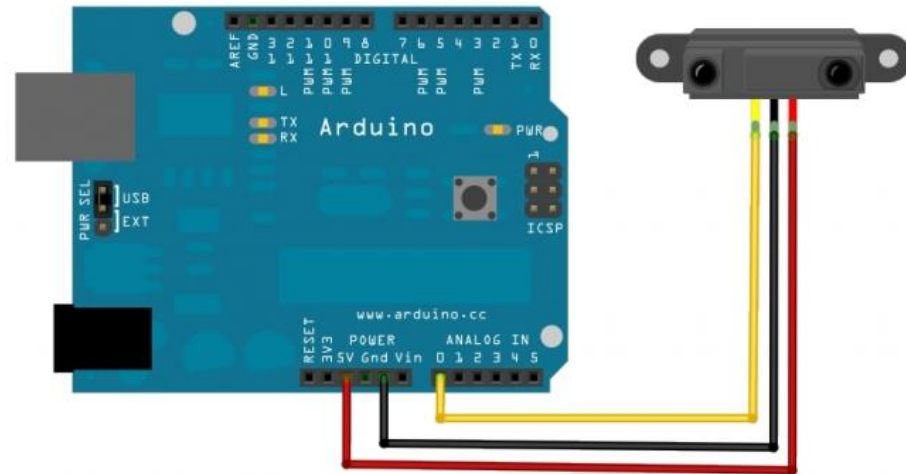
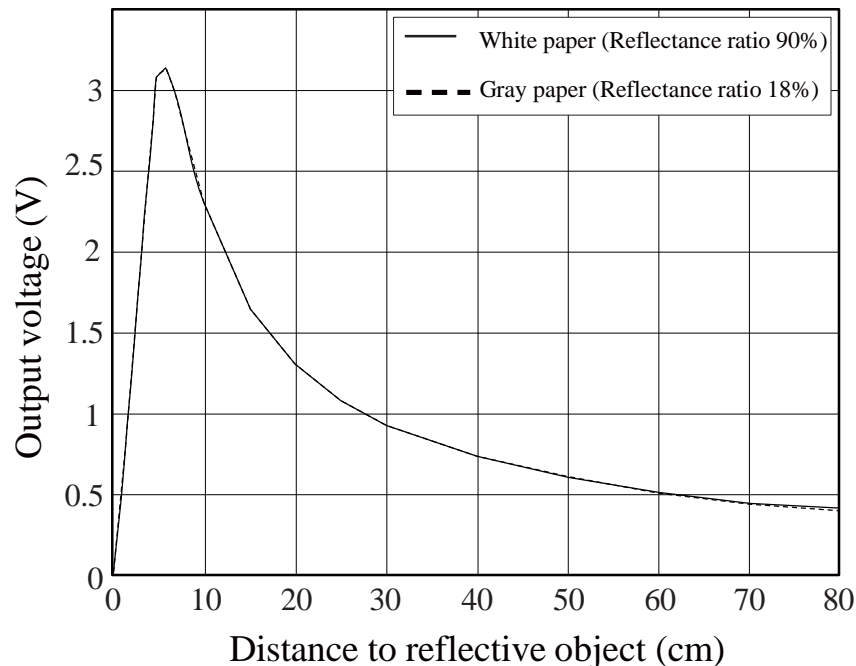
# Quiz

- Build a circuit that composes of an LED
- The LED is connected to a PWM pin
- Increase the brightness of the LED when the key '+' of the computer keyboard is pressed
- Decrease the brightness of the LED when the key '-' of the computer keyboard is pressed



# Example – DMS Sensor

- Read distance from proximity sensor
- It is an analog device
- Insusceptible to object color



# Sketch Code – DMS Sensor

```
void setup() {  
  Serial.begin(9600); // initialize serial communication at 9600 bits per second  
}  
  
void loop() {  
  int sensorValue = analogRead(A0); // read the input on analog pin 0  
  Serial.println(sensorValue);      // print out the value you read  
  delay(100);                      // wait for 1000 milliseconds  
}
```

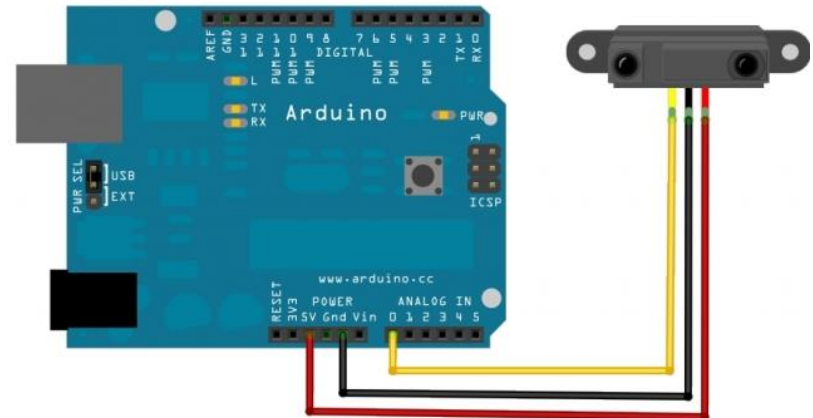
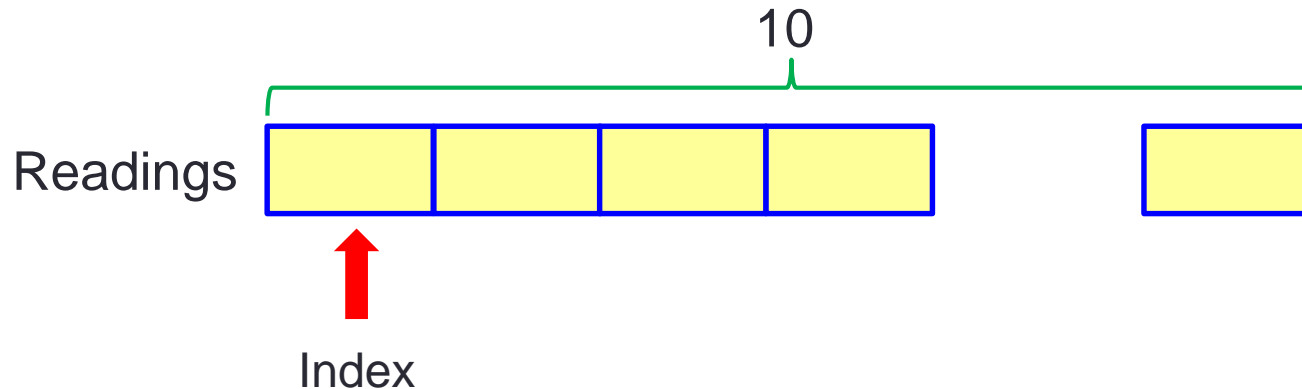
What is the minimum and maximum `analogRead` values?

# Practice – Fading LED according to Distance

- Fad an LED according to the distance from an proximity sensor
- Fad off the LED when the proximity sensor reading is small; fad on the LED when the reading is large

# Example – Smoothing

- Calculate a running average of an analog signal and print it on the computer screen



# Sketch Code – Smoothing

[Link](#)

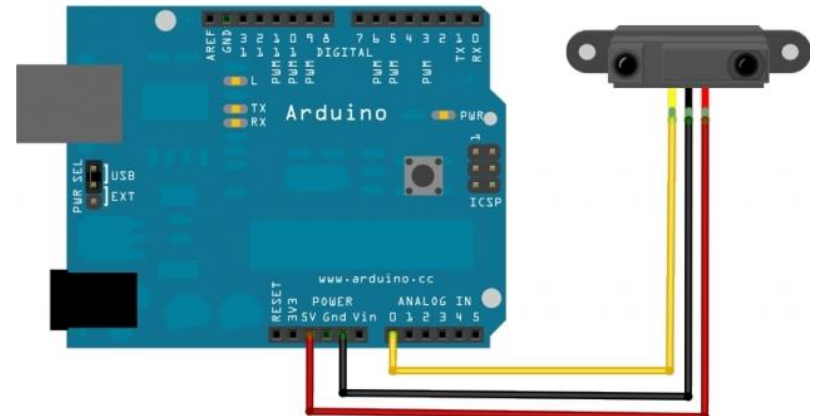
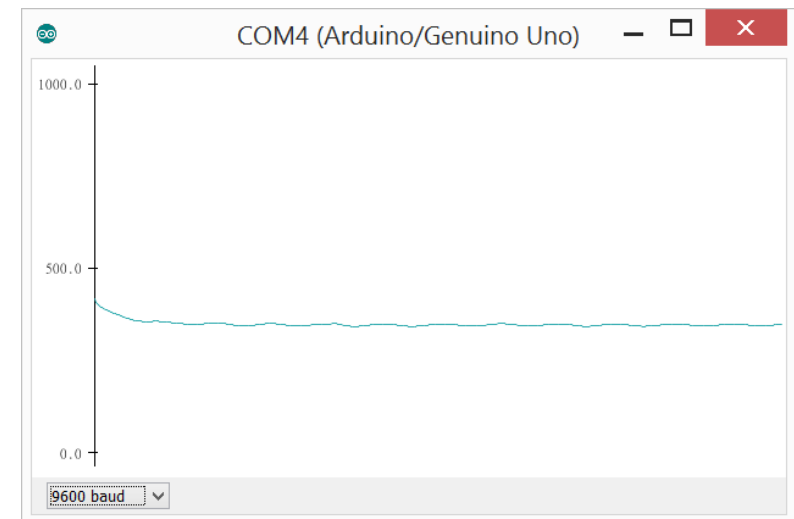
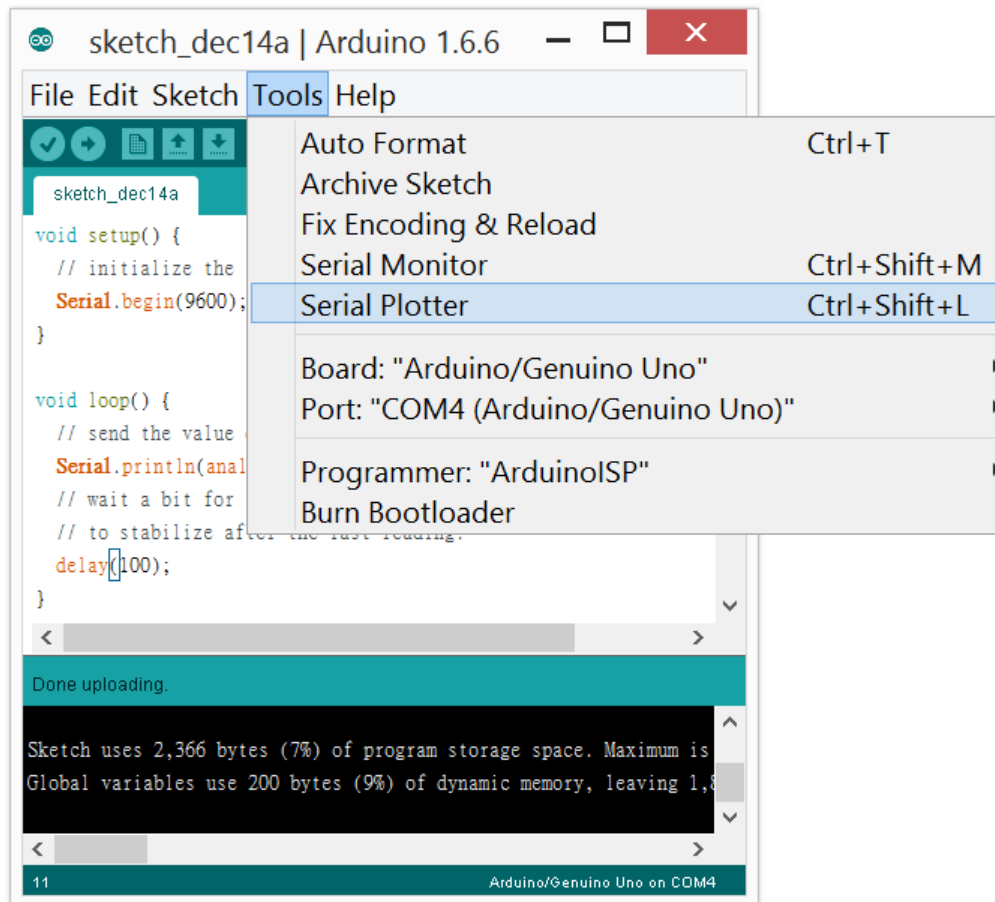
```
const int numReadings = 10;
int readings[numReadings];           // the readings from the analog input
int readIndex = 0;                   // the index of the current reading
int total = 0;                       // the running total
int average = 0;                     // the average
int inputPin = A0;

void setup() {
  Serial.begin(9600);
  for (int thisReading = 0; thisReading < numReadings; thisReading++) { // initialize
    readings[thisReading] = 0;
  }
}

void loop() {
  total = total - readings[readIndex]; // subtract the last reading
  readings[readIndex] = analogRead(inputPin); // read from the sensor
  total = total + readings[readIndex]; // add the reading to the total
  readIndex = readIndex + 1;           // advance to the next position in the array
  if (readIndex >= numReadings) {      // wrap around to the beginning if at the end
    readIndex = 0;
  }
  average = total / numReadings;       // calculate the average
  Serial.println(average);
  delay(10);
}
```

# Example – Serial Plotter

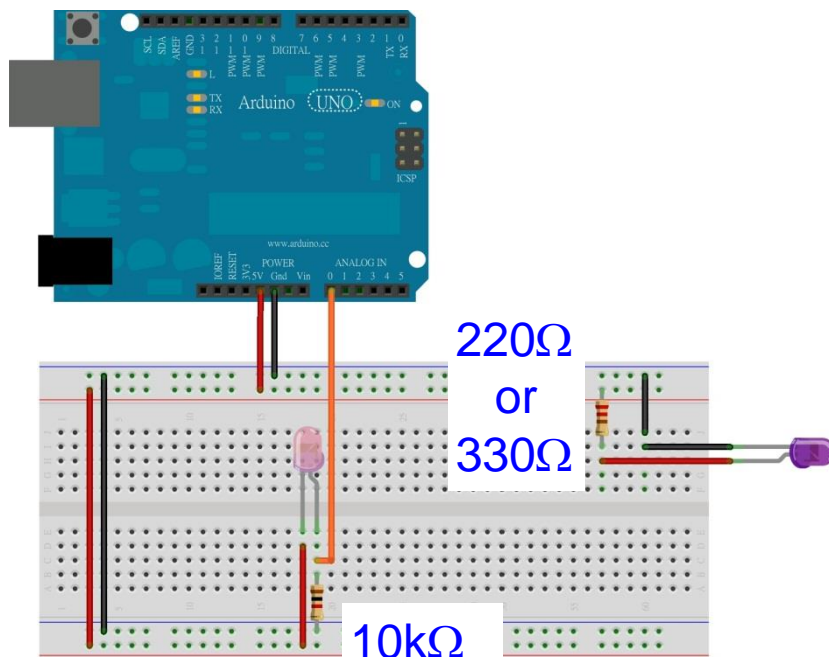
- Plot the analog signals



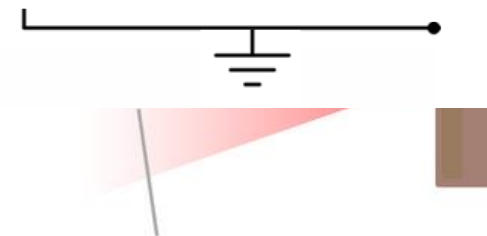


# Example – IR Sensor

- An infrared (IR) sensor is an electronic device that emits and detects infrared radiation to sense surroundings
- It is an analog device



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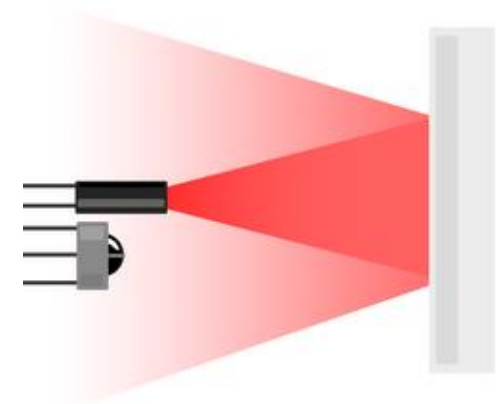
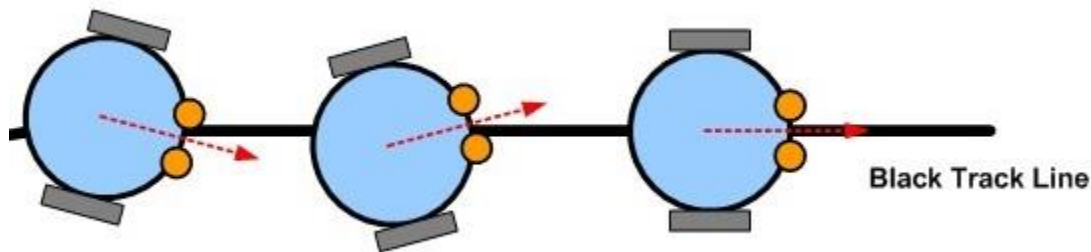
Object present - reflected IR light detected by sensor

# Sketch Code – IR Sensor

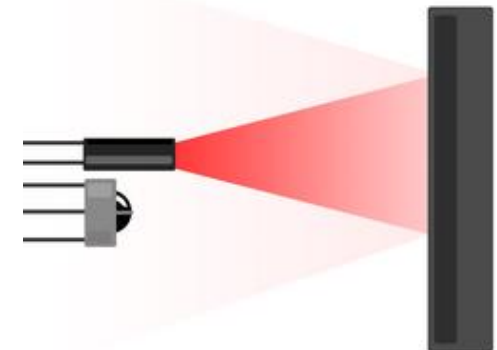
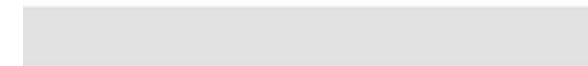
```
void setup() {  
  Serial.begin(9600); // initialize serial communication at 9600 bits per second  
}  
  
void loop() {  
  int sensorValue = analogRead(A0); // read the input on analog pin 0  
  Serial.println(sensorValue);      // print out the value you read  
  delay(1000);                     // wait for 1000 milliseconds  
}
```

# IR Sensor to Detect Brightness

- IR sensors can be used to detect brightness of objects
- An approach to detect black line using two IR sensors:



Lightly colored objects reflect more IR light

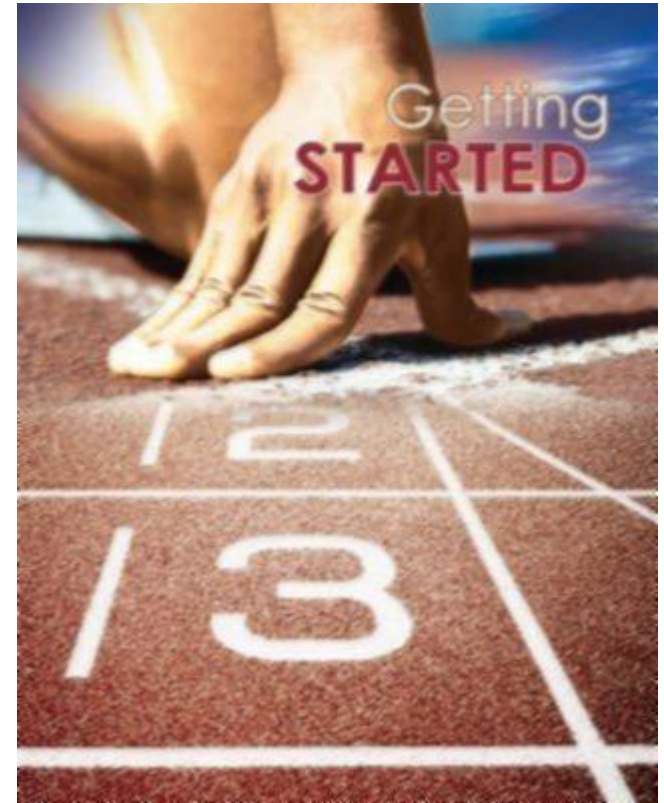


Darker colored object reflect less IR light

# What Have We Learned So Far?

- There is a math library from Arduino
- There is a component in the microcontroller that can approximate digital output to analog one – PWM

# Getting Started



# Reference

- <http://www.arduino.cc/>
- ATmega328P data sheet

